### 3.3 V, 50 Mbps to 4.25 Gbps, Single-Loop, Laser Diode Driver

## FEATURES

SFP/SFF and SFF-8472 MSA-compliant
SFP reference design available
50 Mbps to 4.25 Gbps operation
Automatic average power control
Typical rise/fall time 60 ps
Supports VCSEL, DFB, and FP lasers
Bias current range $\mathbf{2} \mathbf{~ m A}$ to $\mathbf{1 0 0} \mathbf{~ m A}$
Modulation current range 5 mA to 90 mA
Laser fail alarm and automatic laser shutdown (ALS)
Bias and modulation current monitoring
3.3 V operation
$4 \mathrm{~mm} \times 4 \mathrm{~mm}$ LFCSP
Voltage setpoint control
Resistor setpoint control
Pin-compatible with ADN2870

## APPLICATIONS

$1 \times / 2 \times / 4 \times$ Fibre Channel SFP/SFF modules Multirate OC3 to OC48-FEC SFP/SFF modules
LX-4 modules
DWDM/CWDM SFP modules
1GE SFP/SFF transceiver modules
VCSEL, DFB, and FP transmitters

## GENERAL DESCRIPTION

The ADN2871 laser diode driver is designed for advanced SFP and SFF modules, using SFF-8472 digital diagnostics. The ADN2871 supports operation from 50 Mbps to 4.25 Gbps .

Average power and extinction ratio can be set with a voltage provided by a microcontroller DAC or by a trimmable resistor or digital potentiometer. The average power control loop is implemented using feedback from a monitor photodiode. The part provides bias and modulation current monitoring as well as fail alarms and automatic laser shutdown (ALS). The device interfaces easily with the Analog Devices, Inc. ADuC70xx family of MicroConverters ${ }^{\circ}$ and with the ADN289x family of limiting amplifiers to make a complete SFP/SFF transceiver solution. An SFP reference design is available. The product is pin-compatible with the ADN2870 dual-loop LDD, allowing one PC board layout to work with either device. For dual-loop applications, refer to the ADN2870 data sheet.

The product is available in a space-saving $4 \mathrm{~mm} \times 4 \mathrm{~mm}$ LFCSP specified over the $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ temperature range.

Figure 1 shows an application diagram of the voltage setpoint control with single-ended laser interface. Figure 36 shows a differential laser interface.


Figure 1. Application Diagram of Voltage Setpoint Control with a Single-Ended Laser Interface
Rev. A
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## ADN2871

## TABLE OF CONTENTS

Features ..... 1
Applications. ..... 1
General Description .....  1
Revision History ..... 2
Specifications ..... 3
SFP Timing Specifications ..... 5
Absolute Maximum Ratings ..... 6
ESD Caution ..... 6
Pin Configuration and Function Descriptions ..... 7
Optical Waveforms ..... 8
Multirate Performance Using Low Cost Fabry Perot TOSA NEC NX7315UA ..... 8
Performance Over Temperature Using DFB Tosa SUMITOMO SLT2486 .....  8
Typical Performance Characteristics ..... 9
Single-Ended Output ..... 9
Differential Output ..... 10
REVISION HISTORY
2/07—Rev. 0 to Rev. A
Changes to Figure 1 .....  1
Changes to Table 3 ..... 6
Changes to Table 4 ..... 7
Changes to Figure 29 and Figure 30 ..... 14
Changes to Resistor Setpoint Calibration Section, Figure 32, and Figure 33 ..... 15
Inserted Power-On Sequence in Resistor Setpoint Mode Section. ..... 15
Changes to Loop Bandwidth Selection Section ..... 16
Changes to Laser Diode Interfacing Section, Figure 35, and Figure 36 ..... 17
Changes to Table 6 ..... 18
Performance Characteristics ..... 11
Theory of Operation ..... 13
Laser Control ..... 13
Control Methods ..... 13
Voltage Setpoint Calibration ..... 13
Resistor Setpoint Calibration. ..... 15
Impd Monitoring ..... 15
Loop Bandwidth Selection ..... 16
Power Consumption ..... 16
Automatic Laser Shutdown (Tx_Disable) ..... 16
Bias and Modulation Monitor Currents ..... 16
Data Inputs ..... 17
Laser Diode Interfacing ..... 17
Alarms. ..... 18
Outline Dimensions ..... 19
Ordering Guide ..... 19

## SPECIFICATIONS

$\mathrm{V}_{\mathrm{CC}}=3.0 \mathrm{~V}$ to 3.6 V . All specifications $\mathrm{T}_{\text {MIN }}$ to $\mathrm{T}_{\mathrm{MAX}}{ }^{1}$, unless otherwise noted. Typical values as specified at $25^{\circ} \mathrm{C}$.
Table 1.

