

56F8014

Data Sheet
Technical Data

56F8000
16-bit Digital Signal Controllers

MC56F8014
Rev. 11
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freescale.com



Document Revision History

| Version History | Description of Change |
|-----------------|--|
| Rev 0 | Initial release |
| Rev 1 | Updates to Part 10, Specifications , Table 10-1 , added maximum clamp current, per pin Table 10-11 , clarified variation over temperature table and graph Table 10-15 , added LIN slave timing |
| Rev 2 | Added alternate pins to Figure 11-1 and Table 11-1 . |
| Rev 3 | Corrected bit selects in Timer Channel 3 Input (TC3_INP) bit 9, Section 6.3.1.7 , clarified Section 1.4.1 , and simplified notes in Table 10-9 , |
| Rev 4 | Added clarification on sync inputs in Section 1.4.1 , added voltage difference specification to Table 10-1 and Table 10-4 , deleted formula for Ambient Operating Temperature in Table 10-4 , and a note for pin group 3, corrected Table 8-1 , error in Port C peripheral function configuration, updated notes in Table 10-9 . Added RoHs and “pb-free” language to back cover. |
| Rev 5 | Updates to Section 10 Table 10-5 , corrected max values for ADC Input Current High and Low; corrected typ value for pull-up disabled Digital Input Current Low (a) Table 10-6 , corrected typ and added max values for Standby > Stop and Powerdown modes Table 10-7 , corrected min value for Low-Voltage Interrupt for 3.3V Table 10-11 , corrected typ and max values and units for PLL lock time Table 10-12 , corrected typ values for Relaxation Oscillator output frequency and variation over temperature (also increased temp range to 150 degreesC) and added variation over temperature from 0—105 degreesC Updated Figure 10-5 Table 10-19 , updated max values for Integral Non-Linearity full input signal range, Negative Differential Non-Linearity, ADC internal clock, Offset Voltage Internal Ref, Gain Error and Offset Voltage External Ref; updated typ values for Negative Differential Non-Linearity, Offset Voltage Internal Ref, Gain Error and Offset Voltage External Ref; added new min values and corrected typ values for Signal-to-noise ratio, Total Harmonic Distortion, Spurious Free Dynamic Range, Signal-to-noise plus distortion, Effective Number of Bits |
| Rev 6 | Added details to Section 1. Clarified language in State During Reset column in Table 2-3 ; corrected flash data retention temperature in Table 10-4 ; moved input current high/low to Table 10-19 and location of footnotes in Table 10-5 ; reorganized Table 10-19 ; clarified title of Figure 10-1 . |
| Rev. 7 | <ul style="list-style-type: none"> • In Table 10-4, added an entry for flash data retention with less than 100 program/erase cycles (minimum 20 years). • In Table 10-6, changed the device clock speed in STOP mode from 8MHz to 4MHz. • In Table 10-12, changed the typical relaxation oscillator output frequency in Standby mode from 400kHz to 200kHz. |
| Rev. 8 | In Table 10-19 , changed the maximum ADC internal clock frequency from 8MHz to 5.33MHz. |

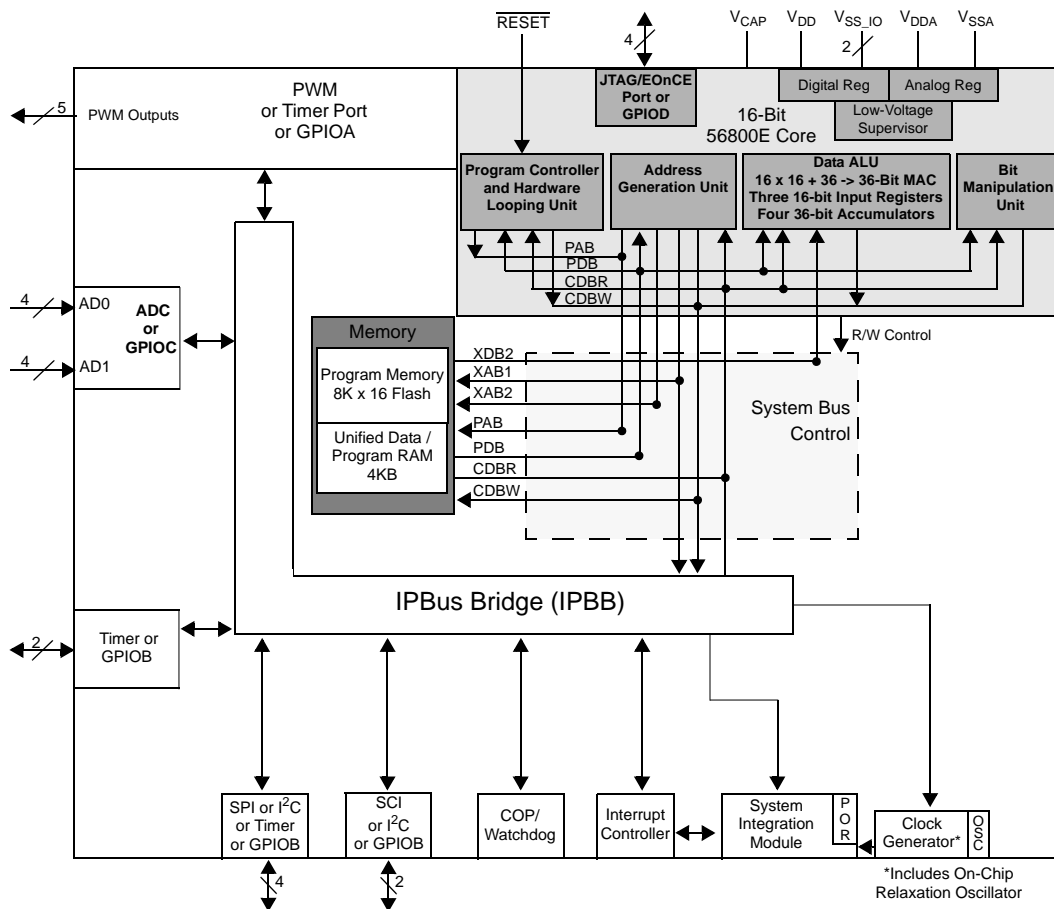
Document Revision History (Continued)

| Version History | Description of Change |
|-----------------|---|
| Rev. 9 | Added the following note to the description of the TMS signal in Table 2-3 : Note: Always tie the TMS pin to V _{DD} through a 2.2K resistor. |
| Rev. 10 | <ul style="list-style-type: none">• In Table 2-3, changed V_{CAP} value from 4.7 μF to 2.2 μF.• In Table 2-3, changed the input type for FAULT3 (was “Output”, is “Input”).• In Table 2-3, changed the input type for FAULT2 (was “Input/Output”, is “Input”).• Revised Section 7, Security Features.• Added MC56F8014MFAE to Section 13, Ordering Information.• Fixed miscellaneous errors. |
| Rev.11 | <ul style="list-style-type: none">• Updated temperature information in Table 10-1 and Table 10-4. |

Please see <http://www.freescale.com> for the most current data sheet revision.

56F8014 General Description

- Up to 32 MIPS at 32MHz core frequency
- DSP and MCU functionality in a unified, C-efficient architecture
- 16KB Program Flash
- 4KB Unified Data/Program RAM
- One 5-channel PWM module
- Two 4-channel 12-bit ADCs
- One Serial Communication Interface (SCI) with LIN slave functionality
- One Serial Peripheral Interface (SPI)
- One 16-bit Quad Timer
- One Inter-Integrated Circuit (I²C) Port
- Computer Operating Properly (COP)/Watchdog
- On-Chip Relaxation Oscillator
- Integrated Power-On Reset and Low-Voltage Interrupt Module
- JTAG/Enhanced On-Chip Emulation (OnCE™) for unobtrusive, real-time debugging
- Up to 26 GPIO lines
- 32-pin LQFP Package



56F8014 Block Diagram

56F8014 Data Sheet Table of Contents

| | | | |
|---|-----------|--|------------|
| Part 1: Overview | 6 | Part 7: Security Features | 82 |
| 1.1. 56F8014 Features | 6 | 7.1. Operation with Security Enabled | 82 |
| 1.2. 56F8014 Description | 8 | 7.2. Flash Access Lock and Unlock Mechanisms | 83 |
| 1.3. Award-Winning Development Environment . | 8 | 7.3. Product Analysis | 84 |
| 1.4. Architecture Block Diagram | 9 | Part 8: General Purpose Input/Output (GPIO) | 84 |
| 1.5. Synchronize ADC with PWM | 9 | | 84 |
| 1.6. Multiple Frequency PWM Output | 9 | 8.1. Introduction | 84 |
| 1.7. Product Documentation | 13 | 8.2. Configuration | 84 |
| 1.8. Data Sheet Conventions | 13 | 8.3. Reset Values | 86 |
| Part 2: Signal/Connection Descriptions .. | 14 | Part 9: Joint Test Action Group (JTAG) .. | 91 |
| 2.1. Introduction | 14 | 9.1. 56F8014 Information | 91 |
| 2.2. 56F8014 Signal Pins | 18 | Part 10: Specifications | 91 |
| Part 3: OCCS | 26 | 10.1. General Characteristics | 91 |
| 3.1. Overview | 26 | 10.2. DC Electrical Characteristics | 95 |
| 3.2. Features | 26 | 10.3. AC Electrical Characteristics | 97 |
| 3.3. Operating Modes | 26 | 10.4. Flash Memory Characteristics | 98 |
| 3.4. Block Diagram | 28 | 10.5. External Clock Operation Timing | 99 |
| 3.5. Pin Descriptions | 29 | 10.6. Phase Locked Loop Timing | 99 |
| Part 4: Memory Map | 29 | 10.7. Relaxation Oscillator Timing | 100 |
| 4.1. Introduction | 29 | 10.8. Reset, Stop, Wait, Mode Select, and | |
| 4.2. Interrupt Vector Table | 29 | Interrupt Timing | 101 |
| 4.3. Program Map | 31 | 10.9. Serial Peripheral Interface (SPI) Timing .. | 102 |
| 4.4. Data Map | 32 | 10.10. Quad Timer Timing | 105 |
| 4.5. EOnCE Memory Map | 32 | 10.11. Serial Communication Interface (SCI) | |
| 4.6. Peripheral Memory Mapped Registers | 33 | Timing | 107 |
| Part 5: Interrupt Controller (ITCN) | 43 | 10.12. Inter-Integrated Circuit Interface (I2C) | |
| 5.1. Introduction | 43 | Timing | 108 |
| 5.2. Features | 43 | 10.13. JTAG Timing | 109 |
| 5.3. Functional Description | 43 | 10.14. Analog-to-Digital Converter (ADC) | |
| 5.4. Block Diagram | 45 | Parameters | 111 |
| 5.5. Register Descriptions | 45 | 10.15. Equivalent Circuit for ADC Inputs | 112 |
| 5.6. Resets | 61 | 10.16. Power Consumption | 112 |
| Part 6: System Integration Module (SIM) .. | 62 | Part 11: Packaging | 115 |
| 6.1. Introduction | 62 | 11.1. 56F8014 Package and Pin-Out | |
| 6.2. Features | 62 | Information | 115 |
| 6.3. Register Descriptions | 64 | Part 12: Design Considerations | 118 |
| 6.4. Clock Generation Overview | 77 | 12.1. Thermal Design Considerations | 118 |
| 6.5. Power-Down Modes | 77 | 12.2. Electrical Design Considerations | 119 |
| 6.6. Resets | 79 | Part 13: Ordering Information | 121 |
| 6.7. Clocks | 81 | Part 14: Appendix | 122 |
| 6.8. Interrupts | 82 | | |

Part 1 Overview

1.1 56F8014 Features

1.1.1 Digital Signal Controller Core

- Efficient 16-bit 56800E family Digital Signal Controller (DSC) engine with dual Harvard architecture
- As many as 32 Million Instructions Per Second (MIPS) at 32MHz core frequency
- Single-cycle 16×16 -bit parallel Multiplier-Accumulator (MAC)
- Four 36-bit accumulators, including extension bits
- 32-bit arithmetic and logic multi-bit shifter
- Parallel instruction set with unique DSP addressing modes
- Hardware DO and REP loops
- Three internal address buses
- Four internal data buses
- Instruction set supports both DSP and controller functions
- Controller-style addressing modes and instructions for compact code
- Efficient C compiler and local variable support
- Software subroutine and interrupt stack with depth limited only by memory
- JTAG/Enhanced On-Chip Emulation (OnCE) for unobtrusive, processor speed-independent, real-time debugging

1.1.2 Memory

- Dual Harvard architecture permits as many as three simultaneous accesses to program and data memory
- Flash security and protection that prevent unauthorized users from gaining access to the internal Flash
- On-chip memory
 - 16KB of Program Flash
 - 4KB of Unified Data/Program RAM
- EEPROM emulation capability using Flash

1.1.3 Peripheral Circuits for 56F8014

- One multi-function five-output Pulse Width Modulator (PWM) module
 - Up to 96MHz PWM operating clock
 - 15 bits of resolution
 - Center-aligned and Edge-aligned PWM signal mode
 - Three programmable fault inputs with programmable digital filter
 - Double-buffered PWM registers

- Each complementary PWM signal pair can output a different switching frequency by selecting PWM generation sources from:
 - PWM generator
 - External GPIO
 - Internal timers
 - ADC conversion result of over/under limits:
 - When conversion result is greater than high limit, deactivate PWM signal
 - When conversion result is less than low limit, activate PWM signal
- Two independent 12-bit Analog-to-Digital Converters (ADCs)
 - 2 x 4 channel inputs
 - Supports both simultaneous and sequential conversions
 - ADC conversions can be synchronized by both PWM and timer modules
 - Sampling rate up to 2.67MSPS
 - 8-word result buffer registers
 - ADC Smart Power Management (Auto-standby, auto-powerdown)
- One 16-bit multi-purpose Quad Timer module (TMR)
 - Up to 96MHz operating clock
 - Four independent 16-bit counter/timers with cascading capability
 - Each timer has capture and compare capability
 - Up to 12 operating modes
- One Serial Communication Interface (SCI) with LIN slave functionality
 - Full-duplex or single-wire operation
 - Two receiver wake-up methods:
 - Idle line
 - Address mark
- One Serial Peripheral Interface (SPI)
 - Full-duplex operation
 - Master and slave modes
 - Programmable length transactions (two to sixteen bits)
- One Inter-Integrated Circuit (I²C) port
 - Operates up to 400 kbps
 - Supports both master and slave operation
- Computer Operating Properly (COP)/Watchdog timer capable of selecting different clock sources
- Up to 26 General-Purpose I/O (GPIO) pins with 5V tolerance
- Integrated Power-On Reset and Low-Voltage Interrupt Module
- Phase Lock Loop (PLL) provides a high-speed clock to the core and peripherals
- Clock Sources:
 - On-chip relaxation oscillator

- External clock source
- On-chip regulators for digital and analog circuitry to lower cost and reduce noise
- JTAG/EOnCE debug programming interface for real-time debugging

1.1.4 Energy Information

- Fabricated in high-density CMOS with 5V-tolerant, TTL-compatible digital inputs
- On-chip regulators for digital and analog circuitry to lower cost and reduce noise
- Wait and Stop modes available
- ADC smart power management
- Each peripheral can be individually disabled to save power

1.2 56F8014 Description

The 56F8014 is a member of the 56800E core-based family of Digital Signal Controllers (DSCs). It combines, on a single chip, the processing power of a DSP and the functionality of a microcontroller with a flexible set of peripherals to create an extremely cost-effective solution. Because of its low cost, configuration flexibility, and compact program code, the 56F8014 is well-suited for many applications. The 56F8014 includes many peripherals that are especially useful for industrial control, motion control, home appliances, general purpose inverters, smart sensors, fire and security systems, switched-mode power supplies, power management, and medical monitoring applications.

The 56800E core is based on a dual Harvard-style architecture consisting of three execution units operating in parallel, allowing as many as six operations per instruction cycle. The MCU-style programming model and optimized instruction set allow straightforward generation of efficient, compact DSP and control code. The instruction set is also highly efficient for C compilers to enable rapid development of optimized control applications.

The 56F8014 supports program execution from internal memories. Two data operands can be accessed from the on-chip data RAM per instruction cycle. The 56F8014 also offers up to 26 General Purpose Input/Output (GPIO) lines, depending on peripheral configuration.

The 56F8014 Digital Signal Controller includes 16KB of Program Flash and 4KB of Unified Data/Program RAM. Program Flash memory can be independently bulk erased or erased in pages. Program Flash page erase size is 512 Bytes/256 Words.

A full set of programmable peripherals—PWM, ADCs, SCI, SPI, I²C, Quad Timer—support various applications. Each peripheral can be independently shut down to save power. Any pin in these peripherals can also be used as a General Purpose Input/Outputs (GPIO).

1.3 Award-Winning Development Environment

Processor ExpertTM (PE) provides a Rapid Application Design (RAD) tool that combines easy-to-use component-based software application creation with an expert knowledge system.

The CodeWarrior Integrated Development Environment is a sophisticated tool for code navigation, compiling, and debugging. A complete set of evaluation modules (EVMs), demonstration board kit and development system cards will support concurrent engineering. Together, PE, CodeWarrior and EVMs

create a complete, scalable tools solution for easy, fast, and efficient development.

1.4 Architecture Block Diagram

The 56F8014's architecture is shown in [Figure 1-1](#), [Figure 1-2](#), and [Figure 1-3](#). [Figure 1-1](#) illustrates how the 56800E system buses communicate with internal memories and the IPBus Bridge, as well as showing the internal connections between each unit of the 56800E core. [Figure 1-2](#) shows the peripherals and control blocks connected to the IPBus Bridge. [Figure 1-3](#) details how the device's I/O pins are muxed. The figures do not show the on-board regulator and power and ground signals. They also do not show the multiplexing between peripherals or the dedicated GPIOs. Please see [Part 2 Signal/Connection Descriptions](#) to see which signals are multiplexed with those of other peripherals.

1.5 Synchronize ADC with PWM

ADC conversion can be synchronized with the PWM module via Quad Timer channel 2 and 3 if needed. Internally, the PWM synch signal — which is generated at every PWM reload — can be connected to the timer channel 3 input, and the timer channel 2 and channel 3 outputs are connected to the ADC sync inputs. Timer channel 3 output is connected to SYNC0 and timer channel 2 is connected to SYNC1. The setting is controlled by the TC3_INP bit in the SIM Control Register; see [Section 6.3.1](#).

SYNC0 is the master ADC sync input, used to trigger both ADCA and ADCB in sequence and parallel mode. SYNC1 is used to trigger ADCB in parallel independent mode, while SYNC0 is used to trigger ADCA. See *MC56F8000RM*, the 56F801X Peripheral Reference Manual, for additional information.

1.6 Multiple Frequency PWM Output

When both PWM channels of a complementary pair in software control mode and software control bits are set to 1, each complementary PWM signal pair — PWM 0 and 1; PWM 2 and 3; and PWM 4 and 5 — can select a PWM source from one of the following sources. This will enable each PWM pair and PWM2 to output PWM signals at different frequencies.

- External GPIO input:
 - GPIOB2 input can be used to drive PWM 0 and 1
 - GPIOB3 input can be used to drive PWM 2
 - GPIOB4 input can be used to drive PWM 4 and 5
- Quad Timer output:
 - Timer0 output can be used to drive PWM 0 and 1
 - Timer2 output can be used to drive PWM 2
 - Timer3 output can be used to drive PWM 4 and 5
- ADC conversion result:
 - Signal of over/under limit of ADC sample 0 can be used to drive PWM 0 and 1
 - Signal of over/under limit of ADC sample 1 can be used to drive PWM 2

— Signal of over/under limit of ADC sample 2 can be used to drive PWM 4 and 5

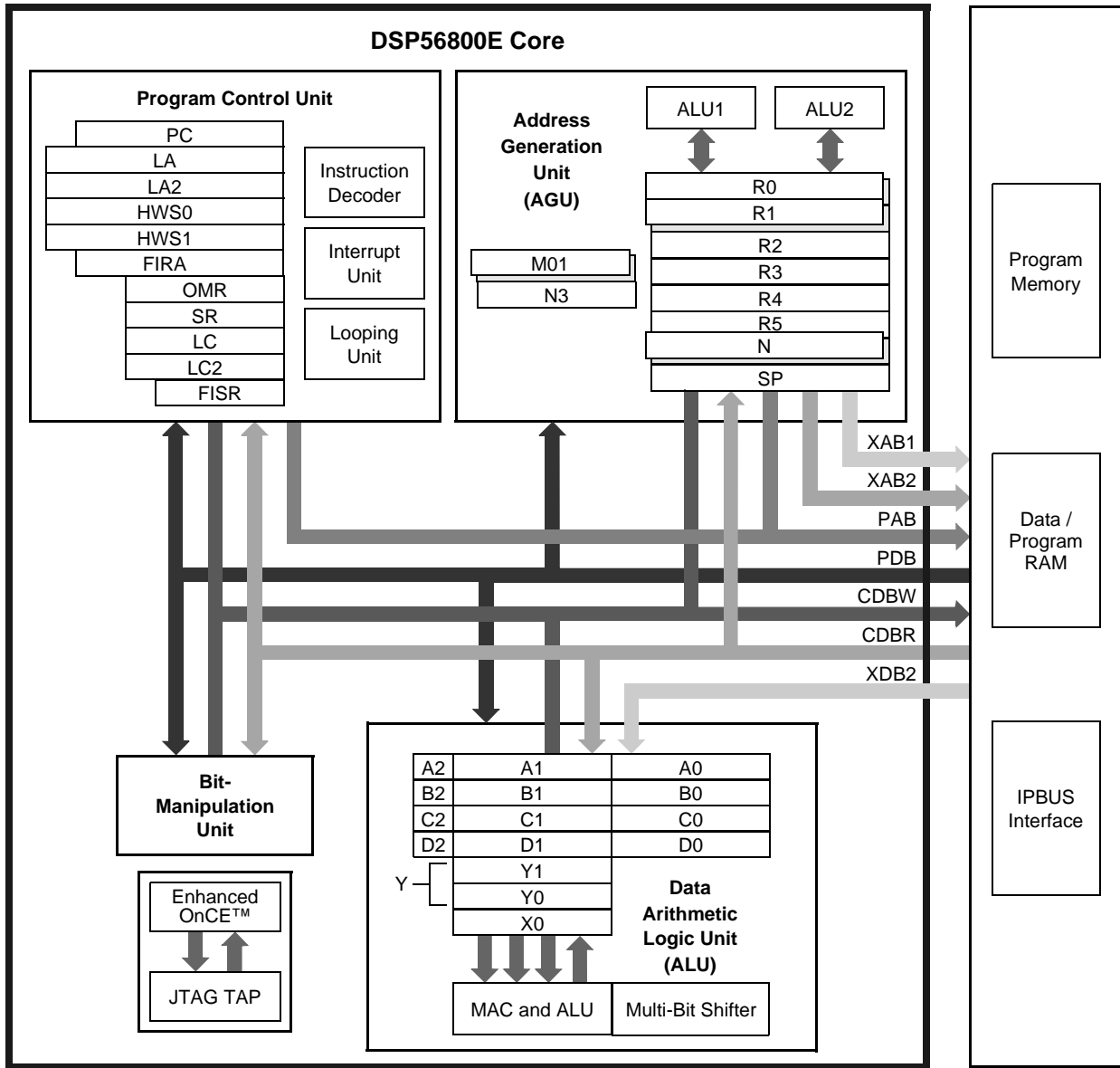


Figure 1-1 56800E Core Block Diagram

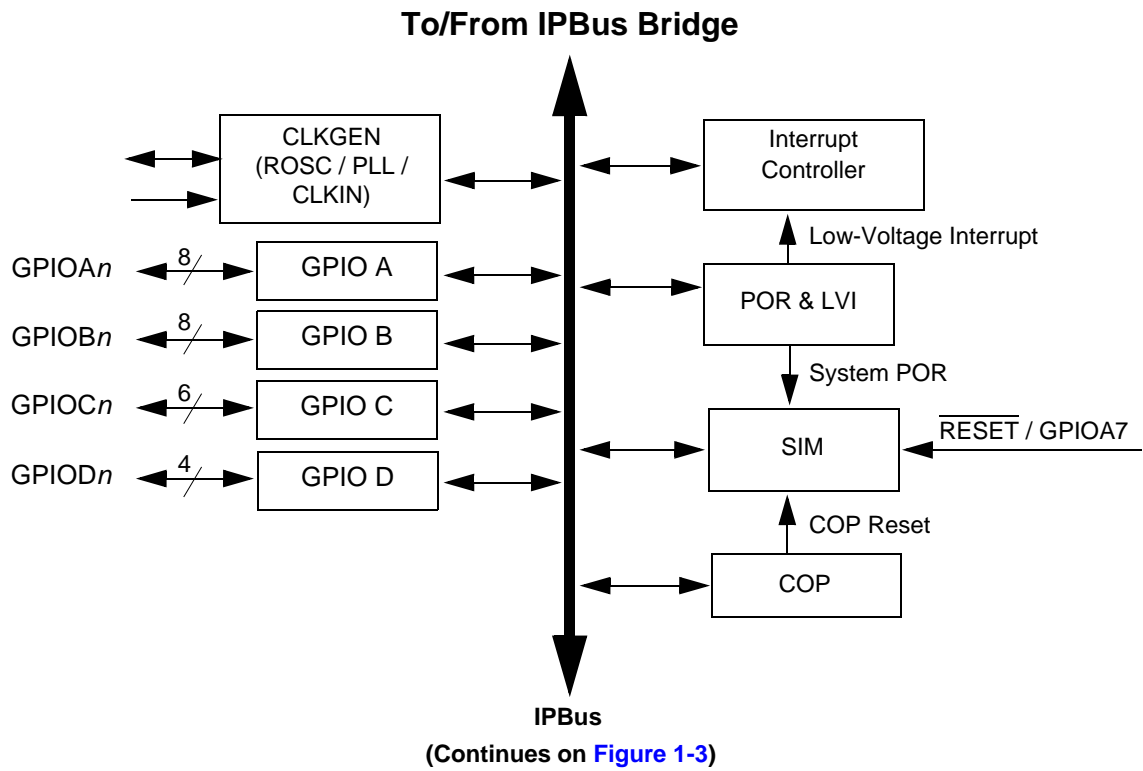


Figure 1-2 Peripheral Subsystem

(Continued from Figure 1-2)
To/From IPBus Bridge

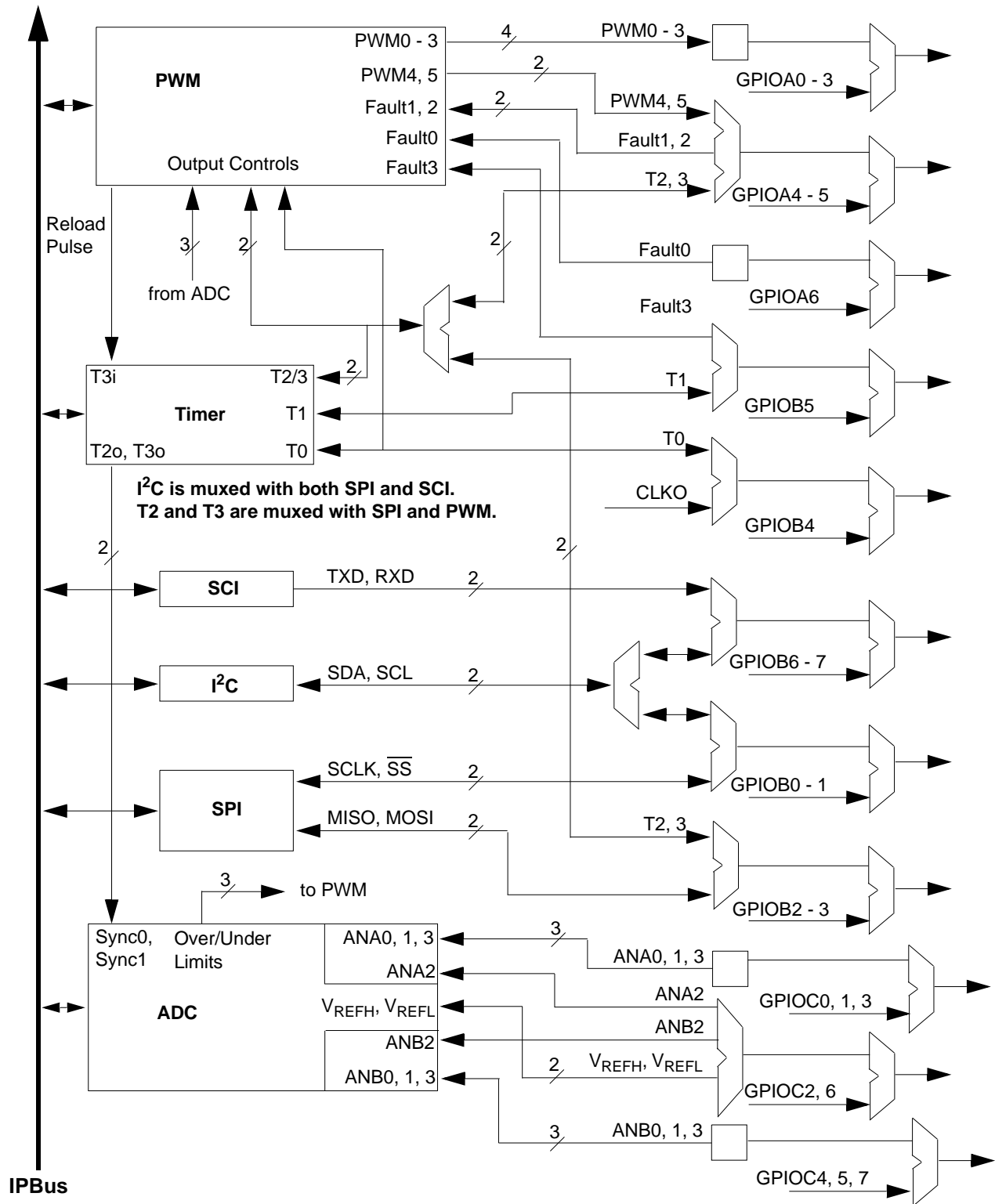


Figure 1-3 56F8014 Peripheral I/O Pin-Out

1.7 Product Documentation

The documents listed in [Table 1-1](#) are required for a complete description and proper design with the 56F8014. Documentation is available from local Freescale distributors, Freescale Semiconductor sales offices, Freescale Literature Distribution Centers, or online at:

<http://www.freescale.com>

Table 1-1 56F8014 Chip Documentation

| Topic | Description | Order Number |
|--------------------------------------|--|--------------|
| DSP56800E Reference Manual | Detailed description of the 56800E family architecture, 16-bit Digital Signal Controller core processor, and the instruction set | DSP56800ERM |
| 56F801X Peripheral Reference Manual | Detailed description of peripherals of the 56F801X family of devices | MC56F8000RM |
| 56F801x Serial Bootloader User Guide | Detailed description of the Serial Bootloader in the 56F801x family of devices | 56F801xBLUG |
| 56F8014 Technical Data Sheet | Electrical and timing specifications, pin descriptions, and package descriptions (this document) | MC56F8014 |
| 56F8014 Errata | Details any chip issues that might be present | MC56F8014E |

1.8 Data Sheet Conventions

This data sheet uses the following conventions:

$\overline{\text{OVERBAR}}$ This is used to indicate a signal that is active when pulled low. For example, the $\overline{\text{RESET}}$ pin is active when low.

“asserted” A high true (active high) signal is high or a low true (active low) signal is low.

“deasserted” A high true (active high) signal is low or a low true (active low) signal is high.

| Examples: | Signal/Symbol | Logic State | Signal State | Voltage ¹ |
|-----------|-------------------------|-------------|--------------|----------------------|
| | $\overline{\text{PIN}}$ | True | Asserted | V_{IL}/V_{OL} |
| | $\overline{\text{PIN}}$ | False | Deasserted | V_{IH}/V_{OH} |
| | PIN | True | Asserted | V_{IH}/V_{OH} |
| | PIN | False | Deasserted | V_{IL}/V_{OL} |

1. Values for V_{IL} , V_{OL} , V_{IH} , and V_{OH} are defined by individual product specifications.

Part 2 Signal/Connection Descriptions

2.1 Introduction

The input and output signals of the 56F8014 are organized into functional groups, as detailed in [Table 2-1](#). [Table 2-2](#) summarizes all device pins. In [Table 2-2](#), each table row describes the signal or signals present on a pin, sorted by pin number.

