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## FAN53555

## 5 A, 2.4 MHz, Digitally Programmable TinyBuck ${ }^{\circledR}$ Regulator

## Features

- Fixed-Frequency Operation: 2.4 MHz
- Best-in-Class Load Transient
- Continuous Output Current Capability: 5 A
- Pulse Current Capability: 6.5 A (05 Option)
- 2.5 V to 5.5 V Input Voltage Range
- Digitally Programmable Output Voltage:
- 00/01/03/05/08/18 Options: 0.6-1.23 V in 10 mV Steps
- 04/042/09/ Options: 0.603-1.411 V in 12.826 mV Steps
- 23 Option: 0.60-1.3875 V in 12.5 mV Steps
- 24 Option: 0.603-1.420 V in 12.967 mV Steps
- 13 Option: 0.8-1.43 V in 10 mV Steps
- Programmable Slew Rate for Voltage Transitions
- $I^{2} \mathrm{C}$-Compatible Interface Up to 3.4 Mbps
- PFM Mode for High Efficiency in Light Load
- Quiescent Current in PFM Mode: $60 \mu \mathrm{~A}$ (Typical)
- Internal Soft-Start
- Input Under-Voltage Lockout (UVLO)
- Thermal Shutdown and Overload Protection
- 20-Bump Wafer-Level Chip Scale Package (WLCSP)


## Applications

- Application, Graphic, and DSP Processors - ARM $^{\text {TM }}$, Krait $^{\text {TM }}$, OMAP ${ }^{\text {TM }}$, NovaThor ${ }^{\text {TM }}$, ARMADA ${ }^{\text {TM }}$
- Hard Disk Drives
- Tablets, Netbooks, Ultra-Mobile PCs
- Smart Phones
- Gaming Devices


## Description

The FAN53555 is a step-down switching voltage regulator that delivers a digitally programmable output from an input voltage supply of 2.5 V to 5.5 V . The output voltage is programmed through an $\mathrm{I}^{2} \mathrm{C}$ interface capable of operating up to 3.4 MHz .

Using a proprietary architecture with synchronous rectification, the FAN53555 is capable of delivering 5 A continuous at over $80 \%$ efficiency, while maintaining over $80 \%$ efficiency at load currents as low as 10 mA . Pulse currents as high as 6.5 A can be supported by the 05 option. The regulator operates at a nominal fixed frequency of 2.4 MHz , which reduces the value of the external components to 330 nH for the output induction and as low as $20 \mu \mathrm{~F}$ for the output capacitor. Additional output capacitance can be added to improve regulation during load transients without affecting stability. Inductance up to $1.2 \mu \mathrm{H}$ may be used with additional output capacitance.

At moderate and light loads, Pulse Frequency Modulation (PFM) is used to operate in Power-Save Mode with a typical quiescent current of $60 \mu \mathrm{~A}$. Even with such a low quiescent current, the part exhibits excellent transient response during large load swings. At higher loads, the system automatically switches to fixed-frequency control, operating at 2.4 MHz . In Shutdown Mode, the supply current drops below $1 \mu \mathrm{~A}$, reducing power consumption. PFM Mode can be disabled if constant frequency is desired. The FAN53555 is available in a 20-bump, $1.6 \times 2 \mathrm{~mm}$, WLCSP.


Figure 1. Typical Application

Ordering Information

| Part Number | Power-Up Defaults |  | $I^{2} C$ Slave Address | A1 PIN Function | Max. <br> RMS Current | Max. <br> Pulse Current ( 50 ms ) | Temperature Range | Package | Packing Method |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | VSELO | VSEL1 |  |  |  |  |  |  |  |
| FAN53555UC00X | 1.05 | 1.20 | C0 | VSEL | 5 A | N/A | -40 to $85^{\circ} \mathrm{C}$ | $\begin{gathered} \text { WLCSP- } \\ 20 \end{gathered}$ | Tape \& Reel |
| FAN53555UC01X | 0.90 | OFF |  | VSEL | 5 A | N/A |  |  |  |
| FAN53555UC03X | 0.90 | N/A |  | PGOOD | 5 A | N/A |  |  |  |
| FAN53555UC04X | 1.10 | 1.20 |  | VSEL | 5 A | N/A |  |  |  |
| FAN53555UC05X | 0.90 | OFF |  | VSEL | 5 A | 6.5 A |  |  |  |
| FAN53555BUC05X ${ }^{(1)}$ | 0.90 | OFF |  | VSEL | 5 A | 6.5 A |  |  |  |
| FAN53555UC08X | 1.02 | 1.15 |  | VSEL | 4 A | N/A |  |  |  |
| FAN53555BUC08X ${ }^{(1)}$ | 1.02 | 1.15 |  | VSEL | 4 A | N/A |  |  |  |
| FAN53555BUC09X ${ }^{(1)}$ | 1.10 | 1.10 |  | VSEL | 3 A | N/A |  |  |  |
| FAN53555UC09X | 1.10 | 1.10 |  | VSEL | 3 A | N/A |  |  |  |
| FAN53555UC13X | 1.15 | 1.15 |  | VSEL | 5 A | N/A |  |  |  |
| FAN53555BUC13X ${ }^{(1)}$ | 1.15 | 1.15 |  | VSEL | 5 A | N/A |  |  |  |
| FAN53555UC18X | 1.02 | 1.15 |  | VSEL | 5 A | N/A |  |  |  |
| FAN53555BUC18X ${ }^{(1)}$ | 1.02 | 1.15 |  | VSEL | 5 A | N/A |  |  |  |
| FAN53555BUC23X ${ }^{(1)}$ | 1.15 | 1.15 |  | VSEL | 5 A | N/A |  |  |  |
| FAN53555UC24X | 1.225 | 1.212 |  | VSEL | 4 A | N/A |  |  |  |
| FAN53555BUC24X ${ }^{(1)}$ | 1.225 | 1.212 |  | VSEL | 4 A | N/A |  |  |  |
| FAN53555UC042X ${ }^{(2)}$ | 1.10 | 1.20 | C4 | VSEL | 5 A | N/A |  |  |  |

## Notes:

1. The FAN53555BUC05X, FAN53555BUC08X, FAN53555BUC09X, FAN53555BUC13X, FAN53555BUC18X, FAN53555BUC23X, and FAN53555BUC24X, include backside lamination.
2. The 042 option is the same as the 04 option, except the $I^{2} C$ slave addresses.

## Recommended External Components

Table 1. Recommended External Components for 5 A Maximum Load Current

| Component | Description | Vendor | Parameter | Typ. | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: |
| L1 | 330 nH Nominal | See Table 2 | L | 0.33 | $\mu \mathrm{H}$ |
|  |  |  | DCR | 13 | $\mathrm{m} \Omega$ |
| Cout | $\begin{gathered} 2 \text { Pieces; } \\ 22 \mu \mathrm{~F}, 6.3 \mathrm{~V}, \mathrm{X} 5 \mathrm{R}, 0805 \end{gathered}$ | GRM21BR60J226M (Murata) C2012X5R0J226M (TDK) | C | 44 | $\mu \mathrm{F}$ |
| $\mathrm{C}_{\text {IN }}$ | $\begin{gathered} 1 \text { Piece; } \\ 10 \mu \mathrm{~F}, 10 \mathrm{~V}, \mathrm{X} 5 \mathrm{R}, 0805 \end{gathered}$ | LMK212BJ106KG-T (Taiyo Yuden) C2012X5R1A106M (TDK) | C | 10 |  |
|  | $\begin{gathered} 2 \text { Pieces; } \\ 10 \mu \mathrm{~F}, 6.3 \mathrm{~V}, \mathrm{X} 5 \mathrm{R}, 0805 \end{gathered}$ | GRM21BR60J106M (Murata) C2012X5ROJ106M (TDK) | C | 20 |  |
| $\mathrm{Cl}_{\text {IN1 }}$ | $10 \mathrm{nF}, 25 \mathrm{~V}, \mathrm{X} 7 \mathrm{R}, 0402$ | GRM155R71E103K (Murata) C1005X7R1E103K (TDK) | C | 10 | nF |

Table 2. Recommended Inductors for High-Current Applications

|  | dur |  |  |  | Component Dimensions |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Manufacturer | Part\# | L ( nH ) | DCR (m) | $\mathrm{I}_{\text {MAXDC }}{ }^{(3)}$ | L | W | H |
| Vishay | IHLP1616ABERR47M01 | 470 | 20.0 | 5.0 | 4.5 | 4.1 | 1.2 |
| Mag. Layers ${ }^{(4)}$ | MMD-04ABNR33M-M1-RU | 330 | 12.5 | 7.5 | 4.5 | 4.1 | 1.2 |
| Mag. Layers | MMD-04ABNR47M-M1-RU | 470 | 20.0 | 5.0 | 4.5 | 4.1 | 1.2 |
| Inter-Technical | SM1608-R33M | 330 | 9.6 | 9.0 | 4.5 | 4.1 | 2.0 |
| Bournes | SRP4012-R33M | 330 | 15.0 | 6.7 | 4.7 | 4.2 | 1.2 |
| Bournes | SRP4012-R47M | 470 | 20.0 | 5.0 | 4.7 | 4.2 | 1.2 |
| TDK | VLC5020T-R47M | 470 | 15.0 | 5.4 | 5.0 | 5.0 | 2.0 |

## Notes:

3. $I_{\text {MAXDC }}$ is the lesser current to produce $40^{\circ} \mathrm{C}$ temperature rise or $30 \%$ inductance roll-off.
4. Preferred inductor value is 330 nH and all dynamic characterization was performed with this coil.

