## MARCH 2006

## GENERAL DESCRIPTION

The XRT75R03 is a three-channel fully integrated Line Interface Unit (LIU) featuring EXAR's R $^{3}$ Technology (Reconfigurable, Relayless Redundancy) with Jitter Attenuator for E3/DS3/STS-1 applications. It incorporates 3 independent Receivers, Transmitters and Jitter Attenuators in a single 128 pin LQFP package.
Each channel of the XRT75R03 can be independently configured to operate in the data rate, E3 ( 34.368 MHz ), DS3 ( 44.736 MHz ) or STS-1 ( 51.84 MHz . Each transmitter can be turned off and tristated for redundancy support or for conserving power.
The XRT75R03's differential receiver provides high noise interference margin and is able to receive the data over 1000 feet of cable or with up to 12 dB of cable attenuation.
The XRT75R03 incorporates an advanced crystalless jitter attenuator per channel that can be selected either in the transmit or receive path. The jitter attenuator performance meets the ETSI TBR-24 and Bellcore GR-499 specifications.
The XRT75R03 provides both Serial Microprocessor Interface as well as Hardware mode for programming and control.

The XRT75R03 supports local, remote and digital loop-backs. The device also has a built-in Pseudo Random Binary Sequence (PRBS) generator and detector with the ability to insert and detect single bit error for diagnostic purposes.

## FEATURES

## RECEIVER:

- $\mathrm{R}^{3}$ Technology (Reconfigurable, Relayless Redundancy)
- On chip Clock and Data Recovery circuit for high input jitter tolerance
- Meets E3/DS3/STS-1 Jitter Tolerance Requirement
- Detects and Clears LOS as per G. 775
- Receiver Monitor mode handles up to 20 dB flat loss with 6 dB cable attenuation
- On chip B3ZS/HDB3 encoder and decoder that can be either enabled or disabled
- On-chip clock synthesizer provides the appropriate rate clock from a single 12.288 MHz Clock
- Provides low jitter output clock


## TRANSMITTER:

- $\mathrm{R}^{3}$ Technology (Reconfigurable, Relayless Redundancy)
- Compliant with Bellcore GR-499, GR-253 and ANSI T1.102 Specification for transmit pulse
- Tri-state Transmit output capability for redundancy applications
- Each Transmitter can be independently turned on or off
- Transmitters provide Voltage Output Drive

JITTER ATTENUATOR:

- On chip advanced crystal-less Jitter Attenuator for each channel
- Jitter Attenuator can be selected in Receive or Transmit paths
- Meets ETSI TBR 24 Jitter Transfer Requirements
- Compliant with jitter transfer template outlined in ITU G.751, G.752, G. 755 and GR-499-CORE, 1995 standards
- 16 or 32 bits selectable FIFO size
- Jitter Attenuator can be disabled


## CONTROL AND DIAGNOSTICS:

- 5 wire Serial Microprocessor Interface for control and configuration
- Supports optional internal Transmit driver monitoring
- Hardware Mode for control and configuration
- Each channel supports Local, Remote and Digital Loop-backs
- Single $3.3 \mathrm{~V} \pm 5 \%$ power supply
- 5 V Tolerant digital inputs
- Available in 128 pin LQFP
- $-40^{\circ} \mathrm{C}$ to $85^{\circ} \mathrm{C}$ Industrial Temperature Range


## APPLICATIONS

- E3/DS3 Access Equipment
- DSLAMs
- Digital Cross Connect Systems
- CSU/DSU Equipment
- Routers
- Fiber Optic Terminals

Figure 1. Block Diagram of the XRT 75R03


Notes: 1. ( $n$ ) $=0,1$ or 2 for respective Channels
2. Serial Processor Interface input pins are shared by the three Channels in "Host" Mode and redefined in the "Hardware" Mode.

## TRANSMIT INTERFACE CHARACTERISTICS

- Accepts either Single-Rail or Dual-Rail data from Terminal Equipment and generates a bipolar signal to the line
- Integrated Pulse Shaping Circuit
- Built-in B3ZS/HDB3 Encoder (which can be disabled)
- Accepts Transmit Clock with duty cycle of 30\%-70\%
- Generates pulses that comply with the ITU-T G. 703 pulse template for E3 applications
- Generates pulses that comply with the DSX-3 pulse template, as specified in Bellcore GR-499-CORE and ANSI T1.102_1993
- Generates pulses that comply with the STSX-1 pulse template, as specified in Bellcore GR-253-CORE
- Transmitter can be turned off in order to support redundancy designs


## RECEIVE INTERFACE CHARACTERISTICS

- Integrated Adaptive Receive Equalization (optional) for optimal Clock and Data Recovery
- Declares and Clears the LOS defect per ITU-T G. 775 requirements for E3 and DS3 applications
- Meets Jitter Tolerance Requirements, as specified in ITU-T G.823_1993 for E3 Applications
- Meets Jitter Tolerance Requirements, as specified in Bellcore GR-499-CORE for DS3 Applications
- Declares Loss of Signal (LOS) and Loss of Lock (LOL) Alarms
- Built-in B3ZS/HDB3 Decoder (which can be disabled)
- Recovered Data can be muted while the LOS Condition is declared
- Outputs either Single-Rail or Dual-Rail data to the Terminal Equipment

Figure 2. Pin Out of the XRT75R03


ORDERING INFORMATION

| Part Number | Package | Operating Temperature Range |
| :---: | :---: | :---: |
| XRT75R03IV | 128 Pin LQFP | $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ |

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PIN DESCRIPTIONS (BY FUNCTION)

## SYSTEM-SIDE TRANSMIT INPUT AND TRANSMIT CONTROL PINS

| Pin \# | Signal Name | TYPE | Description |
| :---: | :---: | :---: | :---: |
| $\begin{gathered} 38 \\ 1 \\ 125 \end{gathered}$ | TxON_0 <br> TxON_1 <br> TxON_2 | I | Transmitter ON Input - Channel 0: <br> Transmitter ON Input - Channel 1: <br> Transmitter ON Input - Channel 2: <br> These input pins are used to either enable or disable the Transmit Output Driver corresponding to Channel_n. <br> "Low" - Disables the Transmit Output Driver of the corresponding Channel. In this setting, the corresponding TTIP_n and TRING_n output pins will be tri-stated. <br> "High" - Enables the Transmit Output Driver of the corresponding Channel. In this setting, the corresponding TTIP_n and TRING_n output pins will be enabled. <br> Notes: <br> 1. Even when the XRT75R03 is configured in HOST mode, these pins will be active. To enable software control of the Transmit Output Driver outputs, pull these pins "High". <br> 2. When Transmitters are turned off either in Host or Hardware mode, the TTIP and TRing outputs are Tri-stated. <br> 3. These pins are internally pulled "High" |
| $\begin{gathered} 35 \\ 4 \\ 26 \end{gathered}$ | TxClk_0 <br> TxClk_1 <br> TxClk_2 | I | Transmit Clock Input - Channel 0: <br> Transmit Clock Input f-Channel 1: <br> Transmit Clock Input - Channel 2: <br> These input pins have two functions: <br> - They function as the timing source for the Transmit Section of the corresponding channel within the XRT75R03. <br> - They also are used by the Transmit Section of the LIU IC to sample the corresponding TPDATA_n and TNDATA_n input pin. <br> Note: The user is expected to supply a $44.736 \mathrm{MHz} \pm 20 \mathrm{ppm}$ clock signal (for DS3 applications), $34.368 \mathrm{MHz} \pm 20 \mathrm{ppm}$ clock signal (for E3 applications) or a $51.84 \mathrm{MHz} \pm 4.6 \mathrm{ppm}$ clock signal (for STS-1, Stratum 3E or better applications). |

## SYSTEM-SIDE TRANSMIT INPUT AND TRANSMIT CONTROL PINS

| Pin \# | Signal Name | TYPE | Description |
| :---: | :---: | :---: | :---: |
| $\begin{gathered} 34 \\ 3 \\ 25 \end{gathered}$ | TPDATA_0/TxDATA_0 TPDATA_1/TxDATA_1 TPDATA_2/TxDATA_2 | 1 | Transmit Positive Data Input - Channel 0: <br> Transmit Positive Data Input - Channel 1: <br> Transmit Positive Data Input - Channel 2: <br> Transmit Positive Data/Data Input - Channel n: <br> The function of these input pins depends upon whether the corresponding channel has been configured to operate in the Single-Rail or Dual-Rail Mode. <br> Single Rail Mode - Transmit Data Input - Channel n: <br> If the Channel has been configured to operate in the Single-Rail Mode, then all transmit output data will be serially applied to this input pin. This signal will latched into the Transmit Section circuitry upon either the rising or falling edge of the TxCLK_n signal, depending upon user configuration. In the Single-Rail Mode, the Transmit Section of the LIU IC will then encode this data into either the B3ZS line code (for DS3 and STS-1 applications) or the HDB3 line code (for E3 applications). <br> Dual Rail Mode - Transmit Positive Data Input - Channel n: <br> If the Channel has been configured to operate in the Dual-Rail Mode, then the user should apply a pulse to this input pin, anytime the Transmit Section of the LIU IC is suppose to generate and transmit a positive-polarity pulse onto the line. This signal will be latched into the Transmit Section circuitry upon either the rising or falling edge of the TxCLK_n signal, depending upon user configuration. <br> In the Dual-Rail Mode, the Transmit Section of the LIU IC will NOT encode this data into either the B3ZS or HDB3 line codes. If the user configures the LIU IC to operate in the Dual-Rail Mode, then B3ZS/HDB3 encoding must have already been done prior to providing the transmit output data to this input pin. |
| $\begin{gathered} 33 \\ 2 \\ 24 \end{gathered}$ | TNData_0 <br> TNData_1 <br> TNData_2 | I | Transmit Negative Data Input - Channel 0: <br> Transmit Negative Data Input - Channel 1: <br> Transmit Negative Data Input - Channel 2: <br> If a Channel has been configured to operate in the Dual-Rail Mode, then the user should apply a pulse to this input pin anytime the Transmit Section of the LIU IC is suppose to generate and transmit a negative-polarity pulse onto the line. This signal will be latched into the Transmit Section circuitry upon either the rising or falling edge of the TxCLK_n signal, depending upon user configuration. <br> Note: If the Channel has been configured operate in the Single-Rail Mode, then this input pin has no function, and should be tied to GND. |

## SYSTEM-SIDE TRANSMIT INPUT AND TRANSMIT CONTROL PINS

| Pin \# | Signal Name | TYPE | Description |
| :---: | :---: | :---: | :---: |
| $\begin{gathered} 37 \\ 7 \\ 8 \end{gathered}$ | $\begin{aligned} & \text { TAOS_0 } \\ & \text { TAOS_1 } \\ & \text { TAOS_2 } \end{aligned}$ | 1 | Transmit "All Ones" Input - Channel 0: <br> Transmit "All Ones" Input - Channel 1: <br> Transmit "All Ones" Input - Channel 2: <br> These input pin are used to configure the Transmit Section of the corresponding channel to generate and transmit an unframed "All Ones" pattern via the DS3, E3 or STS-1 line signal to the remote terminal equipment. <br> When this configuration is implemented the Transmit Section will ignore the data that it is accepting from the System-side equipment and will overwrite this data will the "All Ones" Pattern. <br> "Low" - Does not configure the channel to transmit an unframed "All Ones" Pattern to the remote terminal equipment. In this mode, the Transmit Section of the Channel will output data based upon the signals that are applied to the TxPOS_n and TxNEG_n input pins. <br> "High" - Configures the Channel to transmit an unframed "All Ones" Pattern to the remote terminal equipment. In this mode, the Transmit Section will override the data that is applied to the TxPOS_n and TxNEG_n input pins, and will proceed to generate and transmit an unframed "All Ones" pattern. <br> Notes: <br> 1. This input pin is ignored if the XRT75R03 is operating in the HOST Mode and should be tied to GND. <br> 2. These input pins are internally pulled down. |
| $\begin{gathered} 36 \\ 9 \\ 10 \end{gathered}$ | TxLEV_0 <br> TxLEV_1 <br> TxLEV_2 | I | Transmit Line Build-Out Enable/Disable Select - Channel 0: Transmit Line Build-Out Enable/Disable Select - Channel 1: Transmit Line Build-Out Enable/Disable Select - Channel 2: <br> These input pins are used to enable or disable the Transmit Line Build-Out (e.g., pulse-shaping) circuit within the corresponding channel. The user should set these input pins either "High" or "Low" based upon the following guidelines. <br> "Low" - If the cable length between the Transmit Output of the corresponding Channel and the DSX-3/STSX-1 location is 225 feet or less. <br> "High" - If the cable length between the Transmit Output of the corresponding Channel and the DSX-3/STSX-1 location is 225 feet or more. <br> Notes: <br> 1. These guidelines must be followed in order to insure that the Transmit Section of Channel_n will always generate a DS3 pulse that complies with the Isolated Pulse Template requirements per Bellcore GR-499-CORE, or an STS-1 pulse that complies with the Pulse Template requirements per Telcordia GR-253-CORE. <br> 2. This input pin is inactive if the XRT75R03 has been configured to operate in the Host Mode, or if the corresponding channel has been configured to operate in the E3 Mode. If either of these cases are true, then tie this input pin to GND. <br> 3. These input pins are internally pulled "Low". |

## SYSTEM-SIDE TRANSMIT INPUT AND TRANSMIT CONTROL PINS

| Pin \# | Signal Name | TYPE | Description |
| :---: | :---: | :---: | :---: |
| $\begin{gathered} \hline 40 \\ 127 \\ 22 \end{gathered}$ | DMO_0 <br> DMO_1 <br> DMO_2 | O | Drive Monitor Output - Channel 0: <br> Drive Monitor Output - Channel 1: <br> Drive Monitor Output - Channel 2: <br> These output signals are used to indicate some sort of fault condition within the Transmit Output signal path. <br> This output pin will toggle "High" anytime the Transmit Drive Monitor circuitry either, via the corresponding MTIP and MRING input pins or internally, detects no bipolar pulses via the Transmit Output line signal (e.g., via the TTIP_n and TRING_n output pins) for 128 bit-periods. <br> This output pin will be driven "Low" anytime the Transmit Drive Monitor circuitry has detected at least one bipolar pulse via the Transmit Output line signal within the last 128 bit periods. |
| 67 | TxClkINV/ SCIk | 1 | Hardware Mode: Transmit Clock Invert <br> Host Mode: Serial Clock Input: <br> Hardware mode <br> This input pin is used to select the edge of the TxCLK_n input that the Transmit Section of all channels will use to sample the TPDATA_n and TNDATA_n input pins. <br> Setting this input pin "High" configures all three Transmitters to sample the TPData_n and TNData_n data on the rising edge of the TxClk_n. <br> Setting this input pin "Low" configures all three Transmitters to sample the TPData_n and TNData_n data on the falling edge of the TxClk_n. <br> Host Mode <br> In the Host Mode this pin functions as SClk input pin please refer to the pin descriptions for the Microprocessor interface. |

## TRANSMIT LINE SIDE PINS

| PIN \# | SIGNAL NAME | TYPE | DESCRIPTION |
| :---: | :---: | :---: | :--- |
| 30 | TTIP_0 | O |  |
| TTIP_1 |  |  |  |
| 21 | TTIP_2 |  |  |

## TRANSMIT LINE SIDE PINS

| PIN \# | Signal Name | TYPE | Description |
| :---: | :---: | :---: | :---: |
| $\begin{gathered} \hline 31 \\ 6 \\ 17 \end{gathered}$ | $\begin{aligned} & \hline \text { MTIP_0 } \\ & \text { MTIP_1 } \\ & \text { MTIP_2 } \end{aligned}$ | 1 | Monitor Tip Input - Positive Polarity Signal - Channel 0: <br> Monitor Tip Input - Positive Polarity Signal - Channel 1: <br> Monitor Tip Input - Positive Polarity Signal - Channel 2: <br> These input pins along with MRING_n function as the Transmit Drive Monitor Output (DMO) input monitoring pins. To (1) monitor the Transmit Output line signal and (2) to perform this monitoring externally, then this pin MUST be connected to the corresponding TTIP_n output pin via a 274 ohm series resistor. Similarly, the MRING_n input pin MUST also be connected to its corresponding TRING_n output pin via a 274 ohm series resistor. <br> The MTIP_n and MRING_n input pins will continuously monitor the Transmit Output line signal via the TTIP_n and TRING_n output pins for bipolar activity. If these pins do not detect any bipolar activity for 128 bit periods, then the Transmit Drive Monitor circuit will drive the corresponding DMO_n output pin "High" in order to denote a possible fault condition in the Transmit Output Line signal path. <br> Notes: <br> 1. These input pins are inactive if the user choose to internally monitor the Transmit Output line signal. <br> 2. Internal Monitoring is only available as an option if the XRT75R03 in is being operated in the Host Mode. |
| $\begin{gathered} \hline 32 \\ 5 \\ 16 \end{gathered}$ | MRing_0 MRing_1 MRing_2 | I | Monitor Ring Input - Channel 0: <br> Monitor Ring Input - Channel 1: <br> Monitor Ring Input - Channel 2: <br> These input pins along with MTIP_n function as the Transmit Drive Monitor Output (DMO) input monitoring pins. To (1) monitor the Transmit Output line signal and (2) to perform this monitoring externally, then this input pin MUST be connected to the corresponding TRING_n output pin via a 274 ohm series resistor. Similarly, the MTIP_n input pin MUST be connected to its corresponding TTIP_n output pin via a 274 ohm series resistor. <br> The MTIP_n and MRING_n input pins will continuously monitor the Transmit Output line signal via the TTIP_n and TRING_n output pins for bipolar activity. If these pins do not detect any bipolar activity for 128 bit periods, then the Transmit Drive Monitor circuit will drive the corresponding DMO_n output pin "High" to indicate a possible fault condition in the Transmit Output Line signal path. <br> Notes: <br> 1. These input pins are inactive if the user chooses to internally monitor the Transmit Output line signal. <br> 2. Internal Monitoring is only available as an option if the XRT75R03 is being operated in the Host Mode. |

## SYSTEM-SIDE RECEIVE OUTPUT AND RECEIVE CONTROL PINS

| Pin \# | Signal Name | TYPE | Description |
| :---: | :---: | :---: | :---: |
| $\begin{gathered} 60 \\ 104 \\ 63 \end{gathered}$ | $\begin{aligned} & \text { RLOS_0 } \\ & \text { RLOS_1 } \\ & \text { RLOS_2 } \end{aligned}$ | O | Receive Loss of Signal Output Indicator - Channel 0: <br> Receive Loss of Signal Output Indicator - Channel 1: <br> Receive Loss of Signal Output Indicator - Channel 2: <br> This output pin indicates whether or not the corresponding channel is declaring the Loss of Signal (LOS) Defect condition. <br> "Low" - Indicates that the corresponding Channel is NOT currently declaring the LOS defect condition. <br> "High" - Indicates that the corresponding Channel is currently declaring the LOS defect condition. |
| $\begin{gathered} 61 \\ 103 \\ 64 \end{gathered}$ | RLOL_0 <br> RLOL_1 <br> RLOL_2 | 0 | Receive Loss of Lock Output Indicator - Channel 0: <br> Receive Loss of Lock Output Indicator - Channel 1: <br> Receive Loss of Lock Output Indicator - Channel 2: <br> This output pin indicates whether or not the corresponding channel is declaring the Loss of Lock (LOL) Condition. <br> "Low" - Indicates that the corresponding Channel is NOT declaring the LOL condition. <br> "High" - Indicates that the corresponding Channel is currently declaring the LOL condition. <br> Note: The Receive Section of a given channel will declare the LOL condition anytime the frequency of the Recovered Clock (RCLK) signal differs from that of the E3CLK input clock signal (if the channel is operating in the E3 Mode), the DS3CLK input clock signal (if the channel is operating in the DS3 Mode) the STS-1CLK input clock signal (if the channel is operating in the STS-1 Mode), or that clock signal which is derived from the SFM Clock Synthesizer block (if the chip is operating in the Single-Frequency Mode) by $0.5 \%$ (or 5000ppm) or more. |
| $\begin{gathered} 58 \\ 112 \\ 53 \end{gathered}$ | $\begin{aligned} & \hline \text { RPOS_0/ } \\ & \text { RDATA_0 } \\ & \text { RPOS_1/ } \\ & \text { RDATA_1 } \\ & \text { RPOS_2/ } \\ & \text { RDATA_2 } \end{aligned}$ | O | Receive Positive Data Output - Receive Data Output - Channel 0: Receive Positive Data Output - Receive Data Output - Channel 1: Receive Positive Data Output - Receive Data Output - Channel 2: <br> The function of these output pins depends upon whether the channel/device has been configured to operate in the Single-Rail or Dual-Rail Mode. <br> Dual-Rail Mode - Receive Positive Polarity Data Output <br> If the channel/device has been configured to operate in the Dual-Rail Mode, then all positive-polarity data will be output via this output pin. The negativepolarity data will be output via the corresponding RNEG_n output pin. In other words, the Receive Section of the corresponding Channel will pulse this output pin "High" for one period of RCLK_n anytime it receives a positive-polarity pulse via the RTIP/RRING input pins. <br> The data that is output via this pin is updated upon a user-selectable edge of the RCLK_n output clock signal. <br> Single-Rail Mode - Receive Data Output <br> If the channel/device has been configured to operate in the Single-Rail Mode, then all Receive (or Recovered) data will be output via this output pin. <br> The data that is output via this pin is updated upon a user-selectable edge of the RCLK_n output clock signal. |