Table 2-1 Functional Group Pin Allocations

| Functional Group | Number of Pins |
|--|----------------|
| Power (V_{DD} or V_{DDA}) | 2 |
| Ground (V_{SS} or V_{SSA}) | 3 |
| Supply Capacitors | 1 |
| Reset | 1 |
| Pulse Width Modulator (PWM) Ports ¹ | 5 |
| Serial Peripheral Interface (SPI) Ports ² | 4 |
| Analog-to-Digital Converter (ADC) Ports | 8 |
| Timer Module Ports ³ | 2 |
| Serial Communications Interface (SCI) Ports ⁴ | 2 |
| JTAG/Enhanced On-Chip Emulation (EOnCE) | 4 |

1. Pins in this section can function as TMR and GPIO.

2. Pins in this section can function as TMR, I²C, and GPIO.

3. Pins can function as PWM and GPIO.

4. Pins in this section can function as I²C and GPIO.

Table 2-2 56F8014 Pins

| | | | Peripherals: | | | | | | | | | |
|------------|---------------|-------------------------------|--------------|-----|-----|-----------------|--------------------------|--------------|------------|----------------|------------|--------------|
| LQFP Pin # | Pin Name | Signal Name | GPIO | I2C | SCI | SPI | ADC | PWM | Quad Timer | Power & Ground | JTAG | Misc. |
| 1 | GPIOB1 | GPIOB1, \overline{SS} , SDA | B1 | SDA | | \overline{SS} | | | | | | |
| 2 | GPIOB7 | GPIOB7, TXD, SCL | B7 | SCL | TXD | | | | | | | |
| 3 | GPIOB5 | GPIOB5, T1, FAULT3 | B5 | | | | | FAULT3 | T1 | | | |
| 4 | ANB0 | ANB0, GPIOC4 | C4 | | | | ANB0 | | | | | |
| 5 | ANB1 | ANB1, GPIOC5 | C5 | | | | ANB1 | | | | | |
| 6 | ANB2 | ANB2, V_{REFL} , GPIOC6 | C6 | | | | ANB2 , V_{REFL} | | | | | |
| 7 | ANB3 | ANB3, GPIOC7 | C7 | | | | ANB3 | | | | | |
| 8 | VDDA | V_{DDA} | | | | | | | | V_{DDA} | | |
| 9 | VSSA | V_{SSA} | | | | | | | | V_{SSA} | | |
| 10 | ANA3 | ANA3, GPIOC3 | C3 | | | | ANA3 | | | | | |
| 11 | ANA2 | ANA2, V_{REFH} , GPIOC2 | C2 | | | | ANA2 , V_{REFH} | | | | | |
| 12 | ANA1 | ANA1, GPIOC1 | C1 | | | | ANA1 | | | | | |
| 13 | ANA0 | ANA0, GPIOC0 | C0 | | | | ANA0 | | | | | |
| 14 | VSS_IO | V_{SS_IO} | | | | | | | | V_{SS_IO} | | |
| 15 | TCK | TCK, GPIOD2 | D2 | | | | | | | | TCK | |
| 16 | RESET | \overline{RESET} , GPIOA7 | A7 | | | | | | | | | RESET |
| 17 | GPIOB3 | GPIOB3, MOSI, T3 | B3 | | | MOSI | | | T3 | | | |
| 18 | GPIOB2 | GPIOB2, MISO, T2 | B2 | | | MISO | | | T2 | | | |
| 19 | GPIOB4 | GPIOB4, T0, CLKO | B4 | | | | | | T0 | | | CLKO |
| 20 | GPIOA5 | GPIOA5, PWM5, FAULT2, T3 | A5 | | | | | PWM5, FAULT2 | T3 | | | |
| 21 | GPIOB0 | GPIOB0, SCLK, SCL | B0 | SCL | | SCLK | | | | | | |
| 22 | GPIOA4 | GPIOA4, PWM4, FAULT1, T2 | A4 | | | | | PWM4, FAULT1 | T2 | | | |
| 23 | GPIOA2 | GPIOA2, PWM2 | A2 | | | | | PWM2 | | | | |
| 24 | VCAP | V_{CAP} | | | | | | | | V_{CAP} | | |

Table 2-2 56F8014 Pins (Continued)

| | | | Peripherals: | | | | | | | | | |
|------------|---------------|-------------------------|--------------|-----|-----|-----|-----|------|------------|--------------------|------------|-------|
| LQFP Pin # | Pin Name | Signal Name | GPIO | I2C | SCI | SPI | ADC | PWM | Quad Timer | Power & Ground | JTAG | Misc. |
| 25 | VDD_IO | V _{DD_IO} | | | | | | | | V _{DD_IO} | | |
| 26 | VSS_IO | V _{SS_IO} | | | | | | | | V _{SS_IO} | | |
| 27 | GPIOA1 | GPIOA1, PWM1 | A1 | | | | | PWM1 | | | | |
| 28 | GPIOA0 | GPIOA0, PWM0 | A0 | | | | | PWM0 | | | | |
| 29 | TDI | TDI, GPIOD0 | D0 | | | | | | | | TDI | |
| 30 | TMS | TMS, GPIOD3 | D3 | | | | | | | | TMS | |
| 31 | TDO | TDO, GPIOD1 | D1 | | | | | | | | TDO | |
| 32 | GPIOB6 | GPIOB6, RXD, SDA, CLKIN | B6 | SDA | RXD | | | | | | | CLKIN |

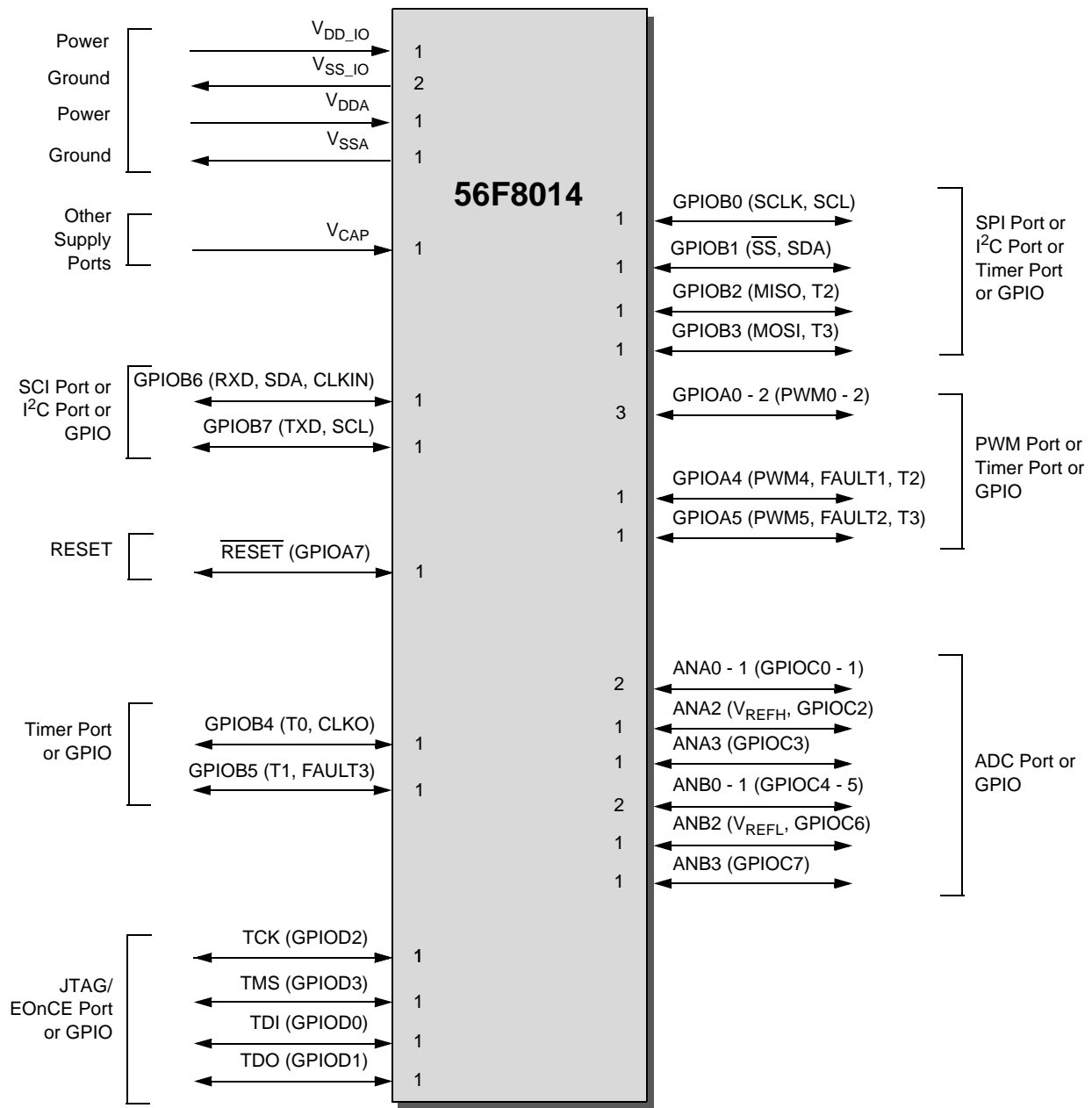


Figure 2-1 56F8014 Signals Identified by Functional Group (32-Pin LQFP)

2.2 56F8014 Signal Pins

After reset, each pin is configured for its primary function (listed first). Any alternate functionality must be programmed.

Table 2-3 56F8014 Signal and Package Information for the 32-Pin LQFP

| Signal Name | LQFP Pin No. | Type | State During Reset | Signal Description |
|--|--------------|--|--|--|
| V _{DD_IO} | 25 | Supply | Supply | I/O Power — This pin supplies 3.3V power to the chip I/O interface. |
| V _{SS_IO} | 14 | Supply | Supply | V_{SS} — These pins provide ground for chip logic and I/O drivers. |
| V _{SS_IO} | 26 | | | |
| V _{DDA} | 8 | Supply | Supply | ADC Power — This pin supplies 3.3V power to the ADC modules. It must be connected to a clean analog power supply. |
| V _{SSA} | 9 | Supply | Supply | ADC Analog Ground — This pin supplies an analog ground to the ADC modules. |
| V _{CAP} | 24 | Supply | Supply | V_{CAP} — Connect a 2.2 μ F or greater bypass capacitor between this pin and V _{SS_IO} , which is required by the internal voltage regulator for proper chip operation. See Section 10.2.1 . |
| GPIOB6 (RXD) (SDA ¹) (CLKIN) | 32 | Input/ Output Input Input/ Output Input | Input with internal pull-up enabled | <p>Port B GPIO — This GPIO pin can be individually programmed as an input or output pin.</p> <p>Receive Data — SCI receive data input.</p> <p>Serial Data — This pin serves as the I²C serial data line.</p> <p>Clock Input — This pin serves as an optional external clock input.</p> <p>After reset, the default state is GPIOB6. The alternative peripheral functionality is controlled via the SIM (See Section 6.3.8) and the CLKMODE bit of the OCCS Oscillator Control Register.</p> |
| 1. This signal is also brought out on the GPIOB1 pin. | | | | |

Return to [Table 2-2](#)

Table 2-3 56F8014 Signal and Package Information for the 32-Pin LQFP (Continued)

| Signal Name | LQFP Pin No. | Type | State During Reset | Signal Description |
|--|--------------|--|--|--|
| GPIOB7 (TXD) (SCL²) | 2 | Input/ Output Input/ Output Input/ Output | Input with internal pull-up enabled | <p>Port B GPIO — This GPIO pin can be individually programmed as an input or output pin.</p> <p>Transmit Data — SCI transmit data output or transmit / receive in single wire operation.</p> <p>Serial Clock — This pin serves as the I²C serial clock.</p> <p>After reset, the default state is GPIOB7. The alternative peripheral functionality is controlled via the SIM. See Section 6.3.8.</p> |
| 2. This signal is also brought out on the GPIOB0 pin. | | | | |
| $\overline{\text{RESET}}$ (GPIOA7) | 16 | Input Input/Open Drain Output | Input with internal pull-up enabled | <p>Reset — This input is a direct hardware reset on the processor. When $\overline{\text{RESET}}$ is asserted low, the chip is initialized and placed in the reset state. A Schmitt trigger input is used for noise immunity. The internal reset signal will be deasserted synchronous with the internal clocks after a fixed number of internal clocks.</p> <p>Port A GPIO — This GPIO pin can be individually programmed as an input or open drain output pin. Note that $\overline{\text{RESET}}$ functionality is disabled in this mode and the chip can only be reset via POR, COP reset, or software reset.</p> <p>After reset, the default state is $\overline{\text{RESET}}$.</p> |
| GPIOB4 (T0) (CLKO) | 19 | Input/ Output Input/ Output Output | Input with internal pull-up enabled | <p>Port B GPIO — This GPIO pin can be individually programmed as an input or output pin.</p> <p>T0 — Timer, Channel 0</p> <p>Clock Output — This is a buffered clock signal. Using the SIM_CLKO Select Register (SIM_CLKOSR), this pin can be programmed as any of the following: disabled (logic 0), CLK_MSTR (system clock), IPBus clock, or oscillator output. See Section 6.3.7.</p> <p>After reset, the default state is GPIOB4. The alternative peripheral functionality is controlled via the SIM. See Section 6.3.8.</p> |

Return to [Table 2-2](#)

Table 2-3 56F8014 Signal and Package Information for the 32-Pin LQFP (Continued)

| Signal Name | LQFP Pin No. | Type | State During Reset | Signal Description |
|---|--------------|---|-------------------------------------|---|
| GPIOB5 (T1) (FAULT3) | 3 | Input/ Output Input/ Output Input | Input with internal pull-up enabled | <p>Port B GPIO — This GPIO pin can be individually programmed as an input or output pin.</p> <p>T1 — Timer, Channel 1</p> <p>FAULT3 — This fault input pin is used for disabling selected PWM outputs in cases where fault conditions originate off-chip.</p> <p>After reset, the default state is GPIOB5. The alternative peripheral functionality is controlled via the SIM. See Section 6.3.8.</p> |
| TCK (GPIOD2) | 15 | Input Input/ Output | Input with internal pull-up enabled | <p>Test Clock Input — This input pin provides a gated clock to synchronize the test logic and shift serial data to the JTAG/EOnCE port. The pin is connected internally to a pull-up resistor. A Schmitt trigger input is used for noise immunity.</p> <p>Port D GPIO — This GPIO pin can be individually programmed as an input or output pin.</p> <p>After reset, the default state is TCK.</p> |
| TMS (GPIOD3) | 30 | Input Input/ Output | Input with internal pull-up enabled | <p>Test Mode Select Input — This input pin is used to sequence the JTAG TAP controller's state machine. It is sampled on the rising edge of TCK and has an on-chip pull-up resistor.</p> <p>Port D GPIO — This GPIO pin can be individually programmed as an input or output pin.</p> <p>After reset, the default state is TMS.</p> <p>Note: Always tie the TMS pin to V_{DD} through a 2.2K resistor if this pin is configured as TMS.</p> |
| TDI (GPIOD0) | 29 | Input Input/ Output | Input with internal pull-up enabled | <p>Test Data Input — This input pin provides a serial input data stream to the JTAG/EOnCE port. It is sampled on the rising edge of TCK and has an on-chip pull-up resistor.</p> <p>Port D GPIO — This GPIO pin can be individually programmed as an input or output pin.</p> <p>After reset, the default state is TDI.</p> |

Return to [Table 2-2](#)

Table 2-3 56F8014 Signal and Package Information for the 32-Pin LQFP (Continued)

| Signal Name | LQFP Pin No. | Type | State During Reset | Signal Description |
|--|--------------|--|--|---|
| TDO (GPIOD1) | 31 | Output Input/ Output | Output | Test Data Output — This tri-stateable output pin provides a serial output data stream from the JTAG/EOnCE port. It is driven in the shift-IR and shift-DR controller states, and changes on the falling edge of TCK. Port D GPIO — This GPIO pin can be individually programmed as an input or output pin. After reset, the default state is TDO. |
| GPIOB0 (SCLK) (SCL³) | 21 | Input/ Output Input/ Output Input/ Output | Input with internal pull-up enabled | Port B GPIO — This GPIO pin can be individually programmed as an input or output pin. SPI Serial Clock — In the master mode, this pin serves as an output, clocking slaved listeners. In slave mode, this pin serves as the data clock input. A Schmitt trigger input is used for noise immunity. Serial Data — This pin serves as the I ² C serial clock. After reset, the default state is GPIOB0. The alternative peripheral functionality is controlled via the SIM. See Section 6.3.8 . |
| 3. This signal is also brought out on the GPIOB7 pin. | | | | |
| GPIOB1 (\overline{SS}) (SDA⁴) | 1 | Input/ Output Input Input/ Output | Input with internal pull-up enabled | Port B GPIO — This GPIO pin can be individually programmed as an input or output pin. SPI Slave Select — \overline{SS} is used in slave mode to indicate to the SPI module that the current transfer is to be received. Serial Clock — This pin serves as the I ² C serial data line. After reset, the default state is GPIOB1. The alternative peripheral functionality is controlled via the SIM. See Section 6.3.8 . |
| 4. This signal is also brought out on the GPIOB6 pin. | | | | |

Return to [Table 2-2](#)

Table 2-3 56F8014 Signal and Package Information for the 32-Pin LQFP (Continued)

| Signal Name | LQFP Pin No. | Type | State During Reset | Signal Description |
|--|--------------|------------------|--|---|
| GPIOB2 | 18 | Input/ Output | Input with internal pull-up enabled | Port B GPIO — This GPIO pin can be individually programmed as an input or output pin. |
| (MISO) | | Input/ Output | | SPI Master In/Slave Out — This serial data pin is an input to a master device and an output from a slave device. The MISO line of a slave device is placed in the high-impedance state if the slave device is not selected. The slave device places data on the MISO line a half-cycle before the clock edge the master device uses to latch the data. |
| (T2⁵) | | Input/ Output | | T2 — Timer, Channel 2 After reset, the default state is GPIOB2. The alternative peripheral functionality is controlled via the SIM. See Section 6.3.8 . |
| 5. This signal is also brought out on the GPIOA4 pin. | | | | |
| GPIOB3 | 17 | Input/ Output | Input with internal pull-up enabled | Port B GPIO — This GPIO pin can be individually programmed as an input or output pin. |
| (MOSI) | | Input/ Output | | SPI Master Out/Slave In — This serial data pin is an output from a master device and an input to a slave device. The master device places data on the MOSI line a half-cycle before the clock edge the slave device uses to latch the data. |
| (T3⁶) | | Input/ Output | | T3 — Timer, Channel 3 After reset, the default state is GPIOB3. The alternative peripheral functionality is controlled via the SIM. See Section 6.3.8 . |
| 6. This signal is also brought out on the GPIOA5 pin. | | | | |
| GPIOA0 | 28 | Input/ Output | Input with internal pull-up enabled | Port A GPIO — This GPIO pin can be individually programmed as an input or output pin. |
| (PWM0) | | Output | | PWM0 — This is one of the six PWM output pins. After reset, the default state is GPIOA0. |

Return to [Table 2-2](#)

Table 2-3 56F8014 Signal and Package Information for the 32-Pin LQFP (Continued)

| Signal Name | LQFP Pin No. | Type | State During Reset | Signal Description |
|--|--------------|---|--|---|
| GPIOA1 (PWM1) | 27 | Input/ Output Output | Input with internal pull-up enabled | Port A GPIO — This GPIO pin can be individually programmed as an input or output pin. PWM1 — This is one of the six PWM output pins. After reset, the default state is GPIOA1. |
| GPIOA2 (PWM2) | 23 | Input/ Output Output | Input with internal pull-up enabled | Port A GPIO — This GPIO pin can be individually programmed as an input or output pin. PWM2 — This is one of the six PWM output pins. After reset, the default state is GPIOA2. |
| GPIOA4 (PWM4) (FAULT1) (T2⁷) | 22 | Input/ Output Output Input Input/ Output | Input with internal pull-up enabled | Port A GPIO — This GPIO pin can be individually programmed as an input or output pin. PWM4 — This is one of the six PWM output pins. Fault1 — This fault input pin is used for disabling selected PWM outputs in cases where fault conditions originate off-chip. T2 — Timer, Channel 2 After reset, the default state is GPIOA4. The alternative peripheral functionality is controlled via the SIM. See Section 6.3.8 . |
| 7. This signal is also brought out on the GPIOB2 pin. | | | | |
| GPIOA5 (PWM5) (FAULT2) (T3⁸) | 20 | Input/ Output Output Input Input/ Output | Input with internal pull-up enabled | Port A GPIO — This GPIO pin can be individually programmed as an input or output pin. PWM5 — This is one of the six PWM output pins. Fault2 — This fault input pin is used for disabling selected PWM outputs in cases where fault conditions originate off-chip. T3 — Timer, Channel 3 After reset, the default state is GPIOA5. The alternative peripheral functionality is controlled via the SIM. See Section 6.3.8 . |
| 8. This signal is also brought out on the GPIOB3 pin. | | | | |

Return to [Table 2-2](#)

Table 2-3 56F8014 Signal and Package Information for the 32-Pin LQFP (Continued)

| Signal Name | LQFP Pin No. | Type | State During Reset | Signal Description |
|---|--------------|--|--------------------|--|
| ANA0 (GPIOC0) | 13 | Input Input/ Output | Analog Input | ANA0 — Analog input to ADC A, channel 0 Port C GPIO — This GPIO pin can be individually programmed as an input or output pin. After reset, the default state is ANA0. |
| ANA1 (GPIOC1) | 12 | Input Input/ Output | Analog Input | ANA1 — Analog input to ADC A, channel 1 Port C GPIO — This GPIO pin can be individually programmed as an input or output pin. After reset, the default state is ANA1. |
| ANA2 (V_{REFH}) (GPIOC2) | 11 | Input Input Input/ Output | Analog Input | ANA2 — Analog input to ADC A, channel 2 V_{REFH} — Analog reference voltage high Port C GPIO — This GPIO pin can be individually programmed as an input or output pin. After reset, the default state is ANA2. |
| ANA3 (GPIOC3) | 10 | Input Input/ Output | Analog Input | ANA3 — Analog input to ADC A, channel 3 Port C GPIO — This GPIO pin can be individually programmed as an input or output pin. After reset, the default state is ANA3. |
| ANB0 (GPIOC4) | 4 | Input Input/ Output | Analog Input | ANB0 — Analog input to ADC B, channel 0 Port C GPIO — This GPIO pin can be individually programmed as an input or output pin. After reset, the default state is ANB0. |

Return to [Table 2-2](#)

Table 2-3 56F8014 Signal and Package Information for the 32-Pin LQFP (Continued)

| Signal Name | LQFP Pin No. | Type | State During Reset | Signal Description |
|---|--------------|--|--------------------|---|
| ANB1 (GPIOC5) | 5 | Input Input/ Output | Analog Input | ANB1 — Analog input to ADC B, channel 1 Port C GPIO — This GPIO pin can be individually programmed as an input or output pin. After reset, the default state is ANB1. |
| ANB2 (V_{REFL}) (GPIOC6) | 6 | Input Input Input/ Output | Analog Input | ANB2 — Analog input to ADC B, channel 2 V_{REFL} — Analog reference voltage low. This should normally be connected to a low-noise V _{SS} . Port C GPIO — This GPIO pin can be individually programmed as an input or output pin. After reset, the default state is ANB2. |
| ANB3 (GPIOC7) | 7 | Input Input/ Output | Analog Input | ANB3 — Analog input to ADC B, channel 3 Port C GPIO — This GPIO pin can be individually programmed as an input or output pin. After reset, the default state is ANB3. |

Return to [Table 2-2](#)

Part 3 OCCS

3.1 Overview

This module provides the system clock, which uses it to generate the various chip clocks. This module also produces the oscillator clock signals, plus the ADC clock and high-speed peripheral clock.

The on-chip clock synthesis module allows product design using an internal relaxation oscillator to run 56F801X family parts at user-selectable frequencies up to 32MHz.

3.2 Features

The On-Chip Clock Synthesis (OCCS) module interfaces to the oscillator and PLL. The OCCS module features:

- Internal relaxation oscillator
- Ability to power down the internal relaxation oscillator
- Ability to put the internal relaxation oscillator into a standby mode
- 3-bit postscaler provides control for the PLL output
- Ability to power down the internal PLL
- Provides 2X system clock frequency, which operates at twice the system clock, to the System Integration Module (SIM) that is used to generate the various device clocks
- Provides 3X system clock, which operates at three times the system clock, to PWM and Timer
- Safety shutdown feature is available in the event that the PLL reference clock disappears
- Can be driven from an external clock source

The clock generation module provides the programming interface for both the PLL and internal relaxation oscillator.

3.3 Operating Modes

In 56F801X family parts, either an internal oscillator or an external frequency source can be used to provide a reference clock to the SIM.

The 2X system clock source output from the OCCS can be described by one of the following equations:

$$2X \text{ system frequency} = \text{oscillator frequency}$$

$$2X \text{ system frequency} = (\text{oscillator frequency} \times 8) / (\text{postscaler})$$

where:

$$\text{postscaler} = 1, 2, 4, 8, 16, \text{ or } 32 \text{ PLL output divider}$$

The SIM is responsible for further dividing these frequencies by two, which will insure a 50% duty cycle in the system clock output.

The 56F801X family parts' on-chip clock synthesis module has the following registers:

- Control Register (OCCS_CR)
- Divide-by Register (OCCS_DB)
- Status Register (OCCS_SR)
- Shutdown Register (OCCS_SHUTDOWN)
- Oscillator Control Register (OCCS_OCTRL)

For more information on these registers, please refer to the **56F801X Peripheral Reference Manual**.

3.3.1 External Clock Source

The recommended method of connecting an external clock is illustrated in [Figure 3-1](#). The external clock source is connected to GPIOB6 / RXD / SDA / CLKIN.

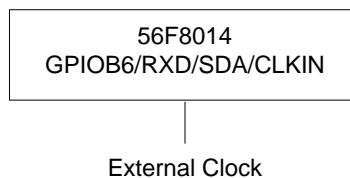


Figure 3-1 Connecting an External Clock Signal using GPIOB6 / RXD / SDA / CLKIN

3.4 Block Diagram

Figure 3-2 provides a block diagram which shows how the 56F8014 creates its internal clock, using the relaxation oscillator as an 8MHz clock reference for the PLL.

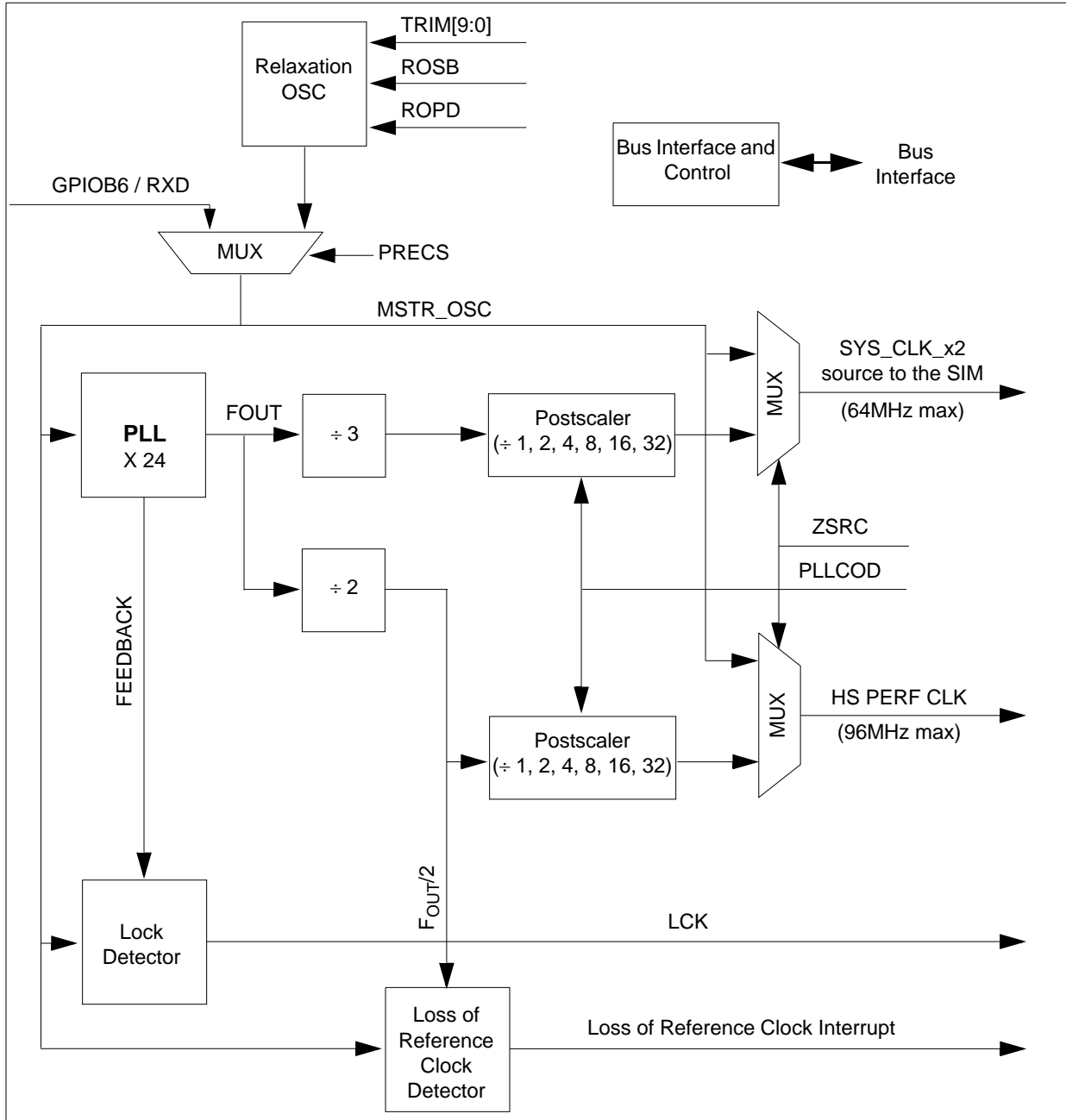


Figure 3-2 OCSS Block Diagram with Relaxation Oscillator

3.5 Pin Descriptions

3.5.1 External Reference (GPIOB6 / RXD / SDA / CLKIN)

After reset, the internal relaxation oscillator is selected as the clock source for the chip. The user then has the option of switching to an external clock reference by enabling the PRECS bit in the OCCS Oscillator Control register, if desired.

Part 4 Memory Map

4.1 Introduction

The 56F8014 device is a 16-bit motor-control chip based on the 56800E core. It uses a Harvard-style architecture with two independent memory spaces for Data and Program. On-chip RAM is used in both spaces and Flash memory is used only in Program space.

This section provides memory maps for:

- Program Address Space, including the Interrupt Vector Table
- Data Address Space, including the EOnCE Memory and Peripheral Memory Maps

On-chip memory sizes for the device are summarized in [Table 4-1](#). Flash memories' restrictions are identified in the "Use Restrictions" column of [Table 4-1](#).

Table 4-1 Chip Memory Configurations

| On-Chip Memory | 56F8014 | Use Restrictions |
|------------------------|---------|--|
| Program Flash (PFLASH) | 8k x 16 | Erase / Program via Flash interface unit and word writes to CDBW |
| Unified RAM (ram) | 2k x 16 | Usable by both the Program and Data memory spaces |

4.2 Interrupt Vector Table

[Table 4-2](#) provides the 56F8014's reset and interrupt priority structure, including on-chip peripherals. The table is organized with higher-priority vectors at the top and lower-priority interrupts lower in the table. As indicated, the priority of an interrupt can be assigned to different levels, allowing some control over interrupt priorities. All level 3 interrupts will be serviced before level 2, and so on. For a selected priority level, the lowest vector number has the highest priority.

The location of the vector table is determined by the Vector Base Address (VBA). Please see [Section 5.5.6](#) for the reset value of the VBA.

By default, the chip reset address and COP reset address will correspond to vector 0 and 1 of the interrupt vector table. In these instances, the first two locations in the vector table must contain branch or JMP instructions. All other entries must contain JSR instructions.

Table 4-2 Interrupt Vector Table Contents¹

| Peripheral | Vector Number | Priority Level | Vector Base Address + | Interrupt Function |
|-----------------------|---------------|----------------|-----------------------|---|
| core | | | P:\$00 | Reserved for Reset Overlay ² |
| core | | | P:\$02 | Reserved for COP Reset Overlay |
| core | 2 | 3 | P:\$04 | Illegal Instruction |
| core | 3 | 3 | P:\$06 | SW Interrupt 3 |
| core | 4 | 3 | P:\$08 | HW Stack Overflow |
| core | 5 | 3 | P:\$0A | Misaligned Long Word Access |
| core | 6 | 1-3 | P:\$0C | EOnCE Step Counter |
| core | 7 | 1-3 | P:\$0E | EOnCE Breakpoint Unit 0 |
| core | 8 | 1-3 | P:\$10 | EOnCE Trace Buffer |
| core | 9 | 1-3 | P:\$12 | EOnCE Transmit Register Empty |
| core | 10 | 1-3 | P:\$14 | EOnCE Receive Register Full |
| core | 11 | 2 | P:\$16 | SW Interrupt 2 |
| core | 12 | 1 | P:\$18 | SW Interrupt 1 |
| core | 13 | 0 | P:\$1A | SW Interrupt 0 |
| | 14 | | | Reserved |
| | 15 | | | Reserved |
| PS | 16 | 0-2 | P:\$20 | Power Sense |
| OCCS | 17 | 0-2 | P:\$22 | PLL Lock, Loss of Clock Reference Interrupt |
| FM | 18 | 0-2 | P:\$24 | FM Access Error Interrupt |
| FM | 19 | 0-2 | P:\$26 | FM Command Complete |
| FM | 20 | 0-2 | P:\$28 | FM Command, data and address Buffers Empty |
| | 21 | | | Reserved |
| GPIOD | 22 | 0-2 | P:\$2C | GPIOD |
| GPIOC | 23 | 0-2 | P:\$2E | GPIOC |
| GPIOB | 24 | 0-2 | P:\$30 | GPIOB |
| GPIOA | 25 | 0-2 | P:\$32 | GPIOA |
| SPI | 26 | 0-2 | P:\$34 | SPI Receiver Full / Error |
| SPI | 27 | 0-2 | P:\$36 | SPI Transmitter Empty |
| SCI | 28 | 0-2 | P:\$38 | SCI Transmitter Empty |
| SCI | 29 | 0-2 | P:\$3A | SCI Transmitter Idle |
| SCI | 30 | 0-2 | P:\$3C | SCI Reserved |
| SCI | 31 | 0-2 | P:\$3E | SCI Receiver Error |
| SCI | 32 | 0-2 | P:\$40 | SCI Receiver Full |
| | 33, 34 | | | Reserved |
| I ² C | 35 | 0-2 | P:\$46 | I ² C |
| Timer | 36 | 0-2 | P:\$48 | Timer Channel 0 |
| Timer | 37 | 0-2 | P:\$4A | Timer Channel 1 |
| (Continues next page) | | | | |

Table 4-2 Interrupt Vector Table Contents¹ (Continued)

| Peripheral | Vector Number | Priority Level | Vector Base Address + | Interrupt Function |
|------------|---------------|----------------|-----------------------|----------------------------------|
| Timer | 38 | 0-2 | P:\$4C | Timer Channel 2 |
| Timer | 39 | 0-2 | P:\$4E | Timer Channel 3 |
| ADC | 40 | 0-2 | P:\$50 | ADCA Conversion Complete |
| ADC | 41 | 0-2 | P:\$52 | ADCB Conversion Complete |
| ADC | 42 | 0-2 | P:\$54 | ADC Zero Crossing or Limit Error |
| PWM | 43 | 0-2 | P:\$56 | Reload PWM |
| PWM | 44 | 0-2 | P:\$58 | PWM Fault |
| SWILP | 45 | -1 | P:\$5A | SW Interrupt Low Priority |

- Two words are allocated for each entry in the vector table. This does not allow the full address range to be referenced from the vector table, providing only 19 bits of address.
- If the VBA is set to the reset value, the first two locations of the vector table will overlay the chip reset addresses.

4.3 Program Map

The Program Memory map is shown in [Table 4-3](#).

Table 4-3 Program Memory Map¹

| Begin/End Address | Memory Allocation |
|------------------------------|--|
| P: \$FF FFFF P: \$00 8800 | RESERVED |
| P: \$00 87FF P: \$00 8000 | On-Chip RAM ² 4KB |
| P: \$00 7FFF P: \$00 2000 | RESERVED |
| P: \$00 1FFF P: \$00 0000 | Internal Program Flash 16KB Cop Reset Address = \$00 0002 Boot Location = \$00 0000 |

- All addresses are 16-bit Word addresses.
- This RAM is shared with Data space starting at address X: \$00 0000; see [Figure 4-1](#).

4.4 Data Map

Table 4-4 Data Memory Map¹

| Begin/End Address | Memory Allocation |
|----------------------------|---|
| X:\$FF FFFF X:\$FF FF00 | EOnCE 256 locations allocated |
| X:\$FF FEFF X:\$01 0000 | RESERVED |
| X:\$00 FFFF X:\$00 F000 | On-Chip Peripherals 4096 locations allocated |
| X:\$00 EFFF X:\$00 8800 | RESERVED |
| X:\$00 EFFF X:\$00 0800 | Reserved |
| X:\$00 7FFF X:\$00 0040 | RESERVED |
| X:\$00 07FF X:\$00 0000 | On-Chip Data RAM ² 4KB |

1. All addresses are 16-bit Word addresses.
2. This RAM is shared with Program space starting at P: \$00 8000; see [Figure 4-1](#).

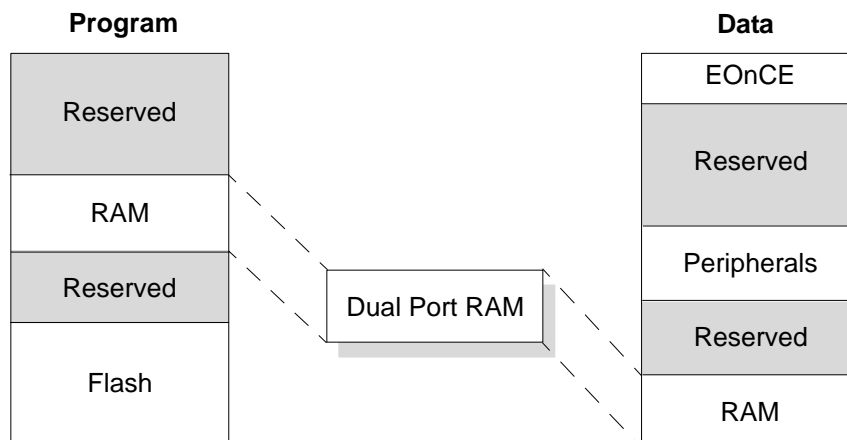


Figure 4-1 Dual Port RAM

4.5 EOnCE Memory Map

[Figure 4-5](#) lists all EOnCE registers necessary to access or control the EOnCE.

