



PCF8562

Universal LCD driver for low multiplex rates

Rev. 7 — 21 July 2015

Product data sheet

1. General description

The PCF8562 is a peripheral device which interfaces to almost any Liquid Crystal Display (LCD)¹ with low multiplex rates. It generates the drive signals for any static or multiplexed LCD containing up to four backplanes and up to 32 segments. The PCF8562 is compatible with most microcontrollers and communicates via the two-line bidirectional I²C-bus. Communication overheads are minimized by a display RAM with auto-incremented addressing, by hardware subaddressing and by display memory switching (static and duplex drive modes).

2. Features and benefits

- AEC-Q100 compliant (PCF8562TT/S400/2) for automotive applications
- Single chip LCD controller and driver
- Selectable backplane drive configuration: static, 2, 3, or 4 backplane multiplexing
- Selectable display bias configuration: static, 1/2, or 1/3
- Internal LCD bias generation with voltage-follower buffers
- 32 segment drives:
 - ◆ Up to sixteen 7-segment numeric characters
 - ◆ Up to eight 14-segment alphanumeric characters
 - ◆ Any graphics of up to 128 elements
- 32 × 4-bit RAM for display data storage
- Auto-incremented display data loading across device subaddress boundaries
- Display memory bank switching in static and duplex drive modes
- Versatile blinking modes
- Independent supplies possible for LCD and logic voltages
- Wide power supply range: from 1.8 V to 5.5 V
- Wide logic LCD supply range:
 - ◆ From 2.5 V for low-threshold LCDs
 - ◆ Up to 6.5 V for guest-host LCDs and high-threshold twisted nematic LCDs
- Low power consumption
- 400 kHz I²C-bus interface
- No external components required
- Manufactured in silicon gate CMOS process

1. The definition of the abbreviations and acronyms used in this data sheet can be found in [Section 18](#).



3. Ordering information

Table 1. Ordering information

Type number	Package		
	Name	Description	Version
PCF8562TT/2 ^[1]	TSSOP48	plastic thin shrink small outline package; 48 leads; body width 6.1 mm	SOT362-1
PCF8562TT/S400/2 ^[2]	TSSOP48	plastic thin shrink small outline package; 48 leads; body width 6.1 mm	SOT362-1

[1] Not to be used for new designs. Replacement part is PCF85162T/1 for industrial applications.

[2] Not to be used for new designs. Replacement part is PCA85162T/Q900/1 for automotive applications.

4. Marking

Table 2. Marking codes

Type number	Marking code
PCF8562TT/2	PCF8562TT
PCF8562TT/S400/2	PCF8562TT/S400

5. Block diagram

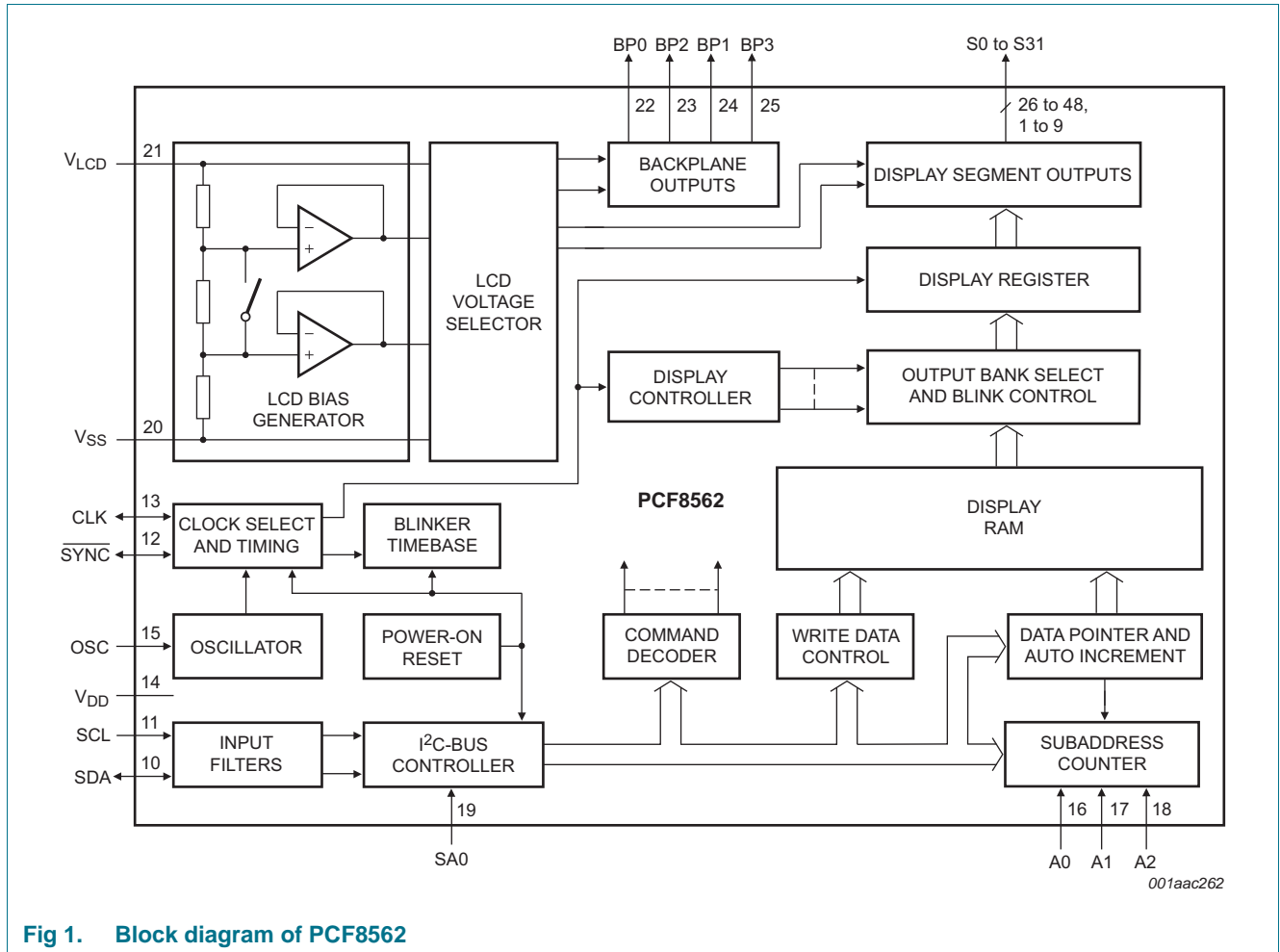
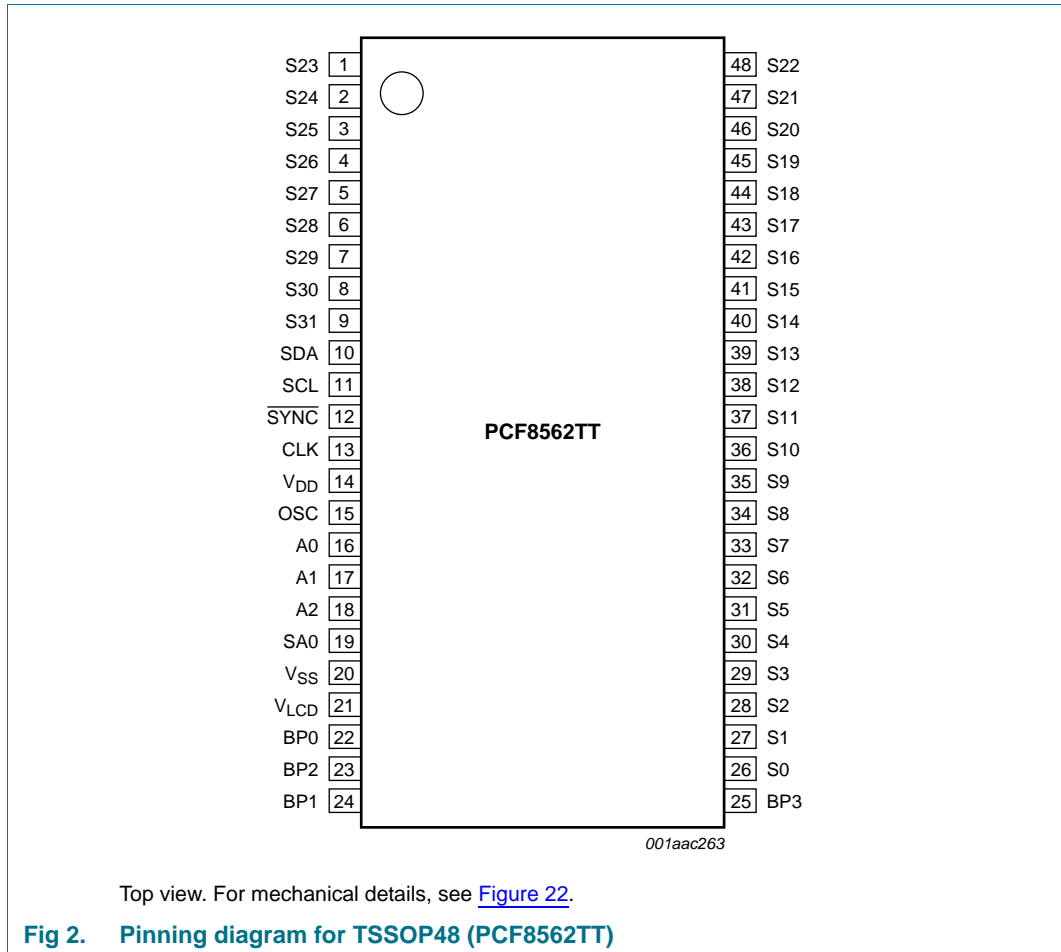


