



Important Notes

Restrictions in Use

IDT's ZSSC3154 SSC Evaluation Kit, consisting of the Communication Board (SSC CB), the ZSSC3154 Evaluation Board (SSC EB), and the calibration software, is designed for sensor module evaluation, laboratory setup, and module calibration development only.

The SSC Mass Calibration System is designed only for development, evaluation, and laboratory setup of sensor modules with IDT Sensor Signal Conditioner ICs. The IDT Mass Calibration System hardware and software must not be used for module production and production test setups.

IDT's Evaluation Kit hardware and software must not be used for module production or production test setups.

Disclaimer

IDT shall not be liable for any damages arising out of defects resulting from

- (i) delivered hardware or software
- (ii) non-observance of instructions contained in this manual and in any other documentation provided to user, or
- (iii) misuse, abuse, use under abnormal conditions, or alteration by anyone other than IDT.

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1 Introduction

This document covers the use of the ZSSC3154 Evaluation Kit and the ZSSC3154 Mass Calibration System (MCS) with the ZSSC3154 Evaluation Kit Software including hardware setup. Kit contents for the ZSSC3154 Evaluation Kit are provided in section 2. Refer to section 7 for the contents of the ZSSC3154 MCS. Also see the *Mass Calibration Board Data Sheet* for full details for the MCS.

2 SSC Evaluation Kit Contents and Overview

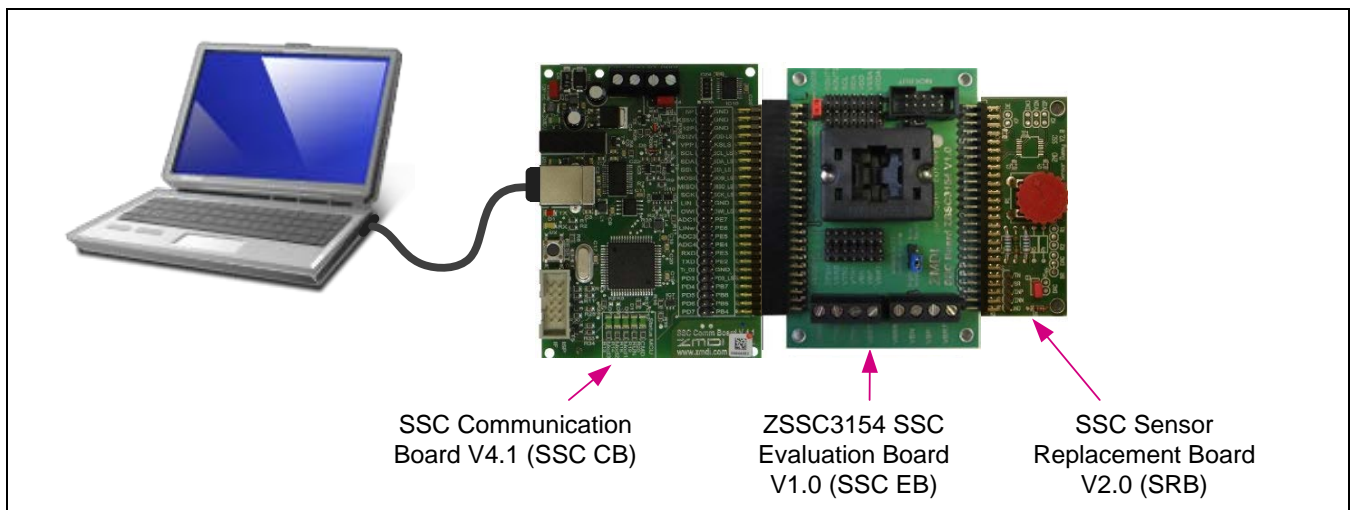
The ZSSC3154 Evaluation Kit consists of the following parts:

- SSC Communication Board (SSC CB) V4.1 (including USB cable) †
- ZSSC3154 SSC Evaluation Board (SSC EB) V1.0
- SSC Sensor Replacement Board (SRB) V2.0
- 5 samples of the ZSSC3154xA2T (QFN32 5x5mm)

Note: The ZSSC3154 Evaluation Kit Software is downloaded from www.IDT.com/ZSSC3154KIT as described in section 4.1.

If the SSC CB revision is V3.3 or earlier, installation of a USB driver is required before installing the software (refer to section 4.2).

Figure 2.1 ZSSC3154 SSC Evaluation Kit



The SSC Evaluation Kit contains the hardware needed for communication and calibration of ZSSC3154 sensor signal conditioning ICs. A PC can communicate with the ZSSC3154 via the Communication Board (SSC CB) through a USB connection. The Sensor Replacement Board (SRB) provides a replacement for an actual sensor and can be used for the first step of calibration or a dry-run calibration as described in section 5. On the SRB, the sensor replacement signal is controlled by a potentiometer (see Figure 5.1).

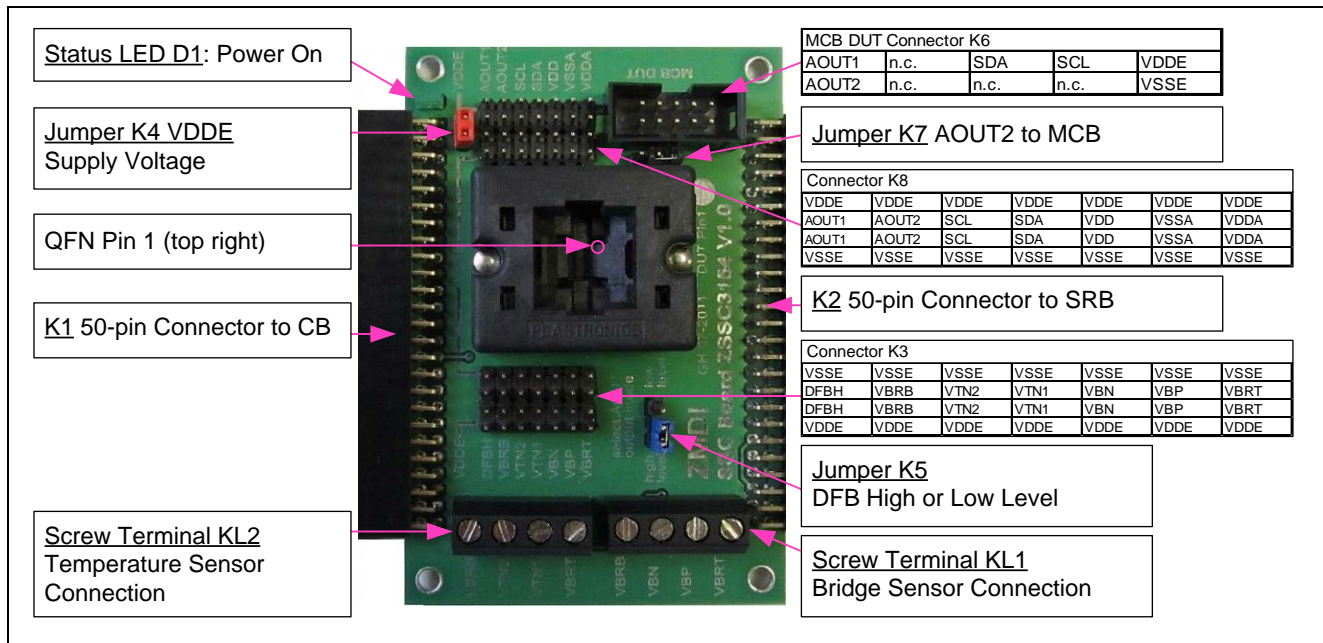
The software will run under Windows® 98/ME/XP/NT/Vista/Windows® 7/Windows® 8 operation systems.

† For detailed information about SSC Communication Board, please refer to the *SSC Communication Board Data Sheet* available on the IDT website at <http://www.IDT.com>.

3 ZSSC3154 Evaluation Board

3.1. Overview

Figure 3.1 ZSSC3154 SSC Evaluation Board – Overview



The main purpose of the SSC Evaluation Kit is communication between the user's PC and the ZSSC3154. The PC sends commands and data via its USB port (configured as a virtual COM port) to the SSC CB. The microcontroller on the SSC CB interprets these commands and relays them to the ZSSC3154 in the I²C™[‡] or OWI (One-Wire Interface) communication mode. The microcontroller will also forward any data bytes from the ZSSC3154 back to the PC via the USB connection. These bytes can be sensor and temperature readings to be displayed by the PC software, raw ADC data used during calibration, or EEPROM data. The SSC CB microcontroller controls the power signals required for entering the Command Mode.

3.2. Schematic

Figure 2.2 shows the schematic of the ZSSC3154 SSC Evaluation Board (SSC EB). The SSC EB is powered by the KS5V supply controlled by the μ C on the SSC CB. The D1 green LED on the SSC EB displays the status of this supply (see Figure 3.1). Its forward current is not included in the measured supply current.

The SSC EB board type is hard-coded by three resistors on the backside of the PCB on **K1** connector pins D5 (low), D6 (low), and D7 (high). The SSC EB is connected to the SSC CB via the **K1** 50-pin female connector.

The SRB can be connected to the SSC EB via its **K2** 50-pin male connector. Alternatively, an external bridge sensor element and external temperature sensors can be connected using the on-board screw terminal **KL1/KL2**.