Table 4-5 EOnCE Memory Map

| Address | Register Acronym | Register Name |
|---------------------------|--------------------------|---|
| X:\$FF FFFF | OTX1 / ORX1 | Transmit Register Upper Word Receive Register Upper Word |
| X:\$FF FFFE | OTX / ORX (32 bits) | Transmit Register Receive Register |
| X:\$FF FFFD | OTXRCSR | Transmit and Receive Status and Control Register |
| X:\$FF FFFC | OCLSR | Core Lock / Unlock Status Register |
| X:\$FF FFFB - X:\$FF FFA1 | | Reserved |
| X:\$FF FFA0 | OCR | Control Register |
| X:\$FF FF9F | | Instruction Step Counter |
| X:\$FF FF9E | OSCNTR (24 bits) | Instruction Step Counter |
| X:\$FF FF9D | OSR | Status Register |
| X:\$FF FF9C | OBASE | Peripheral Base Address Register |
| X:\$FF FF9B | OTBCR | Trace Buffer Control Register |
| X:\$FF FF9A | OTBPR | Trace Buffer Pointer Register |
| X:\$FF FF99 | | Trace Buffer Register Stages |
| X:\$FF FF98 | OTB (21 - 24 bits/stage) | Trace Buffer Register Stages |
| X:\$FF FF97 | | Breakpoint Unit Control Register |
| X:\$FF FF96 | OBCR (24 bits) | Breakpoint Unit Control Register |
| X:\$FF FF95 | | Breakpoint Unit Address Register 1 |
| X:\$FF FF94 | OBAR1 (24 bits) | Breakpoint Unit Address Register 1 |
| X:\$FF FF93 | | Breakpoint Unit Address Register 2 |
| X:\$FF FF92 | OBAR2 (32 bits) | Breakpoint Unit Address Register 2 |
| X:\$FF FF91 | | Breakpoint Unit Mask Register 2 |
| X:\$FF FF90 | OBMSK (32 bits) | Breakpoint Unit Mask Register 2 |
| X:\$FF FF8F | | Reserved |
| X:\$FF FF8E | OBCNTR | EOnCE Breakpoint Unit Counter |
| X:\$FF FF8D | | Reserved |
| X:\$FF FF8C | | Reserved |
| X:\$FF FF8B | | Reserved |
| X:\$FF FF8A | OESCR | External Signal Control Register |
| X:\$FF FF89 - X:\$FF FF00 | | Reserved |

4.6 Peripheral Memory Mapped Registers

On-chip peripheral registers are part of the data memory map on the 56800E series. These locations may be accessed with the same addressing modes used for ordinary Data memory, except all peripheral registers should be read/written using word accesses only.

Table 4-6 summarizes base addresses for the set of peripherals on the 56F8014 device. Peripherals are listed in order of the base address.

The following tables list all of the peripheral registers required to control or access the peripherals.

Table 4-6 Data Memory Peripheral Base Address Map Summary

| Peripheral | Prefix | Base Address | Table Number |
|---------------------|---------|--------------|----------------------|
| Timer | TMR n | X:\$00 F000 | 4-7 |
| PWM | PWM | X:\$00 F040 | 4-8 |
| ITCN | ITCN | X:\$00 F060 | 4-9 |
| ADC | ADC | X:\$00 F080 | 4-10 |
| SCI | SCI | X:\$00 F0B0 | 4-11 |
| SPI | SPI | X:\$00 F0C0 | 4-12 |
| I ² C | I2C | X:\$00 F0D0 | 4-13 |
| COP | COP | X:\$00 F0E0 | 4-14 |
| CLK, PLL, OSC, TEST | OCCS | X:\$00 F0F0 | 4-15 |
| GPIO Port A | GPIOA | X:\$00 F100 | 4-16 |
| GPIO Port B | GPIOB | X:\$00 F110 | 4-17 |
| GPIO Port C | GPIOC | X:\$00 F120 | 4-18 |
| GPIO Port D | GPIOD | X:\$00 F130 | 4-19 |
| SIM | SIM | X:\$00 F140 | 4-20 |
| Power Supervisor | PS | X:\$00 F160 | 4-21 |
| FM | FM | X:\$00 F400 | 4-22 |

**Table 4-7 Quad Timer Registers Address Map
(TMR_BASE = \$00 F000)**

| Register Acronym | Address Offset | Register Description |
|------------------|----------------|--|
| TMR0_COMP1 | \$0 | Compare Register 1 |
| TMR0_COMP2 | \$1 | Compare Register 2 |
| TMR0_CAPT | \$2 | Capture Register |
| TMR0_LOAD | \$3 | Load Register |
| TMR0_HOLD | \$4 | Hold Register |
| TMR0_CNTR | \$5 | Counter Register |
| TMR0_CTRL | \$6 | Control Register |
| TMR0_SCTRL | \$7 | Status and Control Register |
| TMR0_CMPLD1 | \$8 | Comparator Load Register 1 |
| TMR0_CMPLD2 | \$9 | Comparator Load Register 2 |
| TMR0_CSCTRL | \$A | Comparator Status and Control Register |
| | | Reserved |
| TMR1_COMP1 | \$10 | Compare Register 1 |
| TMR1_COMP2 | \$11 | Compare Register 2 |

Table 4-7 Quad Timer Registers Address Map (Continued)
(TMR_BASE = \$00 F000)

| Register Acronym | Address Offset | Register Description |
|------------------|----------------|--|
| TMR1_CAPT | \$12 | Capture Register |
| TMR1_LOAD | \$13 | Load Register |
| TMR1_HOLD | \$14 | Hold Register |
| TMR1_CNTR | \$15 | Counter Register |
| TMR1_CTRL | \$16 | Control Register |
| TMR1_SCTRL | \$17 | Status and Control Register |
| TMR1_CMPLD1 | \$18 | Comparator Load Register 1 |
| TMR1_CMPLD2 | \$19 | Comparator Load Register 2 |
| TMR1_CSCTRL | \$1A | Comparator Status and Control Register |
| | | Reserved |
| TMR2_COMP1 | \$20 | Compare Register 1 |
| TMR2_COMP2 | \$21 | Compare Register 2 |
| TMR2_CAPT | \$22 | Capture Register |
| TMR2_LOAD | \$23 | Load Register |
| TMR2_HOLD | \$24 | Hold Register |
| TMR2_CNTR | \$25 | Counter Register |
| TMR2_CTRL | \$26 | Control Register |
| TMR2_SCTRL | \$27 | Status and Control Register |
| TMR2_CMPLD1 | \$28 | Comparator Load Register 1 |
| TMR2_CMPLD2 | \$29 | Comparator Load Register 2 |
| TMR2_CSCTRL | \$2A | Comparator Status and Control Register |
| | | Reserved |
| TMR3_COMP1 | \$30 | Compare Register 1 |
| TMR3_COMP2 | \$31 | Compare Register 2 |
| TMR3_CAPT | \$32 | Capture Register |
| TMR3_LOAD | \$33 | Load Register |
| TMR3_HOLD | \$34 | Hold Register |
| TMR3_CNTR | \$35 | Counter Register |
| TMR3_CTRL | \$36 | Control Register |
| TMR3_SCTRL | \$37 | Status and Control Register |
| TMR3_CMPLD1 | \$38 | Comparator Load Register 1 |
| TMR3_CMPLD2 | \$39 | Comparator Load Register 2 |
| TMR3_CSCTRL | \$3A | Comparator Status and Control Register |

**Table 4-8 Pulse Width Modulator Registers Address Map
(PWM_BASE = \$00 F040)**

| Register Acronym | Address Offset | Register Description |
|------------------|----------------|--------------------------------------|
| PWM_CTRL | \$0 | Control Register |
| PWM_FCTRL | \$1 | Fault Control Register |
| PWM_FLTACK | \$2 | Fault Status Acknowledge Register |
| PWM_OUT | \$3 | Output Control Register |
| PWM_CNTR | \$4 | Counter Register |
| PWM_CMOD | \$5 | Counter Modulo Register |
| PWM_VAL0 | \$6 | Value Register 0 |
| PWM_VAL1 | \$7 | Value Register 1 |
| PWM_VAL2 | \$8 | Value Register 2 |
| PWM_VAL3 | \$9 | Value Register 3 |
| PWM_VAL4 | \$A | Value Register 4 |
| PWM_VAL5 | \$B | Value Register 5 |
| PWM_DTIM0 | \$C | Dead Time Register 0 |
| PWM_DTIM1 | \$D | Dead Time Register 1 |
| PWM_DMAP1 | \$E | Disable Mapping Register 1 |
| PWM_DMAP2 | \$F | Disable Mapping Register 2 |
| PWM_CNFG | \$10 | Configure Register |
| PWM_CCTRL | \$11 | Channel Control Register |
| PWM_PORT | \$12 | Port Register |
| PWM_ICCTRL | \$13 | Internal Correction Control Register |
| PWM_SCTRL | \$14 | Source Control Register |

**Table 4-9 Interrupt Control Registers Address Map
(ITCN_BASE = \$00 F060)**

| Register Acronym | Address Offset | Register Description |
|------------------|----------------|---|
| ITCN_IPR0 | \$0 | Interrupt Priority Register 0 |
| ITCN_IPR1 | \$1 | Interrupt Priority Register 1 |
| ITCN_IPR2 | \$2 | Interrupt Priority Register 2 |
| ITCN_IPR3 | \$3 | Interrupt Priority Register 3 |
| ITCN_IPR4 | \$4 | Interrupt Priority Register 4 |
| ITCN_VBA | \$5 | Vector Base Address Register |
| ITCN_FIM0 | \$6 | Fast Interrupt Match 0 Register |
| ITCN_FIVAL0 | \$7 | Fast Interrupt Vector Address Low 0 Register |
| ITCN_FIVAHO | \$8 | Fast Interrupt Vector Address High 0 Register |

Table 4-9 Interrupt Control Registers Address Map (Continued)
(ITCN_BASE = \$00 F060)

| Register Acronym | Address Offset | Register Description |
|------------------|----------------|---|
| ITCN_FIM1 | \$9 | Fast Interrupt Match 1 Register |
| ITCN_FIVAL1 | \$A | Fast Interrupt Vector Address Low 1 Register |
| ITCN_FIVAH1 | \$B | Fast Interrupt Vector Address High 1 Register |
| ITCN_IRQP 0 | \$C | IRQ Pending Register 0 |
| ITCN_IRQP 1 | \$D | IRQ Pending Register 1 |
| ITCN_IRQP 2 | \$E | IRQ Pending Register 2 |
| | | Reserved |
| ITCN_ICTRL | \$12 | Interrupt Control Register |
| | | Reserved |

Table 4-10 Analog-to-Digital Converter Registers Address Map
(ADC_BASE = \$00 F080)

| Register Acronym | Address Offset | Register Description |
|------------------|----------------|--------------------------------|
| ADC_CTRL1 | \$0 | Control Register 1 |
| ADC_CTRL2 | \$1 | Control Register 2 |
| ADC_ZXCTRL | \$2 | Zero Crossing Control Register |
| ADC_CLIST 1 | \$3 | Channel List Register 1 |
| ADC_CLIST 2 | \$4 | Channel List Register 2 |
| ADC_SDIS | \$5 | Sample Disable Register |
| ADC_STAT | \$6 | Status Register |
| ADC_LIMSTAT | \$7 | Limit Status Register |
| ADC_ZXSTAT | \$8 | Zero Crossing Status Register |
| ADC_RSLT0 | \$9 | Result Register 0 |
| ADC_RSLT1 | \$A | Result Register 1 |
| ADC_RSLT2 | \$B | Result Register 2 |
| ADC_RSLT3 | \$C | Result Register 3 |
| ADC_RSLT4 | \$D | Result Register 4 |
| ADC_RSLT5 | \$E | Result Register 5 |
| ADC_RSLT6 | \$F | Result Register 6 |
| ADC_RSLT7 | \$10 | Result Register 7 |
| ADC_LOLIM0 | \$11 | Low Limit Register 0 |
| ADC_LOLIM1 | \$12 | Low Limit Register 1 |
| ADC_LOLIM2 | \$13 | Low Limit Register 2 |
| ADC_LOLIM3 | \$14 | Low Limit Register 3 |
| ADC_LOLIM4 | \$15 | Low Limit Register 4 |
| ADC_LOLIM5 | \$16 | Low Limit Register 5 |

**Table 4-10 Analog-to-Digital Converter Registers Address Map (Continued)
(ADC_BASE = \$00 F080)**

| Register Acronym | Address Offset | Register Description |
|------------------|----------------|----------------------------|
| ADC_LOLIM6 | \$17 | Low Limit Register 6 |
| ADC_LOLIM7 | \$18 | Low Limit Register 7 |
| ADC_HILIM0 | \$19 | High Limit Register 0 |
| ADC_HILIM1 | \$1A | High Limit Register 1 |
| ADC_HILIM2 | \$1B | High Limit Register 2 |
| ADC_HILIM3 | \$1C | High Limit Register 3 |
| ADC_HILIM4 | \$1D | High Limit Register 4 |
| ADC_HILIM5 | \$1E | High Limit Register 5 |
| ADC_HILIM6 | \$1F | High Limit Register 6 |
| ADC_HILIM7 | \$20 | High Limit Register 7 |
| ADC_OFFST0 | \$21 | Offset Register 0 |
| ADC_OFFST1 | \$22 | Offset Register 1 |
| ADC_OFFST2 | \$23 | Offset Register 2 |
| ADC_OFFST3 | \$24 | Offset Register 3 |
| ADC_OFFST4 | \$25 | Offset Register 4 |
| ADC_OFFST5 | \$26 | Offset Register 5 |
| ADC_OFFST6 | \$27 | Offset Register 6 |
| ADC_OFFST7 | \$28 | Offset Register 7 |
| ADC_PWR | \$29 | Power Control Register |
| ADC_VREF | \$2A | Voltage Reference Register |
| | | Reserved |

**Table 4-11 Serial Communication Interface Registers Address Map
(SCI_BASE = \$00 F0B0)**

| Register Acronym | Address Offset | Register Description |
|------------------|----------------|----------------------|
| SCI_RATE | \$0 | Baud Rate Register |
| SCI_CTRL1 | \$1 | Control Register 1 |
| SCI_CTRL2 | \$2 | Control Register 2 |
| SCI_STAT | \$3 | Status Register |
| SCI_DATA | \$4 | Data Register |

**Table 4-12 Serial Peripheral Interface Registers Address Map
(SPI_BASE = \$00 F0C0)**

| Register Acronym | Address Offset | Register Description |
|------------------|----------------|--------------------------------|
| SPI_SCTRL | \$0 | Status and Control Register |
| SPI_DSCTRL | \$1 | Data Size and Control Register |
| SPI_DRCV | \$2 | Data Receive Register |
| SPI_DXMIT | \$3 | Data Transmit Register |

**Table 4-13 I²C Registers Address Map
(I2C_BASE = \$00 F0D0)**

| Register Acronym | Address Offset | Register Description |
|------------------|----------------|----------------------------|
| I2C_ADDR | \$0 | Address Register |
| I2C_FDIV | \$1 | Frequency Divider Register |
| I2C_CTRL | \$2 | Control Register |
| I2C_STAT | \$3 | Status Register |
| I2C_DATA | \$4 | Data Register |
| I2C_NFILT | \$5 | Noise Filter Register |

**Table 4-14 Computer Operating Properly Registers Address Map
(COP_BASE = \$00 F0E0)**

| Register Acronym | Address Offset | Register Description |
|------------------|----------------|----------------------|
| COP_CTRL | \$0 | Control Register |
| COP_TOUT | \$1 | Time-Out Register |
| COP_CNTR | \$2 | Counter Register |

**Table 4-15 Clock Generation Module Registers Address Map
(OCCS_BASE = \$00 F0F0)**

| Register Acronym | Address Offset | Register Description |
|------------------|----------------|-----------------------------|
| OCCS_CTRL | \$0 | Control Register |
| OCCS_DIVBY | \$1 | Divide-By Register |
| OCCS_STAT | \$2 | Status Register |
| | | Reserved |
| OCCS_SHUTDN | \$4 | Shutdown Register |
| OCCS_OCTRL | \$5 | Oscillator Control Register |

**Table 4-16 GPIOA Registers Address Map
(GPIOA_BASE = \$00 F100)**

| Register Acronym | Address Offset | Register Description |
|------------------|----------------|--|
| GPIOA_PUPEN | \$0 | Pull-up Enable Register |
| GPIOA_DATA | \$1 | Data Register |
| GPIOA_DDIR | \$2 | Data Direction Register |
| GPIOA_PEREN | \$3 | Peripheral Enable Register |
| GPIOA_IASSRT | \$4 | Interrupt Assert Register |
| GPIOA_IEN | \$5 | Interrupt Enable Register |
| GPIOA_IEPOL | \$6 | Interrupt Edge Polarity Register |
| GPIOA_IPEND | \$7 | Interrupt Pending Register |
| GPIOA_IEDGE | \$8 | Interrupt Edge-Sensitive Register |
| GPIOA_PPOUTM | \$9 | Push-Pull Output Mode Control Register |
| GPIOA_RDATA | \$A | Raw Data Register |
| GPIOA_DRIVE | \$B | Drive Strength Control Register |

**Table 4-17 GPIOB Registers Address Map
(GPIOB_BASE = \$00 F110)**

| Register Acronym | Address Offset | Register Description |
|------------------|----------------|--|
| GPIOB_PUPEN | \$0 | Pull-up Enable Register |
| GPIOB_DATA | \$1 | Data Register |
| GPIOB_DDIR | \$2 | Data Direction Register |
| GPIOB_PEREN | \$3 | Peripheral Enable Register |
| GPIOB_IASSRT | \$4 | Interrupt Assert Register |
| GPIOB_IEN | \$5 | Interrupt Enable Register |
| GPIOB_IEPOL | \$6 | Interrupt Edge Polarity Register |
| GPIOB_IPEND | \$7 | Interrupt Pending Register |
| GPIOB_IEDGE | \$8 | Interrupt Edge-Sensitive Register |
| GPIOB_PPOUTM | \$9 | Push-Pull Output Mode Control Register |
| GPIOB_RDATA | \$A | Raw Data Register |
| GPIOB_DRIVE | \$B | Drive Strength Control Register |

**Table 4-18 GPIOC Registers Address Map
(GPIOC_BASE = \$00 F120)**

| Register Acronym | Address Offset | Register Description |
|------------------|----------------|--|
| GPIOC_PUPEN | \$0 | Pull-up Enable Register |
| GPIOC_DATA | \$1 | Data Register |
| GPIOC_DDIR | \$2 | Data Direction Register |
| GPIOC_PEREN | \$3 | Peripheral Enable Register |
| GPIOC_IASSRT | \$4 | Interrupt Assert Register |
| GPIOC_IEN | \$5 | Interrupt Enable Register |
| GPIOC_IEPOL | \$6 | Interrupt Edge Polarity Register |
| GPIOC_IPEND | \$7 | Interrupt Pending Register |
| GPIOC_IEDGE | \$8 | Interrupt Edge-Sensitive Register |
| GPIOC_PPOUTM | \$9 | Push-Pull Output Mode Control Register |
| GPIOC_RDATA | \$A | Raw Data Register |
| GPIOC_DRIVE | \$B | Drive Strength Control Register |

**Table 4-19 GPIOD Registers Address Map
(GPIOD_BASE = \$00 F130)**

| Register Acronym | Address Offset | Register Description |
|------------------|----------------|--|
| GPIOD_PUPEN | \$0 | Pull-up Enable Register |
| GPIOD_DATA | \$1 | Data Register |
| GPIOD_DDIR | \$2 | Data Direction Register |
| GPIOD_PEREN | \$3 | Peripheral Enable Register |
| GPIOD_IASSRT | \$4 | Interrupt Assert Register |
| GPIOD_IEN | \$5 | Interrupt Enable Register |
| GPIOD_IEPOL | \$6 | Interrupt Edge Polarity Register |
| GPIOD_IPEND | \$7 | Interrupt Pending Register |
| GPIOD_IEDGE | \$8 | Interrupt Edge-Sensitive Register |
| GPIOD_PPOUTM | \$9 | Push-Pull Output Mode Control Register |
| GPIOD_RDATA | \$A | Raw Data Register |
| GPIOD_DRIVE | \$B | Drive Strength Control Register |

**Table 4-20 System Integration Module Registers Address Map
(SIM_BASE = \$00 F140)**

| Register Acronym | Address Offset | Register Description |
|------------------|----------------|--|
| SIM_CTRL | \$0 | Control Register |
| SIM_RSTAT | \$1 | Reset Status Register |
| SIM_SWC0 | \$2 | Software Control Register 0 |
| SIM_SWC1 | \$3 | Software Control Register 1 |
| SIM_SWC2 | \$4 | Software Control Register 2 |
| SIM_SWC3 | \$5 | Software Control Register 3 |
| SIM_MSHID | \$6 | Most Significant Half JTAG ID |
| SIM_LSHID | \$7 | Least Significant Half JTAG ID |
| SIM_PWR | \$8 | Power Control Register |
| | | Reserved |
| SIM_CLKOUT | \$A | Clock Out Select Register |
| SIM_GPS | \$B | GPIO Peripheral Select Register |
| SIM_PCE | \$C | Peripheral Clock Enable Register |
| SIM_IOSAHI | \$D | I/O Short Address Location High Register |
| SIM_IOSALO | \$E | I/O Short Address Location Low Register |

**Table 4-21 Power Supervisor Registers Address Map
(PS_BASE = \$00 F160)**

| Register Acronym | Address Offset | Register Description |
|------------------|----------------|----------------------|
| PS_CTRL | \$0 | Control Register |
| PS_STAT | \$1 | Status Register |

**Table 4-22 Flash Module Registers Address Map
(FM_BASE = \$00 F400)**

| Register Acronym | Address Offset | Register Description |
|------------------|----------------|-----------------------------|
| FM_CLKDIV | \$0 | Clock Divider Register |
| FM_CNFG | \$1 | Configuration Register |
| | \$2 | Reserved |
| FM_SECHI | \$3 | Security High Half Register |
| FM_SECLO | \$4 | Security Low Half Register |
| | \$5 - \$9 | Reserved |
| FM_PROT | \$10 | Protection Register |
| | \$11 - \$12 | Reserved |

Table 4-22 Flash Module Registers Address Map (Continued)
(FM_BASE = \$00 F400)

| Register Acronym | Address Offset | Register Description |
|------------------|----------------|-------------------------------|
| FM_USTAT | \$13 | User Status Register |
| FM_CMD | \$14 | Command Register |
| | \$15 | Reserved |
| | \$16 | Reserved |
| | \$17 | Reserved |
| FM_DATA | \$18 | Data Buffer Register |
| | \$19 | Reserved |
| | \$1A | Reserved |
| FM_OPT1 | \$1B | Optional Data 1 Register |
| | | Reserved |
| FM_TSTSIG | \$1D | Test Array Signature Register |

Part 5 Interrupt Controller (ITCN)

5.1 Introduction

The Interrupt Controller (ITCN) module is used to arbitrate between various interrupt requests (IRQs), to signal to the 56800E core when an interrupt of sufficient priority exists, and to what address to jump in order to service this interrupt.

5.2 Features

The ITCN module design includes these distinctive features:

- Programmable priority levels for each IRQ
- Two programmable Fast Interrupts
- Notification to SIM module to restart clocks out of Wait and Stop modes
- Ability to drive initial address on the address bus after reset

For further information, see [Table 4-2](#), Interrupt Vector Table Contents.

5.3 Functional Description

The Interrupt Controller contains registers that allow each of the 46 interrupt sources to be set to one of three priority levels (excluding certain interrupts that are of fixed priority). Next, all of the interrupt requests of a given level are priority encoded to determine the lowest numerical value of the active interrupt requests for that level. Within a given priority level, number 0 is the highest priority and number 45 is the lowest.

During wait and stop modes, the system clocks and the 56800E core are turned off. The ITCN can wake the core and restart system clocks by signaling a pending IRQ to the System Integration Module (SIM) to

restart the clocks and service the IRQ. An IRQ can only wake the core if the IRQ is enabled prior to entering wait or stop mode.

5.3.1 Normal Interrupt Handling

Once the INTC has determined that an interrupt is to be serviced and which interrupt has the highest priority, an interrupt vector address is generated. Normal interrupt handling concatenates the Vector Base Address (VBA) and the vector number to determine the vector address, generating an offset into the vector table for each interrupt.

5.3.2 Interrupt Nesting

Interrupt exceptions may be nested to allow an IRQ of higher priority than the current exception to be serviced. The following table defines the nesting requirements for each priority level.

Table 5-1 Interrupt Mask Bit Definition

| SR[9] | SR[8] | Exceptions Permitted | Exceptions Masked |
|-------|-------|-----------------------|--------------------|
| 0 | 0 | Priorities 0, 1, 2, 3 | None |
| 0 | 1 | Priorities 1, 2, 3 | Priority 0 |
| 1 | 0 | Priorities 2, 3 | Priorities 0, 1 |
| 1 | 1 | Priority 3 | Priorities 0, 1, 2 |

5.3.3 Fast Interrupt Handling

Fast interrupts are described in the **DSP56800E Reference Manual**. The interrupt controller recognizes Fast Interrupts before the core does.

A Fast Interrupt is defined (to the ITCN) by:

1. Setting the priority of the interrupt as level 2, with the appropriate field in the IPR registers
2. Setting the FIM n register to the appropriate vector number
3. Setting the FIVAL n and FIVAH n registers with the address of the code for the Fast Interrupt

When an interrupt occurs, its vector number is compared with the FIM0 and FIM1 register values. If a match occurs, and it is a level 2 interrupt, the ITCN handles it as a Fast Interrupt. The ITCN takes the vector address from the appropriate FIVAL n and FIVAH n registers, instead of generating an address that is an offset from the VBA.

The core then fetches the instruction from the indicated vector address and if it is not a JSR, the core starts its Fast Interrupt handling.

5.4 Block Diagram

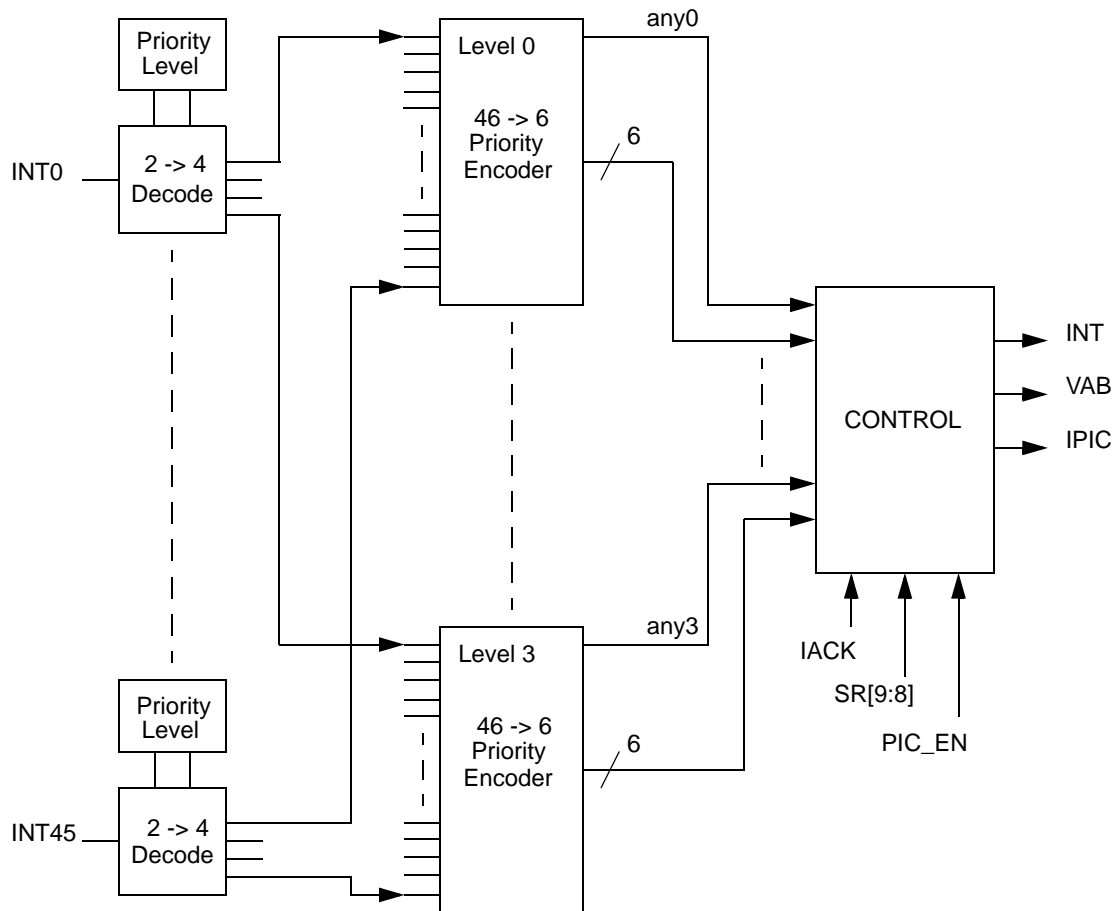


Figure 5-1 Interrupt Controller Block Diagram

5.5 Register Descriptions

A register address is the sum of a base address and an address offset. The base address is defined at the system level and the address offset is defined at the module level. The ITCN module has 16 registers.

Table 5-2 ITCN Register Summary
(ITCN_BASE = \$00 F060)

| Register Acronym | Base Address + | Register Name | Section Location |
|------------------|----------------|-------------------------------|-----------------------|
| IPR0 | \$0 | Interrupt Priority Register 0 | 5.5.1 |
| IPR1 | \$1 | Interrupt Priority Register 1 | 5.5.2 |
| IPR2 | \$2 | Interrupt Priority Register 2 | 5.5.3 |

Table 5-2 ITCN Register Summary (Continued)
(ITCN_BASE = \$00 F060)

| Register Acronym | Base Address + | Register Name | Section Location |
|-------------------------|-----------------------|---|-------------------------|
| IPR3 | \$3 | Interrupt Priority Register 3 | 5.5.4 |
| IPR4 | \$4 | Interrupt Priority Register 4 | 5.5.5 |
| VBA | \$5 | Vector Base Address Register | 5.5.6 |
| FIM0 | \$6 | Fast Interrupt Match 0 Register | 5.5.7 |
| FIVAL0 | \$7 | Fast Interrupt 0 Vector Address Low Register | 5.5.8 |
| FIVAH0 | \$8 | Fast Interrupt 0 Vector Address High Register | 5.5.9 |
| FIM1 | \$9 | Fast Interrupt Match 1 Register | 5.5.10 |
| FIVAL1 | \$A | Fast Interrupt 1 Vector Address Low Register | 5.5.11 |
| FIVAH1 | \$B | Fast Interrupt 1 Vector Address High Register | 5.5.12 |
| IRQP0 | \$C | IRQ Pending Register 0 | 5.5.13 |
| IRQP1 | \$D | IRQ Pending Register 1 | 5.5.14 |
| IRQP2 | \$E | IRQ Pending Register 2 | 5.5.15 |
| | | Reserved | |
| ICTRL | \$12 | Interrupt Control Register | 5.5.16 |
| | | Reserved | |

| Add. Offset | Register Name | | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 | |
|-------------|---------------|---|-------------------------------------|------|---------------------|----------------|-----------|----|--------------|---|--------------|---------|--------------------------------------|--------------------------------------|---------------|---|-------------|---|--|
| \$0 | IPR0 | R | LVI IPL | | 0 | 0 | 0 | 0 | RX_REG IPL | | TX_REG IPL | | TRBUF IPL | | BKPT_U IPL | | STPCNT IPL | | |
| | | W | | | | | | | | | | | | | | | | | |
| \$1 | IPR1 | R | GPIOB IPL | | GPIOC IPL | | GPIOD IPL | | 0 | 0 | FM_CBE IPL | | FM_CC IPL | | FM_ERR IPL | | PLL IPL | | |
| | | W | | | | | | | | | | | | | | | | | |
| \$2 | IPR2 | R | SCI_RCV IPL | | SCI_RERR IPL | | 0 | 0 | SCI_TIDL IPL | | SCI_XMIT IPL | | SPL_XMIT IPL | | SPL_RCV IPL | | GPIOA IPL | | |
| | | W | | | | | | | | | | | | | | | | | |
| \$3 | IPR3 | R | ADCA_CC IPL | | TMR_3 IPL | | TMR_2 IPL | | TMR_1 IPL | | TMR_0 IPL | | I2C_ADDR IPL | | 0 | 0 | 0 | 0 | |
| | | W | | | | | | | | | | | | | | | | | |
| \$4 | IPR4 | R | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | PWM_F IPL | | PWM_RL IPL | | ADC_ZC_LE IPL | | ADCB_CC IPL | | |
| | | W | | | | | | | | | | | | | | | | | |
| \$5 | VBA | R | 0 | 0 | VECTOR_BASE_ADDRESS | | | | | | | | | | | | | | |
| | | W | | | | | | | | | | | | | | | | | |
| \$6 | FIM0 | R | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | FAST INTERRUPT 0 | | | | | | |
| | | W | | | | | | | | | | | | | | | | | |
| \$7 | FIVAL0 | R | FAST INTERRUPT 0 VECTOR ADDRESS LOW | | | | | | | | | | | | | | | | |
| | | W | | | | | | | | | | | | | | | | | |
| \$8 | FIVAH0 | R | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | FAST INTERRUPT 0 VECTOR ADDRESS HIGH | | | | | |
| | | W | | | | | | | | | | | | | | | | | |
| \$9 | FIM1 | R | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | FAST INTERRUPT 1 | | | | | | |
| | | W | | | | | | | | | | | | | | | | | |
| \$A | FIVAL1 | R | FAST INTERRUPT 1 VECTOR ADDRESS LOW | | | | | | | | | | | | | | | | |
| | | W | | | | | | | | | | | | | | | | | |
| \$B | FIVAH1 | R | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | FAST INTERRUPT 1 VECTOR ADDRESS HIGH | | | | | | |
| | | W | | | | | | | | | | | | | | | | | |
| \$C | IRQP0 | R | PENDING[16:2] | | | | | | | | | | | | | | | 1 | |
| | | W | | | | | | | | | | | | | | | | | |
| \$D | IRQP1 | R | PENDING[32:17] | | | | | | | | | | | | | | | | |
| | | W | | | | | | | | | | | | | | | | | |
| \$E | IRQP2 | R | 1 | 1 | 1 | PENDING[45:33] | | | | | | | | | | | | | |
| | | W | | | | | | | | | | | | | | | | | |
| Reserved | | | | | | | | | | | | | | | | | | | |
| \$12 | ICTRL | R | INT | IPIC | | VAB | | | | | | INT_DIS | | 1 | 1 | 1 | 0 | 0 | |
| | | W | | | | | | | | | | | | | | | | | |
| Reserved | | | | | | | | | | | | | | | | | | | |


 = Reserved

Figure 5-2 ITCN Register Map Summary

5.5.1 Interrupt Priority Register 0 (IPR0)

| Base + \$0 | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|------------|---------|----|----|----|----|----|------------|---|------------|---|-----------|---|------------|---|------------|---|
| Read | LVI IPL | | 0 | 0 | 0 | 0 | RX_REG IPL | | TX_REG IPL | | TRBUF IPL | | BKPT_U IPL | | STPCNT IPL | |
| Write | | | | | | | | | | | | | | | | |
| RESET | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

Figure 5-3 Interrupt Priority Register 0 (IPR0)

5.5.1.1 LVI IPL—Bits 15–14

This field is used to set the interrupt priority levels for a peripheral IRQ. This IRQ is limited to priorities 0 through 2 and is disabled by default.

