MTi 1-series Development Kit

MTi-3-DK and MTi-7-DK
User Manual

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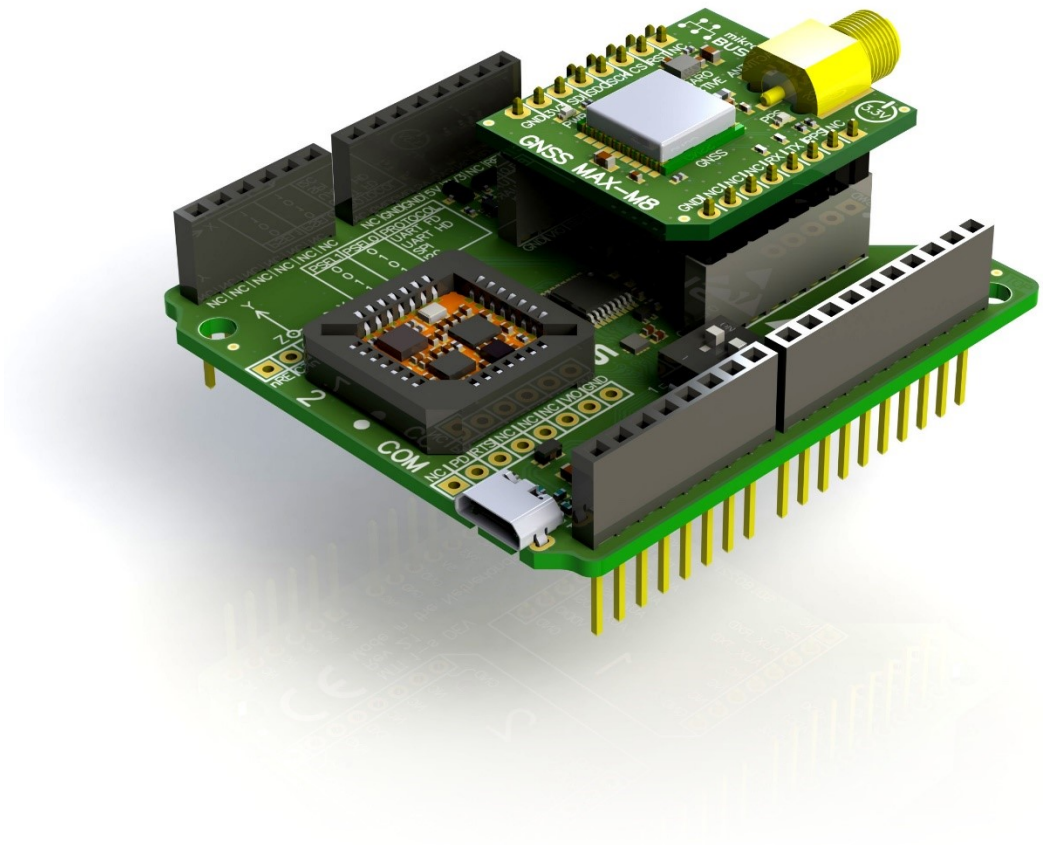

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1 General information

This document provides information on the contents and usage of the MTi 1-series Development Kits. The MTi 1-series module (MTi 1-s) is a fully functional, self-contained module that is easy to design-in. The MTi 1-s can be connected to a host through I²C, SPI or UART interfaces. The MTi-3 Development Kit (MTi-3-DK) enables users to evaluate features for the MTi-3 (AHRS), MTi-2 (VRU) and MTi-1 (IMU) modules. The MTi-7 Development Kit (MTi-7-DK) enables users to evaluate features of the MTi-7 (external-GNSS/INS). In addition to the MTi 1-s interfaces, both Development Kits include a USB interface.

1.1 Package information

Table 1: Package contents for 1-series Development Kits

Component	Name
	Shield board
	MTi 1-series module (MTi 1-s)
	GNSS daughter card[1]
	GNSS antenna[1]
	USB cable

[1] Only with MTi-7-DK

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1.2 Ordering information

Table 2: Ordering information for 1-series Development Kits

Kit	Description	Package contents	Packing Method
MTi-7-DK	Development kit for MTi-7 (external-GNSS-aided-AHRS)	- Shield board - MTi-7 module (in the socket) - GNSS daughter card - GNSS antenna - USB cable	Single unit
MTi-3-DK	Development kit for MTi-1 (IMU), MTi-2 (VRU) and MTi-3 (AHRS)	- Shield board - MTi-3 module (in the socket) - USB cable	Single unit

