

# TLI4946

High Precision Hall Effect Latches for Industrial and Consumer Applications

TLI4946K, TLI4946-2K, TLI4946-2L

Datasheet

Rev. 1.0

Sense and Control



Never stop thinking

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| Page | Subjects (major changes since last revision) |
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## 1 Product Description

### 1.1 Overview

The TLI4946xy is a high precision Hall Effect Latch with highly accurate switching thresholds for ambient operating temperatures up to 125°C.

The TLI4946K and the TLI4946-2K is available in a PG-SC59-3-4 package, the TLI4946-2L in a PG-SSO-3-2 package.

### 1.2 Features

- 2.7 V to 18 V supply voltage operation.
- Operation from unregulated power supply.
- High sensitivity and high stability of the magnetic switching points.
- High resistance to mechanical stress by active error compensation.
- Reverse battery protection (-18 V).
- Superior temperature stability.
- Low jitter (typically 1  $\mu$ s).
- High ESD performance ( $\pm$  4 kV HBM).
- Digital output signal (open-drain).
- Not suitable for automotive applications

### 1.3 Target Applications

The TLI4946xy is ideally suited to detect the rotor position in Brushless DC (BLDC) Motors used in industrial and consumer applications, such as: air conditioning systems, pumps, washing machines, DVD players, rolling shutter, etc. The sensor also provides a reliable switching for index counting with small pole wheels and large air gaps. The TLI4946xy can also be used for index counting.



| Product Name      | Product Type | Ordering Code | Package     |
|-------------------|--------------|---------------|-------------|
| Hall Effect Latch | TLI4946K     | SP000604398   | PG-SC59-3-4 |
| Hall Effect Latch | TLI4946-2K   | SP000604328   | PG-SC59-3-4 |
| Hall Effect Latch | TLI4946-2L   | SP000604336   | PG-SSO-3-2  |

## 2 Functional Description

### 2.1 General

Precise magnetic switching thresholds and high temperature stability are achieved by active compensation circuits and chopper techniques on chip. Offset voltages generated by temperature-induced stress or overmolding are canceled so that high accuracy is achieved. The IC has an open collector output stage with 20 mA current sink capability. A wide operating voltage range from 2.7 V to 18 V with reverse polarity protection down to -18 V makes the TLI4946 suitable for a wide range of applications. A magnetic south pole with a field strength above  $B_{op}$  turns the output on. A magnetic north pole exceeding  $B_{rp}$  turns it off.

### 2.2 Pin Configuration

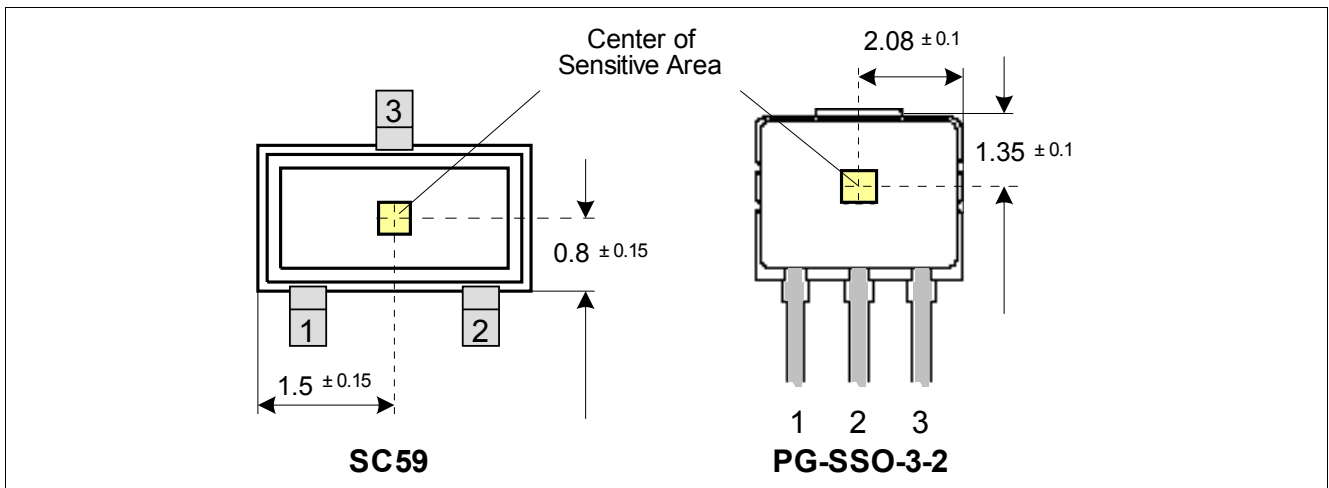


Figure 1 Pin Configuration and sensitive area (Top view, figure not to scale)