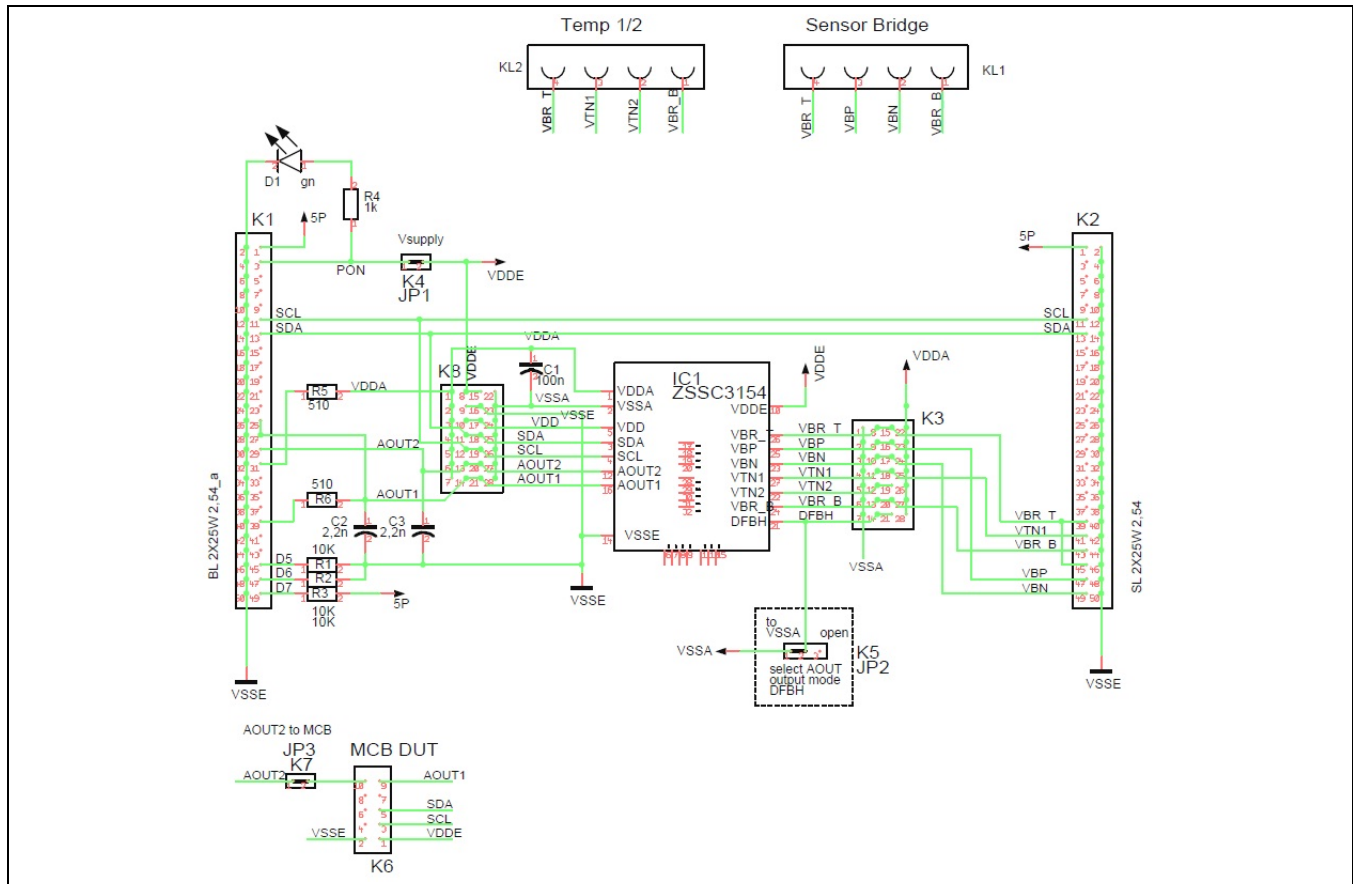
On-board there are several strips for simple access to all IC signals (connectors **K3** and **K8**).

[‡] I²C™ is a trademark of NXP.

The **K4** jumper can be used to remove the power supply for the ZSSC3154 manually or for a simple measurement of the supply current. The **K5** jumper is used to determine the Diagnostic Fault Band Mode (DFB) for the AOUT voltage level. If left open, the level is low (DFBL); if shorted to ground, the level is high (DFBH).

The output signal of AOUT2 can also be connected to pin10 on K6 if jumper **K7** is shortened.

Figure 3.2 SSC Evaluation Board Schematic



3.3. Connections to the ZSSC3154

The SSC EB has a QFN-32 socket for inserting the QFN 5x5 ZSSC3154. The K8 connector on the SSC EB can be used to connect directly to the ZSSC3154 for in-circuit programming.

NOTE: Only one ZSSC3154 connection option can be used at a time through the SSC CB or via individual connections.

Multiple ZSSC3154 can be connected through the Mass Calibration Board (MCB) via individual connections or through the ZSSC3154 EB connector K6. For more details, see section 6.

3.4. Reset Switch

Use the push button on the SSC CB to reset communications if needed.

4 ZSSC3154 Software

4.1 Overview and Installation

The ZSSC3154 Evaluation Software is intended for demonstration purposes and calibration of single units using the ZSSC3154 Evaluation Kit. It can also be used for calibrating multiple units using the Mass Calibration System (MCS) as described in section 6. This section gives installation instructions and a short overview of the variety of ways to use the Evaluation Software. For calibration examples using the complete SSC Evaluation Kit, refer to section 5. IDT can provide users with algorithms and assistance in developing their full production calibration software.

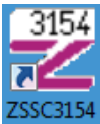
Note: If using a previous revision SSC CB, see section 4.2 regarding USB drivers that must be installed prior to the ZSSC3154 Evaluation Software.

The ZSSC3154 Evaluation Kit does not include the software, which must be downloaded from IDT's website to ensure receiving the latest release.

To download and install the software:

1. Download the software from the website www.IDT.com/ZSSC3154KIT
2. Open the zip file and extract the executable file `ZSSC3154_SW_Rev.X.xxx.exe`.
3. To install the software on the user's PC hard drive, double-click on the downloaded *extracted* executable file. Respond to the dialog box to select the installation directory. The default software installation folder is `C:\program files\ZMD\ZSSC3154`.

The software will automatically complete the installation, which results in a program shortcut on the PC's desktop:



The software logs various data and commands into log files as described in section 4.3.

The software contains five menus that are intended for the following functions:

- Main Window: IC setup, configuration, and communication via check boxes, entry fields, and pull-down menus
- RAM/EEPROM Dialog: Direct access to RAM/EEPROM registers (consecutively numbered)
- Calibration Dialog: Acquisition of raw values from sensor and calculation of coefficients
- Get Raw Values Dialog: Special Dx commands for the ZSSC3154[§]
- Send Command Dialog: Low-level write/read communication with SSC CB^{**}

[§] For details about the Dx commands, refer to the *ZSSC3154 Functional Description*.

^{**} For details about SSC CB command structure, refer to the *SSC Communication Board Data Sheet* and *SSC Command Syntax Spreadsheet*.

4.2. USB Driver Installation

USB driver installation is not applicable to the current version ZSSC3154 Evaluation Kit because it includes the current version of the SSC CB (rev. 4.1). This also applies to the MCS. The USB driver installation is only required if the CB revision is the previous version V3.3 or earlier. For more information, refer to the SSC *Application Note – Communication Board Driver Installation* available on <http://www.IDT.com>.

4.3. User Files

User files are saved in *[Program Files]\ZMDI\ZSSC3154* and consist of log files and EEPROM files:

- *ZSSC3154_*.log* is a communication log file created when the connection between the SSC CB and the ZSSC3154 is established (via OWI or I²C™^{††} interface). To enable logging, after activating the software, navigate to “Calibration” > “Send Command” and check the box for “logFile.” This file is a log of the communication to the ZSSC3154 during the software session, and it can be saved after closing the software by renaming the file. Otherwise, it is overwritten the next time the software is opened.
- *save_[date]_[time].3154* is a log file containing the ZSSC3154 settings and acquired RAW data. This file can be used to load/save EEPROM contents.
- *save_[date]_[time].3154.txt* is a log file in text format containing the ZSSC3154 settings and acquired RAW data. This file can be used to view the EEPROM contents.

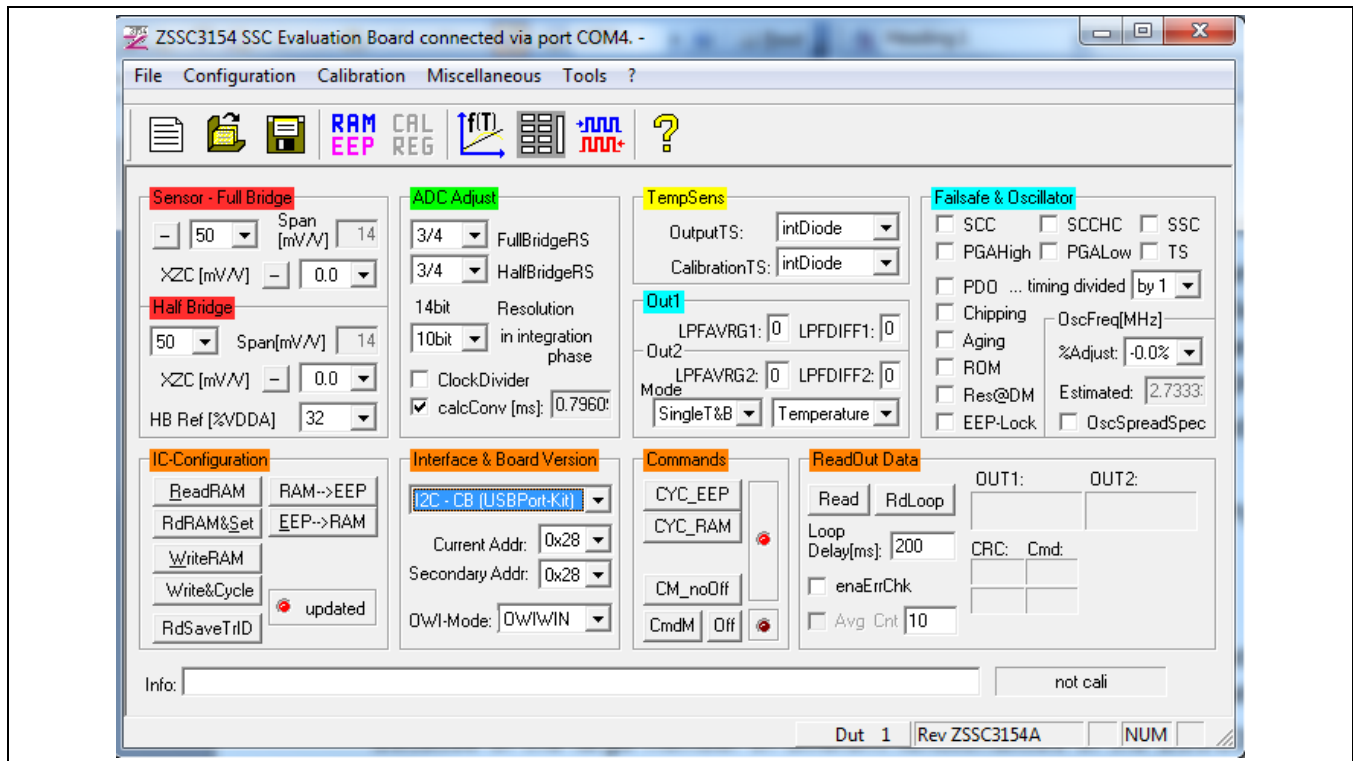
^{††} I²C is a registered trademark of NXP.

4.4. General Setup of the Software

The software features described in this section are applicable to both the ZSSC3154 Evaluation Kit and the ZSSC3154 MCS.

Because of the large number of different functionalities of the ZSSC3154, the user interface is divided into different sections. Within each section, a number of associated functionalities are implemented. Several submenus allow access to sub-functionalities. After the ZSSC3154 Evaluation Software is started, the main window is displayed (see Figure 4.1). When communication is established with a ZSSC3154 inserted in the socket on the SSC EB, the software can be adapted to the IC's configuration by clicking the **RdRAM&Set** button on the main window in the "IC Configuration" section.