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2 Introduction

2.1 Kit contents and features

The MTi 1-series Development Kit contains

- Shield board
- MTi-3 or MTi-7 mounted in the socket
- GNSS daughter card (only with MTi-7-DK)
- GNSS antenna (only with MTi-7-DK)
- USB cable

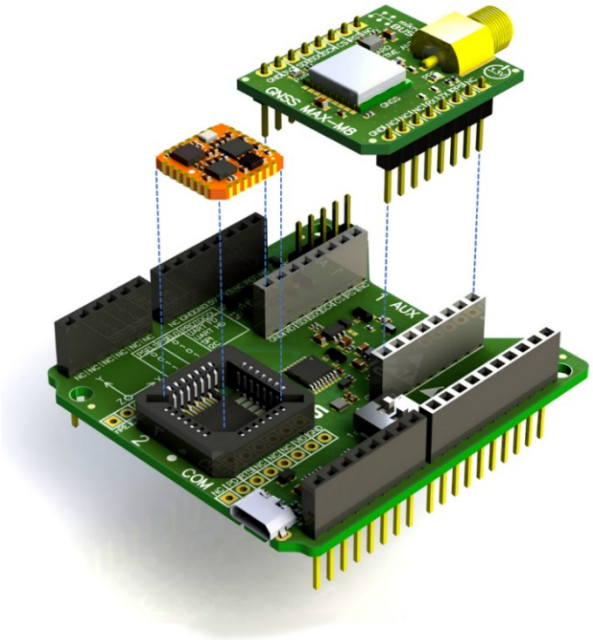

Figure 1: Exploded view of the MTi 1-series Shield board

The Shield Board, the MTi 1-s (orange module) and the GNSS daughter card (with the SMA connector) are shown in Figure 1. The features of the Shield Board include:

- 3.3 V compatible I/O
- Power indicator LEDs
- Arduino-compatible headers
- External power pin header
- Manual peripheral selection switch for MTi 1-series
- Switching between UART and I^2C on Arduino-compatible headers based on PSEL switch setting
- USB to UART converter
- Auxiliary extension socket
- Optional socket connections for mikroBUS™ RS232/RS485 click boards™

See Section 4 for more details.

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2.2 Software and documentation

The MTi 1-series Development Kit is supported by the MT Software Suite, which includes the following software components:

- MT Manager
- Magnetic Field Mapper
- MT SDK with documentation

Additionally, the latest firmware for the MTi-3 or the MTi-7 module can be downloaded and updated using the Firmware Updater that is also available on our website.

The Software components can be downloaded from the Xsens website – www.xsens.com.

Along with the SDK documentation that is part of the MT Software Suite installer package, the MTi 1-series Development Kit is supported by the following additional documents[2]

- Hardware Integration Manual: MTi 1-series (MT1503)
- Datasheet: MTi 1-series (MT0512P)
- MT Low Level Communication Protocol (MT0101P)
- MT Manager User Manual (MT0216P)
- MT Magnetic Field Mapper Documentation (MT0202P)
- Product Change Notification
    - *MTi 1-series: Components placement change*

2.2.1 Embedded examples

The MTi 1-series is designed for easy integration in embedded systems. To aid in development, example code is provided for the ARM® Mbed™ platform.

An example implementation of the Xbus Low Level Communication Protocol is provided as generic C99 compliant source code[3], while an ARM® Mbed™ specific application demonstrates the use of the Xbus library to communicate with an MTi 1-series development kit using UART communications.

The example code has been tested with the following ARM® Mbed™ compatible boards:

- ST Nucleo F302R8 – Cortex M4
- FreeScale FRDM-KL46Z – Cortex M0+
- NXP EA LPC 4088 – Cortex M4

The example code is available at http://www.mbed.org/teams/Xsens. Documentation on how to use the project is provided on the description page and in the code. Note that these examples are provided as is and are not supported by the Xsens support team. The examples are licensed under the Apache Licence version 2.0.

It is easy to extend the program with commands from the Xsens Low Level Communication Protocol (LLCP). This protocol is documented in detail in the Low Level Communication Protocol Documentation.

[2] The MT SDK and other documentation links can be found here 'C:\Program Files\Xsens\MT Software Suite x.x.x\Documentation'.
[3] Xbus example code is not specific to ARM processors and should be compatible with other embedded architectures.

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3 Getting started

3.1 Installing MT Software Suite

The MT Software Suite is available from the Xsens website (www.xsens.com/mt-software-suite).

The installation procedure consists of a set of several installers and starts with the GUI as shown in Figure 2.