## FAN53555-24, -08, and -09 Reduced Output Current (4 A Max. RMS. for 08, and 24, 3 A Max. RMS for 09) Smaller Footprint Application

The FAN53555-24, -08, and -09 were developed to provide power for core processors with high-performance graphics acceleration in Li-lon-powered handheld devices. These applications require a very compact solution. The smaller input and output capacitors in the table below assume that additional bypass capacitance exists across the battery in fairly close proximity to the regulator(s). The $\mathrm{C}_{\mathbb{N}}$ capacitors specified below are the capacitors that are required in very close proximity to VIN and PGND (see layout recommendations in Figure 2 below).

Table 3. Recommended External Components for Lower-Current Applications with FAN53555-08-09-24

| Component | Description | Vendor | Parameter | Typ. | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: |
| L1 | 470 or $330 \mathrm{nH}, 2016$ case size | See Table 4 |  |  |  |
| Cout | $\begin{gathered} -08,, 24 \text { Option } \\ 2 \text { Pieces } 22 \mu \mathrm{~F}, 6.3 \mathrm{~V}, \mathrm{X} 5 \mathrm{R}, 0603 \end{gathered}$ | C1608X5ROJ226M (TDK) | C | 44 | $\mu \mathrm{F}$ |
|  | -09 Option <br> 1 Piece $22 \mu \mathrm{~F}, 6.3 \mathrm{~V}$, X5R, 0603 |  |  | 22 |  |
| $\mathrm{Clin}^{\text {a }}$ | $\begin{gathered} \hline \text { Piece; } \\ 10 \mu \mathrm{~F}, 10 \mathrm{~V}, \mathrm{X} 5 \mathrm{R}, 0402 \end{gathered}$ | GRM155R61A106M (Murata) | C | 10 |  |
| $\mathrm{C}_{\text {IN } 1}$ | $10 \mathrm{nF}, 25 \mathrm{~V}, \mathrm{X} 5 \mathrm{R}, 0201$ | TMK063CG100DT-F (Taiyo Yuden) | C | 10 | nF |

Table 4. Recommended Inductors for Lower-Current Applications with FAN53555-08-09-24


## Note:

5. $I_{\text {MAXDC }}$ is the lesser current to produce $40^{\circ} \mathrm{C}$ temperature rise or $30 \%$ inductance roll-off.

## Layout



Figure 2. Reduced-Footprint Layout

## Pin Configuration



Figure 3. Top View

Pin Definitions

Figure 4. Bottom View
$A 1=$ VSEL for $00,01,04,05,08,09,13,18,23,24$
A1 = PGOOD for 03
(A4) (A3) (A2) (A1)
(34) (B3) (B2) (B1)
(C4) (C3) (C2) (C1)
(ㄷ4) (ㅁ) (D2) (1)
(E4) ③) © © ${ }^{-1}$

| Pin \# | Name | Description |
| :---: | :---: | :---: |
| A1 | VSEL <br> (Except - <br> 03 Option) | Voltage Select. When this pin is LOW, Vout is set by the VSELO register. When this pin is HIGH, $\mathrm{V}_{\text {Out }}$ is set by the VSEL1 register. |
|  | $\begin{aligned} & \text { PGOOD } \\ & (03) \end{aligned}$ | Power Good. This open-drain pin pulls LOW if an overload condition occurs or soft-start is in progress. |
| A2 | EN | Enable. The device is in Shutdown Mode when this pin is LOW. All register values are kept during shutdown. Options $00,01,03,05,0809,13,18$, and 23 do not reset register values when EN is raised. The 04, 24, and 042 options reset all registers to default values when EN pin is LOW. If pulled up to a low-impedance voltage source greater than 1.8 V , use at least $100 \Omega$ series resistor. |
| A3 | SCL | $1^{2} \mathrm{C}$ Serial Clock |
| A4 | VOUT | VOUT. Sense pin for VOUT. Connect to COUT. |
| B1 | SDA | $I^{2} \mathrm{C}$ Serial Data |
| $\begin{aligned} & \mathrm{B} 2, \mathrm{~B} 3, \\ & \mathrm{C} 1-\mathrm{C} 4 \end{aligned}$ | GND | Ground. Low-side MOSFET is referenced to this pin. $\mathrm{C}_{\mathbb{I N}}$ and $\mathrm{C}_{\text {out }}$ should be returned with a minimal path to these pins. |
| B4 | AGND | Analog Ground. All signals are referenced to this pin. Avoid routing high dV/dt AC currents through this pin. |
| $\begin{gathered} \hline \text { D1, D2, } \\ \text { E1, E2 } \end{gathered}$ | VIN | Power Input Voltage. Connect to the input power source. Connect to $\mathrm{C}_{\text {IN }}$ with minimal path. |
| $\begin{aligned} & \text { D3, D4, } \\ & \text { E3, E4 } \end{aligned}$ | SW | Switching Node. Connect to the inductor. |

## Absolute Maximum Ratings

Stresses exceeding the absolute maximum ratings may damage the device. The device may not function or be operable above the recommended operating conditions and stressing the parts to these levels is not recommended. In addition, extended exposure to stresses above the recommended operating conditions may affect device reliability. The absolute maximum ratings are stress ratings only.

| Symbol | Parameter |  | Min. | Max. | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: |
| VIN | Voltage on SW, VIN Pins | IC Not Switching | -0.3 | 7.0 | V |
|  |  | IC Switching | -0.3 | 6.5 |  |
|  | Voltage on EN Pin | Tied without Series Resistance) | -0.3 | 2.0 | V |
|  |  | Tied through Series Resistance of at Least $100 \Omega$ | -0.3 | $\mathrm{V}_{\text {IN }}{ }^{(6)}$ |  |
|  | Voltage on All Other Pins | IC Not Switching | -0.3 | $\mathrm{V}_{\text {IN }}{ }^{(6)}$ | V |
| Vout | Voltage on VOUT Pin |  | -0.3 | 3.0 | V |
| VInov_Slew | Maximum Slew Rate of $\mathrm{V}_{\text {IN }}>6.5 \mathrm{~V}$, PWM Switching |  |  | 100 | V/ms |
| ESD | Electrostatic Discharge Protection Level | Human Body Model per JESD22-A114 | 2000 |  | V |
|  |  | Charged Device Model per JESD22-C101 | 1500 |  |  |
| $\mathrm{T}_{\mathrm{J}}$ | Junction Temperature |  | -40 | +150 | ${ }^{\circ} \mathrm{C}$ |
| TSTG | Storage Temperature |  | -65 | +150 | ${ }^{\circ} \mathrm{C}$ |
| $\mathrm{T}_{\mathrm{L}}$ | Lead Soldering Temperature, 10 Seconds |  |  | +260 | ${ }^{\circ} \mathrm{C}$ |

## Note:

6. Lesser of 7 V or $\mathrm{V}_{\mathrm{IN}}+0.3 \mathrm{~V}$.

## Recommended Operating Conditions

The Recommended Operating Conditions table defines the conditions for actual device operation. Recommended operating conditions are specified to ensure optimal performance to the datasheet specifications. Fairchild does not recommend exceeding them or designing to Absolute Maximum Ratings.

| Symbol | Parameter | Min. | Typ. | Max. | Unit |
| :---: | :--- | :---: | :---: | :---: | :---: |
| $\mathrm{V}_{\mathbb{I N}}$ | Supply Voltage Range | 2.5 |  | 5.5 | V |
| $\mathrm{I}_{\text {OUT }}$ | Output Current | 0 |  | 5 | A |
| L | Inductor |  | 0.33 |  | $\mu \mathrm{H}$ |
| $\mathrm{C}_{\mathbb{I}}$ | Input Capacitor |  | 10 |  | $\mu \mathrm{~F}$ |
| $\mathrm{C}_{\text {out }}$ | Output Capacitor |  | 44 |  | $\mu \mathrm{~F}$ |
| $\mathrm{~T}_{\mathrm{A}}$ | Operating Ambient Temperature | -40 |  | +85 | ${ }^{\circ} \mathrm{C}$ |
| $\mathrm{T}_{J}$ | Operating Junction Temperature | -40 |  | +125 | ${ }^{\circ} \mathrm{C}$ |

## Thermal Properties

| Symbol | Parameter | Min. | Typ. | Max. | Unit |
| :---: | :--- | :---: | :---: | :---: | :---: |
| $\theta_{\mathrm{JA}}$ | Junction-to-Ambient Thermal Resistance ${ }^{(7)}$ |  | 38 |  | ${ }^{\circ} \mathrm{C} / \mathrm{W}$ |

## Note:

7. See Thermal Considerations in the Application Information section.

## Electrical Characteristics

Minimum and maximum values are at $\mathrm{V}_{\mathbb{N}}=2.5 \mathrm{~V}$ to $5.5 \mathrm{~V}, \mathrm{~T}_{\mathrm{A}}=-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$, unless otherwise noted. Typical values are at $\mathrm{T}_{\mathrm{A}}=25^{\circ} \mathrm{C}, \mathrm{V}_{\text {IN }}=5 \mathrm{~V}$, and $\mathrm{EN}=\mathrm{HIGH}$.

| Symbol | Parameter | Condition | Min. | Typ. | Max. | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Power Supplies |  |  |  |  |  |  |
| $\mathrm{I}_{\mathrm{Q}}$ | Quiescent Current | $\mathrm{I}_{\text {LOAD }}=0$ |  | 60 | 100 | $\mu \mathrm{A}$ |
|  |  | $\mathrm{I}_{\text {LOAD }}=0, \mathrm{MODE}$ Bit=1 (Forced PWM) |  | 43 |  | mA |
| Isd | H/W Shutdown Supply Current | EN=GND |  | 0.1 | 5.0 | $\mu \mathrm{A}$ |
|  | S/W Shutdown Supply Current | EN= VIN, BUCK_ENx=0 |  | 41 | 75 | $\mu \mathrm{A}$ |
| V UVLO | Under-Voltage Lockout Threshold | $\mathrm{V}_{\text {IN }}$ Rising |  | 2.35 | 2.45 | V |
| V UVHYSt | Under-Voltage Lockout Hysteresis |  |  | 350 |  | mV |