Figure 4.1 Main Window of the Evaluation Software



The main window includes all the settings for configuration of the ZSSC3154 in a clear structure that hides the corresponding HEX commands behind buttons and drop-down menus. For a detailed description of the commands, refer to the *ZSSC3154 Functional Description*. An information box that explains functionality appears when the cursor is placed over most buttons, drop-down menus, and check boxes.

4.4.1. Interface Selection

The ZSSC3154 supports two interfaces: OWI and I²C™ (see Figure 4.2). After starting the software, select the interface for the application in the “Interface & Board Version” section. (“USBPort-Kit” refers to the ZSSC3154 Evaluation Kit.)

The one-wire digital interface (OWI) combines a simple and easy protocol adaptation with a cost-saving pin sharing (AOUT1). The communication principle is derived from the I²C™ protocol. An advantage of OWI output signal capability is that it enables “end-of-line” calibration. It is designed mainly for calibration, but it can also be used to digitally read the calibrated sensor signal continuously.


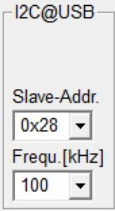
Adjacent to the drop-down menu for the interface is a menu for selecting the I²C™ addresses to be used for communication.

If the I²C™ interface is selected, additional settings for the I²C™ interface are enabled in the “Send Command” dialog window. For more details about the “Send Command” menu, see section 4.10.

Figure 4.2 Interface Selection Section



Figure 4.3 Additional I²C™ and OWI Interface Settings in the “Send Command” Menu

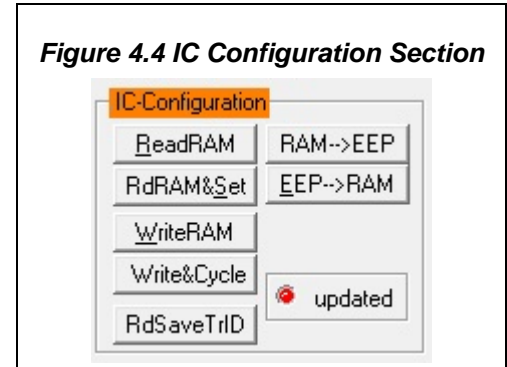
The “Send Command” button in the top menu	Resulting addition to “Send Command” dialog window if I ² C™ interface is selected	Resulting addition to “Send Command” dialog window if OWI interface is selected
		

4.4.2. ZSSC3154 Configuration

The “IC Configuration” section includes the following buttons:

- **ReadRAM** : reads the complete RAM contents and updates only the “RAM_Register” menu.
- **RdRAM&Set** : reads the complete RAM contents and updates all of the ZSSC3154 software.
- **Write RAM** : copies the current software settings into the RAM of the ZSSC3154.
- **RAM-->EEP** : copies the RAM contents into EEPROM. The free-user-memory registers (19_{HEX} & 1A_{HEX}) will also be copied using the contents of the IDT software registers^{††}.
- **EEP-->RAM** : copies the EEPROM contents into RAM using the C0_{HEX} command.
- **Write&Cycle** : copies the current software settings into the RAM of the ZSSC3154 and starts the measurement cycle using the current RAM settings (command: 02_{HEX}^{§§}).
- **RdSaveTrID** : Read and save traceability information (the contents of two free-user-memory registers 19_{HEX} and 1A_{HEX}).

Figure 4.4 IC Configuration Section



The “updated” virtual LED in the “IC Configuration” section displays the software configuration status compared to the attached ZSSC3154’s register content. If the content is identical, the LED is green (on).

4.4.3. Analog Front End (AFE) Adjustment

The ZSSC3154 has different options to adapt the analog front end (AFE) to the specific sensing element. The “Sensor - Full Bridge” and “Half Bridge” sections (shown in Figure 4.5) influence the programmable gain amplifier (PGA) and extended zero compensation.

The sensor’s span or sensitivity is defined by mV/V and is referenced to the bridge supply voltage.

Different reference voltages can be selected for the half bridge, which are entered as a percentage of the positive analog supply voltage (VDDA).

Refer to the *ZSSC3154 Data Sheet* for details about the AFE and XZC settings.


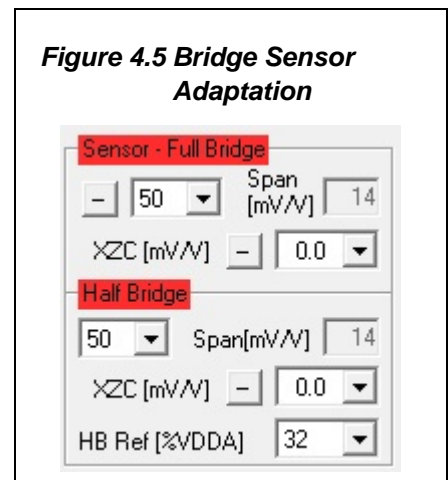
The polarity of the sensor signal can be selected via the  button and can be changed if the PCB layout requires swapped input pins.

Figure 4.5 Bridge Sensor Adaptation



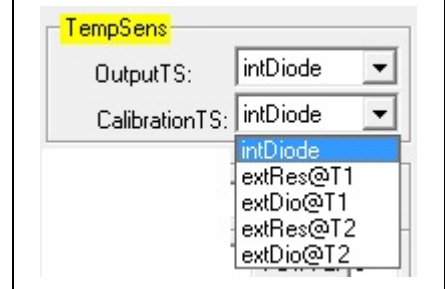
^{††} The contents of the “RAM-Register” dialog will be used for free-user-memory registers.

^{§§} For details about ZSSC3154 commands, refer to the *ZSSC3154 Functional Description*.

4.4.4. Temperature Sensor Selection

The next stage in the AFE is the multiplexer that selects the input signal for measuring temperature (see Figure 4.6). The ZSSC3154 can use three different temperature channels: one internal and two external. Each input can be used for calibration calculation. External temperature sensors can be used as an optional additional output signal during Normal Operating Mode (NOM).

Figure 4.6 Temperature Sensor



4.4.5. ADC Settings

The last stage of the ZSSC3154's AFE is the analog-to-digital converter (ADC). The signal path within the AFE is designed in fully differential switched capacitor technology with a selectable resolution of 13 or 14 bits. The ADC input must be within 10% to 90% of the ADC range of the application.

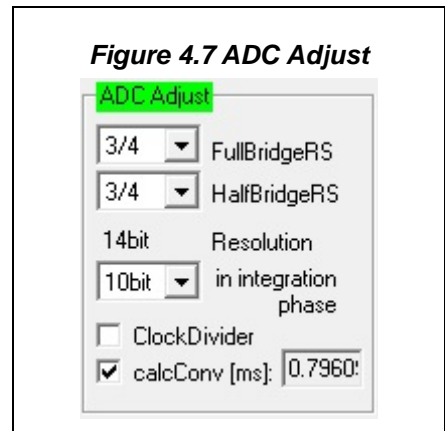
Refer to the *ZSSC3154 Data Sheet* for details about ADC settings.

If the analog input voltage does not fit the ADC range resulting in an underflow or overflow, the “FullBridgeRS” or “HalfBridgeRS” drop-down menus in the “ADC Adjust” section can be used to fine-tune the range shift of the full bridge or half bridge inputs respectively (see Figure 4.7). A lower “Span (mV/V)” setting (see section 4.4.3) can also be useful for fitting the ADC range.

The “Resolution in integration phase” drop-down menu allows adjusting the ADC resolution for the first step of the conversion integration phase, which influences the integration time. Select a conversion time that is as long as possible to secure a high degree of noise suppression.

If enabled, the clock divider makes the ADC operate with half of the clock frequency. This increases accuracy and linearity.

Figure 4.7 ADC Adjust

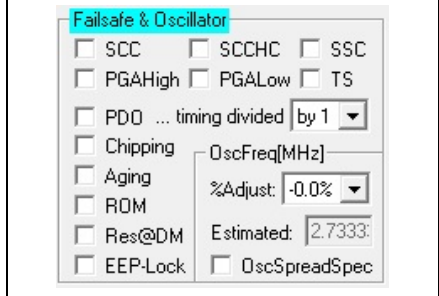


4.4.6. Application Settings

The internal microcontroller of the ZSSC3154 can detect various errors and perform different types of measurement cycles. It controls multiple protection options that can be configured by the ZSSC3154 Software.

Figure 4.8 illustrates all the application options for the ZSSC3154, which can be enabled/disabled via the checkboxes. The example in Figure 4.8 shows the ZSSC3154 settings with no options enabled. For more details about the related options, refer to the *ZSSC3154 Functional Description*.

Figure 4.8 Application and Settings



SCC : Enables Sensor Connection Check.

SCCHC : Enables Sensor Connection Check (SCC) high-capacity mode.

SSC : Enables Sensor Short Check.

PGAHigh : Main sensor channel data validation upper limit check.

PGALow : Main sensor channel data validation lower limit check.

TS : Temperature sensor channel data validation check.

PDO: Power-on Diagnostic Mode. A sequence of upper limit, lower limit, and diagnostic range is output at startup.

Chipping : Broken chip check.

Aging : Enables Sensor Aging Check.

ROM : Enables ROM check after power-on. If ROM check is enabled, the start-up time will be increased approximately 10ms.

Res@DM : If enabled, the ZSSC3154 is reset if the ZSSC3154 enters the Steady Diagnostic Mode.

EEP-Lock : Enables EEPROM lock for OWI communication. If enabled, the EEPROM cannot be changed via the OWI interface and must be reset via the I²C™ interface.

Oscillator Frequency (OscFreq[MHz] section):

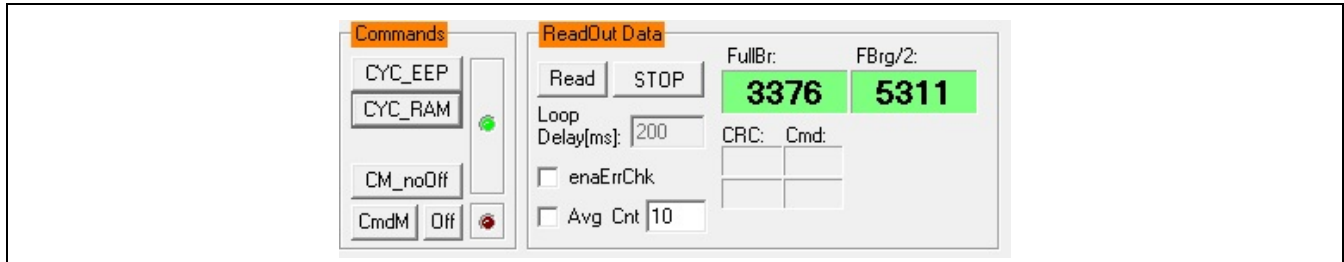
%Adjust: Clock frequency adjustment. An estimate of the clock frequency is displayed in MHz.