Fig 1. Block diagram of PCF8562

6. Pinning information

6.1 Pinning



6.2 Pin description

Table 3. Pin description

Symbol	Pin	Type	Description
SDA	10	input/output	I ² C-bus serial data line
SCL	11	input	I ² C-bus serial clock
$\overline{\text{SYNC}}$	12	input/output	cascade synchronization
CLK	13	input/output	clock line
V _{DD}	14	supply	supply voltage
OSC	15	input	internal oscillator enable
A0 to A2	16 to 18	input	subaddress inputs
SA0	19	input	I ² C-bus address input
V _{SS}	20	supply	ground supply voltage

Table 3. Pin description ...continued

Symbol	Pin	Type	Description
V _{LCD}	21	supply	LCD supply voltage
BP0 to BP3	22 to 25	output	LCD backplane outputs
S0 to S22, S23 to S31	26 to 48, 1 to 9	output	LCD segment outputs

7. Functional description

The PCF8562 is a versatile peripheral device designed to interface between any microcontroller to a wide variety of LCD segment or dot matrix displays (see [Figure 3](#)). It can directly drive any static or multiplexed LCD containing up to four backplanes and up to 32 segments.

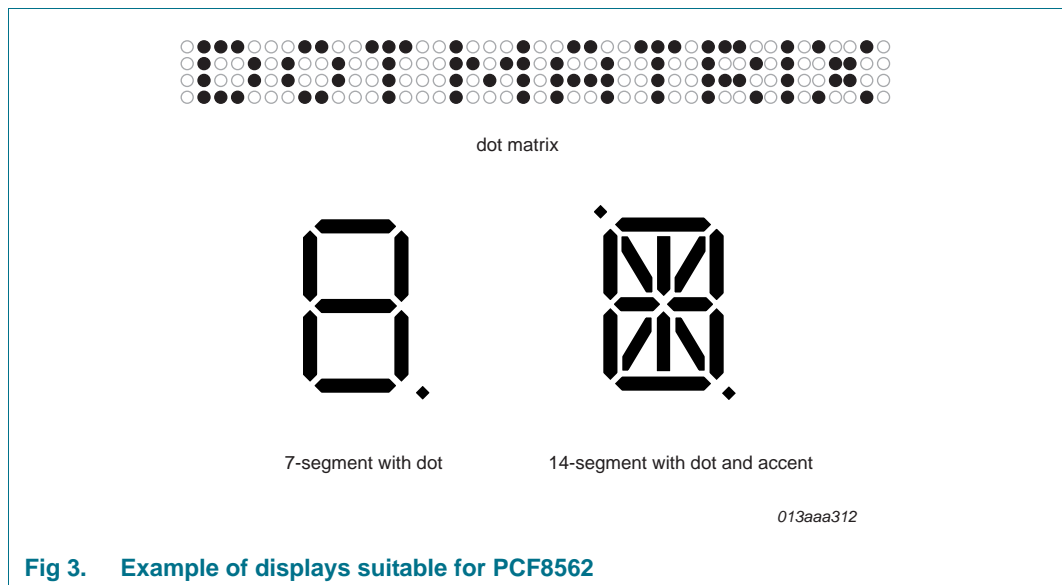
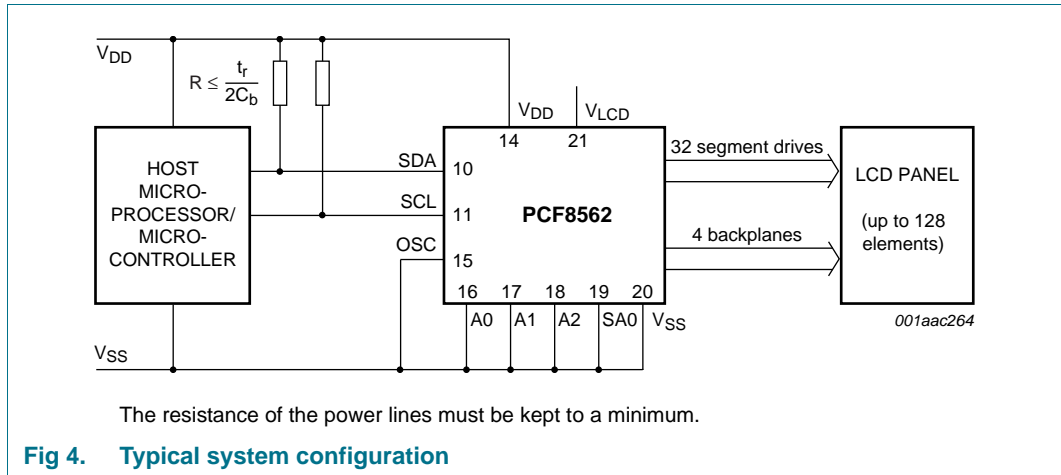