## EN, VSEL, SDA, SCL

| $\mathrm{V}_{\mathrm{IH}}$ | HIGH-Level Input Voltage |  | 1.1 |  |  | V |
| :---: | :--- | :--- | :---: | :---: | :---: | :---: |
| $\mathrm{~V}_{\mathrm{IL}}$ | LOW-Level Input Voltage |  |  |  | 0.4 | V |
| $\mathrm{~V}_{\text {LHYST }}$ | Logic Input Hysteresis Voltage |  |  | 160 |  | mV |
| $\mathrm{I}_{\mathrm{IN}}$ | Input Bias Current | Input Tied to GND or VIN |  | 0.01 | 1.00 | $\mu \mathrm{~A}$ |

PGOOD (03 Option)

| I OutL | PGOOD Pull-Down Current |  |  |  | 1 | mA |
| :---: | :--- | :--- | :--- | :--- | :---: | :---: |
| I Outh | PGOOD HIGH Leakage Current |  |  | 0.01 | 1.00 | $\mu \mathrm{~A}$ |

$\mathrm{V}_{\text {OUT }}$ Regulation

| $V_{\text {ReG }}$ | Vout DC Accuracy | lout(DC)=0, Forced PWM, Vout=VSELO Default Value |  | -1.5 |  | 1.5 | \% |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | 08, 24 Options | $2.5 \mathrm{~V} \leq \mathrm{V}_{\mathrm{IN}} \leq 4.5 \mathrm{~V},$ <br> $\mathrm{V}_{\text {OUt }}$ from Minimum to Maximum, lout(DC)=0 to 4 A, Auto PFM/PWM | -2.0 |  | 4.0 | \% |
|  |  | 09 Option | $2.5 \mathrm{~V} \leq \mathrm{V}_{\mathrm{IN}} \leq 4.5 \mathrm{~V},$ <br> Vout from Minimum to Maximum, lout(DC)=0 to 3 A, Auto PFM/PWM | -2.0 |  | 4.0 | \% |
|  |  | $13,18,23$ Options | $2.5 \mathrm{~V} \leq \mathrm{V}_{\mathrm{IN}} \leq 4.5 \mathrm{~V},$ <br> $\mathrm{V}_{\text {OUt }}$ from Minimum to Maximum, $\mathrm{I}_{\mathrm{OUt}(\mathrm{DC})}=0$ to 5 A, Auto PFM/PWM | -2.0 |  | 4.0 | \% |
|  |  | All Other Options | $2.5 \mathrm{~V} \leq \mathrm{V}_{\mathrm{IN}} \leq 5.5 \mathrm{~V},$ <br> $\mathrm{V}_{\text {OUt }}$ from Minimum to Maximum, $\mathrm{I}_{\mathrm{OUt}(\mathrm{DC})}=0$ to 5 A, Auto PFM/PWM | -3.0 |  | 5.0 | \% |
| $\frac{\Delta \mathrm{V}_{\mathrm{OUT}}}{\Delta \mathrm{I}_{\mathrm{LOAD}}}$ | Load Regulation | $\operatorname{lout}(\mathrm{DC})=1$ to 5 A |  |  | -0.1 |  | \%/A |
| $\frac{\Delta \mathrm{V}_{\mathrm{OUT}}}{\Delta \mathrm{~V}_{\mathrm{IN}}}$ | Line Regulation | $2.5 \mathrm{~V} \leq \mathrm{V}_{\text {IN }} \leq 5.5 \mathrm{~V}$, $\mathrm{lout}_{(\mathrm{DC})}=1.5 \mathrm{~A}$ |  |  | 0.01 |  | \%/V |
| $\mathrm{V}_{\text {TRSP }}$ | Transient Response | ILoad Step 0.1 A to 1.5 A , $\mathrm{t}_{\mathrm{r}}=\mathrm{t}_{\mathrm{f}}=100 \mathrm{~ns}, \mathrm{~V}_{\text {Out }}=1.2 \mathrm{~V}$ |  |  | $\pm 40$ |  | mV |

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## Electrical Characteristics

Minimum and maximum values are at $\mathrm{V}_{\mathbb{N}}=2.5 \mathrm{~V}$ to $5.5 \mathrm{~V}, \mathrm{~T}_{\mathrm{A}}=-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$, unless otherwise noted. Typical values are at $\mathrm{T}_{\mathrm{A}}=25^{\circ} \mathrm{C}, \mathrm{V}_{\text {IN }}=5 \mathrm{~V}$, and $\mathrm{EN}=\mathrm{HIGH}$.

| Symbol | Parameter | Condition | Min. | Typ. | Max. | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Power Switch and Protection |  |  |  |  |  |  |
| $\mathrm{R}_{\text {DS(ON)P }}$ | P-Channel MOSFET On Resistance | $\mathrm{V}_{\text {IN }}=5 \mathrm{~V}$ |  | 28 |  | $\mathrm{m} \Omega$ |
| $\mathrm{R}_{\text {DS(ON)N }}$ | N-Channel MOSFET On Resistance | $\mathrm{V}_{\text {IN }}=5 \mathrm{~V}$ |  | 17 |  | $\mathrm{m} \Omega$ |
| ILIMPK | P-MOS Peak Current Limit | $00,01,03,04,13,18,23,042$ Options | 6.3 | 7.4 | 8.5 | A |
|  |  | 05 Option | 8.5 | 10.0 | 11.5 | A |
|  |  | 08, 24 Options | 5.0 | 5.9 | 6.8 | A |
|  |  | 09 Option | 4.0 | 4.75 | 5.5 |  |
| TLIMIT | Thermal Shutdown |  |  | 150 |  | ${ }^{\circ} \mathrm{C}$ |
| $\mathrm{T}_{\text {HYST }}$ | Thermal Shutdown Hysteresis |  |  | 17 |  | ${ }^{\circ} \mathrm{C}$ |
| $\mathrm{V}_{\text {SDWN }}$ | Input OVP Shutdown | Rising Threshold |  | 6.15 |  | V |
|  |  | Falling Threshold | 5.50 | 5.85 |  | V |
| Frequency Control |  |  |  |  |  |  |
| $\mathrm{f}_{\text {sw }}$ | Oscillator Frequency |  | 2.05 | 2.40 | 2.75 | MHz |
| DAC |  |  |  |  |  |  |
|  | Resolution |  |  | 6 |  | Bits |
|  | Differential Nonlinearity ${ }^{(8)}$ |  |  |  | 0.5 | LSB |
| Timing |  |  |  |  |  |  |
| $1^{2} \mathrm{C}_{\text {EN }}$ | EN=HIGH to ${ }^{2} \mathrm{C}$ Start |  | 100 |  |  | $\mu \mathrm{s}$ |
| Soft-Start |  |  |  |  |  |  |
| tss | Regulator Enable to Regulated $\mathrm{V}_{\text {OUT }}$ | $R_{\text {LOAD }}>5 \Omega$; to $\mathrm{V}_{\text {OUt }}=1.2 \mathrm{~V}$; $00,01,03,04,042,05,09,13$, and 23 Options |  | 300 |  | $\mu \mathrm{s}$ |
|  |  | $2.5 \mathrm{~V} \leq \mathrm{V}_{\mathrm{IN}} \leq 4.5 \mathrm{~V}$; $\mathrm{R}_{\mathrm{LOAD}}=2 \Omega$; to Vout=1.127 V with 1.1 V Pre-Bias Voltage; 08 and 18 Options |  | 135 | 175 | $\mu \mathrm{s}$ |
| $\mathrm{R}_{\text {OFF }}$ | VOUT Pull-Down Resistance, Disabled | $\mathrm{EN}=0$ or $\mathrm{V}_{\text {IN }}<\mathrm{V}_{\text {UVLI }}$ |  | 160 |  | $\Omega$ |

## Note:

8. Monotonicity assured by design.

## $I^{2} \mathrm{C}$ Timing Specifications

Guaranteed by design.