OscSpreadSpec : Oscillator spread spectrum mode. Using the Oscillator Spread Spectrum Mode reduces electromagnetic emission (EME).

4.5. Operation Section

The “Commands” and “ReadOut Data” sections control the collection of data and configuration of the ZSSC3154.

Figure 4.9 Normal Operation Section



4.5.1. Normal Operation Mode (NOM)

In the “Commands” section, use the **CYC_EEP** or **CYC_RAM** button to exit Command Mode (CM) and start NOM using either the EEPROM or RAM registers settings, respectively. In NOM, the ZSSC3154 continually performs the measurement cycle and displays the results in the adjacent “ReadOut Data” section. The top virtual status LED, which is green when the IC is running in NOM, is updated accordingly.

4.5.2. Command Mode (CM)

In the “Commands” section, use the **CmdM** button to start the Command Mode of the ZSSC3154 by sending the Start_CM command (0x7274) to the ZSSC3154.

4.5.3. Power IC OFF

The **Off** button in the “Commands” section can be used to power off the ZSSC3154. If the **Off** button is clicked, all communication interfaces are disabled, so no further communication is possible until the **CmdM** button is pressed (entering the Command Mode) or an interface is selected. In both cases, the ZSSC3154 will be powered on and communication established. The virtual LEDs indicate whether the ZSSC3154 is in Command Mode (CM) or running in Normal Operation Mode (NOM).

4.5.4. Data Read-Out

The **Read** and **RdLoop** buttons in the “ReadOut Data” section (see Figure 4.1) start a read-out of sensor data. When a loop measurement is started, the button text will change to **STOP** (see Figure 4.9). Clicking again on the button stops the loop. The “Loop Delay” field sets the rate in milliseconds of the readouts in the loop mode.

4.5.5. Enable Error Check

The **enaErrChk** checkbox in the “Read Out Data” section enables the error checks selected in the “Application & Settings” section (section 4.4.6). An error message is processed if any of the errors selected occur.

4.5.6. Average Count and Statistics

The **Avg Cnt** checkbox in the “ReadOut Data” section starts the averaging and statistics calculations. It is only enabled if the measurement is in a loop mode. The resulting data is displayed in the adjacent fields after the specified cycles in the field are passed.

4.6. Operational Modes

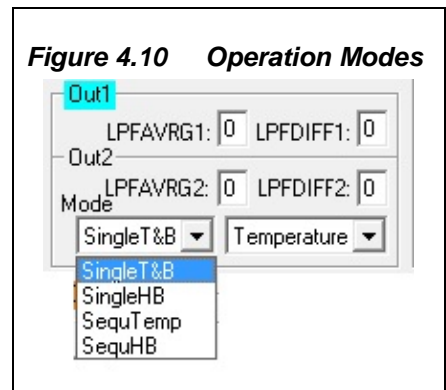
ZSSC3154 provides several AOUT2 output modes based on the EEPROM settings. The AOUT2 output is selected by the “Mode” drop-down menu under “Out2” (see Figure 4.10 and Table 4.1).

The AOUT1 output always represents the calibrated sensor signal. Digital filter settings can also be adjusted in this section with the LPFAVRG and LPFDIFF fields for each output in the range of 0 to 7. For more details refer to the *ZSSC3154 Functional Description*.

Note: It is recommended that both outputs have the same filter settings for LPFAVRG and LPFDIFF.

Table 4.1 Operational Modes for the AOUT2 Output

AOUT2 Mode	Mode Setting	AOUT2 Sensor Output Options
Single Temperature and Bridge Signal	SingleT&B	Temperature
		1-Bridge
		Bridge/2
		(1-Bridge)/2
Single Half Bridge	SingleHB	Half Bridge
Sequential Temperature	SequTemp	Temperature & Bridge Sensor
		Temperature & (1 - Bridge Sensor)
		Temperature & (Bridge Sensor)/2
		Temperature & (1 - Bridge Sensor)/2
Sequential Half Bridge	SequHB	Half Bridge & Bridge Sensor
		Half Bridge & (1 - Bridge Sensor)
		Half Bridge & (Bridge Sensor)/2
		Half Bridge & (1 - Bridge Sensor)/2

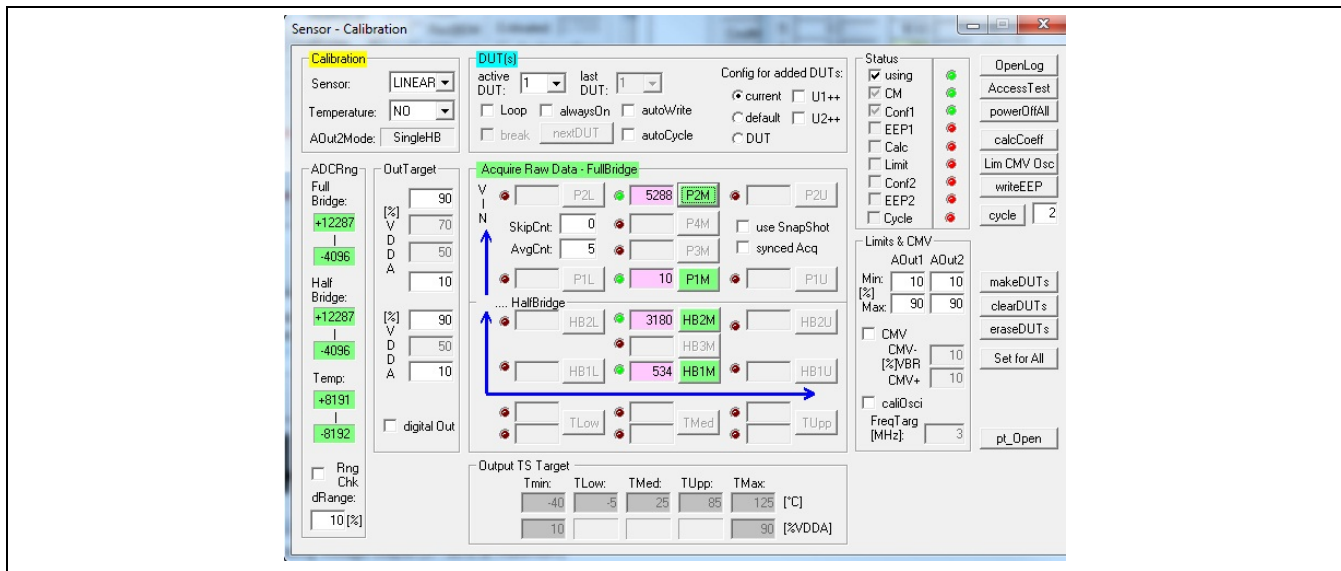


4.7. Calibration Window

The “Sensor – Calibration” dialog is used to perform a calibration of the ZSSC3154 device under test (DUT) with either the SRB or the user’s sensor module. The MCS allows calibration of multiple DUTs (see section 6).


The “Sensor – Calibration” dialog (see Figure 4.11) can be accessed by either clicking on the icon in the top banner or selecting “Calibration” on the top menu. Section 4 gives an example calibration using the commands on this screen.

Figure 4.11 “Sensor – Calibration” Dialog Window



4.8. RAM/EEPROM Register Dialog Window

This dialog window is used to read and write register contents into the ZSSC3154 memories and has the same functionality as the “IC Configuration” section in the main window.

Access the RAM/EEPROM dialog window by clicking on the  icon in the top banner or by selecting “Configuration” on the top menu and then RAM/EEPROM on the top menu.

There is also a **WriteEEP** button to store all register contents into the EEPROM of the ZSSC3154. Register indexing numbers correspond to the ZSSC3154 memory addresses.

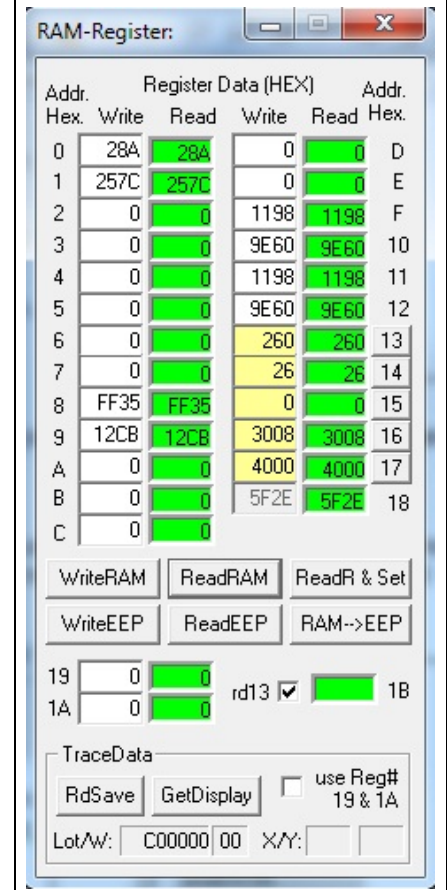
The configuration of the ZSSC3154 is stored in 28 EEPROM 16-bit words.

- Calibration coefficients for conditioning the sensor signal via conditioning calculations and the output limits are stored in 19 registers (registers 0_{HEX} to 12_{HEX}).
- There are 5 words for setting the configuration of the ZSSC3154 (registers 13_{HEX} to 17_{HEX}).
- One register is used for storing the EEPROM signature (register 18_{HEX}), which is used in NOM to check the validity of the EEPROM contents after power-on.
- Two additional 16-bit registers are available for optional user data (registers 19_{HEX} and 1A_{HEX}).

For more information regarding the registers, refer to the *ZSSC3154 Functional Description*.

Note: If current settings differ from the memory contents, registers that do not correspond to memory will have a **red** background after the “Read” operation; otherwise, the background will be **green**.