Fig 3. Example of displays suitable for PCF8562

The possible display configurations of the PCF8562 depend on the number of active backplane outputs required. A selection of display configurations is shown in [Table 4](#). All of these configurations can be implemented in the typical system shown in [Figure 4](#).

Table 4. Selection of possible display configurations

Number of				
Backplanes	Icons	Digits/Characters		Dot matrix/ Elements
		7-segment	14-segment	
4	128	16	8	128 dots (4 × 32)
3	96	12	6	96 dots (3 × 32)
2	64	8	4	64 dots (2 × 32)
1	32	4	2	32 dots (1 × 32)



The host microcontroller maintains the 2-line I²C-bus communication channel with the PCF8562. The internal oscillator is enabled by connecting pin OSC to pin V_{SS}. The appropriate biasing voltages for the multiplexed LCD waveforms are generated internally. The only other connections required to complete the system are to the power supplies (V_{DD}, V_{SS}, and V_{LCD}) and the LCD panel chosen for the application.

7.1 Power-On Reset (POR)

At power-on the PCF8562 resets to the following starting conditions:

- All backplane and segment outputs are set to V_{LCD}
- The selected drive mode is: 1:4 multiplex with 1/3 bias
- Blinking is switched off
- Input and output bank selectors are reset
- The I²C-bus interface is initialized
- The data pointer and the subaddress counter are cleared (set to logic 0)
- Display is disabled

Remark: Do not transfer data on the I²C-bus for at least 1 ms after a power-on to allow the reset action to complete.

7.2 LCD bias generator

Fractional LCD biasing voltages are obtained from an internal voltage divider consisting of three impedances connected in series between V_{LCD} and V_{SS}. The center impedance is bypassed by switch if the 1/2 bias voltage level for the 1:2 multiplex drive mode configuration is selected. The LCD voltage can be temperature compensated externally, using the supply to pin V_{LCD}.

7.3 LCD voltage selector

The LCD voltage selector coordinates the multiplexing of the LCD in accordance with the selected LCD drive configuration. The operation of the voltage selector is controlled by the mode-set command from the command decoder. The biasing configurations that apply to the preferred modes of operation, together with the biasing characteristics as functions of V_{LCD} and the resulting discrimination ratios (D) are given in [Table 5](#).

Discrimination is a term which is defined as the ratio of the on and off RMS voltage across a segment. It can be thought of as a measurement of contrast.

Table 5. Biasing characteristics

LCD drive mode	Number of:		LCD bias configuration	$\frac{V_{off(RMS)}}{V_{LCD}}$	$\frac{V_{on(RMS)}}{V_{LCD}}$	$D = \frac{V_{on(RMS)}}{V_{off(RMS)}}$
	Backplanes	Levels				
static	1	2	static	0	1	∞
1:2 multiplex	2	3	$\frac{1}{2}$	0.354	0.791	2.236
1:2 multiplex	2	4	$\frac{1}{3}$	0.333	0.745	2.236
1:3 multiplex	3	4	$\frac{1}{3}$	0.333	0.638	1.915
1:4 multiplex	4	4	$\frac{1}{3}$	0.333	0.577	1.732

A practical value for V_{LCD} is determined by equating $V_{off(RMS)}$ with a defined LCD threshold voltage ($V_{th(off)}$), typically when the LCD exhibits approximately 10 % contrast. In the static drive mode a suitable choice is $V_{LCD} > 3V_{th(off)}$.

Multiplex drive modes of 1:3 and 1:4 with $\frac{1}{2}$ bias are possible but the discrimination and hence the contrast ratios are smaller.

Bias is calculated by $\frac{1}{1+a}$, where the values for a are

a = 1 for $\frac{1}{2}$ bias

a = 2 for $\frac{1}{3}$ bias

The RMS on-state voltage ($V_{on(RMS)}$) for the LCD is calculated with [Equation 1](#):

$$V_{on(RMS)} = V_{LCD} \sqrt{\frac{a^2 + 2a + n}{n \times (1 + a)^2}} \tag{1}$$

where the values for n are

n = 1 for static drive mode

n = 2 for 1:2 multiplex drive mode

n = 3 for 1:3 multiplex drive mode

n = 4 for 1:4 multiplex drive mode

The RMS off-state voltage ($V_{off(RMS)}$) for the LCD is calculated with [Equation 2](#):

$$V_{off(RMS)} = V_{LCD} \sqrt{\frac{a^2 - 2a + n}{n \times (1 + a)^2}} \tag{2}$$

Discrimination is the ratio of $V_{on(RMS)}$ to $V_{off(RMS)}$ and is determined from [Equation 3](#):

$$D = \frac{V_{on(RMS)}}{V_{off(RMS)}} = \sqrt{\frac{a^2 + 2a + n}{a^2 - 2a + n}} \tag{3}$$

Using [Equation 3](#), the discrimination for an LCD drive mode of 1:3 multiplex with $\frac{1}{2}$ bias is $\sqrt{3} = 1.732$ and the discrimination for an LCD drive mode of 1:4 multiplex with $\frac{1}{2}$ bias is $\frac{\sqrt{21}}{3} = 1.528$.