### 2.3 Pin Description

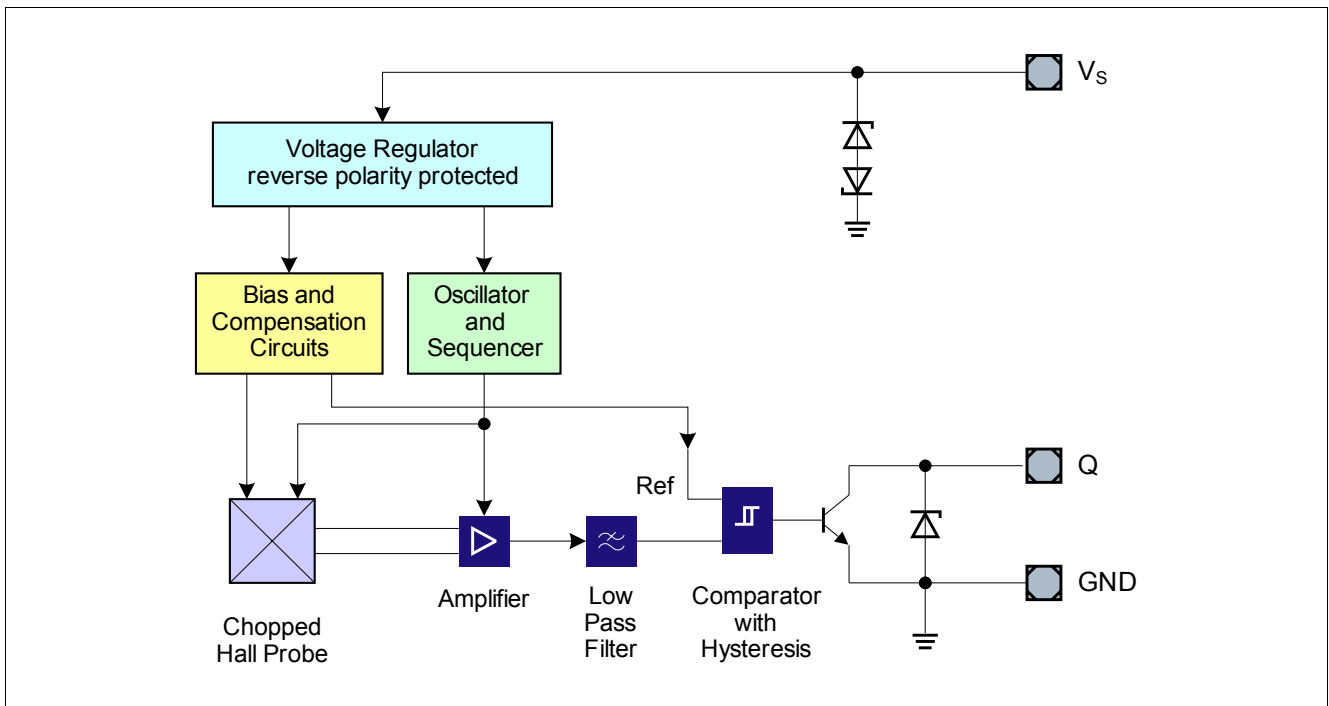
**Table 1 PIN Definitions for the PG-SC59-3-4 package**

| PIN No. | Name           | Function       |
|---------|----------------|----------------|
| 1       | V <sub>s</sub> | Supply Voltage |
| 2       | Q              | Output         |
| 3       | GND            | Ground         |

**Table 2 PIN Definitions for the PG-SSO-3-2 package**

| PIN No. | Name           | Function       |
|---------|----------------|----------------|
| 1       | V <sub>s</sub> | Supply Voltage |
| 2       | GND            | Ground         |
| 3       | Q              | Output         |

### 2.4 Block Diagram



**Figure 2 TLI4946xy Block Diagram**

## 2.5 Operating Modes and States

### Field Direction and Definition

Positive magnetic fields correspond to the south pole of the magnet targeting the branded side of the package.