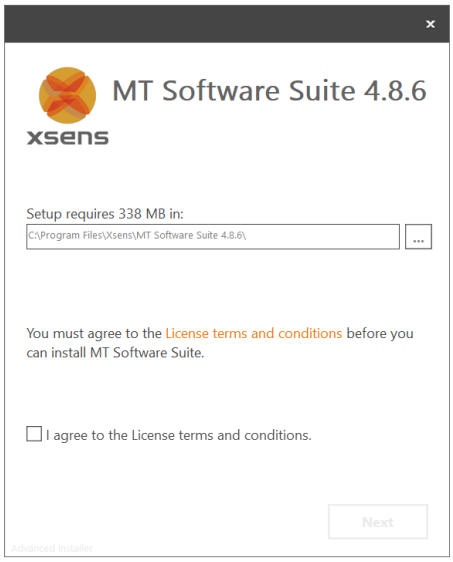

Figure 2: Start up screen for MT Software Suite installer

It is possible to choose the components that you need to install (Figure 3).

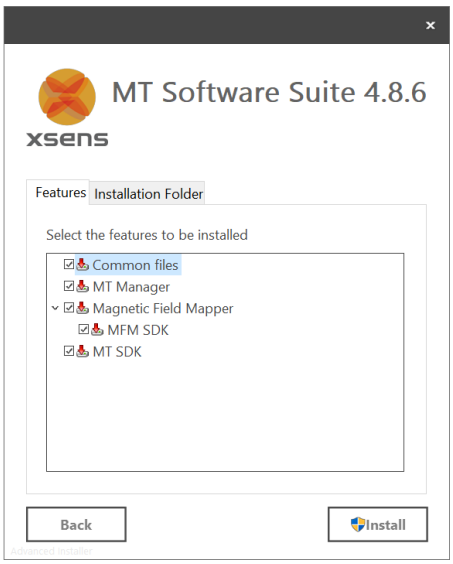

Figure 3: Software components installation

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When you cancel the installation of a particular component, the installer will continue with the next component. Make sure to accept the End-User License agreement and Software License Agreements, and then wait for the successful installation screen to appear as shown in Figure 4.

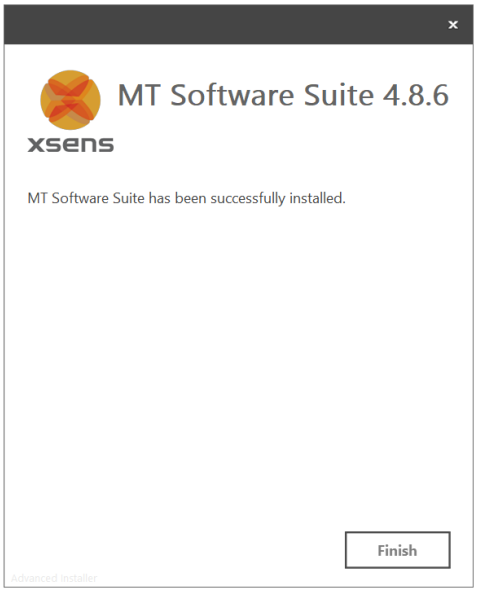

Figure 4: Successful installation screen

3.2 Displaying data in MT Manager

When the MTi 1-series Shield Board is connected in MT Manager, the device description is shown in the "Device List" (Figure 5). To see a real time 3D orientation of the MTi click the 3D View icon . The inertial data , orientation data in Euler angles and the status data can be visualized by clicking their respective icons in Figure 5.