| Parameter | Min | Typ | Max | Unit | Conditions/Comments |
| :---: | :---: | :---: | :---: | :---: | :---: |
| LASER BIAS CURRENT (IBIAS) <br> Output Current (IBIAS) <br> Compliance Voltage IBIAS when ALS is High |  |  | $\begin{aligned} & 100 \\ & V_{c c} \\ & 0.1 \end{aligned}$ | $\begin{aligned} & \mathrm{mA} \\ & \mathrm{~V} \\ & \mathrm{~mA} \end{aligned}$ |  |
| MODULATION CURRENT (IMODP, IMODN) ${ }^{2}$ <br> Output Current (IMOD) <br> Compliance Voltage <br> IMOD when ALS is High <br> Rise Time, Single-Ended Output ${ }^{2,3}$ <br> Fall Time, Single-Ended Output ${ }^{2,3}$ <br> Random Jitter, Single-Ended Output ${ }^{2,3}$ <br> Deterministic Jitter, Single-Ended Output ${ }^{3,4}$ <br> Pulse-Width Distortion, Single-Ended Output ${ }^{2,3}$ <br> Rise Time, Differential Output ${ }^{3,5}$ <br> Fall Time, Differential Output ${ }^{3,5}$ <br> Random Jitter, Differential Output ${ }^{3,5}$ <br> Deterministic Jitter, Differential Output ${ }^{3,6}$ <br> Pulse-Width Distortion, Differential Output ${ }^{3,5}$ <br> Rise Time, Differential Output ${ }^{3,5}$ <br> Fall Time, Differential Output ${ }^{3,5}$ <br> Random Jitter, Differential Output ${ }^{3,5}$ <br> Deterministic Jitter, Differential Output ${ }^{3,7}$ <br> Pulse-Width Distortion, Differential Output ${ }^{3,5}$ | 1.5 | 60 <br> 60 <br> 0.8 <br> 19 <br> 21 <br> 47.1 <br> 46 <br> 0.64 <br> 12 <br> 2.1 <br> 56 <br> 55 <br> 0.61 <br> 17 <br> 1.6 | $\begin{aligned} & 90 \\ & V_{c c} \\ & 0.1 \\ & 104 \\ & 96 \\ & 1.1 \\ & 35 \\ & 30 \end{aligned}$ | ```mA V mA ps ps ps (rms) ps ps ps ps ps (rms) ps ps ps ps ps (rms) ps ps``` | $\begin{aligned} & 5 \mathrm{~mA}<\mathrm{IMOD}<90 \mathrm{~mA} \\ & 5 \mathrm{~mA}<\mathrm{IMOD}<90 \mathrm{~mA} \\ & 5 \mathrm{~mA}<\mathrm{IMOD}<90 \mathrm{~mA} \\ & 5 \mathrm{~mA}<\mathrm{IMOD}<90 \mathrm{~mA} \\ & 20 \mathrm{~mA}<\mathrm{IMOD}<90 \mathrm{~mA} \\ & 20 \mathrm{~mA}<\mathrm{IMOD}<90 \mathrm{~mA} \\ & 5 \mathrm{~mA}<\mathrm{IMOD}<30 \mathrm{~mA} \\ & 5 \mathrm{~mA}<\mathrm{IMOD}<30 \mathrm{~mA} \\ & 5 \mathrm{~mA}<\mathrm{IMOD}<30 \mathrm{~mA} \\ & 5 \mathrm{~mA}<\mathrm{IMOD}<30 \mathrm{~mA} \\ & 5 \mathrm{~mA}<\mathrm{IMOD}<30 \mathrm{~mA} \\ & 5 \mathrm{~mA}<\mathrm{IMOD}<90 \mathrm{~mA} \\ & 5 \mathrm{~mA}<\mathrm{IMOD}<90 \mathrm{~mA} \\ & 5 \mathrm{~mA}<\mathrm{IMOD}<90 \mathrm{~mA} \\ & 5 \mathrm{~mA}<\mathrm{IMOD}<90 \mathrm{~mA} \\ & 5 \mathrm{~mA}<\mathrm{IMOD}<90 \mathrm{~mA} \end{aligned}$ |
| AVERAGE POWER SET (PAVSET) <br> Pin Capacitance <br> Voltage <br> Photodiode Monitor Current (Average Current) | $\begin{aligned} & 1.1 \\ & 50 \end{aligned}$ | 1.2 | $\begin{aligned} & 80 \\ & 1.3 \\ & 1200 \end{aligned}$ | $\begin{aligned} & \mathrm{pF} \\ & \mathrm{~V} \\ & \mu \mathrm{~A} \end{aligned}$ | Resistor setpoint mode |
| EXTINCTION RATIO SET INPUT (ERSET) <br> Resistance Range <br> Resistance Range |  |  | $\begin{aligned} & 25 \\ & 1.01 \end{aligned}$ | $\begin{aligned} & \mathrm{k} \Omega \\ & \mathrm{k} \Omega \end{aligned}$ | Resistor setpoint mode Voltage setpoint mode |
| AVERAGE POWER REFERENCE VOLTAGE INPUT (PAVREF) Voltage Range Photodiode Monitor Current (Average Current) | 0.07 70 |  | $\begin{aligned} & 1 \\ & 1000 \end{aligned}$ | V <br> $\mu \mathrm{A}$ | Voltage setpoint mode (RPAV fixed at $1 \mathrm{k} \Omega$ ) <br> Voltage setpoint mode (RPAV fixed at $1 \mathrm{k} \Omega$ ) |
| EXTINCTION RATIO REFERENCE VOLTAGE INPUT (ERREF) <br> Voltage Range <br> ERREF Voltage to IMOD Gain | 0.05 | $100$ | 0.9 | V $\mathrm{mA} / \mathrm{V}$ | Voltage setpoint mode (RERSET fixed at $1 \mathrm{k} \Omega$ ) |
| DATA INPUTS (DATAP, DATAN) ${ }^{8}$ <br> V p-p (Differential) <br> Input Impedance (Single-Ended) | 0.4 |  | 2.4 | $\begin{aligned} & \mathrm{V} \\ & \Omega \end{aligned}$ | AC-coupled |
| $\begin{aligned} & \text { LOGIC INPUTS (ALS) } \\ & \mathrm{V}_{\mathrm{IH}} \\ & \mathrm{~V}_{\mathrm{IL}} \\ & \hline \end{aligned}$ | 2 |  | 0.8 | $\begin{aligned} & \mathrm{V} \\ & \mathrm{~V} \end{aligned}$ |  |