The advantage of these LCD drive modes is a reduction of the LCD full scale voltage V_{LCD} as follows:

- 1:3 multiplex ($\frac{1}{2}$ bias): $V_{LCD} = \sqrt{6} \times V_{off(RMS)} = 2.449V_{off(RMS)}$
- 1:4 multiplex ($\frac{1}{2}$ bias): $V_{LCD} = \left[\frac{4 \times \sqrt{3}}{3} \right] = 2.309V_{off(RMS)}$

These compare with $V_{LCD} = 3V_{off(RMS)}$ when $\frac{1}{3}$ bias is used.

It should be noted that V_{LCD} is sometimes referred as the LCD operating voltage.

7.3.1 Electro-optical performance

Suitable values for $V_{on(RMS)}$ and $V_{off(RMS)}$ are dependent on the LCD liquid used. The RMS voltage, at which a pixel will be switched on or off, determine the transmissibility of the pixel.

For any given liquid, there are two threshold values defined. One point is at 10 % relative transmission (at $V_{th(off)}$) and the other at 90 % relative transmission (at $V_{th(on)}$), see [Figure 5](#). For a good contrast performance, the following rules should be followed:

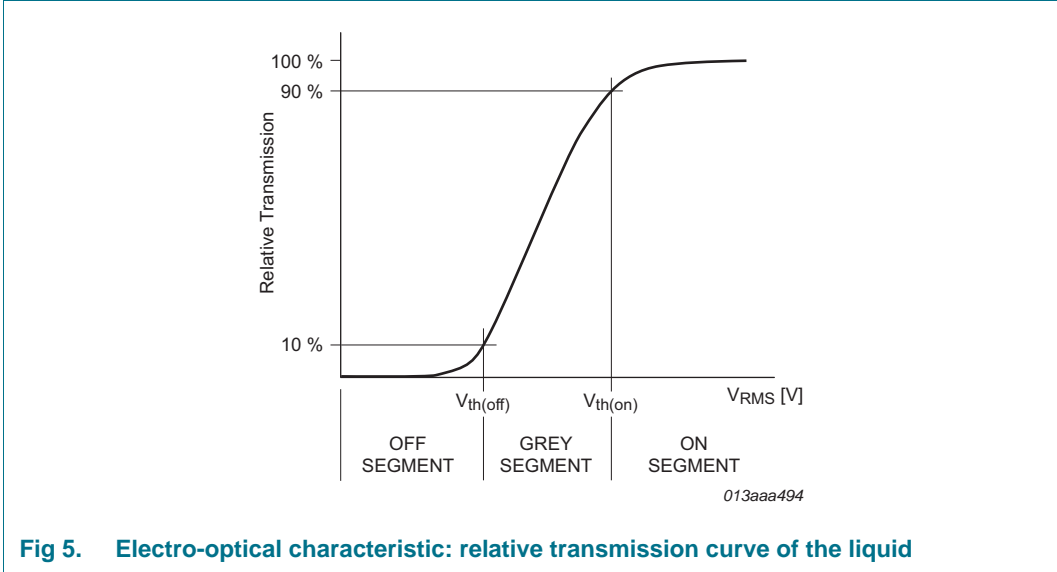
$$V_{on(RMS)} \geq V_{th(on)} \tag{4}$$

$$V_{off(RMS)} \leq V_{th(off)} \tag{5}$$

$V_{on(RMS)}$ and $V_{off(RMS)}$ are properties of the display driver and are affected by the selection of a, n (see [Equation 1](#) to [Equation 3](#)) and the V_{LCD} voltage.

$V_{th(off)}$ and $V_{th(on)}$ are properties of the LCD liquid and can be provided by the module manufacturer.

It is important to match the module properties to those of the driver in order to achieve optimum performance.



7.4 LCD drive mode waveforms

7.4.1 Static drive mode

The static LCD drive mode is used when a single backplane is provided in the LCD. The backplane (BPn) and segment (Sn) drive waveforms for this mode are shown in [Figure 6](#).