- 00 = IRQ disabled (default)
- 01 = IRQ is priority level 0
- 10 = IRQ is priority level 1
- 11 = IRQ is priority level 2

5.5.1.2 Reserved—Bits 13–10

This bit field is reserved or not implemented. It is read as 0 and cannot be modified by writing.

5.5.1.3 EOnCE Receive Register Full Interrupt Priority Level (RX_REG IPL)— Bits 9–8

This field is used to set the interrupt priority level for IRQs. This IRQ is limited to priorities 1 through 3. It is disabled by default.

- 00 = IRQ disabled (default)
- 01 = IRQ is priority level 1
- 10 = IRQ is priority level 2
- 11 = IRQ is priority level 3

5.5.1.4 EOnCE Transmit Register Empty Interrupt Priority Level (TX_REG IPL)— Bits 7–6

This field is used to set the interrupt priority level for IRQs. This IRQ is limited to priorities 1 through 3. It is disabled by default.

- 00 = IRQ disabled (default)
- 01 = IRQ is priority level 1
- 10 = IRQ is priority level 2
- 11 = IRQ is priority level 3

5.5.1.5 EOnCE Trace Buffer Interrupt Priority Level (TRBUF IPL)— Bits 5–4

This field is used to set the interrupt priority level for IRQs. This IRQ is limited to priorities 1 through 3. It is disabled by default.

- 00 = IRQ disabled (default)
- 01 = IRQ is priority level 1
- 10 = IRQ is priority level 2
- 11 = IRQ is priority level 3

5.5.1.6 EOnCE Breakpoint Unit Interrupt Priority Level (BKPT_U IPL)— Bits 3–2

This field is used to set the interrupt priority level for IRQs. This IRQ is limited to priorities 1 through 3. It is disabled by default.

- 00 = IRQ disabled (default)
- 01 = IRQ is priority level 1
- 10 = IRQ is priority level 2
- 11 = IRQ is priority level 3

5.5.1.7 EOnCE Step Counter Interrupt Priority Level (STPCNT IPL)— Bits 1–0

This field is used to set the interrupt priority level for IRQs. This IRQ is limited to priorities 1 through 3. It is disabled by default.

- 00 = IRQ disabled (default)
- 01 = IRQ is priority level 1
- 10 = IRQ is priority level 2
- 11 = IRQ is priority level 3

5.5.2 Interrupt Priority Register 1 (IPR1)

| Base + \$1 | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|------------|-----------|----|-----------|----|-----------|----|---|---|------------|---|-----------|---|------------|---|---------|---|
| Read | GPIOB IPL | | GPIOC IPL | | GPIOD IPL | | 0 | 0 | FM_CBE IPL | | FM_CC IPL | | FM_ERR IPL | | PLL IPL | |
| Write | | | | | | | | | | | | | | | | |
| RESET | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

Figure 5-4 Interrupt Priority Register 1 (IPR1)

5.5.2.1 GPIOB Interrupt Priority Level (GPIOB IPL)—Bits 15–14

This field is used to set the interrupt priority level for IRQs. This IRQ is limited to priorities 0 through 2. It is disabled by default.

- 00 = IRQ disabled (default)
- 01 = IRQ is priority level 0
- 10 = IRQ is priority level 1
- 11 = IRQ is priority level 2

5.5.2.2 GPIOC Interrupt Priority Level (GPIOC IPL)—Bits 13–12

This field is used to set the interrupt priority level for IRQs. This IRQ is limited to priorities 0 through 2. It is disabled by default.

- 00 = IRQ disabled (default)
- 01 = IRQ is priority level 0
- 10 = IRQ is priority level 1
- 11 = IRQ is priority level 2

5.5.2.3 GPIOD Interrupt Priority Level (GPIOD IPL)—Bits 11–10

This field is used to set the interrupt priority level for IRQs. This IRQ is limited to priorities 0 through 2. It is disabled by default.

- 00 = IRQ disabled (default)
- 01 = IRQ is priority level 0
- 10 = IRQ is priority level 1
- 11 = IRQ is priority level 2

5.5.2.4 Reserved—Bits 9–8

This bit field is reserved or not implemented. It is read as 0 and cannot be modified by writing.

5.5.2.5 FM Command, Data, Address Buffers Empty Interrupt Priority Level (FM_CBE IPL)—Bits 7–6

This field is used to set the interrupt priority level for IRQs. This IRQ is limited to priorities 0 through 2. It is disabled by default.

- 00 = IRQ disabled (default)
- 01 = IRQ is priority level 0
- 10 = IRQ is priority level 1
- 11 = IRQ is priority level 2

5.5.2.6 FM Command Complete Priority Level (FM_CC IPL)—Bits 5–4

This field is used to set the interrupt priority level for IRQs. This IRQ is limited to priorities 0 through 2. It is disabled by default.

- 00 = IRQ disabled (default)
- 01 = IRQ is priority level 0
- 10 = IRQ is priority level 1
- 11 = IRQ is priority level 2

5.5.2.7 FM Error Interrupt Priority Level (FM_ERR IPL)—Bits 3–2

This field is used to set the interrupt priority level for IRQs. This IRQ is limited to priorities 0 through 2. It is disabled by default.

- 00 = IRQ disabled (default)
- 01 = IRQ is priority level 0
- 10 = IRQ is priority level 1
- 11 = IRQ is priority level 2

5.5.2.8 PLL Loss of Reference or Change in Lock Status Interrupt Priority Level (PLL IPL)—Bits 1–0

This field is used to set the interrupt priority level for IRQs. This IRQ is limited to priorities 0 through 2. It is disabled by default.

- 00 = IRQ disabled (default)
- 01 = IRQ is priority level 0
- 10 = IRQ is priority level 1
- 11 = IRQ is priority level 2

5.5.3 Interrupt Priority Register 2 (IPR2)

| Base + \$2 | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|------------|-------------|----|--------------|----|----|----|--------------|---|--------------|---|--------------|---|-------------|---|-----------|---|
| Read | SCI_RCV IPL | | SCI_RERR IPL | | 0 | 0 | SCI_TIDL IPL | | SCI_XMIT IPL | | SPI_XMIT IPL | | SPI_RCV IPL | | GPIOA IPL | |
| Write | | | | | | | | | | | | | | | | |
| RESET | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

Figure 5-5 Interrupt Priority Register 2 (IPR2)

5.5.3.1 SCI Receiver Full Interrupt Priority Level (SCI_RCV IPL)—Bits 15–14

This field is used to set the interrupt priority level for IRQs. This IRQ is limited to priorities 0 through 2. It is disabled by default.

- 00 = IRQ disabled (default)
- 01 = IRQ is priority level 0
- 10 = IRQ is priority level 1
- 11 = IRQ is priority level 2

5.5.3.2 SCI Receiver Error Interrupt Priority Level (SCI_RERR IPL)—Bits 13–12

This field is used to set the interrupt priority level for IRQs. This IRQ is limited to priorities 0 through 2. It is disabled by default.

- 00 = IRQ disabled (default)
- 01 = IRQ is priority level 0
- 10 = IRQ is priority level 1
- 11 = IRQ is priority level 2

5.5.3.3 Reserved—Bits 11–10

This bit field is reserved or not implemented. It is read as 0 and cannot be modified by writing.

5.5.3.4 SCI Transmitter Idle Interrupt Priority Level (SCI_TIDL IPL)— Bits 9–8

This field is used to set the interrupt priority level for IRQs. This IRQ is limited to priorities 0 through 2. It is disabled by default.

- 00 = IRQ disabled (default)
- 01 = IRQ is priority level 0
- 10 = IRQ is priority level 1
- 11 = IRQ is priority level 2

5.5.3.5 SCI Transmitter Empty Interrupt Priority Level (SCI_XMIT IPL)— Bits 7–6

This field is used to set the interrupt priority level for IRQs. This IRQ is limited to priorities 0 through 2. It is disabled by default.

- 00 = IRQ disabled (default)
- 01 = IRQ is priority level 0
- 10 = IRQ is priority level 1
- 11 = IRQ is priority level 2

5.5.3.6 SPI Transmitter Empty Interrupt Priority Level (SPI_XMIT IPL)— Bits 5–4

This field is used to set the interrupt priority level for IRQs. This IRQ is limited to priorities 0 through 2. It is disabled by default.

- 00 = IRQ disabled (default)
- 01 = IRQ is priority level 0
- 10 = IRQ is priority level 1
- 11 = IRQ is priority level 2

5.5.3.7 SPI Receiver Full Interrupt Priority Level (SPI_RCV IPL)— Bits 3–2

This field is used to set the interrupt priority level for IRQs. This IRQ is limited to priorities 0 through 2. It is disabled by default.

- 00 = IRQ disabled (default)
- 01 = IRQ is priority level 0
- 10 = IRQ is priority level 1
- 11 = IRQ is priority level 2

5.5.3.8 GPIOA Interrupt Priority Level (GPIOA IPL)—Bits 1–0

This field is used to set the interrupt priority level for IRQs. This IRQ is limited to priorities 0 through 2. It is disabled by default.

- 00 = IRQ disabled (default)
- 01 = IRQ is priority level 0
- 10 = IRQ is priority level 1
- 11 = IRQ is priority level 2

5.5.4 Interrupt Priority Register 3 (IPR3)

| Base + \$3 | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|------------|-------------|----|-----------|----|-----------|----|-----------|---|-----------|---|--------------|---|---|---|---|---|
| Read | ADCA_CC IPL | | TMR_3 IPL | | TMR_2 IPL | | TMR_1 IPL | | TMR_0 IPL | | I2C_ADDR IPL | | 0 | 0 | 0 | 0 |
| Write | | | | | | | | | | | | | | | | |
| RESET | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

Figure 5-6 Interrupt Priority Register 3 (IPR3)

5.5.4.1 ADCA Conversion Complete Interrupt Priority Level (ADCA_CC IPL)—Bits 15–14

This field is used to set the interrupt priority level for IRQs. This IRQ is limited to priorities 0 through 2. They are disabled by default.

- 00 = IRQ disabled (default)
- 01 = IRQ is priority level 0
- 10 = IRQ is priority level 1
- 11 = IRQ is priority level 2

5.5.4.2 Timer Channel 3 Interrupt Priority Level (TMR_3 IPL)—Bits 13–12

This field is used to set the interrupt priority level for IRQs. This IRQ is limited to priorities 0 through 2. They are disabled by default.

- 00 = IRQ disabled (default)
- 01 = IRQ is priority level 0
- 10 = IRQ is priority level 1
- 11 = IRQ is priority level 2

5.5.4.3 Timer Channel 2 Interrupt Priority Level (TMR_2 IPL)—Bits 11–10

This field is used to set the interrupt priority level for IRQs. This IRQ is limited to priorities 0 through 2. They are disabled by default.

- 00 = IRQ disabled (default)
- 01 = IRQ is priority level 0
- 10 = IRQ is priority level 1
- 11 = IRQ is priority level 2

5.5.4.4 Timer Channel 1 Interrupt Priority Level (TMR_1 IPL)—Bits 9–8

This field is used to set the interrupt priority level for IRQs. This IRQ is limited to priorities 0 through 2. They are disabled by default.

- 00 = IRQ disabled (default)
- 01 = IRQ is priority level 0
- 10 = IRQ is priority level 1
- 11 = IRQ is priority level 2

5.5.4.5 Timer Channel 0 Interrupt Priority Level (TMR_0 IPL)—Bits 7–6

This field is used to set the interrupt priority level for IRQs. This IRQ is limited to priorities 0 through 2. They are disabled by default.

- 00 = IRQ disabled (default)
- 01 = IRQ is priority level 0
- 10 = IRQ is priority level 1
- 11 = IRQ is priority level 2

5.5.4.6 I²C Address Detect Interrupt Priority Level (I2C_ADDR IPL)—Bits 5–4

This field is used to set the interrupt priority level for IRQs. This IRQ is limited to priorities 0 through 2. They are disabled by default.

- 00 = IRQ disabled (default)
- 01 = IRQ is priority level 0
- 10 = IRQ is priority level 1
- 11 = IRQ is priority level 2

5.5.4.7 Reserved—Bits 3–0

This bit field is reserved or not implemented. It is read as 0 and cannot be modified by writing.

5.5.5 Interrupt Priority Register 4 (IPR4)

| Base + \$4 | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|------------|----|----|----|----|----|----|---|---|-----------|---|------------|---|---------------|---|-------------|---|
| Read | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | PWM_F IPL | | PWM_RL IPL | | ADC_ZC_LE IPL | | ADCB_CC IPL | |
| Write | | | | | | | | | | | | | | | | |
| RESET | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

Figure 5-7 Interrupt Priority Register 4 (IPR4)

5.5.5.1 Reserved—Bits 15–8

This bit field is reserved or not implemented. It is read as 0 and cannot be modified by writing.

5.5.5.2 PWM Fault Interrupt Priority Level (PWM_F IPL)— Bits 7–6

This field is used to set the interrupt priority level for IRQs. This IRQ is limited to priorities 0 through 2. They are disabled by default.

- 00 = IRQ disabled (default)
- 01 = IRQ is priority level 0
- 10 = IRQ is priority level 1
- 11 = IRQ is priority level 2

5.5.5.3 Reload PWM Interrupt Priority Level (PWM_RL IPL)— Bits 5–4

This field is used to set the interrupt priority level for IRQs. This IRQ is limited to priorities 0 through 2. They are disabled by default.

- 00 = IRQ disabled (default)
- 01 = IRQ is priority level 0
- 10 = IRQ is priority level 1
- 11 = IRQ is priority level 2

5.5.5.4 ADC Zero Crossing or Limit Error Interrupt Priority Level (ADC_ZC_LE IPL)— Bits 3–2

This field is used to set the interrupt priority level for IRQs. This IRQ is limited to priorities 0 through 2. They are disabled by default.

- 00 = IRQ disabled (default)
- 01 = IRQ is priority level 0
- 10 = IRQ is priority level 1
- 11 = IRQ is priority level 2

5.5.5.5 ADCB Conversion Complete Interrupt Priority Level (ADCB_CC IPL)—Bits 1–0

This field is used to set the interrupt priority level for IRQs. This IRQ is limited to priorities 0 through 2. They are disabled by default.

- 00 = IRQ disabled (default)
- 01 = IRQ is priority level 0
- 10 = IRQ is priority level 1
- 11 = IRQ is priority level 2

5.5.6 Vector Base Address Register (VBA)

| Base + \$5 | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------------------|----|----|---------------------|----|----|----|---|---|---|---|---|---|---|---|---|---|
| Read | 0 | 0 | VECTOR_BASE_ADDRESS | | | | | | | | | | | | | |
| Write | | | | | | | | | | | | | | | | |
| RESET ¹ | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

1. The 56F8014 resets to a value of 0x0000. This corresponds to reset addresses of 0x00 0000.

Figure 5-8 Vector Base Address Register (VBA)

5.5.6.1 Reserved—Bits15—14

This bit field is reserved or not implemented. It is read as 0 and cannot be modified by writing.

5.5.6.2 Vector Address Bus (VAB)—Bits 13—0

The value in this register is used as the upper 14 bits of the interrupt vector VAB[20:0]. The lower 7 bits are determined based on the highest priority interrupt and are then appended onto VBA before presenting the full VAB to the Core.

5.5.7 Fast Interrupt Match 0 Register (FIM0)

| Base + \$6 | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|------------|----|----|----|----|----|----|---|---|---|---|------------------|---|---|---|---|---|
| Read | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | FAST INTERRUPT 0 | | | | | |
| Write | | | | | | | | | | | | | | | | |
| RESET | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

Figure 5-9 Fast Interrupt Match 0 Register (FIM0)

5.5.7.1 Reserved—Bits 15–6

This bit field is reserved or not implemented. It is read as 0 and cannot be modified by writing.

5.5.7.2 Fast Interrupt 0 Vector Number (FAST INTERRUPT 0)—Bits 5–0

These values determine which IRQ will be Fast Interrupt 0. Fast Interrupts vector directly to a service routine based on values in the Fast Interrupt Vector Address registers without having to go to a jump table first. IRQs used as Fast Interrupts *must* be set to priority level 2. Unexpected results will occur if a Fast Interrupt vector is set to any other priority. A Fast Interrupt automatically becomes the highest-priority level 2 interrupt regardless of its location in the interrupt table prior to being declared as Fast Interrupt. Fast Interrupt 0 has priority over fast Interrupt 1. To determine the vector number of each IRQ, refer to the vector table.

5.5.8 Fast Interrupt 0 Vector Address Low Register (FIVAL0)

| Base + \$7 | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|------------|-------------------------------------|----|----|----|----|----|---|---|---|---|---|---|---|---|---|---|
| Read | FAST INTERRUPT 0 VECTOR ADDRESS LOW | | | | | | | | | | | | | | | |
| Write | FAST INTERRUPT 0 VECTOR ADDRESS LOW | | | | | | | | | | | | | | | |
| RESET | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

Figure 5-10 Fast Interrupt 0 Vector Address Low Register (FIVAL0)

5.5.8.1 Fast Interrupt 0 Vector Address Low (FIVAL0)—Bits 15—0

The lower 16 bits of the vector address used for Fast Interrupt 0. This register is combined with FIVAH0 to form the 21-bit vector address for Fast Interrupt 0 defined in the FIM0 register.

5.5.9 Fast Interrupt 0 Vector Address High Register (FIVAH0)

| Base + \$8 | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|------------|----|----|----|----|----|----|---|---|---|---|---|--------------------------------------|---|---|---|---|
| Read | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | FAST INTERRUPT 0 VECTOR ADDRESS HIGH | | | | |
| Write | | | | | | | | | | | | FAST INTERRUPT 0 VECTOR ADDRESS HIGH | | | | |
| RESET | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

Figure 5-11 Fast Interrupt 0 Vector Address High Register (FIVAH0)

5.5.9.1 Reserved—Bits 15—5

This bit field is reserved or not implemented. It is read as 0 and cannot be modified by writing.

5.5.9.2 Fast Interrupt 0 Vector Address High (FIVAH0)—Bits 4—0

The upper five bits of the vector address used for Fast Interrupt 0. This register is combined with FIVAL0 to form the 21-bit vector address for Fast Interrupt 0 defined in the FIM0 register.

5.5.10 Fast Interrupt 1 Match Register (FIM1)

| Base + \$9 | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|------------|----|----|----|----|----|----|---|---|---|---|------------------|---|---|---|---|---|
| Read | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | FAST INTERRUPT 1 | | | | | |
| Write | | | | | | | | | | | FAST INTERRUPT 1 | | | | | |
| RESET | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

Figure 5-12 Fast Interrupt 1 Match Register (FIM1)

5.5.10.1 Reserved—Bits 15—6

This bit field is reserved or not implemented. It is read as 0 and cannot be modified by writing.

5.5.10.2 Fast Interrupt 1 Vector Number (FAST INTERRUPT 1)—Bits 5—0

These values determine which IRQ will be Fast Interrupt 1. Fast Interrupts vector directly to a service routine based on values in the Fast Interrupt Vector Address registers without having to go to a jump table first. IRQs used as Fast Interrupts *must* be set to priority level 2. Unexpected results will occur if a Fast

Interrupt vector is set to any other priority. A Fast Interrupt automatically becomes the highest-priority level 2 interrupt regardless of its location in the interrupt table prior to being declared as Fast Interrupt. Fast Interrupt 0 has priority over Fast Interrupt 1. To determine the vector number of each IRQ, refer to the vector table.

5.5.11 Fast Interrupt 1 Vector Address Low Register (FIVAL1)

| Base + \$A | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|------------|-------------------------------------|----|----|----|----|----|---|---|---|---|---|---|---|---|---|---|
| Read | FAST INTERRUPT 1 VECTOR ADDRESS LOW | | | | | | | | | | | | | | | |
| Write | | | | | | | | | | | | | | | | |
| RESET | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

Figure 5-13 Fast Interrupt 1 Vector Address Low Register (FIVAL1)

5.5.11.1 Fast Interrupt 1 Vector Address Low (FIVAL1)—Bits 15–0

The lower 16 bits of the vector address used for Fast Interrupt 1. This register is combined with FIVAH1 to form the 21-bit vector address for Fast Interrupt 1 defined in the FIM1 register.

5.5.12 Fast Interrupt 1 Vector Address High Register (FIVAH1)

| Base + \$B | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|------------|----|----|----|----|----|----|---|---|---|---|---|--------------------------------------|---|---|---|---|
| Read | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | FAST INTERRUPT 1 VECTOR ADDRESS HIGH | | | | |
| Write | | | | | | | | | | | | | | | | |
| RESET | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

Figure 5-14 Fast Interrupt 1 Vector Address High Register (FIVAH1)

5.5.12.1 Reserved—Bits 15–5

This bit field is reserved or not implemented. It is read as 0 and cannot be modified by writing.

5.5.12.2 Fast Interrupt 1 Vector Address High (FIVAH1)—Bits 4–0

The upper five bits of the vector address are used for Fast Interrupt 1. This register is combined with FIVAL1 to form the 21-bit vector address for Fast Interrupt 1 defined in the FIM1 register.

5.5.13 IRQ Pending Register 0 (IRQP0)

| Base + \$C | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|------------|---------------|----|----|----|----|----|---|---|---|---|---|---|---|---|---|---|
| Read | PENDING[16:2] | | | | | | | | | | | | | | | 1 |
| Write | | | | | | | | | | | | | | | | |
| RESET | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |

Figure 5-15 IRQ Pending Register 0 (IRQP0)

5.5.13.1 IRQ Pending (PENDING)—Bits 15–1

This register combines with IRQP1 and IRQP2 to represent the pending IRQs for interrupt vector numbers 2 through 45.

- 0 = IRQ pending for this vector number
- 1 = No IRQ pending for this vector number

5.5.13.2 Reserved—Bit 0

This bit is reserved or not implemented. It is read as 1 and cannot be modified by writing.

5.5.14 IRQ Pending Register 1 (IRQP1)

| Base + \$D | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|------------|----------------|----|----|----|----|----|---|---|---|---|---|---|---|---|---|---|
| Read | PENDING[32:17] | | | | | | | | | | | | | | | |
| Write | | | | | | | | | | | | | | | | |
| RESET | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |

Figure 5-16 IRQ Pending Register 1 (IRQP1)

5.5.14.1 IRQ Pending (PENDING)—Bits 32–17

This register combines with IRQP0 and IRQP2 to represent the pending IRQs for interrupt vector numbers 2 through 45.

- 0 = IRQ pending for this vector number
- 1 = No IRQ pending for this vector number

5.5.15 IRQ Pending Register 2 (IRQP2)

| Base + \$E | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|------------|----|----|----|----------------|----|----|---|---|---|---|---|---|---|---|---|---|
| Read | 1 | 1 | 1 | PENDING[45:33] | | | | | | | | | | | | |
| Write | | | | | | | | | | | | | | | | |
| RESET | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |

Figure 5-17 IRQ Pending Register 2 (IRQP2)

5.5.15.1 IRQ Pending (PENDING)—Bits 45–33

This register combines with IRQP0 and IRQP1 to represent the pending IRQs for interrupt vector numbers 2 through 45.

- 0 = IRQ pending for this vector number
- 1 = No IRQ pending for this vector number

5.5.16 Interrupt Control Register (ICTRL)

| \$Base + \$12 | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 | |
|---------------|-----|------|----|-----|----|----|---|---|---|---|----------|---|---|---|---|---|---|
| Read | INT | IPIC | | VAB | | | | | | | INT_ DIS | 1 | 1 | 1 | 0 | 0 | |
| Write | | | | | | | | | | | | | | | | | |
| RESET | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 1 | 1 | 1 | 0 | 0 |

Figure 5-18 Interrupt Control Register (ICTRL)

5.5.16.1 Interrupt (INT)—Bit 15

This *read-only* bit reflects the state of the interrupt to the 56800E core.

- 0 = No interrupt is being sent to the 56800E core
- 1 = An interrupt is being sent to the 56800E core

5.5.16.2 Interrupt Priority Level (IPIC)—Bits 14–13

These *read-only* bits reflect the state of the new interrupt priority level bits being presented to the 56800E core. These bits indicate the priority level needed for a new IRQ to interrupt the current interrupt being sent to the 56800E core. This field is only updated when the 56800E core jumps to a new interrupt service routine.

Note: Nested interrupts may cause this field to be updated before the original interrupt service routine can read it.

- 00 = Required nested exception priority levels are 0, 1, 2, or 3
- 01 = Required nested exception priority levels are 1, 2, or 3
- 10 = Required nested exception priority levels are 2 or 3
- 11 = Required nested exception priority level is 3

Table 5-3 Interrupt Priority Encoding

| IPIC_VALUE[1:0] | Current Interrupt Priority Level | Required Nested Exception Priority |
|-----------------|----------------------------------|------------------------------------|
| 00 | No interrupt or SWILP | Priorities 0, 1, 2, 3 |
| 01 | Priority 0 | Priorities 1, 2, 3 |
| 10 | Priority 1 | Priorities 2, 3 |
| 11 | Priority 2 or 3 | Priority 3 |

5.5.16.3 Vector Number - Vector Address Bus (VAB)—Bits 12–6

This *read-only* field shows the vector number (VAB[6:0]) used at the time the last IRQ was taken. In the case of a Fast Interrupt, it shows the lower address bits of the jump address. This field is only updated when the 56800E core jumps to a new interrupt service routine.

Note: Nested interrupts may cause this field to be updated before the original interrupt service routine can read it.

5.5.16.4 Interrupt Disable (INT_DIS)—Bit 5

This bit allows all interrupts to be disabled.

- 0 = Normal operation (default)
- 1 = All interrupts disabled

5.5.16.5 Reserved—Bits 4–2

This bit field is reserved or not implemented. It is read as 1 and cannot be modified by writing.

5.5.16.6 Reserved—Bits 1–0

This bit field is reserved or not implemented. It is read as 0 and cannot be modified by writing.

5.6 Resets

5.6.1 General

Table 5-4 Reset Summary

| Reset | Priority | Source | Characteristics |
|------------|----------|--------|-------------------------|
| Core Reset | | RST | Core reset from the SIM |

5.6.2 Description of Reset Operation

5.6.2.1 Reset Handshake Timing

The ITCN provides the 56800E core with a reset vector address on the VAB pins whenever $\overline{\text{RESET}}$ is asserted from the SIM. The reset vector will be presented until the second rising clock edge after $\overline{\text{RESET}}$ is released. The general timing is shown in [Figure 5-19](#).

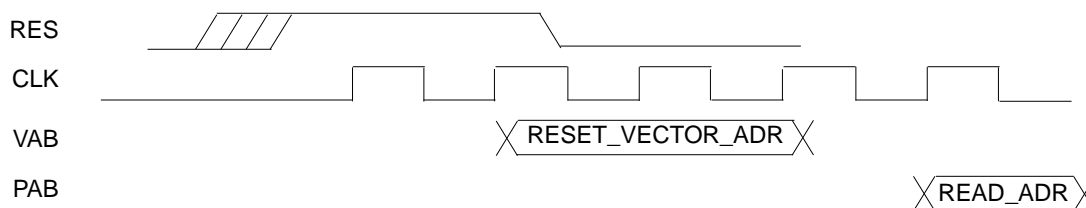


Figure 5-19 Reset Interface

5.6.3 ITCN After Reset

After reset, all of the ITCN registers are in their default states. This means all interrupts are disabled, except the core IRQs with fixed priorities:

- Illegal Instruction
- SW Interrupt 3
- HW Stack Overflow
- Misaligned Long Word Access
- SW Interrupt 2
- SW Interrupt 1

- SW Interrupt 0
- SW Interrupt LP

These interrupts are enabled at their fixed priority levels.

Part 6 System Integration Module (SIM)

6.1 Introduction

The SIM module is a system catchall for the glue logic that ties together the system-on-chip. It controls distribution of resets and clocks and provides a number of control features. The System Integration Module is responsible for the following functions:

- Reset sequencing
- Clock control & distribution
- Stop/Wait control
- System status registers
- Registers for software access to the JTAG ID of the chip
- Test registers
- Power control
- I/O pad multiplexing

These are discussed in more detail in the sections that follow.

6.2 Features

The SIM has the following features:

- Reset sequencing
 - Core and Peripheral Clock control & distribution
 - Stop/Wait mode control
 - System status
 - Power control
 - Control I/O multiplexing
- System bus clocks with pipeline hold-off support
- System clocks for non-pipelined interfaces
- Peripheral clocks for Quad Timer and PWM with high-speed (3X) option
- Power-saving clock gating for peripherals
- Three power modes (Run, Wait, Stop) to control power utilization
 - Stop mode shuts down the 56800E core, system clock, and peripheral clock
 - Wait mode shuts down the 56800E core and unnecessary system clock operation
 - Run mode supports full part operation
- Controls, with write protection, the enable/disable of 56800E core WAIT and STOP instructions

- Controls, with write protection, the enable/disable of Large Regulator Standby mode
- Controls to route functional signals to selected peripherals and I/O pads
- Controls deassertion sequence of internal resets
- Software-initiated reset
- Four 16-bit registers reset only by a Power-On Reset usable for general-purpose software control
- Timer channel Stop mode clocking controls
- SCI Stop mode clocking control to support LIN Sleep mode stop recovery
- Short addressing location control
- Registers for containing the JTAG ID of the chip
- Controls output to CLKO pin

6.3 Register Descriptions

Table 6-1 SIM Registers (SIM_BASE = \$00 F140)

| Address Offset | Address Acronym | Register Name | Section Location |
|----------------|-----------------|--|------------------------|
| Base + \$0 | SIM_CTRL | Control Register | 6.3.1 |
| Base + \$1 | SIM_RSTAT | Reset Status Register | 6.3.2 |
| Base + \$2 | SIM_SWC0 | Software Control Register 0 | 6.3.3 |
| Base + \$3 | SIM_SWC1 | Software Control Register 1 | 6.3.3 |
| Base + \$4 | SIM_SWC2 | Software Control Register 2 | 6.3.3 |
| Base + \$5 | SIM_SWC3 | Software Control Register 3 | 6.3.3 |
| Base + \$6 | SIM_MSHID | Most Significant Half of JTAG ID | 6.3.4 |
| Base + \$7 | SIM_LSHID | Least Significant Half of JTAG ID | 6.3.5 |
| Base + \$8 | SIM_PWR | Power Control Register | 6.3.6 |
| | | Reserved | |
| Base + \$A | SIM_CLKOUT | CLKO Select Register | 6.3.7 |
| Base + \$B | SIM_GPS | GPIO Peripheral Select Register | 6.3.8 |
| Base + \$C | SIM_PCE | Peripheral Clock Enable Register | 6.3.9 |
| Base + \$D | SIM_IOSAHI | I/O Short Address Location High Register | 6.3.10 |
| Base + \$E | SIM_IOSALO | I/O Short Address Location Low Register | 6.3.10 |

| Add. Offset | Address Acronym | | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|-------------|-----------------|---|-------------------------|--------|--------|--------|--------|--------|---------|--------|--------|--------|----------|---------|--------------|-----|--------------|-----|
| \$0 | SIM_CTRL | R | TC3_SD | TC2_SD | TC1_SD | TC0_SD | SCL_SD | 0 | TC3_INP | 0 | 0 | 0 | ONCE_EBL | SW_RST | STOP_DISABLE | | WAIT_DISABLE | |
| \$1 | SIM_RSTAT | R | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | SWR | COPR | EXTR | POR | 0 | 0 |
| \$2 | SIM_SWC0 | R | Software Control Data 0 | | | | | | | | | | | | | | | |
| \$3 | SIM_SWC1 | R | Software Control Data 1 | | | | | | | | | | | | | | | |
| \$4 | SIM_SWC2 | R | Software Control Data 2 | | | | | | | | | | | | | | | |
| \$5 | SIM_SWC3 | R | Software Control Data 3 | | | | | | | | | | | | | | | |
| \$6 | SIM_MSHID | R | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 1 | 1 | 1 | 1 | 1 | 0 | 0 | 1 | 0 |
| \$7 | SIM_LSHID | R | 0 | 1 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 1 | 1 | 1 | 0 | 1 |
| \$8 | SIM_PWR | R | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | LRSTDBY | |
| | Reserved | | | | | | | | | | | | | | | | | |
| \$A | SIM_CLKOUT | R | 0 | 0 | 0 | 0 | 0 | 0 | PWM3 | PWM2 | PWM1 | PWM0 | CLK_DIS | CLKOSEL | | | | |
| \$B | SIM_GPS | R | TCR | PCR | 0 | 0 | CFG_B7 | CFG_B6 | CFG_B5 | CFG_B4 | CFG_B3 | CFG_B2 | CFG_B1 | CFG_B0 | CFG_A5 | | CFG_A4 | |
| \$C | SIM_PCE | R | I2C | 0 | ADC | 0 | 0 | 0 | 0 | 0 | 0 | TMR | 0 | SCI | 0 | SPI | 0 | PWM |
| \$D | SIM_IOSAHI | R | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | ISAL[23:22] | |
| \$E | SIM_IOSALO | R | ISAL[21:6] | | | | | | | | | | | | | | | |

0 = Read as 0
1 = Read as 1
 = Reserved

Figure 6-1 SIM Register Map Summary

6.3.1 SIM Control Register (SIM_CTRL)

| Base + \$0 | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|------------|--------|--------|--------|--------|--------|----|---------|---|---|---|----------|--------|--------------|---|--------------|---|
| Read | TC3_SD | TC2_SD | TC1_SD | TC0_SD | SCL_SD | 0 | TC3_INP | 0 | 0 | 0 | ONCE_EBL | SW_RST | STOP_DISABLE | | WAIT_DISABLE | |
| Write | | | | | | | | | | | | | | | | |
| RESET | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

Figure 6-2 SIM Control Register (SIM_CTRL)

6.3.1.1 Timer Channel 3 Stop Disable (TC3_SD)—Bit 15

This bit enables the operation of the Timer Channel 3 peripheral clock in Stop mode.

- 0 = Timer Channel 3 disabled in Stop mode

- 1 = Timer Channel 3 enabled in Stop mode

6.3.1.2 Timer Channel 2 Stop Disable (TC2_SD)—Bit 14

This bit enables the operation of the Timer Channel 2 peripheral clock in Stop mode.

- 0 = Timer Channel 2 disabled in Stop mode
- 1 = Timer Channel 2 enabled in Stop mode

6.3.1.3 Timer Channel 1 Stop Disable (TC1_SD)—Bit 13

This bit enables the operation of the Timer Channel 1 peripheral clock in Stop mode.

- 0 = Timer Channel 1 disabled in Stop mode
- 1 = Timer Channel 1 enabled in Stop mode

6.3.1.4 Timer Channel 0 Stop Disable (TC0_SD)—Bit 12

This bit enables the operation of the Timer Channel 0 peripheral clock in Stop mode.