## ADN2871

| Parameter | Min | Typ | Max | Unit | Conditions/Comments |
| :---: | :---: | :---: | :---: | :---: | :---: |
| ALARM OUTPUT (FAIL) ${ }^{9}$ |  |  |  |  |  |
| Voff |  | >1.8 |  | V | Voltage required at FAIL for IBIAS and IMOD to turn off when FAIL asserted |
| Von | <1.3 |  |  | V | Voltage required at FAIL for IBIAS and IMOD to stay on when FAIL asserted |
| IBMON/IMMON DIVISION RATIO |  |  |  |  |  |
| IBIAS/IBMON ${ }^{3}$ | 76 | 94 | 112 | A/A | $2 \mathrm{~mA}<\mathrm{IBIAS}<11 \mathrm{~mA}$ |
| IBIAS/IBMON ${ }^{3}$ | 85 | 100 | 115 | A/A | 11 mA < IBIAS < 50 mA |
| IBIAS/IBMON ${ }^{3}$ | 92 | 100 | 108 | A/A | 50 mA < IBIAS < 100 mA |
| IBIAS/IBMON Stability ${ }^{3,10}$ |  |  | $\pm 5$ | \% | 10 mA < IBIAS < 100 mA |
| IMOD/IMMON |  | 42 |  | A/A |  |
| IBMON Compliance Voltage | 0 |  | 1.3 | V |  |
| SUPPLY |  |  |  |  |  |
| $\mathrm{Icc}^{11}$ |  | 32 |  | mA | When IBIAS $=I M O D=0$ |
| $\mathrm{V}_{\text {cc }}\left(\right.$ with respect to GND) ${ }^{12}$ | 3.0 | 3.3 | 3.6 | V |  |

${ }^{1}$ Temperature range: $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$.
${ }^{2}$ Measured into a single-ended $15 \Omega$ load ( $22 \Omega$ resistor in parallel with digital scope $50 \Omega$ input) using a 1111111100000000 pattern at 2.5 Gbps , shown in Figure 2 .
${ }^{3}$ Guaranteed by design and characterization. Not production tested.
${ }^{4}$ Measured into a single-ended $15 \Omega$ load using a K28.5 pattern at 2.5 Gbps , shown in Figure 2.
${ }^{5}$ Measured into a differential $30 \Omega(43 \Omega$ differential resistor in parallel with a digital scope of $50 \Omega$ input) load using a 1111111100000000 pattern at 4.25 Gbps , as shown in Figure 3.
${ }^{6}$ Measured into a differential $30 \Omega$ load using a K28.5 pattern at 4.25 Gbps , as shown in Figure 3.
${ }^{7}$ Measured into a differential $30 \Omega$ load using a K28.5 pattern at 2.7 Gbps , as shown in Figure 3.
${ }^{8}$ When the voltage on DATAP is greater than the voltage on DATAN, the modulation current flows in the IMODP pin.
${ }^{9}$ Guaranteed by design. Not production tested.
${ }^{10}$ IBIAS/IBMON ratio stability is defined in SFF-8472 Revision 9 over temperature and supply variation.
${ }^{11}$ See the $I_{c c}$ minimum for power calculation in the Power Consumption section.
${ }^{12}$ All Vcc pins should be shorted together.


Figure 2. High Speed Electrical Test Single-Ended Output Circuit


Figure 3. High Speed Electrical Test Differential Output Circuit

## SFP TIMING SPECIFICATIONS

Table 2.

| Parameter | Symbol | Min | Typ | Max | Unit | Conditions/Comments |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| ALS Assert Time | t_off |  | 1 | 5 | $\mu \mathrm{s}$ | Time for the rising edge of ALS (Tx_DISABLE) to when the bias current falls below $10 \%$ of nominal |
| ALS Negate Time ${ }^{1}$ | t_on |  | 0.15 | 0.4 | ms | Time for the falling edge of ALS to when the modulation current rises above $90 \%$ of nominal |
| Time to Initialize, Including Reset of FAIL ${ }^{1}$ | t_init |  | 25 | 275 | ms | From power-on or negation of FAIL using ALS |
| FAIL Assert Time | t_fault |  |  | 100 | $\mu \mathrm{s}$ | Time to fault to FAIL on |
| ALS to Reset Time | t_reset |  |  | 5 | $\mu \mathrm{s}$ | Time Tx_DISABLE must be held high to reset Tx_FAULT. |

${ }^{1}$ Guaranteed by design and characterization. Not production tested.


Figure 4. Signal Level Definition


Figure 5. Recommended SFP Supply

## ADN2871

## ABSOLUTE MAXIMUM RATINGS

Table 3.

| Parameter | Rating |
| :--- | :--- |
| V $_{\text {cc to GND }}$ | 4.2 V |
| IMODN, IMODP | -0.3 V to +4.8 V |
| All Other Pins | -0.3 V to +3.9 V |
| Junction Temperature | $150^{\circ} \mathrm{C}$ |
| Operating Temperature Range |  |
| $\quad$ Industrial | $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ |
| $\quad$ Storage Temperature Range | $-65^{\circ} \mathrm{C}$ to $+150^{\circ} \mathrm{C}$ |
| $\quad$ Junction Temperature (T」 max) | $125^{\circ} \mathrm{C}$ |
| LFCSP |  |
| Power Dissipation ${ }^{1}$ | $\left(\mathrm{~T}_{\mathrm{J}} \mathrm{max}-\mathrm{T}_{\mathrm{A}}\right) / \theta_{\mathrm{JA}} \mathrm{W}$ |
| $\theta_{\mathrm{JA}}$ Thermal Impedance ${ }^{2}$ | $30^{\circ} \mathrm{C} / \mathrm{W}$ |
| $\theta_{\mathrm{Jc}}$ Thermal Impedance | $29.5^{\circ} \mathrm{C} / \mathrm{W}$ |
| Lead Temperature (Soldering 10 sec ) | $300^{\circ} \mathrm{C}$ |

${ }^{1}$ Power consumption equations are provided in the Power Consumption section.
${ }^{2} \theta_{\mathrm{JA}}$ is defined when part is soldered on a 4-layer board.