## SYSTEM-SIDE RECEIVE OUTPUT AND RECEIVE CONTROL PINS

| Pin \# | Signal Name | TYPE | Description |
| :---: | :---: | :---: | :---: |
| 57 113 52 | RNEG_0/LCV_0 <br> RNEG_1/LCV_1 <br> RNEG_2/LCV_2 | 0 | Receive Negative Data Output/Line Code Violation Indicator Channel 0: <br> Receive Negative Data Output/Line Code Violation Indicator Channel 1: <br> Receive Negative Data Output/Line Code Violation Indicator Channel 2: <br> The function of these pins depends on whether the XRT75R03 is configured in Single Rail or Dual Rail mode. <br> Dual-Rail Mode - Receive Negative Polarity Data Output <br> If the channel/device has been configured to operate in the Dual-Rail Mode, then all negative-polarity data will be output via this output pin. The positivepolarity data will be output via the corresponding RPOS_n output pin. In other words, the Receive Section of the corresponding Channel will pulse this output pin "High" for one period of RCLK_n anytime it receives a negative-polarity pulse via the RTIP/RRING input pins. <br> The data that is output via this pin is updated upon a user-selectable edge of the RCLK_n output clock signal. <br> Single-Rail Mode - Line Code Violation Indicator Output <br> If the channel/device has been configured to operate in the Single-Rail Mode, then this particular output pin will function as the Line Code Violation indicator output. <br> In this configuration, the Receive Section of the Channel will pulse this output pin "High" for at least one RCLK period whenever it detects either an LCV (Line Code Violation) or an EXZ (Excessive Zero Event). <br> The data that is output via this pin is updated upon a user-selectable edge of the RCLK_n output clock signal. |
| $\begin{gathered} 56 \\ 114 \\ 51 \end{gathered}$ | $\begin{aligned} & \text { RxClk_0 } \\ & \text { RxClk_1 } \\ & \text { RxClk_2 } \end{aligned}$ | 0 | Receive Clock Output - Channel 0: <br> Receive Clock Output - Channel 1: <br> Receive Clock Output - Channel 2: <br> This output pin functions as the Receive or recovered clock signal. All Receive (or recovered) data will output via the RPOS_n and RNEG_n outputs upon the user-selectable edge of this clock signal. <br> Additionally, if the device/channel has been configured to operate in the SingleRail Mode, then the RNEG_n/LCV_n output pins will also be updated upon the user-selectable edge of this clock signal. |
| $\begin{aligned} & 75 \\ & 95 \\ & 84 \end{aligned}$ | REQEN_0 <br> REQEN_1 <br> REQEN_2 | I | Receive Equalization Enable Input - Channel 0: <br> Receive Equalization Enable Input - Channel 1: <br> Receive Equalization Enable Input - Channel 2: <br> These input pins are used to either enable or disable the Receive Equalizer block within the Receive Section of the corresponding channel. <br> "Low" - Disables the Receive Equalizer within the corresponding channel. <br> "High" - Enables the Receive Equalizer within the corresponding channel. <br> Notes: <br> 1. For virtually all applications, it is recommend that this input pin be pulled "High" and enable the Receive Equalizer. <br> 2. This input pin ignored and should be tied to GND if the XRT75R03 device has been configured to operate in the Host Mode. <br> 3. These input pins are internally pulled low. |

## SYSTEM-SIDE RECEIVE OUTPUT AND RECEIVE CONTROL PINS

| Pin \# | Signal Name | TYPE | Description |
| :---: | :---: | :---: | :---: |
| 71 | LOSMUT/ <br> INT | I/O | Muting Upon LOS Enable/Interrupt Output Pin <br> This input pin is used to configure the Receive Section, in each of the three channels within the chip, to automatically pull their corresponding Recovered Data Output pins (e.g. RPOS_n and RNEG_n) to GND anytime and for the duration that the Receive Section declares the LOS defect condition. In other words, this feature if enabled will cause the Receive Channel to automatically mute the Recovered data anytime and for the duration that the Receive Section declares the LOS defect condition. <br> "Low" - Disables the Muting upon LOS feature. In this setting the Receive Section will NOT automatically mute the Recovered Data whenever it is declaring the LOS defect condition. <br> "High" - Enables the Muting upon LOS feature. In this setting the Receive Section will automatically mute the Recovered Data whenever it is declaring the LOS defect condition. <br> Notes: <br> 1. This input pin is will function as the Interrupt Request output pin within the Microprocessor Serial Interface, if the XRT75R03 has been configured to operate in the Host Mode. <br> 2. This configuration setting applies globally to each of the three (3) channels within the XRT75R03. |
| 99 | LOSTHR | 1 | Analog LOS Detector Threshold Level Select Input: <br> This input pin permits the user to select both of the following parameters for the Analog LOS Detector within each of the three Receive Sections within the XRT75R03 device. <br> 1. The Analog LOS Defect Declaration Threshold (e.g., the maximum signal level that the Receive Section of a given channel must detect before declaring the LOS Defect condition), and <br> 2. The Analog LOS Defect Clearance Threshold (e.g., the minimum signal level that the Receive Section of a given channel must detect before clearing the LOS Defect condition) <br> Setting this input pin "High" selects one set of Analog LOS Defect Declaration and Clearance thresholds. Setting this input pin "Low" selects the other set of Analog LOS Defect Declaration and Clearance thresholds. <br> Please see Table 10 for more details. <br> Note: This input pin is only active if at least one channel within the XRT75R03 has been configured to operate in the DS3 or STS-1 Modes. |

## SYSTEM-SIDE RECEIVE OUTPUT AND RECEIVE CONTROL PINS

| Pin \# | Signal Name | TYPE | Description |
| :---: | :---: | :---: | :---: |
| 69 | $\begin{aligned} & \text { RxMON/ } \\ & \text { SDO } \end{aligned}$ | I | Receiver Monitor Mode Enable: <br> This input pin permits the user to configure each of the three (3) Receive Sections within the XRT75R03 device, into the Receiver Monitor Mode. <br> If the user configures each of the Receive Sections into the Receive Monitor Mode, then each of the Receiver Sections will be able to receive a nominal DSX-3/STSX-1 signal that has been attenuated by 20 dB of flat loss along with 6 dB of cable loss, in an error-free manner. This allows monitoring very weak signal, however the internal LOS circuitry is suppressed and LOS will never assert nor LOS be declared when operating under this mode. <br> "Low" - Configures each of the Receive Sections to operate in the Normal Mode. <br> "High" - Configures each of the Receive Sections to operate in the Receive Monitor Mode. <br> Notes: <br> 1. This input pin will function as the SDO (Serial Data Output pin within the Microprocessor Serial Interface) whenever the XRT75R03 has been configured to operate in the Host Mode. <br> 2. This configuration setting applies globally to all three (3) of the channels within the XRT75R03. <br> 3. In HOST Mode, each channel can be independently configured to be a monitoring channel by setting the bits in the channel control registers. |
| 68 | RxON/ SDI | I | Receive ON: <br> This input pin permits the user to either turn on or turn off each of the three (3) Receive Sections within the XRT75R03. If the user turns on the Receive Sections of each channel, then all three channels will begin to receive the incoming DS3, E3 or STS-1 data-streams via the RTIP_n and RRING_n input pins. <br> Conversely, if the user turns off the Receive Section, then the entire Receive Section (e.g., the AGC and Receive Equalizer blocks, Clock Recovery PLL, etc.) will be powered down. <br> "Low" - Shuts off the Receive Sections within each of the three (3) Channels in the XRT75R03. <br> "High" - Turns on the Receive Sections within each of the three (3) Channels in the XRT75R03. <br> Notes: <br> 1. This input pin will function as the SDI (Serial Data Input pin within the Microprocessor Serial Interface) whenever the XRT75R03 has been configured to operate in the Host Mode. <br> 2. This configuration setting applies globally to all three (3) of the channels within the XRT75R03 device. <br> 3. This pin is internally pulled low. |

## SYSTEM-SIDE RECEIVE OUTPUT AND RECEIVE CONTROL PINS

| PIN \# | Signal Name | TYPE | Description |
| :---: | :---: | :---: | :---: |
| 66 | $\begin{gathered} \text { RxClkINV/ } \\ \text { CS } \end{gathered}$ | I | Receive Clock Invert Input - Chip Selectl: <br> In Hardware Mode is pin is used to configure the Receive Sections of the three (3) channels in the XRT75R03 to either output the recovered data via the RPOS_n or RNEG_n/LCV_n output pins upon either the rising or falling edge of the RCLK_n clock output signal. <br> "Low" - Configures each of the Receive Sections to output the recovered data via the RPOS_n and RNEG_n/LCV_n output pins upon the rising edge of the RCLK_n output clock signal. <br> "High" - Configures each of the Receive Sections to output the recovered data via the RPOS_n and RNEG_n/LCV_n output pins upon the falling edge of the RCLK_n output clock signal. <br> Notes: <br> 1. This input pin will function as the $\overline{C S}$ (Chip Select Input pin) of the Microprocessor Serial Interface when the XRT75R03 has been configured to operate in the Host Mode. <br> 2. This configuration setting applies globally to all three (3) of the channels within the XRT75R03. <br> 3. If the Receive Sections are configured to operate in the Single-Rail Mode, then the LCV_n output pin will be updated on the user-selected edge of the RCLK_n signal, per this configuration selection. |
| 106 | SFM_EN | 1 | Single Frequency Mode Enable: <br> This input pin is used to configure the XRT75R03 to operate in the SFM (Single Frequency) Mode. <br> When this feature is invoked the Single-Frequency Mode Synthesizer will become active. By applying a 12.288 MHz clock signal to pin 109, STS-1CLK/ 12M the XRT75R03 will, depending upon which mode the user has configured each of the three channels, generate all of the appropriate clock signals (e.g., $34.368 \mathrm{MHz}, 44.736 \mathrm{MHz}$ or 51.84 . Further, the XRT75R03 internal circuitry will route each of these synthesized clock signals to the appropriate nodes of the corresponding three channels in the XRT75R03. <br> "Low" - Disables the Single Frequency Mode. In this configuration setting, the user is required to supply to the E3CLK, DS3CLK or STS-1CLK input pins all of the relevant clock signals that are to be used within the chip. <br> "High" - Enables the Single-Frequency Mode. A 12.288MHz clock signal MUST be applied to pin 109 (STS-1CLK/12M). <br> Note: This input pin is internally pulled low. |

## SYSTEM-SIDE RECEIVE OUTPUT AND RECEIVE CONTROL PINS

| PIN \# | SIGNAL NAME | TYPE | DESCRIPTION |
| :---: | :---: | :---: | :--- |
| 107 | E3CIK/ CLK_EN | I | E3 Reference Clock Input/SFM Clock Output Enable: <br> The function of this chip depends upon whether or not the XRT75R03 has been <br> configured to operate in the Single-Frequency Mode. <br> If NOT operating in the Single-Frequency Mode <br> If the XRT75R03 has NOT been configured to operate in the SFM (Single Fre- <br> quency) Mode, and if at least one channel is to be operated in the E3 Mode, <br> then a 34.368MHz $\pm$ 20ppm clock signal must be applied to this input pin. <br> If the user does not intend to operate the device in the SFM Mode nor operate <br> any of the channels in the E3 Mode tie this input signal to GND. <br> If operating in the Single-Frequency Mode <br> If the XRT75R03 is operated in the SFM Mode and is to output a clock signal <br> that is synthesized from the SFM Clock Synthesizer PLL so that the user's sys- <br> tem can use this clock signal as a timing source, pull this input pin to a logic <br> "High". <br> If the user pull this input pin "High", then the XRT75R03 will output the line rate <br> clock signal that has been synthesized for Channel 1, via pin 108 (DS3CLK/ <br> CLK_OUT). <br> For example, if Channel 1 is configured to operate in the STS-1 Mode and this <br> input pin is pulled "High", then the XRT75R03 will output a 51.84MHz clock sig- |
| nal via the CLK_OUT pin. |  |  |  |

## SYSTEM-SIDE RECEIVE OUTPUT AND RECEIVE CONTROL PINS

| Pin \# | Signal Name | TYPE | Description |
| :---: | :---: | :---: | :---: |
| 108 | DS3CIk/ CLK_OUT | I/O | DS3 Reference Clock Input/SFM Synthesizer Clock Output: <br> The function of this chip depends upon whether or not the XRT75R03 has been configured to operate in the SFM Mode. <br> If NOT operating in the Single-Frequency Mode <br> If the XRT75R03 has NOT been configured to operate in the SFM Mode, and if at least one channel of the XRT75R03 is configured in the DS3 Mode, then a clock signal with a frequency of $44.736 \mathrm{MHz} \pm 20 \mathrm{ppm}$ must be applied to this input pin. <br> If the XRT75R03 is not configured to operate in the SFM Mode and none of the channels are to be operated in the DS3 Mode, tie this input signal to GND. <br> If operating in the Single-Frequency Mode <br> If the XRT75R03 is configured to operate in the SFM Mode, and if pin 107 (E3CLK/CLKEN) is pulled to a logic "High", then the SFM Clock Synthesizer PLL generated line rate clock signal for Channel 1 will be output via this output pin. <br> In this mode, this particular output pin can be used by the user's system as a timing source. |
| 109 | STS-1Clk/ 12M | I | STS-1 Reference Clock Input/12.288MHz SFM Reference Clock Input: <br> The function of this pin depends upon whether or not the XRT75R03 has been configured to operate in the SFM Mode. <br> If NOT operating in the Single-Frequency Mode <br> If the XRT75R03 has NOT been configured to operate in the SFM Mode and if at least one channel is intended to operate in the STS-1 Mode, then the user must supply a clock signal with a frequency of $51.84 \mathrm{MHz} \pm 20 \mathrm{ppm}$ to this input pin <br> If the XRT75R03 is not to be operatedin the SFM Mode and none of the channels are to be operated in the STS-1 Mode, tie this input signal to GND. <br> If operating in the Single-Frequency Mode <br> If the XRT75R03 has been configured to operate in the SFM Mode a clock signal with a frequency of $12.288 \mathrm{MHz} \pm 20 \mathrm{ppm}$ MUST be applied to this input pin. The SFM Synthesizer will then synthesize all of the appropriate line rate frequencies (e.g., 34.368 MHz for E3, 44.736 MHz for DS3, and 51.84 MHz for STS- <br> 1) based upon this 12.288 MHz Reference Clock source. |

## RECEIVE LINE SIDE PINS

| PIN \# | SIGNAL NAME | TYPE | DESCRIPTION |  |
| :---: | :---: | :---: | :--- | :--- |
| 79 | RTIP_0 | I | Receive TIP Input - Channel 0: <br> Receive TIP Input - Channel 1: <br> Receive TIP Input - Channel 2: <br> R8 <br> RTIP_1 <br> RTIP_2 |  |
| These input pins along with the corresponding RRing_n input pin function as the |  |  |  |  |
| Receive DS3/E3/STS-1 Line input signal receiver for a given channel of the |  |  |  |  |
| XRT75R03. |  |  |  |  |
| Cconnect this signal and the corresponding RRING_n input signal to a 1:1 |  |  |  |  |
| Cransformer. |  |  |  |  |
| Whenever the RTIP/RRING input pins are receiving a positive-polarity pulse |  |  |  |  |
| within the incoming DS3, E3 or STS-1 line signal, then this input pin will be |  |  |  |  |
| pulsed to a "higher-voltage" than its corresponding RRING_n input pin. |  |  |  |  |
| Conversely, whenever the RTIP/RRING input pins are receiving a negative- |  |  |  |  |
| polarity pulse within the incoming DS3, E3 or STS-1 line signal, then this input |  |  |  |  |
| pin will be pulsed to a "lower-voltage" than its corresponding RRING_n input |  |  |  |  |
| pin. |  |  |  |  |

## GENERAL CONTROL PINS

| Pin \# | Signal Name | TYPE | Description |
| :---: | :---: | :---: | :---: |
| 65 | SR/ $\overline{\mathrm{DR}}$ | I | Single-Rail/Dual-Rail Select Input - Chip Level <br> This input pin is used to configure the XRT75R03 to operate in either the SingleRail or Dual-Rail Mode. <br> If the XRT75R03 is configured to operate in the Single-Rail Mode, then all of the following will happen. <br> - All of the B3ZS/HDB3 Encoder and Decoder blocks in the XRT75R03 will be enabled. <br> - The Transmit Section of each channel will accept all of the outbound data from the System-side Equipment via the TPDATA_n (or TxDATA_n) input pin. <br> - The Receive Section of each channel will output all of the recovered data to the System-side Equipment via the RPOS output pin. <br> - Each of the RNEG/LCV output pins will now function as the LCV (Line Code Violation or Excessive Zero Event) indicator output pin. <br> If the user configures the device to operate in the Dual-Rail Mode, then all of the following will happen. <br> - All of the B3ZS/HDB3 Encoder and Decoder blocks in the XRT75R03 will be disabled. <br> - The Transmit Section of each channel will accept positive-polarity data via the TPDATA_n input pin, and negative-polarity data via the TNDATA_n input pin. <br> - The Receive Section of each channel will pulse the RPOS_n output pin "High" for one period of RCLK_n for each time a positive-polarity pulse is received via the RTIP_n/RRING_n input pins <br> - Likewise, the Receive Section of each channel will also pulse the RNEG_n output pin "High" for one period of RCLK_n for each time a negative-polarity pulse is received via the RTIP_n/RRING_n input pins. <br> "Low" - Configures the XRT75R03 device to operate in the Dual-Rail Mode. <br> "High" - Configures the XRT75R03 device to operate in the Single-Rail Mode. <br> Notes: <br> 1. This input pin is ignored and should be tied to GND if the XRT75R03 has been configured to operate in the Host Mode. <br> 2. This pin is internally pulled "Low". |
| $\begin{aligned} & 76 \\ & 94 \\ & 85 \end{aligned}$ | $\begin{aligned} & \text { E3_0 } \\ & \text { E3_1 } \\ & \text { E3_2 } \end{aligned}$ | I | E3 Mode Select Input - Channel 0 <br> E3 Mode Select Input - Channel1 <br> E3 Mode Select Input - Channel 2 <br> This input pin, along with the corresponding STS-1/ $\overline{\mathrm{DS3}} \_\mathrm{n}$ input pin is used the to configure a given channel within the XRT75R03 into either the DS3, E3 or STS-1 Modes. <br> "High" - Configures the corresponding channel to operate in the E3 Mode. <br> "Low" - Configures the corresponding channel to operate in either the DS3 or STS-1 Modes, depending upon the setting of the corresponding STS-1/DS3_n input pin. <br> Notes: <br> 1. This input pin is ignored and should be tied to GND if the XRT75R03 has been configured to operate in the Host Mode. <br> 2. This input pin is internally pulled low. |

## GENERAL CONTROL PINS

| Pin \# | Signal Name | TYPE | Description |
| :---: | :---: | :---: | :---: |
| $\begin{aligned} & 72 \\ & 98 \\ & 81 \end{aligned}$ |  | I | STS-1/DS3 Select Input - Channel 0 <br> STS-1/DS3 Select Input - Channel 1 <br> STS-1/DS3 Select Input - Channel 2 <br> This input pin, along with the corresponding E3_n input pin is used the to configure a given channel within the XRT75R03 into either the DS3, E3 or STS-1 Modes. <br> "High" - Configures the corresponding channel to operate in the STS-1 Mode provided that the corresponding E3_n input pin is pulled "Low". <br> "Low" - Configures the corresponding channel to operate in DS3 Mode provided that the corresponding E3_n input pin is pulled "Low". <br> Notes: <br> 1. This input pin is ignored and should be tied to GND if the XRT75R03 has been configured to operate in the Host Mode or if the corresponding E3_n input pin is pulled "High". <br> 2. This input pin is internally pulled low. |
| $\begin{aligned} & 74 \\ & 96 \\ & 83 \end{aligned}$ | $\begin{aligned} & \hline \text { RLB_0 } \\ & \text { RLB_1 } \\ & \text { RLB_2 } \end{aligned}$ | I | Remote Loop-back - RLB Input - Channel 0: <br> Remote Loop-back - RLB Input - Channel 1: <br> Remote Loop-back - RLB Input - Channel 2: <br> This input pin along with LLB_n is used to configure different Loop-Back modes. <br> Note: This input pin is ignored and should be connected to GND if the XRT75R03 is operating in the HOST Mode. |
| $\begin{aligned} & \hline 73 \\ & 97 \\ & 82 \end{aligned}$ | $\begin{aligned} & \text { LLB_0 } \\ & \text { LLB_1 } \\ & \text { LLB_2 } \end{aligned}$ | 1 | Loop-Back Select - LLB Input - Channel 0 Loop-Back Select - LLB Input - Channel 1 Loop-Back Select - LLB Input - Channel 2 Please see description above for RLB_n |
| 102 | TEST | **** | Factory Test Mode Input Pin <br> This pin must be connected to GND for normal operation. <br> Note: This input pin is internally pulled "Low". |

GENERAL CONTROL PINS

| Pin \# | SIGNAL NAME | TYPE | DESCRIPTION |
| :---: | :---: | :---: | :--- |
| 62 | ICT | I | In-Circuit Test Input: <br> Setting this pin "Low" causes all digital and analog outputs to go into a high- <br> impedance state to allow for in-circuit testing. For normal operation, set this pin <br> "High". <br> Note: This pin is internally pulled "High". |
| 70 | HOST/HW | I | HOST/Hardware Mode Select: <br> Tie this pin "High" to configure the XRT75R03 in HOST mode. Tie this "Low" to <br> configure in Hardware mode. <br> When the XRT75R03 is configured in HOST mode, the states of many of the dis- <br> crete input pins are controlled by internal register bits. <br> Note: This pin is internally pulled up. |