| Symbol | Parameter | Condition | Min. | Typ. | Max. | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $\mathrm{f}_{\text {SCL }}$ | SCL Clock Frequency | Standard Mode |  |  | 100 | kHz |
|  |  | Fast Mode |  |  | 400 |  |
|  |  | Fast Mode Plus |  |  | 1000 |  |
|  |  | High-Speed Mode, $\mathrm{C}_{\mathrm{B}} \leq 100 \mathrm{pF}$ |  |  | 3400 |  |
|  |  | High-Speed Mode, $\mathrm{C}_{\mathrm{B}} \leq 400 \mathrm{pF}$ |  |  | 1700 |  |
| $\mathrm{t}_{\text {BUF }}$ | Bus-Free Time between STOP and START Conditions | Standard Mode |  | 4.7 |  | $\mu \mathrm{s}$ |
|  |  | Fast Mode |  | 1.3 |  |  |
|  |  | Fast Mode Plus |  | 0.5 |  |  |
| thd; STA | START or REPEATED START Hold Time | Standard Mode |  | 4 |  | $\mu \mathrm{s}$ |
|  |  | Fast Mode |  | 600 |  | ns |
|  |  | Fast Mode Plus |  | 260 |  | ns |
|  |  | High-Speed Mode |  | 160 |  | ns |
| tLow | SCL LOW Period | Standard Mode |  | 4.7 |  | $\mu \mathrm{s}$ |
|  |  | Fast Mode |  | 1.3 |  | $\mu \mathrm{s}$ |
|  |  | Fast Mode Plus |  | 0.5 |  | $\mu \mathrm{s}$ |
|  |  | High-Speed Mode, $\mathrm{C}_{\mathrm{B}} \leq 100 \mathrm{pF}$ |  | 160.0 |  | ns |
|  |  | High-Speed Mode, $\mathrm{C}_{\mathrm{B}} \leq 400 \mathrm{pF}$ |  | 320.0 |  | ns |
| $t_{\text {HIGH }}$ | SCL HIGH Period | Standard Mode |  | 4 |  | $\mu \mathrm{s}$ |
|  |  | Fast Mode |  | 600 |  | ns |
|  |  | Fast Mode Plus |  | 260 |  | ns |
|  |  | High-Speed Mode, $\mathrm{C}_{\mathrm{B}} \leq 100 \mathrm{pF}$ |  | 60 |  | ns |
|  |  | High-Speed Mode, $\mathrm{C}_{\mathrm{B}} \leq 400 \mathrm{pF}$ |  | 120 |  | ns |
| $\mathrm{t}_{\text {Su; }}$ STA | REPEATED START Setup Time | Standard Mode |  | 4.7 |  | $\mu \mathrm{s}$ |
|  |  | Fast Mode |  | 600.0 |  | ns |
|  |  | Fast Mode Plus |  | 260.0 |  | ns |
|  |  | High-Speed Mode |  | 160.0 |  | ns |
| tsu;dat | Data Setup Time | Standard Mode |  | 250 |  | ns |
|  |  | Fast Mode |  | 100 |  |  |
|  |  | Fast Mode Plus |  | 50 |  |  |
|  |  | High-Speed Mode |  | 10 |  |  |
| $\mathrm{thd}_{\text {; DAT }}$ | Data Hold Time | Standard Mode | 0 |  | 3.45 | $\mu \mathrm{s}$ |
|  |  | Fast Mode | 0 |  | 900.00 | ns |
|  |  | Fast Mode Plus | 0 |  | 450.00 | ns |
|  |  | High-Speed Mode, $\mathrm{C}_{\mathrm{B}} \leq 100 \mathrm{pF}$ | 0 |  | 70.00 | ns |
|  |  | High-Speed Mode, $\mathrm{C}_{\mathrm{B}} \leq 400 \mathrm{pF}$ | 0 |  | 150.00 | ns |
| $t_{\text {RCL }}$ | SCL Rise Time | Standard Mode | 20+0 |  | 1000 | ns |
|  |  | Fast Mode | 20+0 |  | 300 |  |
|  |  | Fast Mode Plus | 20+0 |  | 120 |  |
|  |  | High-Speed Mode, $\mathrm{C}_{\mathrm{B}} \leq 100 \mathrm{pF}$ |  | 10 | 80 |  |
|  |  | High-Speed Mode, $\mathrm{C}_{\mathrm{B}} \leq 400 \mathrm{pF}$ |  | 20 | 160 |  |

Continued on the following page...
$I^{2} \mathrm{C}$ Timing Specifications (Continued)
Guaranteed by design.

| Symbol | Parameter | Condition | Min. | Typ. | Max. | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $t_{\text {FCL }}$ | SCL Fall Time | Standard Mode | 20+ |  | 300 | ns |
|  |  | Fast Mode | 20+ |  | 300 |  |
|  |  | Fast Mode Plus | $20+0.1 \mathrm{C}_{\text {в }}$ |  | 120 |  |
|  |  | High-Speed Mode, $\mathrm{C}_{\mathrm{B}} \leq 100 \mathrm{pF}$ |  | 10 | 40 |  |
|  |  | High-Speed Mode, $\mathrm{C}_{\mathrm{B}} \leq 400 \mathrm{pF}$ |  | 20 | 80 |  |
| $t_{\text {RCL1 }}$ | Rise Time of SCL After a REPEATED START Condition and After ACK Bit | High-Speed Mode, $\mathrm{C}_{\mathrm{B}} \leq 100 \mathrm{pF}$ |  | 10 | 80 | ns |
|  |  | High-Speed Mode, $\mathrm{C}_{\mathrm{B}} \leq 400 \mathrm{pF}$ |  | 20 | 160 |  |
| $t_{\text {RDA }}$ | SDA Rise Time | Standard Mode | $20+0.1 \mathrm{C}_{\text {в }}$ |  | 1000 | ns |
|  |  | Fast Mode | $20+0.1 \mathrm{C}_{\text {в }}$ |  | 300 |  |
|  |  | Fast Mode Plus | $20+0.1 \mathrm{C}_{\text {в }}$ |  | 120 |  |
|  |  | High-Speed Mode, $\mathrm{C}_{\mathrm{B}} \leq 100 \mathrm{pF}$ |  | 10 | 80 |  |
|  |  | High-Speed Mode, $\mathrm{C}_{\mathrm{B}} \leq 400 \mathrm{pF}$ |  | 20 | 160 |  |
| $\mathrm{t}_{\text {FDA }}$ | SDA Fall Time | Standard Mode | $20+0.1 \mathrm{C}_{\text {B }}$ |  | 300 | ns |
|  |  | Fast Mode | $20+0.1 \mathrm{C}_{\text {в }}$ |  | 300 |  |
|  |  | Fast Mode Plus | $20+0.1 \mathrm{C}_{\text {в }}$ |  | 120 |  |
|  |  | High-Speed Mode, $\mathrm{C}_{\mathrm{B}} \leq 100 \mathrm{pF}$ |  | 10 | 80 |  |
|  |  | High-Speed Mode, $\mathrm{C}_{\mathrm{B}} \leq 400 \mathrm{pF}$ |  | 20 | 160 |  |
| $\mathrm{t}_{\text {su; }}$ Sto | Stop Condition Setup Time | Standard Mode |  | 4 |  | $\mu \mathrm{s}$ |
|  |  | Fast Mode |  | 600 |  | ns |
|  |  | Fast Mode Plus |  | 120 |  | ns |
|  |  | High-Speed Mode |  | 160 |  | ns |
| $\mathrm{C}_{\mathrm{B}}$ | Capacitive Load for SDA and SCL |  |  |  | 400 | pF |

## Timing Diagrams



Figure 5. $I^{2} \mathrm{C}$ Interface Timing for Fast Plus, Fast, and Slow Modes


Figure 6. $I^{2} \mathrm{C}$ Interface Timing for High-Speed Mode

## Typical Characteristics

Unless otherwise specified, Auto $\mathrm{PFM} / \mathrm{PWM}, \mathrm{V}_{\mathbb{I N}}=3.6 \mathrm{~V}, \mathrm{~V}_{\text {OUT }}=1.2 \mathrm{~V}, \mathrm{SCL}=\mathrm{SDA}=\mathrm{VSEL}=\mathrm{EN}=1.8 \mathrm{~V}, \mathrm{~T}_{\mathrm{A}}=25^{\circ} \mathrm{C}$; circuit and components according to Figure 1 and Table 1.


Figure 7. Efficiency vs. Load Current and Input Voltage


Figure 9. Efficiency vs. Load Current and Input Voltage, $V_{\text {out }}=0.9 \mathrm{~V}$


Figure 11. Efficiency vs. Load Current and Input Voltage, $V_{\text {out }}=0.6 \mathrm{~V}$


Figure 8. Efficiency vs. Load Current and Temperature


Figure 10. Efficiency vs. Load Current and Temperature, $V_{\text {IN }}=5 \mathrm{~V}, \mathrm{~V}_{\text {OUT }}=1.2 \mathrm{~V}$


Figure 12. Efficiency vs. Load Current, $\mathrm{V}_{\mathrm{IN}}=3.6 \mathrm{~V}$ and 5 V , $V_{\text {OUt }}=1.2 \mathrm{~V}$ and 0.9 V

## Typical Characteristics (Continued)

Unless otherwise specified, Auto $\mathrm{PFM} / \mathrm{PWM}, \mathrm{V}_{\mathbb{I}}=3.6 \mathrm{~V}, \mathrm{~V}_{\text {OUT }}=1.2 \mathrm{~V}, \mathrm{SCL}=\mathrm{SDA}=\mathrm{VSEL}=\mathrm{EN}=1.8 \mathrm{~V}, \mathrm{~T}_{\mathrm{A}}=25^{\circ} \mathrm{C}$; circuit and components according to Figure 1 and Table 1.


Figure 13. Output Regulation vs. Load Current and Input Voltage, $\mathrm{V}_{\text {out }}=1.2 \mathrm{~V}$


Figure 15. PFM Entry / Exit Level vs. Input Voltage, $V_{\text {out }}=1.2$ V


Figure 17. Output Ripple vs. Load Current, $\mathrm{V}_{\mathrm{IN}}=5 \mathrm{~V}$ and 3.6 V, V


Figure 14. Output Regulation vs. Load Current and Input Voltage, $\mathrm{V}_{\text {OUT }}=0.9 \mathrm{~V}$


Figure 16. PFM Entry / Exit Level vs. Input Voltage, $V_{\text {out }}=0.9 \mathrm{~V}$


Figure 18. Frequency vs. Load Current, $\mathrm{V}_{\mathrm{IN}}=5 \mathrm{~V}$ and 3.6 V , $\mathrm{V}_{\text {out }}=1.2 \mathrm{~V}$ and 0.9 V , Auto PWM

Typical Characteristics (Continued)
Unless otherwise specified, Auto PFM/PWM, $\mathrm{V}_{\mathbb{I}}=3.6 \mathrm{~V}, \mathrm{~V}_{\mathrm{OUT}}=1.2 \mathrm{~V}, \mathrm{SCL}=\mathrm{SDA}=\mathrm{VSEL}=\mathrm{EN}=1.8 \mathrm{~V}, \mathrm{~T}_{\mathrm{A}}=25^{\circ} \mathrm{C}$; circuit and components according to Figure 1 and Table 1.