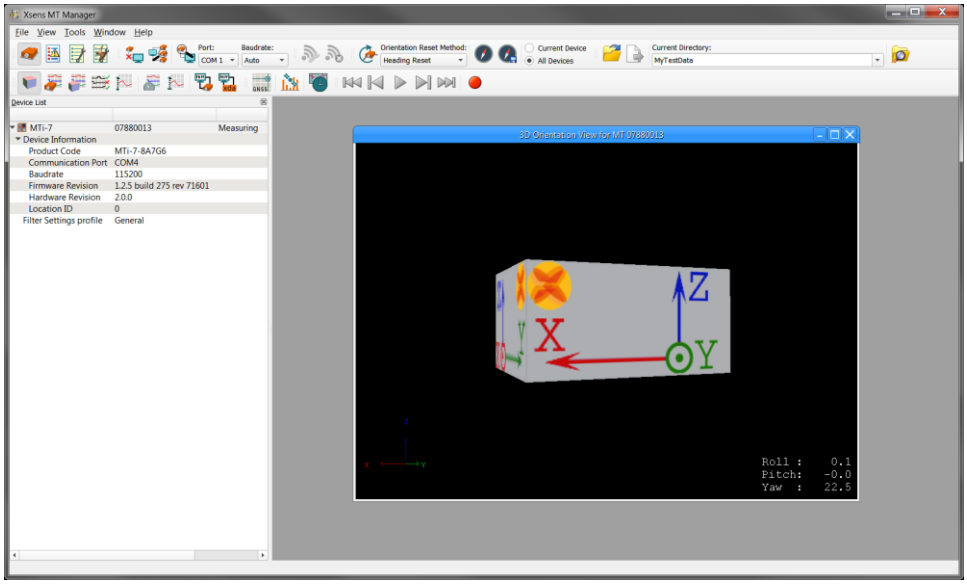

Figure 5: MT Manager overview

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3.3 Configuring the MTi 1-series

The MTi-1s can be directly configured by means of MT Manager. Click the Output Configuration button to open the Output Configuration dialog (Figure 6).

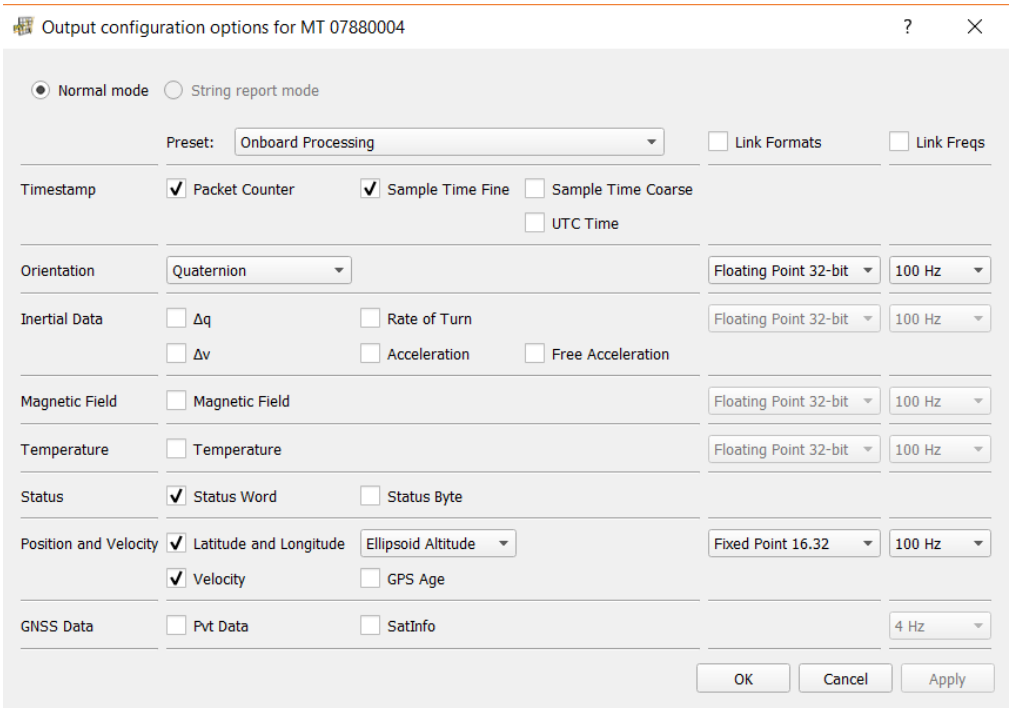

Figure 6: Output configuration dialog in MT Manager using an MTi-7-DK

By default, the output of the MTi-3 and MTi-7 is set to the 'Onboard Processing' preset, whereas the MTi-1 module is set to 'XDA processing' preset. Click "Inertial Data" (Δq/Δv or Rate of Turn/Acceleration) and "Magnetic Field" to be able to show this data in MT Manager.

With MT Manager, it is possible to record data and export that data for use in other programs, set alignment matrices, configure synchronization options and to review the test and calibration report. More information on the functions and features can be found in the MT Manager User Manual. The MT Manager User Manual can be found via Help –> Documentation.

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4 Shield board

The MTi 1-s modules are available with a development kit. An MTi-3 AHRS or an MTi-7 external-GNSS/INS is mounted in a PLCC-28 socket and connected to USB, UART, I²C and SPI. The Shield Board exposes the pins of the MTi 1-s module making it easier for the user to test all the features and the peripherals offered by the MTi 1-s. This chapter discusses in more detail the connections and peripherals available on the MTi 1-s Shield Board.