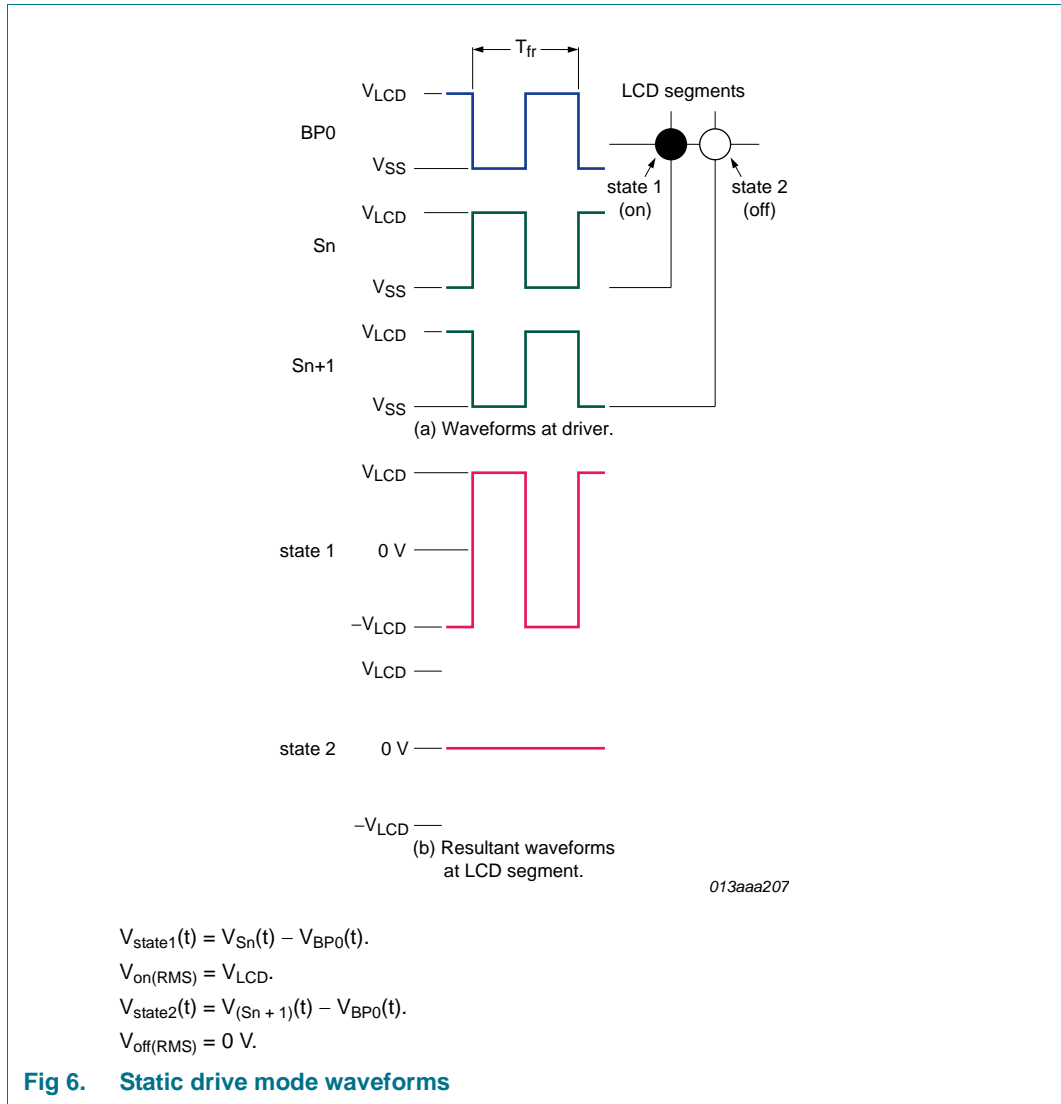


Fig 6. Static drive mode waveforms

7.4.2 1:2 Multiplex drive mode

When two backplanes are provided in the LCD, the 1:2 multiplex mode applies. The PCF8562 allows the use of 1/2 bias or 1/3 bias in this mode as shown in Figure 7 and Figure 8.