Stresses above those listed under Absolute Maximum Ratings may cause permanent damage to the device. This is a stress rating only; functional operation of the device at these or any other conditions above those indicated in the operational section of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

## ESD CAUTION

|  | ESD (electrostatic discharge) sensitive device. <br> Charged devices and circuit boards can discharge <br> without detection. Although this product features <br> patented or proprietary protection circuitry, damage <br> may occur on devices subjected to high energy ESD. <br> Therefore, proper ESD precautions should be taken to <br> avoid performance degradation or loss of functionality. |
| :--- | :--- |

## PIN CONFIGURATION AND FUNCTION DESCRIPTIONS



Figure 6. Pin Configuration—Top View
Note: The LFCSP has an exposed paddle that must be connected to ground.

Table 4. Pin Function Descriptions

| Pin No. | Mnemonic | Description |
| :--- | :--- | :--- |
| 1 | CCBIAS | In ac-coupled mode, CCBIAS can connect to either IBIAS or Vcc. In dc-coupled mode, CCBIAS can connect to Vcc. |
| 2 | PAVSET | Average Optical Power Set Pin. |
| 3 | GND | Supply Ground. |
| 4 | Vcc | Supply Voltage. |
| 5 | PAVREF | Reference Voltage Input for Average Optical Power Control. |
| 6 | RPAV | Average Power Resistor when Using PAVREF. |
| 7 | NC | No Connect. |
| 8 | PAVCAP | Average Power Loop Capacitor. |
| 9 | GND | Supply Ground. |
| 10 | DATAP | Data, Positive Differential Input. |
| 11 | DATAN | Data, Negative Differential Input. |
| 12 | ALS | Automatic Laser Shutdown. |
| 13 | ERSET | Extinction Ratio Set Pin. |
| 14 | IMMON | Modulation Current Monitor Current Source. |
| 15 | ERREF | Reference Voltage Input for Extinction Ratio Control. |
| 16 | Vcc | Supply Voltage. |
| 17 | IBMON | Bias Current Monitor Current Source. |
| 18 | FAIL | Fail Alarm Output. |
| 19 | GND | Supply Ground. |
| 20 | Vcc | Supply Voltage. |
| 21 | IMODP | Modulation Current Positive Output (Current Sink), Connect to Laser Diode. |
| 22 | IMODN | Modulation Current Negative Output (Current Sink). |
| 23 | GND | Supply Ground. |
| 24 | IBIAS | Laser Diode Bias (Current Sink to Ground). |

## ADN2871

## OPTICAL WAVEFORMS

$\mathrm{V}_{\mathrm{CC}}=3.3 \mathrm{~V}$ and $\mathrm{T}_{\mathrm{A}}=25^{\circ} \mathrm{C}$, unless otherwise noted. Note: No change to PAVCAP and ERCAP values.

## MULTIRATE PERFORMANCE USING LOW COST FABRY PEROT TOSA NEC NX7315UA



Figure 7. Optical Eye 2.488 Gbps, 65 ps/DIV, PRBS $2^{31-1}$ $P_{A V}=-4.5 \mathrm{dBm}, E R=9 \mathrm{~dB}$, Mask Margin 25\%


Figure 8. Optical Eye 622 Mbps, 264 ps/DIV, PRBS $2^{31-1}$ $P_{A V}=-4.5 \mathrm{dBm}, E R=9 \mathrm{~dB}$, Mask Margin 50\%


Figure 9. Optical Eye $155 \mathrm{Mbps}, 1.078 \mathrm{~ns} / \mathrm{DIV}$, PRBS $2^{31-1}$ $P_{A V}=-4.5 \mathrm{dBm}, E R=9 \mathrm{~dB}$, Mask Margin 50\%

## PERFORMANCE OVER TEMPERATURE USING DFB TOSA SUMITOMO SLT2486

(ACQ LIMIT TEST) WAVEFORMS 1001


Figure 10. Optical Eye 2.488 Gbps, 65 ps/DIV, PRBS $2^{31-1}$ $P_{A V}=0 \mathrm{dBm}, E R=9 \mathrm{~dB}$, Mask Margin $22 \%, T_{A}=25^{\circ} \mathrm{C}$
(ACQ LIMIT TEST) WAVEFORMS 1001


Figure 11. Optical Eye 2.488 Gbps, 65 ps/DIV, PRBS $2^{31-1}$ $P_{A V}=-0.2 \mathrm{dBm}, E R=8.96 \mathrm{~dB}$, Mask Margin 21\%, $T_{A}=85^{\circ} \mathrm{C}$

## TYPICAL PERFORMANCE CHARACTERISTICS

## SINGLE-ENDED OUTPUT

These performance characteristics were measured using the high speed, electrical single-ended, output circuit shown in Figure 2.