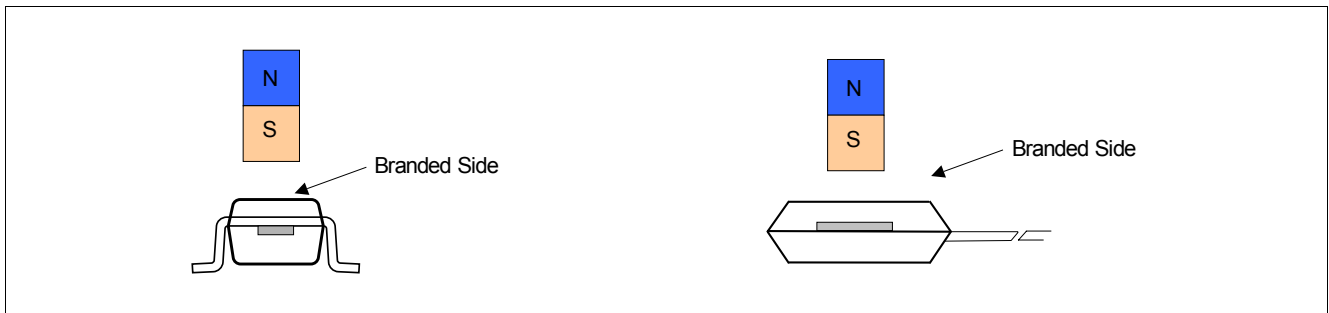


Figure 3 Definition of the Magnetic Field direction

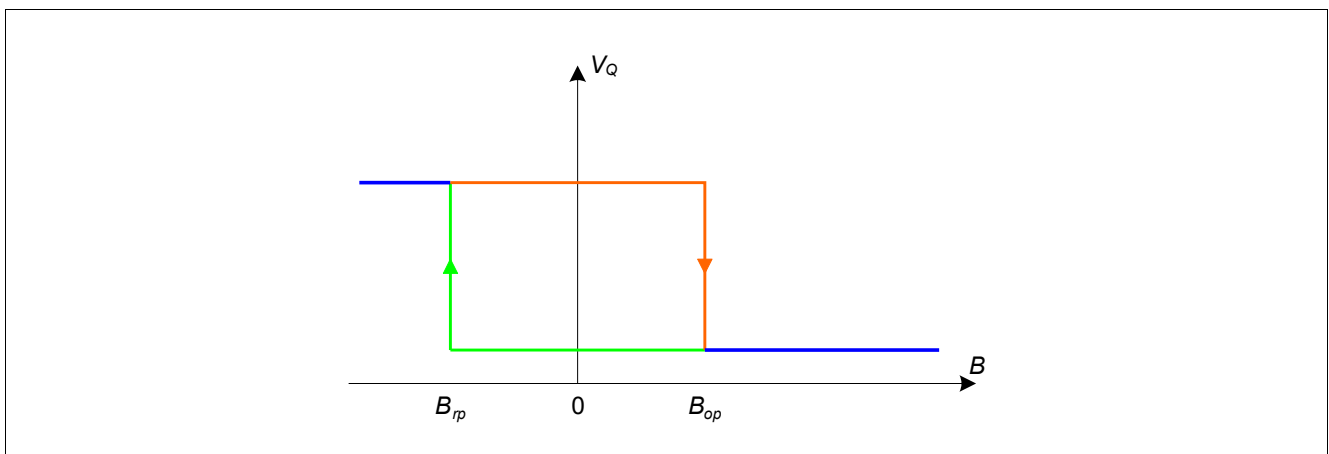


Figure 4 Output Signal

## 2.6 Functional Block Description

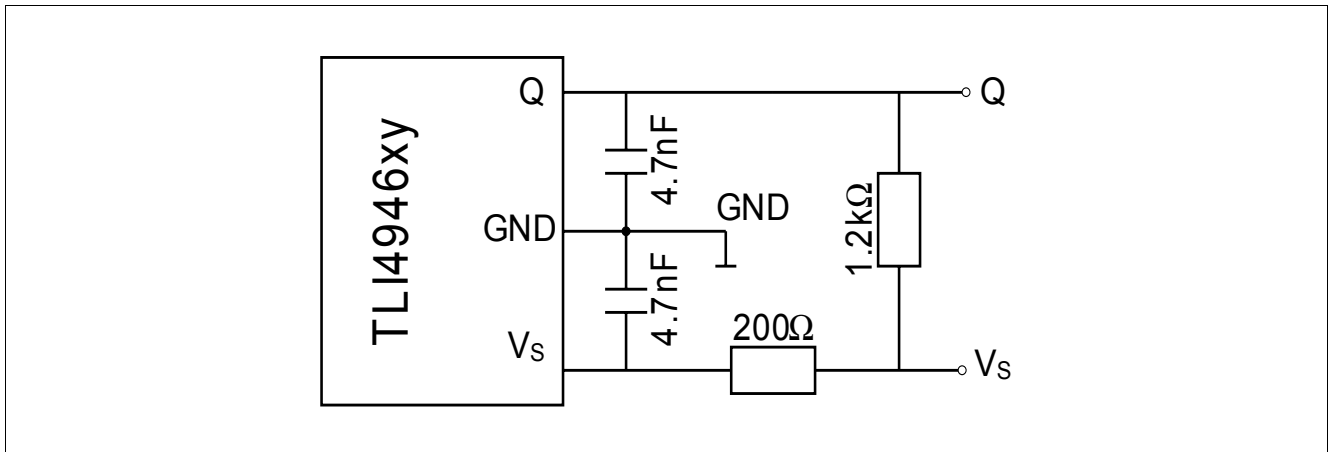
The chopped Hall Effect Latch comprises a Hall probe, a bias generator, compensation circuits, an oscillator and an output transistor. The bias generator provides currents to the Hall probe and the active circuits. Compensation circuits stabilize response of the IC over temperature and reduce the impact of process variations.

The Active Error Compensation rejects offsets in the signal path and reduces the impact of mechanical stress in the package caused by molding, soldering and thermal effects.

The chopper technique together with the threshold generator and the comparator ensure high accurate magnetic switching points.