4.1 Connections and peripheral switch

The MTi 1-series Shield Board has the following connections as shown in Figure 7:

- External power pin header (J100)
- Arduino-compatible headers (P100, P101, P102 and P103)
- UART communication extension socket, not placed by default (P202 and P203)
- Micro USB (J102)
- Peripheral selection switch (SW200)
- Auxiliary sensor extension socket (P200 and P201) used for GNSS daughter card
- MTi 1-series module placed in J101

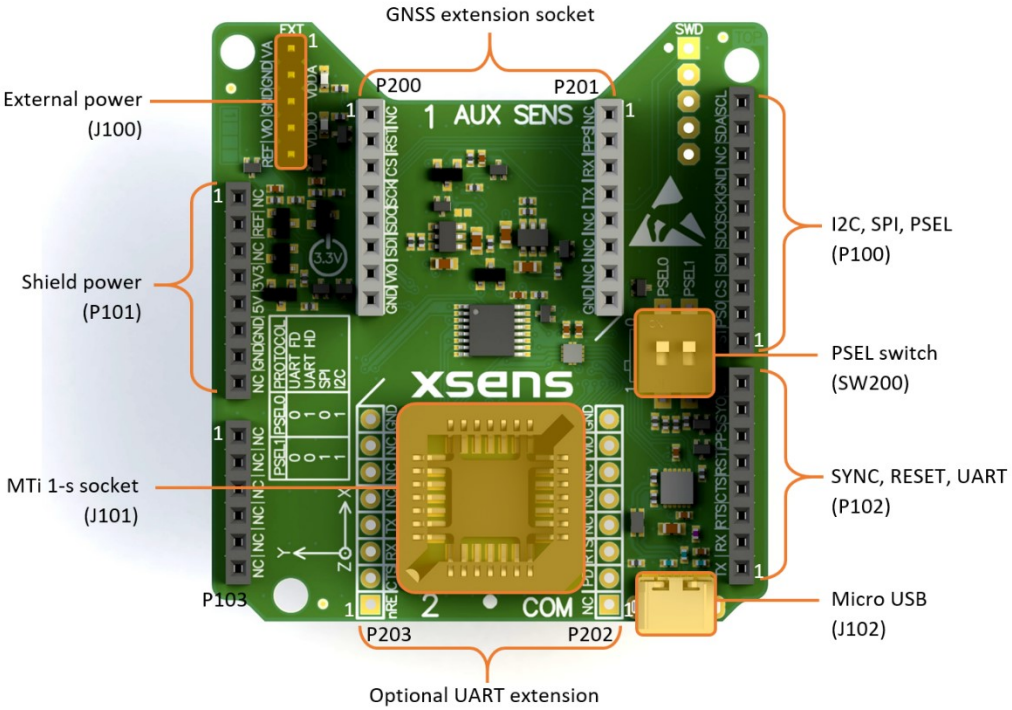

Figure 7: MTi 1-series Shield Board with connector designators

The *External power pin header* J100 can be used to directly supply the VDDIO and/or VDDA supplies for the MTi 1-s module (Table 3). The IOREF pin on this connector can be used to override the default 3.3 V VDDIO by placing a jumper from this pin to the adjacent VDDIO pin.

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Table 3: Connections on external power header (J100 in Figure 7)

Pin	Description
1	VDDA
2	GND
3	GND
4	VDDIO
5	IOREF

The connections for *Arduino-compatible headers* with a pitch of 2.54 mm (0.1 inch) are shown in Table 4. The MTi 1-series Shield Board does not support Arduino-compatible boards with an IOREF of 5V as the maximum VDDIO is 3.6V for the MTi 1-s module. Therefore, the VDDIO is by default set to 3.3V. This default VDDIO voltage can be overruled by placing a jumper on the external power header, but only for voltages within the operational VDDIO range of the MTi 1-s module. For information on the connections, refer to the pin description in Section 4.2. Refer to Table 6 on how to enable the various interfaces on the Shield Board.