Figure 12. Rise Time vs. Modulation Current, $I_{B A A}=20 \mathrm{~mA}$


Figure 13. Fall Time vs. Modulation Current, $I_{B A S}=20 \mathrm{~mA}$


Figure 14. Random Jitter vs. Modulation Current, $I_{B A S}=20 \mathrm{~mA}$


Figure 15. Deterministic Jitter at 2.488 Gbps vs. Modulation Current, $I_{B A A}=20 \mathrm{~mA}$

## ADN2871

## DIFFERENTIAL OUTPUT

These performance characteristics were measured using the high speed, electrical differential output circuit shown in Figure 3.


Figure 16. Rise Time vs. Modulation Current, $I_{B I A S}=20 \mathrm{~mA}$


Figure 17. Fall Time vs. Modulation Current, $I_{B A A S}=20 \mathrm{~mA}$


Figure 18. Random Jitter vs. Modulation Current, $I_{B A S}=20 \mathrm{~mA}$


Figure 19. Deterministic Jitter at 4.25 Gbps vs. Modulation Current, $I_{B A S}=20 \mathrm{~mA}$

## PERFORMANCE CHARACTERISTICS



Figure 20. Total Supply Current vs. Modulation Current Total Supply Current $=I_{C C}+I_{\text {BAS }}+I_{\text {MOD }}$


Figure 21. IBIAS/IBMON Gain vs. Temperature, $I_{B I A S}=20 \mathrm{~mA}$


Figure 22. ALS Assert Time, $5 \mu \mathrm{~s} / \mathrm{D} / \mathrm{V}$


Figure 23. Supply Current (IICC) vs. Temperature with ALS Asserted, $I_{B A A S}=20 \mathrm{~mA}$


Figure 24. $I M O D / I M M O N$ Gain vs. Temperature, $I_{M O D}=30 \mathrm{~mA}$


Figure 25. ALS Negate Time, $50 \mu \mathrm{~s} / \mathrm{DIV}$

## ADN2871



Figure 26. FAIL Assert Time, 1 нs/DIV


Figure 27. Time to Initialize, Including Reset, $40 \mathrm{~ms} / \mathrm{DIV}$

## THEORY OF OPERATION

Laser diodes have a current-in to light-out transfer function, as shown in Figure 28. Two key characteristics of this transfer function are the threshold current, Ith, and the slope in the linear region beyond the threshold current, referred to as the slope efficiency, LI.


## LASER CONTROL

Typically, laser threshold current and slope efficiency are both functions of temperature. For FP- and DFB-type lasers, the threshold current increases and the slope efficiency decreases with increasing temperature. In addition, these parameters vary as the laser ages. To maintain a constant optical average power and a constant optical extinction ratio over temperature and laser lifetime, it is necessary to vary the applied electrical bias current and modulation current to compensate for the changing LI characteristics of the laser.

## Average Power Control Loop (APCL)

The APCL compensates for changes in Ith and LI by varying IBIAS. Average power control is performed by measuring the MPD current, $\mathrm{I}_{\text {MPD }}$. This current is bandwidth-limited by the MPD. This is not a problem because the APCL is required to respond to the average current from the MPD.

## Extinction Ratio (ER) Control

ER control is implemented by adjusting the modulation current. Temperature calibration is required to adjust the modulation current to compensate for variations of the laser characteristics with temperature.

## CONTROL METHODS

The ADN2871 has two methods for setting the average power ( $\mathrm{P}_{\mathrm{AV}}$ ) and extinction ratio (ER). The average power and extinction ratio can be voltage-set using the output of a microcontroller's voltage DACs to provide controlled reference voltages, PAVREF and ERREF. Alternatively, the average power and extinction ratio can be resistor-set using potentiometers at the PAVSET and ERSET pins, respectively.

## VOLTAGE SETPOINT CALIBRATION

The ADN2871 allows interface to a microcontroller for both control and monitoring (see Figure 29). The average power and extinction ratio can be set using the microcontroller DACs to provide controlled reference voltages, PAVREF and ERREF.

$$
\begin{align*}
& \text { PAVREF }=P_{A V} \times R_{S P} \times R_{P A V}  \tag{V}\\
& E R R E F=\frac{I_{M O D} \times R_{E R S E T}}{100} \tag{V}
\end{align*}
$$

where:
$R_{S P}$ is the optical responsivity (in amperes per watt).
$P_{A V}$ is the average power required.
$R_{P A V}=R_{E R S E T}=1 \mathrm{k} \Omega$.
$I_{M O D}$ is the modulation current.
In voltage setpoint mode, $\mathrm{R}_{\text {PAV }}$ and $\mathrm{R}_{\text {ERSET }}$ must be $1 \mathrm{k} \Omega$ resistors with a $1 \%$ tolerance and a temperature coefficient of $50 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$.

## Power-On Sequence in Voltage Setpoint Mode

Note that during power-up, there is an internal sequence that allows 25 ms before enabling the alarms; therefore, the customer must ensure that the voltages for PAVREF and ERREF are active within 20 ms after ramp-up of the power supply. If the PARREF and ERREF voltages are supplied after 25 ms , then the part alarms and FAIL is activated.