## CONTROL AND ALARM INTERFACE

| Pin \# | Signal Name | Type | Description |
| :---: | :---: | :---: | :--- |
| 122 | RXA | $* * * *$ | External Resistor of $3.01 \mathrm{~K} \Omega \pm 1 \%$. <br> Should be connected between RxA and RxB for internal bias. |
| 123 | RXB | $* * * *$ | External Resistor of $3.01 \mathrm{~K} \Omega \pm 1 \%$. <br> Should be connected between RxA and RxB for internal bias. |

## JITTER ATTENUATOR INTERFACE

| Pin \# | SIGNAL NAME | TYPE | DESCRIPTION |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 44 | JAO | I | Jitter Attenuator Select 0: <br> In Hardware Mode, this pin along with pin 42 configures the Jitter Attenuator as <br> shown in the table below. |  |  |

## JITTER ATTENUATOR INTERFACE

| 42 | JA1 | I | Jitter Attenuator Select 1: <br> Please see the Description above for JA0 |
| :---: | :---: | :---: | :--- |
| 43 | JATx/Rx | I | Jitter Attenuator in Transmit/Receive Path Select Input: <br> This input pin is used to configure the Jitter Attenuator to operate in either the <br> Transmit or Receive path within each of the three (3) channels of the <br> XRT75R03. <br> "Low" - Configures the Jitter Attenuator within each channel to operate in the <br> Receive Path. <br> "High" - Configures the Jitter Attenuator within each channel to operate in the <br> Transmit Path. <br> Notes: <br> 1.The setting of this input pin applies globally to all three (3) channels of <br> the XRT75R03. <br> 2. <br> This input pin is ignored and should be tied to GND if the XRT75R03 is <br> configured to operate in the Host Mode or if the Jitter Attenuators are <br> disabled. |

Microprocessor Serial INTERFACE - (HOST MODE)

| PIN \# | SIGNAL NAME | TYPE | DESCRIPTION |
| :---: | :---: | :---: | :--- |
| 69 | SDO/RxMON | I/O | Microprocessor Serial Interface - Serial Data Output: <br> This pin serially outputs the contents of a specified on-chip Command Register <br> during READ Operations via the Microprocessor Serial Interface. The data <br> which is output via this pin is updated upon the falling edge of the SCLK clock <br> signal. <br> This output pin will be tri-stated upon completion of a given READ operation. <br> Note: This pin functions as the RxMON input pin if the XRT75R03 has been <br> configured to operate in the Hardware Mode. |
| 68 | SDI/RxON | I | Microprocessor Serial Interface - Serial Data Input: <br> This input pin functions as the Serial Data Input pin for the Microprocessor <br> Serial Interface. In particular, this input pin will accept all of the following data in <br> a serial manner during READ and WRITE operations with the Microprocessor <br> Serial Interface. <br> - The READ/WRITE indicator bit. <br> - The Address Value of the Targeted Command Register for this particular <br> READ or WRITE operation. <br> - The Data to be written into the targeted Command Register for a given <br> WRITE operation. <br> All data that is applied to this input will be sampled upon the rising edge of the <br> SCLK input clock signal. <br> NotE: This input pin will function as the RxON input pin if the XRT75R03 has <br> been configured to operate in the Hardware Mode. |

Microprocessor Serial INTERFACE - (HOST MODE)

| Pin \# | Signal Name | TYPE | DESCRIPTION |
| :---: | :---: | :---: | :---: |
| 67 | SCIk/TCLKINV | I | Microprocessor Serial Interface -Serial Clock Input: <br> This input pin functions as the Clock Source for the Microprocessor Serial Interface. <br> Each time the user wishes to perform a READ or WRITE operate with the onchip Command Registers via the Microprocessor Serial Interface, the user MUST do the following. <br> - Assert the $\overline{\mathrm{CS}}$ input pin by toggling it "Low", and <br> - Provide 16 Clock Periods to this particular input pin for each READ and WRITE operation. <br> The Microprocessor Serial Interface will sample any data residing upon the SDI input pin, upon the rising edge of this clock signal. Further, for READ operations, the Microprocessor Serial Interface will serially output the contents of a target Command Register upon the falling edge of this clock signal. <br> Note: The maximum frequency of this particular clock signal is 10 MHz . |
| 66 | CS/RCLKINV | I | Microprocessor Serial Interface - Chip Select Input: <br> This input pin should be pulled "Low" whenever a READ or WRITE operation is to be executed to the on-chip Command Registers, via the Microprocessor Serial Interface. <br> This input pin should remain "Low" until the READ or WRITE operation has been completed. This input pin should be pulled "High" at all other times. <br> Note: If the XRT75R03 has been configured to operate in the Host Mode then this input pin will function as the RCLKINV input pin. |
| 71 | INT/LOSMUT | 0 | Microprocessor Serial Interface - Interrupt Request Output: <br> If the XRT75R03 has been configured to operate in the Host Mode, then this pin becomes the Interrupt Request Output for the XRT75R03. <br> During normal conditions, this output pin will be pulled "High". However, if the user enables certain interrupts within the device, and if those conditions occur, then the XRT75R03 will request an interrupt from the Microprocessor by toggling this output pin "Low". <br> Notes: <br> 1. If the XRT75R03 device is configured to operate in the Hardware Mode, then this pin functions as the LOSMUT input pin. <br> 2. This pin will remain "Low" until the Interrupt has been served. |
| 101 | RESET | 1 | Microprocessor Serial Interface - H/W RESET Input: <br> Pulsing this input "Low" causes the XRT75R03 to reset the contents of the onchip Command Registers to their default values. As a consequence, the XRT75R03 will then also be operating in its default condition. <br> For normal operation pull this input pin to a logic "High". <br> Note: This input pin is internally pulled high. |

POWER SUPPLY AND GROUND PINS

| PIN \# | PIn NAME | TYPE | DESCRIPTION |
| :---: | :--- | :---: | :--- |
| Receive ANALOG VDD |  |  |  |
| 77 | RxAVDD_0 | $* * * *$ |  |
| 93 | RxAVDD_1 |  |  |
| 86 | RxAVDD_2 |  |  |

POWER SUPPLY AND GROUND PINS


## XRT75R03 PIN LISTING IN NUMERICAL ORDER

| Pin \# | Pin Name | TYPE | Comments |
| :---: | :---: | :---: | :---: |
| 1 | TxON_1 | 1 | This input pin is internally pulled "High". |
| 2 | TNDATA_1 | I |  |
| 3 | TPDATA_1 | I |  |
| 4 | TxCLK_1 | I |  |
| 5 | MRING_1 | I |  |
| 6 | MTIP_1 | 1 |  |
| 7 | TAOS_1 | I | 1. Not Active while in Host Mode <br> 2. This input pin is internally pulled low. |
| 8 | TAOS_2 | I | 1. Not Active while in Host Mode <br> 2. This input pin is internally pulled low. |
| 9 | TxLEV_1 | 1 | 1. Not Active while in Host Mode <br> 2. This input pin is internally pulled low. |
| 10 | TxLEV_2 | I | 1. Not Active while in Host Mode <br> 2. This input pin is internally pulled low. |
| 11 | TTIP_1 | O |  |
| 12 | DVDD | *** |  |
| 13 | TRING_1 | 0 |  |
| 14 | TxAGND_1 | *** |  |
| 15 | TxAGND_2 | *** |  |
| 16 | MRING_2 | I |  |
| 17 | MTIP_2 | 1 |  |
| 18 | GND | *** |  |
| 19 | TRING_2 | O |  |
| 20 | TxVDD_2 | *** |  |
| 21 | TTIP_2 | 0 |  |
| 22 | DMO_2 | O |  |
| 23 | TxAVDD_2 | *** |  |
| 24 | TNDATA_2 | I |  |
| 25 | TPDATA_2 | I |  |
| 26 | TxCLK_2 | 1 |  |
| 27 | TxGND_0 | *** |  |
| 28 | TRING_0 | 0 |  |
| 29 | TxVDD_0 | *** |  |

## XRT75R03 PIN LISTING IN NUMERICAL ORDER

| Pin \# | Pin Name | TYPE | Comments |
| :---: | :---: | :---: | :---: |
| 30 | TTIP_0 | O |  |
| 31 | MTIP_0 | 1 |  |
| 32 | MRING_0 | 1 |  |
| 33 | TNDATA_0 | 1 |  |
| 34 | TPDATA_0 | 1 |  |
| 35 | TxCLK_0 | 1 |  |
| 36 | TxLEV_0 | I | 1. Not Active while in Host Mode <br> 2. This input pin is internally pulled low. |
| 37 | TAOS_0 | I | 1. Not Active while in Host Mode <br> 2. This input pin is internally pulled low. |
| 38 | TxON_0 | I | This input pin is internally pulled "High". |
| 39 | TxAVDD_0 | *** |  |
| 40 | DMO_0 | 0 |  |
| 41 | TxAGND_0 | *** |  |
| 42 | JA1 | I | Not Active while in Host Mode |
| 43 | JATx/ $\overline{R x}$ | I | Not Active while in Host Mode |
| 44 | JAO | 1 | Not Active while in Host Mode |
| 45 | JAVDD_2 | *** |  |
| 46 | JAVDD_0 | *** |  |
| 47 | JAGND_0 | *** |  |
| 48 | JAGND_2 | *** |  |
| 49 | AGND_0 | *** |  |
| 50 | RxDGND_2 | *** |  |
| 51 | RCLK_2 | 0 |  |
| 52 | RNEG_2/LCV_2 | 0 |  |
| 53 | RPOS_2 | 0 |  |
| 54 | RxDVDD_2 | *** |  |
| 55 | RxDVDD_0 | *** |  |
| 56 | RCLK_0 | 0 |  |
| 57 | RNEG_0/LCV_0 | 0 |  |
| 58 | RPOS_0 | O |  |
| 59 | RxDGND_0 | *** |  |
| 60 | RLOS_0 | 0 |  |
| 61 | RLOL_0 | O |  |

THREE CHANNEL E3/DS3/STS-1 LINE INTERFACE UNIT WITH JITTER ATTENUATOR

## XRT75R03 PIN LISTING IN NUMERICAL ORDER

| Pin \# | Pin Name | TYPE | Comments |
| :---: | :---: | :---: | :---: |
| 62 | ICT | I | This input pin is internally pulled low. |
| 63 | RLOS_2 | 0 |  |
| 64 | RLOL_2 | 0 |  |
| 65 | SR/ $\overline{\mathrm{DR}}$ | I | 1. Not Active while in Host Mode <br> 2. This input pin is internally pulled low. |
| 66 | RCLKINV ( $\overline{\mathrm{CS}}$ ) | I |  |
| 67 | TCLKINV (SCLK) | 1 |  |
| 68 | RxON (SDI) | 1 | This input pin is internally pulled low. |
| 69 | RxMON (SDO) | I/O |  |
| 70 | HOST/HW | 1 | This input pin is internally pulled low. |
| 71 | LOSMUT (INT) | I/O |  |
| 72 | STS-1/[)] | I | 1. Not Active while in Host Mode <br> 2. This input pin is internally pulled low. |
| 73 | LLB_0 | 1 | Not Active while in Host Mode |
| 74 | RLB_0 | I | Not Active while in Host Mode |
| 75 | REQEN_0 | I | 1. Not Active while in Host Mode <br> 2. This input pin is internally pulled low. |
| 76 | E3_0 | 1 | 1. Not Active while in Host Mode <br> 2. This input pin is internally pulled low. |
| 77 | RxAVDD_0 | *** |  |
| 78 | RRING_0 | 1 |  |
| 79 | RTIP_0 | I |  |
| 80 | RxAGND_0 | *** |  |
| 81 | STS-1/(̄)3_2 | I | 1. Not Active while in Host Mode <br> 2. This input pin is internally pulled low. |
| 82 | LLB_2 | I | Not Active while in Host Mode |
| 83 | RLB_2 | I | Not Active while in Host Mode |
| 84 | REQEN_2 | I | 1. Not Active while in Host Mode <br> 2. This input pin is internally pulled low. |
| 85 | E3_2 | I | 1. Not Active while in Host Mode <br> 2. This input pin is internally pulled low. |
| 86 | RxAVDD_2 | *** |  |
| 87 | RRING_2 | I |  |
| 88 | RTIP_2 | I |  |
| 89 | RxAGND_2 | *** |  |
| 90 | RxAGND_1 | *** |  |

## XRT75R03 PIN LISTING IN NUMERICAL ORDER

| Pin \# | Pin Name | TYPE | Comments |
| :---: | :---: | :---: | :---: |
| 91 | RTIP_1 | I |  |
| 92 | RRING_1 | 1 |  |
| 93 | RxAVDD_1 | *** |  |
| 94 | E3_1 | 1 | 1. Not Active while in Host Mode <br> 2. This input pin is internally pulled low. |
| 95 | REQEN_1 | 1 | 1. Not Active while in Host Mode <br> 2. This input pin is internally pulled low. |
| 96 | RLB_1 | I | Not Active while in Host Mode |
| 97 | LLB_1 | 1 | Not Active while in Host Mode |
| 98 | STS-1/[̄D3_1 | 1 | 1. Not Active while in Host Mode <br> 2. This input pin is internally pulled low. |
| 99 | LOSTHR | 1 |  |
| 100 | AGND_2 | *** |  |
| 101 | RESET | 1 | This input pin is internally pulled high. |
| 102 | TEST | 1 | This input pin is internally pulled low. |
| 103 | RLOL_1 | 0 |  |
| 104 | RLOS_1 | 0 |  |
| 105 | EXDGND | *** |  |
| 106 | SFM_EN | 1 | This input pin is internally pulled low. |
| 107 | E3CLK/CLK_EN | 1 |  |
| 108 | $\begin{aligned} & \hline \text { DS3CLK/ } \\ & \text { CLK_OUT } \end{aligned}$ | I/O |  |
| 109 | STS-1CLK/12M | 1 |  |
| 110 | EXDVDD | *** |  |
| 111 | RxDVDD_1 | *** |  |
| 112 | RPOS_1 | 0 |  |
| 113 | RNEG_1/LCV_1 | 0 |  |
| 114 | RCLK_1 | 0 |  |
| 115 | RxDGND_1 | *** |  |
| 116 | AGND_1 | *** |  |
| 117 | JADGND | *** |  |
| 118 | JAGND_1 | *** |  |
| 119 | JADVDD | *** |  |
| 120 | JADVDD_1 | *** |  |
| 121 | REFAVDD | *** |  |

## XRT75R03 PIN LISTING IN NUMERICAL ORDER

| Pin \# | Pin NAme | Type | Comments |
| :---: | :---: | :---: | :--- |
| 122 | RXA | $* * *$ |  |
| 123 | RXB | $* * *$ |  |
| 124 | REFGND | $* * *$ |  |
| 125 | TxON_2 | I | This input pin is internally pulled "High". |
| 126 | TxAGND_1 | ${ }^{* * *}$ |  |
| 127 | DMO_1 | 0 |  |
| 128 | TxAVDD_1 | $* * *$ |  |

## $1.0 \mathrm{R}^{3}$ TECHNOLOGY (RECONFIGURABLE, RELAYLESS REDUNDANCY)

Redundancy is used to introduce reliability and protection into network card design. The redundant card in many cases is an exact replicate of the primary card, such that when a failure occurs the network processor can automatically switch to the backup card. EXAR's $R^{3}$ technology has re-defined E3/DS-3/STS-1 LIU design for $1: 1$ and $1+1$ redundancy applications. Without relays and one Bill of Materials, EXAR offers multi-port, integrated LIU solutions to assist high density agregate applications and framing requirements with reliability. The following section can be used as a reference for implementing $R^{3}$ Technology with EXAR's world leading line interface units.

### 1.1 Network Architecture

A common network design that supports $1: 1$ or $1+1$ redundancy consists of N primary cards along with N backup cards that connect into a mid-plane or back-plane architecture without transformers installed on the network cards. In addition to the network cards, the design has a line interface card with one source of transformers, connectors, and protection components that are common to both network cards. Wtih this design, the bill of materials is reduced to the fewest amount of components. See Figure 3 for a simplified block diagram of a typical redundancy design.
Figure 3. Network Redundancy Architecture


### 1.2 Power Failure Protection

EXAR's "High" impedance circuits protect the LIU and preserve the line impedance characteristics when a power failure occurs. As the power supply decreases to a pre-determined voltage, the I/O pads are automatically switched to "High" impedance. This effectively removes the LIU, preventing a line impedance mismatch or system degradation. Power failures or network card hot swapping change the network circuit. It is critical that under these circumstances, that the primary card still behaves according to network standards. The three sensitive specifications are pulse mask conformance, receive sensitivity and return loss. Each must be carefully characterized to ensure network integrity and reliability.

### 1.3 Software vs Hardware Automatic Protection Switching

The implementation of $R^{3}$ technology can be controlled through programming the internal registers or through the use of the TxON hardware pin available within the LIU. To use software to tri-state the transmitters, first the TxON pin must be pulled "High". Once the pin is pulled "High", the individual register bits can be used to control the output activity of the transmit path. To use the TxON pin, the individual register bits can be set "High", and the control of the transmitters is handled by setting the state of the TxON pin.

### 2.0 ELECTRICAL CHARACTERISTICS

Table 1: Absolute Maximum Ratings

| SYMBOL | Parameter | MIN | MAX | UNITS | COMMENTS |
| :---: | :---: | :---: | :---: | :---: | :---: |
| $\mathrm{V}_{\mathrm{DD}}$ | Supply Voltage | -0.5 | 6.0 | V | Note 1 |
| $\mathrm{V}_{\mathrm{IN}}$ | Input Voltage at any Pin | -0.5 | 5.5 | V | Note 1 |
| $\mathrm{I}_{\mathrm{IN}}$ | Input current at any pin |  | 100 | mA | Note 1 |
| $\mathrm{S}_{\text {TEMP }}$ | Storage Temperature | -65 | 150 | ${ }^{0} \mathrm{C}$ | Note 1 |
| $\mathrm{A}_{\text {TEMP }}$ | Ambient Operating Temperature | -40 | 85 | ${ }^{0} \mathrm{C}$ | linear airflow 0 ft ./min |
| Theta JA | Thermal Resistance |  | 35 | ${ }^{0} \mathrm{C} / \mathrm{W}$ | linear airflow 0 ft ./min (See Note 3 below) |
| M LEVL | Exposure to Moisture | 5 |  | level | $\begin{gathered} \text { EIA/JEDEC } \\ \text { JESD22-A112-A } \end{gathered}$ |
| ESD | ESD Rating | 2000 |  | V | Note 2 |

Notes:

1. Exposure to or operating near the Min or Max values for extended period may cause permanent failure and impair reliability of the device.
2. ESD testing method is per MIL-STD-883D,M-3015.7
3. With Linear Air flow of $200 \mathrm{ft} / \mathrm{min}$, reduce Theta JA by $20 \%$, Theta JC is unchanged.

Table 2: DC Electrical Characteristics:

| SYMBOL | Parameter | MIN. | TYP. | MAX. | UNITS |
| :---: | :---: | :---: | :---: | :---: | :---: |
| DV ${ }_{\text {DD }}$ | Digital Supply Voltage | 3.135 | 3.3 | 3.465 | V |
| $A V_{\text {DD }}$ | Analog Supply Voltage | 3.135 | 3.3 | 3.465 | V |
| $\mathrm{I}_{\mathrm{CC}}$ | Supply current requirements |  | 410 | 470 | mA |
| $\mathrm{P}_{\mathrm{DD}}$ | Power Dissipation |  | 1.1 | 1.2 | W |
| $\mathrm{V}_{\mathrm{IL}}$ | Input Low Voltage |  |  | 0.8 | V |
| $\mathrm{V}_{\mathrm{IH}}$ | Input High Voltage | 2.0 |  | 5.5 | V |
| $\mathrm{V}_{\mathrm{OL}}$ | Output Low Voltage, $\mathrm{I}_{\text {OUT }}=-4 \mathrm{~mA}$ |  |  | 0.4 | V |
| $\mathrm{V}_{\mathrm{OH}}$ | Output High Voltage, $\mathrm{I}_{\text {OUT }}=4 \mathrm{~mA}$ | 2.4 |  |  | V |
| $\mathrm{I}_{\mathrm{L}}$ | Input Leakage Current ${ }^{1}$ |  |  | $\pm 10$ | $\mu \mathrm{A}$ |
| $\mathrm{C}_{1}$ | Input Capacitance |  |  | 10 | pF |
| $\mathrm{C}_{\mathrm{L}}$ | Load Capacitance |  |  | 10 | pF |

## Notes:

1. Not applicable for pins with pull-up or pull-down resistors.
2. The Digital inputs and outputs are TTL 5 V compliant.

### 3.0 TIMING CHARACTERISTICS

Figure 4. Typical interface between terminal equipment and the XRT75R03 (dual-rail data)


Figure 5. Transmitter Terminal Input Timing


| SYMBOL | PARAMETER | MIN | TYP | MAX | UNITS |
| :---: | :--- | :---: | :---: | :---: | :---: |
| TxClk | Duty Cycle | 30 | 50 | 70 | $\%$ |
|  | E3 |  | 34.368 |  | MHz |
|  | DS3 |  | 44.736 |  | MHz |
|  | STS-1 |  | 51.84 |  | MHz |
| $\mathrm{t}_{\text {RTX }}$ | TxClk Rise Time (10\% to 90\%) |  |  | 4 | ns |
| $\mathrm{t}_{\text {FTX }}$ | TxClk Fall Time (10\% to 90\%) |  |  | 4 | ns |
| $\mathrm{t}_{\text {TSU }}$ | TPData/TNData to TxClk falling set up time | 3 |  | ns |  |
| $\mathrm{t}_{\text {THO }}$ | TPData/TNData to TxClk falling hold time | 3 |  |  | ns |

Figure 6. Receiver Data output and code violation timing


Figure 7. Transmit Pulse Amplitude test circuit for E3, DS3 and StS-1 Rates


XRT75R03 (Only one channel shown)

### 4.0 LINE SIDE CHARACTERISTICS:

### 4.1 E3 line side parameters:

The XRT75R03 line output at the transformer output meets the pulse shape specified in ITU-T G. 703 for 34.368 Mbits/s operation. The pulse mask as specified in ITU-T G. 703 for $34.368 \mathrm{Mbits} / \mathrm{s}$ is shown in Figure 7.