Table 4: Connections on Arduino-compatible header (P100, P101, P102 and P103 in Figure 7)

Pin	Arduino	Shield Board	Pin	Arduino	Shield Board
			P100-10	SCL/D15	SCL
			P100-9	SDA/D14	SDA
			P100-8	AVDD	NC
P101-1	NC	NC	P100-7	GND	GND
P101-2	IOREF	IOREF	P100-6	SCK/D13	SCK/ADD0
P101-3	NRST	NC	P100-5	MISO/D12	MISO/ADD1
P101-4	3V3	3V3	P100-4	MOSI/D11	MOSI/ADD2
P101-5	5V	5V	P100-3	CS/D10	nCS
P101-6	GND	GND	P100-2	D9	PSEL0
P101-7	GND	GND	P100-1	D8	PSEL1
P101-8	VIN	NC	P102-8	D7	SYNC_IN
			P102-7	D6	SYNC_OUT
P103-1	A0	NC	P102-6	D5	SYNC_PPS
P103-2	A1	NC	P102-5	D4	RESET
P103-3	A2	NC	P102-4	D3	DRDY/CTS/nRE
P103-4	A3	NC	P102-3	D2	RTS/DE
P103-5	A4	NC	P102-2	TX/D1	RxD
P103-6	A5	NC	P102-1	RX/D0	TxD

The *UART communication extension socket* is not placed by default. When the socket is placed, it can be used to directly plug an UART transceiver module of MikroElektronika like the ‘RS232 click’ or ‘RS485

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click 3.3V'. This UART communication extension socket uses (only) the 3.3V supply pin, which is connected to VDDIO. We recommend to place low profile sockets (like the *CES-108-01-T-S*) to make sure that the MTi 1-s module is still easily accessible. The pin description of these headers is shown in Table 5.

Table 5: Connections on UART communication extension sockets (P202 and P203 in Figure 7)

Pin	Mikro BUS	MTi 1-s	Pin	Mikro BUS	MTi 1-s
P202-1	AN	NC	P203-1	PWM	DRDY/CTS/nRE
P202-2	RST	Pull-down	P203-2	INT	DRDY/CTS/nRE
P202-3	CS	RTS/DE	P203-3	TX	RxD
P202-4	SCK	NC	P203-4	RX	TxD
P202-5	MISO	NC	P203-5	SCL	NC
P202-6	MOSI	NC	P203-6	SDA	NC
P202-7	3.3V	VDDIO	P203-7	5V	NC
P202-8	GND	GND	P203-8	GND	GND

The MTi 1-series Shield Board has a *Micro USB* connection that can be connected directly to a USB port on a PC or laptop. **Note**: Make sure to disconnect any other power supply, as this will overrule the USB connection.

The *Peripheral selection switch* sets the interface configuration of the MTi 1-s module in the socket. The switch connects the PSEL lines (Table 6) to GND with a 5 kΩ pull-down when set to ON. Otherwise, the PSEL lines are pulled-up with a 100 kΩ resistor. The PSEL pins on the Arduino-compatible headers can be used to overrule these lines.

Table 6: Switch positions to enable interfaces on Shield Board (SW200 in Figure 7)

PSEL1	PSEL0	Interface	Comments
0	0	UART full-duplex	This interface uses the flow control lines RTS and CTS. The UART full-duplex communications mode can be used without hardware flow control. In this case the CTS line needs to be tied low (GND) to make the MTi device transmit.
0	1	UART half-duplex	The UART itself is still full duplex but the DE and nRE lines are used to control a half-duplex transceiver
1	0	SPI	
1	1	I^2C	When I^2C interface is selected, it is required to set the address on the Arduino-compatible headers (see MTi 1-series Data Sheet for the I^2C-addresses table)

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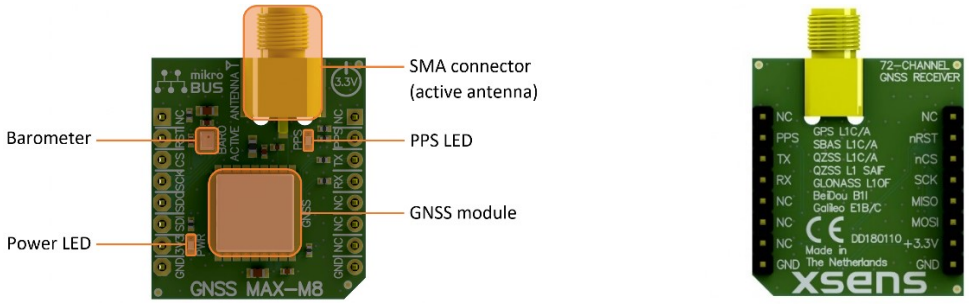

Figure 8: Top view (left) and the bottom view (right) of the GNSS daughter card

The MTi-7-DK comes with the GNSS daughter card installed in the *auxiliary sensor extension sockets* (P200 and P201). As shown in Figure 8, the GNSS daughter card consists of a GNSS and a barometer sensor component. The LEDs (Power and PPS) give indication of proper functioning of the GNSS daughter card. The supplied GNSS antenna can be connected to the SMA connector.