### 3 Specification

#### 3.1 Application circuit



**Figure 5 Application circuit**

It is recommended to use a resistor of 200  $\Omega$  in the supply line for current limitation in the case of an overvoltage pulse. Two capacitors of 4.7 nF enhance the EMC performance. The pull-up of 1.2 k $\Omega$  limits the current through the output transistor.

#### 3.2 Absolute Maximum Ratings

Stress above the maximum values listed in this section may cause permanent damage to the device. Exposure to absolute maximum rating conditions for extended periods may affect the reliability of the device. Exceeding only one of these values may cause irreversible damage to the device.

**Table 3 Absolute Maximum Ratings**

| Parameter                                      | Symbol                    | Values |      |           | Unit               | Note / Test Condition |
|--|---------------------------|--------|------|-----------|--------------------|-----------------------|
|  |                           | Min.   | Typ. | Max.      |                    |                       |
| Maximum Ambient Temperature                    | $T_A$                     | - 40   | –    | 125       | $^{\circ}\text{C}$ |                       |
| Maximum Junction Temperature                   | $T_J$                     | - 40   | –    | 150       | $^{\circ}\text{C}$ |                       |
| Supply Voltage                                 | $V_S$                     | - 18   | –    | 18        | V                  |                       |
| Supply current through protection device       | $I_S$                     | -50    | –    | 50        | mA                 |                       |
| Output Voltage                                 | $V_{\text{OUT}}$          | - 0.7  | –    | 18        | V                  |                       |
| Storage Temperature                            | $T_S$                     | - 40   | –    | 150       | $^{\circ}\text{C}$ |                       |
| Magnetic flux density                          | $B$                       | –      | –    | unlimited | mT                 |                       |
| ESD Robustness HBM:<br>1.5 k $\Omega$ , 100 pF | $V_{\text{ESD,HBM}}^{1)}$ | –      | –    | 4         | kV                 |                       |

1) According to EIA/JESD22-A114-E

### 3.3 Operating Range

The following operating conditions must not be exceeded in order to ensure correct operation of the TLI4946xy. All parameters specified in the following sections refer to these operating conditions unless otherwise mentioned.

**Table 4 Operating Range**

| Parameter                   | Symbol | Values |      |      | Unit | Note / Test Condition |
|-----------------------------|--------|--------|------|------|------|-----------------------|
|                             |        | Min.   | Typ. | Max. |      |                       |
| Supply Voltage              | $V_S$  | 2.7    | –    | 18   | V    |                       |
| Output Voltage              | $V_Q$  | -0.7   | –    | 18   | V    |                       |
| Output Current              | $I_Q$  | 0      | –    | 20   | mA   |                       |
| Maximum Ambient Temperature | $T_A$  | -40    | –    | 125  | °C   |                       |

### 3.4 Electrical Characteristics

Product characteristics include the spread of values guaranteed within the specified voltage and ambient temperature range. typical characteristics are the median of the production (at  $V_S=12V$  and  $T_A=25^\circ C$ ).

**Table 5 Electrical Characteristics**

| Parameter  | Symbol      | Values |      |                  | Unit          | Note / Test Condition                        |
|--|-------------|--------|------|------------------|---------------|--|
|  |             | Min.   | Typ. | Max.             |               |  |
| Supply Current                                       | $I_S$       | 2      | 4    | 6                | mA            | $V_S=2.7 V \dots 18 V$                       |
| Reverse Current                                      | $I_{SR}$    | 0      | 0.2  | 1                | mA            | $V_S=-18 V$                                  |
| Output Saturation Voltage                            | $V_{QSAT}$  | –      | 0.3  | 0.6              | V             | $I_Q=20 mA$                                  |
| Output leakage current                               | $I_{QLEAK}$ | –      | 0.05 | 10               | $\mu A$       | $V_Q=18 V$                                   |
| Output fall time <sup>1)</sup>                       | $t_f$       | –      | 0.02 | 1                | $\mu s$       | $R_L=1.2k \Omega, C_L=50 pF$                 |
| Output rise time <sup>1)</sup>                       | $t_r$       | –      | 0.4  | 1                | $\mu s$       |  |
| Chopper frequency                                    | $f_{OSC}$   | –      | 320  | –                | kHz           |  |
| Switching frequency                                  | $f_{SW}$    | 0      | –    | 15 <sup>2)</sup> | kHz           |  |
| Delay time <sup>3)</sup>                             | $t_d$       | –      | 13   | –                | $\mu s$       |  |
| Output jitter <sup>4)</sup>                          | $t_{QJ}$    | –      | 1    | –                | $\mu s_{RMS}$ | Typical value for a 1 kHz square wave signal |
| Power-on Time <sup>5)</sup>                          | $t_{PON}$   | –      | 13   | –                | $\mu s$       | $V_S > 2.7 V$                                |
| Thermal Resistance junction to ambient <sup>6)</sup> | $R_{thja}$  | –      | 100  | –                | K/W           | TLI4946K, TLI4946-2K                         |
|  |             | –      |      | 190              | K/W           | TLI4946-2L                                   |

1) See [Figure 6](#)

2) To operate the sensor at maximum switching frequency, the value of the magnetic signal amplitude must be 1.4 times higher than the static fields. This is due to the -3 dB corner frequency of the low pass filter in the signal path.