Figure 8. Pulse Mask for E3 ( $\mathbf{3 4 . 3 6 8} \mathbf{~ m b i t s / s ) ~ i n t e r f a c e ~ a s ~ p e r ~ i t u - t ~ G . ~} 703$


Table 3: E3 Transmitter line side output and receiver line side input specifications

| PARAMETER | MIN | TYP | MAX | UNITS |
| :---: | :---: | :---: | :---: | :---: |
| Transmitter line side output characteristics |  |  |  |  |
| Transmit Output Pulse Amplitude (Measured at secondary of the transformer) | 0.90 | 1.00 | 1.10 | $\mathrm{V}_{\mathrm{pk}}$ |
| Transmit Output Pulse Amplitude Ratio | 0.95 | 1.00 | 1.05 |  |
| Transmit Output Pulse Width | 12.5 | 14.55 | 16.5 | ns |
| Transmit Intrinsic Jitter |  | 0.02 | 0.05 | UlPP |
| Receiver line side input characteristics |  |  |  |  |
| Receiver Sensitivity (length of cable) | 900 | 1200 |  | feet |
| Interference Margin | -20 | -14 |  | dB |
| Jitter Tolerance @ Jitter Frequency 800KHz | 0.15 | 0.28 |  | Ulpp |
| Signal level to Declare Loss of Signal |  |  | -35 | dB |
| Signal Level to Clear Loss of Signal | -15 |  |  | dB |
| Occurence of LOS to LOS Declaration Time | 10 |  | 255 | UI |
| Termination of LOS to LOS Clearance Time | 10 |  | 255 | UI |

Note: The above values are at $T A=25^{\circ} \mathrm{C}$ and $V_{D D}=3.3 V \pm 5 \%$.

Figure 9. Bellcore GR-253 CORE Transmit Output Pulse Template for SONET STS-1 Applications


Table 4: STS-1 Pulse Mask Equations

| Time in Unit Intervals | Normalized Amplitude |
| :---: | :---: |
| LOWER CURVE |  |
| $-0.85 \leq T \leq-0.38$ | -0.03 |
| $-0.38 \leq \mathrm{T} \leq 0.36$ | $\left.0.5\left[1+\sin \left\{\frac{\pi}{2} /\left(1+\frac{T}{0.18}\right)\right\},\right\}\right]-0.03$ |
| $0.36 \leq T \leq 1.4$ | - 0.03 |
| UPPER CURVE |  |
| $-0.85 \leq T \leq-0.68$ | 0.03 |
| $-0.68 \leq T \leq 0.26$ | $0.5\left[1+\sin \left\{\frac{\pi}{2}\left(1+\frac{T}{0.34}\right) l_{6}\right]+0.03\right.$ |
| $0.26 \leq T \leq 1.4$ | $0.1+0.61 \times \mathrm{e}^{-2.4[T-0.26]}$ |

Table 5: STS-1 Transmitter Line Side Output and Receiver Line Side Input Specifications (GR-253)

| Parameter | Min | TYP | MAX | UnITS |
| :---: | :---: | :---: | :---: | :---: |
| Transmitter line side output characteristics |  |  |  |  |
| Transmit Output Pulse Amplitude (measured with TxLEV $=0$ ) | 0.65 | 0.75 | 0.9 | $\mathrm{V}_{\mathrm{pk}}$ |
| Transmit Output Pulse Amplitude (measured with TxLEV = 1) | 0.90 | 1.00 | 1.10 | $\mathrm{V}_{\mathrm{pk}}$ |
| Transmit Output Pulse Width | 8.6 | 9.65 | 10.6 | ns |
| Transmit Output Pulse Amplitude Ratio | 0.90 | 1.00 | 1.10 |  |
| Transmit Intrinsic Jitter |  | 0.02 | 0.05 | $\mathrm{Ul}_{\mathrm{pp}}$ |
| Receiver line side input characteristics |  |  |  |  |
| Receiver Sensitivity (length of cable) | 900 | 1100 |  | feet |
| Jitter Tolerance @ Jitter Frequency 400 KHz | 0.15 |  |  | $\mathrm{Ul}_{\mathrm{pp}}$ |
| Signal Level to Declare Loss of Signal | Refer to Table 10 |  |  |  |
| Signal Level to Clear Loss of Signal | Refer to Table 10 |  |  |  |

Note: The above values are at $T A=25^{\circ} \mathrm{C}$ and $V_{D D}=3.3 V \pm 5 \%$.

Figure 10. Transmit Ouput Pulse Template for DS3 as per Bellcore Gr-499


Table 6: DS3 Pulse Mask Equations

| Time in Unit Intervals | Normalized Amplitude |
| :---: | :---: |
| LOWER CURVE |  |
| $-0.85 \leq T \leq-0.36$ | -0.03 |
| $-0.36 \leq T \leq 0.36$ | $0.5\left[1+\sin \left\{\frac{\pi}{2} /\left(1+\frac{T}{0.18}\right)\right.\right.$ ) $\}$ ] $]-0.03$ |
| $0.36 \leq T \leq 1.4$ | - 0.03 |
| UPPER CURVE |  |
| $-0.85 \leq T \leq-0.68$ | 0.03 |
| $-0.68 \leq T \leq 0.36$ | $\left.0.5\left[1+\sin \left\{\frac{\pi}{2} /\left(1+\frac{T}{0.34}\right)\right\},\right\}\right]+0.03$ |
| $0.36 \leq T \leq 1.4$ | $0.08+0.407 \times \mathrm{e}^{-1.84[T-0.36]}$ |

XRT75R03

Table 7: DS3 Transmitter Line Side Output and Receiver Line Side Input Specifications (GR-499)

| Parameter | Min | TYP | MAX | UnITS |
| :---: | :---: | :---: | :---: | :---: |
| Transmitter line side output characteristics |  |  |  |  |
| Transmit Output Pulse Amplitude (measured with TxLEV = 0) | 0.65 | 0.75 | 0.85 | $\mathrm{V}_{\mathrm{pk}}$ |
| Transmit Output Pulse Amplitude (measured with TxLEV = 1) | 0.90 | 1.00 | 1.10 | $\mathrm{V}_{\mathrm{pk}}$ |
| Transmit Output Pulse Width | 10.10 | 11.18 | 12.28 | ns |
| Transmit Output Pulse Amplitude Ratio | 0.90 | 1.00 | 1.10 |  |
| Transmit Intrinsic Jitter |  | 0.02 | 0.05 | $\mathrm{Ul}_{\mathrm{pp}}$ |
| Receiver line side input characteristics |  |  |  |  |
| Receiver Sensitivity (length of cable) | 900 | 1100 |  | feet |
| Jitter Tolerance @ 400 KHz (Cat II) | 0.15 |  |  | $\mathrm{Ul}_{\mathrm{pp}}$ |
| Signal Level to Declare Loss of Signal | Refer to Table 10 |  |  |  |
| Signal Level to Clear Loss of Signal | Refer to Table 10 |  |  |  |

NOTE: The above values are at $T A=25^{\circ} \mathrm{C}$ and $V_{D D}=3.3 \mathrm{~V} \pm 5 \%$.
Figure 11. Microprocessor Serial Interface Structure


Note: If the R/W bit is set to "1", then this denotes a "READ" operation with the Microprocessor Serial Interface. Conversely, if the R/W bit is set to " 0 ", then this denotes a "WRITE" operation.

Figure 12. Timing Diagram for the Microprocessor Serial Interface


Table 8: Microprocessor Serial Interface Timings ( $\mathrm{T}_{\mathrm{A}}=25^{\circ} \mathrm{C}, \mathrm{V}_{\mathrm{DD}}=3.3 \mathrm{~V} \pm 5 \%$ and load $=10 \mathrm{PF}$ )

| SYMBOL | Parameter | Min. | TYP. | Max | UnITS |
| :---: | :---: | :---: | :---: | :---: | :---: |
| $\mathrm{t}_{21}$ | $\overline{\mathrm{CS}}$ Low to Rising Edge of SClk | 5 |  |  | ns |
| $\mathrm{t}_{22}$ | SDI to Rising Edge of SClk | 5 |  |  | ns |
| $\mathrm{t}_{23}$ | SDI to Rising Edge of SClk Hold Time | 5 |  |  | ns |
| $\mathrm{t}_{24}$ | SCIk "Low" Time | 50 |  |  | ns |
| $\mathrm{t}_{25}$ | SCIk "High" Time | 50 |  |  | ns |
| $t_{26}$ | SCIk Period | 100 |  |  | ns |
| $\mathrm{t}_{27}$ | Falling Edge of SCIk to rising edge of $\overline{\mathrm{CS}}$ | 0 |  |  | ns |
| $\mathrm{t}_{28}$ | $\overline{\mathrm{CS}}$ Inactive Time | 50 |  |  | ns |
| $\mathrm{t}_{29}$ | Falling Edge of SCIk to SDO Valid Time |  |  | 20 | ns |
| $\mathrm{t}_{30}$ | Falling Edge of SCIk to SDO Invalid Time |  |  | 10 | ns |
| $t_{31}$ | Rising edge of $\overline{\overline{C S}}$ to High Z |  |  | 25 | ns |
| $\mathrm{t}_{32}$ | Rise/Fall time of SDO Output |  |  | 5 | ns |

## FUNCTIONAL DESCRIPTION:

Figure 1 shows the functional block diagram of the device. Each channel can be independently configured either by Hardware Mode or by Host Mode to support E3, DS3 or STS-1 modes. A detailed operation of each section is described below.

Each channel consists of the following functional blocks:

### 5.0 THE TRANSMITTER SECTION:

The Transmitter Section, within each Channel, accepts TTL/CMOS level signals from the Terminal Equipment in selectable data formats.

- Convert the CMOS level B3ZS or HDB3 encoded data into pulses with shapes that are compliant with the various industry standard pulse template requirements. Figures 7,8 and 9 illustrate the pulse template requirements.
- Encode the un-encoded NRZ data into either B3ZS format for (DS3 or STS-1) or HDB3 format (for E3) and convert to pulses with shapes and width that are compliant with industry standard pulse template requirements. Figures 7,8 and 9 illustrate the pulse template requirements.
- In Single-Rail or un-encoded Non-Return-to-Zero (NRZ) mode, data is input via TPData_n pins while TNData_n pins must be grounded. The NRZ or Single-Rail mode is selected when the SR/DR input pin is "High" (in Hardware Mode) or bit 0 of channel control register is " 1 " (in Host Mode). Figure 12 illustrates the Single-Rail or NRZ format.

Figure 13. Single-Rail or NRZ Data Format (Encoder and Decoder are Enabled)


- In Dual-Rail mode, data is input via TPData_n and TNData_n pins. TPData_n contains positive data and TNData_n contains negative data. The SR/DR input pin = "Low" (in Hardware Mode) or bit 0 of channel register $=$ " 0 " (in Host Mode) enables the Dual-Rail mode. Figure 13 illustrates the Dual-Rail data format.

Figure 14. Dual-Rail Data Format (encoder and decoder are disabled)


### 5.1 Transmit Clock:

The Transmit Clock applied via TxCIk_n pins, for the selected data rate (for E3 $=34.368 \mathrm{MHz}$, DS3 $=44.736$ MHz or STS $-1=51.84 \mathrm{MHz}$ ), is duty cycle corrected by the internal PLL circuit to provide a $50 \%$ duty cycle clock to the pulse shaping circuit. This allows a $30 \%$ to $70 \%$ duty cycle Transmit Clock to be supplied.

### 5.2 B3ZS/HDB3 Encoder:

When the Single-Rail (NRZ) data format is selected, the Encoder Block encodes the data into either B3ZS format (for either DS3 or STS-1) or HDB3 format (for E3).

### 5.2.1 B3ZS Encoding:

An example of B3ZS encoding is shown in Figure 14. If the encoder detects an occurrence of three consecutive zeros in the data stream, it is replaced with either BOV or OOV, where 'B' refers to Bipolar pulse that is compliant with the Alternating polarity requirement of the AMI (Alternate Mark Inversion) line code and ' V ' refers to a Bipolar Violation (e.g., a bipolar pulse that violates the AMI line code). The substitution of BOV or 00 V is made so that an odd number of bipolar pulses exist between any two consecutive violation (V) pulses. This avoids the introduction of a DC component into the line signal.

Figure 15. B3ZS Encoding Format


### 5.2.2 HDB3 Encoding:

An example of the HDB3 encoding is shown in Figure 15. If the HDB3 encoder detects an occurrence of four consecutive zeros in the data stream, then the four zeros are substituted with either 000 V or B00V pattern. The substitution code is made in such a way that an odd number of pulses exist between any consecutive $\vee$ pulses. This avoids the introduction of DC component into the analog signal.

Figure 16. HDB3 Encoding Format


## Notes:

1. When Dual-Rail data format is selected, the B3ZS/HDB3 Encoder is automatically disabled.
2. In Single-Rail format, the Bipolar Violations in the incoming data stream is converted to valid data pulses.
3. Encoder and Decoder is enabled only in Single-Rail mode.

### 5.3 Transmit Pulse Shaper:

The Transmit Pulse Shaper converts the B3ZS encoded digital pulses into a single analog Alternate Mark Inversion (AMI) pulse that meet the industry standard mask template requirements for STS-1 and DS3. See Figures 8 and 9.
For E3 mode, the pulse shaper converts the HDB3 encoded pulses into a single full amplitude square shaped pulse with very little slope. This is illustrated in Figure 7.
The Pulse Shaper Block also includes a Transmit Build Out Circuit, which can either be disabled or enabled by setting the TxLEV_n input pin "High" or "Low" (in Hardware Mode) or setting the TxLEV_n bit to " 1 " or " 0 " in the control register (in Host Mode).
For DS3/STS-1 rates, the Transmit Build Out Circuit is used to shape the transmit waveform that ensures that transmit pulse template requirements are met at the Cross-Connect system. The distance between the transmitter output and the Cross-Connect system can be between 0 to 450 feet.
For E3 rate, since the output pulse template is measured at the secondary of the transformer and since there is no Cross-Connect system pulse template requirements, the Transmit Build Out Circuit is always disabled.

### 5.3.1 Guidelines for using Transmit Build Out Circuit:

If the distance between the transmitter and the DSX3 or STSX-1, Cross-Connect system, is less than 225 feet, enable the Transmit Build Out Circuit by setting the TxLEV_n input pin "Low" (in Hardware Mode) or setting the TxLEV_n control bit to "0" (in Host Mode).
If the distance between the transmitter and the DSX3 or STSX-1 is greater than 225 feet, disable the Transmit Build Out Circuit.

### 5.3.2 Interfacing to the line:

The differential line driver increases the transmit waveform to appropriate level and drives into the $75 \Omega$ load as shown in Figure 6.

### 5.4 Transmit Drive Monitor:

This feature is used for monitoring the transmit line for occurrence of fault conditions such as a short circuit on the line or a defective line driver.
To activate this function, connect MTIP_n pins to the TTIP_n lines via a $270 \Omega$ resistor and MRing_n pins to TRing_n lines via $270 \Omega$ resistor as shown in Figure 16.

Figure 17. Transmit Driver Monitor set-up.


When the MTIP_n and MRing_n are connected to the TTIP_n and TRing_n lines, the drive monitor circuit monitors the line for transitions. The DMO_n (Drive Monitor Output) will be asserted "Low" as long as the transitions on the line are detected via MTIP_n and MRing_n.
If no transitions on the line are detected for $128 \pm 32$ TxClk_n periods, the DMO_n output toggles "High" and when the transitions are detected again, DMO_n toggles "Low".
Note: The Drive Monitor Circuit is only for diagnostic purpose and does not have to be used to operate the transmitter.

### 5.5 Transmitter Section On/Off:

The transmitter section of each channel can either be turned on or off. To turn on the transmitter, set the input pin TxON_n to "High" (in Hardware Mode) or write a " 1 " to the TxON_n control bits (in Host Mode) and TxON_n pins tied "High".
When the transmitter is turned off, TTIP_n and TRing_n are tri-stated.

## Notes:

1. This feature provides support for Redundancy.
2. If the XRT75R03 is configured in Host mode, to permit a system designed for redundancy to quickly shut-off the defective line card and turn on the back-up line card, writing a " 1 " to the TxON_n control bits transfers the control to $T x O N \_n$ pins.

### 6.0 THE RECEIVER SECTION:

This section describes the detailed operation of the various blocks in the receiver. The receiver recovers the TTL/CMOS level data from the incoming bipolar B3ZS or HDB3 encoded input pulses.

### 6.1 AGC/Equalizer:

The Adaptive Gain Control circuit amplifies the incoming analog signal and compensates for the various flat losses and also for the loss at one-half symbol rate. The AGC has a dynamic range of 30 dB .
The Equalizer restores the integrity of the signal and compensates for the frequency dependent attenuation of up to 900 feet of coaxial cable ( 1300 feet for E3). The Equalizer also boosts the high frequency content of the
signal to reduce Inter-Symbol Interference (ISI) so that the slicer slices the signal at $50 \%$ of peak voltage to generate Positive and Negative data.
The Equalizer can either be "IN" or "OUT" by setting the REQEN_n pin "High" or "Low" (in Hardware Mode) or setting the REQEN_n control bit to " 1 " or " 0 " (in Host Mode).

## Recommendations for Equalizer Settings:

The Equalizer has two gain settings to provide optimum equalization. In the case of normally shaped DS3/ STS-1 pulses (pulses that meet the template requirements) that has been driven through 0 to 900 feet of cable, the Equalizer can be left "IN" by setting the REQEN_n pin to "High" (in Hardware Mode) or setting the REQEN_n control bit to " 1 " (in Host Mode).
However, for square-shaped pulses such as E3 or for DS3/STS-1 high pulses (that does not meet the pulse template requirements), it is recommended that the Equalizer be left "OUT" for cable length less than 300 feet by setting the REQEN_n pin "Low" (in Hardware Mode) or by setting the REQEN_n control bit to "0" (in Host Mode).This would help to prevent over-equalization of the signal and thus optimize the performance in terms of better jitter transfer characteristics.
Note: The results of extensive testing indicates that even when the Equalizer was left "IN" (REQEN_n="HIGH"), regardless of the cable length, the integrity of the E3 signal was restored properly over 0 to 12 dB cable loss at Industrial Temperature.
The Equalizer also contain an additional 20 dB gain stage to provide the line monitoring capability of the resistively attenuated signals which may have 20dB flat loss. This capability can be turned on by writing a " 1 " to the RxMON_n bits in the control register or by setting the RxMON pin (pin 69) "High". However, asserting or enabling RxMON suppresses the internal LOS circuitry and LOS will never assert nor LOS be declared when operating with RxMON enabled.

### 6.1.1 Interference Tolerance:

For E3 mode, ITU-T G. 703 Recommendation specifies that the receiver be able to recover error-free clock and data in the presence of a sinusoidal interfering tone signal. For DS3 and STS-1 modes, the same recommendation is being used. Figure 17 shows the configuration to test the interference margin for DS3/ STS1. Figure 18 shows the set up for E3.

Figure 18. Interference Margin Test Set up for DS3/STS-1


Figure 19. Interference Margin Test Set up for E3.


Table 9: Interference Margin Test Results

| Mode | Cable Length (Attenuation) | Interference Tolerance |
| :---: | :---: | :---: |
| E3 | 0 dB | Equalizer "IN" |
|  |  | -14 dB |
|  | 12 dB | -19 gB |
| DS3 | 0 feet | $-18.5 \mathrm{~dB}$ |
|  | 225 feet | -17.5 dB |
|  | 450 feet | -17 dB |
| STS-1 | 0 feet | -15 dB |
|  | 225 feet | -14 dB |
|  | 450 feet | -14 dB |

### 6.2 Clock and Data Recovery:

The Clock and Data Recovery Circuit extracts the embedded clock, RxClk_n from the sliced digital data stream and provides the retimed data to the B3ZS (HDB3) decoder.
The Clock Recovery PLL can be in one of the following two modes:
Training Mode:
In the absence of input signals at RTIP_n and RRing_n pins, or when the frequency difference between the recovered line clock signal and the reference clock applied on the ExClk_n input pins exceed $0.5 \%$, a Loss of Lock condition is declared by toggling RLOL_n output pin "High" (in Hardware Mode) or setting the RLOL_n bit to " 1 " in the control registers (in Host Mode). Also, the clock output on the RxClk_n pins are the same as the reference clock channel.

## Data/Clock Recovery Mode:

In the presence of input line signals on the RTIP_n and RRing_n input pins and when the frequency difference between the recovered clock signal and the reference clock signal is less than $0.5 \%$, the clock that is output on the RxClk_n out pins is the Recovered Clock signal.