- 0 = Timer Channel 0 disabled in Stop mode
- 1 = Timer Channel 0 enabled in Stop mode

6.3.1.5 SCI Stop Disable (SCI_SD)—Bit 11

This bit enables the operation of the SCI peripheral clock in Stop mode. This is recommended for use in LIN mode so that the SCI can generate interrupts and recover from Stop mode while the LIN interface is in Sleep mode and using Stop mode to reduce power consumption.

- 0 = SCI disabled in Stop mode
- 1 = SCI enabled in Stop mode

6.3.1.6 Reserved—Bit 10

This bit field is reserved or not implemented. It is read as 0 and cannot be modified by writing.

6.3.1.7 Timer Channel 3 Input (TC3_INP)—Bit 9

This bit selects the input of Timer Channel 3 to be from the PWM sync signal or GPIO pin.

- 1 = Timer Channel 3 Input from PWM sync signal
- 0 = Timer Channel 3 Input controlled by SIM_GPS register CFG_B3 and CFG_A5 fields

6.3.1.8 Reserved—Bits 8–6

This bit field is reserved or not implemented. It is read as 0 and cannot be modified by writing.

6.3.1.9 OnCE Enable (ONCEEBL)—Bit 5

- 0 = OnCE clock to 56800E core enabled when core TAP is enabled
- 1 = OnCE clock to 56800E core is always enabled

6.3.1.10 Software Reset (SWRST)—Bit 4

Writing 1 to this field will cause the part to reset.

6.3.1.11 Stop Disable (STOP_DISABLE[1:0])—Bits 3–2

- 00 = Stop mode will be entered when the 56800E core executes a STOP instruction
- 01 = The 56800E STOP instruction will not cause entry into Stop mode
- 10 = Stop mode will be entered when the 56800E core executes a STOP instruction and the STOP_DISABLE field is write-protected until the next reset
- 11 = The 56800E STOP instruction will not cause entry into Stop mode and the STOP_DISABLE field is write-protected until the next reset

6.3.1.12 Wait Disable (WAIT_DISABLE[1:0])—Bits 1–0

- 00 = Wait mode will be entered when the 56800E core executes a WAIT instruction
- 01 = The 56800E WAIT instruction will not cause entry into Wait mode
- 10 = Wait mode will be entered when the 56800E core executes a WAIT instruction and the WAIT_DISABLE field is write-protected until the next reset
- 11 = The 56800E WAIT instruction will not cause entry into Wait mode and the WAIT_DISABLE field is write-protected until the next reset

6.3.2 SIM Reset Status Register (SIM_RSTAT)

This register is updated upon any system reset and indicates the cause of the most recent reset. It also controls whether the COP reset vector or regular reset vector in the vector table is used. This register is asynchronously reset during Power-On Reset (see power supervisor module) and subsequently is synchronously updated based on the level of the external reset, software reset, or cop reset inputs. Only one source will ever be indicated. In the event that multiple reset sources assert simultaneously, the highest-precedence source will be indicated. The precedence from highest to lowest is POR, EXTR, COPR, and SWR. While POR is always set during a Power-On Reset, EXTR will become set if the external reset pin is asserted or remains asserted after the Power-On Reset (POR) has deasserted.

| Base + \$1 | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|------------|----|----|----|----|----|----|---|---|---|---|-----|------|------|-----|---|---|
| Read | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | SWR | COPR | EXTR | POR | 0 | 0 |
| Write | | | | | | | | | | | | | | | | |
| RESET | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | | | | | 0 | 0 |

Figure 6-3 SIM Reset Status Register (SIM_RSTAT)

6.3.2.1 Reserved—Bits 15–6

This bit field is reserved or not implemented. It is read as zero and cannot be modified by writing.

6.3.2.2 Software Reset (SWR)—Bit 5

When set, this bit indicates that the previous system reset occurred as a result of a software reset (written 1 to SW RST bit in the SIM_CTRL register). It will not be set if a COP, external, or POR reset also occurred.

6.3.2.3 COP Reset (COPR)—Bit 4

When set, this bit indicates that the previous system reset was caused by the Computer Operating Properly

(COP) timer. It will not be set if an external or POR reset also occurred. If COPR is set as code starts executing, the COP reset vector in the vector table will be used. Otherwise, the normal reset vector is used.

6.3.2.4 External Reset (EXTR)—Bit 3

When set, this bit indicates that the previous system reset was caused by an external reset. It will only be set if the external reset pin was asserted or remained asserted after the Power-On Reset deasserted.

6.3.2.5 Power-On Reset (POR)—Bit 2

This bit is set during a Power-On Reset.

6.3.2.6 Reserved—Bits 1–0

This bit field is reserved or not implemented. It is read as 0 and cannot be modified by writing.

6.3.3 SIM Software Control Registers (SIM_SWC0, SIM_SWC1, SIM_SWC2, and SIM_SWC3)

Only SIM_SWC0 is shown in this section. SIM_SWC1, SIM_SWC2, and SIM_SWC3 are identical in functionality.

| Base + \$2 | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|------------|-------------------------|----|----|----|----|----|---|---|---|---|---|---|---|---|---|---|
| Read | Software Control Data 0 | | | | | | | | | | | | | | | |
| Write | Software Control Data 0 | | | | | | | | | | | | | | | |
| RESET | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

Figure 6-4 SIM Software Control Register 0 (SIM_SWC0)

6.3.3.1 Software Control Data 0 (FIELD)—Bits 15–0

This register is reset only by the Power-On Reset (POR). It has no part-specific functionality and is intended for use by a software developer to contain data that will be unaffected by the other reset sources ($\overline{\text{RESET}}$ pin, software reset, and COP reset).

6.3.4 Most Significant Half of JTAG ID (SIM_MSHID)

This read-only register displays the most significant half of the JTAG ID for the chip. This register reads \$01F2.

| Base + \$6 | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|------------|----|----|----|----|----|----|---|---|---|---|---|---|---|---|---|---|
| Read | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 1 | 1 | 1 | 1 | 1 | 0 | 0 | 1 | 0 |
| Write | | | | | | | | | | | | | | | | |
| RESET | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 1 | 1 | 1 | 1 | 1 | 0 | 0 | 1 | 0 |

Figure 6-5 Most Significant Half of JTAG ID (SIM_MSHID)

6.3.5 Least Significant Half of JTAG ID (SIM_LSHID)

This read-only register displays the least significant half of the JTAG ID for the chip. This register reads \$401D.

| Base + \$7 | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|------------|----|----|----|----|----|----|---|---|---|---|---|---|---|---|---|---|
| Read | 0 | 1 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 1 | 1 | 1 | 0 | 1 |
| Write | | | | | | | | | | | | | | | | |
| RESET | 0 | 1 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 1 | 1 | 1 | 0 | 1 |

Figure 6-6 Least Significant Half of JTAG ID (SIM_LSHID)

6.3.6 SIM Power Control Register (SIM_PWR)

This register controls the Standby mode of the large regulator. The large regulator derives the core digital logic power supply from the IO power supply. In some circumstances, the large regulator may be put in a reduced-power Standby mode without interfering with part operation. Refer to the overview of power-down modes and the overview of clock generation for more information on the use of large regulator standby.

| Base + \$8 | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|------------|----|----|----|----|----|----|---|---|---|---|---|---|---|---|---------|---|
| Read | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | LRSTDBY | |
| Write | | | | | | | | | | | | | | | | |
| RESET | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

Figure 6-7 SIM Power Control Register (SIM_PWR)

6.3.6.1 Reserved—Bits 15–2

This bit field is reserved or not implemented. It is read as 0 and cannot be modified by writing.

6.3.6.2 Large Regulator Standby Mode[1:0] (LRSTDBY)—Bits 1–0

This bit controls the pull-up resistors on the IRQA pin.

- 00 = Large regulator is in Normal mode
- 01 = Large regulator is in Standby (reduced-power) mode
- 10 = Large regulator is in Normal mode and the LRSTDBY field is write-protected until the next reset
- 11 = Large regulator is in Standby mode and the LRSTDBY field is write-protected until the next reset

Note: Standby mode can be used when the device operates below 200 kHz if the PLL is shut down.

6.3.7 CLKO Select Register (SIM_CLKOUT)

The CLKO select register can be used to multiplex out selected clocks generated inside the clock generation and SIM modules. All functionality is for test purposes only and is subject to unspecified latencies. Glitches may be produced when the clock is enabled or switched.

The lower four bits of the GPIO A register can function as GPIO, PWM, or as additional clock output signals. GPIO has priority and is enabled/disabled via the GPIOA_PEREN. If GPIOA[3:0] are programmed to operate as peripheral outputs, then the choice between PWM and additional clock outputs is done here in the CLKOUT. The default state is for the peripheral function of GPIOA[3:0] to be programmed as PWM. This can be changed by altering $\overline{\text{PWM}}3$ through $\overline{\text{PWM}}0$.

| Base + \$A | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|------------|----|----|----|----|----|----|--------------------------|--------------------------|--------------------------|--------------------------|---------|---------|---|---|---|---|
| Read | 0 | 0 | 0 | 0 | 0 | 0 | $\overline{\text{PWM}}3$ | $\overline{\text{PWM}}2$ | $\overline{\text{PWM}}1$ | $\overline{\text{PWM}}0$ | CLK DIS | CLKOSEL | | | | |
| Write | | | | | | | | | | | | | | | | |
| RESET | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 1 | 0 | 0 | 0 | 0 | 0 |

Figure 6-8 CLKO Select Register (SIM_CLKOUT)

6.3.7.1 Reserved—Bits 15–10

This bit field is reserved or not implemented. It is read as 0 and cannot be modified by writing.

6.3.7.2 $\overline{\text{PWM}}3$ —Bit 9

- 0 = Peripheral output function of GPIOA[3] is defined to be $\overline{\text{PWM}}3$
- 1 = Peripheral output function of GPIOA[3] is defined to be the Relaxation Oscillator Clock

6.3.7.3 $\overline{\text{PWM}}2$ —Bit 8

- 0 = Peripheral output function of GPIOA[2] is defined to be $\overline{\text{PWM}}2$
- 1 = Peripheral output function of GPIOA[2] is defined to be the system clock

6.3.7.4 $\overline{\text{PWM}}1$ —Bit 7

- 0 = Peripheral output function of GPIOA[1] is defined to be $\overline{\text{PWM}}1$
- 1 = Peripheral output function of GPIOA[1] is defined to be two times the rate of the system clock

6.3.7.5 $\overline{\text{PWM}}0$ —Bit 6

- 0 = Peripheral output function of GPIOA[0] is defined to be $\overline{\text{PWM}}0$
- 1 = Peripheral output function of GPIOA[0] is defined to be three times the rate of the system clock

6.3.7.6 Clockout Disable (CLKDIS)—Bit 5

- 0 = CLKOUT output is enabled and will output the signal indicated by CLKOSEL
- 1 = CLKOUT is 0

6.3.7.7 Clockout Select (CLKOSEL)—Bits 4–0

Selects clock to be muxed out on the CLKO pin.

- 00000 = Reserved for factory test—Continuous system clock
- 01001 = Reserved for factory test—OCCS MSTR OSC clock
- 01011 = Reserved for factory test—ADC clock
- 01100 = Reserved for factory test—JTAG TCLK

- 01101 = Reserved for factory test—Continuous peripheral clock
- 01110 = Reserved for factory test—Continuous inverted peripheral clock
- 01111 = Reserved for factory test—Continuous high-speed peripheral clock

6.3.8 SIM GPIO Peripheral Select Register (SIM_GPS)

All of the peripheral pins on the 56F8014 share their Input/Output (I/O) with GPIO ports. To select peripheral or GPIO control, program the corresponding bit in the GPIOx_PEREN register in the GPIO module. (See *MC56F8000RM*, the 56F801x Peripheral Reference Manual, for details.) In some cases, there are two possible peripherals as well as the GPIO functionality available for control of the I/O. In these cases, the SIM_GPS register is used to determine which peripheral has control when the corresponding I/O pin is configured in peripheral mode.

As shown in [Figure 6-9](#), the GPIO Peripheral Enable Register (PEREN) has the final control over which pin controls the I/O. SIM_GPS simply decides which peripheral will be routed to the I/O when PEREN = 1.

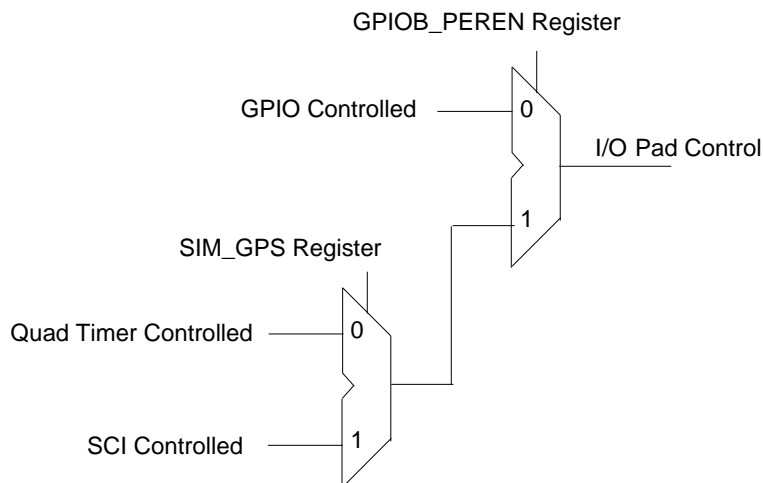


Figure 6-9 Overall Control of Pads Using SIM_GPS Control

| Base + \$B | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|------------|-----|-----|----|----|--------|--------|--------|--------|--------|--------|--------|--------|--------|---|--------|---|
| Read | TCR | PCR | 0 | 0 | CFG_B7 | CFG_B6 | CFG_B5 | CFG_B4 | CFG_B3 | CFG_B2 | CFG_B1 | CFG_B0 | CFG_A5 | | CFG_A4 | |
| Write | | | | | | | | | | | | | | | | |
| RESET | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

Figure 6-10 GPIO Peripheral Select Register (SIM_GPS)

6.3.8.1 Quad Timer Clock Rate (TCR)—Bit 15

This bit selects the clock speed for the Quad Timer module.

- 0 = Quad Timer module clock rate equals system clock rate, to a maximum 32 MHz (default)
- 1 = Quad Timer module clock rate equals three times system clock rate, to a maximum 96 MHz

Note: This bit should only be changed while the Quad Timer module's clock is disabled. See [Section 6.3.9](#).

Note: High-speed clocking is only available when the PLL is being used.

Note: If the PWM sync signal is used as input to Timer 3 (See SIM_CTRL: TC3_INP, [Section 6.3.1.7](#)), then the clocks of the Quad Timer and PWM must be related, as shown in [Table 6-2](#).

6.3.8.2 PWM Clock Rate (PCR)—Bit 14

This bit selects the clock speed for the PWM module.

- 0 = PWM module clock rate equals system clock rate, to a maximum 32 MHz (default)
- 1 = PWM module clock rate equals three times system clock rate, to a maximum 96 MHz

Note: This bit should only be changed while the PWM module's clock is disabled. See [Section 6.3.9](#).

Note: High-speed clocking is only available when the PLL is being used.

Note: If the PWM sync signal is used as input to Timer 3 (See SIM_CTRL: TC3_INP, [Section 6.3.1.7](#)), then the clocks of the Quad Timer and PWM must be related, as shown in [Table 6-2](#).

Table 6-2 Allowable Quad Timer and PWM Clock Rates when Using PWM Reload Pulse

| | | Quad Timer | |
|-----|----|------------|----|
| | | 1X | 3X |
| PWM | 1X | OK | OK |
| | 3X | NO | OK |

6.3.8.3 Reserved—Bits 13–12

This bit field is reserved or not implemented. It is read as 0 and cannot be modified by writing.

6.3.8.4 Configure GPIOB7 (CFG_B7)—Bit 11

This bit selects the alternate function for GPIOB7.

- 0 = TXD — SCI Transmit Data (default)
- 1 = SCL — I²C Serial Clock

6.3.8.5 Configure GPIOB6 (CFG_B6)—Bit 10

This bit selects the alternate function for GPIOB6.

- 0 = RXD — SCI Receive Data (default)
- 1 = SDA — I²C Serial Data

Note: The PRECS bit in the OCCS Oscillator Control register can enable this pin as the

source clock to the chip. In this mode, make sure that no on-chip peripheral (including the GPIO) is driving this pin.

6.3.8.6 Configure GPIOB5 (CFG_B5)—Bit 9

This bit selects the alternate function for GPIOB5.

- 0 = T1 — Timer channel 1 input/output (default)
- 1 = FAULT3 — PWM FAULT3 input

6.3.8.7 Configure GPIOB4 (CFG_B4)—Bit 8

This bit selects the alternate function for GPIOB4.

- 0 = T0 — Timer channel 0 input/output (default)
- 1 = CLKO — Clock output

6.3.8.8 Configure GPIOB3 (CFG_B3)—Bit 7

This bit selects the alternate function for GPIOB3.

- 0 = MOSI — SPI master out/slave in (default)
- 1 = T3 — Timer channel 3 input/output

6.3.8.9 Configure GPIOB2 (CFG_B2)—Bit 6

This bit selects the alternate function for GPIOB2.

- 0 = MISO — SPI master in/slave out (default)
- 1 = T2 — Timer channel 2 input/output

6.3.8.10 Configure GPIOB1 (CFG_B1)—Bit 5

This bit selects the alternate function for GPIOB1.

- 0 = SS — SPI Slave Select (default)
- 1 = SDA — I²C Serial Data

6.3.8.11 Configure GPIOB0 (CFG_B0)—Bit 4

This bit selects the alternate function for GPIOB0.

- 0 = SCLK — SPI Serial Clock (default)
- 1 = SCL — I2C Serial Clock

6.3.8.12 Configure GPIOA5[1:0] (CFG_A5)—Bits 3–2

These bits select the alternate function for GPIOA5.

- 00 = PWM5 — PWM5 output (default)
- 01 = PWM5 — PWM5 output
- 10 = FAULT2 — PWM FAULT2 input

- 11 = T3 — Timer Channel 3 input/output

6.3.8.13 Configure GPIOA4[1:0] (CFG_A4)—Bits 1–0

These bits select the alternate function for GPIOA4.

- 00 = PWM4 — PWM4 output
- 01 = PWM4 — PWM4 output
- 10 = FAULT1 — PWM FAULT1 input
- 11 = T2 — Timer Channel 2 input/output

Note: When programming the CFG_* signals be careful so as not to connect two different I/O pins to the same peripheral input. For example, do not set CFG_B7 to select SCL and also set CFG_B0 to select SCL. If this occurs for an output signal, then the signal will be routed to two I/O pins. For input signals, the values on the two I/O pins will be ORed together before reaching the peripheral.

6.3.9 Peripheral Clock Enable Register (SIM_PCE)

The Peripheral Clock Enable register is used to enable or disable clocks to the peripherals as a power savings feature. The clocks can be individually controlled for each peripheral on the chip. The corresponding peripheral should itself be disabled while its clock is shut off.

| Base + \$C | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|------------|-----|----|-----|----|----|----|---|---|---|-----|---|-----|---|-----|---|-----|
| Read | I2C | 0 | ADC | 0 | 0 | 0 | 0 | 0 | 0 | TMR | 0 | SCI | 0 | SPI | 0 | PWM |
| Write | | | | | | | | | | | | | | | | |
| RESET | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

Figure 6-11 Peripheral Clock Enable Register (SIM_PCE)

6.3.9.1 I²C Clock Enable (I2C)—Bit 15

- 0 = The clock is not provided to the I²C module (the I²C module is disabled)
- 1 = Clocks to the I²C module are enabled

6.3.9.2 Reserved—Bit 14

This bit field is reserved or not implemented. It is read as 0 and cannot be modified by writing.

6.3.9.3 Analog-to-Digital Converter IPBus Clock Enable (ADC)—Bit 13

- 0 = The clock is not provided to the ADC module (the ADC module is disabled)
- 1 = Clocks to the ADC module are enabled

6.3.9.4 Reserved—Bits 12–7

This bit field is reserved or not implemented. It is read as 0 and cannot be modified by writing.

6.3.9.5 Timer Clock Enable (TMR)—Bit 6

- 0 = The clock is not provided to the Quad Timer module (the Quad Timer module is disabled)

- 1 = Clocks to the Quad Timer module are enabled

6.3.9.6 Reserved—Bit 5

This bit field is reserved or not implemented. It is read as 0 and cannot be modified by writing.

6.3.9.7 SCI IPBus Clock Enable (SCI)—Bit 4

- 0 = The clock is not provided to the SCI module (the SCI module is disabled)
- 1 = Clocks to the SCI module are enabled

6.3.9.8 Reserved—Bit 3

This bit field is reserved or not implemented. It is read as 0 and cannot be modified by writing.

6.3.9.9 SPI Clock Enable (SPI)—Bit 2

- 0 = The clock is not provided to the SPI module (the SPI module is disabled)
- 1 = Clocks to the SPI module are enabled

6.3.9.10 Reserved—Bit 1

This bit field is reserved or not implemented. It is read as 0 and cannot be modified by writing.

6.3.9.11 PWM Clock Enable (PWM)—Bit 0

- 0 = The clock is not provided to the PWM module (the PWM module is disabled)
- 1 = Clocks to the PWM module are enabled

6.3.10 I/O Short Address Location Register (SIM_IOSAHI and SIM_IOSALO)

The I/O Short Address Location registers are used to specify the memory referenced via the I/O short address mode. The I/O short address mode allows the instruction to specify the lower six bits of address; the upper address bits are not directly controllable. This register set allows limited control of the full address, as shown in [Figure 6-12](#).

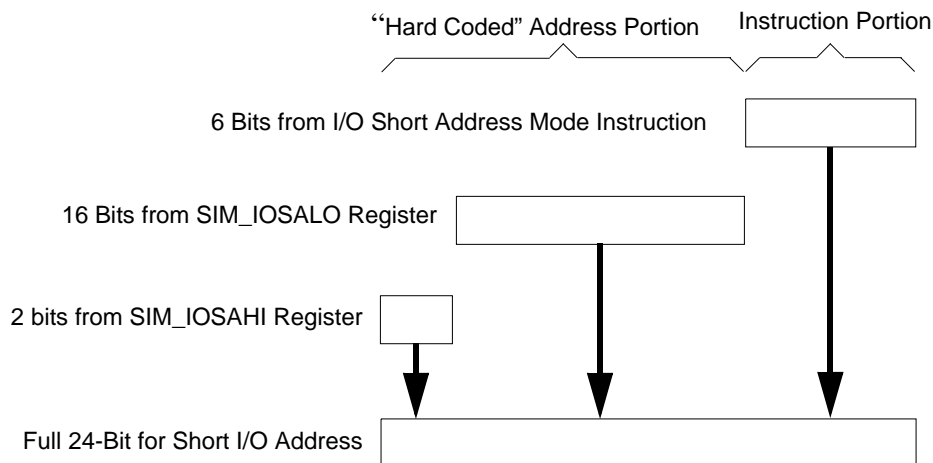


Figure 6-12 I/O Short Address Determination

With this register set, an interrupt driver can set the SIM_IOSALO register pair to point to its peripheral registers and then use the I/O Short addressing mode to reference them. The ISR should restore this register to its previous contents prior to returning from interrupt.

Note: The default value of this register set points to the EOnCE registers.

Note: The pipeline delay between setting this register set and using short I/O addressing with the new value is five instruction cycles.

| Base + \$D | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|------------|----|----|----|----|----|----|---|---|---|---|---|---|---|---|-------------|---|
| Read | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | ISAL[23:22] | |
| Write | | | | | | | | | | | | | | | | |
| RESET | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 1 | 1 |

Figure 6-13 I/O Short Address Location High Register (SIM_IOSAHI)

6.3.10.1 Reserved—Bits 15—2

This bit field is reserved or not implemented. It is read as 0 and cannot be modified by writing.

6.3.10.2 Input/Output Short Address Location (ISAL[23:22])—Bit 1—0

This field represents the upper two address bits of the “hard coded” I/O short address.

| | | | | | | | | | | | | | | | | |
|------------|------------|----|----|----|----|----|---|---|---|---|---|---|---|---|---|---|
| Base + \$E | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| Read | ISAL[21:6] | | | | | | | | | | | | | | | |
| Write | ISAL[21:6] | | | | | | | | | | | | | | | |
| RESET | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |

Figure 6-14 I/O Short Address Location Low Register (SIM_IOSALO)

6.3.10.3 Input/Output Short Address Location (ISAL[21:6])—Bit 15–0

This field represents the lower 16 address bits of the “hard coded” I/O short address.

6.4 Clock Generation Overview

The SIM uses master clocks, 2X system clock at a maximum of 64 MHz, from the OCCS module to produce the peripheral and system (core and memory) clocks at a maximum of 32 MHz. It divides the master clock by two and gates it with appropriate power mode and clock gating controls. The high speed peripheral clock input from OCCS operates at three times the system clock for PWM and Quad Timer module at a maximum of 96 MHz.

The OCCS configuration controls the operating frequency of the SIM’s master clocks. In the OCCS, either an external clock or the relaxation oscillator can be selected as the master clock source (MSTR_OSC). When selected, the relaxation oscillator can be operated at full speed (8 MHz), standby speed (200 kHz), or powered down. An 8 MHz clock can be multiplied to 192 MHz using the PLL and postscaled to provide a variety of high speed clock rates. Either the postscaled PLL output or the input clock of the PLL signal can be selected to produce the master clocks to the SIM. When the PLL is not selected, the high speed peripheral clock is disabled and the 2x system clock is the input clock from either the internal relaxation oscillator or from an external clock source.

In combination with the OCCS module, the SIM provides power modes (see [Section 6.5](#)), clock enables (SIM_PCE register, CLK_DIS, ONCE_EBL), and clock rate controls (TCR, PCR) to provide flexible control of clocking and power utilization. The SIM’s clock enable controls can be used to disable individual clocks when not needed. The clock rate controls enable the high speed clocking option for the Timer channels and PWM but require the PLL to be on and selected. Refer to the **56F801X Peripheral Reference Manual** for further details.

6.5 Power-Down Modes

The 56F8014 operates in one of five Power-Down modes, as shown in [Table 6-3](#).

Table 6-3 Clock Operation in Power-Down Modes

| Mode | Core Clocks | Peripheral Clocks | Description |
|------|---------------------------------|---------------------------|----------------------------|
| Run | Core and memory clocks disabled | Peripheral clocks enabled | Device is fully functional |

Table 6-3 Clock Operation in Power-Down Modes (Continued)

| Mode | Core Clocks | Peripheral Clocks | Description |
|------------|--|---------------------------|--|
| Wait | Core and memory clocks disabled | Peripheral clocks enabled | Core executes WAIT instruction to enter this mode. Typically used for power-conscious applications. Possible recoveries from Wait mode to Run mode are: 1. Any interrupt 2. Executing a Debug mode entry command during the 56800E core JTAG interface 2. Any reset (POR, external, software, COP) |
| Stop | Master clock generation in the OCCS remains operational, but the SIM disables the generation of system and peripheral clocks. | | Core executes STOP instruction to enter this mode. Possible recoveries from Stop mode to Run mode are: 1. Interrupt from Timer channels that have been configured to operate in Stop mode (TCx_SD) 2. Interrupt for SCI configured to operate in Stop mode (SCI_SD) 3. Low-voltage interrupt 4. Executing a Debug mode entry command using the 56800E core JTAG interface 5. Any reset (POR, external, software, COP) |
| Standby | The OCCS generates the 2x System Clock at a reduced frequency (200 kHz). The PLL and high speed peripheral clocks are disabled and the high-speed peripheral option is not available. System and peripheral clocks operate at 100 kHz. | | The user configures the OCCS and SIM to select the relaxation oscillator clock source (PRECS), shut down the PLL (PLLPD), put the relaxation oscillator in Standby mode (ROSB), and put the large regulator in Standby (LRSTDBY). The part is fully operational, but operating at a minimum frequency and power configuration. Recovery requires reversing the sequence used to enter this mode (allowing for PLL lock time). |
| Power-Down | Master clock generation in the OCCS is completely shut down. All system and peripheral clocks are disabled. | | The user configures the OCCS and SIM to enter Standby mode as shown in the previous description, followed by powering down the oscillator (ROPD). The only possible recoveries from this mode are: 1. External reset 2. Power-on reset |

The power modes provide additional means to disable clock domains, configure the voltage regulator, and configure clock generation to manage power utilization, as shown in [Table 6-3](#). Run, Wait, and Stop modes provide means of enabling/disabling the peripheral and/or core clocking as a group. Stop disable controls are provided for selected peripherals in the control register so that these peripheral clocks can optionally continue to operate in Stop mode and generate interrupts which will return the part from Stop to Run mode. Standby mode provides normal operation but at very low speed and power utilization. It is possible to invoke Stop or Wait mode while in Standby mode for even greater levels of power reduction. A 200 kHz clock external clock can optionally be used in Standby mode to produce the required Standby 100 kHz system bus rate. Power-down mode, which selects the ROSC clock source but shuts it off, fully disables the part and minimizes its power utilization but is only recoverable via reset.

When the PLL is not selected and the system bus is operating at around 100 kHz, the large regulator can

be put into its Standby mode (LRSTDBY) to reduce the power utilization of that regulator.

All peripherals, except the COP/watchdog timer, run at the system clock (peripheral bus) frequency¹, which is the same as the main processor frequency in this architecture. The COP timer runs at $MSTR_OSC / 1024$. The maximum frequency of operation is $SYS_CLK = 32\text{MHz}$. The only exception is the Quad Timer and PWM, which can be configured to operate at three times the system bus rate using TCR and PCR controls, provided the PLL is active and selected.

6.6 Resets

The SIM supports four sources of reset, as shown in [Figure 6-15](#). The two asynchronous sources are the external reset pin and the Power-On Reset (POR). The two synchronous sources are the software reset, which is generated within the SIM itself by writing the SIM_CTRL register in [Section 6.3.1](#), and the COP reset. The SIM uses these to generate resets for the internal logic. These are outlined in [Table 6-4](#). The first column lists the four primary resets which are calculated. The JTAG circuitry is reset by the Power-On Reset. Columns two through five indicate which reset sources trigger these reset signals. The last column provides additional detail.

Table 6-4 Primary System Resets

| Reset Signal | Reset Sources | | | | Comments |
|--------------|---------------|----------|----------|-----|--|
| | POR | External | Software | COP | |
| EXTENDED_POR | X | | | | Stretched version of \overline{POR} . Relevant 64 Relaxation Oscillator Clock cycles after \overline{POR} deasserts. |
| CLKGEN_RST | X | X | X | X | Released 32 Relaxation Oscillator Clock cycles after all reset sources have released. |
| PERIP_RST | X | X | X | X | Releases 32 Relaxation Oscillator Clock cycles after the CLKGEN_RST is released. |
| CORE_RST | X | X | X | X | Releases 32 SYS_CLK periods after PERIP_RST is released. |

[Figure 6-15](#) provides a graphic illustration of the details in [Table 6-4](#). Note that the POR_Delay blocks use the Relaxation Oscillator Clock as their time base since other system clocks are inactive during this phase of reset.

1. The Quad Timer and PWM modules can be operated at three times the IPBus clock frequency.

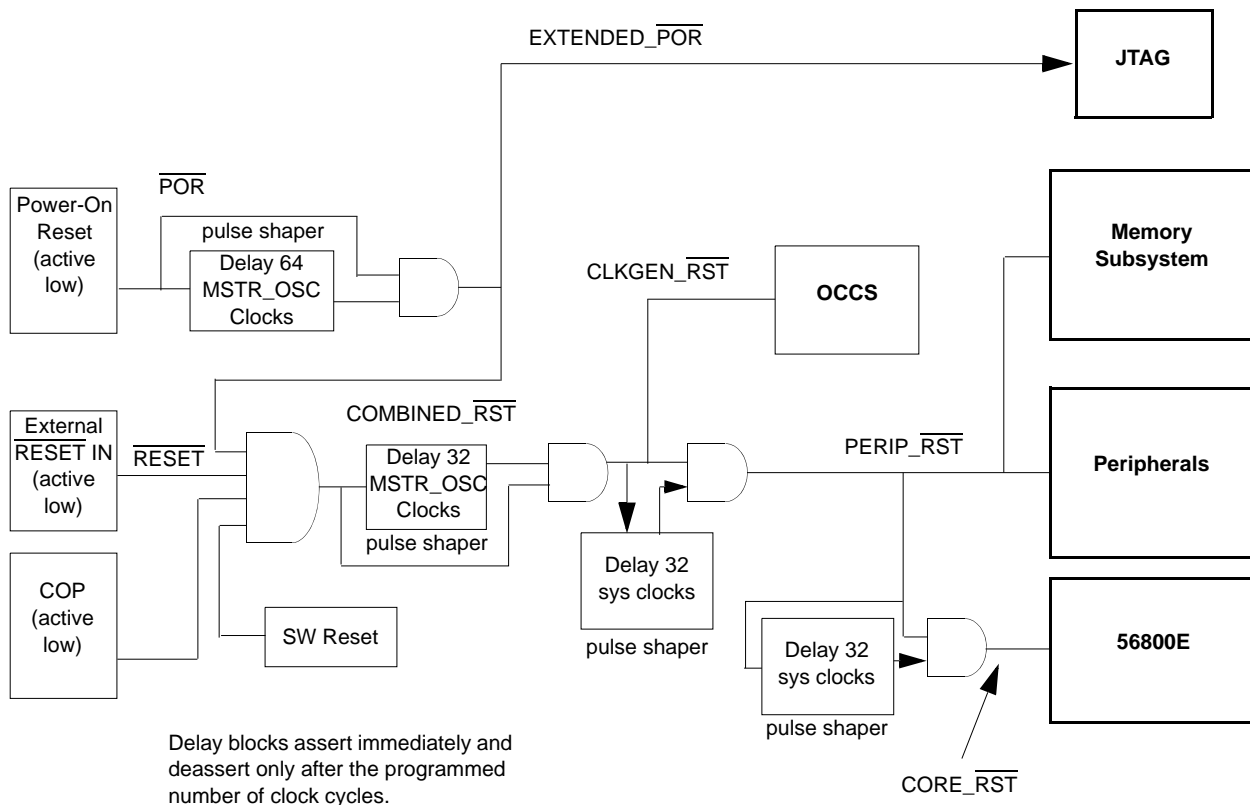


Figure 6-15 Sources of RESET Functional Diagram (Test modes not included)

POR resets are extended 64 MSTR_OSC clocks to stabilize the power supply. All resets are subsequently extended for an additional 32 MSTR_OSC clocks and 64 system clocks as the various internal reset controls are released. Given the normal relaxation oscillator rate of 8MHz, the duration of a POR reset from when power comes on to when code is running is 28μs. An external reset generation chip may also be used. Resets may be asserted asynchronously, but they are always released internally on a rising edge of the system clock.