3) Systematic delay between magnetic threshold reached and output.

4) Jitter is the unpredictable deviation of the output switching delay.

5) Time from applying  $V_S > 2.7 V$  to the sensor until the output state is valid.

6) Relationship between junction and ambient temperature:  $T_J = T_{amb} + R_{thja} \cdot (V_S \cdot I_S + V_{QS} \cdot I_Q)$ .

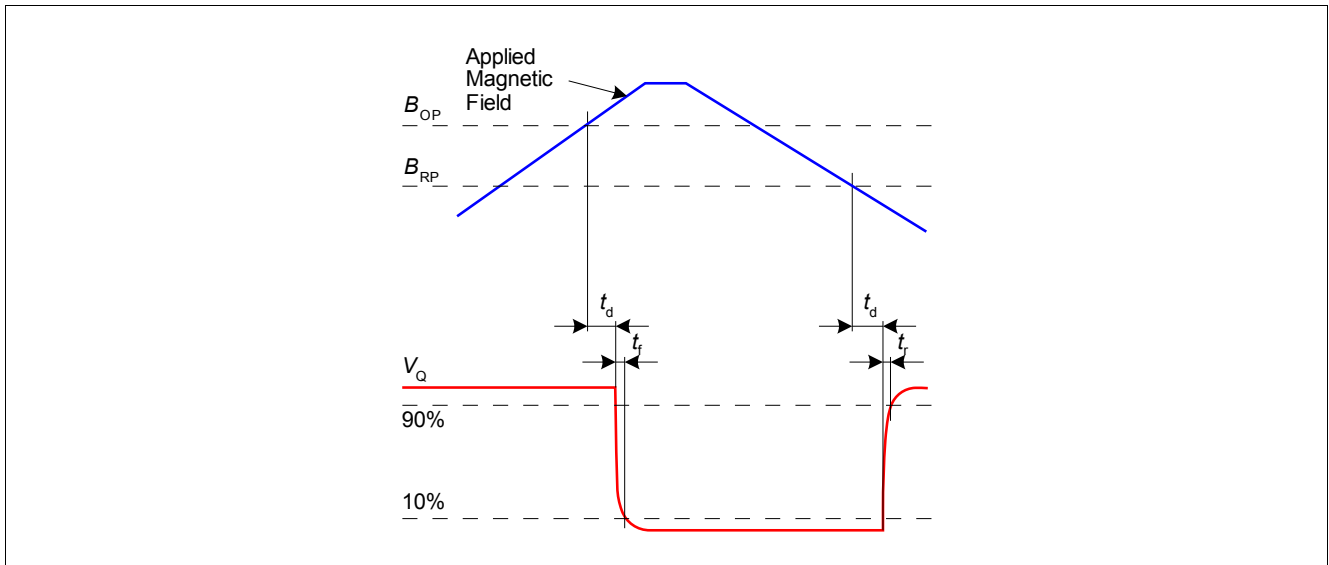


Figure 6 Timing Diagram

Table 6 Magnetic Characteristics<sup>1)</sup>

| Parameter  | Symbol    | Values |       |      | Unit          | Note / Test Condition                           |
|--|-----------|--------|-------|------|---------------|---|
|  |           | Min.   | Typ.  | Max. |               |   |
| Operate point                                      | $B_{OP}$  | 6.1    | 14.0  | 19.2 | mT            | TLI4946K  |
|  |           | 0.5    | 2.0   | 3.5  | mT            | TLI4946-2K, TLI4946-2L                          |
| Release point                                      | $B_{RP}$  | -19.2  | -14.0 | -6.1 | mT            | TLI4946K  |
|  |           | -3.5   | -2.0  | -0.5 | mT            | TLI4946-2K, TLI4946-2L                          |
| Hysteresis   | $B_{HYS}$ | 22.0   | 28.0  | 34.0 | mT            | TLI4946K <sup>2)</sup>                          |
|  |           | 1.0    | 4.0   | 6.0  | mT            | TLI4946-2K, TLI4946-2L                          |
| Magnetic offset <sup>3)</sup>                      | $B_{OFF}$ | -3.0   | –     | 3.0  | mT            | TLI4946K <sup>2)</sup>                          |
|  |           | -1.5   | 0     | 1.5  | mT            | TLI4946-2K, TLI4946-2L                          |
| Temperature compensation of magnetic thresholds    | $TC$      | –      | -2000 | –    | ppm/°C        | TLI4946K  |
|  |           | –      | -350  | –    | ppm/°C        | TLI4946-2K, TLI4946-2L                          |
| Repeatability of magnetic thresholds <sup>4)</sup> | $B_{REP}$ | –      | 20    | –    | $\mu T_{RMS}$ | typical value for $\Delta B/\Delta t > 12mT/ms$ |

1) Over all operating conditions

2) at 25°C.