Figure 29. ADN2871 Using Microconverter Voltage Setpoint Calibration and Monitoring


Figure 30. ADN2871 Using Resistor Setpoint Calibration of Average Power and Extinction Ratio

## RESISTOR SETPOINT CALIBRATION

In resistor setpoint calibration, Pin PAVREF, Pin ERREF, and Pin RPAV must all be tied to $V_{\mathrm{cc}}$. The average power and extinction ratio can be set using the PAVSET and ERSET pins, respectively. A resistor is placed between the pin and GND to set the current flowing in each pin, as shown in Figure 30. The ADN2871 ensures that both PAVSET and ERSET are kept 1.23 V above GND. The PAVSET and ERSET resistors are given by

$$
\begin{align*}
& R_{\text {PAVSET }}=\frac{1.2 \mathrm{~V}}{P_{A V} \times R_{S P}} \\
& R_{E R S E T}=\frac{1.2 \mathrm{~V} \times 100}{I_{M O D}}
\end{align*}
$$

where:
$R_{S P}$ is the optical responsivity (in amperes per watt).
$I_{M O D}$ is the modulation current required ( mA ).
$P_{A V}$ is the average power required ( mW ).

## Power-On Sequence in Resistor Setpoint Mode

After power-on, the ADN2871 starts an initial process sequence that takes 25 ms before enabling the alarms. Therefore, the resistors connected to Pin PAVSET and Pin ERSET should be stabilized within 20 ms after power-on. If the PAVSET and ERSET resistors are connected to the ADN2871 20 ms after the power supply is turned on, the ADN2871 alarm may kick in and assert FAIL.

## $I_{\text {MPD }}$ MONITORING

ImPD monitoring can be implemented for voltage setpoint and resistor setpoint as described next.

## Voltage Setpoint

In voltage setpoint calibration, two methods can be used for $\mathrm{I}_{\text {MPD }}$ monitoring.

## Method 1: Measuring Voltage at RPAV

The IMPD current is equal to the voltage at RPAV divided by the value of RPAV (see Figure 31) as long as the laser is on and is being controlled by the control loop. This method does not provide a valid $\mathrm{I}_{\text {MPD }}$ reading when the laser is in shutdown or fail mode. A MicroConverter buffered ADC input can be connected to RPAV to make this measurement. No decoupling or filter capacitors should be placed on the RPAV node because this can disturb the control loop.


Figure 31. Single Measurement of IMPD at RPAV in Voltage Setpoint Mode

## Method 2: Measuring I MPD $_{\text {Across a Sense Resistor }}$

The second method has the advantage of providing a valid $\mathrm{I}_{\text {MPD }}$ reading at all times, but has the disadvantage of requiring a differential measurement across a sense resistor directly in series with the $\mathrm{I}_{\text {MPD }}$. As shown in Figure 32, a small resistor, Rx, is placed in series with the $\mathrm{I}_{\text {mpD. }}$. If the laser used in the design has a pinout where the monitor photodiode cathode and the lasers anode are not connected, a sense resistor, Rx , can be placed in series with the photodiode cathode and $\mathrm{V}_{\mathrm{CC}}$, as shown in Figure 33. When choosing the value of the resistor, the user must take into account the expected $\mathrm{I}_{\text {MPD }}$ value in normal operation. The resistor must be large enough to make a significant signal for the buffered ADC to read, but small enough not to cause a significant voltage reduction across the $\mathrm{I}_{\text {mpd. }}$. The voltage across the sense resistor should not exceed 250 mV when the laser is in normal operation. It is recommended that a 10 pF capacitor be placed in parallel with the sense resistor.


Figure 32. Differential Measurement of $I_{\text {MPD }}$ Across a Sense Resistor


Figure 33. Single Measurement of IMPD Across a Sense Resistor

## ADN2871

## Resistor Setpoint

In resistor setpoint calibration, the current through the resistor from PAVSET to ground is the $I_{\text {MPD }}$ current. The recommended method for measuring the $\mathrm{I}_{\text {MPD }}$ current is to place a small resistor in series with the PAVSET resistor (or potentiometer) and measure the voltage across this resistor, as shown in Figure 34. The $\mathrm{I}_{\text {MPD }}$ current is then equal to this voltage divided by the value of resistor used. In resistor setpoint calibration, PAVSET is held to 1.2 V nominal; it is recommended that the sense resistor be selected so that the voltage across the sense resistor does not exceed 250 mV .


Figure 34. Single Measurement of $I_{\text {MPD }}$ Across a Sense Resistor in Resistor Setpoint IMPD Monitoring

## LOOP BANDWIDTH SELECTION

To ensure that the ADN2871 control loop has sufficient bandwidth, the average power loop capacitor (PAVCAP) is calculated using the laser's slope efficiency (watts/amps) and the average power required.
For resistor setpoint control:

$$
\begin{equation*}
P A V C A P=3.2 \times 10^{-6} \times \frac{L I}{P_{A V}} \tag{Farad}
\end{equation*}
$$

For voltage setpoint control:

$$
\begin{equation*}
P A V C A P=1.28 \times 10^{-6} \times \frac{L I}{P_{A V}} \tag{Farad}
\end{equation*}
$$

where:
$P_{\mathrm{AV}}$ is the average power required $(\mathrm{mW})$.
$L I$ is the typical slope efficiency at $25^{\circ} \mathrm{C}$ of a batch of lasers that are used in a design ( $\mathrm{mW} / \mathrm{mA}$ ).

LI can be calculated as

$$
\begin{equation*}
L I=\frac{P 1-P 0}{I_{M O D}} \tag{mW/mA}
\end{equation*}
$$

where:
$P 1$ is the optical power at the one level (mW).
$P 0$ is the optical power at the zero level (mW).
The capacitor value equation is used to get a centered value for the particular type of laser that is used in a design and an average power setting. The laser LI can vary by a factor of 7 between different physical lasers of the same type and across temperatures without the need to recalculate the PAVCAP value.