Figure 19. Quiescent Current vs. Input Voltage and Temperature, Auto PWM


Figure 21. Shutdown Current vs. Input Voltage and Temperature


Figure 23. Line Transient, 3-4 $\mathrm{V}_{\mathrm{IN}}, 1.2 \mathrm{~V}_{\mathrm{OUT}}, 10 \mu \mathrm{~s}$ Edge, $50 \Omega$ Load


Figure 20. Quiescent Current vs. Input Voltage and Temperature, FPWM


Figure 22. PSRR vs. Frequency


Figure 24. Line Transient, 3-4 $\mathrm{V}_{\mathrm{IN}}, 1.2 \mathrm{~V}_{\mathrm{out}}, 10 \mu \mathrm{~s}$ Edge, 1 A Load

## Typical Characteristics (Continued)

Unless otherwise specified, Auto PFM/PWM, $\mathrm{V}_{\text {IN }}=3.6 \mathrm{~V}, \mathrm{~V}_{\text {OUT }}=1.2 \mathrm{~V}, \mathrm{SCL}=\mathrm{SDA}=\mathrm{VSEL}=\mathrm{EN}=1.8 \mathrm{~V}, \mathrm{~T}_{\mathrm{A}}=25^{\circ} \mathrm{C}$; circuit and components according to Figure 1 and Table 1.


Figure 25. Load Transient, $5 \mathrm{~V}_{\mathrm{IN}}, 0.9 \mathrm{~V}_{\text {out, }}$ 0.3-3 A, 100 ns Edge


Figure 27. Load Transient, 3.6 $\mathrm{V}_{\mathrm{IN}}$, 1.2 $\mathrm{V}_{\mathrm{OUT}}$, 0.3-3 A, 100 ns Edge, Cout=4x22 $\mu \mathrm{F}$


Figure 29. Input Over-Voltage Protection

## Typical Characteristics (Continued)

Unless otherwise specified, Auto PFM/PWM, $\mathrm{V}_{\text {IN }}=3.6 \mathrm{~V}, \mathrm{~V}_{\text {OUT }}=1.2 \mathrm{~V}, \mathrm{SCL}=\mathrm{SDA}=\mathrm{VSEL}=\mathrm{EN}=1.8 \mathrm{~V}, \mathrm{~T}_{\mathrm{A}}=25^{\circ} \mathrm{C}$; circuit and components according to Figure 1 and Table 1.


Figure 30. Startup / Shutdown, No Load, Vout=0.9 V


Figure 32. Overload Protection and Recovery


Figure 31. Startup / Shutdown, $180 \mathrm{~m} \Omega$ Load, $\mathrm{V}_{\text {out }}=0.9 \mathrm{~V}$


Figure 33. Startup into Faulted Load, $\mathrm{V}_{\text {Out }}=0.9 \mathrm{~V}$

## Operation Description

The FAN53555 is a step-down switching voltage regulator that delivers a programmable output voltage from an input voltage supply of 2.5 V to 5.5 V . Using a proprietary architecture with synchronous rectification, the FAN53555 is capable of delivering 5 A at over $80 \%$ efficiency. Pulse currents as high as 6.5 A can be supported by the 05 option. The regulator operates at a nominal frequency of 2.4 MHz at full load, which reduces the value of the external components to 330 nH for the output inductor and $22 \mu \mathrm{~F}$ for the output capacitor. High efficiency is maintained at light load with single-pulse PFM.
The FAN53555 integrates an $\mathrm{I}^{2} \mathrm{C}$-compatible interface, allowing transfers up to 3.4 Mbps . This communication interface can be used to:

- Dynamically re-program the output voltage in 10 mV , 12.826 mV increments (option 04, 09, and 042), 12.5 mV increments (option 23), or 12.967 mV increments (option 24);
- Reprogram the mode to enable or disable PFM;
- Control voltage transition slew rate; or
- Enable / disable the regulator.


## Control Scheme

The FAN53555 uses a proprietary non-linear, fixed-frequency PWM modulator to deliver a fast load transient response, while maintaining a constant switching frequency over a wide range of operating conditions. The regulator performance is independent of the output capacitor ESR, allowing for the use of ceramic output capacitors. Although this type of operation normally results in a switching frequency that varies with input voltage and load current, an internal frequency loop holds the switching frequency constant over a large range of input voltages and load currents.
For very light loads, the FAN53555 operates in Discontinuous Current Diode (DCM) single-pulse PFM, which produces low output ripple compared with other PFM architectures. Transition between PWM and PFM is relatively seamless, providing a smooth transition between DCM and CCM Modes.
PFM can be disabled by programming the MODE bit HIGH in the VSEL registers.

## Enable and Soft-Start

When the EN pin is LOW; the IC is shut down, all internal circuits are off, and the part draws very little current. In this state, $I^{2} C$ cannot be written to or read from. For all options except the 04, 24, and 042 options, all register values are kept while EN pin is LOW. For the 04, 24 and 042 options; registers are reset to default values when EN pin is LOW. For all options, registers are reset to default values during a Power On Reset (POR).
When the OUTPUT_DISCHARGE bit in the CONTROL register is enabled (logic HIGH) and the EN pin is LOW or the BUCK_ENx bit is LOW, a load is connected from VOUT to GND to discharge the output capacitors.

Raising EN while the BUCK_ENx bit is HIGH activates the part and begins the soft-start cycle. During soft-start, the modulator's internal reference is ramped slowly to minimize surge currents on the input and prevent overshoot of the
output voltage. Synchronous rectification is inhibited during soft-start, allowing the IC to start into a pre-charged capacitive load.

If large output capacitance values are used, the regulator may fail to start. Maximum Cout capacitance for successfully starting with a heavy constant-current load is approximately:

$$
\begin{equation*}
\mathrm{C}_{\text {OUTMAX }} \approx\left(\mathrm{I}_{\text {LIMPK }}-\mathrm{I}_{\text {LOAD }}\right) \cdot \frac{320 \mu}{\mathrm{~V}_{\text {OUT }}} \tag{1}
\end{equation*}
$$

where Coutmax is expressed in $\mu \mathrm{F}$ and $\mathrm{I}_{\text {load }}$ is the load current during soft-start, expressed in A.
If the regulator is at its current limit for 16 consecutive current limit cycles, the regulator shuts down and enters 3 -state before reattempting soft-start 1700 ms later. This limits the duty cycle of full output current during soft-start to prevent excessive heating.

The IC allows for software enable of the regulator, when EN is HIGH, through the BUCK_EN bits. BUCK_ENO and BUCK_EN1 are both initialized HIGH in the 00, 04, 08, 09, 23, 24, and 042 options. These options start after a POR regardless of the state of the VSEL pin.
In the 01 and 05 options, BUCK_ENO and BUCK_EN1 are initialized to 10. Using these options, VSEL must be LOW after a POR if the IC is powering the processor used to communicate through $I^{2} \mathrm{C}$. The 03 option has the VSEL input to the modulator logic internally tied LOW.
Table 5. Hardware and Software Enable

| Pins |  | BITS |  |  |
| :---: | :---: | :---: | :---: | :---: |
| EN | VSEL | BUCK_ENO | BUCK_EN1 | Output |
| 0 | $X$ | $X$ | $X$ | OFF |
| 1 | 0 | 0 | $X$ | OFF |
| 1 | 0 | 1 | $X$ | ON |
| 1 | 1 | $X$ | 0 | OFF |
| 1 | 1 | X | 1 | ON |

## VSEL Pin and ${ }^{2} \mathrm{C}$ Programming Output Voltage

The output voltage is set by the NSELx control bits in VSELO and VSEL1 registers. The output voltage for options 00, 01, $03,05,08$, and 18 is given as:

$$
\begin{equation*}
\mathrm{V}_{\text {OUT }}=0.60 \mathrm{~V}+\text { NSELx } \bullet 10 \mathrm{mV} \tag{2}
\end{equation*}
$$

For example, when NSEL = 011111 (31 decimal), then $\mathrm{V}_{\text {OUt }}=$ $0.60+0.310=0.91 \mathrm{~V}$.
For the 04,042 , and 09 options; the output voltage is given as:

$$
\begin{equation*}
V_{\text {OUT }}=0.603 \mathrm{~V}+\mathrm{NSELx} \bullet 12.826 \mathrm{mV} \tag{3}
\end{equation*}
$$

For the 13 option, the output voltage is given as:

$$
\begin{equation*}
\mathrm{V}_{\text {OUT }}=0.80 \mathrm{~V}+\text { NSELx } \bullet 10 \mathrm{mV} \tag{4}
\end{equation*}
$$

For the 23 option, the output voltage is given as:

$$
\begin{equation*}
V_{\text {OUT }}=0.60 \mathrm{~V}+\text { NSELx } \bullet 12.5 \mathrm{mV} \tag{5}
\end{equation*}
$$

For the 24 option, the output voltage is given as:

$$
\begin{equation*}
V_{\text {OUT }}=0.603 V+N S E L x \times 12.967 m V \tag{6}
\end{equation*}
$$

Output voltage can also be controlled by toggling the VSEL pin LOW or HIGH. VSEL LOW corresponds to VSELO and VSEL HIGH corresponds to VSEL1. Upon POR, VSELO and VSEL1 are reset to their default voltages, shown in Table 9.