The *auxiliary sensor extension socket* has mikroBUS™ compatible pinning. This enables the user to connect alternate GNSS daughter card modules with mikroBUS™ pinning to the MTi 1-series Shield board. The pinning connections for the auxiliary sensor extension socket are listed in Table 7. This extension only uses the 3.3V supply pin, which is connected to VDDIO. Therefore, make sure that the VDDIO is within the required voltage range of the GNSS module.

Table 7: Connections on auxiliary sensor extension sockets (P200 and P201 in Figure 7)

Pin	Mikro BUS	MTi 1-s	Pin	Mikro BUS	MTi 1-s
P200-1	AN	NC	P201-1	PWM	NC
P200-2	RST	nRST	P201-2	INT	SYNC_PPS
P200-3	CS	AUX_nCS	P201-3	TX	AUX_RxD
P200-4	SCK	AUX_SCK	P201-4	RX	AUX_TxD
P200-5	MISO	AUX_MISO	P201-5	SCL	NC
P200-6	MOSI	AUX_MOSI	P201-6	SDA	NC
P200-7	3.3V	VDDIO	P201-7	5V	NC
P200-8	GND	GND	P201-8	GND	GND

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4.2 Pin descriptions

Table 8: Pin descriptions Shield Board

Name	Type	Description
Power Interface		
VDDA	Power	Power supply voltage for sensing elements
VDDIO	Power	Digital I/O supply voltage
Controls		
PSEL0	Selection pins	These pins determine the signal interface. Note that when the PSEL0/PSEL1 is not connected, its logic value is 1. When PSEL0/PSEL1 is connected to GND, its logic value is 0
PSEL1		
RESET		Active high reset pin, connect to GND if not used
Peripheral Interface		
SDA	I2C interface	I2C serial data
SCL		I2C serial clock
ADD[0..2]		I2C address selection pins
nCS	SPI interface	SPI chip select
MOSI		SPI serial data input (slave)
MISO		SPI serial data output (slave)
SCK		SPI serial clock
RTS	UART interface	Hardware flow control in UART full-duplex mode (Ready-to-Send)
CTS		Hardware flow control in UART full-duplex mode (Clear-to-Send)
nRE		Receiver control signal in UART half-duplex mode
DE		Transmitter control signal in UART half-duplex mode
RxD		Receiver data input
TxD		Transmitter data output
DRDY	Data ready	Data ready pin indicates that data is available (SPI / I2C)
SYNC_IN	Sync interface	Accepts a trigger input to request the latest available data message
SYNC_OUT		N/A
SYNC_PPS		Pulse Per Second output of GNSS module
AUX_RxD	Auxiliary UART interface	Auxiliary UART data input
AUX_TxD		Auxiliary UART data output
AUX_nCS	Auxiliary SPI interface	Auxiliary SPI chip select
AUX_MOSI		Auxiliary SPI serial data output (master)
AUX_MISO		Auxiliary SPI serial data input (master)
AUX_SCK		Auxiliary SPI serial clock

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4.3 Electrical specifications

The Shield Board has the same communication protocol as the MTi 1-s module. Table 9 shows the electrical specifications for the Shield Board.

Table 9: System specification Shield Board

		Min	Typ	Max	Unit
VDDA		2.16	3.3	3.6	V
VDDIO		1.8	3.3	3.6	V
V_{IO}	V_{IH}	0.75 * VDDIO			V
	V_{IL}			0.25 * VDDIO	V

4.4 Absolute maximum ratings

Table 10: Absolute maximum ratings Shield Board

Parameter	Min	Max	Unit	Comments
Storage temperature	-50	+125	ºC	
Operating temperature	-40	+85	ºC	
VDD	-0.3	4.0	V	Specification for the external power header J100.
5V on P101 and J102	-0.3	6.0	V	Specification for the Arduino and USB.
VDDIO	-0.3	4.0	V	Specification for the external power header J100.
$V_{UART,PSEL,I^2C}$	-0.3	VDDIO + 0.3	V	
$V_{RESET,SYNC,SPI}$	-0.3	VDDIO + 4.0	V	
Acceleration [4]		10,000	g	Any axis, unpowered, for 0.2 ms
ESD protection[5]		±2000	V	Human body model

Stresses beyond those listed under “Absolute Maximum Ratings” may cause permanent damage to the device. These are stress ratings only. Functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability. Make sure not to apply force on the components of the MTi 1-s module, especially when placing the MTi 1-s module in a PLCC socket.