3)  $B_{OFF} = (B_{OP} + B_{RP}) / 2$ .

4)  $B_{REP}$  is equivalent to the noise constant.

## 4 Package Information

### 4.1 TLI4946K and TLI4946-2K Package Outline

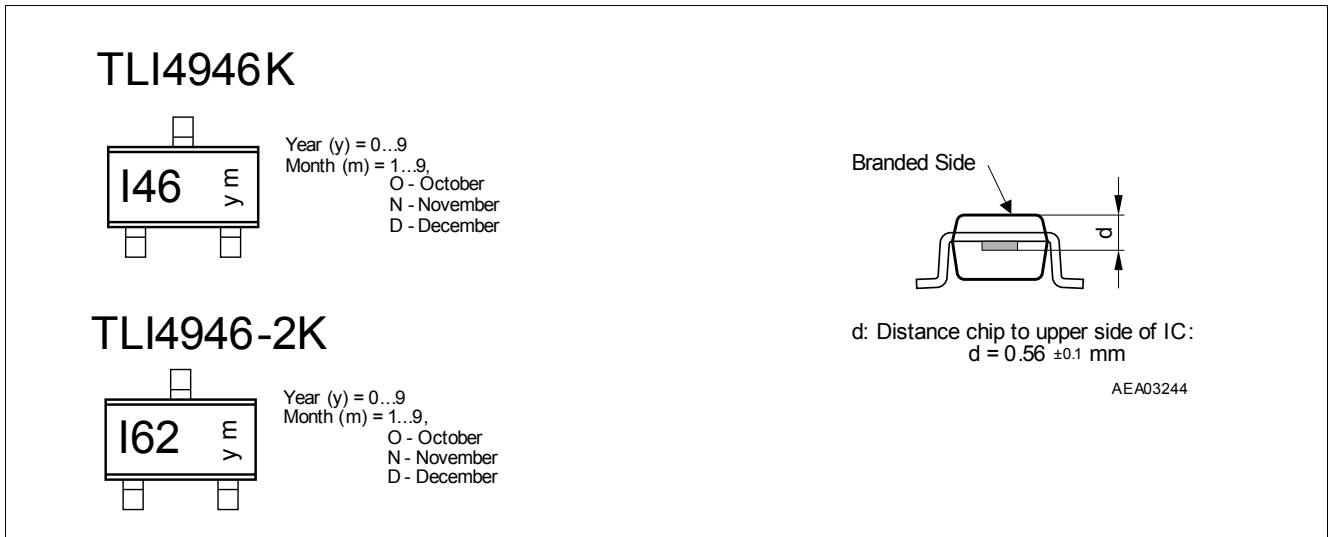


Figure 7 Marking of the TLI4946K and TLI4946-2K distance of the chip to the upper side