Figure 4.12 Displaying RAM-EEP Register Contents



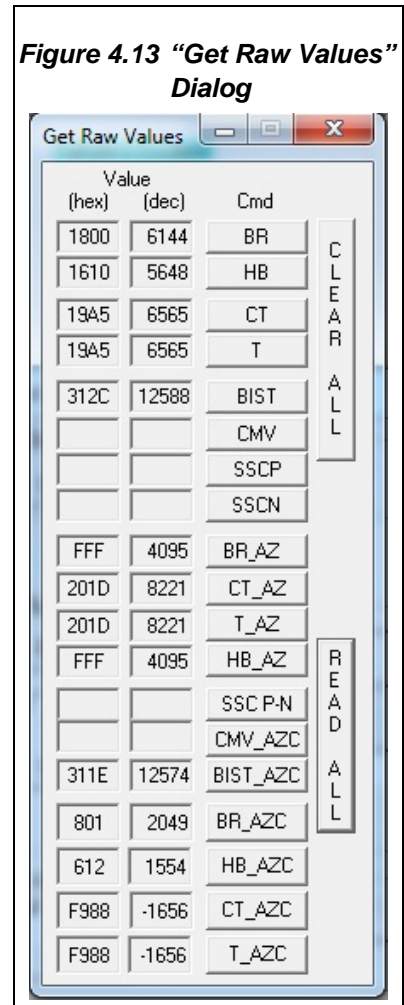
4.9. Get Raw Values Dialog

The “Get Raw Values” dialog is used to acquire the RAW values of the measurements for the following values:

<input type="button" value="BR"/>	Bridge Signal Raw Data (main channel)
<input type="button" value="HB"/>	Half-Bridge Signal Raw Data (main channel)
<input type="button" value="CT"/>	Main Calibration Temperature Raw Data
<input type="button" value="T"/>	Calibration Temperature Raw Data
<input type="button" value="BIST"/>	Built In Self-Test Raw Data
<input type="button" value="CMV"/>	Common Mode Voltage
<input type="button" value="SSCP"/>	Positive-Biased Sensor Short Check Raw Data
<input type="button" value="SSCN"/>	Negative-Biased Sensor Short Check Raw Data
<input type="button" value="BR_AZ"/>	Sensor Signal Auto-Zero Raw Data
<input type="button" value="CT_AZ"/>	Calibration Temperature Auto-Zero Raw Data
<input type="button" value="T_AZ"/>	Temperature Auto-Zero Raw Data
<input type="button" value="HB_AZ"/>	Half-Bridge Sensor Signal Auto-Zero Raw Data
<input type="button" value="SSCP-N"/>	Positive-Negative Biased Sensor Short Check Raw Data
<input type="button" value="CMV_AZC"/>	Common Mode Voltage, Auto-Zero Compensated
<input type="button" value="BIST_AZC"/>	Built In Self-Test Raw Data, Auto-Zero Compensated

<input type="button" value="BR_AZC"/>	Sensor Signal Main Channel Raw Data including Auto-Zero Compensation
<input type="button" value="HB_AZC"/>	Half-Bridge Sensor Signal Main Channel Raw Data including Auto-Zero Compensation
<input type="button" value="CT_AZC"/>	Calibration Temperature Raw Data including Auto-Zero Compensation
<input type="button" value="T_AZC"/>	Temperature Raw Data including Auto-Zero Compensation

Figure 4.13 “Get Raw Values” Dialog



4.10. Send Command



The “Send Command” dialog is accessed by clicking this icon on the top banner or clicking on “Calibration” in the top menu and then on “Send Command” in the resulting drop-down menu (see Figure 4.14). It is used for transferring commands from the PC to the microcontroller on the SSC CB and reading the result of the commands. A full summary and detailed command description of the applicable controller commands are given in the *ZSSC3154 Functional Description*.

For the communication between the SSC CB and the ZSSC3154 DUT, the ZSSC3154’s slave address and the communication frequency can be selected from the drop-down menus in the “Send Command” dialog.

The “Send Command” dialog includes the following buttons:

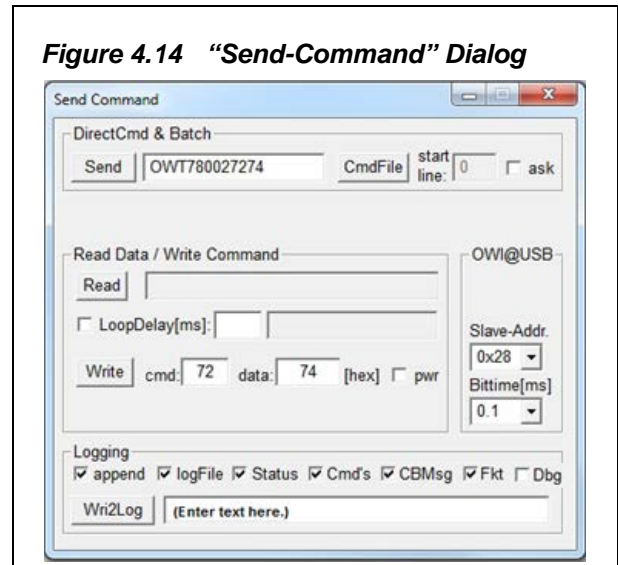
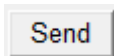


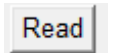
Figure 4.14 “Send-Command” Dialog



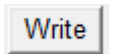
Sends the command entered in the adjacent field to the SSC CB. Alternatively, a *.3154_cmd command file can be loaded. For more information refer to *SSC Command Syntax* document.



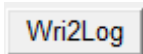
Loads a ZSSC3154 command file (*.3154_cmd).



Reads the output data buffer of the ZSSC3154. A loop delay can also be added between the readings.



Performs the same function as the “Send” command except that the command field and the data field are separated. The ZSSC3154 software generates the actual instruction to be sent to the SSC CB.




Writes text entered in the adjacent field to the log file. The checkboxes can be used to write various data into the log file, such as status, commands, messages, etc.

Note: For additional functionality, the *IDT SSC Terminal Software* can be used as an alternative to the ZSSC3154 Evaluation Software. The *SSC Terminal Software* can be downloaded from IDT’s web site at www.IDT.com/ZSSC3154KIT. This is the lowest level of communication for transferring commands from the PC to the microcontroller on the SSC CB. A full summary and detailed command description of the applicable controller commands are given in IDT’s *SSC Command Syntax Spreadsheet*, (see section 8).

Clicking on the downloaded executable file *SSC TermVxxy.exe* installs the terminal software and creates a *IDT SSC Terminal* icon on the PC desktop. Click on this icon to activate the terminal program. For the communication mode, use the setting explained for I²C™.

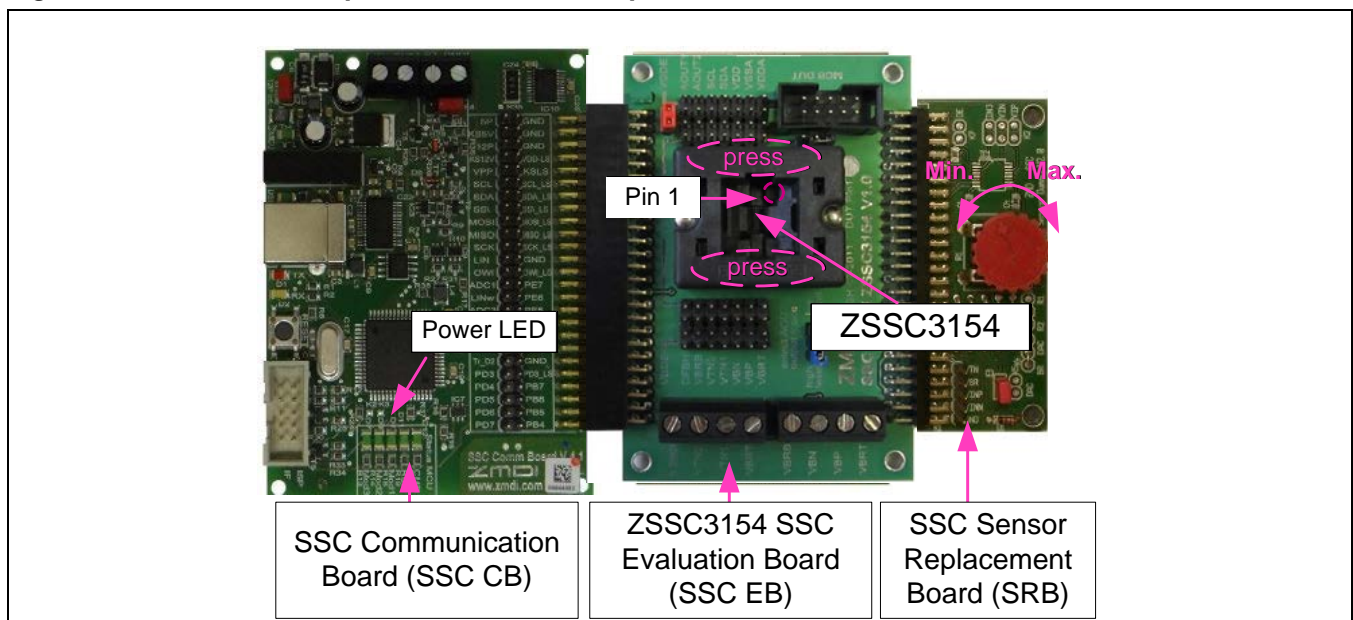
5 Calibration Example using the ZSSC3154 Evaluation Kit

 The following directions perform an example of a simple calibration using the sensor replacement board (SRB). The calibrated output will be displayed as a calibration result by the software.

5.1. Hardware Setup

- Connect the SSC CB, SSC EB, and SRB as shown in Figure 5.1.
- Press down on top of the socket on the SSC EB to open it and insert a ZSSC3154 (see Figure 5.1; note pin 1 orientation).
- Connect a USB cable from the USB connector on the SSC CB to an available USB port on the PC. Verify that the green PWR LED is lit on the SSC CB.

Figure 5.1 Hardware Setup for Calibration Example



5.2. Software Startup

- Start the ZSSC3154 Software by clicking on the desktop icon or activate it from the Windows Start Menu folder: #Start_Menu#ZMDI\ZSSC3154\ZSSC3154.
- Select the "I2C – CB (USBPort-Kit)" or "OWI – CB (USBPort-Kit)" interface from the drop down menu in the "Interface Selection" section of the main window as described in section 4.4.1.
- Select the following settings as shown in Figure 5.2:
 - In the "Sensor – Full Bridge" and "Half Bridge" sections, set the "Span [mV/V]" (sensor sensitivity) drop-down menu to **50mV/V**, which is the typical span when using the SRB. With the 5V supply, this equals a total span of 250mV ($5V * 50mV/V = 250mV$).
 - In the "ADC Adjust" section, set the resolution integration phase to **10bits**. ADC resolution is set to **14bits**.

- In the “ADC Adjust” section, set the “FullBridgeRS” and “HalfBridgeRS” (range shift) menus to $\frac{3}{4}$, which fits the input signal range to the ADC output value (“analog zero”). For example for a range shift of $\frac{3}{4}$ and 14 bits resolution, the read-out values would be between -4096 and +12287.
- Operational mode: for this example, set the “Out2” section mode to “Single HB” (single half bridge; see section 4.6).