6.7 Clocks

The memory, peripheral and core clocks all operate at the same frequency (32MHz max) with the exception of the TMR and PWM peripheral clocks, which have the option (using TCR and PCR) to operate three times faster. The SIM is responsible for stalling individual clocks as a response to various hold-off requests, low power modes, and other configuration parameters. The SIM has access to the following signals from the OCCS module:

| | |
|------------|--|
| MSTR_OSC | This comes from the input clock source mux of the OCCS. It is the output of the relaxation oscillator or the external clock source, depending on PRECS. It is not guaranteed to be at 50% duty cycle (+ or - 10% can probably be assumed for design purposes). This clock runs continuously, even during reset and is used for reset generation. |
| HS_PERF | The PLL multiplies the MSTR_OSC by 24, to a maximum of 192MHz. The ZSRC field in OCCS selects the active source to be the PLL. This is divided by 2 and postscaled to produce this maximum 96MHz clock. It is used without further division to produce the high-speed (3x system bus rate) variants of the Quad Timer and PWM peripheral clocks. This clock is disabled when ZSRC is selecting MSTR_OSC. |
| SYS_CLK_x2 | The PLL can multiply the MSTR_OSC by 24, to a maximum of 192MHz. When the PLL is selected by the OCCS ZSRC field, the PLL is divided by three and postscaled to produce this maximum 64MHz clock. When MSTR_OSC is selected by the OCCS ZSRC field, MSTR_OSC feeds SYS_CLK_x2 directly. The SIM takes this clock and divides it by two to generate all the normal (1x system bus rate) peripheral and system clocks. |

While the SIM generates the ADC peripheral clock in the same way it generates all other peripheral clocks, the ADC standby and conversion clocks are generated by a direct interface between the ADC and the OCCS module.

Figure 6-16 illustrates clock relationships to one another and to the various resets as the device comes out of reset. \overline{RST} is assumed to be the logical AND of all active-low system resets (for example, POR, external reset, COP and Software reset). In the 56F8014 architecture, this signal will be stretched by the SIM for a period of time (up to 96 MSTR_OSC clock cycles, depending upon the status of the POR) to create the clock generation reset signal (CLKGEN_ \overline{RST}). The SIM should deassert CLKGEN_ \overline{RST} synchronously with the negative edge of OSC_CLK in order to avoid skew problems. CLKGEN_ \overline{RST} is delayed 32 SYS_CLK cycles to create the peripheral reset signal (PERIP_ \overline{RST}). PERIP_ \overline{RST} is then delayed by 32 SYS_CLK cycles to create CORE_ \overline{RST} . Both PERIP_ \overline{RST} and CORE_ \overline{RST} should be released on the negative edge of SYS_CLK_D as shown. This phased releasing of system resets is necessary to give some peripherals (for example, the Flash interface unit) set-up time prior to the 56800E core becoming active.

Maximum Delay = 64 MSTR_OSC cycles for POR reset extension and 32 MSTR_OSC cycles for combined reset extension

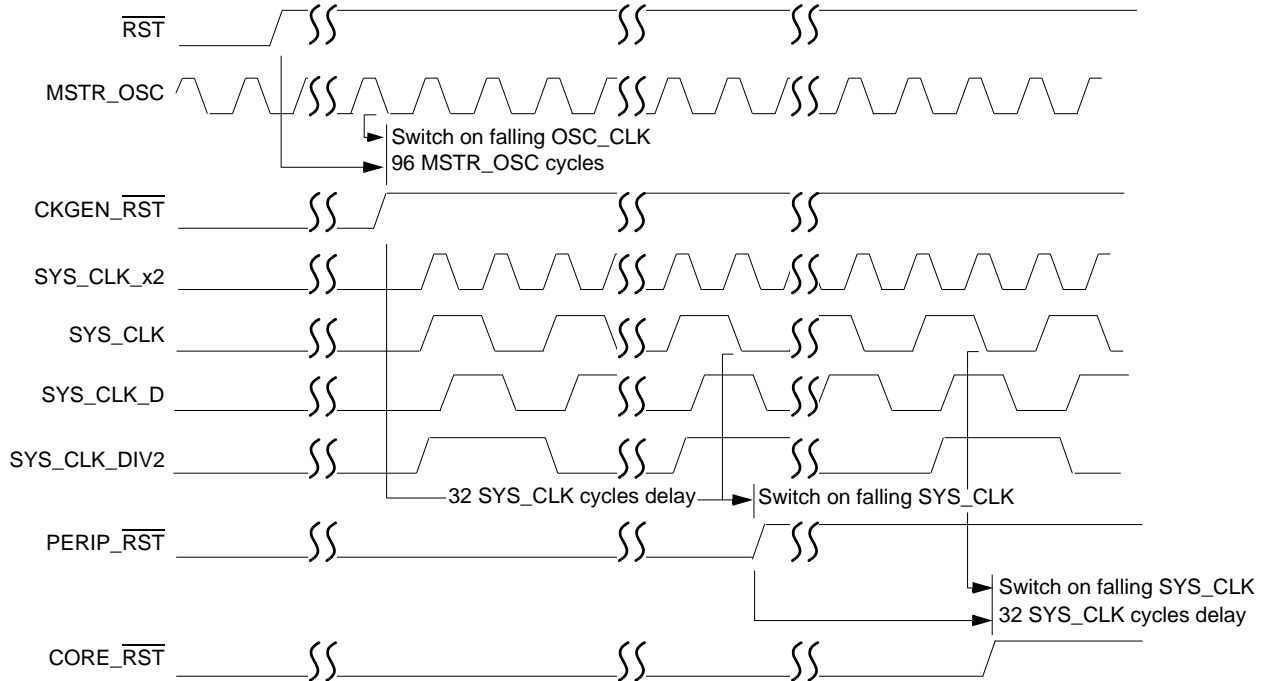


Figure 6-16 Timing Relationships of Reset Signal to Clocks

6.8 Interrupts

The SIM generates no interrupts.

Part 7 Security Features

The 56F8014 offers security features intended to prevent unauthorized users from reading the contents of the flash memory (FM) array. The 56F8014's flash security consists of several hardware interlocks that prevent unauthorized users from gaining access to the flash array.

After flash security is set, an authorized user is still able to access on-chip memory if the user purposely includes a subroutine to read and transfer the contents of internal memory via serial communication peripherals, as this code would defeat the purpose of security.

7.1 Operation with Security Enabled

After the user has programmed the flash with his application code, the 56F8014 can be secured by programming a security word (\$E70A) into program memory location \$00 1FF7. This nonvolatile word will keep the device secured through reset and through power-down of the device. Refer to the flash

memory chapter in *MC56F8000RM*, the 56F8000 Peripheral Reference Manual for details. When flash security mode is enabled, the 56F8014 will disable the core EOnCE debug capabilities. Normal program execution is otherwise unaffected.

7.2 Flash Access Lock and Unlock Mechanisms

There are several methods that effectively lock or unlock the on-chip flash.

7.2.1 Disabling EOnCE Access

On-chip flash can be read by issuing commands across the EOnCE port, which is the debug interface for the 56800E CPU. The TCK, TMS, TDO, and TDI pins comprise a JTAG interface onto which the EOnCE port functionality is mapped. When the device boots, the chip-level JTAG TAP (Test Access Port) is active and provides the chip's boundary scan capability and access to the ID register, but proper implementation of flash security will block any attempt to access the internal flash memory via the EOnCE port when security is enabled.

7.2.2 Flash Lockout Recovery Using JTAG

If the device is secured, one lockout recovery mechanism is the complete erasure of the internal flash contents, including the configuration field, thus disabling security (the protection register is cleared). This does not compromise security, as the entire contents of the user's secured code stored in flash are erased before security is disabled on the device on the next reset or power-up sequence.

To start the lockout recovery sequence via JTAG, the JTAG public instruction (LOCKOUT_RECOVERY) must first be shifted into the chip-level TAP controller's instruction register. Once the LOCKOUT_RECOVERY instruction has been shifted into the instruction register, the clock divider value must be shifted into the corresponding 7-bit data register. After the data register has been updated, the user must transition the TAP controller into the RUN-TEST/IDLE state for the lockout sequence to commence. The controller must remain in this state until the erase sequence has completed. Refer to *MC56F8000RM*, the 56F8000 Peripheral Reference Manual, for more details, or contact Freescale.

Note: Once the lockout recovery sequence has completed, the user must reset both the JTAG-TAP controller and the device to return to normal unsecured operation. Power-on reset will also reset both.

7.2.3 Flash Lockout Recovery Using CodeWarrior

CodeWarrior can unlock a device by selecting the Debug menu, then selecting DSP56800E, followed by Unlock Flash. Another mechanism is also built into CodeWarrior using the device's memory configuration file. The command `Unlock_Flash_on_Connect1` in the `.cfg` file accomplishes the same task as using the Debug menu.

This lockout recovery mechanism also includes the complete erasure of the internal flash contents, including the configuration field, thus disabling security (the protection register is cleared).

7.2.4 Flash Lockout Recovery Without Mass Erase

The user can un-secure a secured device by programming the word \$0000 into program memory location \$00 1FF7. After completing the programming, both the JTAG TAP controller and the device must be reset

in order to return to normal unsecured operation. Power-on reset will also reset both.

The user is responsible for directing the device to invoke the flash programming subroutine to reprogram the word \$0000 into program memory location \$00 1FF7. This is done by, for example, toggling a specific pin, or by downloading a user-defined key through serial interfaces.

Note: Flash contents can only be programmed for 1s to 0s.

7.3 Product Analysis

The recommended method of unsecuring a secured device for product analysis of field failures is via the method suggested in section 7.2.4. The customer would need to supply Technical Support with the details of the protocol to access the subroutines in flash. An alternative method for performing analysis on a secured device would be to mass-erase and reprogram the flash with the original code, but also either modify the security word or else not program the security word.

Part 8 General Purpose Input/Output (GPIO)

8.1 Introduction

This section is intended to supplement the GPIO information found in the **56F801X Peripheral Reference Manual** and contains only chip-specific information. This information supercedes the generic information in the **56F801X Peripheral Reference Manual**.

8.2 Configuration

There are four GPIO ports defined on the 56F8014. The width of each port, the associated peripheral and reset functions are shown in [Table 8-1](#). The specific mapping of GPIO port pins is shown in [Table 8-2](#).

Table 8-1 GPIO Ports Configuration

| GPIO Port | Available Pins in 56F8014 | Peripheral Function | Reset Function |
|-----------|---------------------------|---------------------|---------------------|
| A | 6 | PWM, Reset | GPIO, except GPIOA7 |
| B | 8 | SPI, SCI, Timer | GPIO |
| C | 8 | ADC | Analog |
| D | 4 | JTAG | JTAG |

Table 8-2 GPIO External Signals Map
Pins in shaded rows are not available in 56F8014

| GPIO Function | Peripheral Function | LQFP Package Pin | Notes |
|---------------|------------------------------|------------------|---|
| GPIOA0 | PWM0 | 28 | Defaults to A0 |
| GPIOA1 | PWM1 | 27 | Defaults to A1 |
| GPIOA2 | PWM2 | 23 | Defaults to A2 |
| GPIOA3 | PWM3 | | Not bonded out in 56F8014 Defaults to A3 |
| GPIOA4 | PWM4 / FAULT1 / T2 | 22 | SIM register SIM_GPS is used to select between PWM4, FAULT1, and T2 Defaults to A4 |
| GPIOA5 | PWM5 / FAULT2 / T3 | 20 | SIM register SIM_GPS is used to select between PWM5, FAULT2, and T3 Defaults to A5 |
| GPIOA6 | FAULT0 | | Not bonded out in 56F8014 Defaults to A6 |
| GPIOA7 | $\overline{\text{RESET}}$ | 16 | Defaults to $\overline{\text{RESET}}$ |
| GPIOB0 | SCLK / SCL | 21 | SIM register SIM_GPS is used to select between SCLK and SCL Defaults to B0 |
| GPIOB1 | $\overline{\text{SS}}$ / SDA | 1 | SIM register SIM_GPS is used to select between $\overline{\text{SS}}$ and SDA Defaults to B1 |
| GPIOB2 | MISO / T2 | 18 | SIM register SIM_GPS is used to select between MISO and T2 Defaults to B2 |
| GPIOB3 | MOSI / T3 | 17 | SIM register SIM_GPS is used to select between MOSI and T3 Defaults to B3 |
| GPIOB4 | T0 / CLKO | 19 | SIM register SIM_GPS is used to select between T0 and CLKO Defaults to B4 |
| GPIOB5 | T1 / FAULT3 | 3 | SIM register SIM_GPS is used to select between T1 and FAULT3 Defaults to B5 |

Table 8-2 GPIO External Signals Map (Continued)
Pins in shaded rows are not available in 56F8014

| GPIO Function | Peripheral Function | LQFP Package Pin | Notes |
|---------------|--------------------------|------------------|---|
| GPIOB6 | RXD / SDA / CLKIN | 32 | SIM register SIM_GPS is used to select between RXD and SDA. CLKIN functionality is enabled using the PLL Control Register within the OCCS block. Defaults to B6 |
| GPIOB7 | TXD / SCL | 2 | SIM register SIM_GPS is used to select between TXD and SCL. Defaults to B7 |
| GPIOC0 | ANA0 | 13 | Defaults to ANA0 |
| GPIOC1 | ANA1 | 12 | Defaults to ANA1 |
| GPIOC2 | ANA2 / V _{REFH} | 11 | Defaults to ANA2 |
| GPIOC3 | ANA3 | 10 | Defaults to ANA3 |
| GPIOC4 | ANB0 | 4 | Defaults to ANB0 |
| GPIOC5 | ANB1 | 5 | Defaults to ANB1 |
| GPIOC6 | ANB2 / V _{REFL} | 6 | Defaults to ANB2 |
| GPIOC7 | ANB3 | 7 | Defaults to ANB3 |
| GPIOD0 | TDI | 29 | Defaults to TDI |
| GPIOD1 | TDO | 31 | Defaults to TDO |
| GPIOD2 | TCK | 15 | Defaults to TCK |
| GPIOD3 | TMS | 30 | Defaults to TMS |

8.3 Reset Values

Tables 4-16 through 4-19 detail registers for the 56F8014; Figures 8-1 through 8-4 summarize register maps and reset values.

| Add. Offset | Register Acronym | | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 | |
|-------------|------------------|----|----|----|----|----|----|----|---|---|----------|---|---|---|---|---|---|---|---|
| \$0 | GPIOA_PUPEN | R | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | PU | | | | | | | | |
| | | W | | | | | | | | | | | | | | | | | |
| | | RS | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |
| \$1 | GPIOA_DATA | R | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | D | | | | | | | | |
| | | W | | | | | | | | | | | | | | | | | |
| | | RS | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |
| \$2 | GPIOA_DDIR | R | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | DD | | | | | | | | |
| | | W | | | | | | | | | | | | | | | | | |
| | | RS | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| \$3 | GPIOA_PEREN | R | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | PE | | | | | | | | |
| | | W | | | | | | | | | | | | | | | | | |
| | | RS | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 1 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| \$4 | GPIOA_IASSRT | R | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | IA | | | | | | | | |
| | | W | | | | | | | | | | | | | | | | | |
| | | RS | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| \$5 | GPIOA_IEN | R | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | IEN | | | | | | | | |
| | | W | | | | | | | | | | | | | | | | | |
| | | RS | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| \$6 | GPIOA_IEPOL | R | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | IEPOL | | | | | | | | |
| | | W | | | | | | | | | | | | | | | | | |
| | | RS | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| \$7 | GPIOA_IPEND | R | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | IPR | | | | | | | | |
| | | W | | | | | | | | | | | | | | | | | |
| | | RS | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| \$8 | GPIOA_IEDGE | R | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | IES | | | | | | | | |
| | | W | | | | | | | | | | | | | | | | | |
| | | RS | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| \$9 | GPIOA_PPOUTM | R | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | OEN | | | | | | | | |
| | | W | | | | | | | | | | | | | | | | | |
| | | RS | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |
| \$A | GPIOA_RDATA | R | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | RAW DATA | | | | | | | | |
| | | W | | | | | | | | | | | | | | | | | |
| | | RS | X | X | X | X | X | X | X | X | X | X | X | X | X | X | X | X | X |
| \$B | GPIOA_DRIVE | R | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | DRIVE | | | | | | | | |
| | | W | | | | | | | | | | | | | | | | | |
| | | RS | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

| | | |
|----|---|-----------|
| R | 0 | Read as 0 |
| W | | Reserved |
| RS | | Reset |

Figure 8-1 GPIOA Register Map Summary

| Add. Offset | Register Acronym | | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 | |
|-------------|------------------|----|----|----|----|----|----|----|---|---|----------|---|---|---|---|---|---|---|---|
| \$0 | GPIOB_PUPEN | R | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | PU | | | | | | | | |
| | | W | | | | | | | | | | | | | | | | | |
| | | RS | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |
| \$1 | GPIOB_DATA | R | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | D | | | | | | | | |
| | | W | | | | | | | | | | | | | | | | | |
| | | RS | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |
| \$2 | GPIOB_DDIR | R | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | DD | | | | | | | | |
| | | W | | | | | | | | | | | | | | | | | |
| | | RS | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| \$3 | GPIOB_PEREN | R | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | PE | | | | | | | | |
| | | W | | | | | | | | | | | | | | | | | |
| | | RS | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| \$4 | GPIOB_IASSRT | R | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | IA | | | | | | | | |
| | | W | | | | | | | | | | | | | | | | | |
| | | RS | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| \$5 | GPIOB_IEN | R | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | IEN | | | | | | | | |
| | | W | | | | | | | | | | | | | | | | | |
| | | RS | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| \$6 | GPIOB_IEPOL | R | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | IEPOL | | | | | | | | |
| | | W | | | | | | | | | | | | | | | | | |
| | | RS | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| \$7 | GPIOB_IPEND | R | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | IPR | | | | | | | | |
| | | W | | | | | | | | | | | | | | | | | |
| | | RS | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| \$8 | GPIOB_IEDGE | R | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | IES | | | | | | | | |
| | | W | | | | | | | | | | | | | | | | | |
| | | RS | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| \$9 | GPIOB_PPOUTM | R | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | OEN | | | | | | | | |
| | | W | | | | | | | | | | | | | | | | | |
| | | RS | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |
| \$A | GPIOB_RDATA | R | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | RAW DATA | | | | | | | | |
| | | W | | | | | | | | | | | | | | | | | |
| | | RS | X | X | X | X | X | X | X | X | X | X | X | X | X | X | X | X | X |
| \$B | GPIOB_DRIVE | R | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | DRIVE | | | | | | | | |
| | | W | | | | | | | | | | | | | | | | | |
| | | RS | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

| | | |
|----|---|-----------|
| R | 0 | Read as 0 |
| W | | Reserved |
| RS | | Reset |

Figure 8-2 GPIOB Register Map Summary

| Add. Offset | Register Acronym | | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 | |
|-------------|------------------|----|----|----|----|----|----|----|---|---|----------|---|---|---|---|---|---|---|---|
| \$0 | GPIOC_PUPEN | R | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | PU | | | | | | | | |
| | | W | | | | | | | | | | | | | | | | | |
| | | RS | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |
| \$1 | GPIOC_DATA | R | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | D | | | | | | | | |
| | | W | | | | | | | | | | | | | | | | | |
| | | RS | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| \$2 | GPIOC_DDIR | R | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | DD | | | | | | | | |
| | | W | | | | | | | | | | | | | | | | | |
| | | RS | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| \$3 | GPIOC_PEREN | R | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | PE | | | | | | | | |
| | | W | | | | | | | | | | | | | | | | | |
| | | RS | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |
| \$4 | GPIOC_IASSRT | R | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | IA | | | | | | | | |
| | | W | | | | | | | | | | | | | | | | | |
| | | RS | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| \$5 | GPIOC_IEN | R | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | IEN | | | | | | | | |
| | | W | | | | | | | | | | | | | | | | | |
| | | RS | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| \$6 | GPIOC_IEPOL | R | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | IEPOL | | | | | | | | |
| | | W | | | | | | | | | | | | | | | | | |
| | | RS | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| \$7 | GPIOC_IPEND | R | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | IPR | | | | | | | | |
| | | W | | | | | | | | | | | | | | | | | |
| | | RS | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| \$8 | GPIOC_IEDGE | R | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | IES | | | | | | | | |
| | | W | | | | | | | | | | | | | | | | | |
| | | RS | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| \$9 | GPIOC_PPOUTM | R | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | OEN | | | | | | | | |
| | | W | | | | | | | | | | | | | | | | | |
| | | RS | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |
| \$A | GPIOC_RDATA | R | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | RAW DATA | | | | | | | | |
| | | W | | | | | | | | | | | | | | | | | |
| | | RS | X | X | X | X | X | X | X | X | X | X | X | X | X | X | X | X | X |
| \$B | GPIOC_DRIVE | R | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | DRIVE | | | | | | | | |
| | | W | | | | | | | | | | | | | | | | | |
| | | RS | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

| | | |
|----|---|-----------|
| R | 0 | Read as 0 |
| W | | Reserved |
| RS | | Reset |

Figure 8-3 GPIOC Register Map Summary

| Add. Offset | Register Acronym | | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|-------------|------------------|----|----|----|----|----|----|----|---|---|---|---|---|----------|----|---|---|---|
| \$0 | GPIOD_PUPEN | R | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | PU | | | |
| | | W | | | | | | | | | | | | | | | | |
| | | RS | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 1 | 1 | 1 | 1 |
| \$1 | GPIOD_DATA | R | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | D | | | | |
| | | W | | | | | | | | | | | | | | | | |
| | | RS | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| \$2 | GPIOD_DDIR | R | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | DD | | | | |
| | | W | | | | | | | | | | | | | | | | |
| | | RS | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| \$3 | GPIOD_PEREN | R | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | PE | | | | |
| | | W | | | | | | | | | | | | | | | | |
| | | RS | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 1 | 1 | 1 | 1 |
| \$4 | GPIOD_IASSRT | R | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | IA | | | | |
| | | W | | | | | | | | | | | | | | | | |
| | | RS | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| \$5 | GPIOD_IEN | R | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | IEN | | | | |
| | | W | | | | | | | | | | | | | | | | |
| | | RS | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| \$6 | GPIOD_IEPOL | R | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | IEPOL | | | | |
| | | W | | | | | | | | | | | | | | | | |
| | | RS | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| \$7 | GPIOD_IPEND | R | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | IPR | | | | |
| | | W | | | | | | | | | | | | | | | | |
| | | RS | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| \$8 | GPIOD_IEDGE | R | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | IES | | | | |
| | | W | | | | | | | | | | | | | | | | |
| | | RS | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| \$9 | GPIOD_PPOUTM | R | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | OEN | | | | |
| | | W | | | | | | | | | | | | | | | | |
| | | RS | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 1 | 1 | 1 | 1 |
| \$A | GPIOD_RDATA | R | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | RAW DATA | | | | |
| | | W | | | | | | | | | | | | | | | | |
| | | RS | X | X | X | X | X | X | X | X | X | X | X | X | X | X | X | X |
| \$B | GPIOD_DRIVE | R | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | DRIVE | | | | |
| | | W | | | | | | | | | | | | | | | | |
| | | RS | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

| | | |
|---|---|-----------|
| R | 0 | Read as 0 |
| W | | Reserved |



Figure 8-4 GPIO Register Map Summary

Part 9 Joint Test Action Group (JTAG)

9.1 56F8014 Information

Please contact your Freescale sales representative or authorized distributor for device/package-specific BSDL information.

The $\overline{\text{TRST}}$ pin is not available in this package. The pin is tied to V_{DD} in the package.

The JTAG state machine is reset during POR and can also be reset via a soft reset by holding TMS high for five rising edges of TCK, as described in the **56F8000 Peripheral User Manual**.

Part 10 Specifications

10.1 General Characteristics

The 56F8014 is fabricated in high-density CMOS with 5V-tolerant TTL-compatible digital inputs. The term “5V-tolerant” refers to the capability of an I/O pin, built on a 3.3V-compatible process technology, to withstand a voltage up to 5.5V without damaging the device. Many systems have a mixture of devices designed for 3.3V and 5V power supplies. In such systems, a bus may carry both 3.3V- and 5V-compatible I/O voltage levels (a standard 3.3V I/O is designed to receive a maximum voltage of $3.3\text{V} \pm 10\%$ during normal operation without causing damage). This 5V-tolerant capability therefore offers the power savings of 3.3V I/O levels, combined with the ability to receive 5V levels without damage.

Absolute maximum ratings in **Table 10-1** are stress ratings only, and functional operation at the maximum is not guaranteed. Stress beyond these ratings may affect device reliability or cause permanent damage to the device.

Unless otherwise stated, all specifications within this chapter apply over the temperature range of -40°C to 125°C ambient temperature over the following supply ranges:

$$V_{\text{SS}} = V_{\text{SSA}} = 0\text{V}, V_{\text{DD}} = V_{\text{DDA}} = 3.0\text{--}3.6\text{V}, C_{\text{L}} \leq 50\text{pF}, f_{\text{OP}} = 32\text{MHz}$$

CAUTION

This device contains protective circuitry to guard against damage due to high static voltage or electrical fields. However, normal precautions are advised to avoid application of any voltages higher than maximum-rated voltages to this high-impedance circuit. Reliability of operation is enhanced if unused inputs are tied to an appropriate voltage level.

Table 10-1 Absolute Maximum Ratings

($V_{SS} = 0V$, $V_{SSA} = 0V$)

| Characteristic | Symbol | Notes | Min | Max | Unit |
|--|-----------------|-----------------|-------|-----|------|
| Supply Voltage Range | V_{DD} | | -0.3 | 4.0 | V |
| Analog Supply Voltage Range | V_{DDA} | | - 0.3 | 4.0 | V |
| ADC High Voltage Reference | V_{REFH} | | - 0.3 | 4.0 | V |
| Voltage difference V_{DD_IO} to V_{DDA} | ΔV_{DD} | | - 0.3 | 0.3 | V |
| Voltage difference V_{SS_IO} to V_{SSA} | ΔV_{SS} | | - 0.3 | 0.3 | V |
| Input Voltage Range (Digital inputs) | V_{IN} | Pin Groups 1, 2 | - 0.3 | 6.0 | V |
| Input Voltage Range (ADC inputs) ¹ | V_{INA} | Pin Group 3 | - 0.3 | 4.0 | V |
| Input clamp current, per pin ($V_{IN} < 0$) ² | V_{IC} | | - | -20 | mA |
| Output clamp current, per pin ($V_O < 0$) ² | V_{OC} | | - | -20 | mA |
| Output Voltage Range (Normal Push-Pull mode) | V_{OUT} | Pin Group 1 | -0.3 | 4.0 | V |
| Output Voltage Range (Open Drain mode) | V_{OUTOD} | Pin Groups 1, 2 | -0.3 | 6.0 | V |
| Ambient Temperature (Automotive) | T_A | | -40 | 125 | °C |
| Ambient Temperature (Industrial) | T_A | | -40 | 105 | °C |
| Junction Temperature (Automotive) | T_J | | -40 | 150 | °C |
| Junction Temperature (Industrial) | T_J | | -40 | 125 | °C |
| Storage Temperature (Automotive) | T_{STG} | | -55 | 150 | °C |
| Storage Temperature (Industrial) | T_{STG} | | -55 | 150 | °C |

1. Pin Group 3 can tolerate 6V for less than 5 seconds when they are configured as ADC inputs or during reset. Pin Group 3 can tolerate 6V if they are configured as GPIO.
2. Continuous input current per pin is -2 mA

Default Mode

Pin Group 1: GPIO, TDI, TDO, TMS, TCK

Pin Group 2: $\overline{\text{RESET}}$, GPIOA7

Pin Group 3: ADC analog inputs

10.1.1 ElectroStatic Discharge (ESD) Model**Table 10-2 56F8014 ESD Protection**

| Characteristic | Min | Typ | Max | Unit |
|-----------------------------------|------|-----|-----|------|
| ESD for Human Body Model (HBM) | 2000 | — | — | V |
| ESD for Machine Model (MM) | 200 | — | — | V |
| ESD for Charge Device Model (CDM) | 750 | — | — | V |

Table 10-3 LQFP Package Thermal Characteristics⁶

| Characteristic | Comments | Symbol | Value (LQFP) | Unit | Notes |
|---|----------------------------|------------------|--------------|------|-------|
| Junction to ambient Natural convection | Single layer board (1s) | $R_{\theta JA}$ | 74 | °C/W | 1,2 |
| Junction to ambient Natural convection | Four layer board (2s2p) | $R_{\theta JMA}$ | 50 | °C/W | 1,3 |
| Junction to ambient (@200 ft/min) | Single layer board (1s) | $R_{\theta JMA}$ | 67 | °C/W | 1,3 |
| Junction to ambient (@200 ft/min) | Four layer board (2s2p) | $R_{\theta JMA}$ | 46 | °C/W | 1,3 |
| Junction to board | | $R_{\theta JB}$ | 23 | °C/W | 4 |
| Junction to case | | $R_{\theta JC}$ | 20 | °C/W | 5 |
| Junction to package top | Natural Convection | Ψ_{JT} | 4 | °C/W | 6 |

1. Junction temperature is a function of die size, on-chip power dissipation, package thermal resistance, mounting site (board) temperature, ambient temperature, air flow, power dissipation of other components on the board, and board thermal resistance.
2. Per SEMI G38-87 and JEDEC JESD51-2 with the single layer board horizontal.
3. Per JEDEC JESD51-6 with the board horizontal.
4. Thermal resistance between the die and the printed circuit board per JEDEC JESD51-8. Board temperature is measured on the top surface of the board near the package.


- 
5. Thermal resistance between the die and the case top surface as measured by the cold plate method (MIL SPEC-883 Method 1012.1).
 6. Thermal characterization parameter indicating the temperature difference between package top and the junction temperature per JEDEC JESD51-2. When Greek letters are not available, the thermal characterization parameter is written as Psi-JT.
 7. See [Section 12.1](#) for more details on thermal design considerations.

Table 10-4 Recommended Operating Conditions $(V_{REFL} = 0V, V_{SSA} = 0V, V_{SS} = 0V)$

| Characteristic | Symbol | Notes | Min | Typ | Max | Unit |
|--|-----------------|---|--------|--------|-----------|--------|
| Supply voltage | V_{DD} | | 3 | 3.3 | 3.6 | V |
| ADC Supply voltage | V_{DDA} | | 3 | 3.3 | 3.6 | V |
| ADC High Voltage Reference | V_{REFH} | | 3 | — | V_{DDA} | V |
| Voltage difference V_{DD_IO} to V_{DDA} | ΔV_{DD} | | -0.1 | 0 | 0.1 | V |
| Voltage difference V_{SS_IO} to V_{SSA} | ΔV_{SS} | | -0.1 | 0 | 0.1 | V |
| Device Clock Frequency Using relaxation oscillator Using external clock source | FSYSCLK | | 8 0 | — | 32 32 | MHz |
| Input Voltage High (digital inputs) | V_{IH} | Pin Groups 1, 2 | 2 | — | 5.5 | V |
| Input Voltage Low (digital inputs) | V_{IL} | Pin Groups 1, 2 | -0.3 | — | 0.8 | V |
| Output Source Current High (at V_{OH} min.) When programmed for low drive strength When programmed for high drive strength | I_{OH} | Pin Group 1 Pin Group 1 | — — | — — | -4 -8 | mA |
| Output Source Current Low (at V_{OL} max.) When programmed for low drive strength When programmed for high drive strength | I_{OL} | Pin Groups 1, 2 Pin Groups 1, 2 | — — | — — | 4 8 | mA |
| Ambient Operating Temperature (Automotive) | T_A | | -40 | — | 125 | °C |
| Ambient Operating Temperature (Industrial) | T_A | | -40 | — | 105 | °C |
| Flash Endurance (Automotive) (Program Erase Cycles) | N_F | $T_A = -40^{\circ}\text{C}$ to 125°C | 10,000 | — | — | Cycles |
| Flash Endurance (Industrial) (Program Erase Cycles) | N_F | $T_A = -40^{\circ}\text{C}$ to 105°C | 10,000 | — | — | Cycles |
| Flash Data Retention | T_R | $T_J \leq 85^{\circ}\text{C}$ avg | 15 | — | — | Years |
| Flash Data Retention with <100 Program/Erase Cycles | t_{FLRET} | $T_J \leq 85^{\circ}\text{C}$ avg | 20 | — | — | Years |

Note: Total chip source or sink current cannot exceed 50mA

Default Mode

Pin Group 1: GPIO, TDI, TDO, TMS, TCK

Pin Group 2: $\overline{\text{RESET}}$, GPIOA7

Pin Group 3: ADC analog inputs

10.2 DC Electrical Characteristics

Table 10-5 DC Electrical Characteristics
At Recommended Operating Conditions

| Characteristic | Symbol | Notes | Min | Typ | Max | Unit | Test Conditions |
|---|-----------|-----------------|----------|----------|----------------|---------|-----------------------------------|
| Output Voltage High | V_{OH} | Pin Group 1 | 2.4 | — | — | V | $I_{OH} = I_{OHmax}$ |
| Output Voltage Low | V_{OL} | Pin Groups 1, 2 | — | — | 0.4 | V | $I_{OL} = I_{OLmax}$ |
| Digital Input Current High pull-up enabled or disabled ¹ | I_{IH} | Pin Groups 1, 2 | — | 0 | +/- 2.5 | μA | $V_{IN} = 2.4V$ to 5.5V |
| Digital Input Current Low pull-up enabled pull-up disabled ¹ | I_{IL} | Pin Groups 1, 2 | -15 — | -30 0 | -60 +/- 2.5 | μA | $V_{IN} = 0V$ |
| Output Current High Impedance State ¹ | I_{OZ} | Pin Groups 1, 2 | — | 0 | +/- 2.5 | μA | $V_{OUT} = 2.4V$ to 5.5V or 0V |
| Schmitt Trigger Input Hysteresis | V_{HYS} | Pin Groups 1, 2 | — | 0.35 | — | V | — |
| Input Capacitance | C_{IN} | | — | 10 | — | pF | — |
| Output Capacitance | C_{OUT} | | — | 10 | — | pF | — |

1. See [Figure 10-1](#)

Default Mode

Pin Group 1: GPIO, TDI, TDO, TMS, TCK

Pin Group 2: \overline{RESET} , GPIOA7

Pin Group 3: ADC analog inputs

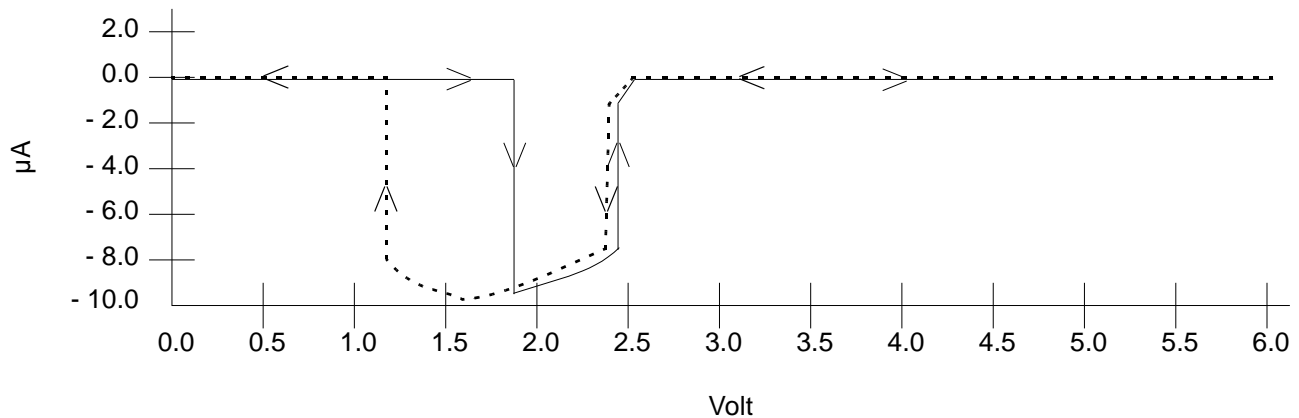


Figure 10-1 I_{IN}/I_{OZ} vs. V_{IN} (Typical; Pull-Up Disabled)

Table 10-6 Current Consumption per Power Supply Pin (Typical)

| Mode | Conditions | Typical @ 3.3V, 25°C | | Maximum @ 3.6V, 25°C | |
|----------------|--|------------------------------|------------------|------------------------------|------------------|
| | | I _{DD} ¹ | I _{DDA} | I _{DD} ¹ | I _{DDA} |
| RUN | 32MHz Device Clock Relaxation Oscillator on PLL powered on Continuous MAC instructions with fetches from Program Flash All peripheral modules enabled. Quad Timer and PWM using 1x Clock ADC powered on and clocked | 42mA | 13.5mA | — | — |
| WAIT | 32MHz Device Clock Relaxation Oscillator on PLL powered on Processor Core in WAIT state All Peripheral modules enabled. Quad Timer and PWM using 1x Clock ADC powered off | 17mA | 0μA | — | — |
| STOP | 4MHz Device Clock Relaxation Oscillator on PLL powered off Processor Core in STOP state All peripheral module and core clocks are off ADC powered off | 5mA | 0μA | — | — |
| STANDBY > STOP | 100KHz Device Clock Relaxation Oscillator in Standby mode PLL powered off Processor Core in STOP state All peripheral module and core clocks are off ADC powered off Voltage regulator in Standby mode | 430μA | 0μA | 550μA | 1μA |
| POWERDOWN | Device Clock is off Relaxation Oscillator powered off PLL powered off Processor Core in STOP state All peripheral module and core clocks are off ADC powered off Voltage Regulator in Standby mode | 300μA | 0μA | 400μA | 1μA |

1. No Output Switching
All ports configured as inputs
All inputs Low
No DC Loads

Table 10-7 Power-On Reset Low-Voltage Parameters

| Characteristic | Symbol | Min | Typ | Max | Unit |
|--|-------------|------|------|-----|------|
| Low-Voltage Interrupt for 3.3V supply ¹ | $V_{EI3.3}$ | 2.60 | 2.7 | — | V |
| Low-Voltage Interrupt for 2.5V supply ² | $V_{EI2.5}$ | 2.05 | 2.15 | — | V |
| Low-Voltage Interrupt Recovery Hysteresis | V_{EIH} | — | 50 | — | mV |
| Power-On Reset ³ | POR | — | 1.8 | 1.9 | V |

1. When V_{DD} drops below $V_{EI3.3}$, an interrupt is generated.

2. When V_{DD} drops below $V_{EI2.5}$, an interrupt is generated.

3. Power-On Reset occurs whenever the internally regulated 2.5V digital supply drops below 1.8V. While power is ramping up, this signal remains active for as long as the internal 2.5V is below 2.15V or the 3.3V I/O voltage is below 2.7V, no matter how long the ramp-up rate is. The internally regulated voltage is typically 100mV less than V_{DD} during ramp-up until 2.5V is reached, at which time it self-regulates.