This capacitor is placed between the PAVCAP pin and ground. It is important that the capacitor is a low leakage, multilayer ceramic type with an insulation resistance greater than $100 \mathrm{G} \Omega$ or a time constant of 1000 seconds, whichever is less. Pick a standard off-the-shelf capacitor value such that the actual capacitance is within $\pm 30 \%$ of the calculated value after the capacitor's own tolerance is taken into account.

## POWER CONSUMPTION

The ADN2871 die temperature must be kept below $125^{\circ} \mathrm{C}$. The LFCSP has an exposed paddle, which should be connected so that it is at the same potential as the ADN2871 ground pins. Power consumption can be calculated as

$$
\begin{aligned}
& I_{C C}=I_{C C} \min +0.3 I_{M O D} \\
& P=V_{C C} \times I_{C C}+\left(I_{B A A S} \times V_{\text {BIAS_PIN }}\right)+I_{M O D}\left(V_{M O D P \_P I N}+V_{M O D N_{-} P I N}\right) / 2 \\
& T_{D I E}=T_{A M B I E N T}+\theta_{J A} \times P
\end{aligned}
$$

Thus, the maximum combination of $\mathrm{I}_{\text {BIAS }}+\mathrm{I}_{\text {MOD }}$ must be calculated, where:
$I_{C C} \min =30 \mathrm{~mA}$, the typical value of $\mathrm{I}_{\mathrm{CC}}$ provided in Table 1 with $I_{B I A S}=I_{M O D}=0$.
$T_{\text {DIE }}$ is the die temperature.
$T_{\text {AMBIENT }}$ is the ambient temperature.
$V_{\text {BIAS_PIN }}$ is the voltage at the IBIAS pin.
$V_{M O D P_{-} P I N}$ is the voltage at the IMODP pin.
$V_{M O D N \_P I N}$ is the voltage at the IMODN pin.

## AUTOMATIC LASER SHUTDOWN (Tx_DISABLE)

ALS (Tx_DISABLE) is an input that is used to shut down the transmitter's optical output. The ALS pin is pulled up internally with a $6 \mathrm{k} \Omega$ resistor and conforms to SFP MSA specifications. When ALS is logic high or when open, both the bias and modulation currents are turned off. If an alarm has triggered, and the bias and modulation currents are turned off, ALS can be brought high and then low to clear the alarm.

## BIAS AND MODULATION MONITOR CURRENTS

IBMON and IMMON are current-controlled current sources that mirror a ratio of the bias and modulation current. The monitor bias current (IBMON) and the monitor modulation current (IMMON) should both be connected to ground through a resistor to provide a voltage proportional to the bias current and modulation current, respectively. When using a microcontroller, the voltage developed across these resistors can be connected to two of the ADC channels, making available a digital representation of the bias and modulation current.

## DATA INPUTS

Data inputs should be ac-coupled ( 10 nF capacitors are recommended) and are terminated via a $100 \Omega$ internal resistor between the DATAP and DATAN pins. A high impedance circuit sets the common-mode voltage and is designed to allow maximum input voltage headroom over temperature. It is necessary to use ac coupling to eliminate the need for matching between common-mode voltages.

## LASER DIODE INTERFACING

Figure 35 shows the recommended circuit for interfacing the ADN2871 to most TO Can or coax lasers. DFB and FP lasers typically have impedances of $5 \Omega$ to $7 \Omega$ and have axial leads. The circuit shown works over the full range of data rates from 155 Mbps to 3.3 Gbps , including multirate operation (with no change to PAVCAP and ERCAP values); see the Multirate Performance Using Low Cost Fabry Perot TOSA NEC NX7315UA section for multirate performance examples. Coax lasers have special characteristics that make them difficult to interface to. They tend to have higher inductance, and their impedance is not well controlled. The circuit in Figure 35 operates by deliberately misterminating the transmission line on the laser side while providing a very high quality matching network on the driver side. The impedance of the driver side matching network is very flat in comparison to frequency and enables multirate operation. A series damping resistor should not be used.


Figure 35. Recommended Interface for ADN2871 AC Coupling

The $30 \Omega$ transmission line used is a compromise between drive current required and the total power consumed. Other transmission line values can be used, with some modification of the component values. In Figure 35, the R and C snubber values, $24 \Omega$ and 2.2 pF respectively, represent a starting point and must be tuned for the particular model of laser being used. $\mathrm{R}_{\mathrm{P}}$, the pull-up resistor, is in series with a very small $(0.5 \mathrm{nH})$ inductor. In some cases, an inductor is not required or can be accommodated with deliberate parasitic inductance, such as a thin trace or a via placed on the PC board.

Care should be taken to mount the laser as close as possible to the PC board, minimizing the exposed lead length between the laser can and the edge of the board. The axial lead of a coax laser is very inductive (approximately 1 nH per mm ). Long exposed leads result in slower edge rates and reduced eye margin.
Recommended component layouts and Gerber files are available by contacting Sales. Note that the circuit in Figure 35 can supply up to 56 mA of modulation current to the laser, sufficient for most lasers available today. Higher currents can be accommodated by changing transmission lines and backmatch values; contact Sales for recommendations. This interface circuit is not recommended for butterfly-style lasers or other lasers with $25 \Omega$ characteristic impedance. Instead, a $25 \Omega$ transmission line and inductive (instead of resistive) pull-up is recommended. The ADN2871 single-ended application shown in Figure 35 is recommended for use up to 2.7 Gbps . From 2.7 Gbps to 4.25 Gbps , a differential drive is recommended when driving VCSELs or lasers that have slow fall times. Differential drive can be implemented by adding a few extra components. A possible implementation is shown in Figure 36. The bias and modulation currents that are programmed into the ADN2871 need to be larger that the bias and modulation current required at the laser due to the laser ac coupling interface and because some modulation current flows in pull-up Resistors R1 and R2.