Note: Write the configuration into the RAM by pressing on the **WriteRAM** button in the “IC Configuration” section (see section 4.4.2).

Figure 5.2 Select Span and Range Shift

The screenshot shows a software configuration window with three main sections:

- Sensor - Full Bridge:** Includes a dropdown for span (set to 50), a text input for span in mV/V (set to 14), and a dropdown for XZC in mV/V (set to 0.0).
- Half Bridge:** Includes a dropdown for span (set to 50), a text input for span in mV/V (set to 14), a dropdown for XZC in mV/V (set to 0.0), and a dropdown for HB Ref [%VDDA] (set to 0).
- ADC Adjust (highlighted in green):** Includes dropdowns for FullBridgeRS (set to 3/4) and HalfBridgeRS (set to 3/4), a dropdown for Resolution (set to 14bit), a dropdown for in integration phase (set to 10bit), and checkboxes for ClockDivider and calcConv [ms] (set to 0.7960).

5.3. Calibration Data Acquisition

- Click on the icon or select “Calibration” on the top menu and then “Calibration” from the drop-down menu. The “Sensor – Calibration” dialog window appears as shown in Figure 4.11 and Figure 5.3. Select the calibration mode from the “Calibration” drop-down menu.

For this example, the recommended mode is

- ✓ **LINEAR** (two points only) for the sensor
 - ✓ **NO** calibration for the temperature (temperature calibration requires a chamber with a controlled environment)
- In the “OutTarget” section, enter the target sensor calibration points corresponding in percent to the VDD supply (“[%] VDDA”). It is recommended that the output targets for the sensor points be between 10% and 90%. For this example, use 90% as the maximum and 10% as the minimum for both full bridge and half bridge entry fields (top section).
 - Next start data collection. Normally this would be done with a real sensor attached on a remote board in a controlled chamber. Instead, this calibration-example run uses the SRB as the input as follows:
 - ✓ **Minimum** [10%] sensor signal: turn the SRB counter-clockwise (CCW) to the end and click both the **P1M** button and **HB1M** buttons.
 - ✓ **Maximum** [90%] sensor signal: turn the SRB clockwise (CW) to the end and click both the **P2M** button and **HB2M** buttons.

Acquired data will be displayed in the text boxes next to the buttons.

Note: only active buttons corresponding to the calibration mode are active as indicated by green shading.

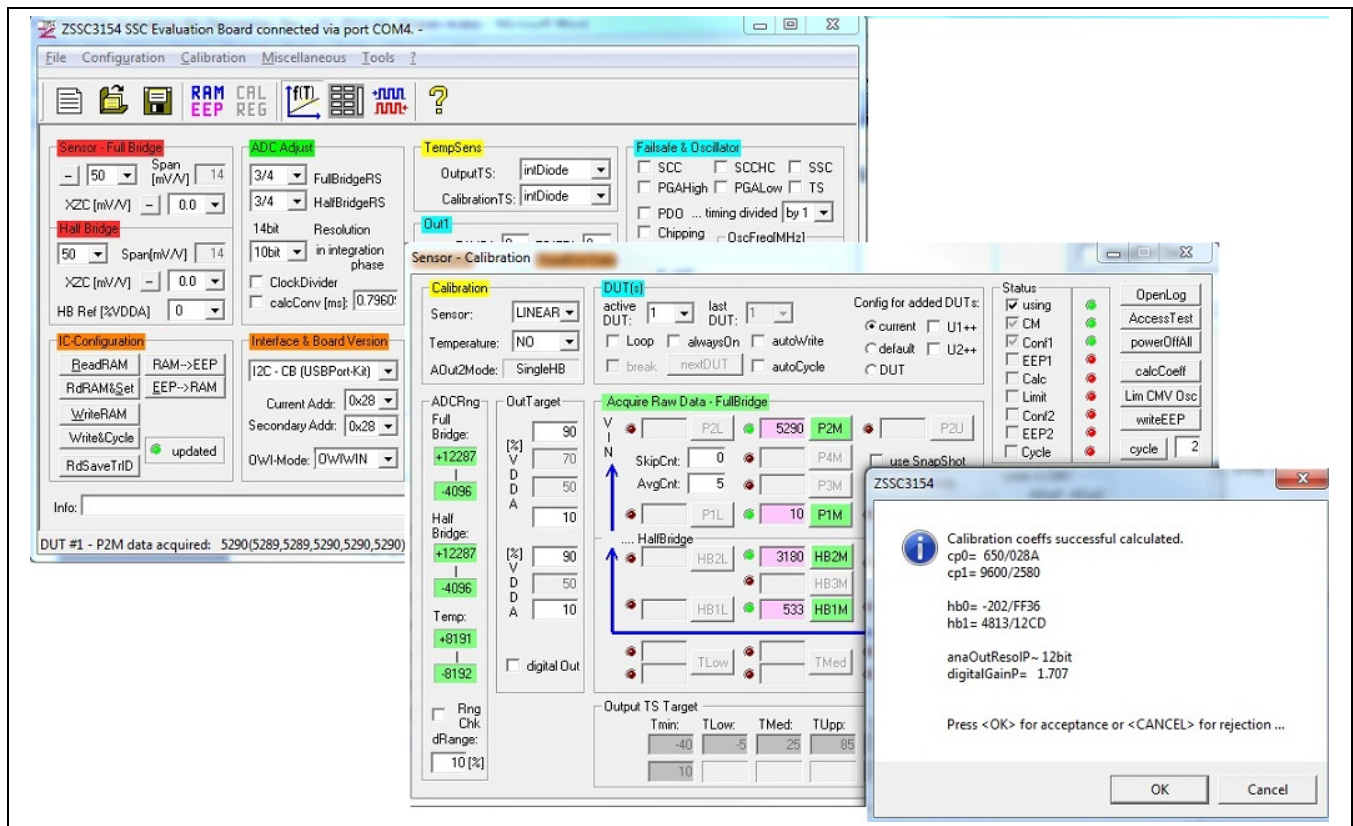
5.4. Calculation of the Coefficients and Limits

- Click the **calcCoeff** button at the right of the “Sensor – Calibration” dialog window to calculate the calibration coefficients. The result of the calculation (if successful) is displayed on the screen as shown in Figure 5.3. The ZSSC3154’s calibration microcontroller (CMC) removes the offset and temperature dependency so that the measured output result is within the target values (user’s %VDDA entries or in this case, between 10% and 90%).

Note: The number of calibration points is equal to the number of coefficients to be calculated.

- Click on the **Limits CMV Osc** button to calculate the sensor aging (CMV) and output limits if the CMV check is enabled.
- Click on **writeEEP** to make these calculations effective and written in the EEPROM. Option: starting a measuring cycle can be triggered by clicking the **cycle** button.

Figure 5.3 Displaying the Result of the Coefficient Calculation



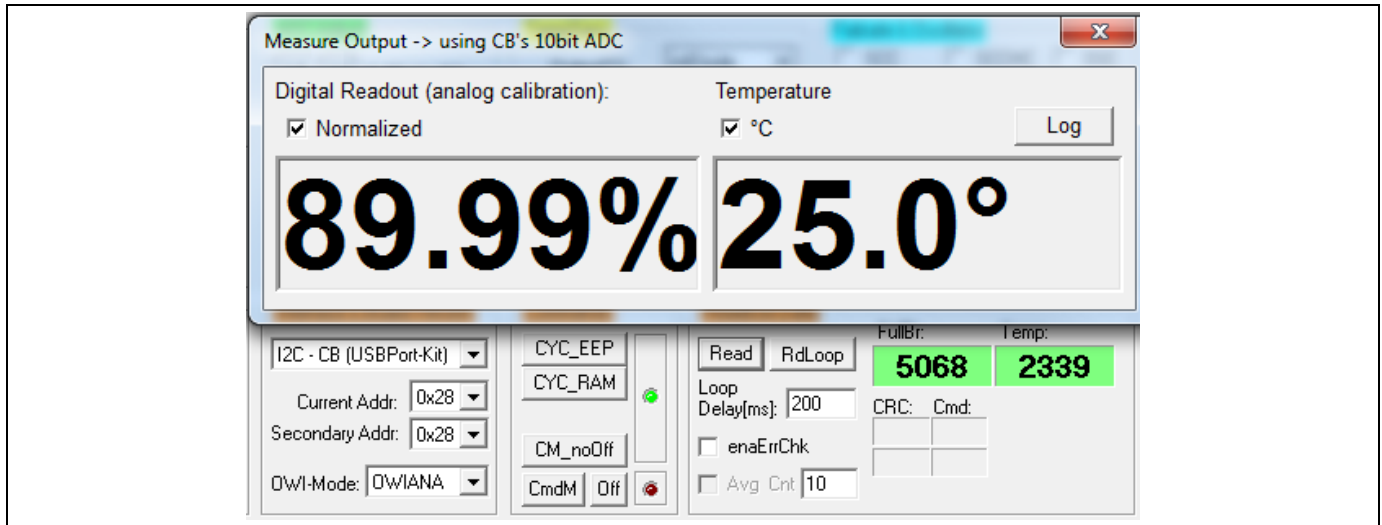
Note: all active buttons corresponding to the calibration method selected are shaded green.

5.5. Displaying Measurement Results in Normal Operating Mode (NOM)

Close the calibration window and trigger a measurement in the main window (see section 4.5.1 and Figure 4.9) by clicking on either the **Read** or **Read Loop** button in the “ReadOut Data” section (see Figure 4.9). The ZSSC3154 is already running in Normal Operation Mode (NOM) if the **cycle** button was clicked in the calibration window in the previous step.

Measurement results can also be displayed in % by clicking on “Tools” in the top menu and then “Measure Output” and then selecting the output format in the checkbox in the resulting dialog window.