## Transition Slew Rate Limiting

When transitioning from a low to high voltage, the IC can be programmed for one of eight possible slew rates using the SLEW bits in the CONTROL register.

Table 6. Transition Slew Rate

| Decimal | Bin | Slew Rate |  |
| :---: | :---: | :---: | :---: |
| 0 | 000 | 64.00 | $\mathrm{mV} / \mu \mathrm{s}$ |
| 1 | 001 | 32.00 | $\mathrm{mV} / \mu \mathrm{s}$ |
| 2 | 010 | 16.00 | $\mathrm{mV} / \mu \mathrm{s}$ |
| 3 | 011 | 8.00 | $\mathrm{mV} / \mu \mathrm{s}$ |
| 4 | 100 | 4.00 | $\mathrm{mV} / \mu \mathrm{s}$ |
| 5 | 101 | 2.00 | $\mathrm{mV} / \mu \mathrm{s}$ |
| 6 | 110 | 1.00 | $\mathrm{mV} / \mu \mathrm{s}$ |
| 7 | 111 | 0.50 | $\mathrm{mV} / \mu \mathrm{s}$ |

Transitions from high to low voltage rely on the output load to discharge $V_{\text {out t }}$ to the new set point. Once the high-to-low transition begins, the IC stops switching until Vout has reached the new set point.
For options 04, 042, 09, 23, and 24 where the Dynamic Voltage Scaling (DVS) step is not 10 mV ; the actual slew rate is the corresponding number shown in Table 6 scaled by the ratio of the DVS step to 10 mV . For example, the slew rate of option 13 for $\mathrm{Bin}=011$ is $8.00 \mathrm{mV} / \mu \mathrm{s} \times 12.5 \mathrm{mV} / 10 \mathrm{mV}=$ $10.00 \mathrm{mV} / \mu \mathrm{s}$.

## Under-Voltage Lockout

When EN is HIGH, the under-voltage lockout keeps the part from operating until the input supply voltage rises HIGH enough to properly operate. This ensures proper operation of the regulator during startup or shutdown.

## Input Over-Voltage Protection (OVP)

When $\mathrm{V}_{\mathbb{I N}}$ exceeds $\mathrm{V}_{\text {SDWN }}($ about 6.2 V ) the IC stops switching to protect the circuitry from internal spikes above 6.5 V . An internal filter prevents the circuit from shutting down due to noise spikes.

## Power Good (03 Option)

The PGOOD pin is an open-drain output indicating that the regulator is enabled when its state is HIGH. PGOOD pulls LOW under the following conditions:

- Regulator is disabled (EN pin LOW, disabled by $I^{2} C$, fault time-out, UVLO, OVP, over-temperature);
- Regulator is performing a soft-start.

PGOOD remains HIGH during $I^{2} \mathrm{C}$ initiated $\mathrm{V}_{\text {OUT }}$ transitions.

## Current Limiting

A heavy load or short circuit on the output causes the current in the inductor to increase until a maximum current threshold is reached in the high-side switch. Upon reaching this point, the high-side switch turns off, preventing high currents from causing damage. Sixteen consecutive current limit cycles in current limit cause the regulator to shut down and stay off for about $1700 \mu$ s before attempting a restart.

## Thermal Shutdown

When the die temperature increases, due to a high load condition and/or high ambient temperature, the output switching is disabled until the die temperature falls sufficiently. The junction temperature at which the thermal shutdown activates is nominally $150^{\circ} \mathrm{C}$ with a $17^{\circ} \mathrm{C}$ hysteresis.

## Monitor Register (Reg05)

The Monitor register indicates of the regulation state of the IC. If the IC is enabled and is regulating, its value is (1000 0000).

## $I^{2} \mathbf{C}$ Interface

The FAN53555's serial interface is compatible with Standard, Fast, Fast Plus, and HS Mode $I^{2} \mathrm{C}-\mathrm{Bus} ®$ specifications. The FAN53555's SCL line is an input and its SDA line is a bidirectional open-drain output; it can only pull down the bus when active. The SDA line only pulls LOW during data reads and when signaling ACK. All data is shifted in MSB (bit 7) first.

## $I^{2} C$ Slave Address

In hex notation, the slave address assumes a 0 LS Bit. The hex slave address is C0 for all options except -42, which has a hex slave address of C 4 .

## Table 7. $1^{2} \mathrm{C}$ Slave Address

| Option | Hex | Bits |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | $\mathbf{7}$ | $\mathbf{6}$ | $\mathbf{5}$ | $\mathbf{4}$ | $\mathbf{3}$ | $\mathbf{2}$ | $\mathbf{1}$ | $\mathbf{0}$ |
| 00 to 24 | C 0 | 1 | 1 | 0 | 0 | 0 | 0 | 0 | $\mathrm{R} / \overline{\mathrm{W}}$ |
| 42 | C 4 | 1 | 1 | 0 | 0 | 0 | 1 | 0 | $\mathrm{R} / \overline{\mathrm{W}}$ |

Other slave addresses can be assigned. Contact a Fairchild Semiconductor representative.

## Bus Timing

As shown in Figure 34, data is normally transferred when SCL is LOW. Data is clocked in on the rising edge of SCL. Typically, data transitions shortly at or after the falling edge of SCL to allow ample time for the data to set up before the next SCL rising edge.


Figure 34. Data Transfer Timing
Each bus transaction begins and ends with SDA and SCL HIGH. A transaction begins with a START condition, which is defined as SDA transitioning from 1 to 0 with SCL HIGH, as shown in Figure 35.


Figure 35. START Bit
A transaction ends with a STOP condition, which is defined as SDA transitioning from 0 to 1 with SCL HIGH, as shown in Figure 36.


Figure 36. STOP Bit
During a read from the FAN53555, the master issues a REPEATED START after sending the register address, and before resending the slave address. The REPEATED START is a 1 to 0 transition on SDA while SCL is HIGH, as shown in Figure 37.


Figure 37. REPEATED START Timing

## High-Speed (HS) Mode

The protocols for High-Speed (HS), Low-Speed (LS), and Fast-Speed (FS) Modes are identical, except the bus speed for HS mode is 3.4 MHz . HS Mode is entered when the bus master sends the HS master code 00001XXX after a START condition. The master code is sent in Fast or Fast-Plus Mode (less than 1 MHz clock); slaves do not ACK this transmission.

The master generates a REPEATED START condition (Figure 35) that causes all slaves on the bus to switch to HS Mode. The master then sends $I^{2} C$ packets, as described above, using the HS Mode clock rate and timing.
The bus remains in HS Mode until a STOP bit (Figure 36) is sent by the master. While in HS Mode, packets are separated by REPEATED START conditions (Figure 37).

## Read and Write Transactions

The following figures outline the sequences for data read and write. Bus control is signified by the shading of the packet,
defined as Master Drives Bus and Slave Drives Bus. All addresses and data are MSB first.
Table 8. $I^{2} \mathrm{C}$ Bit Definitions for Figure 38 \& Figure 39

| Symbol | Definition |
| :---: | :--- |
| $R$ | REPEATED START, see Figure 37 |
| $P$ | STOP, see Figure 36 |
| S | START, see Figure 35 |
| $A$ | ACK. The slave drives SDA to 0 to <br> acknowledge the preceding packet. |
| $\bar{A}$ | NACK. The slave sends a 1 to NACK the <br> preceding packet. |
| $R$ | REPEATED START, see Figure 37. |
| $P$ | STOP, see Figure 36. |



Figure 38. Write Transaction


Figure 39. Read Transaction

## Register Description

Table 9. Register Map

| Hex Address | Name | Function | POR Default |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  | Option | $\mathrm{V}_{\text {OUT }}$ | Binary | Hex |
| 00 | VSELO | Controls V ${ }_{\text {OUT }}$ settings when VSEL pin $=0$ | 00 | 1.050 | 10101101 | AD |
|  |  |  | 08, 18 | 1.020 | 10101010 | AA |
|  |  |  | 01, 03, 05 | 0.900 | 10011110 | 9 E |
|  |  |  | 04, | 1.100 | 10100111 | A7 |
|  |  |  | 24 | 1.225 | 10110000 | B0 |
|  |  |  | 13 | 1.150 | 10100011 | A3 |
|  |  |  | 23 | 1.150 | 10101100 | AC |
|  |  |  | 09 | 1.100 | 10100111 | A7 |
| 01 | VSEL1 | Controls Vout settings when VSEL pin $=1$ | 00 | 1.200 | 11111100 | FC |
|  |  |  | 01, 05 | 1.000 | 01101000 | 68 |
|  |  |  | 04, | 1.200 | 11101111 | EF |
|  |  |  | 24 | 1.212 | 10101111 | AF |
|  |  |  | 08, 18 | 1.150 | 10110111 | B7 |
|  |  |  | 13 | 1.150 | 10100011 | A3 |
|  |  |  | 23 | 1.150 | 10101100 | AC |
|  |  |  | 09 | 1.100 | 11100111 | E7 |
| 02 | CONTROL | Determines whether Vout output discharge is enabled and also the slew rate of positive transitions | $\begin{aligned} & 00,01,03, \\ & 04,05,24 \end{aligned}$ |  | 10000000 | 80 |
|  |  |  | 08, 09, 18 |  | 00000000 | 00 |
|  |  |  | 13, 23 |  | 10110000 | B0 |
| 03 | ID1 | Read-only register identifies vendor and chip type | $\begin{gathered} 00,13,23, \\ 24 \end{gathered}$ |  | 10000000 | 80 |
|  |  |  | 01 |  | 10000001 | 81 |
|  |  |  | 03 |  | 10000011 | 83 |
|  |  |  | 04 |  | 10000100 | 84 |
|  |  |  | 05 |  | 10000101 | 85 |
|  |  |  | 08, 18 |  | 10001000 | 88 |
|  |  |  | 09 |  | 10001100 | 8C |
| 04 | ID2 | Read-only register identifies die revision | All |  | 0000XXXX | 0X |
| 05 | MONITOR | Indicates device status | All |  | X0000000 | x0 |