[4] This is a mechanical shock (g) sensitive device. Proper handling is required to prevent damage to the part.
[5] This is an ESD-sensitive device. Proper handling is required to prevent damage to the part.

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4.5 Package drawing

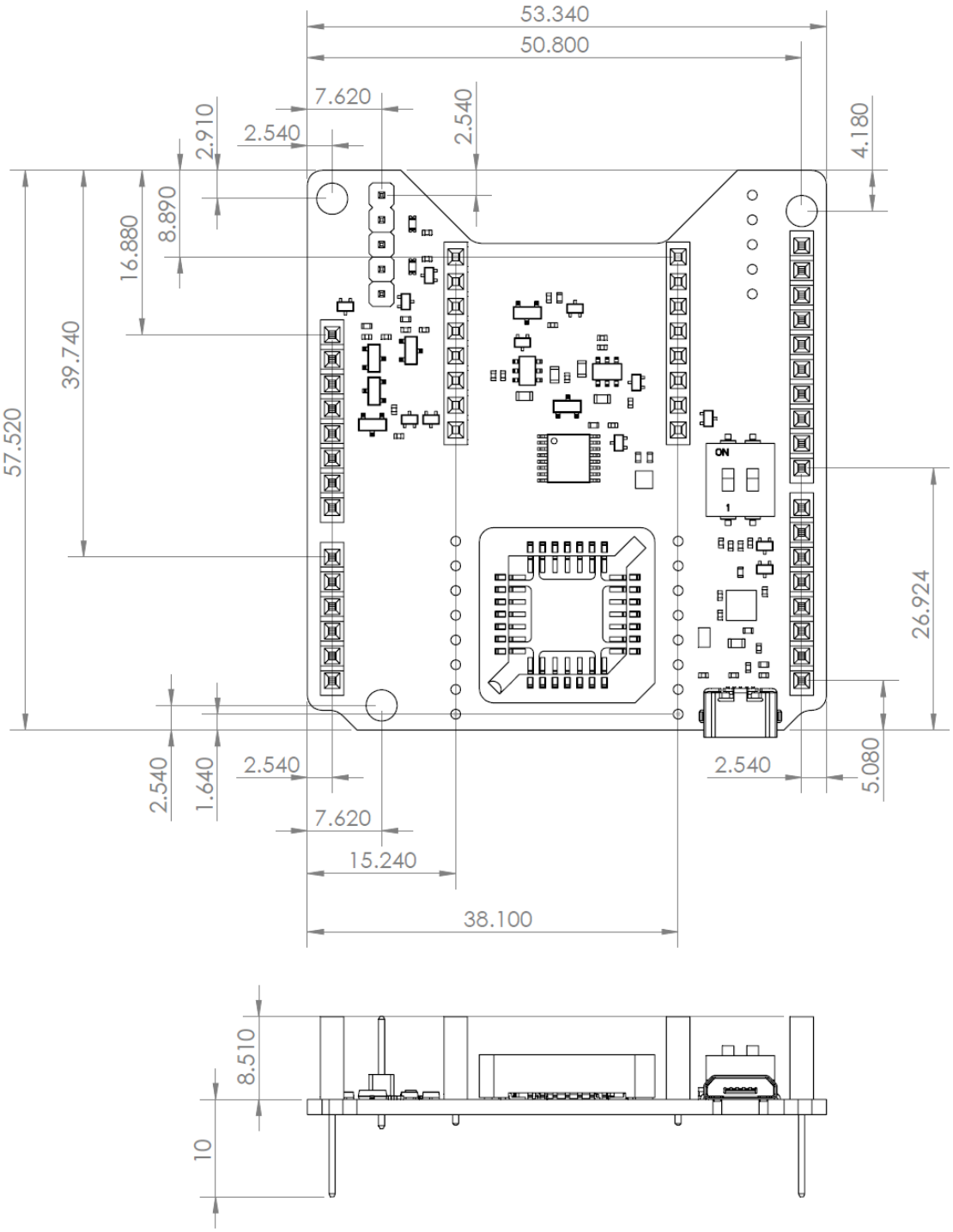

Figure 9: MTi 1-series Shield Board package drawing (Top and Side view)

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- Поставка специализированных компонентов военного и аэрокосмического уровня качества (Xilinx, Altera, Analog Devices, Intersil, Interpoint, Microsemi, Actel, Aeroflex, Peregrine, VPT, Syfer, Eurofarad, Texas Instruments, MS Kennedy, Miteq, Cobham, E2V, MA-COM, Hittite, Mini-Circuits, General Dynamics и др.);

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