### 6.3 B3ZS/HDB3 Decoder:

The decoder block takes the output from clock and data recovery block and decodes the B3ZS (for DS3 or STS-1) or HDB3 (for E3) encoded line signal and detects any coding errors or excessive zeros in the data stream.
Whenever the input signal violates the B3ZS or HDB3 coding sequence for bipolar violation or contains three (for B3ZS) or four (for HDB3) or more consecutive zeros, an active "High" pulse is generated on the RLCV_n output pins to indicate line code violation.
Note: In Dual- Rail mode, the decoder is bypassed.

### 6.4 LOS (Loss of Signal) Detector:

### 6.4.1 DS3/STS-1 LOS Condition:

A Digital Loss of Slgnal (DLOS) condition occurs when a string of $175 \pm 75$ consecutive zeros occur on the line. When the DLOS condition occurs, the DLOS_n bit is set to " 1 " in the status control register. DLOS condition is cleared when the detected average pulse density is greater than $33 \%$ for $175 \pm 75$ pulses.
Analog Loss of Signal (ALOS) condition occurs when the amplitude of the incoming line signal is below the threshold as shown in the Table 10.The status of the ALOS condition is reflected in the ALOS_n status control register.

RLOS is the logical OR of the DLOS and ALOS states. When the RLOS condition occurs the RLOS_n output pin is toggled "High" and the RLOS_n bit is set to " 1 " in the status control register.

Table 10: The Alos (Analog LOS) Declaration and Clearance Thresholds for a given setting of LOSTHR AND REQEN (DS3 AND STS-1 Applications)

| APPLICATION | REQEN SEtting | LOSTHR Setting | Signal Level to Declare alos Defect | Signal Level to Clear ALOS Defect |
| :---: | :---: | :---: | :---: | :---: |
| DS3 | 0 | 0 | < 61mVpk | > 144mVpk |
|  | 1 | 0 | < 97mVpk | > 192mVpk |
|  | 0 | 1 | < 35mVpk | > 67mVpk |
|  | 1 | 1 | < 43mVpk | > 82mVpk |
| STS-1 | 0 | 0 | < 91mVpk | > 185 mVpk |
|  | 1 | 0 | < 95mVpk | $>215 \mathrm{mVpk}$ |
|  | 0 | 1 | < 44mVpk | > 78 mVpk |
|  | 1 | 1 | < 44mVpk | > 91mVpk |

## DISABLING ALOS/DLOS DETECTION:

For debugging purposes it is useful to disable the ALOS and/or DLOS detection. Writing a "1" to both ALOSDIS_n and DLOSDIS_n bits disables the LOS detection on a per channel basis.

### 6.4.2 E3 LOS Condition:

If the level of incoming line signal drops below the threshold as described in the ITU-T G. 775 standard, the LOS condition is detected. Loss of signal level is defined to be between 15 and 35 dB below the normal level. If the signal drops below 35 dB for 10 to 225 consecutive pulse periods, LOS condition is declared. This is illustrated in Figure 19.

Figure 20. Loss Of Signal Definition for E3 as per itu-t g. 775


As defined in ITU-T G.775, an LOS condition is also declared between 10 and 255 UI (or E3 bit periods) after the actual time the LOS condition has occurred. The LOS condition is cleared within 10 to 255 UI after restoration of the incoming line signal. Figure 20 shows the LOS declaration and clearance conditions.

Figure 21. Loss of Signal Definition for E3 as per itu-t G.775.


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### 6.4.3 Muting the Recovered Data with LOS condition:

When the LOS condition is declared, the clock recovery circuit locks into the reference clock applied to the ExClk_n pin and output this clock on the RxClk_n output.In Single Frequency Mode (SFM), the clock recovery locks into the rate clock generated and output this clock on the RxClk_n pins. The data on the RPOS_n and RNEG_n pins can be forced to zero by pulling the LOSMUT pin "High" (in Hardware Mode) or by setting the LOSMUT_n bits in the individual channel control register to "1" (in Host Mode).

## NOTE: When the LOS condition is cleared, the recovered data is output on RPOS_n and RNEG_n pins.

### 7.0 JITTER:

There are three fundamental parameters that describe circuit performance relative to jitter:

- Jitter Tolerance (Receiver)
- Jitter Transfer (Receiver/Transmitter)


## - Jitter Generation

### 7.1 Jitter Tolerance - Receiver:

Jitter tolerance is a measure of how well a Clock and Data Recovery unit can successfully recover data in the presence of various forms of jitter. It is characterized by the amount of jitter required to produce a specified bit error rate. The tolerance depends on the frequency content of the jitter. Jitter Tolerance is measured as the jitter amplitude over a jitter spectrum for which the clock and data recovery unit achieves a specified bit error rate (BER). To measure the jitter tolerance as shown in Figure 21, jitter is introduced by the sinusoidal modulation of the serial data bit sequence.

Figure 22. Jitter Tolerance Measurements


Input jitter tolerance requirements are specified in terms of compliance with jitter mask which is represented as a combination of points.Each point corresponds to a minimum amplitude of sinusoidal jitter at a given jitter frequency.

### 7.1.1 DS3/STS-1 Jitter Tolerance Requirements:

Bellcore GR-499 CORE, Issue 1, December 1995 specifies the minimum requirement of jitter tolerance for Category I and Category II. The jitter tolerance requirement for Category II is the most stringent. Figure 22 shows the jitter tolerance curve as per GR-499 specification.

Figure 23. Input Jitter Tolerance For DS3/STS-1


### 7.1.2 E3 Jitter Tolerance Requirements:

ITU-T G. 823 standard specifies that the clock and data recovery unit must be able to accommodate and tolerate jitter up to certain specified limits. Figure 23 shows the tolerance curve.

Figure 24. Input Jitter Tolerance for E3


As shown in the Figures 22 and 23 above, in the jitter tolerance measurement, the dark line indicates the minimum level of jitter that the E3/DS3/STS-1 compliant component must tolerate.

The Table 11 below shows the jitter amplitude versus the modulation frequency for various standards.

Table 11: Jitter Amplitude versus Modulation Frequency (Jitter Tolerance)

| Bit Rate <br> (KB/s) | Standard | Input Jitter Amplitude (UI p-p) |  | Modulation Frequency |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | A1 | A2 | A3 | F1(Hz) | F2(Hz) | F3(KHz) | F4(KHz) | F5(KHz) |
| 34368 | ITU-T G.823 | 1.5 | 0.15 | - | 100 | 1000 | 10 | 800 | - |
| 44736 | GR-499 <br> CORE Cat I | 5 | 0.1 | - | 10 | 2.3 k | 60 | 300 | - |
| 44736 | GR-499 <br> CORE Cat II | 10 | 0.3 | - | 10 | 669 | 22.3 | 300 | - |
| 51840 | GR-253 <br> CORE Cat II | 15 | 1.5 | 0.15 | 10 | 30 | 300 | 2 | 20 |

### 7.2 Jitter Transfer - Receiver/Transmitter:

Jitter Transfer function is defined as the ratio of jitter on the output relative to the jitter applied on the input versus frequency.
There are two distinct characteristics in jitter transfer: jitter gain (jitter peaking) defined as the highest ratio above 0dB; and jitter transfer bandwidth. The overall jitter transfer bandwidth is controlled by a low bandwidth loop, typically using a voltage-controller crystal oscillator (VCXO).
The jitter transfer function is a ratio between the jitter output and jitter input for a component, or system often expressed in dB. A negative dB jitter transfer indicates the element removed jitter. A positive dB jitter transfer indicates the element added jitter.A zero dB jitter transfer indicates the element had no effect on jitter.
Table 12 shows the jitter transfer characteristics and/or jitter attenuation specifications for various data rates:
Table 12: Jitter Transfer Specification/References

| E3 | DS3 | STS-1 |
| :---: | :---: | :---: |
| ETSI TBR-24 | GR-499 CORE section 7.3.2 <br> Category I and Category II | GR-253 CORE section 5.6.2.1 |

The above specifications can be met only with a jitter attenuator that supports E3/DS3/STS-1 rates.

### 7.3 Jitter Attenuator:

An advanced crystal-less jitter attenuator per channel is included in the XRT75R03. The jitter attenuator requires no external crystal nor high-frequency reference clock.
In Host mode, by clearing or setting the JATx/Rx_n bits in the channel control registers selects the jitter attenuator either in the Receive or Transmit path on per channel basis. In Hardware mode, JATx/Rx pin selects globally all three channels either in Receive or Transmit path.
The FIFO size can be either 16-bit or 32 -bit. In HOST mode, the bits JAO_n and JA1_n can be set to appropriate combination to select the different FIFO sizes or to disable the Jitter Attenuator on a per channel basis. In Hardware mode, appropriate setting of the pins JA0 and JA1 selects the different FIFO sizes or disables the Jitter Attenuator for all three channels. Data is clocked into the FIFO with the associated clock signal (TxClk or RxClk) and clocked out of the FIFO with the dejittered clock. When the FIFO is within two bits of overflowing or underflowing, the FIFO limit status bit, FL_n is set to "1" in the Alarm status register. Reading this bit clears the FIFO and resets the bit into default state.
Note: It is recommended to select the 16 -bit FIFO for delay-sensitive applications as well as for removing smaller amounts of jitter. Table 13 specifies the jitter transfer mask requirements for various data rates:

Table 13: Jitter Transfer Pass Masks

| Rate (KBITS) | MASK | $\begin{gathered} \hline \text { F1 } \\ (\mathrm{Hz}) \end{gathered}$ | $\begin{gathered} \hline \text { F2 } \\ \text { (Hz) } \end{gathered}$ | $\begin{gathered} \text { F3 } \\ \text { (Hz) } \end{gathered}$ | $\begin{gathered} \text { F4 } \\ (\mathrm{KHz}) \end{gathered}$ | A1(dB) | A2(dB) |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 34368 | $\begin{gathered} \text { G. } 823 \\ \text { ETSI-TBR-24 } \end{gathered}$ | 100 | 300 | 3 K | 800k | 0.5 | -19.5 |
| 44736 | $\begin{aligned} & \text { GR-499, Cat I } \\ & \text { GR-499, Cat II } \\ & \text { GR-253 CORE } \end{aligned}$ | $\begin{aligned} & 10 \\ & 10 \\ & 10 \end{aligned}$ | $\begin{gathered} 10 \mathrm{k} \\ 56.6 \mathrm{k} \\ 40 \end{gathered}$ |  | $\begin{gathered} 15 \mathrm{k} \\ 300 \mathrm{k} \\ 15 \mathrm{k} \end{gathered}$ | $\begin{aligned} & 0.1 \\ & 0.1 \\ & 0.1 \end{aligned}$ |  |
| 51840 | GR-253 CORE | 10 | 40k | - | 400k | 0.1 | - |

The jitter attenuator within the XRT75R03 meets the latest jitter attenuation specifications and/or jitter transfer characteristics as shown in the Figure 24.

Figure 25. Jitter Transfer Requirements and Jitter Attenuator Performance


### 7.3.1 Jitter Generation:

Jitter Generation is defined as the process whereby jitter appears at the output port of the digital equipment in the absence of applied input jitter. Jitter Generation is measured by sending jitter free data to the clock and data recovery circuit and measuring the amount of jitter on the output clock or the re-timed data. Since this is essentially a noise measurement, it requires a definition of bandwidth to be meaningful. The bandwidth is set according to the data rate. In general, the jitter is measured over a band of frequencies.

### 8.0 SERIAL HOST INTERFACE:

A serial microprocessor interface is included in the XRT75R03. The interface is generic and is designed to support the common microprocessors/microcontrollers. The XRT75R03 operates in Host mode when the HOST/HW pin is tied "High". The serial interface includes a serial clock (SCIk), serial data input (SDI), serial data output (SDO), chip select (CS) and interrupt output (INT). The serial interface timing is shown in Figure 11.

The active low interrupt output signal ( $\overline{\text { INT }}$ pin) indicates alarm conditions like LOS, DMO and FL to the processor.

When the XRT75R03 is configured in Host mode, the following input pins,TxLEV_n, TAOS_n, RLB_n, LLB_n, E3_n, STS-1/DS3_n, REQEN_n, JATx/Rx, JA0 and JA1 are disabled and must be connected to ground.
The Table 14 below illustrates the functions of the shared pins in either Host mode or in Hardware mode.
Table 14: Functions of shared pins

| Pin Number | In Host Mode | In Hardware Mode |
| :---: | :---: | :--- |
| 66 | CS | RxCIkINV |
| 67 | SCIk | TxCIkINV |
| 68 | SDI | RxON |
| 69 | SDO | RxMON |
| 71 | INT | LOSMUT |

Note: While configured in Host mode, the TxON_n input pins will be active if the TxON_n bits in the control register are set to "1", and can be used to turn on and off the transmit output drivers. This permits a system designed for redundancy to quickly switch out a defective line card and switch-in the backup line card.

Table 15: XRT75R03 Register Map - Quick Look

| Addres <br> S <br> Locatio <br> N | Register Name | Bıt 7 | Віт 6 | BIT 5 | Bit 4 | Bıt 3 | BIt 2 | BIt 1 | Віт 0 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 0x00 | APS/Redundancy Control Register | Reserved | RxON Ch 2 | $\mathrm{RxON} \mathrm{Ch}$ $1$ | RxON Ch 0 | $\begin{gathered} \text { Reserve } \\ \mathrm{d} \end{gathered}$ | TxON Ch 2 | $\begin{array}{\|c} \hline \text { TxON Ch } \\ 1 \end{array}$ | TxON Ch 0 |
| Channel 0 Registers |  |  |  |  |  |  |  |  |  |
| $0 \times 01$ | Source Level Interrupt Enable Register - Ch 0 | Reserved |  |  |  | Change of <br> FL Alarm <br> Condition Interrupt Enable | Change of RLOL <br> Condition Interrupt Enable | Change of RLOS <br> Defect Condition Interrupt Enable | Change of DMO <br> Condition Interrupt Enable |
| 0x02 | Source Level Interrupt Status Register - Ch 0 | Reserved |  |  |  | Change of FL Alarm Condition Interrupt Status | Change of RLOL Condition Interrupt Status | Change of RLOS <br> Condition Interrupt Status | Change of DMO Condition Interrupt Status |
| $0 \times 03$ | Alarm Status <br> Register - Ch 0 | Reserved | Loss of <br> PRBS <br> Pattern Sync | DLOS <br> Defect Declared | ALOS <br> Defect Declared | FL Alarm Declared | RLOL <br> Condition Declared | RLOS <br> Defect Condition | DMO <br> Condition Status |
| 0x04 | Transmit Control <br> Register - Ch 0 | Res | erved | Internal <br> Transmit Drive Monitoring | Insert PRBS Error | Unused | TAOS | TxCLK INV | TxLEV |
| 0x05 | Receive Control <br> Register - Ch 0 | Res | erved | DisableDLOS Detector | DisableALOS <br> Detector | RxCLK INV | LOSMUTE nable | Receive <br> Monitor Mode Enable | Receive Equalizer Enable |
| 0x06 | Channel Control Register - Ch 0 | Res | erved | PRBS <br> Enable | RLB | LLB | E3 Mode | $\begin{aligned} & \text { STS-1/ } \\ & \text { DS3 } \\ & \text { Mode } \end{aligned}$ | SR/DR <br> Mode |
| $0 \times 07$ | Jitter Attenuator Control Register - Ch 0 | Reserved |  |  |  | $\begin{gathered} \text { JA } \\ \text { RESET } \end{gathered}$ | JA1 <br> (JA Mode Select Bit 1) | $J A$ in TxPath | JAO <br> (JA Mode Select 0) |
| Channel 1 Registers |  |  |  |  |  |  |  |  |  |
| $0 \times 08$ | Reserved |  |  | Reserved | Reserved | Reserve d | Reserved | Reserved | Reserved |

Table 15: XRT75R03 Register Map - Quick Look

| Addres S Locatio N | Register Name | BIt 7 | Віт 6 | BIt 5 | Bit 4 | Bıт 3 | Вıт 2 | BIT 1 | Віт 0 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $0 \times 09$ | Source Level Interrupt Enable Register - Ch 0 | Reserved |  |  |  | Change of FL Alarm Condition Interrupt Enable | Change of RLOL <br> Condition Interrupt Enable | Change of RLOS <br> Defect Condition Interrupt Enable | Change of DMO Condition Interrupt Enable |
| 0x0A | Source Level Interrupt Status Register - Ch 0 | Reserved |  |  |  | Change of <br> FL Alarm <br> Condition Interrupt Status | Change of RLOL Condition Interrupt Status | Change of <br> RLOS <br> Condition <br> Interrupt <br> Status | Change of DMO Condition Interrupt Status |
| 0x0B | Alarm Status <br> Register - Ch 0 | Reserved | Loss of <br> PRBS <br> Pattern Sync | DLOS <br> Defect Declared | ALOS <br> Defect Declared | FL Alarm Declared | RLOL <br> Condition <br> Declared | RLOS <br> Defect Condition | DMO <br> Condition Status |
| 0x0C | Transmit Control <br> Register - Ch 0 | Res | rved | Internal <br> Transmit Drive Monitoring | Insert PRBS Error | Unused | TAOS | TxCLK INV | TxLEV |
| 0x0D | Receive Control <br> Register - Ch 0 | Res | rved | $\begin{array}{\|l\|} \hline \text { DisableD- } \\ \text { LOS } \\ \text { Detector } \end{array}$ | $\begin{aligned} & \text { DisableA- } \\ & \text { LOS } \\ & \text { Detector } \end{aligned}$ | RxCLK INV | LOSMUTE nable | Receive Monitor Mode Enable | Receive Equalizer Enable |
| 0x0E | Channel Control <br> Register - Ch 0 | Res | rved | PRBS <br> Enable | RLB | LLB | E3 Mode | $\frac{\mathrm{STS}-1 /}{\mathrm{DS} 3}$ <br> Mode | $\mathrm{SR} / \overline{\mathrm{DR}}$ Mode |
| 0x0F | Jitter Attenuator Control Register Ch 0 | Reserved |  |  |  | $\begin{gathered} \text { JA } \\ \text { RESET } \end{gathered}$ | JA1 <br> (JA Mode Select Bit 1) | JA in TxPath | JAO <br> (JA Mode Select 0) |
| Channel 2 Registers |  |  |  |  |  |  |  |  |  |
| $0 \times 10$ | Reserved |  |  | Reserved | Reserved | Reserve d | Reserved | Reserved | Reserved |

Table 15: XRT75R03 Register Map - Quick Look

| Addres <br> S <br> Locatio <br> N | Register Name | Bıт 7 | Віт 6 | BIT 5 | Bit 4 | BIt 3 | BIT 2 | BIT 1 | Bıt 0 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 0x11 | Source Level Interrupt Enable Register - Ch 0 | Reserved |  |  |  | Change of <br> FL Alarm Condition Interrupt Enable | Change of RLOL <br> Condition Interrupt Enable | Change of RLOS <br> Defect Condition Interrupt Enable | Change of DMO <br> Condition Interrupt Enable |
| $0 \times 12$ | Source Level Interrupt Status Register - Ch 0 | Reserved |  |  |  | Change of <br> FL Alarm Condition Interrupt Status | Change of RLOL Condition Interrupt Status | Change of RLOS <br> Condition Interrupt Status | Change of DMO <br> Condition Interrupt Status |
| $0 \times 13$ | Alarm Status Register - Ch 0 | Reserved | Loss of <br> PRBS <br> Pattern Sync | DLOS <br> Defect <br> Declared | ALOS <br> Defect <br> Declared | FL Alarm Declared | RLOL <br> Condition <br> Declared | RLOS <br> Defect Condition | DMO <br> Condition Status |
| 0x14 | Transmit Control <br> Register - Ch 0 | Res | ved | Internal <br> Transmit Drive Monitoring | Insert PRBS Error | Unused | TAOS | $\begin{aligned} & \text { TxCLK } \\ & \text { INV } \end{aligned}$ | TxLEV |
| 0x15 | Receive Control <br> Register - Ch 0 | Res | ved | $\begin{aligned} & \text { DisableD- } \\ & \text { LOS } \\ & \text { Detector } \end{aligned}$ | $\begin{aligned} & \text { DisableA- } \\ & \text { LOS } \\ & \text { Detector } \end{aligned}$ | $\begin{aligned} & \text { RxCLK } \\ & \text { INV } \end{aligned}$ | LOSMUTE nable | Receive Monitor Mode Enable | Receive Equalizer Enable |
| 0x16 | Channel Control Register - Ch 0 | Re | ved | PRBS <br> Enable | RLB | LLB | E3 Mode | $\begin{aligned} & \frac{\mathrm{STS}-1 /}{\mathrm{DS} 3} \\ & \text { Mode } \end{aligned}$ | SR/DR Mode |
| 0x17 | Jitter Attenuator Control Register Ch 0 | Reserved |  |  |  | $\begin{gathered} \text { JA } \\ \text { RESET } \end{gathered}$ | JA1 <br> (JA Mode Select Bit 1) | JA in TxPath | JAO <br> (JA Mode Select 0) |
| $\begin{gathered} 0 \times 19- \\ 0 \times 1 F \end{gathered}$ | Reserved | Reserved |  |  |  |  |  |  |  |
| 0x20 | Block Level Interrupt Enable Register - Ch 32 |  |  |  |  |  |  |  |  |
| $0 \times 21$ | Block Level Interrupt Status Register - Ch 33 |  |  |  |  |  |  |  |  |