## Bit Definitions

The following table defines the operation of each register bit. Bold indicates power-on default values.

| Bit | Name | Value | Description |
| :---: | :---: | :---: | :---: |
| vSELO R/w | R/W | Register Address: 00 |  |
| 7 | BUCK_ENO | 1 | Software buck enable. When EN pin is LOW, the regulator is off. When EN pin is HIGH, BUCK_EN bit takes precedent. |
| 6 | MODE0 | 0 | Allow Auto-PFM Mode during light load. |
|  |  | 1 | Forced PWM Mode. |
| 5:0 | NSELO | $00 \text { Option }$ $101101$ | Sets $\mathrm{V}_{\text {Out }}$ value from 0.6 to 1.23 V in 10 mV steps (see Eq. (2)). |
|  |  | $\begin{aligned} & \text { 08, } 18 \text { Options } \\ & 101010 \end{aligned}$ |  |
|  |  | $\text { 01, 03, } 05 \text { Options }$ $011110$ |  |
|  |  | 04 Option <br> 100111 | Sets $V_{\text {out }}$ value from 0.603 to 1.411 V in 12.826 mV steps (see Eq. (3)). |
|  |  | $\begin{aligned} & \hline 09 \text { Option } \\ & 100111 \end{aligned}$ |  |
|  |  | $\begin{gathered} 13 \text { Option } \\ 100011 \end{gathered}$ | Sets Vout value from 0.8 to 1.43 V in 10 mV steps (see Eq. (4)). |
|  |  | $\begin{gathered} 23 \text { Option } \\ 101100 \end{gathered}$ | Sets $\mathrm{V}_{\text {out }}$ value from 0.6 to 1.3875 V in 12.5 mV steps (see Eq. (5)). |
|  |  | $\begin{gathered} 24 \text { Option } \\ 110000 \end{gathered}$ | Sets $\mathrm{V}_{\text {Out }}$ value from 0.603 to 1.42 V in 12.967 mV steps (see Eq. (6)). |
| VS | R/W Register Address: 01 |  |  |
| 7 | BUCK_EN1 | 00, 04, 08, 09,13, 18, 23, 24 Options 1 | Software buck enable. When EN pin is LOW, the regulator is off. When EN pin is HIGH, BUCK_EN bit takes precedent. |
|  |  | $\begin{gathered} \text { 01, } 05 \text { Options } \\ \mathbf{0} \end{gathered}$ |  |
| 6 | MODE1 | 08, 13, 18, 23, 24 Options 0 | Allow AUTO-PFM Mode during light load. |
|  |  | 00, 01, 04, 05, 09 Options 1 | Forced PWM Mode. |
| 5:0 | NSEL1 | $\begin{aligned} & 00 \text { Option } \\ & 111100 \end{aligned}$ | Sets $\mathrm{V}_{\text {out }}$ value from 0.6 to 1.23 V in 10 mV steps (see Eq. (2)). |
|  |  | $\begin{aligned} & \text { 01, } 05 \text { Options } \\ & 101000 \end{aligned}$ |  |
|  |  | $\begin{aligned} & \hline \text { 08, } 18 \text { Options } \\ & \mathbf{1 1 0 1 1 1} \end{aligned}$ |  |
|  |  | $\begin{aligned} & 04 \text { Option } \\ & 101111 \end{aligned}$ | Sets $\mathrm{V}_{\text {out }}$ value from 0.603 to 1.411 V in 12.826 mV steps (see Eq. (3)). |
|  |  | 09 Option <br> 100111 |  |
|  |  | $\begin{gathered} 13 \text { Option } \\ 100011 \end{gathered}$ | Sets $\mathrm{V}_{\text {out }}$ value from 0.8 to 1.43 V in 10 mV steps (see Eq. (4)). |
|  |  | $\begin{gathered} 23 \text { Option } \\ 101100 \end{gathered}$ | Sets $\mathrm{V}_{\text {out }}$ value from 0.6 to 1.3875 V in 12.5 mV steps (see Eq. (5)). |
|  |  | 24 Option 101111 | Sets $\mathrm{V}_{\text {out }}$ value from 0.603 to 1.42 V in 12.967 mV steps (see Eq. (6)). |

## Bit Definitions

The following table defines the operation of each register bit. Bold indicates power-on default values.

| Bit | Name | Value | Description |
| :---: | :---: | :---: | :---: |
| CONTROL R/W |  | Register Address: 02 |  |
| 7 | OUTPUT_DISCHARGE | 08, 09, 18 Options <br> 0 | When the regulator is disabled, $\mathrm{V}_{\text {out }}$ is not discharged. |
|  |  | $\begin{gathered} \text { 00, 01, 03, 04, } \\ 05,13,23,24 \\ \text { Options } \\ \mathbf{1} \\ \hline \end{gathered}$ | When the regulator is disabled, $\mathrm{V}_{\text {Out }}$ discharges through an internal pull-down. |
| 6:4 | SLEW | 000-111 | Sets the slew rate for positive voltage transitions (see Table 6). |
|  |  | 011 | Default value for 13 and 23 options |
| 3 | Reserved | 0 | Always reads back 0 |
| 2 | 04, 09, 24 Options RESET | 0 | Setting to 1 resets all registers to default values. |
|  | All other options Reserved | 0 | Always reads back 0 |
| 1:0 | Reserved | 00 | Always reads back 00 |
| ID1 | R | Register Addr <br> 100 <br> 0 | ss: 03 |
| 7:5 | VENDOR |  | Signifies Fairchild as the IC vendor |
| 4 | Reserved |  | Always reads back 0 |
| 3:0 | DIE_ID | 0000 | IC Type = 00 Option (FAN53555UC00X / FAN53555BUC24X) |
|  |  | 0001 | IC Type = 01 Option (FAN53555UC01X) |
|  |  | 0011 | IC Type = 03 Option (FAN53555UC03X) |
|  |  | 0100 | IC Type = 04 Option (FAN53555UC04X) |
|  |  | 0100 | IC Type $=042$ Option (FAN53555UC042X) |
|  |  | 0101 | IC Type $=05$ Option (FAN53555UC05X / FAN53555BUC05X) |
|  |  | 1000 | IC Type = 08, 18 Options (FAN53555UC08X / FAN53555BUC08X, FAN53555UC18X / FAN53555BUC18X) |
|  |  | 1100 | IC Type = 09 Option (FAN53555UC09X / FAN53555BUC09X) |
|  |  | 0000 | IC Type = 13 Option (FAN53555UC13X / FAN53555BUC13X) |
|  |  | 0000 | IC Type = 23 Option (FAN53555BUC23X) |
| ID2 | R | Register Add | ss: 04 |
| 7:4 | Reserved |  | Always reads back 0000 |
| 3:0 | DIE_REV | 00 Option | IC mask revision |
|  |  | $\begin{aligned} & 01 \text { Option } \\ & 0011 \end{aligned}$ |  |
|  |  | 03 Option 0011 |  |
|  |  | 04 Option 1111 |  |
|  |  | $\begin{aligned} & \text { 24-Option } \\ & 0100 \end{aligned}$ |  |
|  |  | $\begin{gathered} \hline 042 \text { Option } \\ 1111 \end{gathered}$ |  |
|  |  | 05 Option 0011 |  |
|  |  | $\begin{gathered} \hline 08,18 \text { Options } \\ 0001 \end{gathered}$ |  |

## Bit Definitions

The following table defines the operation of each register bit. Bold indicates power-on default values.

| Bit | Name | Value | Description |
| :---: | :---: | :---: | :---: |
|  |  | BUC08, BUC18 Options 1111 |  |
|  |  | $\begin{gathered} 09 \text { Option } \\ 1111 \end{gathered}$ |  |
|  |  | 13 Option |  |
|  |  | $\begin{aligned} & 23 \text { Option } \\ & 1100 \end{aligned}$ |  |
| MONITOR R |  | Register Address: 05 |  |
| 7 | PGOOD | 0 | 1: buck is enabled and soft-start is completed |
| 6:0 | Not used | 0000000 | Always reads back 0000000 |

## Application Information

## Selecting the Inductor

The output inductor must meet both the required inductance and the energy-handling capability of the application. The inductor value affects the average current limit, the output voltage ripple, and the efficiency.
The ripple current $(\Delta I)$ of the regulator is:

$$
\begin{equation*}
\Delta I \approx \frac{V_{O U T}}{V_{\mathbb{N}}} \cdot\left(\frac{V_{\mathbb{N}}-V_{O U T}}{L \bullet f_{S W}}\right) \tag{7}
\end{equation*}
$$

The maximum average load current, $I_{\mathrm{MAX}(\mathrm{LOAD}), \text {, is related to }}$ the peak current limit, $\operatorname{lıIm(PK),~by~the~ripple~current~such~that:~}$

$$
\begin{equation*}
\mathrm{I}_{\mathrm{MAX}(\mathrm{LOAD})}=\mathrm{I}_{\mathrm{LIM}(\mathrm{PK})}-\frac{\Delta \mathrm{l}}{2} \tag{8}
\end{equation*}
$$