Figure 5.4 *Displaying Measurement Results via Tools >> Measure Output*



6 Mass Calibration System Dry Run

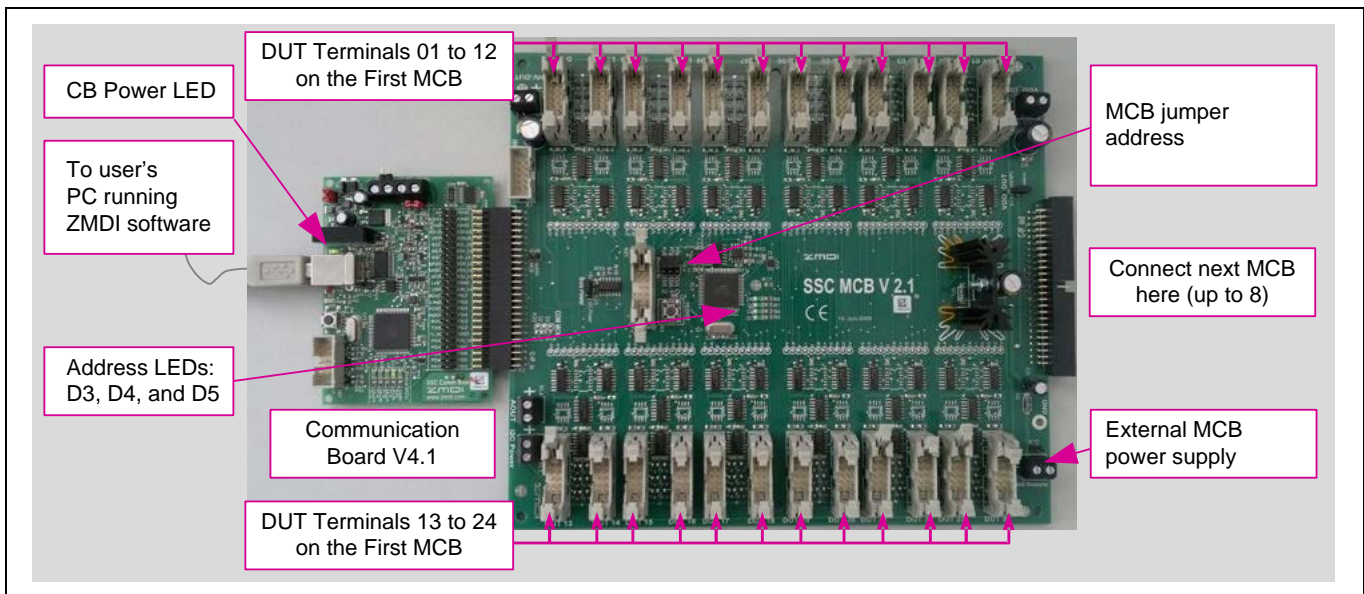


The following directions perform an example of a simple calibration using the Mass Calibration System (MCS) shown in Figure 6.1. Refer to the *SSC Mass Calibration Board Data Sheet* for full details of operation. The calibrated output will be displayed as a calibration result in the ZSSC3154 Evaluation Software.

To connect the DUTs to the Mass Calibration Board (MCB), there are several options, which can be combined as needed. The ZSSC3154 Mass Calibration Reference Board (MCR) provided with the MCS can be connected directly into the DUT terminals on the MCB. User-provided sensor modules and/or the ZSSC3154 SSC Evaluation Board (SSC EB) can also be connected to the DUT terminals using the ribbon cable provided with the MCS. For the SSC EB, connect the ribbon cable to the K6 connector on the SSC EB (see section 3.1).

For the dry run example described in the next sections, MCRs and/or the SSC EB with the SRB are used instead of actual sensor modules.

Figure 6.1 Mass Calibration Board (MCB) Setup

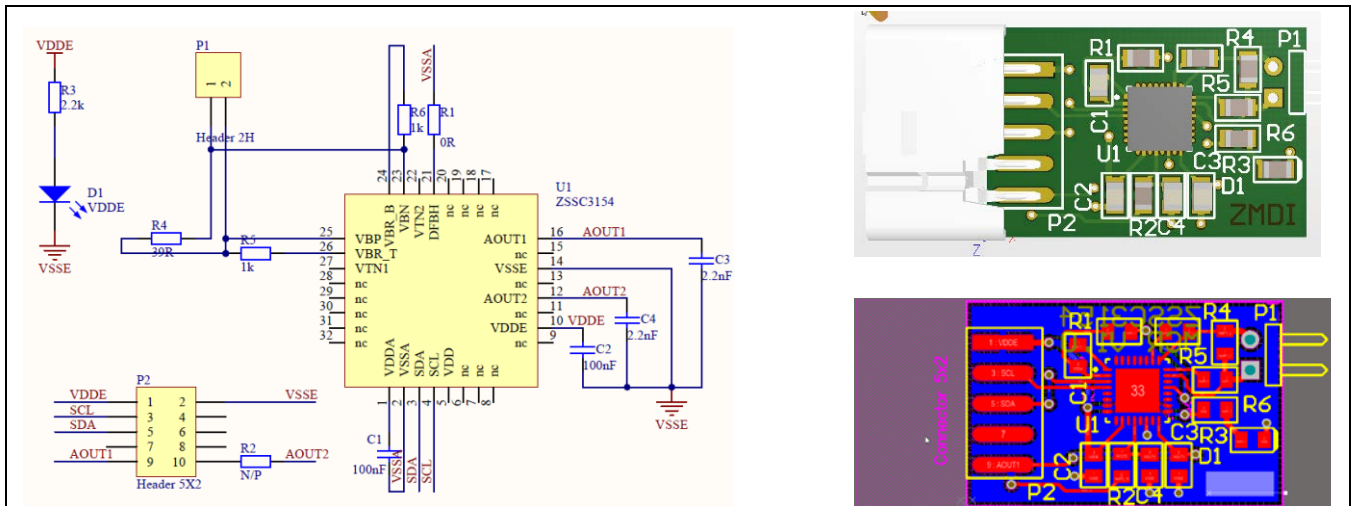


6.1. The Mass Calibration Reference Board Setup

The SSC Mass Calibration System includes four ZSSC3154 MCRs. Each MCR has a sample ZSSC3154 QFN32 for use as the DUT. See Figure 6.2 for the schematic and layout of the MCR. The MCR simulates a typical application circuit, which allows checking the I²C™ and/or one wire communication (OWI) of the ZSSC3154 and simulating an easy 2-point calibration using the P1 jumper on the MCR shorted for the first calibration point and then open for the second point.

If pin 5 of the P2 connector to the SSC Mass Calibration Board of the MCR is soldered, then the MCR is preconfigured for I²C communication. OWI communication will fail if this pin is connected to the MCB.

For OWI communication, unsolder this pin and configure the ZSSC3154 for OWI operation mode as described in section 6.3.

Figure 6.2 Mass Calibration Reference Board (MCR)


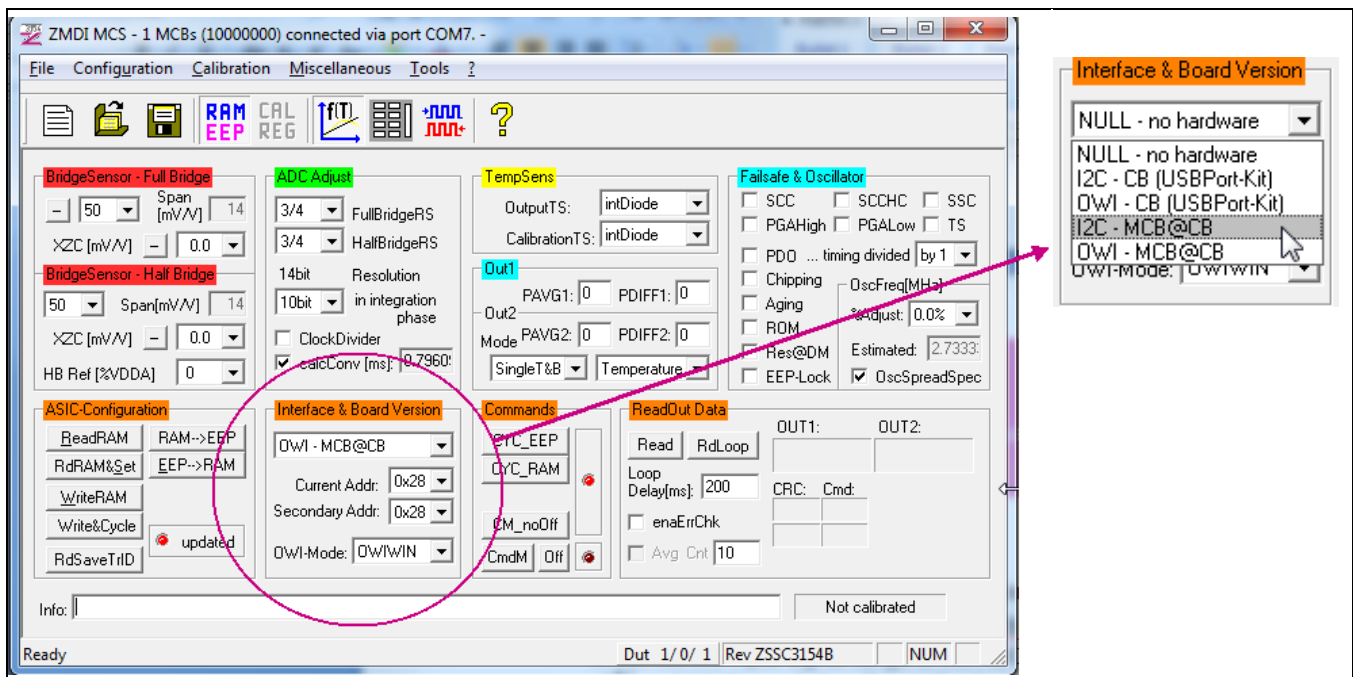
6.2. ZSSC3154 Mass Calibration System Hardware Setup for the Example Dry Run

- Connect the SSC CB and SSC MCB as shown on Figure 6.1. Up to eight MCBs can be connected in series enabling mass calibration of up to 192 DUTs.
- Starting from terminal #01 on the first Mass Calibration Board (MCB), connect the MCR boards in the DUT terminals and/or use the ribbon cables to connect from the DUT terminals to the SSC EB with the SRB connected.
- Ensure that the board address of the first MCB is set to “0,” subsequent MCBs are set to sequential different addresses, and the MCBs are powered by an external supply as described in the *SSC Mass Calibration Board Data Sheet*.
- Verify that only the green power LED is lit on the SSC CB (see Figure 3.1) and also the LEDs on the SSC MCB corresponding to the jumper selected address.
- Connect a USB cable from the USB connector on the SSC CB to an available USB port on the PC.


6.3. Software Startup for Example Dry Run

- a) Start the ZSSC3154 Evaluation Software by clicking on the desktop icon or activate it from the Windows® Start Menu folder: #Start_Menu#ZMDI\ZSSC3154\ZSSC3154.
- b) Select the “I2C – MCB@CB” or “OWI – MCB@CB” interface from the drop-down menu in the “Interface Selection” section of the main window as shown in Figure 6.3.
- c) Select the following settings as shown in Figure 5.2:
 - In the “Sensor – Full Bridge” and “Half Bridge” sections, set the “Span [mV/V]” (sensor sensitivity) menu to **50mV/V**, which is the typical span when using the MCR. With the 5V supply, this equals a total span of 250mV ($5V * 50mV/V = 250mV$).
 - In the “ADC Adjust” section, set the resolution integration phase to **10bits**. ADC resolution is **14bits**.
 - In the “ADC Adjust” section, set the “FullBridgeRS” and “HalfBridgeRS” (range shift) menus to $\frac{3}{4}$, which fits the input signal range to the ADC output value (“analog zero”). For example for a range shift of $\frac{3}{4}$ and 14 bits resolution, the read-out values would be between -4096 and +12287.
 - Operational mode: set the “Out2” section mode to “Single T&B” (single temperature & bridge; see section 4.6).
- d) Write the configuration into the RAM by clicking the **WriteRAM** button in the “ASIC Configuration” section.