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Table 15: XRT75R03 Register Map - Quick Look

| $\begin{array}{\|c} \hline \text { Addres } \\ \mathrm{S} \\ \text { LOCATIO } \\ \mathrm{N} \end{array}$ | Register Name | BIt 7 | Bit 6 | BIT 5 | Bit 4 | BIt 3 | BIT 2 | BIT 1 | Віт 0 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $\begin{gathered} 0 \times 22 \\ 0 \times 3 D \end{gathered}$ | Reserved | Reserved |  |  |  |  |  |  |  |
| 0x3E | Device Part Number Register | 0 | 1 | 1 | 1 | 0 | 0 | 1 | 1 |
| 0x3F | Chip Revision Number Register | 1 | 0 | 0 | 0 | Revision Number Value |  |  |  |
| $\begin{gathered} 0 \times 40 \\ 0 \times F F \end{gathered}$ | Reserved | Reserved |  |  |  |  |  |  |  |

## Legend:

|  | Denotes Reserved (or Unused) Register Bits |
| :--- | :--- |
|  | Denotes Read/Write Bits |
|  | Denotes Read-Only Bits |
|  | Denotes Reset-Upon-Read Bits |

THE REGISTER MAP AND DESCRIPTION FOR THE XRT75R03 3-CHANNEL DS3/E3/STS-1 LIU IC

Table 16: Command Register Address Map, within the XRT75R03 3-Channel DS3/E3/STS-1 LIU w/ Jitter Attenuator IC

| Address | Command Register | TYPE | Register Name |
| :---: | :---: | :---: | :---: |
| $0 \times 00$ | CR0 | R/W | APS/Redundancy Control Register |
| Channel 0 Control Registers |  |  |  |
| $0 \times 01$ | CR1 | R/O | Source Level Interrupt Enable Register - Channel 0 |
| $0 \times 02$ | CR2 | R/W | Source Level Interrupt Status Register Channel 0 |
| $0 \times 03$ | CR3 | R/O | Alarm Status Register - Channel 0 |
| 0x04 | CR4 | R/W | Transmit Control Register - Channel 0 |
| 0x05 | CR5 | R/W | Receive Control Register - Channel 0 |
| 0x06 | CR6 | R/W | Channel Control Register - Channel 0 |
| $0 \times 07$ | CR7 | R/W | Jitter Attenuator Control Register - Channel 0 |
| Channel 1 Control Registers |  |  |  |
| 0x08 | CR8 | R/O | Reserved |
| 0x09 | CR9 | R/W | Source Level Interrupt Enable Register - Channel 1 |
| 0x0A | CR10 | RUR | Source Level Interrupt Status Register - Channel 1 |

Table 16: Command Register Address Map, within the XRT75R03 3-Channel DS3/E3/STS-1 LIU w/ Jitter Attenuator IC

| Address | Command Register | TYPE | Register Name |
| :---: | :---: | :---: | :---: |
| 0x0B | CR11 | R/O | Alarm Status Register - Channel 1 |
| 0x0C | CR12 | R/W | Transmit Control Register - Channel 1 |
| 0x0D | CR13 | R/W | Receive Control Register - Channel 1 |
| 0x0E | CR14 | R/W | Channel Control Register - Channel 1 |
| 0x0F | CR15 | R/W | Jitter Attenuator Control Register - Channel 1 |
| Channel 2 Control Registers |  |  |  |
| $0 \times 10$ | CR16 | R/W | Reserved |
| $0 \times 11$ | CR17 | R/W | Source Level Interrupt Enable Register - Channel 2 |
| $0 \times 12$ | CR18 | RUR | Source Level Interrupt Status Register - Channel 2 |
| $0 \times 13$ | CR19 | R/O | Alarm Status Register - Channel 2 |
| 0x14 | CR20 | R/W | Transmit Control Register - Channel 2 |
| $0 \times 15$ | CR21 | R/W | Receive Control Register - Channel 2 |
| $0 \times 16$ | CR22 | R/W | Channel Control Register - Channel 2 |
| $0 \times 17$ | CR23 | R/W | Jitter Attenuator Control Register - Channel 2 |
| 0x18-0x1F | Reserved |  |  |
| Block Level Interrupt Enable/Status Registers (Channels 0-2) |  |  |  |
| 0x20 | CR32 | R/W | Block Level Interrupt Enable Register |
| 0x21 | CR33 | R/O | Block Level Interrupt Status Register |
| 0x22-0x3D | Reserved |  | Reserved |
| Device Identification Registers |  |  |  |
| 0x3E | CR62 | R/O | Device Part Number Register |
| 0x3F | CR63 | R/O | Chip Revision Number Register |

## THE GLOBAL/CHIP-LEVEL REGISTERS

The register set, within the XRT75R03 consists of five "Global" or "Chip-Level" Registers and 21 per-Channel Registers. This section will present detailed information on the Global Registers.

Table 17: List and Address Locations of Global Registers

| AdDress | Command Register | TyPE | Register Name |
| :---: | :---: | :---: | :--- |
| $0 \times 00$ | CR0 | R/W | APS/Redundancy Control Register |
| $0 \times 01-0 \times 1 \mathrm{~F}$ | Bank of Per-Channel Registers |  |  |
| $0 \times 20$ | CR32 | R/W | Block Level Interrupt Enable Register |
| $0 \times 21$ | CR33 | R/O | Block Level Interrupt Status Register |
| $0 \times 22-0 \times 3 D$ | Reserved Registers |  |  |
| $0 \times 3 E$ | CR62 | R/O | Device/Part Number Register |
| $0 \times 3 F$ | CR63 | R/O | Chip Revision Number Register |

## REGISTER DESCRIPTION - GLOBAL REGISTERS

Table 18: APS/Redundancy Control Register - CRO (Address Location = 0x00)

| Bit 7 | Bit 6 | Bit 5 | Bit 4 | Bit 3 | Bit 2 | Bit 1 | Bit 0 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Reserved | RxONCh 2 | RxON Ch 1 | RxON Ch 0 | Reserved | TxON Ch 2 | TxON Ch 1 | TxON Ch 0 |
| R/O | R/W | R/W | R/W | R/O | R/W | R/W | R/W |
| 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |


| $\begin{gathered} \text { BIT } \\ \text { NUMBER } \end{gathered}$ | Name | TYPE | Default Value | Description |
| :---: | :---: | :---: | :---: | :---: |
| 7 | Reserved | R/O | 0 |  |
| 6 | RxON Ch 2 | R/W | 0 | Receiver Section ON - Channel 2 <br> This READ/WRITE bit-field is used to either turn on or turn off the Receive Section of Channel 2. If the user turns on the Receive Section, then Channel 2 will begin to receive the incoming DS3, E3 or STS-1 data-stream via the RTIP_2 and RRING_2 input pins. <br> Conversely, if the user turns off the Receive Section, then the entire Receive Section (e.g., AGC and Receive Equalizer Block, Clock Recovery PLL, etc) will be powered down. <br> 0 - Shuts off the Receive Section of Channel 2. <br> 1 - Turns on the Receive Section of Channel 2. |


| BIT <br> Number | Name | TYPE | Default Value | DESCRIPTION |
| :---: | :---: | :---: | :---: | :---: |
| 5 | RxON Ch 1 | R/W | 0 | Receiver Section ON - Channel 1 <br> This READ/WRITE bit-field is used to either turn on or turn off the Receive Section of Channel 1. If the user turns on the Receive Section, then Channel 1 will begin to receive the incoming DS3, E3 or STS-1 data-stream via the RTIP_1 and RRING_1 input pins. Conversely, if the user turns off the Receive Section, then the entire Receive Section (e.g., AGC and Receive Equalizer Block, Clock Recovery PLL, etc) will be powered down. <br> 0 - Shuts off the Receive Section of Channel 1. <br> 1 - Turns on the Receive Section of Channel 1. |
| 4 | RxON Ch 0 | R/W | 0 | Receiver Section ON - Channel 0 <br> This READ/WRITE bit-field is used to either turn on or turn off the Receive Section of Channel 0. If the user turns on the Receive Section, then Channel 0 will begin to receive the incoming DS3, E3 or STS-1 data-stream via the RTIP_0 and RRING_0 input pins. <br> Conversely, if the user turns off the Receive Section, then the entire Receive Section (e.g., AGC and Receive Equalizer Block, Clock Recovery PLL, etc) will be powered down. <br> 0 - Shuts off the Receive Section of Channel 0. <br> 1 - Turns on the Receive Section of Channel 0. |
| 3 | Reserved | R/O | 0 |  |
| 2 | TxON Ch 2 | R/W | 0 | Transmit Driver ON - Channel 2 <br> This READ/WRITE bit-field is used to either turn on or turn off the Transmit Driver associated with Channel 2. If the user turns on the Transmit Driver, then Channel 2 will begin to transmit DS3, E3 or STS-1 pulses on the line via the TTIP_2 and TRING_ 2 output pins. Conversely, if the user turns off the Transmit Driver, then the TTIP_2 and TRING_2 output pins will be tri-stated. <br> 0 - Shuts off the Transmit Driver associated with Channel 2 and tristates the TTIP_2 and TRING_2 output pins. <br> 1 - Turns on or enables the Transmit Driver associated with Channel 2. <br> Note: If the user wishes to exercise software control over the state of the Transmit Driver associated with Channel 2, then it is imperative that the user pull the TxON_2 (pin 125) to a logic "High" level. |


| BIT <br> Number | Name | TYPE | Default Value | Description |
| :---: | :---: | :---: | :---: | :---: |
| 1 | TxON Ch 1 | R/W | 0 | Transmit Section ON - Channel 1 <br> This READ/WRITE bit-field is used to either turn on or turn off the Transmit Driver associated with Channel 1. If the user turns on the Transmit Driver, then Channel 1 will begin to transmit DS3, E3 or STS-1 pulses on the line via the TTIP_1 and TRING_ 1 output pins. Conversely, if the user turns off the Transmit Driver, then the TTIP_1 and TRING_1 output pins will be tri-stated. <br> 0 - Shuts off the Transmit Driver associated with Channel 1 and tristates the TTIP_1 and TRING_1 output pins. <br> 1 - Turns on or enables the Transmit Driver associated with Channel 1. <br> Note: If the user wishes to exercise software control over the state of the Transmit Driver associated with Channel 1, then it is imperative that the user pull the TxON_1 (pin 1) to a logic "High" level. |
| 0 | TxON Ch 0 | R/W | 0 | Transmit Section ON - Channel 0 <br> This READ/WRITE bit-field is used to either turn on or turn off the Transmit Driver associated with Channel 0. If the user turns on the Transmit Driver, then Channel 0 will begin to transmit DS3, E3 or STS-1 pulses on the line via the TTIP_0 and TRING_ 0 output pins. Conversely, if the user turns off the Transmit Driver, then the TTIP_0 and TRING_0 output pins will be tri-stated. <br> 0 - Shuts off the Transmit Driver associated with Channel 0 and tristates the TTIP_0 and TRING_0 output pins. <br> 1 - Turns on or enables the Transmit Driver associated with Channel 0. <br> Note: If the user wishes to exercise software control over the state of the Transmit Driver associated with Channel 0, then it is imperative that the user pull the $T x O N \_0$ (pin 38) to a logic "High" level. |

Table 19: Block Level Interrupt Enable Register - CR32 (Address Location =0x20)

| Bit 7 | Віт 6 | ВIT 5 | BIt 4 | Віт 3 | ВIT 2 | BIT 1 | Віт 0 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Reserved |  |  |  |  | Channel 2 Interrupt Enable | Channel 1 Interrupt Enable | Channel 0 Interrupt Enable |
| R/O | R/O | R/O | R/O | R/O | R/W | R/W | R/W |
| 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |


| Bit Number | NamE | TYPE | Default Value | Description |
| :---: | :---: | :---: | :---: | :---: |
| 7-3 | Unused | R/O | 0 |  |
| 2 | Channel 2 Interrupt Enable | R/W | 0 | Channel 2 Interrupt Enable Bit: <br> This READ/WRITE bit-field is used to do either of the following <br> - To enable Channel 2 for Interrupt Generation at the Block Level <br> - To disable all Interrupts associated with Channel 2 within the XRT75R03 <br> If the user enables Channel 2-related Interrupts at the Block Level, then this means that a given Channel 2-related interrupt (e.g., Change in LOS Defect Condition - Channel 2) will be enabled if the user has also enabled this particular interrupt at the Source Level. <br> If the user disables Channel 2-related Interrupts at the Block Level, then this means that the XRT75R03 will NOT generate any Channel 2-Related Interrupts at all. <br> 0 - Disables all Channel 2-related Interrupt. <br> 1 - Enables Channel 2-related Interrupts at the Block Level. The user must still enable individual Channel 2-related Interrupts at the source level, before they are enabled for interrupt generation. |
| 1 | Channel 1 Interrupt Enable | R/W | 0 | Channel 1 Interrupt Enable Bit: <br> Please see the description for Bit 2 Channel 2 Interrupt Enable. |
| 0 | Channel 0 Interrupt Enable | R/W | 0 | Channel 0 Interrupt Enable Bit: <br> Please see the description for Bit 2 Channel 2 Interrupt Enable. |

Table 20: Block Level Interrupt Status Register - CR33 (Address Location =0x21)

| Bit 7 | BIt 6 | BIT 5 | BIT 4 | Віт 3 | BIt 2 | BIt 1 | Віт 0 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Reserved |  |  |  |  | Channel 2 Interrupt Status | Channel 1 Interrupt Status | Channel 0 Interrupt Status |
| R/O | R/O | R/O | R/O | R/O | R/O | R/O | R/O |
| 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |


| Bit Number | Name | TYPE | Default Value | Description |
| :---: | :---: | :---: | :---: | :---: |
| 7-3 | Unused | R/O | 0 |  |
| 2 | Channel 2 Interrupt Status | R/O | 0 | Channel 2 Interrupt Status Bit: <br> This READ-ONLY bit-field indicates whether or not the XRT75R03 has a pending Channel 2 -related interrupt that is awaiting service. 0 - Indicates that there is NO Channel 2 -related Interrupt awaiting service. <br> 1 - Indicates that there is at least one Channel 2 -related Interrupt awaiting service. In this case, the user's Interrupt Service routine should be written such that the Microprocessor will now proceed to read out the contents of the Source Level Interrupt Status Register - Channel 2 (Address Location $=0 \times 12$ ) in order to determine the exact cause of the interrupt request. <br> Note: Once this bit-field is set to "1", it will not be cleared back to "0" until the user has read out the contents of the SourceLevel Interrupt Status Register bit, that corresponds with the interrupt request. |


| Bit Number | Name | TYPE | Default Value | Description |
| :---: | :---: | :---: | :---: | :---: |
| 1 | Channel 1 Interrupt Status | R/W | 0 | Channel 1 Interrupt Enable Bit: <br> This READ-ONLY bit-field indicates whether or not the XRT75R03 has a pending Channel 1 -related interrupt that is awaiting service. <br> 0 - Indicates that there is NO Channel 1-related Interrupt awaiting service. <br> 1 - Indicates that there is at least one Channel 1-related Interrupt awaiting service. In this case, the user's Interrupt Service routine should be written such that the Microprocessor will now proceed to read out the contents of the Source Level Interrupt Status Register <br> - Channel 1 (Address Location $=0 \times 0 A$ ) in order to determine the exact cause of the interrupt request. <br> Note: Once this bit-field is set to "1", it will not be cleared back to " 0 " until the user has read out the contents of the SourceLevel Interrupt Status Register bit, that corresponds with the interrupt request. |
| 0 | Channel 0 Interrupt Status | R/W | 0 | Channel 0 Interrupt Enable Bit: <br> This READ-ONLY bit-field indicates whether or not the XRT75R03 has a pending Channel 0 -related interrupt that is awaiting service. <br> 0 - Indicates that there is NO Channel 0-related Interrupt awaiting service. <br> 1 - Indicates that there is at least one Channel 0-related Interrupt awaiting service. In this case, the user's Interrupt Service routine should be written such that the Microprocessor will now proceed to read out the contents of the Source Level Interrupt Status Register <br> - Channel 0 (Address Location $=0 \times 02$ ) in order to determine the exact cause of the interrupt request. <br> Note: Once this bit-field is set to "1", it will not be cleared back to " 0 " until the user has read out the contents of the SourceLevel Interrupt Status Register bit, that corresponds with the interrupt request. |

Table 21: Device/Part Number Register - CR62 (Address Location $=0 \times 3 E$ )

| Bit 7 | BIT 6 | Віт 5 | Bit 4 | BIT 3 | Віт 2 | Bit 1 | BIT 0 |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Part Number ID Value |  |  |  |  |  |  |  |  |
| R/O | R/O | R/O | R/O | R/O | R/O | R/O | R/O |  |
| 0 | 1 | 1 | 1 | 0 | 0 | 1 | 1 |  |


| Bit Number | Name | TyPe | Default <br> VaLue | Description |
| :---: | :---: | :---: | :---: | :--- |
| $7-0$ | Part Number ID <br> Value | R/O | $0 \times 73$ | Part Number ID Value: <br> This READ-ONLY register contains a unique value that <br> represents the XRT75R03. In the case of the XRT75R03, <br> this value will always be 0x73. |

Table 22: Chip Revision Number Register - CR63 (Address Location $=0 \times 3 F$ )

| BIt 7 | Bit 6 | BIT 5 | BIT 4 | Віт 3 | BIt 2 | BIT 1 | Віт 0 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Chip Revision Number Value |  |  |  |  |  |  |  |
| R/O | R/O | R/O | R/O | R/O | R/O | R/O | R/O |
| 1 | 0 | 0 | 0 | X | X | X | X |


| Bit Number | Name | Type | Default <br> Value | Description |
| :---: | :---: | :---: | :---: | :--- |
| $7-0$ | Chip Revision <br> Number Value | R/O | 0x8\# | Chip Revision Number Value: <br> This READ-ONLY register contains a value that represents <br> the current revision of this XRT75R03. This revision num- <br> ber will always be in the form of "0x8\#", where "\#" is a <br> hexadecimal value that specifies the current revision of the <br> chip. <br> For example, the very first revision of this chip will contain <br> the value "0x81". |

## THE PER-CHANNEL REGISTERS

The XRT75R03 consists of 21 per-Channel Registers. Table 23 presents the overall Register Map with the Per-Channel Registers shaded.

Table 23: Command Register Address Map, within the XRT75R03 3-Channel DS3/E3/STS-1 LIU w/ Jitter Attenuator IC

| Address | Command Register | TYPE | Register Name |
| :---: | :---: | :---: | :---: |
| 0x00 | CR0 | R/W | APS/Redundancy Control Register |
| Channel 0 Control Registers |  |  |  |
| $0 \times 01$ | CR1 | R/O | Source Level Interrupt Enable Register - Channel 0 |
| $0 \times 02$ | CR2 | R/W | Source Level Interrupt Status Register Channel 0 |
| $0 \times 03$ | CR3 | R/O | Alarm Status Register - Channel 0 |
| 0x04 | CR4 | R/W | Transmit Control Register - Channel 0 |
| 0x05 | CR5 | R/W | Receive Control Register - Channel 0 |
| $0 \times 06$ | CR6 | R/W | Channel Control Register - Channel 0 |
| $0 \times 07$ | CR7 | R/W | Jitter Attenuator Control Register - Channel 0 |
| Channel 1 Control Registers |  |  |  |
| 0x08 | CR8 | R/O | Reserved |
| 0x09 | CR9 | R/W | Source Level Interrupt Enable Register - Channel 1 |
| $0 \times 0 \mathrm{~A}$ | CR10 | RUR | Source Level Interrupt Status Register - Channel 1 |
| 0x0B | CR11 | R/O | Alarm Status Register - Channel 1 |
| 0x0C | CR12 | R/W | Transmit Control Register - Channel 1 |

Table 23: Command Register Address Map, within the XRT75R03 3-Channel DS3/E3/STS-1 LIU w/ Jitter Attenuator IC

| Address | Command Register | TYPE | Register Name |
| :---: | :---: | :---: | :---: |
| 0x0D | CR13 | R/W | Receive Control Register - Channel 1 |
| 0x0E | CR14 | R/W | Channel Control Register - Channel 1 |
| 0x0F | CR15 | R/W | Jitter Attenuator Control Register - Channel 1 |
| Channel 2 Control Registers |  |  |  |
| $0 \times 10$ | CR16 | R/W | Reserved |
| $0 \times 11$ | CR17 | R/W | Source Level Interrupt Enable Register - Channel 2 |
| $0 \times 12$ | CR18 | RUR | Source Level Interrupt Status Register - Channel 2 |
| $0 \times 13$ | CR19 | R/O | Alarm Status Register - Channel 2 |
| $0 \times 14$ | CR20 | R/W | Transmit Control Register - Channel 2 |
| $0 \times 15$ | CR21 | R/W | Receive Control Register - Channel 2 |
| 0x16 | CR22 | R/W | Channel Control Register - Channel 2 |
| $0 \times 17$ | CR23 | R/W | Jitter Attenuator Control Register - Channel 2 |
| 0x18-0x1F | Reserved |  |  |
| Block Level Interrupt Enable/Status Registers (Channels 0-2) |  |  |  |
| 0x20 | CR32 | R/W | Block Level Interrupt Enable Register |
| 0x21 | CR33 | R/O | Block Level Interrupt Status Register |
| 0x22-0x3D | Reserved |  | Reserved |
| Device Identification Registers |  |  |  |
| 0x3E | CR62 | R/O | Device Part Number Register |
| 0x3F | CR63 | R/O | Chip Revision Number Register |