Figure 35 and Figure 36, Resistor $\mathrm{Rz}_{z}$ is required to achieve optimum eye quality. The recommended $\mathrm{R}_{\mathrm{z}}$ value is approximately $200 \Omega \sim 500 \Omega$.


Figure 36. Recommended Differential Drive Circuit

## ADN2871

## ALARMS

The ADN2871 has a latched, active high monitoring alarm (FAIL). The FAIL alarm output is an open drain in conformance to SFP MSA specification requirements.

The ADN2871 has a three-fold alarm system that covers

- Use of a bias current higher than expected, probably as a result of laser aging.
- Out-of-bounds average voltage at the monitor photodiode (MPD) input, indicating an excessive amount of laser power or a broken loop.
- Undervoltage in the IBIAS node (laser diode cathode) that would increase the laser power.
The bias current alarm trip point is set by selecting the value of resistor on the IBMON pin to GND. The alarm is triggered when the voltage on the IBMON pin goes above 1.2 V . FAIL is activated when the single-point faults in Table 5 occur. The
circuit in Figure 37 can be used to indicate that FAIL has been activated while allowing the bias and modulation currents to remain on. The transistor's $V_{\text {BE }}$ clamps the FAIL voltage to below 1.3 V disabling the automatic shutdown of bias and modulation currents. If an alarm has triggered and FAIL is activated, ALS can be brought high and then low to clear the alarm.


Figure 37. FAIL Indication Circuit

Table 5. ADN2871 Single-Point Alarms

| Alarm Type | Mnemonic | Overvoltage or Short to V $_{\mathrm{cc}}$ Condition | Undervoltage or Short to GND Condition |
| :--- | :--- | :--- | :--- |
| Bias Current | IBMON | Alarm if $>1.2 \mathrm{~V}$ typical ( $\pm 10 \%$ tolerance) | Ignore |
| MPD Current | PAVSET | Alarm if > threshold (typical threshold: 1.5 V to 2.1 V ) | Alarm if < threshold (typical threshold: 0.6 V to 1.1 V ) |
| Crucial Nodes | ERREF (the ERRREF <br> designed tied to <br> Vcc in resistor <br> setting mode) <br> IBIAS | Alarm if shorted to $V_{c c}$ (the alarm is valid for <br> voltage setting mode only) | Ignore |

Table 6. ADN2871 Response to Various Single-Point Faults in AC-Coupled Configuration (as shown in Figure 35)

| Pin | Short to Vcc | Short to GND | Open |
| :---: | :---: | :---: | :---: |
| CCBIAS | Fault state occurs | Fault state occurs | Does not increase laser average power |
| PAVSET | Fault state occurs | Fault state occurs | Fault state occurs |
| PAVREF | Voltage mode: Fault state occurs | Fault state occurs | Fault state occurs |
|  | Resistor mode: Tied to $\mathrm{V}_{\text {cc }}$ |  | Circuit designed to tie to $\mathrm{V}_{c c}$ in resistor setting mode, so no open case |
| RPAV | Voltage mode: Fault state occurs | Fault state occurs | Voltage mode: Fault state occurs |
|  | Resistor mode: Tied to $\mathrm{V}_{\text {cc }}$ |  | Resistor mode: Does not increase average power |
| PAVCAP | Fault state occurs | Fault state occurs | Fault state occurs |
| DATAP | Does not increase laser average power | Does not increase laser average power | Does not increase laser average power |
| DATAN | Does not increase laser average power | Does not increase laser average power | Does not increase laser average power |
| ALS | Output currents shut off | Normal currents | Output currents shut off |
| ERSET | Does not increase laser average power | Does not increase laser average power | Does not increase laser average power |
| IMMON | Does not affect laser power | Does not increase laser average power | Does not increase laser average power |
| ERREF | Voltage mode: Fault state occurs | Voltage mode: Does not increase average power | Does not increase laser average power |
|  | Resistor mode: Tied to $\mathrm{V}_{\text {cc }}$ | Resistor mode: Fault state occurs |  |
| IBMON | Fault state occurs | Does not increase laser average power | Does not increase laser average power |
| FAIL | Fault state occurs | Does not increase laser average power | Does not increase laser average power |
| IMODP | Does not increase laser average power | Does not increase laser average power | Does not increase laser average power |
| IMODN | Does not increase laser average power | Does not increase laser average power | Does not increase laser power |
| IBIAS | Fault state occurs | Fault state occurs | Fault state occurs |

## OUTLINE DIMENSIONS



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Figure 38. 24-Lead Lead Frame Chip Scale Package [LFCSP_VQ]
$4 \mathrm{~mm} \times 4 \mathrm{~mm}$ Body, Very Thin Quad (CP-24-1)
Dimensions shown in millimeters

ORDERING GUIDE

| Model | Temperature Range | Package Description | Package Option |
| :--- | :--- | :--- | :--- |
| ADN2871ACPZ ${ }^{1}$ | $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ | $24-$ Lead Lead Frame Chip Scale Package (LFCSP_VQ) | CP-24-1 |
| ADN2871ACPZ-RL | $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ | 24-Lead Lead Frame Chip Scale Package (LFCSP_VQ) | CP-24-1 |
| ADN2871ACPZ-RL7 ${ }^{1}$ | $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ | $24-$ Lead Lead Frame Chip Scale Package (LFCSP_VQ) | CP-24-1 |

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## ADN2871

## NOTES

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[^0]:    ${ }^{1} \mathrm{Z}=\mathrm{Pb}$-free part.