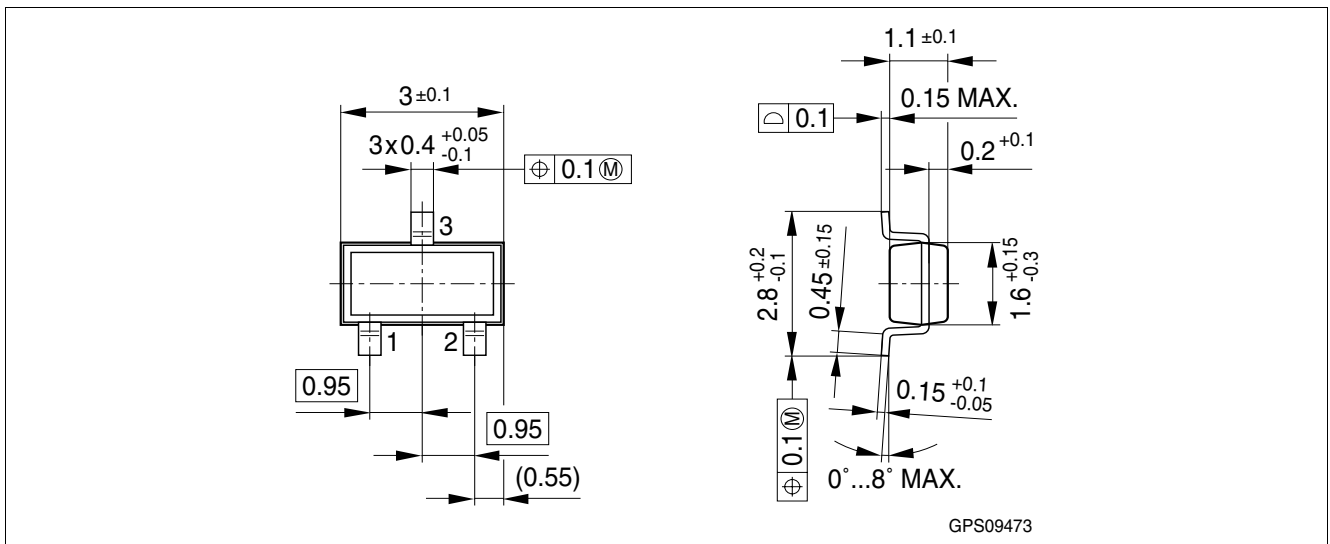


Figure 8 PG-SC59-3-4 Package Outline

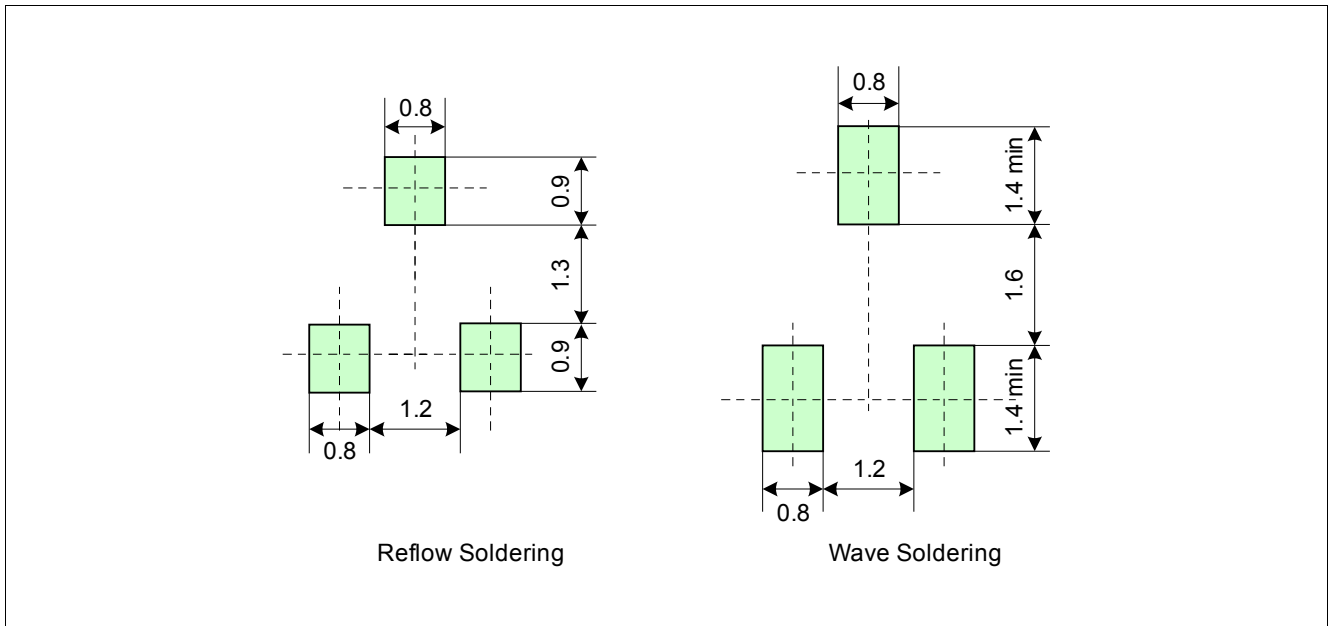


Figure 9 Footprint PG-SC59-3-4 (SOT23 compatible)