10.2.1 Voltage Regulator Specifications

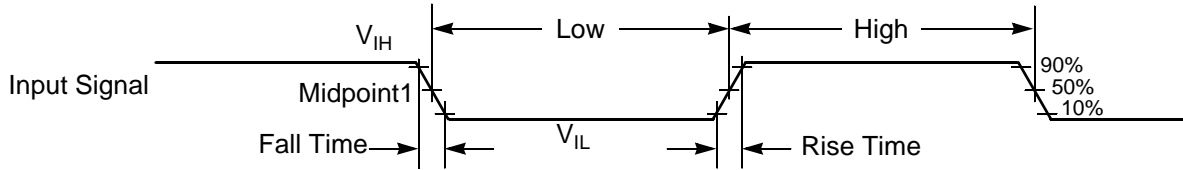
The 56F8014 has two on-chip regulators. One supplies the PLL and relaxation oscillator. It has no external pins and therefore has no external characteristics which must be guaranteed (other than proper operation of the device). The second regulator supplies approximately 2.5 V to the 56F8014's core logic. This regulator requires an external 2.2 μ F, or greater, capacitor for proper operation. Ceramic and tantalum capacitors tend to provide better performance tolerances. The output voltage can be measured directly on the V_{CAP} pin. The specifications for this regulator are shown in [Table 10-8](#).

Table 10-8. Regulator Parameters

| Characteristic | Symbol | Min | Typical | Max | Unit |
|---|-----------|------|---------|------|---------|
| Input Voltage | V_{IN} | 3.0 | — | 3.6 | V |
| Output Voltage | V_{OUT} | 2.25 | 2.5 | 2.75 | V |
| Short Circuit Current | I_{SS} | — | 450 | 650 | mA |
| Short Circuit Tolerance (output shorted to ground) | T_{RSC} | — | — | 30 | Minutes |

10.3 AC Electrical Characteristics

Tests are conducted using the input levels specified in [Table 10-5](#). Unless otherwise specified, propagation delays are measured from the 50% to the 50% point, and rise and fall times are measured between the 10% and 90% points, as shown in [Figure 10-2](#).



Note: The midpoint is $V_{IL} + (V_{IH} - V_{IL})/2$.

Figure 10-2 Input Signal Measurement References

Figure 10-3 shows the definitions of the following signal states:

- Active state, when a bus or signal is driven, and enters a low impedance state
- Tri-stated, when a bus or signal is placed in a high impedance state
- Data Valid state, when a signal level has reached V_{OL} or V_{OH}
- Data Invalid state, when a signal level is in transition between V_{OL} and V_{OH}

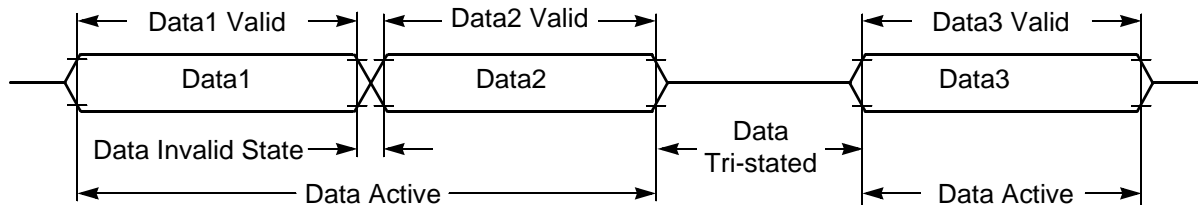


Figure 10-3 Signal States

10.4 Flash Memory Characteristics

Table 10-9 Flash Timing Parameters

| Characteristic | Symbol | Min | Typ | Max | Unit |
|---------------------------|-------------|-----|-----|-----|---------|
| Program time ¹ | T_{prog} | 20 | — | 40 | μs |
| Erase time ² | T_{erase} | 20 | — | — | ms |
| Mass erase time | T_{me} | 100 | — | — | ms |

1. There is additional overhead which is part of the programming sequence. See the **56F801X Peripheral Reference Manual** for details.

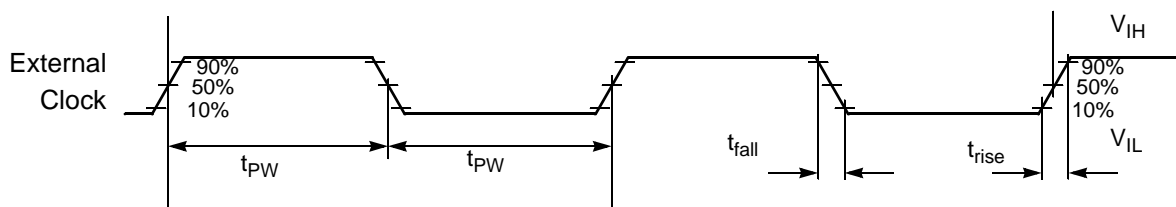
2. Specifies page erase time. There are 512 bytes per page in the Program Flash memory.

10.5 External Clock Operation Timing

Table 10-10 External Clock Operation Timing Requirements¹

| Characteristic | Symbol | Min | Typ | Max | Unit |
|---|------------|------|-----|-----|------|
| Frequency of operation (external clock driver) ² | f_{osc} | 4 | 8 | 8 | MHz |
| Clock Pulse Width ³ | t_{PW} | 6.25 | — | — | ns |
| External Clock Input Rise Time ⁴ | t_{rise} | — | — | 3 | ns |
| External Clock Input Fall Time ⁵ | t_{fall} | — | — | 3 | ns |

- Parameters listed are guaranteed by design.
- See [Figure 10-4](#) for details on using the recommended connection of an external clock driver.
- The high or low pulse width must be no smaller than 6.25ns or the chip may not function.
- External clock input rise time is measured from 10% to 90%.
- External clock input fall time is measured from 90% to 10%.



Note: The midpoint is $V_{IL} + (V_{IH} - V_{IL})/2$.

Figure 10-4 External Clock Timing

10.6 Phase Locked Loop Timing

Table 10-11 PLL Timing

| Characteristic | Symbol | Min | Typ | Max | Unit |
|--|-----------------|-----|-----|-----|---------|
| Internal reference relaxation oscillator frequency for the PLL | f_{rosc} | — | 8 | — | MHz |
| PLL output frequency ¹ (24 x reference frequency) | f_{op} | — | 192 | — | MHz |
| PLL lock time ² | t_{lock} | — | 40 | 100 | μ s |
| Cycle to cycle jitter | $t_{jitterpll}$ | | 350 | | ps |

- The core system clock will operate at 1/6 of the PLL output frequency.
- This is the time required after the PLL is enabled to ensure reliable operation.

10.7 Relaxation Oscillator Timing

Table 10-12 Relaxation Oscillator Timing

| Characteristic | Symbol | Minimum | Typical | Maximum | Unit |
|--|-----------------|---------|--------------|--------------|------------|
| Relaxation Oscillator output frequency Normal Mode ¹ Standby Mode | f_{op} | — | 8.05 200 | — | MHz kHz |
| Relaxation Oscillator stabilization time ² | t_{roscs} | — | 1 | 3 | μ s |
| Cycle-to-cycle jitter. This is measured on the CLKO signal (programmed prescaler_clock) over 264 clocks ³ | $t_{jitterosc}$ | — | 400 | | ps |
| Minimum tuning step size | | | .08 | | % |
| Maximum tuning step size | | | 40 | | % |
| Variation over temperature -40°C to 150°C ⁴ | | | +1.0 to -1.5 | +3.0 to -3.0 | % |
| Variation over temperature 0°C to 105°C ⁴ | | | 0 to +1 | +2.0 to -2.0 | % |

1. Output frequency after factory trim.
2. This is the time required from standby to normal mode transition.
3. J_A is required to meet SCI requirements.
4. See [Figure 10-5](#).

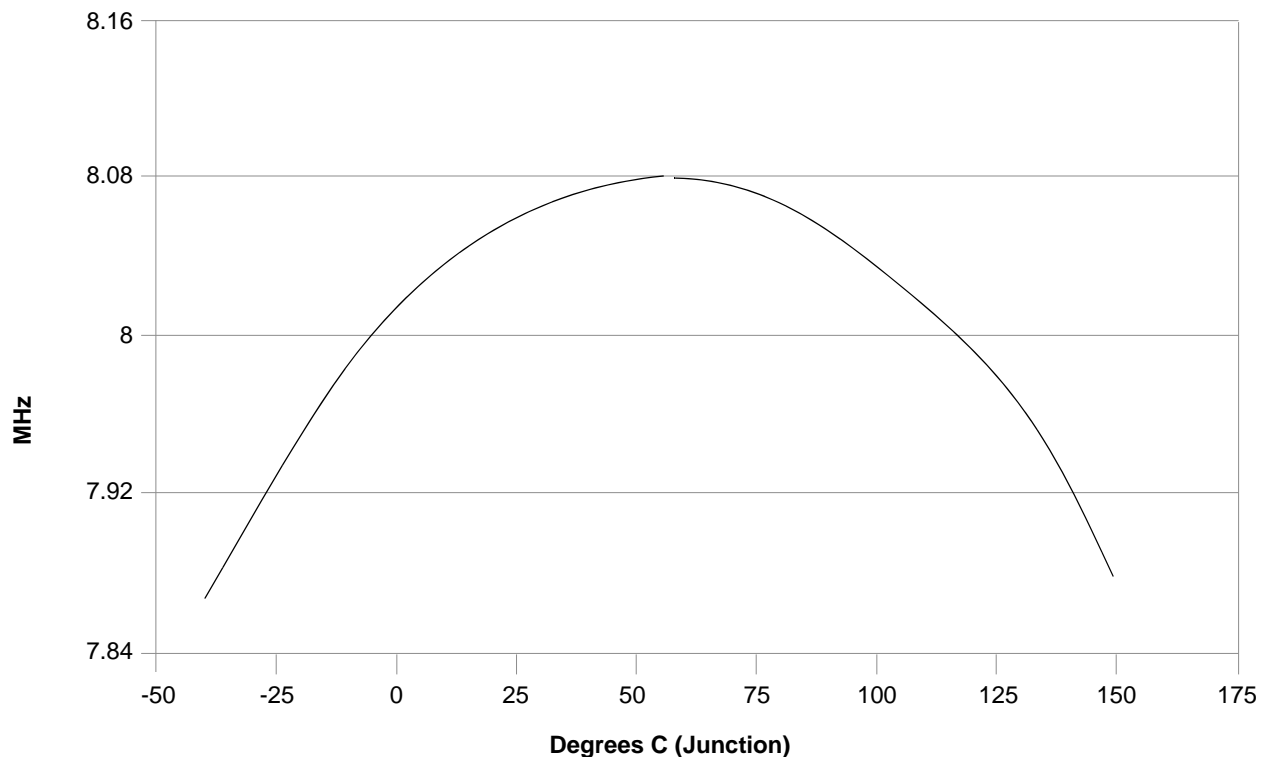


Figure 10-5 Relaxation Oscillator Temperature Variation (Typical) After Trim

10.8 Reset, Stop, Wait, Mode Select, and Interrupt Timing

Note: All the address and data buses described here are internal.

Table 10-13 Reset, Stop, Wait, Mode Select, and Interrupt Timing^{1,2}

| Characteristic | Symbol | Typical Min | Typical Max | Unit | See Figure |
|---|------------------|--------------------------|--------------------------|------|-------------|
| Minimum $\overline{\text{RESET}}$ Assertion Duration | t_{RA} | 4T | — | ns | |
| Minimum GPIO pin Assertion for Interrupt | t_{IW} | 2T | — | ns | 10-6 |
| $\overline{\text{RESET}}$ deassertion to First Address Fetch ³ | t_{RDA} | $96T_{\text{OSC}} + 64T$ | $97T_{\text{OSC}} + 65T$ | ns | |
| Delay from Interrupt Assertion to Fetch of first instruction (exiting Stop) | t_{IF} | — | 6T | ns | |

1. In the formulas, T = clock cycle and T_{OSC} = oscillator clock cycle. For an operating frequency of 32MHz, T = 31.25ns. At 8MHz (used during Reset and Stop modes), T = 125ns.

2. Parameters listed are guaranteed by design.

3. During Power-On Reset, it is possible to use the 56F8014 internal reset stretching circuitry to extend this period to $2^{\wedge}21T$.

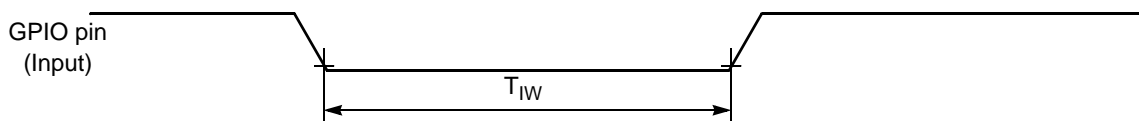


Figure 10-6 GPIO Interrupt Timing (Negative Edge-Sensitive)

10.9 Serial Peripheral Interface (SPI) Timing

Table 10-14 SPI Timing¹

| Characteristic | Symbol | Min | Max | Unit | See Figure |
|---|-----------|-------------|--------------|----------|----------------------------|
| Cycle time Master Slave | t_C | 125 62.5 | — — | ns ns | 10-7, 10-8, 10-9, 10-10 |
| Enable lead time Master Slave | t_{ELD} | — 31 | — — | ns ns | 10-10 |
| Enable lag time Master Slave | t_{ELG} | — 125 | — — | ns ns | 10-10 |
| Clock (SCK) high time Master Slave | t_{CH} | 50 31 | — — | ns ns | 10-7, 10-8, 10-9, 10-10 |
| Clock (SCK) low time Master Slave | t_{CL} | 50 31 | — — | ns ns | 10-10 |
| Data set-up time required for inputs Master Slave | t_{DS} | 20 0 | — — | ns ns | 10-7, 10-8, 10-9, 10-10 |
| Data hold time required for inputs Master Slave | t_{DH} | 0 2 | — — | ns ns | 10-7, 10-8, 10-9, 10-10 |
| Access time (time to data active from high-impedance state) Slave | t_A | 4.8 | 15 | ns | 10-10 |
| Disable time (hold time to high-impedance state) Slave | t_D | 3.7 | 15.2 | ns | 10-10 |
| Data Valid for outputs Master Slave (after enable edge) | t_{DV} | — — | 4.5 20.4 | ns ns | 10-7, 10-8, 10-9, 10-10 |
| Data invalid Master Slave | t_{DI} | 0 0 | — — | ns ns | 10-7, 10-8, 10-9, 10-10 |
| Rise time Master Slave | t_R | — — | 11.5 10.0 | ns ns | 10-7, 10-8, 10-9, 10-10 |
| Fall time Master Slave | t_F | — — | 9.7 9.0 | ns ns | 10-7, 10-8, 10-9, 10-10 |

1. Parameters listed are guaranteed by design.

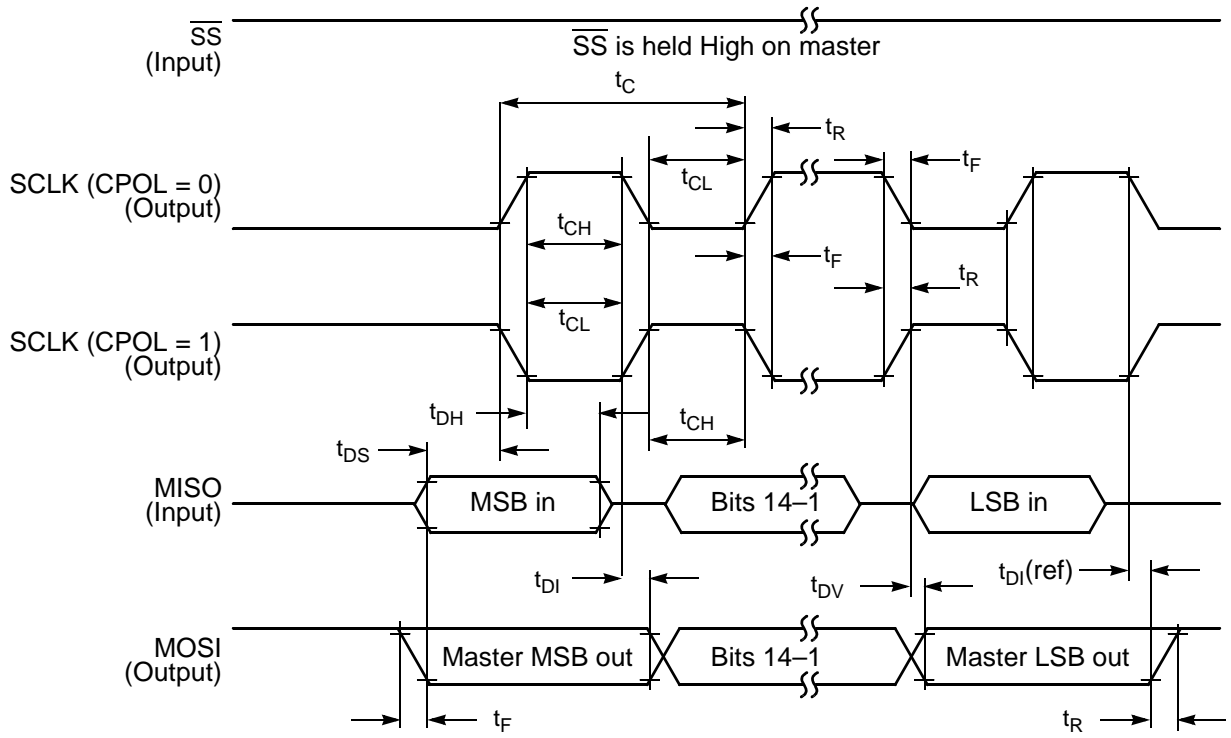


Figure 10-7 SPI Master Timing (CPHA = 0)

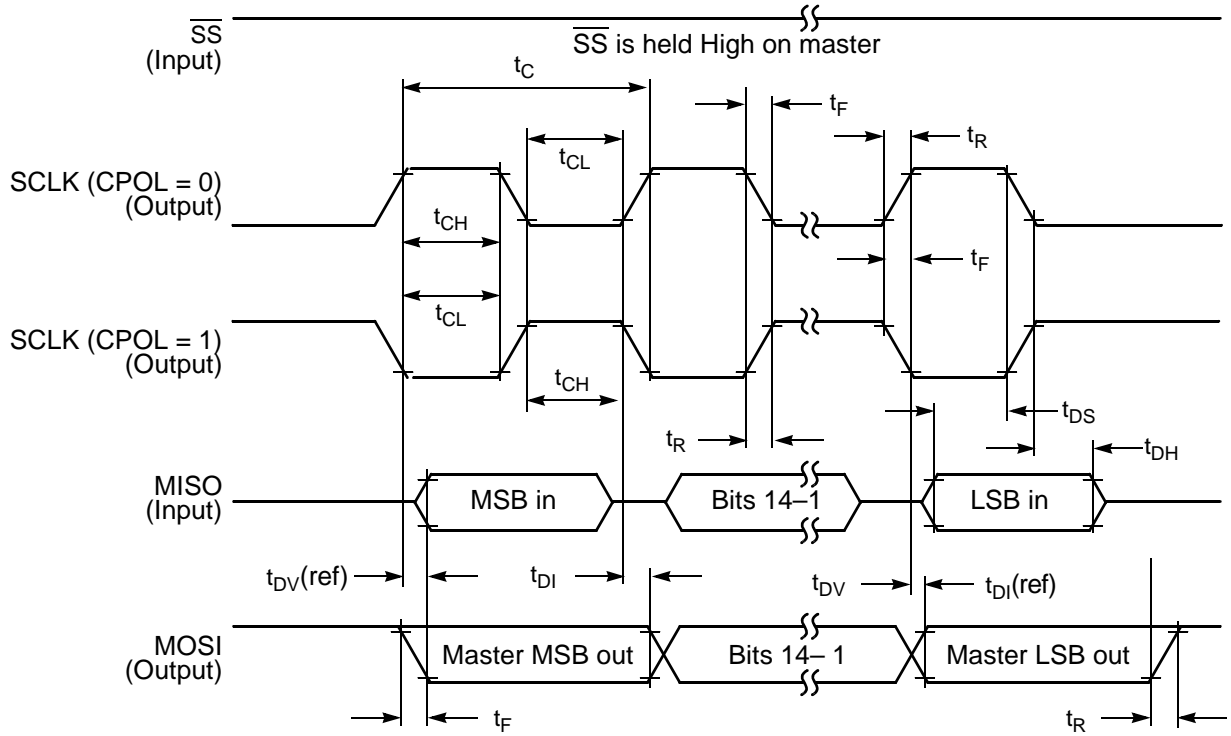


Figure 10-8 SPI Master Timing (CPHA = 1)

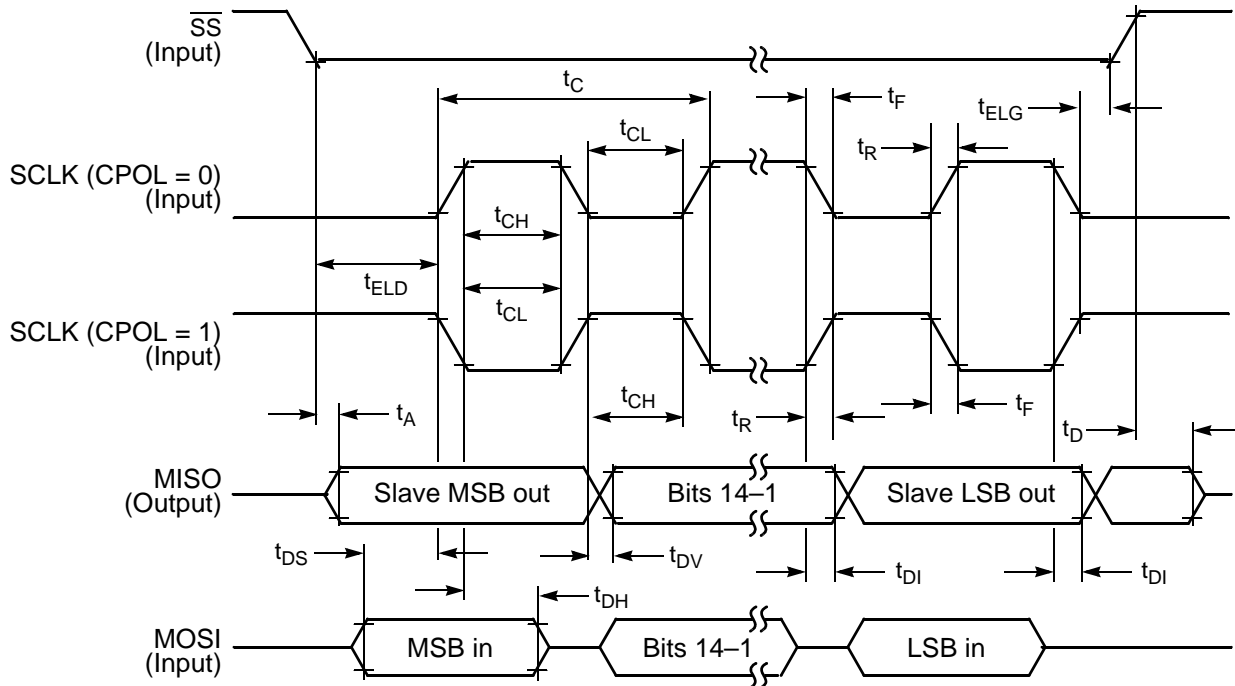


Figure 10-9 SPI Slave Timing (CPHA = 0)

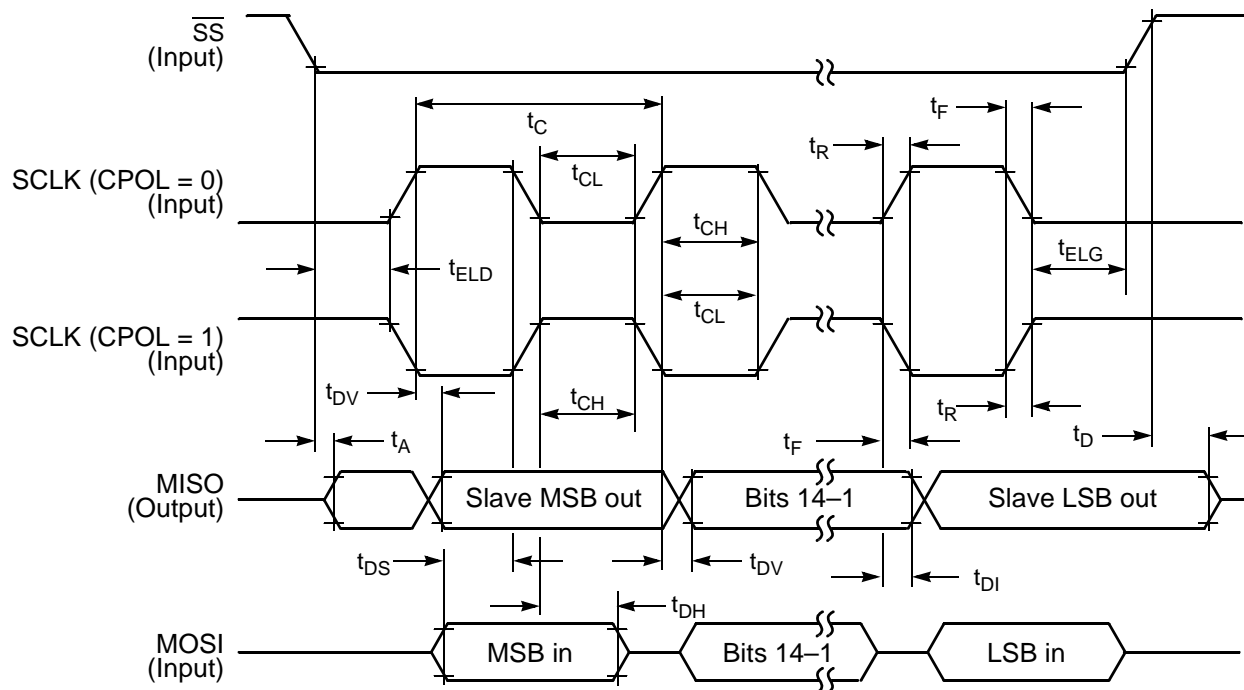


Figure 10-10 SPI Slave Timing (CPHA = 1)

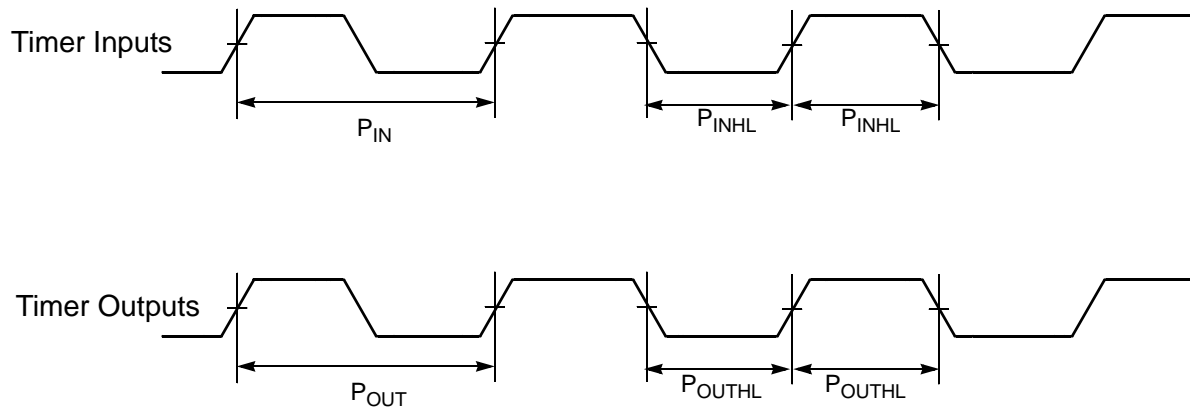
10.10 Quad Timer Timing

Table 10-15 Timer Timing^{1, 2}

| Characteristic | Symbol | Min | Max | Unit | See Figure |
|--------------------------------|-------------|----------|-----|------|------------|
| Timer input period | P_{IN} | $2T + 6$ | — | ns | 10-11 |
| Timer input high / low period | P_{INHL} | $1T + 3$ | — | ns | 10-11 |
| Timer output period | P_{OUT} | 125 | — | ns | 10-11 |
| Timer output high / low period | P_{OUTHL} | 50 | — | ns | 10-11 |

1. In the formulas listed, T = the clock cycle. For 32MHz operation, T = 31.25ns.

2. Parameters listed are guaranteed by design.

**Figure 10-11 Timer Timing**

10.11 Serial Communication Interface (SCI) Timing

Table 10-16 SCI Timing¹

| Characteristic | Symbol | Min | Max | Unit | See Figure |
|---|--------------------------|----------|------------------|-------------------------|-----------------------|
| Baud Rate ² | BR | — | ($f_{MAX}/16$) | Mbps | — |
| RXD ³ Pulse Width | RXD _{PW} | 0.965/BR | 1.04/BR | ns | 10-12 |
| TXD ⁴ Pulse Width | TXD _{PW} | 0.965/BR | 1.04/BR | ns | 10-13 |
| LIN Slave Mode | | | | | |
| Deviation of slave node clock from nominal clock rate before synchronization | F _{TOL_UNSYNCH} | -14 | 14 | % | |
| Deviation of slave node clock relative to the master node clock after synchronization | F _{TOL_SYNCH} | -2 | 2 | % | |
| Minimum break character length | T _{BREAK} | 13 | | Master node bit periods | |
| | | 11 | | Slave node bit periods | |

1. Parameters listed are guaranteed by design.

2. f_{MAX} is the frequency of operation of the system clock in MHz, which is 32MHz for the 56F8014 device.

3. The RXD pin in SCI0 is named RXD0 and the RXD pin in SCI1 is named RXD1.

4. The TXD pin in SCI0 is named TXD0 and the TXD pin in SCI1 is named TXD1.



Figure 10-12 RXD Pulse Width



Figure 10-13 TXD Pulse Width

10.12 Inter-Integrated Circuit Interface (I²C) Timing

Table 10-17 I²C Timing

| Characteristic | Symbol | Standard Mode | | Fast Mode | | Unit |
|---|---------------|----------------|-------------------|------------------|------------------|---------|
| | | Minimum | Maximum | Minimum | Maximum | |
| SCL Clock Frequency | f_{SCL} | 0 | 100 | 0 | 400 | kHz |
| Hold time (repeated) START condition. After this period, the first clock pulse is generated. | $t_{HD; STA}$ | 4.0 | | 0.6 | | μs |
| LOW period of the SCL clock | t_{LOW} | 4.7 | | 1.25 | | μs |
| HIGH period of the SCL clock | t_{HIGH} | 4.0 | | 0.6 | | μs |
| Set-up time for a repeated START condition | $t_{SU; STA}$ | 4.7 | | 0.6 | | μs |
| Data hold time for I ² C bus devices | $t_{HD; DAT}$ | 0 ¹ | 3.45 ² | 0 ¹ | 0.9 ² | μs |
| Data set-up time | $t_{SU; DAT}$ | 250 | | 100 ³ | | ns |
| Rise time of both SDA and SCL signals | t_r | | 1000 | $2 + 0.1C_b^4$ | 300 | ns |
| Fall time of both SDA and SCL signals | t_f | | 300 | $2 + 0.1C_b^4$ | 300 | ns |
| Set-up time for STOP condition | $t_{SU; STO}$ | 4.0 | | 0.6 | | μs |
| Bus free time between STOP and START condition | t_{BUF} | 4.7 | | 1.3 | | μs |
| Pulse width of spikes that must be suppressed by the input filter | t_{SP} | N/A | N/A | 0.0 | 50 | ns |

1. A device must internally provide a hold time of at least 300ns for the SDA signal (referred to the V_{IH} min of the SCL signal) to bridge the undefined region of the falling edge of SCL.
2. The maximum $t_{HD; DAT}$ has only to be met if the device does not stretch the LOW period (t_{LOW}) of the SCL signal.
3. A Fast mode I²C bus device can be used in a Standard mode I²C bus system, but the requirement $t_{SU; DAT} \geq 250ns$ must then be met. This will automatically be the case if the device does not stretch the LOW period of the SCL signal. If such a device does stretch the LOW period of the SCL signal, it must output the next data bit to the SDA line
 $t_{rmax} + t_{SU; DAT} = 1000 + 250 = 1250ns$ (according to the Standard mode I²C bus specification) before the SCL line is released.
4. C_b = total capacitance of the one bus line in pF.