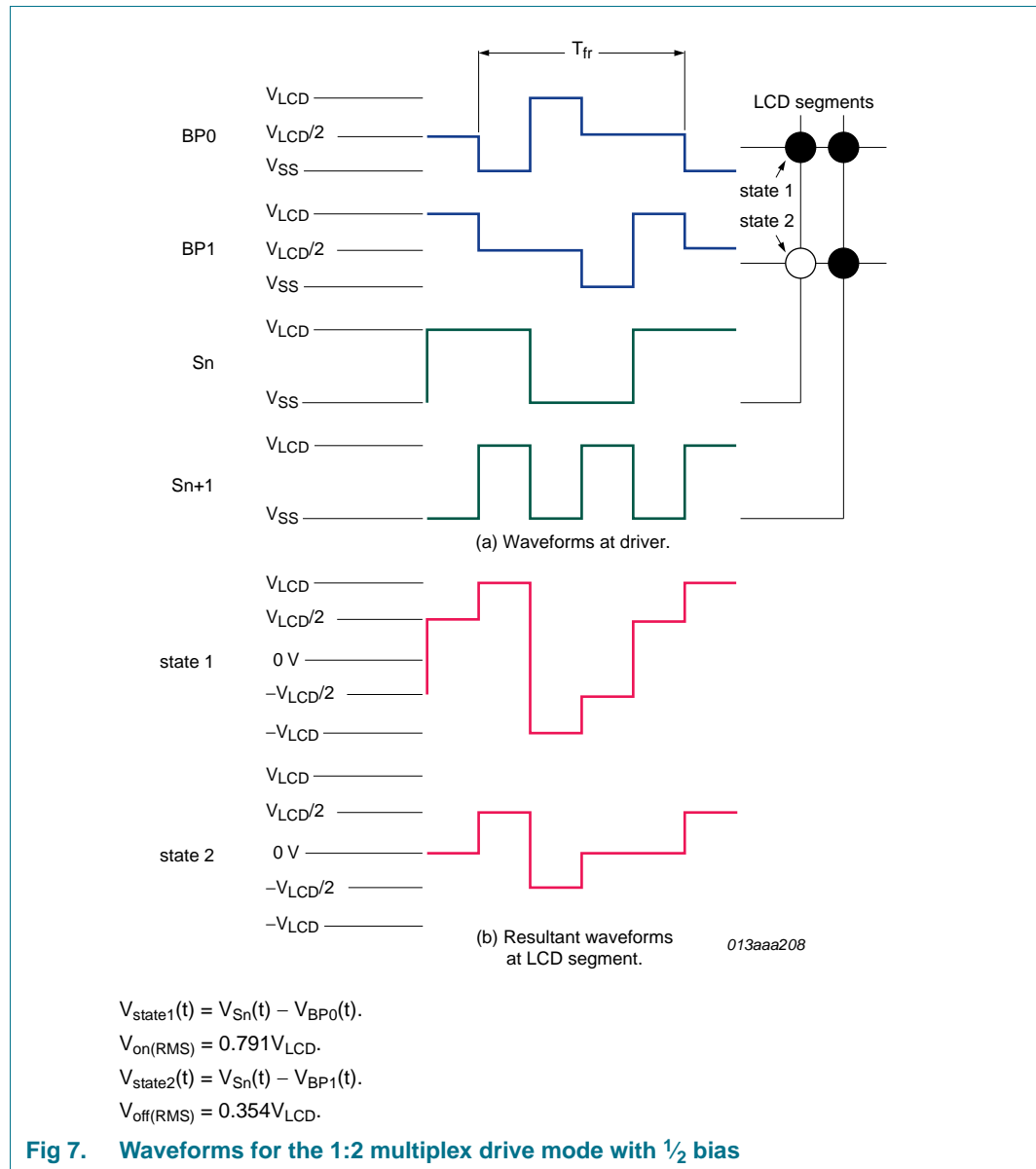


Fig 7. Waveforms for the 1:2 multiplex drive mode with 1/2 bias

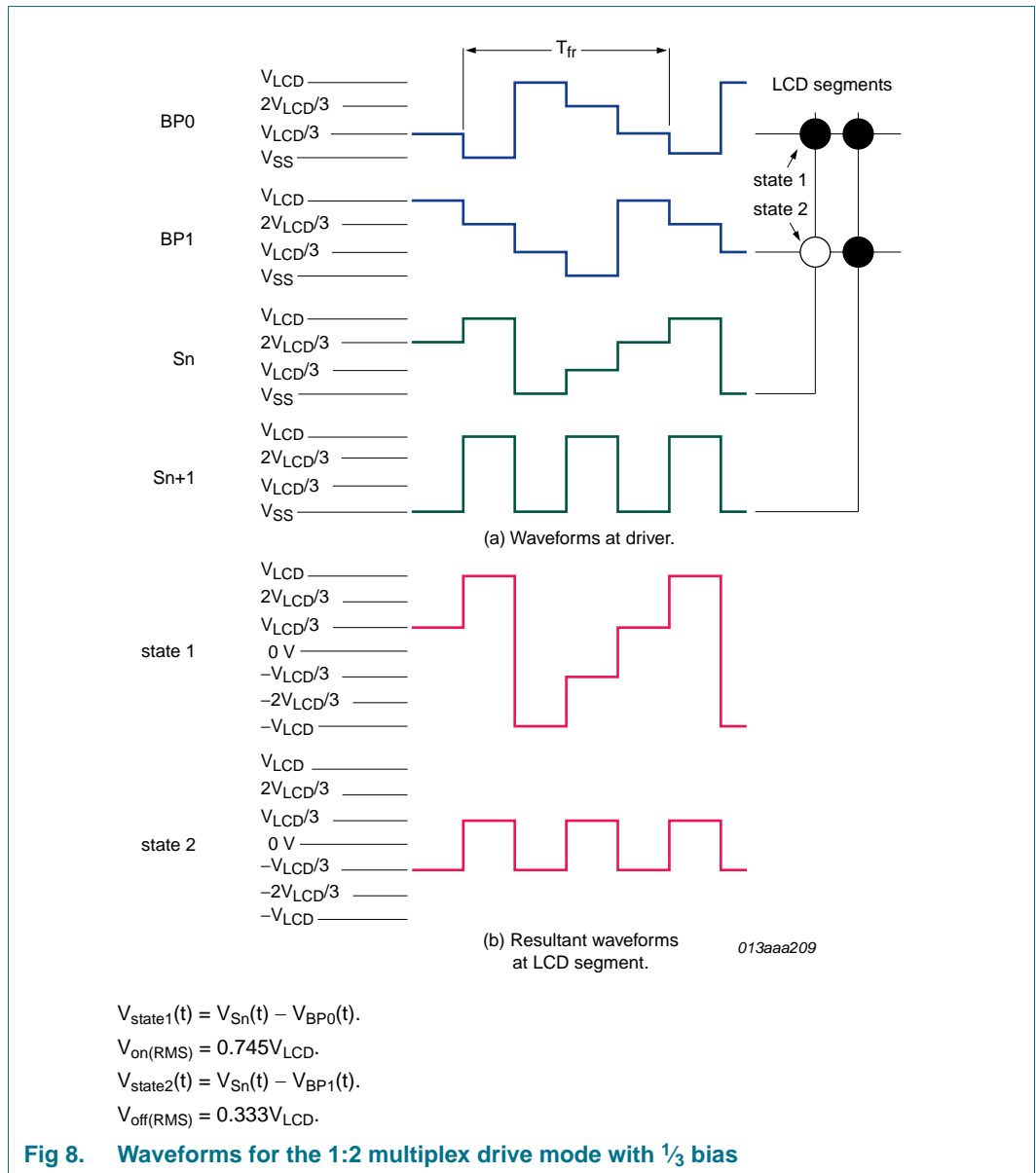


Fig 8. Waveforms for the 1:2 multiplex drive mode with 1/3 bias

7.4.3 1:3 Multiplex drive mode

When three backplanes are provided in the LCD, the 1:3 multiplex drive mode applies, as shown in Figure 9.