#### 4.2 TLI4946-2L Package Outline

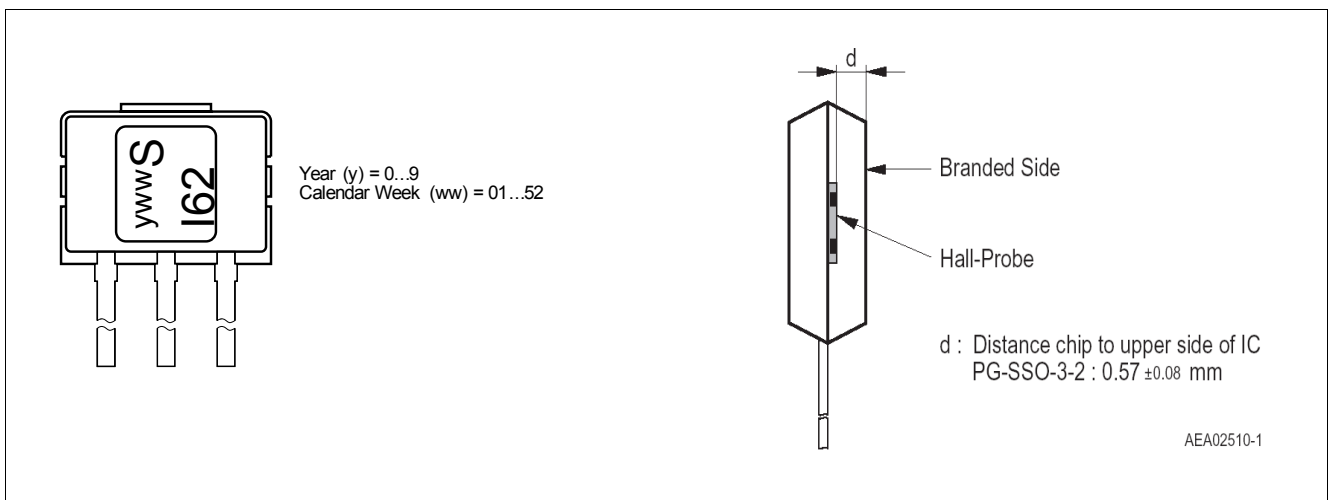


Figure 10 Marking of the TLI4946-2L and distance of the chip to the upper side

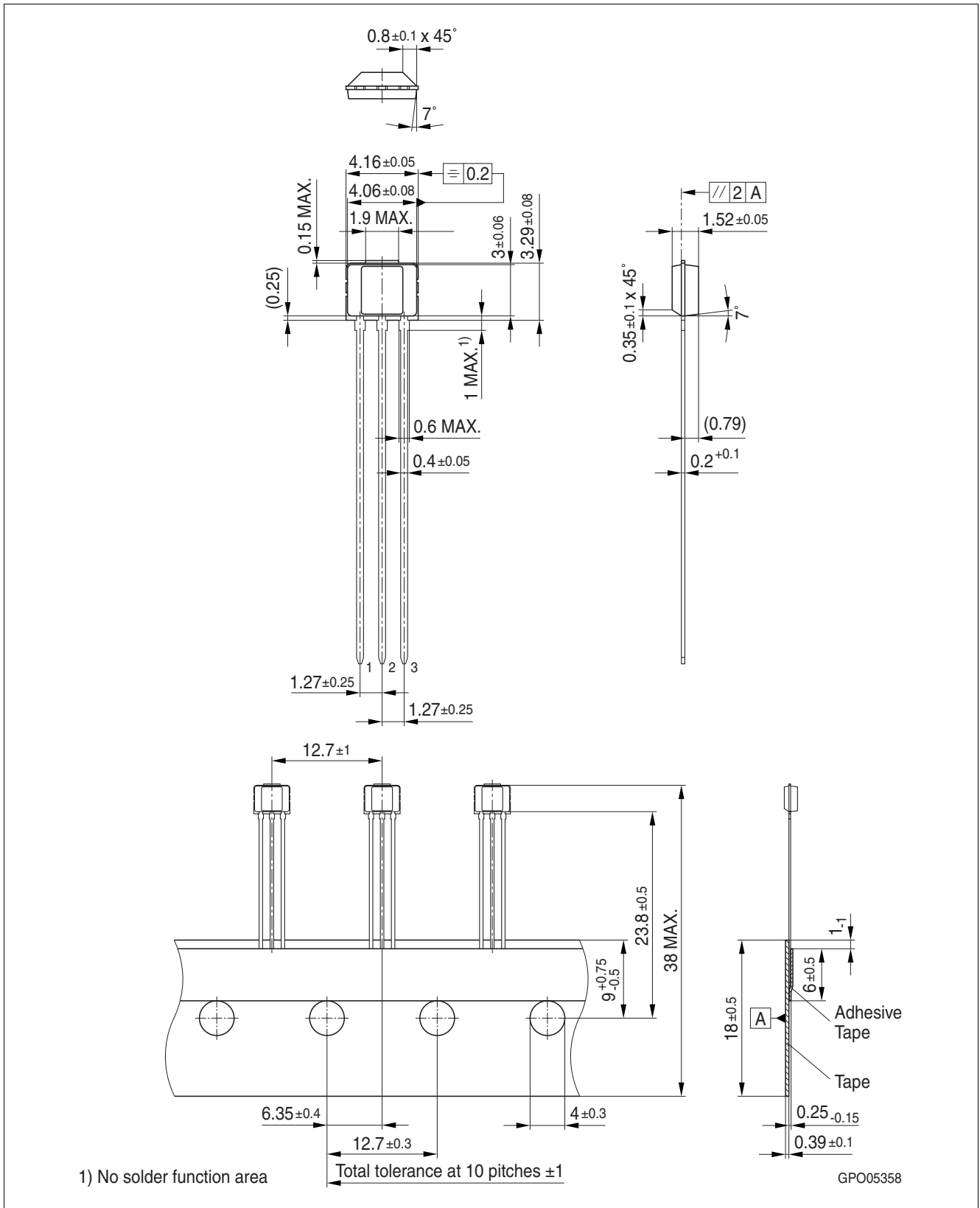


Figure 11 PG-SSO-3-2 Package Outline



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Факс: 8 (812) 320-03-32

Электронная почта: [ocean@oceanchips.ru](mailto:ocean@oceanchips.ru)

Web: <http://oceanchips.ru/>

Адрес: 198099, г. Санкт-Петербург, ул. Калинина, д. 2, корп. 4, лит. А