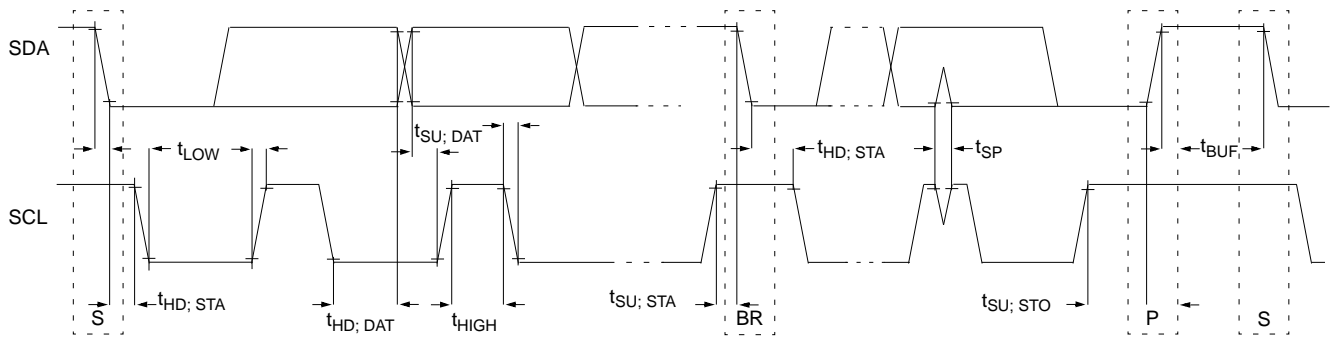


Figure 10-14 Timing Definition for Fast and Standard Mode Devices on the I²C Bus

10.13 JTAG Timing

Table 10-18 JTAG Timing

| Characteristic | Symbol | Min | Max | Unit | See Figure |
|---|----------|-----|-----------|------|------------|
| TCK frequency of operation ¹ | f_{OP} | DC | SYS_CLK/8 | MHz | 10-15 |
| TCK clock pulse width | t_{PW} | 50 | — | ns | 10-15 |
| TMS, TDI data set-up time | t_{DS} | 5 | — | ns | 10-16 |
| TMS, TDI data hold time | t_{DH} | 5 | — | ns | 10-16 |
| TCK low to TDO data valid | t_{DV} | — | 30 | ns | 10-16 |
| TCK low to TDO tri-state | t_{TS} | — | 30 | ns | 10-16 |

1. TCK frequency of operation must be less than 1/8 the processor rate.

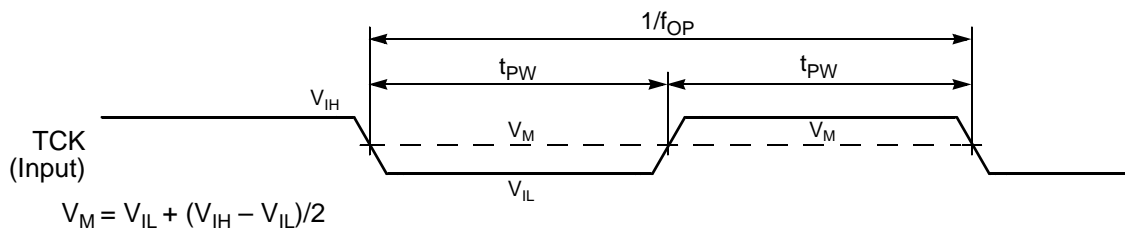


Figure 10-15 Test Clock Input Timing Diagram

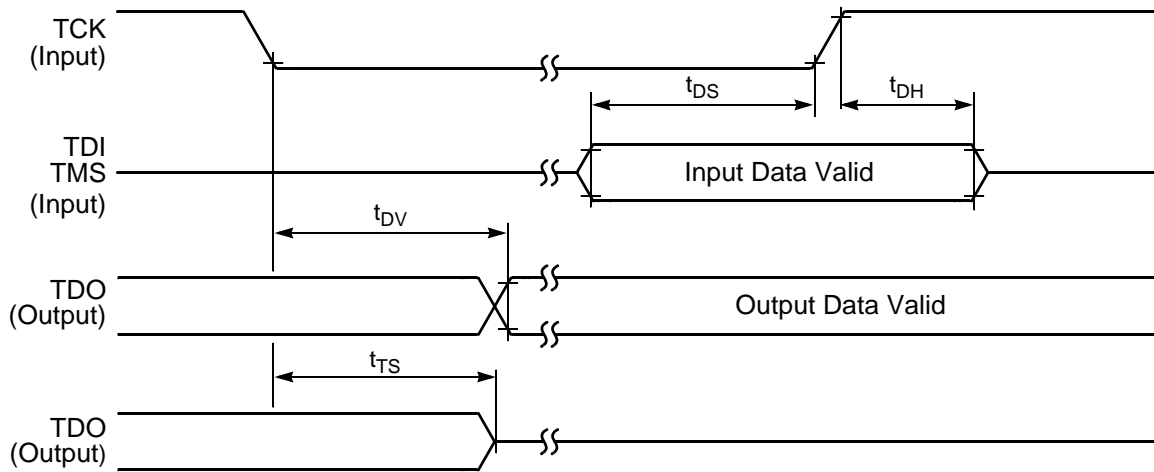


Figure 10-16 Test Access Port Timing Diagram

10.14 Analog-to-Digital Converter (ADC) Parameters

Table 10-19 ADC Parameters¹

| Parameter | Symbol | Min | Typ | Max | Unit |
|--|---------------------|-------------------|----------------------------------|-------------------|--------------------------------------|
| DC Specifications | | | | | |
| Resolution | R _{ES} | 12 | — | 12 | Bits |
| ADC internal clock | f _{ADIC} | 0.1 | — | 5.33 | MHz |
| Conversion range | R _{AD} | V _{REFL} | — | V _{REFH} | V |
| ADC power-up time ² | t _{ADPU} | — | 6 | 13 | t _{AIC} cycles ³ |
| Recovery from auto standby | t _{REC} | — | 0 | 1 | t _{AIC} cycles ³ |
| Conversion time | t _{ADC} | — | 6 | — | t _{AIC} cycles ³ |
| Sample time | t _{ADS} | — | 1 | — | t _{AIC} cycles ³ |
| Accuracy | | | | | |
| Integral non-linearity ⁴ (Full input signal range) | INL | — | +/- 3 | +/- 5 | LSB ⁵ |
| Differential non-linearity | DNL | — | +/- .6 | +/- 1 | LSB ⁵ |
| Monotonicity | GUARANTEED | | | | |
| Offset Voltage Internal Ref | V _{OFFSET} | — | +/- 4 | +/- 9 | mV |
| Offset Voltage External Ref | V _{OFFSET} | — | +/- 6 | +/- 12 | mV |
| Gain Error (transfer gain) | E _{GAIN} | — | .998 to 1.002 | 1.01 to .99 | — |
| ADC Inputs⁶ (Pin Group 3) | | | | | |
| Input voltage (external reference) | V _{ADIN} | V _{REFL} | — | V _{REFH} | V |
| Input voltage (internal reference) | V _{ADIN} | V _{SSA} | — | V _{DDA} | V |
| Input leakage | I _{IA} | — | 0 | +/- 2 | μA |
| V _{REFH} current | I _{VREFH} | — | 0 | — | μA |
| Input injection current ⁷ , per pin | I _{ADI} | — | — | 3 | mA |
| Input capacitance | C _{ADI} | — | See Figure 10-17 | — | pF |
| Input impedance | X _{IN} | — | See Figure 10-17 | — | Ohms |
| AC Specifications | | | | | |
| Signal-to-noise ratio | SNR | 60 | 65 | | dB |
| Total Harmonic Distortion | THD | 60 | 64 | | dB |
| Spurious Free Dynamic Range | SFDR | 61 | 66 | | dB |
| Signal-to-noise plus distortion | SINAD | 58 | 62 | | dB |
| Effective Number Of Bits | ENOB | — | 10.0 | | Bits |

1. All measurements were made at V_{DD} = 3.3V, V_{REFH} = 3.3V, and V_{REFL} = ground

2. Includes power-up of ADC and V_{REF}

3. ADC clock cycles

4. INL measured from V_{IN} = V_{REFL} to V_{IN} = V_{REFH}

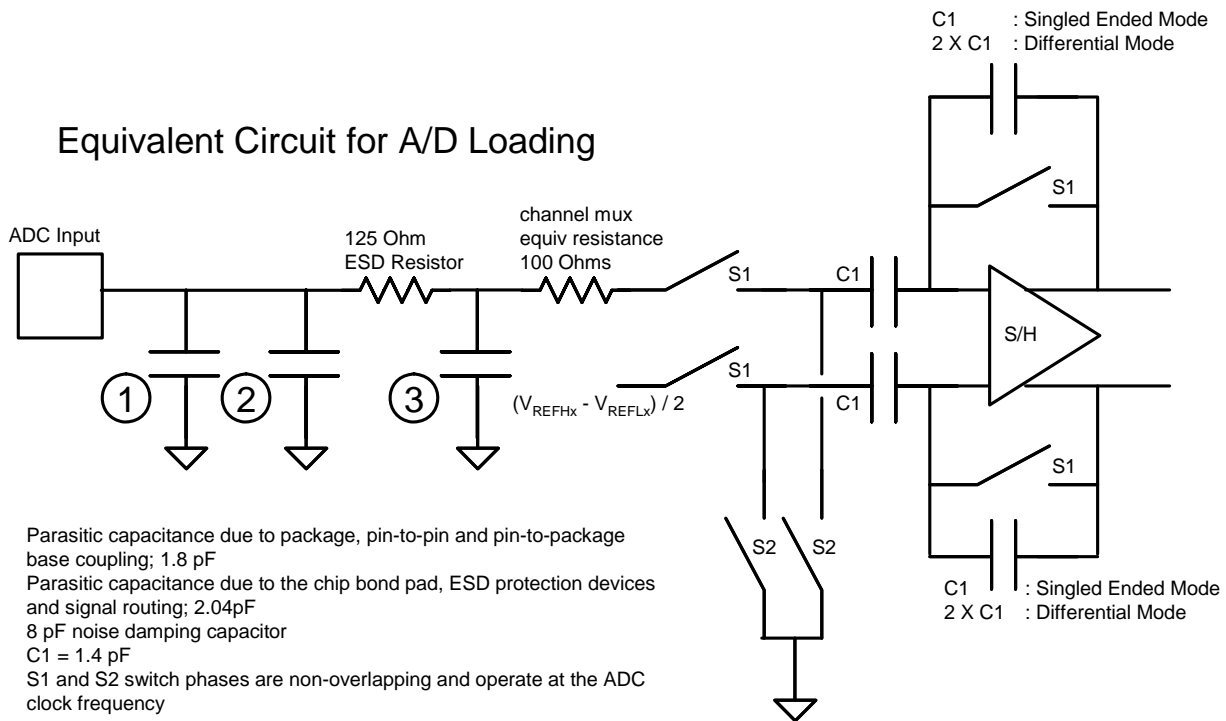
5. LSB = Least Significant Bit = 0.806mV
6. Pin groups are detailed following [Table 10-1](#).
7. The current that can be injected or sourced from an unselected ADC signal input without impacting the performance of the ADC.

10.15 Equivalent Circuit for ADC Inputs

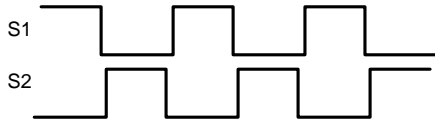
Figure 10-17 illustrates the ADC input circuit during sample and hold. S1 and S2 are always open/closed at the same time that S3 is closed/open. When S1/S2 are closed & S3 is open, one input of the sample and hold circuit moves to $(V_{REFH}-V_{REFL})/2$, while the other charges to the analog input voltage. When the switches are flipped, the charge on C1 and C2 are averaged via S3, with the result that a single-ended analog input is switched to a differential voltage centered about $(V_{REFH}-V_{REFL})/2$. The switches switch on every cycle of the ADC clock (open one-half ADC clock, closed one-half ADC clock). Note that there are additional capacitances associated with the analog input pad, routing, etc., but these do not filter into the S/H output voltage, as S1 provides isolation during the charge-sharing phase.

One aspect of this circuit is that there is an on-going input current, which is a function of the analog input voltage, V_{REF} and the ADC clock frequency.

Equivalent Circuit for A/D Loading



1. Parasitic capacitance due to package, pin-to-pin and pin-to-package base coupling; 1.8 pF
2. Parasitic capacitance due to the chip bond pad, ESD protection devices and signal routing; 2.04pF
3. 8 pF noise damping capacitor
4. C1 = 1.4 pF
5. S1 and S2 switch phases are non-overlapping and operate at the ADC clock frequency



6. Equivalent input impedance, when the input is selected = $\frac{1}{(\text{ADC Clock Rate}) \times 1.4 \times 10^{-12}} + 100\text{ohm} + 125\text{ohm}$

1. Parasitic capacitance due to package, pin-to-pin and pin-to-package base coupling; 1.8pF
2. Parasitic capacitance due to the chip bond pad, ESD protection devices and signal routing; 2.04pF
3. Equivalent resistance for the channel select mux; 100 ohms
4. Sampling capacitor at the sample and hold circuit. Capacitor C1 is normally disconnected from the input and is only connected to it at sampling time; 1.4pf
5. Equivalent input impedance, when the the input is selected = $\frac{1}{(\text{ADC Clock Rate}) \times 1.4 \times 10^{-12}}$

Figure 10-17 Equivalent Circuit for A/D Loading

10.16 Power Consumption

See [Section 10.1](#) for a list of IDD requirements for the 56F8014. This section provides additional detail which can be used to optimize power consumption for a given application.

Power consumption is given by the following equation:

Total power = A: internal [static component]

+B: internal [state-dependent component]

Please see <http://www.freescale.com> for the most current mechanical drawing.

+C: internal [dynamic component]

+D: external [dynamic component]

+E: external [static]

A, the internal [static component], is comprised of the DC bias currents for the oscillator, leakage currents, PLL, and voltage references. These sources operate independently of processor state or operating frequency.

B, the internal [state-dependent component], reflects the supply current required by certain on-chip resources only when those resources are in use. These include RAM, Flash memory and the ADCs.

C, the internal [dynamic component], is classic $C \cdot V^2 \cdot F$ CMOS power dissipation corresponding to the 56800E core and standard cell logic.

D, the external [dynamic component], reflects power dissipated on-chip as a result of capacitive loading on the external pins of the chip. This is also commonly described as $C \cdot V^2 \cdot F$, although simulations on two of the I/O cell types used on the 56800E reveal that the power-versus-load curve does have a non-zero Y-intercept.

Table 10-20 I/O Loading Coefficients at 10MHz

| | Intercept | Slope |
|-----------|-----------|-------------|
| 8mA drive | 1.3 | 0.11mW / pF |
| 4mA drive | 1.15mW | 0.11mW / pF |

Power due to capacitive loading on output pins is (first order) a function of the capacitive load and frequency at which the outputs change. [Table 10-20](#) provides coefficients for calculating power dissipated in the I/O cells as a function of capacitive load. In these cases:


$$TotalPower = \Sigma((Intercept + Slope \cdot Cload) \cdot frequency / 10MHz)$$

where:

- Summation is performed over all output pins with capacitive loads
- TotalPower is expressed in mW
- Cload is expressed in pF

Because of the low duty cycle on most device pins, power dissipation due to capacitive loads was found to be fairly low when averaged over a period of time.

E, the external [static component], reflects the effects of placing resistive loads on the outputs of the device. Sum the total of all V^2/R or IV to arrive at the resistive load contribution to power. Assume $V = 0.5$ for the purposes of these rough calculations. For instance, if there is a total of eight PWM outputs driving 10mA into LEDs, then $P = 8 \cdot 0.5 \cdot 0.01 = 40mW$.



In previous discussions, power consumption due to parasitics associated with pure input pins is ignored, as it is assumed to be negligible.

Part 11 Packaging

11.1 56F8014 Package and Pin-Out Information

This section contains package and pin-out information for the 56F8014. This device comes in a 32-pin Low-profile Quad Flat Pack (LQFP). **Figure 11-1** shows the package outline for the 32-pin LQFP, **Figure 11-2** shows the mechanical parameters for this package, and **Table 11-1** lists the pin-out for the 32-pin LQFP.

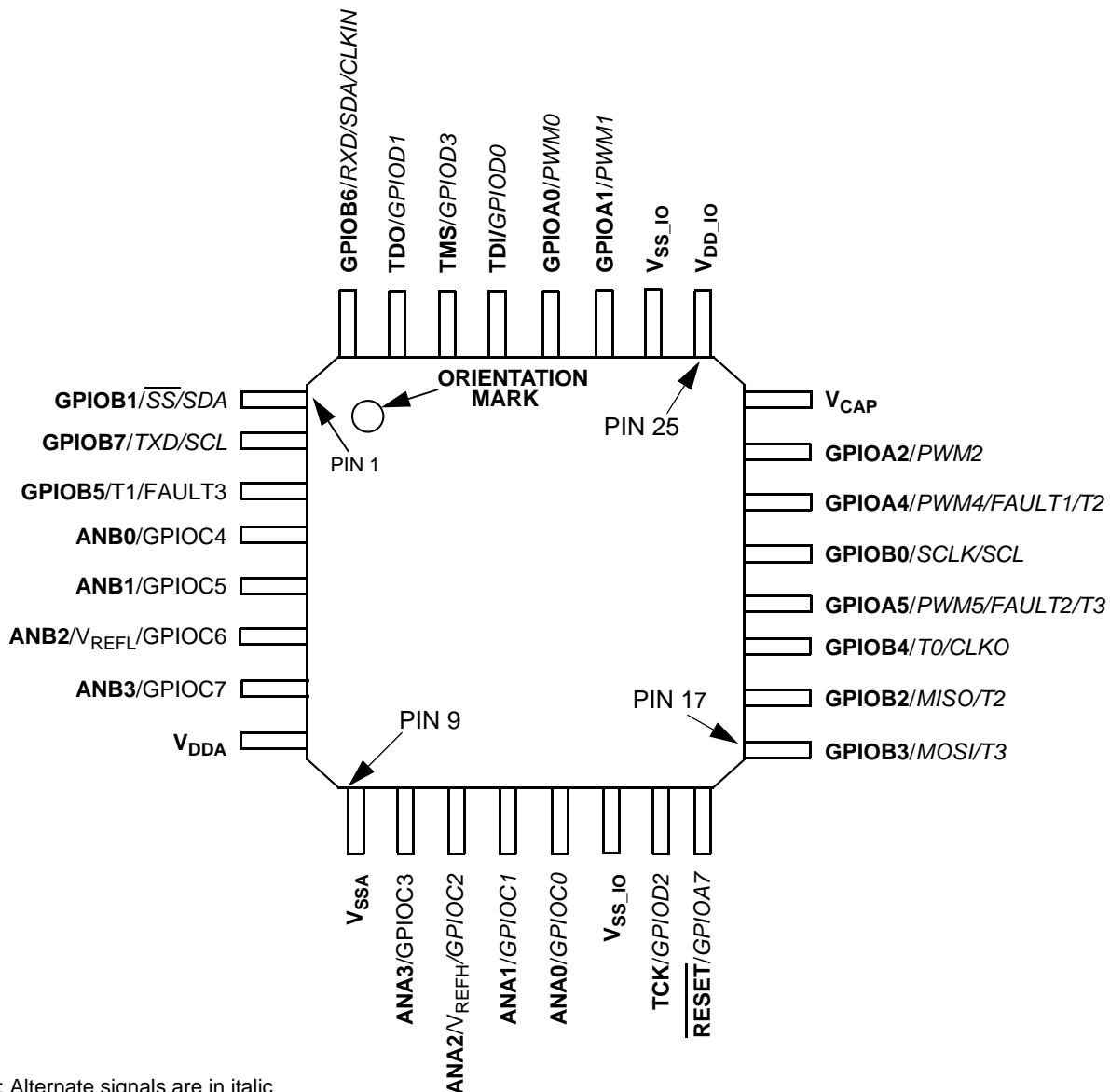


Figure 11-1 Top View, 56F8014 32-Pin LQFP Package

Table 11-1 56F8014 32-Pin LQFP Package Identification by Pin Number¹

| Pin No. | Signal Name | Pin No. | Signal Name | Pin No. | Signal Name | Pin No. | Signal Name |
|---------|---|---------|---|---------|--|---------|---------------------------------------|
| 1 | GPIOB1 <i>SS,SDA</i> | 9 | V_{SSA} | 17 | GPIOB3 <i>MOSI,T3</i> | 25 | V_{DD_IO} |
| 2 | GPIOB7 <i>TXD,SCL</i> | 10 | ANA3 <i>GPIOC3</i> | 18 | GPIOB2 <i>MISO,T2</i> | 26 | V_{SS_IO} |
| 3 | GPIOB5 <i>T1,FAULT3</i> | 11 | ANA2 <i>V_{REFH},GPIOC2</i> | 19 | GPIOB4 <i>T0,CLKO</i> | 27 | GPIOA1 <i>PWM1</i> |
| 4 | ANB0 <i>GPIOC4</i> | 12 | ANA1 <i>GPIOC1</i> | 20 | GPIOA5 <i>PWM5,FAULT2,T3</i> | 28 | GPIOA0 <i>PWM0</i> |
| 5 | ANB1 <i>GPIOC5</i> | 13 | ANA0 <i>GPIOC0</i> | 21 | GPIOB0 <i>SCLK,CL</i> | 29 | TDI <i>GPIOD0</i> |
| 6 | ANB2 <i>V_{REFL},GPIOC6</i> | 14 | V_{SS_IO} | 22 | GPIOA4 <i>PWM4/FAULT1/T2</i> | 30 | TMS <i>GPIOD3</i> |
| 7 | ANB3 <i>GPIOC7</i> | 15 | TCK <i>GPIOD2</i> | 23 | GPIOA2 <i>PWM2</i> | 31 | TDO <i>GPIOD1</i> |
| 8 | V_{DDA} | 16 | RESET <i>GPIOA7</i> | 24 | V_{CAP} | 32 | GPIOB6 <i>RXD,SDA,CLKIN</i> |

1.Alternate signals are in iltalic

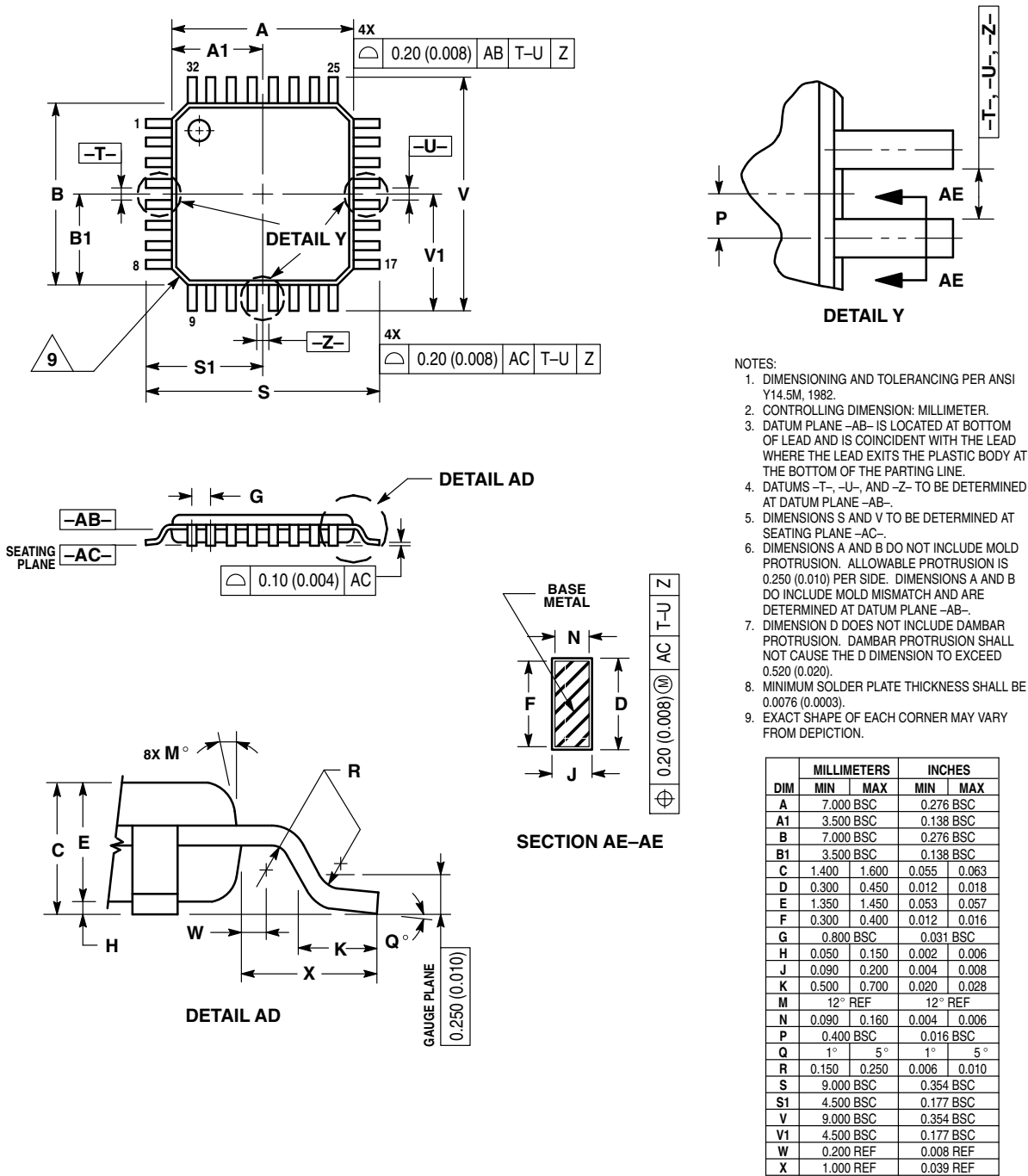


Figure 11-2 56F8014 32-Pin LQFP Mechanical Information

Part 12 Design Considerations

12.1 Thermal Design Considerations

An estimation of the chip junction temperature, T_J , can be obtained from the equation:

$$T_J = T_A + (R_{\theta JA} \times P_D)$$

where

- T_A = Ambient temperature for the package ($^{\circ}\text{C}$)
- $R_{\theta JA}$ = Junction-to-ambient thermal resistance ($^{\circ}\text{C}/\text{W}$)
- P_D = Power dissipation in the package (W)

The junction-to-ambient thermal resistance is an industry-standard value that provides a quick and easy estimation of thermal performance. Unfortunately, there are two values in common usage: the value determined on a single-layer board and the value obtained on a board with two planes. For packages such as the PBGA, these values can be different by a factor of two. Which value is closer to the application depends on the power dissipated by other components on the board. The value obtained on a single layer board is appropriate for the tightly packed printed circuit board. The value obtained on the board with the internal planes is usually appropriate if the board has low-power dissipation and the components are well separated.

When a heat sink is used, the thermal resistance is expressed as the sum of a junction-to-case thermal resistance and a case-to-ambient thermal resistance:

$$R_{\theta JA} = R_{\theta JC} + R_{\theta CA}$$

where

- $R_{\theta JA}$ = Package junction-to-ambient thermal resistance ($^{\circ}\text{C}/\text{W}$)
- $R_{\theta JC}$ = Package junction-to-case thermal resistance ($^{\circ}\text{C}/\text{W}$)
- $R_{\theta CA}$ = Package case-to-ambient thermal resistance ($^{\circ}\text{C}/\text{W}$)

$R_{\theta JC}$ is device related and cannot be influenced by the user. The user controls the thermal environment to change the case to ambient thermal resistance, $R_{\theta CA}$. For instance, the user can change the size of the heat sink, the air flow around the device, the interface material, the mounting arrangement on printed circuit board, or change the thermal dissipation on the printed circuit board surrounding the device.

To determine the junction temperature of the device in the application when heat sinks are not used, the Thermal Characterization Parameter (Ψ_{JT}) can be used to determine the junction temperature with a measurement of the temperature at the top center of the package case using the following equation:

$$T_J = T_T + (\Psi_{JT} \times P_D)$$

where

- T_T = Thermocouple temperature on top of package ($^{\circ}\text{C}$)

- Ψ_{JT} = Thermal characterization parameter ($^{\circ}\text{C}/\text{W}$)
 P_D = Power dissipation in package (W)

The thermal characterization parameter is measured per JESD51-2 specification using a 40-gauge type T thermocouple epoxied to the top center of the package case. The thermocouple should be positioned so that the thermocouple junction rests on the package. A small amount of epoxy is placed over the thermocouple junction and over about 1mm of wire extending from the junction. The thermocouple wire is placed flat against the package case to avoid measurement errors caused by cooling effects of the thermocouple wire.

When heat sink is used, the junction temperature is determined from a thermocouple inserted at the interface between the case of the package and the interface material. A clearance slot or hole is normally required in the heat sink. Minimizing the size of the clearance is important to minimize the change in thermal performance caused by removing part of the thermal interface to the heat sink. Because of the experimental difficulties with this technique, many engineers measure the heat sink temperature and then back-calculate the case temperature using a separate measurement of the thermal resistance of the interface. From this case temperature, the junction temperature is determined from the junction-to-case thermal resistance.

12.2 Electrical Design Considerations

CAUTION

This device contains protective circuitry to guard against damage due to high static voltage or electrical fields. However, normal precautions are advised to avoid application of any voltages higher than maximum-rated voltages to this high-impedance circuit. Reliability of operation is enhanced if unused inputs are tied to an appropriate voltage level.

Use the following list of considerations to assure correct operation of the 56F8014:

- Provide a low-impedance path from the board power supply to each V_{DD} pin on the 56F8014 and from the board ground to each V_{SS} (GND) pin
- The minimum bypass requirement is to place 0.01–0.1 μF capacitors positioned as close as possible to the package supply pins. The recommended bypass configuration is to place one bypass capacitor on each of the V_{DD}/V_{SS} pairs, including V_{DDA}/V_{SSA} . Ceramic and tantalum capacitors tend to provide better tolerances.
- Ensure that capacitor leads and associated printed circuit traces that connect to the chip V_{DD} and V_{SS} (GND) pins are as short as possible
- Bypass the V_{DD} and V_{SS} with approximately 100 μF , plus the number of 0.1 μF ceramic capacitors

- PCB trace lengths should be minimal for high-frequency signals
- Consider all device loads as well as parasitic capacitance due to PCB traces when calculating capacitance. This is especially critical in systems with higher capacitive loads that could create higher transient currents in the V_{DD} and V_{SS} circuits.
- Take special care to minimize noise levels on the V_{REF} , V_{DDA} and V_{SSA} pins
- Using separate power planes for V_{DD} and V_{DDA} and separate ground planes for V_{SS} and V_{SSA} is recommended. Connect the separate analog and digital power and ground planes as close as possible to power supply outputs. If both analog circuit and digital circuit are powered by the same power supply, it is advisable to connect a small inductor or ferrite bead in serial with both V_{DDA} and V_{SSA} traces.
- It is highly desirable to physically separate analog components from noisy digital components by ground planes. Do not place an analog trace in parallel with digital traces. It is also desirable to place an analog ground trace around an analog signal trace to isolate it from digital traces.
- Because the Flash memory is programmed through the JTAG/EOnCE port, SPI, SCI or I²C, the designer should provide an interface to this port if in-circuit Flash programming is desired.

Part 13 Ordering Information

Table 13-1 lists the pertinent information needed to place an order. Consult a Freescale Semiconductor sales office or authorized distributor to determine availability and to order parts.

Table 13-1 56F8014 Ordering Information

| Part | Supply Voltage | Package Type | Pin Count | Frequency (MHz) | Ambient Temperature Range | Order Number |
|-----------|----------------|-----------------------------------|-----------|-----------------|---------------------------|----------------|
| MC56F8014 | 3.0–3.6 V | Low-Profile Quad Flat Pack (LQFP) | 32 | 32 | -40° to + 105° C | MC56F8014VFAE* |
| MC56F8014 | 3.0–3.6 V | Low-Profile Quad Flat Pack (LQFP) | 32 | 32 | -40° to +125 °C | MC56F8014MFAE* |

*This package is RoHS compliant.

Part 14 Appendix

Register acronyms are revised from previous device data sheets to provide a cleaner register description. A cross reference to legacy and revised acronyms are provided in the following table.

| Module | Register Name | Peripheral Reference Manual | | Data Sheet | | Processor Expert Acronym | Memory Address | |
|----------------------------|--------------------------------|-----------------------------|----------------|--------------|----------------|--------------------------|----------------|--------|
| | | New Acronym | Legacy Acronym | New Acronym | Legacy Acronym | | Start | End |
| ADC | Control Register 1 | CTRL1 | ADCR1 | ADC_CTRL1 | ADC_ADCR1 | ADC_ADCR1 | 0xF080 | |
| | Control Register 2 | CTRL2 | ADCR2 | ADC_CTRL2 | ADC_ADCR2 | ADC_ADCR2 | 0xF081 | |
| | Zero Crossing Control Register | ZXCTRL | ADZCC | ADC_ZXCTRL | ADC_ADZCC | ADC_ADZCC | 0xF082 | |
| | Channel List Register 1 | CLIST1 | ADLST1 | ADC_CLIST1 | ADC_ADLST1 | ADC_ADLST1 | 0xF083 | |
| | Channel List Register 2 | CLIST2 | ADLST2 | ADC_CLIST2 | ADC_ADLST2 | ADC_ADLST2 | 0xF084 | |
| | Sample Disable Register | SDIS | ADSDIS | ADC_SDIS | ADC_ADSDIS | ADC_ADSDIS | 0xF085 | |
| | Status Register | STAT | ADSTAT | ADC_STAT | ADC_ADSTAT | ADC_ADSTAT | 0xF086 | |
| | Limit Status Register | LIMSTAT | ADLSTAT | ADC_LIMSTAT | ADC_ADLSTAT | ADC_ADLSTAT | 0xF087 | |
| | Zero Crossing Status Register | ZXSTAT | ADZCSTAT | ADC_ZXSTAT | ADC_ADZCSTAT | ADC_ADZCSTAT | 0xF088 | |
| | Result Registers 0-7 | RSLT0-7 | ADRSLT0-7 | ADC_RSLT0-7 | ADC_ADRSLT0-7 | ADC_ADRSLT0-7 | 0xF089 | 0xF090 |
| | Low Limit Registers 0-7 | LOLIM0-7 | ADLLMT0-7 | ADC_LOLIM0-7 | ADC_ADLLMT0-7 | ADC_ADLLMT0-7 | 0xF091 | 0xF098 |
| | High Limit Registers 0-7 | HILIM0-7 | ADHLMT0-7 | ADC_HILIM0-7 | ADC_ADHLMT0-7 | ADC_ADHLMT0-7 | 0xF099 | 0xF0A0 |
| | Offset Registers 0-7 | OFFST0-7 | ADOF0-7 | ADC_OFFST0-7 | ADC_ADOF0-7 | ADC_ADOF0-7 | 0xF0A1 | 0xF0A8 |
| | Power Control Register | PWR | ADPOWER | ADC_PWR | ADC_ADPOWER | ADC_ADPOWER | 0xF0A9 | |
| Voltage Reference Register | CAL | ADCAL | ADC_VREF | ADC_ADCAL | ADC_CAL | 0xF0AA | | |
| COP | Control Register | CTRL | COPCTL | COP_CTRL | COPCTL | COPCTL | 0XF0E0 | |
| | Time-Out Register | TOUT | COPTO | COP_TOUT | COPTO | COPTO | 0XF0E1 | |
| | Counter Register | CNTR | COPCTR | COP_CNTR | COPCTR | COPCTR | 0XF0E2 | |

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