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## REGISTER DESCRIPTION - PER CHANNEL REGISTERS

Table 24: Source Level Interrupt Enable Register - Channel 0 Address Location = 0x01
Channel 1 Address Location $=0 \times 09$
Channel 2 Address Location $=0 \times 11$ )

| Bit 7 | BIt 6 | Віт 5 | BIT 4 | Bit 3 | Bit 2 | Bit 1 | Bit 0 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Unused |  |  |  | Change of FL Condition Interrupt Enable Ch 0 | Change of LOL Condition Interrupt Enable Ch 0 | Change of LOS Condition Interrupt Enable Ch 0 | Change of DMO Condition Interrupt Enable Ch 0 |
| R/O | R/O | R/O | R/O | R/W | R/W | R/W | R/W |
| 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |


| Bit Number | Name | TYPE | Default Value | Description |
| :---: | :---: | :---: | :---: | :---: |
| 7-4 | Reserved | R/O | 0 |  |
| 3 | Change of FL Condition Interrupt Enable - Ch 0 | R/W | 0 | Change of FL (FIFO Limit Alarm) Condition Interrupt Enable - Ch 0: <br> This READ/WRITE bit-field is used to either enable or disable the Change of FL Condition Interrupt. If the user enables this interrupt, then the XRT75R03 will generate an interrupt any time any of the following events occur. <br> - Whenever the Jitter Attenuator (within Channel 0) declares the FL (FIFO Limit Alarm) condition. <br> - Whenever the Jitter Attenuator (within Channel 0) clears the FL (FIFO Limit Alarm) condition. <br> 0 - Disables the Change in FL Condition Interrupt. <br> 1 - Enables the Change in FL Condition Interrupt. |
| 2 | Change of LOL Condition Interrupt Enable | R/W | 0 | Change of Receive LOL (Loss of Lock) Condition Interrupt Enable - Channel 0: <br> This READ/WRITE bit-field is used to either enable or disable the Change of Receive LOL Condition Interrupt. If the user enables this interrupt, then the XRT75R03 will generate an interrupt any time any of the following events occur. <br> - Whenever the Receive Section (within Channel 0) declares the Loss of Lock Condition. <br> - Whenever the Receive Section (within Channel 0) clears the Loss of Lock Condition. <br> 0 - Disables the Change in Receive LOL Condition Interrupt. <br> 1 - Enables the Change in Receive LOL Condition Interrupt. |


| Bit Number | Name | TYPE | Default Value | Description |
| :---: | :---: | :---: | :---: | :---: |
| 1 | Change of LOS Condition Interrupt Enable | R/W | 0 | Change of the Receive LOS (Loss of Signal) Defect Condition Interrupt Enable - Ch 0: <br> This READ/WRITE bit-field is used to either enable or disable the Change of the Receive LOS Defect Condition Interrupt. If the user enables this interrupt, then the XRT75R03 will generate an interrupt any time any of the following events occur. <br> - Whenever the Receive Section (within Channel 0) declares the LOS Defect Condition. <br> - Whenever the Receive Section (within Channel 0) clears the LOS Defect condition. <br> 0 - Disables the Change in the LOS Defect Condition Interrupt. <br> 1 - Enables the Change in the LOS Defect Condition Interrupt. |
| 0 | Change of DMO Condition Interrupt Enable | R/W | 0 | Change of Transmit DMO (Drive Monitor Output) Condition Interrupt Enable - Ch 0: <br> This READ/WRITE bit-field is used to either enable or disable the Change of Transmit DMO Condition Interrupt. If the user enables this interrupt, then the XRT75R03 will generate an interrupt any time any of the following events occur. <br> - Whenever the Transmit Section toggles the DMO output pin (or bit-field) to "1". <br> - Whenever the Transmit Section toggles the DMO output pin (or bit-field) to "0". <br> 0 - Disables the Change in the DMO Condition Interrupt. <br> 1 - Enables the Change in the DMO Condition Interrupt. |

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Table 25: Source Level Interrupt Status Register - Channel 0 Address Location = $0 \times 02$
Channel 1 Address Location $=0 \times 0 \mathrm{~A}$
Channel 2 Address Location $=0 \times 12$

| BIT 7 | BIT 6 | BIT 5 | BIT 4 | BIT 3 | BIT 2 | BIT 1 | BIT 0 |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Unused |  |  |  |  |  |  |  |  |  | Change of FL <br> Condition <br> Interrupt Status <br> Ch_n | Change of LOL <br> Condition <br> Interrupt Status <br> Ch_n | Change of LOS <br> Condition <br> nterrupt Status <br> Ch_n | Change of DMO <br> Condition <br> Interrupt Status <br> Ch_n |
| R/O | R/O | R/O | R/O | RUR | RUR | RUR | RUR |  |  |  |  |  |  |
| 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |  |  |  |  |  |  |


| Bit Number | Name | TYPE | Default Value | Description |
| :---: | :---: | :---: | :---: | :---: |
| 7-4 | Unused | R/O | 0 |  |
| 3 | Change of FL Condition Interrupt Status | RUR | 0 | Change of FL (FIFO Limit Alarm) Condition Interrupt Status - Ch 0: <br> This RESET-upon-READ bit-field indicates whether or not the Change of FL Condition Interrupt (for Channel 0) has occurred since the last read of this register. <br> 0 - Indicates that the Change of FL Condition Interrupt has NOT occurred since the last read of this register. <br> 1 - Indicates that the Change of FL Condition Interrupt has occurred since the last read of this register. <br> Note: The user can determine the current state of the FIFO Alarm condition by reading out the contents of Bit 3 (FL Alarm Declared) within the Alarm Status Register. |
| 2 | Change of LOL Condition Interrupt Status | RUR | 0 | Change of Receive LOL (Loss of Lock) Condition Interrupt Status - Ch 0: <br> This RESET-upon-READ bit-field indicates whether or not the Change of Receive LOL Condition Interrupt (for Channel 0 ) has occurred since the last read of this register. <br> 0 - Indicates that the Change of Receive LOL Condition Interrupt has NOT occurred since the last read of this register. <br> 1 - Indicates that the Change of Receive LOL Condition Interrupt has occurred since the last read of this register. <br> Note: The user can determine the current state of the Receive LOL Defect condition by reading out the contents of Bit 2 (Receive LOL Defect Declared) within the Alarm Status Register. |


| Bit Number | Name | TYPE | Default Value | Description |
| :---: | :---: | :---: | :---: | :---: |
| 1 | Change of LOS Condition Interrupt Status | RUR | 0 | Change of Receive LOS (Loss of Signal) Defect Condition Interrupt Status: <br> This RESET-upon-READ bit-field indicates whether or not the Change of the Receive LOS Defect Condition Interrupt (for Channel 0 ) has occurred since the last read of this register. <br> 0 - Indicates that the Change of the Receive LOS Defect Condition Interrupt has NOT occurred since the last read of this register. <br> 1 - Indicates that the Change of the Receive LOS Defect Condition Interrupt has occurred since the last read of this register. <br> Note: The user can determine the current state of the Receive LOS Defect condition by reading out the contents of Bit 1 (Receive LOS Defect Declared) within the Alarm Status Register. |
| 0 | Change of DMO Condition Interrupt Status | RUR | 0 | Change of Transmit DMO (Drive Monitor Output) Condition Interrupt Status - Ch 0: <br> This RESET-upon-READ bit-field indicates whether or not the Change of the Transmit DMO Condition Interrupt (for Channel 0) has occurred since the last read of this register. 0 - Indicates that the Change of the Transmit DMO Condition Interrupt has NOT occurred since the last read of this register. <br> 1 - Indicates that the Change of the Transmit DMO Condition Interrupt has occurred since the last read of this register. <br> Note: The user can determine the current state of the Transmit DMO Condition by reading out the contents of Bit 0 (Transmit DMO Condition) within the Alarm Status Register. |

Table 26: Alarm Status Register - Channel 0 Address Location $=0 \times 03$
Channel 1 Address Location $=0 \times 0 B$
Channel 2 Address Location $=0 \times 13$

| Bit 7 | BIT 6 | BIT 5 | BIT 4 | BIT 3 | Віт 2 | Bit 1 | BIT 0 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Unused | Loss of PRBS <br> Pattern Sync | Digital LOS <br> Defect <br> Declared | Analog LOS <br> Defect <br> Declared | FL <br> (FIFO Limit) <br> Alarm <br> Declared | Receive LOL <br> Defect <br> Declared | Receive LOS <br> Defect <br> Declared | Transmit <br> DMO <br> Condition |
| R/O | R/O | R/O | R/O | R/O | R/O | R/O | R/O |
| 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |


| Bit Number | Name | TYPE | Default Value | Description |
| :---: | :---: | :---: | :---: | :---: |
| 7 | Unused | R/O | 0 |  |
| 6 | Loss of PRBS Pattern Lock | R/O | 0 | Loss of PRBS Pattern Lock Indicator: <br> This READ-ONLY bit-field indicates whether or not the PRBS Receiver (within the Receive Section of Channel 0) is declaring PRBS Lock within the incoming PRBS pattern. If the PRBS Receiver detects a very large number of biterrors within its incoming data-stream, then it will declare the Loss of PRBS Lock Condition. <br> Conversely, if the PRBS Receiver were to detect its predetermined PRBS pattern with the incoming DS3, E3 or STS-1 data-stream, (with little or no bit errors) then the PRBS Receiver will clear the Loss of PRBS Lock condition. <br> 0 - Indicates that the PRBS Receiver is currently declaring the PRBS Lock condition within the incoming DS3, E3 or STS-1 data-stream. <br> 1 - Indicates that the PRBS Receiver is currently declaring the Loss of PRBS Lock condition within the incoming DS3, E3 or STs-1 data-stream. <br> Nоте: This register bit is only valid if all of the following are true. <br> a. The PRBS Generator block (within the Transmit Section of the Chip is enabled). <br> b. The PRBS Receiver is enabled. <br> c. The PRBS Pattern (that is generated by the PRBS Generator) is somehow looped back into the Receive Path (via the Line-Side) and in-turn routed to the receive input of the PRBS Receiver. |


| Bit Number | Name | TYPE | Default Value | Description |
| :---: | :---: | :---: | :---: | :---: |
| 5 | Digital LOS Defect Declared | R/O | 0 | Digital LOS Defect Declared: <br> This READ-ONLY bit-field indicates whether or not the Digital LOS (Loss of Signal) detector is declaring the LOS Defect condition. <br> For DS3 and STS-1 applications, the Digital LOS Detector will declare the LOS Defect condition whenever it detects an absence of pulses (within the incoming DS3 or STS-1 data-stream) for 160 consecutive bit-periods. <br> Further, (again for DS3 and STS-1 applications) the Digital LOS Detector will clear the LOS Defect condition whenever it determines that the pulse density (within the incoming DS3 or STS-1 signal) is at least 33\%. <br> 0 - Indicates that the Digital LOS Detector is NOT declaring the LOS Defect Condition. <br> 1 - Indicates that the Digital LOS Detector is currently declaring the LOS Defect condition. <br> Notes: <br> 1. LOS Detection (within each channel of the XRT75R03) is performed by both an Analog LOS Detector and a Digital LOS Detector. The LOS state of a given Channel is simply a WIRED-OR of the LOS Defect Declare states of these two detectors. <br> 2. The current LOS Defect Condition (for the channel) can be determined by reading out the contents of Bit 1 (Receive LOS Defect Declared) within this register. |


| Bit Number | NAME | TYPE | Default Value | Description |
| :---: | :---: | :---: | :---: | :---: |
| 4 | Analog LOS Defect Declared | R/O | 0 | Analog LOS Defect Declared: <br> This READ-ONLY bit-field indicates whether or not the Analog LOS (Loss of Signal) detector is declaring the LOS Defect condition. <br> For DS3 and STS-1 applications, the Analog LOS Detector will declare the LOS Defect condition whenever it determines that the amplitude of the pulses (within the incoming DS3/STS-1 line signal) drops below a certain Analog LOS Defect Declaration threshold level. <br> Conversely, (again for DS3 and STS-1 applications) the Analog LOS Detector will clear the LOS Defect condition whenever it determines that the amplitude of the pulses (within the incoming DS3/STS-1 line signal) has risen above a certain Analog LOS Defect Clearance threshold level. <br> It should be noted that, in order to prevent "chattering" within the Analog LOS Detector output, there is some builtin hysteresis between the Analog LOS Defect Declaration and the Analog LOS Defect Clearance threshold levels. <br> 0 - Indicates that the Analog LOS Detector is NOT declaring the LOS Defect Condition. <br> 1 - Indicates that the Analog LOS Detector is currently declaring the LOS Defect condition. <br> Notes: <br> 1. LOS Detection (within each channel of the XRT75R03) is performed by both an Analog LOS Detector and a Digital LOS Detector. The LOS state of a given Channel is simply a WIRED-OR of the LOS Defect Declare states of these two detectors. <br> 2. The current LOS Defect Condition (for the channel) can be determined by reading out the contents of Bit 1 (Receive LOS Defect Declared) within this register. |


| Bit Number | Name | TYPE | Default Value | Description |
| :---: | :---: | :---: | :---: | :---: |
| 3 | FL Alarm Declared | R/O | 0 | FL (FIFO Limit) Alarm Declared: <br> This READ-ONLY bit-field indicates whether or not the Jitter Attenuator block (within Channel_n) is currently declaring the FIFO Limit Alarm. <br> The Jitter Attenuator block will declare the FIFO Limit Alarm anytime the Jitter Attenuator FIFO comes within two bit-periods of either overflowing or under-running. <br> Conversely, the Jitter Attenuator block will clear the FIFO Limit Alarm anytime the Jitter Attenuator FIFO is NO longer within two bit-periods of either overflowing or underrunning. <br> Typically, this Alarm will only be declared whenever there is a very serious problem with timing or jitter in the system. <br> 0 - Indicates that the Jitter Attenuator block (within Channel_n) is NOT currently declaring the FIFO Limit Alarm condition. <br> 1 - Indicates that the Jitter Attenuator block (within Channel_n) is currently declaring the FIFO Limit Alarm condition. <br> Note: This bit-field is only active if the Jitter Attenuator (within Channel_n) has been enabled. |
| 2 | Receive LOL Condition Declared | R/O | 0 | Receive LOL (Loss of Lock) Condition Declared: <br> This READ-ONLY bit-field indicates whether or not the Receive Section (within Channel_n) is currently declaring the LOL (Loss of Lock) condition. <br> The Receive Section (of Channel_n) will declare the LOL Condition, if any one of the following conditions are met. <br> - If the frequency of the Recovered Clock signal differs from that of the signal provided to the E3CLK input (for E3 applications), the DS3CLK input (for DS3 applications) or the STS-1CLK input (for STS-1 applications) by $0.5 \%$ (or 5000 ppm ) or more. <br> - If the frequency of the Recovered Clock signal differs from the line-rate clock signal (for Channel_n) that has been generated by the SFM Clock Synthesizer PLL (for SFM Mode Operation) by $0.5 \%$ (or 5000 ppm ) or more. <br> 0 - Indicates that the Receive Section of Channel_n is NOT currently declaring the LOL Condition. <br> 1 - Indicates that the Receive Section of Channel_n is currently declaring the LOL Condition. |


| Bit Number | Name | TYpe | Default Value | Description |
| :---: | :---: | :---: | :---: | :---: |
| 1 | Receive LOS Defect Condition Declared | R/O | 0 | Receive LOS (Loss of Signal) Defect Condition Declared: <br> This READ-ONLY bit-field indicates whether or not the Receive Section (within Channel_n) is currently declaring the LOS defect condition. <br> The Receive Section (of Channel_n) will declare the LOS defect condition, if any one of the following conditions is met. <br> - If the Digital LOS Detector declares the LOS defect condition (for DS3 or STS-1 applications) <br> - If the Analog LOS Detector declares the LOS defect condition (for DS3 or STS-1 applications) <br> - If the ITU-T G. 775 LOS Detector declares the LOS defect condition (for E3 applications). <br> 0 - Indicates that the Receive Section of Channel_n is NOT currently declaring the LOS Defect Condition. <br> 1 - Indicates that the Receive Section of Channel_n is currently declaring the LOS Defect condition. |
| 0 | Transmit DMO Condition Declared | R/O | 0 | Transmit DMO (Drive Monitor Output) Condition Declared: <br> This READ-ONLY bit-field indicates whether or not the Transmit Section of Channel_n is currently declaring the DMO Alarm condition. <br> If configured accordingly, the Transmit Section will either internally or externally check the Transmit Output DS3/E3/ <br> STS-1 Line signal for bipolar pulses via the TTIP_n and TRING_n output signals. If the Transmit Section were to detect no bipolar for 128 consecutive bit-periods, then it will declare the Transmit DMO Alarm condition. This particular alarm can be used to check for fault conditions on the Transmit Output Line Signal path. <br> The Transmit Section will clear the Transmit DMO Alarm condition the instant that it detects some bipolar activity on the Transmit Output Line signal. <br> 0 - Indicates that the Transmit Section of Channel_n is NOT currently declaring the Transmit DMO Alarm condition. <br> 1 - Indicates that the Transmit Section of Channel_n is currently declaring the Transmit DMO Alarm condition. |

Table 27: Transmit Control Register - Channel 0 Address Location $=0 \times 04$
Channel 1 Address Location $=0 \times 0 \mathrm{C}$
Channel 2 Address Location $=0 \times 14$

| Bit 7 | Bit 6 | Bit 5 | Bit 4 | Bit 3 | BIT 2 | BIT 1 | BIT 0 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Unused |  | Internal <br> Transmit <br> Drive Monitor | Insert PRBS <br> Error | Unused | TAOS | TxCLKINV | TxLEV |
| R/O | R/O | R/W | R/W | R/O | R/W | R/W | R/W |
| 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |


| Bit Number | Name | TYPE | Default Value | Description |
| :---: | :---: | :---: | :---: | :---: |
| 7-6 | Unused | R/O | 0 |  |
| 5 | Internal Transmit Drive Monitor | R/W | 0 | Internal Transmit Drive Monitor Enable - Channel_n: <br> This READ/WRITE bit-field is used to configure the Transmit Section of Channel_n to either internally or externally monitor the TTIP_n and TRING_n output pins for bipolar pulses, in order to determine whether to declare the Transmit DMO Alarm condition. <br> If the user configures the Transmit Section to externally monitor the TTIP_n and TRING_n output pins (for bipolar pulses) then the user must make sure that he/she has connected the MTIP_n and MRING_n input pins to their corresponding TTIP_n and TRING_n output pins (via a 274 ohm series resistor). <br> If the user configures the Transmit Section to internally monitor the TTIP_n and TRING_n output pins (for bipolar pulses) then the user does NOT need to make sure that the MTIP_n and MRING_n input pins are connected to the TTIP_n and TRING_n output pins (via series resistors). This monitoring will be performed right at the TTIP_n and TRING_n output pads. <br> 0 - Configures the Transmit Drive Monitor to externally monitor the TTIP_n and TRING_n output pins for bipolar pulses. <br> 1 - Configures the Transmit Drive Monitor to internally monitor the TTIP_n and TRING_n output pins for bipolar pulses. |


| Bit Number | Name | TYPE | Default Value | Description |
| :---: | :---: | :---: | :---: | :---: |
| 4 | Insert PRBS Error | R/W | 0 | Insert PRBS Error - Channel_n: <br> A "0 to 1" transition within this bit-field configures the PRBS Generator (within the Transmit Section of Channel_n) to generate a single bit error within the outbound PRBS pattern-stream. <br> Notes: <br> 1. This bit-field is only active if the PRBS Generator and Receiver have been enabled within the corresponding Channel. <br> 2. After writing the "1" into this register, the user must execute a write operation to clear this particular register bit to " 0 " in order to facilitate the next "0 to 1" transition in this bit-field. |
| 3 | Unused | R/O | 0 |  |
| 2 | TAOS | R/W | 0 | Transmit All OneS Pattern - Channel_n: <br> This READ/WRITE bit-field is used to command the Transmit Section of Channel_n to generate and transmit an unframed, All Ones pattern via the DS3, E3 or STS-1 line signal (to the remote terminal equipment). <br> Whenever the user implements this configuration setting then the Transmit Section will ignore the data that it is accepting from the System-side equipment and overwrite this data with the "All Ones" Pattern. <br> 0 - Configures the Transmit Section to transmit the data that it accepts from the System-side Interface. <br> 1 - Configures the Transmit Section to generate and transmit the Unframed, All Ones pattern. |


| Bit Number | Name | TYpe | Default Value | Description |
| :---: | :---: | :---: | :---: | :---: |
| 1 | TxCLKINV | R/W | 0 | Transmit Clock Invert Select - Channel_n: <br> This READ/WRITE bit-field is used to select the edge of the TxCLK_n input that the Transmit Section of Channel_n will use to sample the TPDATA_n and TNDATA_n input pins, as described below. <br> 0 - Configures the Transmit Section (within the corresponding channel) to sample the TPDATA_n and TNDATA_n input pins upon the falling edge of TxCLK_n. <br> 1 - Configures the Transmit Section (within the corresponding channel) to sample the TPDATA_n and TNDATA_n input pins upon the rising edge of TxCLK_n. <br> Note: Whenever this configuration setting is accomplished via the Host Mode, it is done on a per-channel basis. |
| 0 | TxLEV | R/W | 0 | Transmit Line Build-Out Select - Channel_n: <br> This READ/WRITE bit-field is used to either enable or disable the Transmit Line Build-Out (e.g., pulse-shaping) circuit within the corresponding channel. The user should set this bit-field to either "0" or to "1" based upon the following guidelines. <br> 0 - If the cable length between the Transmit Output (of the corresponding Channel) and the DSX-3/STSX-1 location is 225 feet or less. <br> 1 - If the cable length between the Transmit Output (of the corresponding Channel) and the DSX-3/STSX-1 location is 225 feet or more. <br> The user must follow these guidelines in order to insure that the Transmit Section (of Channel_n) will always generate a DS3 pulse that complies with the Isolated Pulse Template requirements per Bellcore GR-499-CORE, or an STS-1 pulse that complies with the Pulse Template requirements per Telcordia GR-253-CORE. <br> Note: This bit-field is ignored if the channel has been configured to operate in the E3 Mode. |