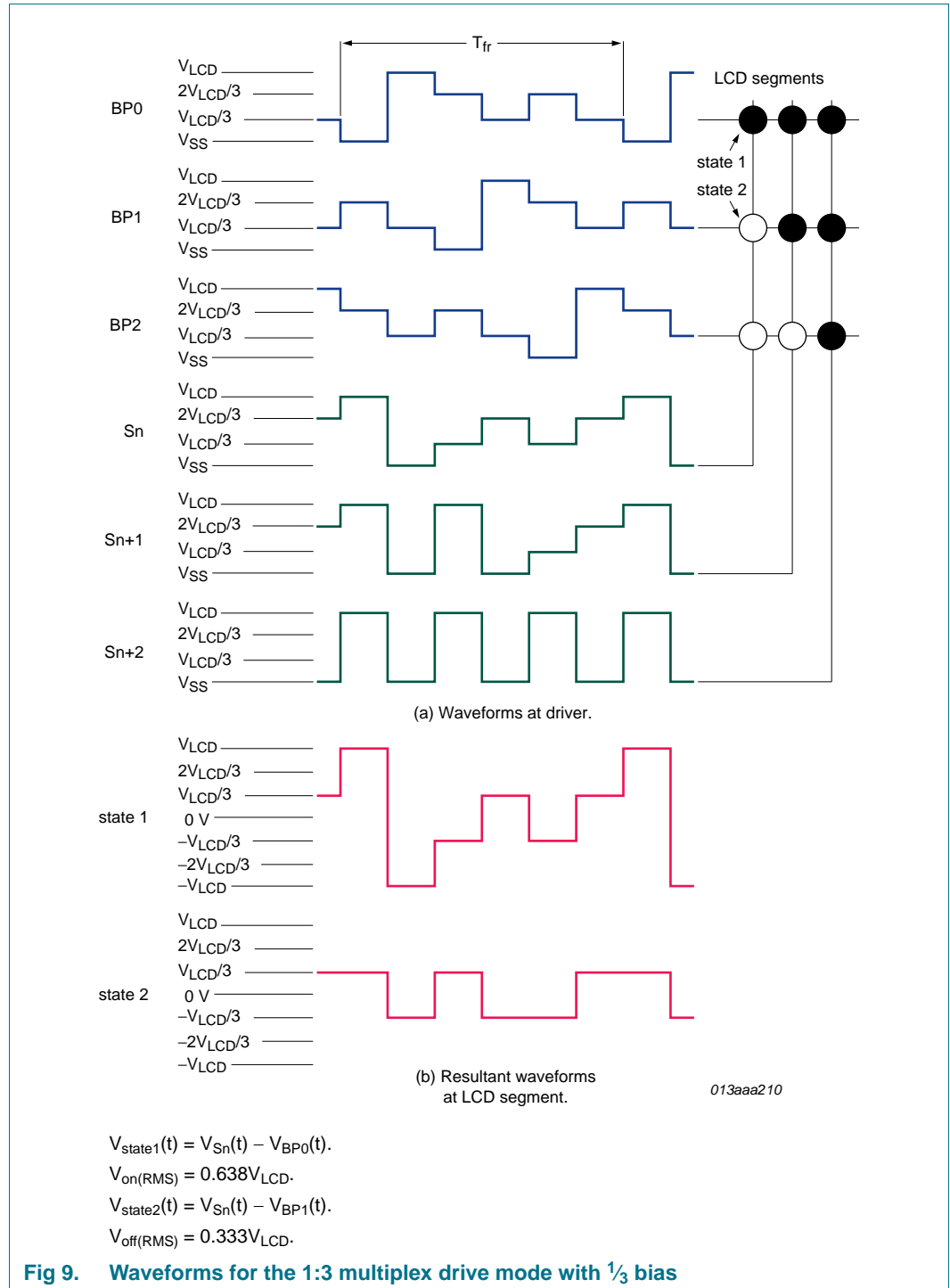


Fig 9. Waveforms for the 1:3 multiplex drive mode with 1/3 bias

7.4.4 1:4 Multiplex drive mode

When four backplanes are provided in the LCD, the 1:4 multiplex drive mode applies as shown in Figure 10.

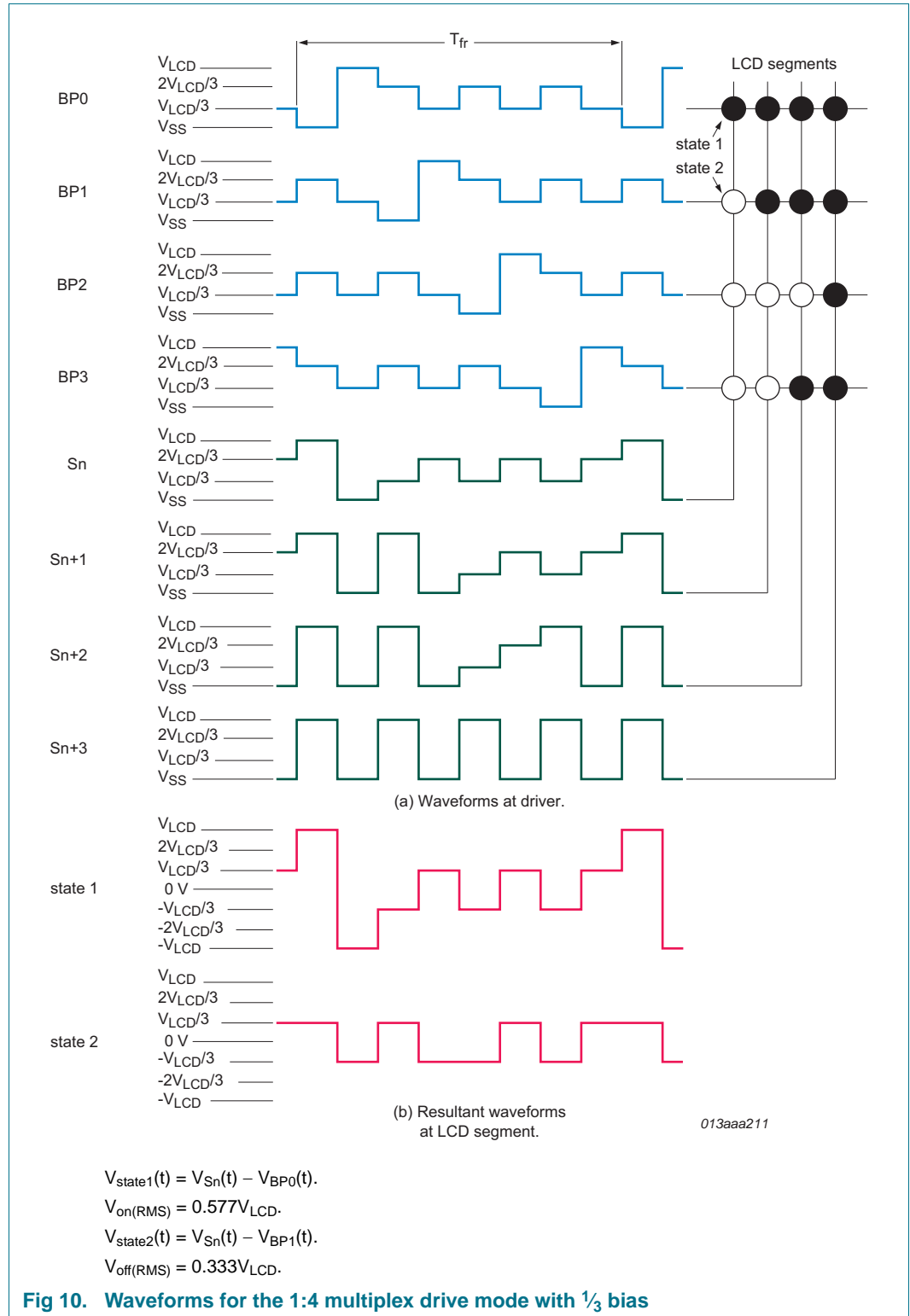


Fig 10. Waveforms for the 1:4 multiplex drive mode with 1/3 bias

7.5 Oscillator

7.5.1 Internal clock

The internal logic of the PCF8562 and its LCD drive signals are timed either by its internal oscillator or by an external clock. The internal oscillator is enabled by connecting pin OSC to pin V_{SS}.

7.5.2 External clock

Pin CLK is enabled as an external clock input by connecting pin OSC to V_{DD}.

The LCD frame signal frequency is determined by the clock frequency (f_{clk}).

Remark: A clock signal must always be supplied to the device; removing the clock may freeze the LCD in a DC state, which is not suitable for the liquid crystal.

7.6 Timing

The PCF8562 timing controls the internal data flow of the device. This includes the transfer of display data from the display RAM to the display segment outputs. The timing also generates the LCD frame signal whose frequency is derived from the clock frequency. The frame signal frequency is a fixed division of the clock frequency from either

the internal or an external clock: $f_{fr} = \frac{f_{clk}}{24}$.

7.7 Display register

The display register holds the display data while the corresponding multiplex signals are generated.

7.8 Segment outputs

The LCD drive section includes 32 segment outputs S0 to S31 which should be connected directly to the LCD. The segment output signals are generated in accordance with the multiplexed backplane signals and with data residing in the display latch. When less than 32 segment outputs are required, the unused segment outputs should be left open-circuit.