The FAN53555 is optimized for operation with $\mathrm{L}=330 \mathrm{nH}$, but is stable with inductances up to $1.0 \mu \mathrm{H}$ (nominal). The inductor should be rated to maintain at least $80 \%$ of its value at $\mathrm{I}_{\mathrm{LIM}(\mathrm{PK}) \text {. Failure to do so lowers the amount of DC current }}$ the IC can deliver.
Efficiency is affected by the inductor DCR and inductance value. Decreasing the inductor value for a given physical size typically decreases the DCR; but since $\Delta l$ increases, the RMS current increases, as do core and skin-effect losses.

$$
\begin{equation*}
\mathrm{I}_{\mathrm{RMS}}=\sqrt{\mathrm{I}_{\mathrm{OUT}(\mathrm{DC})^{2}+\frac{\Delta \mathrm{I}^{2}}{12}} \text {. }} \tag{9}
\end{equation*}
$$

The increased RMS current produces higher losses through the $R_{D S(O N)}$ of the IC MOSFETs as well as the inductor ESR.
Increasing the inductor value produces lower RMS currents, but degrades transient response. For a given physical inductor size, increased inductance usually results in an inductor with lower saturation current.
Table 10. Effects of Inductor Value (from 330 nH Recommended) on Regulator Performance

| $\mathbf{I}_{\text {MAX(LOAD) }}$ | $\Delta \mathbf{V}_{\text {OUT }}{ }^{\text {(Eq.(11)) }}$ | Transient Response |
| :---: | :---: | :---: |
| Increase | Decrease | Degraded |

## Inductor Current Rating

The current limit circuit can allow substantial peak currents to flow through L1 under worst-case conditions. If it is possible for the load to draw such currents, the inductor should be capable of sustaining the current or failing in a safe manner.
For space-constrained applications, a lower current rating for L1 can be used. The FAN53555 may still protect these inductors in the event of a short circuit, but may not be able to protect the inductor from failure if the load is able to draw higher currents than the DC rating of the inductor.

## Output Capacitor and V

Table 1 suggests 0805 capacitors, but 0603 capacitors may be used if space is at a premium. Due to voltage effects, the 0603 capacitors have a lower in-circuit capacitance than the 0805 package, which can degrade transient response and output ripple.

Increasing Cout has negligible effect on loop stability and can be increased to reduce output voltage ripple or to improve transient response. Output voltage ripple, $\Delta \mathrm{V}_{\text {OUT }}$, is calculated by:

$$
\begin{equation*}
\Delta \mathrm{V}_{\text {OUT }}=\Delta \mathrm{L}_{\mathrm{L}}\left[\frac{\mathrm{f}_{\mathrm{SW}} \cdot \mathrm{C}_{\mathrm{OUT}} \cdot \mathrm{ESR}^{2}}{2 \cdot \mathrm{D} \cdot(1-\mathrm{D})}+\frac{1}{8 \cdot \mathrm{f}_{\mathrm{SW}} \cdot \mathrm{C}_{\mathrm{OUT}}}\right] \tag{10}
\end{equation*}
$$

where Cout is the effective output capacitance.
The capacitance of Cout decreases at higher output voltages, which results in higher $\Delta \mathrm{V}_{\text {Out }}$. Equation (10) is only valid for Continuous Current Mode (CCM) operation, which occurs when the regulator is in PWM Mode.
For large Cout values, the regulator may fail to start under a load. If an inductor value greater than $1.0 \mu \mathrm{H}$ is used, at least $30 \mu \mathrm{~F}$ of Cout should be used to ensure stability.

The lowest $\Delta \mathrm{V}_{\text {Out }}$ is obtained when the IC is in PWM Mode and, therefore, operating at 2.4 MHz . In PFM Mode, $\mathrm{f}_{\mathrm{Sw}}$ is reduced, causing $\Delta \mathrm{V}_{\text {OUt }}$ to increase.

## ESL Effects

The Equivalent Series Inductance (ESL) of the output capacitor network should be kept low to minimize the squarewave component of output ripple that results from the division ratio Cout ESL and the output inductor (Lout). The squarewave component due to the ESL can be estimated as:

$$
\begin{equation*}
\Delta \mathrm{V}_{\mathrm{OUT}(\mathrm{SQ})} \approx \mathrm{V}_{\mathbb{I N}} \cdot \frac{\mathrm{ES} L_{\text {COUT }}}{\mathrm{L} 1} \tag{11}
\end{equation*}
$$

A good practice to minimize this ripple is to use multiple output capacitors to achieve the desired Cout value. For example, to obtain $\mathrm{C}_{\text {out }}=20 \mu \mathrm{~F}$, a single $22 \mu \mathrm{~F} 0805$ would produce twice the square wave ripple as two $\times 10 \mu \mathrm{~F} 0805$.

To minimize ESL, try to use capacitors with the lowest ratio of length to width. 0805s have lower ESL than 1206s. If low output ripple is a chief concern, some vendors produce 0508 or 0612 capacitors with ultra-low ESL. Placing additional small-value capacitors near the load also reduces the highfrequency ripple components.

## Input Capacitor

The ceramic input capacitors should be placed as close as possible between the VIN pin and PGND to minimize the parasitic inductance. If a long wire is used to bring power to the IC, additional "bulk" capacitance (electrolytic or tantalum) should be placed between $\mathrm{C}_{\mathrm{IN}}$ and the power source lead to reduce under-damped ringing that can occur between the inductance of the power source leads and $\mathrm{C}_{\mathrm{IN}}$.

The effective $\mathrm{C}_{\mathbb{N}}$ capacitance value decreases as $\mathrm{V}_{\mathbb{N}}$ increases due to DC bias effects. This has no significant impact on regulator performance.

## Thermal Considerations

Heat is removed from the IC through the solder bumps to the PCB copper. The junction-to-ambient thermal resistance ( $\theta_{\mathrm{JA}}$ ) is largely a function of the PCB layout (size, copper weight, and trace width) and the temperature rise from junction to ambient ( $\Delta \mathrm{T}$ ).

For the FAN53555UC, $\theta_{\mathrm{JA}}$ is $38^{\circ} \mathrm{C} / \mathrm{W}$ when mounted on its four-layer evaluation board in still air with two-ounce outer layer copper weight and one-ounce inner layers. Halving the copper thickness results in an increased $\theta_{\mathrm{JA}}$ of $48^{\circ} \mathrm{C} / \mathrm{W}$.
For long-term reliable operation, the IC's junction temperature $\left(T_{J}\right)$ should be maintained below $125^{\circ} \mathrm{C}$.

To calculate maximum operating temperature $\left(\leq 125^{\circ} \mathrm{C}\right)$ for a specific application:

1. Use efficiency graphs to determine efficiency for the desired $V_{I N}$, $V_{\text {OUt, }}$ and load conditions.
2. Calculate total power dissipation using:
$P_{T}=V_{\text {OUT }} \times I_{\text {LOAD }} \times\left(\frac{1}{\eta}-1\right)$
where $\eta$ is efficiency from Figure 7 through Figure 12.
3. Estimate inductor copper losses using:

$$
\begin{equation*}
P_{L}=I_{\text {LOAD }}{ }^{2} \times D C R_{L} \tag{13}
\end{equation*}
$$

4. Determine IC losses by removing inductor losses (step 3) from total dissipation:

$$
\begin{equation*}
P_{I C}=P_{T}-P_{L} \tag{14}
\end{equation*}
$$

5. Determine device operating temperature:

$$
\Delta T=P_{I C} \times \Theta_{J A} \text { and }
$$

$T_{\text {IC }}=T_{A}+\Delta T$

It is important to note that the $\mathrm{R}_{\mathrm{DS}(\mathrm{ON})}$ of the IC's power MOSFETs increases linearly with temperature at about $1.21 \% /{ }^{\circ} \mathrm{C}$. This causes the efficiency $(\eta)$ to degrade with increasing die temperature.

## Layout Recommendation



Figure 40. Guidance for Layer 1


Figure 41. Guidance for Layer 2


Figure 42. Guidance for Layer 3


Figure 43. Remote Sensing Schematic


Figure 44. Remote Sensing Guidance, Top Layer

Product-Specific Dimensions

| Product | $\mathbf{D}$ | $\mathbf{E}$ | $\mathbf{X}$ | $\mathbf{Y}$ | Land Pattern |
| :---: | :---: | :---: | :---: | :---: | :---: |
| FAN53555UC00 to FAN53555UC08X, FAN53555BUC05X | $2.000 \pm 0.03$ | $1.600 \pm 0.03$ | 0.200 | 0.200 | Option 1 |
| FAN53555BUC08X, FAN53555BUC09X, <br> FAN5355UC09X, FAN53555UC13X, FAN53555BUC13X, <br> FAN53555UC18X, FAN53555BUC18X, <br> FAN53555BUC23X, FAN53555UC24X, <br> FAN53555BUC24X, | $2.015 \pm 0.03$ | $1.615 \pm 0.03$ | 0.2075 | 0.2075 | Option 2 |




SIDE VIEWS


NOTES:
A. NO JEDEC REGISTRATION APPLIES.
B. DIMENSIONS ARE IN MILLIMETERS.
C. DIMENSIONS AND TOLERANCE PER ASMEY14.5M, 2009.
D. DATUM C IS DEFINED BY THE SPHERICAL CROWNS OF THE BALLS.
e. PACKAGE NOMINAL HEIGHT IS 586 MICRONS $\pm 39$ MICRONS ( $547-625$ MICRONS).
FOR DIMENSIONS D, E, X, AND Y SEE PRODUCT DATASHEET.
G. DRAWING FILNAME: MKT-UC020AArev4.

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