Table 28: Receive Control Register - Channel 0 Address Location $=0 \times 05$
Channel 1 Address Location $=0 \times 0 \mathrm{D}$
Channel 2 Address Location $=0 \times 15$

| BIT 7 | BIT 6 | BIT 5 | BIT 4 | BIT 3 | BIT 2 | BIT 1 | BIT 0 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Unused |  | Disable DLOS <br> Detector | Disable ALOS <br> Detector | RxCLKINV | LOSMUT <br> Enable | Receive <br> Monitor Mode <br> Enable | Receive <br> Equalizer <br> Enable |
| R/O | R/O | R/W | R/W | R/W | R/W | R/W | R/W |
| 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |


| Bit Number | Name | TYPE | Default Value | Description |
| :---: | :---: | :---: | :---: | :---: |
| 7-6 | Unused | R/O | 0 |  |
| 5 | Disable DLOS Detector | R/W | 0 | Disable Digital LOS Detector - Channel_n: <br> This READ/WRITE bit-field is used to either enable or disable the Digital LOS (Loss of Signal) Detector within Channel_n, as described below. <br> 0 - Enables the Digital LOS Detector within Channel_n. <br> Note: This is the default condition. <br> 1 - Disables the Digital LOS Detector within Channel_n. <br> Note: This bit-field is only active if Channel_n has been configured to operate in the DS3 or STS-1 Modes. |
| 4 | Disable ALOS Detector | R/W | 0 | Disable Analog LOS Detector - Channel_n: <br> This READ/WRITE bit-field is used to either enable or disable the Analog LOS (Loss of Signal) Detector within Channel_n, as described below. <br> 0 - Enables the Analog LOS Detector within Channel_n. <br> Note: This is the default condition. <br> 1 - Disables the Analog LOS Detector within Channel_n. <br> Note: This bit-field is only active if Channel_n has been configured to operate in the DS3 or STS-1 Modes. |
| 3 | RxCLKINV | R/W | 0 | Receive Clock Invert Select - Channel_n: <br> This READ/WRITE bit-field is used to select the edge of the RCLK_n output that the Receive Section of Channel_n will use to output the recovered data via the RPOS_n and RNEG_n output pins, as described below. <br> 0 - Configures the Receive Section (within the corresponding channel) to output the recovered data via the RPOS_n and RNEG_n output pins upon the rising edge of RCLK_n. 1 - Configures the Receive Section (within the corresponding channel) to output the recovered data via the RPOS_n and RNEG_n output pins upon the falling edge of RCLK_n. |


| Bit Number | NAME | TYPE | Default Value | Description |
| :---: | :---: | :---: | :---: | :---: |
| 2 | LOSMUT Enable | R/W | 0 | Muting upon LOS Enable - Channel_n: <br> This READ/WRITE bit-field is used to configure the Receive Section (within Channel_n) to automatically pull their corresponding Recovered Data Output pins (e.g., RPOS_n and RNEG_n) to GND anytime (and for the duration that) the Receive Section declares the LOS defect condition. In other words, this feature (if enabled) will cause the Receive Channel to automatically mute the Recovered data anytime (and for the duration that) the Receive Section declares the LOS defect condition. <br> 0 - Disables the Muting upon LOS feature. In this setting the Receive Section will NOT automatically mute the Recovered Data whenever it is declaring the LOS defect condition. <br> 1 - Enables the Muting upon LOS feature. In this setting the Receive Section will automatically mute the Recovered Data whenever it is declaring the LOS defect condition. |
| 1 | Receive Monitor Mode Enable | R/W | 0 | Receive Monitor Mode Enable - Channel_n: <br> This READ/WRITE bit-field is used to configure the Receive Section of Channel_n to operate in the Receive Monitor Mode. <br> If the user configures the Receive Section to operate in the Receive Monitor Mode, then it will be able to receive a nominal DSX-3/STSX-1 signal that has been attenuated by 20 dB of flat loss along with 6 dB of cable loss, in an errorfree manner. However, internal LOS circuitry is suppressed and LOS will never assert nor LOS be declared when operating under this mode. <br> 0 - Configures the corresponding channel to operate in the Normal Mode. <br> 1-Configure the corresponding channel to operate in the Receive Monitor Mode. |
| 0 | Receive Equalizer Enable | R/W | 0 | Receive Equalizer Enable - Channel_n: <br> This READ/WRITE register bit is used to either enable or disable the Receive Equalizer block within the Receive Section of Channel_n, as listed below. <br> 0 - Disables the Receive Equalizer within the corresponding channel. <br> 1 - Enables the Receive Equalizer within the corresponding channel. <br> Note: For virtually all applications, we recommend that the user set this bit-field to "1" (for all three channels) and enable the Receive Equalizer. |

Table 29: Channel Control Register - Channel 0 Address Location $=0 \times 06$
Channel 1 Address Location $=0 \times 0 \mathrm{E}$
Channel 2 Address Location $=0 \times 16$

| BIT 7 | BIT 6 | BIT 5 | BIT 4 | BIT 3 | BIT 2 | BIT 1 | BIT 0 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Unused |  | PRBS Enable <br> Ch_n | RLB_n | LLB_n | E3_n | STS-1/DS3_n | SR/DR_n |
| R/O | R/O | R/W | R/W | R/W | R/W | R/W | R/W |
| 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |


| Bit Number | Name | TYPE | Default Value | Description |
| :---: | :---: | :---: | :---: | :---: |
| 7-6 | Unused | R/O | 0 |  |
| 5 | PRBS Enable | R/W | 0 | PRBS Generator and Receiver Enable - Channel_n: <br> This READ/WRITE bit-field is used to either enable or disable the PRBS Generator and Receiver within a given Channel of the XRT75R03. <br> If the user enables the PRBS Generator and Receiver, then the following will happen. <br> 1. The PRBS Generator (which resides within the Transmit Section of the Channel) will begin to generate an unframed, $2^{\wedge} 15-1$ PRBS Pattern (for DS3 and STS-1 applications) and an unframed, 2^23-1 PRBS Pattern (for E3 applications). <br> 2. The PRBS Receiver (which resides within the Receive Section of the Channel) will now be enabled and will begin to search the incoming data for the above-mentioned PRBS patterns. <br> 0 - Disables both the PRBS Generator and PRBS Receiver within the corresponding channel. <br> 1 - Enables both the PRBS Generator and PRBS Receiver within the corresponding channel. <br> Notes: <br> 1. To check and monitor PRBS Bit Errors, Bit 0 (SR/ $\overline{D R} \_n$ ) within this register Must be set to " 0 ". This step will configure the RNEG_n/LCV_n output pin to function as the PRBS Error Indicator. In this case, external glue logic will be needed to monitor and count the number of PRBS Bit Errors that are detected by the PRBS Receiver. <br> 2. If the user enables the PRBS Generator and PRBS Receiver, then the Channel will ignore the data that is being accepted from the System-side Equipment (via the TPDATA_n and TNDATA_n input pins) and will overwrite this outbound data with the PRBS Pattern. <br> 3. Use of the PRBS Generator and Receiver is only available through the Host Mode. |


| Bit Number | Name | TYPE | Default Value | Description |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 4 | RLB_n | R/W | 0 | Loop-Back Select - RLB Bit - Channel_n: <br> This READ/WRITE bit-field along with the corresponding LLB_n bit-field is used to configure a given channel (within the XRT75R03) into various loop-back modes. <br> The relationship between the settings for this input pin, the corresponding LLB_n bit-field and the resulting Loop-back Mode is presented below. |  |  |
|  |  |  |  | LLB_n | RLB_n | Loop-back Mode |
|  |  |  |  | 0 | 0 | Normal (No Loop-back) Mode |
|  |  |  |  | 0 | 1 | Remote Loop-back Mode |
|  |  |  |  | 1 | 0 | Analog Local Loop-back Mode |
|  |  |  |  | 1 | 1 | Digital Local Loop-back Mode |
| 3 | LLB_n | R/W | 0 | Loop-Back Select - LLB Bit-field - Channel_n: Please see the description (above) for RLB_n. |  |  |
| 2 | E3_n | R/W | 0 | E3 Mode Select - Channel_n: <br> This READ/WRITE bit-field, along with Bit 1 (STS-1/ DS3_n) within this particular register, is used to configure a given channel (of the XRT75R03) into either the DS3, E3 or STS-1 Modes, as depicted below. <br> 0 - Configures Channel_n to operate in either the DS3 or STS-1 Modes, depending upon the state of Bit 1 (STS-1/ DS3_n) within this same register. <br> 1- Configures Channel_n to operate in the E3 Mode. |  |  |


| Bit Number | Name | TYpe | Default Value | DESCRIPTION |
| :---: | :---: | :---: | :---: | :---: |
| 1 | STS-1/\} { } ^ {  DS3  }  _n  | R/W | 0 | STS-1/DS3 Mode Select - Channel_n: <br> This READ/WRITE bit-field, along with Bit 2 (E3_n) is used to configure a given channel (within the XRT75R03) into either the DS3, E3 or STS-1 Modes. <br> 0 - Configures Channel_n to operate in the DS3 Mode (provided by Bit 2 [E3_n], within this same register) has been set to "0"). <br> 1 - Configures Channel_n to operate in the STS-1 Mode (provided that Bit 2 [E3_n], within the same register) has been set to "0". <br> Note: This bit-field is ignored if Bit 2 (E3_n) has been set to "1". In this case, Channel_n will be configured to operate in the E3 Mode. |
| 0 | SR/DR_n | R/W | 0 | Single-Rail/Dual-Rail Select - Channel_n: <br> This READ/WRITE bit-field is used to configure Channel_n to operate in either the Single-Rail or Dual-Rail Mode. <br> If the user configures the Channel to operate in the SingleRail Mode, then all of the following will happen. <br> - The B3ZS/HDB3 Encoder and Decoder blocks (within Channel_n) will be enabled. <br> - The Transmit Section of Channel_n will accept all of the outbound data (from the System-side Equipment) via the TPDATA_n (or TxDATA_n) input pin. <br> - The Receive Section of each channel will output all of the recovered data (to the System-side Equipment) via the RPOS_n output pin. <br> - The corresponding RNEG_n/LCV_n output pin will now function as the LCV (Line Code Violation or Excessive Zero Event) indicator output pin for Channel_n. <br> If the user configures Channel_n to operate in the DualRail Mode, then all of the following will happen. <br> - The B3ZS/HDB3 Encoder and Decoder blocks of Channel_n will be disabled. <br> - The Transmit Section of Channel_n will be configured to accept positive-polarity data via the TPDATA_n input pin and negative-polarity data via the TNDATA_n input pin. <br> - The Receive Section of Channel_n will pulse the RPOS_n output pin "High" (for one period of RCLK_n) for each time a positive-polarity pulse is received via the RTIP_n/RRING_n input pins. Likewise, the Receive Section of each channel will also pulse the RNEG_n output pin "High" (for one period of RCLK_n) for each time a negative-polarity pulse is received via the RTIP_n/RRING_n input pins. <br> 0 - Configures Channel_n to operate in the Dual-Rail Mode. <br> 1-Configures Channel_n to operate in the Single-Rail Mode. |

Table 30: Jitter Attenuator Control Register - Channel 0 Address Location $=\mathbf{0 x 0 7}$
Channel 1 Address Location $=0 \times 0 F$
Channel 2 Address Location $=0 \times 17$

| BIT 7 | BIT 6 | BIT 5 | BIT 4 | BIT 3 | BIT 2 | BIT 1 | BIT 0 |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Unused |  |  |  |  |  |  |  |  | JA RESET <br> Ch_n | JA1 Ch_n | JA in Tx Path <br> Ch_n | JA0 Ch_n |
| R/O | R/O | R/O | R/W | R/W | R/W | R/W | R/W |  |  |  |  |  |
| 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |  |  |  |  |  |


| Bit Number | Name | TYPE | Default Value | Description |
| :---: | :---: | :---: | :---: | :---: |
| 7-4 | Unused | R/O | 0 |  |
| 3 | JA RESET Ch_n | R/W | 0 | Jitter Attenuator RESET - Channel_n: <br> Writing a "0 to 1 " transition within this bit-field will configure the Jitter Attenuator (within Channel_n) to execute a RESET operation. <br> Whenever the user executes a RESET operation, then all of the following will occur. <br> - The READ and WRITE pointers (within the Jitter Attenuator FIFO) will be reset to their default values. <br> - The contents of the Jitter Attenuator FIFO will be flushed. <br> Note: The user must follow up any "0 to 1 " transition with the appropriate write operate to set this bit-field back to " 0 ", in order to resume normal operation with the Jitter Attenuator. |
| 2 | JA1 Ch_n | R/W | 0 | Jitter Attenuator Configuration Select Input - Bit 1: <br> This READ/WRITE bit-field, along with Bit 0 (JAO Ch_n) is used to do any of the following. <br> - To enable or disable the Jitter Attenuator corresponding to Channel_n. <br> - To select the FIFO Depth for the Jitter Attenuator within Channel_n. <br> The relationship between the settings of these two bitfields and the Enable/Disable States, and FIFO Depths is presented below. |
|  |  |  |  | JAO JA1 $\quad$ Jitter Attenuator Mode |
|  |  |  |  | 0 0 FIFO Depth $=16$ bits |
|  |  |  |  | 0 1 FIFO Depth $=32$ bits |
|  |  |  |  | 1 0 Disabled |
|  |  |  |  | 1 1 Disabled |


| Bit Number | Name | Type | Default <br> VaLUE | Description |
| :---: | :---: | :---: | :---: | :--- |
| 1 | JA in Tx Path Ch_n | R/W | 0 | Jitter Attenuator in Transmit/Receive Path Select Bit: <br> This input pin is used to configure the Jitter Attenuator <br> (within Channel_n) to operate in either the Transmit or <br> Receive path, as described below. <br> $0-$ - Configures the Jitter Attenuator (within Channel_n) to <br> operate in the Receive Path. <br> 1 - Configures the Jitter Attenuator (within Channel_n) to <br> operate in the Transmit Path. |
| 0 | JA0 Ch_n | R/W | 0 | Jitter Attenuator Configuration Select Input - Bit 0: <br> Please see the description for Bit 2 (JA1 Ch_n). |

### 9.0 DIAGNOSTIC FEATURES:

### 9.1 PRBS Generator and Detector:

The XRT75R03 contains an on-chip Pseudo Random Binary Sequence (PRBS) generator and detector for diagnostic purpose. This feature is only available in Host mode. With the PRBSEN_n bit = " 1 ", the transmitter will send out PRBS of $2^{23}-1$ in E3 rate or $2^{15}-1$ in STS-1/DS3 rate. At the same time, the receiver PRBS detector is also enabled. When the correct PRBS pattern is detected by the receiver, the RNEG/LCV pin will go "Low" to indicate PRBS synchronization has been achieved. When the PRBS detector is not in sync the PRBSLS bit will be set to " 1 " and RNEG/LCV pin will go "High".
With the PRBS mode enabled, the user can also insert a single bit error by toggling "INSPRBS" bit. This is done by writing a " 1 " to INSPRBS bit. The receiver at RNEG/LCV pin will pulse "High" for one RxClk cycle for every bit error detected. Any subsequent single bit error insertion must be done by first writing a " 0 " to INSPRBS bit and followed by a " 1 ".
Figure 25 shows the status of RNEG/LCV pin when the XRT75R03 is configured in PRBS mode.
Note: In PRBS mode, the device is forced to operate in Single-Rail Mode.
Figure 26. PRBS MODE


### 9.2 LOOPBACKS:

The XRT75R03 offers three loopback modes for diagnostic purposes. In Hardware mode, the loopback modes are selected via the RLB_n and LLB_n pins. In Host mode, the RLB_n and LLB_n bits $n$ the Channel control registers select the loopback modes.

### 9.2.1 ANALOG LOOPBACK:

In this mode, the transmitter outputs (TTIP_n and TRING_n) are connected internally to the receiver inputs (RTIP_n and RRING_n) as shown in Figure 26. Data and clock are output at RCLK_n, RPOS_n and RNEG_n pins for the corresponding transceiver. Analog loopback exercises most of the functional blocks of the device including the jitter attenuator which can be selected in either the transmit or receive path.
XRT75R03 can be configured in Analog Loopback either in Hardware mode via the LLB_n and RLB_n pins or in Host mode via LLB_n and RLB_n bits in the channel control registers.

## Notes:

1. In the Analog loopback mode, data is also output via TTIP_n and TRING_n pins.
2. Signals on the RTIP_n and RRING_n pins are ignored during analog loopback.

Figure 27. Analog Loopback


### 9.2.2 DIGITAL LOOPBACK:

The Digital Loopback function is available either in Hardware mode or Host mode. When the Digital Loopback is selected, the transmit clock (TxClk_n) and transmit data inputs (TPDATA_n \& TNDATA_n) are looped back and output onto the RxClk_n, RPOS_n and RNEG_n pins as shown in Figure 27.

Figure 28. Digital Loopback


### 9.2.3 REMOTE LOOPBACK:

With Remote loopback activated as shown in Figure 28, the receive data on RTIP and RRING is looped back after the jitter attenuator (if selected in receive or transmit path) to the transmit path using RxClk as transmit timing. The receive data is also output via the RPOS and RNEG pins.
During the remote loopback mode, if the jitter attenuator is selected in the transmit path, the receive data after the Clock and Data Recovery Block is looped back to the transmit path and passed through the jitter attenuator using RxClk as the transmit timing.

Note: Input signals on TxClk, TPDATA and TNDATA are ignored during Remote loopback.
Figure 29. Remote Loopback


### 9.3 TRANSMIT ALL ONES (TAOS):

Transmit All Ones (TAOS) can be set either in Hardware mode by pulling the TAOS_n pins "High" or in Host mode by setting the TAOS_n control bits to " 1 " in the Channel control registers. When the TAOS is set, the Transmit Section generates and transmits a continuous AMI all "1's" pattern on TTIP_n and TRING_n pins. The frequency of this " 1 's" pattern is determined by TCIk_n.TAOS data path is shown in Figure 29. TAOS does not operate in Analog loopback or Remote loopback modes. It will function in Digital loopback mode.

Figure 30. Transmit All Ones (TAOS)


ORDERING INFORMATION

| Part Number | Package | Operating Temperature Range |
| :---: | :---: | :---: |
| XRT75R03IV | $14 \times 20 \mathrm{~mm} \mathrm{128} \mathrm{Pin} \mathrm{LQFP}$ | $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ |

PACKAGE DIMENSIONS - 14X20 MM, 128 PIN PACKAGE


| SYMBOL | INCHES |  | MILLIMETERS |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  | MIN | MAX | MIN | MAX |  |
| A | 0.055 | 0.063 | 1.40 | 1.60 |  |
| A1 | 0.002 | 0.006 | 0.05 | 0.15 |  |
| A2 | 0.053 | 0.057 | 1.35 | 1.45 |  |
| B | 0.007 | 0.011 | 0.17 | 0.27 |  |
| C | 0.004 | 0.008 | 0.09 | 0.20 |  |
| D | 0.858 | 0.874 | 21.80 | 22.20 |  |
| D1 | 0.783 | 0.791 | 19.90 | 20.10 |  |
| E | 0.622 | 0.638 | 15.80 | 16.20 |  |
| E1 | 0.547 | 0.555 | 13.90 | 14.10 |  |
| e | 0.020 |  | BSC | 0.50 BSC |  |
| L | 0.018 | 0.030 | 0.45 | 0.75 |  |
| $\alpha$ | $00^{\circ}$ | $7^{\circ}$ | $0^{\circ}$ | $7{ }^{\circ}$ |  |

## REVISIONS

| Revision | DATE | ComMENTS |
| :---: | :---: | :--- |
| 1.0 .0 | $05 / 03$ | First release. |
| 1.0 .1 | $05 / 03$ | TxOn in numerical pinlist comments changed to pulled "High" |
| 1.0 .2 | $06 / 03$ | In B3ZS/HDB3 Decoder section change NOTE to Dual-Rail mode. Reformat section numbers. <br> Change XRT75vI03 to XRT75VL03. |
| 1.0 .3 | $06 / 03$ | Update figures. Edit Features, 5V tolerant digital inputs. Edit Applications: remove De-sync. <br> Edit Pinlist: loopback mode table, RXA and RXB to 3.01K. Edit Interference margin test set <br> ups and results. E3 LOS condition change from 175 $\pm 75$ to 10 to 255 consecutive pulse peri- <br> ods. TXON in registers pulled "High". TAOS section added text. Table 22: Bit 7 = 0. |
| 1.0 .4 | $08 / 03$ | Changed XRT75VL03 to XRT75R03. Added R3 Technology description. |
| 1.0 .5 | $12 / 03$ | Changed the pin description for E3CIk/CIk_en and STS-1CIk/12M. Removed page 18 (redun- <br> dant page). Changed the Enable to Status in Register 0x21h. <br> 1.0 .6 |
| 1.0 .7 | $09 / 04$ | Removed reference to heat slug in package dimensions. |
| 1.0 .8 | $03 / 06$ | Changed the pin listing for Pin 35. Changed from TAOS to TxCLK_0 |
| Corrected Table 22 Chip Revision register and description to 0x8\#. Updated Table 10 ALOS <br> declaration and clearance threshold. Updated RxMON functional description. |  |  |

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