Figure 6.3 Interface Selection



6.4. Calibration Data Acquisition for Example Dry Run

- a) Click on the  icon or select “Calibration” on the top menu and then “Calibration” from the drop-down menu. The “Sensor – Calibration” window appears as shown in Figure 6.4. Select the calibration mode from the drop down menu.

For this example, the recommended mode is

- **LINEAR** (two points only) for the sensor
 - **NO** calibration for the temperature (temperature calibration requires a chamber with a controlled environment)
- b) Enter the desired sensor targets corresponding in percent of the VDDA supply as described in section 5.3, step b). It is recommended that the output targets for the sensor points be between 10% and 90% for this dry run example.
- c) Next start data collection. Normally this would be done with a real sensor attached on a remote board in a controlled chamber. Instead, this calibration example run uses an MCR or an SRB connected through the SSC EB as the input as follows:
- **Minimum** [10%] sensor signal: short the P1 jumper on the MCR or turn the SRB counter-clockwise (CCW) to the end and click the **P1M** button.
 - **Maximum** [90%] sensor signal: open the P1 jumper on the MCR or turn the SRB clockwise (CW) to the end and click the **P2M** button.

Acquired data will be displayed in the text boxes next to the buttons.

Note: only active buttons corresponding to the calibration mode are active as indicated by green shading.

6.5. Calculation of the Coefficients and Limits

- Click the **calcCoeff** button at the right of the “Sensor – Calibration” dialog window to calculate the calibration coefficients. The result of the calculation (if successful) is displayed on the screen (see Figure 6.4). The ZSSC3154’s calibration microcontroller (CMC) removes the offset and temperature dependency so that the measured output result is within the target values (user’s %VDDA entries or in this case, between 10% and 90%).

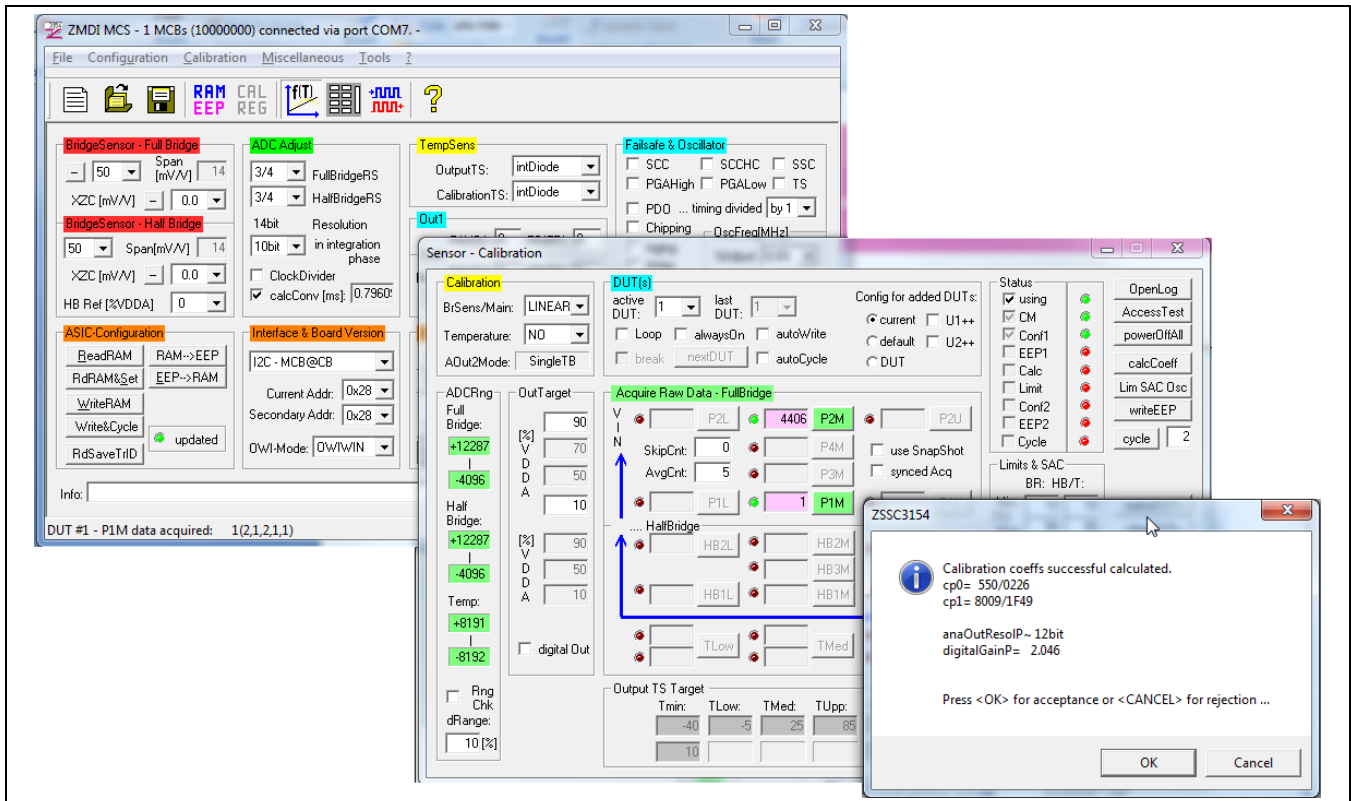
Note: The number of calibration points is equal to the number of coefficients to be calculated.

- Click on the **Limits CMV Osc** button to calculate the sensor aging (CMV) and output limits if the CMV check is enabled.
- Click on **writeEEP** to make these calculations effective and written in the EEPROM. Option: starting a measuring cycle can be triggered by clicking the **cycle** button.

Close the calibration window and trigger a measurement in the main window (see Figure 6.3) by clicking on either the **Read** or **Read Loop** button in the “ReadOut Data” section (see Figure 4.9). The ZSSC3154 is already running in Normal Operation Mode (NOM) because the **cycle** button was clicked in the calibration window.

Measurement results can also be displayed in % by clicking on “Tools” in the top menu and then “Measure Output” and then selecting the output format in the checkbox in the resulting dialog window.

Figure 6.4 Displaying the Result of the Coefficient Calculation



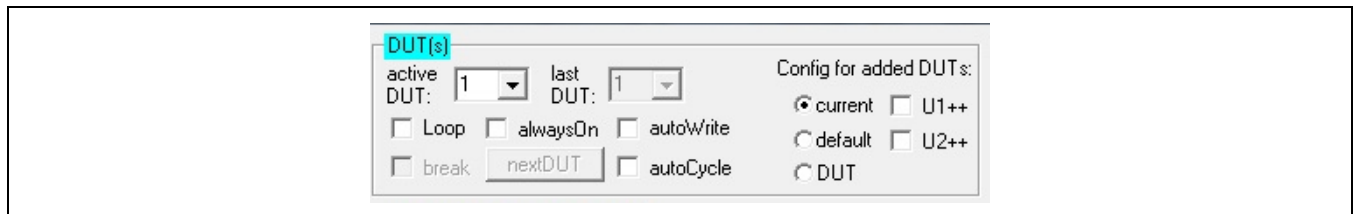
Note: all active buttons corresponding to the calibration method selected are shaded green.

6.6. Managing Multiple DUTs with the Mass Calibration System

Managing multiple DUTs connected to the MCS is handled in the “DUT(s)” section of the calibration dialog window (see Figure 6.5). This section is used to select the active DUT (the “active DUT” field) and activate options such as loading the current configuration of the DUT into the software or writing a new configuration to the DUT from either a default configuration or the current configuration in the software. If the “Loop” checkbox is enabled, calibration of a selected set of DUTs is processed in a loop.

Placing the user’s cursor over the entry fields and checkboxes in this section displays information about their functionality.

Figure 6.5 “DUT” Section for Managing Multiple DUTs



7 Ordering Information

Please refer to www.IDT.com/ZSSC3154KIT for current product ordering codes and descriptions. After a ZSSC3154 Evaluation Kit or ZSSC3154 Mass Calibration System has been ordered, individual parts can be ordered separately.

8 Related Documents

Document
<i>SSC Evaluation Kit Feature Sheet</i>
<i>ZSSC3154 Data Sheet</i>
<i>ZSSC3154 Functional Description</i>
<i>SSC Communication Board Data Sheet *</i>
<i>SSC Sensor Replacement Board Data Sheet*</i>
<i>SSC Command Syntax *</i>
<i>Mass Calibration System Feature Sheet</i>
<i>SSC Mass Calibration Board Data Sheet *</i>

Visit www.IDT.com/ZSSC3154 and www.IDT.com/ZSSC3154KIT or contact your nearest sales office for the latest version of these documents.

9 Glossary

Term	Description
ADC	Analog-to-Digital Converter
AFE	Analog Front End
CB	Communication Board
CMC	Calibration Microcontroller
CMV	Common Mode Voltage
DUT	Device Under Test
OWI	One-Wire Interface
PCB	Printed Circuit Board
PGA	Programmable Gain Amplifier
SRB	Sensor Replacement Board
SSC	Sensor Signal Conditioner
DFB[L/H]	Diagnostic Fault Band [Mode]
MCB	Mass Calibration Board
MCS	Mass Calibration System
MCR	Mass Calibration Reference Board

10 Document Revision History

Revision	Date	Description
1.00	March 13, 2012	First release.
2.00	August 5, 2014	Mass Calibration Board dry run added. Updates for section 8 to note that documentation and software are available on www.IDT.com . Updates for imagery for cover and headers. Updates for contacts. Minor edits for clarity.
	March 29, 2016	Changed to IDT branding.



Corporate Headquarters
 6024 Silver Creek Valley Road
 San Jose, CA 95138
www.IDT.com

Sales
 1-800-345-7015 or 408-284-8200
 Fax: 408-284-2775
www.IDT.com/go/sales

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(Применяются в телекоммуникациях гражданского и специального назначения, в средствах связи, РЛС, а так же военной, авиационной и аэрокосмической отраслях промышленности).



Телефон: 8 (812) 309-75-97 (многоканальный)

Факс: 8 (812) 320-03-32

Электронная почта: ocean@oceanchips.ru

Web: <http://oceanchips.ru/>

Адрес: 198099, г. Санкт-Петербург, ул. Калинина, д. 2, корп. 4, лит. А