7.9 Backplane outputs

The LCD drive section includes four backplane outputs BP0 to BP3 which must be connected directly to the LCD. The backplane output signals are generated in accordance with the selected LCD drive mode. If less than four backplane outputs are required, the unused outputs can be left open-circuit.

- In the 1:3 multiplex drive mode, BP3 carries the same signal as BP1, therefore these two adjacent outputs can be tied together to give enhanced drive capabilities.
- In the 1:2 multiplex drive mode, BP0 and BP2, respectively, BP1 and BP3 carry the same signals and may also be paired to increase the drive capabilities.
- In the static drive mode the same signal is carried by all four backplane outputs and they can be connected in parallel for very high drive requirements.

drive mode	LCD segments	LCD backplanes	display RAM filling order	transmitted display byte																																																	
static			<p>columns display RAM address/segment outputs (s) byte1</p> <table border="1"> <tr> <td></td> <td>n</td> <td>n+1</td> <td>n+2</td> <td>n+3</td> <td>n+4</td> <td>n+5</td> <td>n+6</td> <td>n+7</td> </tr> <tr> <td>rows display RAM</td> <td>0</td> <td>c</td> <td>b</td> <td>a</td> <td>f</td> <td>g</td> <td>e</td> <td>d</td> <td>DP</td> </tr> <tr> <td>rows/backplane</td> <td>1</td> <td>x</td> <td>x</td> <td>x</td> <td>x</td> <td>x</td> <td>x</td> <td>x</td> <td>x</td> </tr> <tr> <td>outputs (BP)</td> <td>2</td> <td>x</td> <td>x</td> <td>x</td> <td>x</td> <td>x</td> <td>x</td> <td>x</td> <td>x</td> </tr> <tr> <td></td> <td>3</td> <td>x</td> <td>x</td> <td>x</td> <td>x</td> <td>x</td> <td>x</td> <td>x</td> <td>x</td> </tr> </table>		n	n+1	n+2	n+3	n+4	n+5	n+6	n+7	rows display RAM	0	c	b	a	f	g	e	d	DP	rows/backplane	1	x	x	x	x	x	x	x	x	outputs (BP)	2	x	x	x	x	x	x	x	x		3	x	x	x	x	x	x	x	x	<p>MSB</p> <p>LSB</p> <p>c b a f g e d DP</p>
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outputs (BP)	2	x	x	x	x	x	x	x	x																																												
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	3	DP	d																																																		

001aaj646

x = data bit unchanged.

Fig 12. Relationship between LCD layout, drive mode, display RAM filling order and display data transmitted over the I²C-bus

The following applies to [Figure 12](#):

- In static drive mode the eight transmitted data bits are placed in row 0 as one byte.
- In 1:2 multiplex drive mode the eight transmitted data bits are placed in pairs into row 0 and 1 as two successive 4-bit RAM words.
- In 1:3 multiplex drive mode the eight bits are placed in triples into row 0, 1, and 2 as three successive 3-bit RAM words, with bit 3 of the third address left unchanged. It is not recommended to use this bit in a display because of the difficult addressing. This last bit may, if necessary, be controlled by an additional transfer to this address but care should be taken to avoid overwriting adjacent data because always full bytes are transmitted (see [Section 7.10.3](#)).
- In 1:4 multiplex drive mode, the eight transmitted data bits are placed in quadruples into row 0, 1, 2, and 3 as two successive 4-bit RAM words.

7.10.1 Data pointer

The addressing mechanism for the display RAM is realized using the data pointer. This allows the loading of an individual display data byte, or a series of display data bytes, into any location of the display RAM. The sequence commences with the initialization of the data pointer by the load-data-pointer command (see [Table 12](#)). Following this command, an arriving data byte is stored at the display RAM address indicated by the data pointer. The filling order is shown in [Figure 12](#).

After each byte is stored, the content of the data pointer is automatically incremented by a value dependent on the selected LCD drive mode:

- In static drive mode by eight
- In 1:2 multiplex drive mode by four
- In 1:3 multiplex drive mode by three
- In 1:4 multiplex drive mode by two

If an I²C-bus data access is terminated early then the state of the data pointer is unknown. The data pointer should be re-written prior to further RAM accesses.

7.10.2 Subaddress counter

The storage of display data is determined by the content of the subaddress counter. Storage is allowed to take place only when the content of the subaddress counter matches with the hardware subaddress applied to A0, A1, and A2. The subaddress counter value is defined by the device-select command (see [Table 13](#)). If the content of the subaddress counter and the hardware subaddress do not match then data storage is inhibited but the data pointer is incremented as if data storage had taken place. The subaddress counter is also incremented when the data pointer overflows.

The hardware subaddress must not be changed while the device is being accessed on the I²C-bus interface.

7.10.3 RAM writing in 1:3 multiplex drive mode

In 1:3 multiplex drive mode, the RAM is written as shown in [Table 6](#) (see [Figure 12](#) as well).

Table 6. Standard RAM filling in 1:3 multiplex drive mode

Assumption: BP2/S2, BP2/S5, BP2/S8 etc. **are not connected** to any elements on the display.

Display RAM bits (rows)/ backplane outputs (BPn)	Display RAM addresses (columns)/segment outputs (Sn)										
	0	1	2	3	4	5	6	7	8	9	:
0	a7	a4	a1	b7	b4	b1	c7	c4	c1	d7	:
1	a6	a3	a0	b6	b3	b0	c6	c3	c0	d6	:
2	a5	a2	-	b5	b2	-	c5	c2	-	d5	:
3	-	-	-	-	-	-	-	-	-	-	:

If the bit at position BP2/S2 would be written by a second byte transmitted, then the mapping of the segment bits would change as illustrated in [Table 7](#).

Table 7. Entire RAM filling by rewriting in 1:3 multiplex drive mode

Assumption: BP2/S2, BP2/S5, BP2/S8 etc. **are connected** to elements on the display.

Display RAM bits (rows)/ backplane outputs (BPn)	Display RAM addresses (columns)/segment outputs (Sn)										
	0	1	2	3	4	5	6	7	8	9	:
0	a7	a4	a1/b7	b4	b1/c7	c4	c1/d7	d4	d1/e7	e4	:
1	a6	a3	a0/b6	b3	b0/c6	c3	c0/d6	d3	d0/e6	e3	:
2	a5	a2	b5	b2	c5	c2	d5	d2	e5	e2	:
3	-	-	-	-	-	-	-	-	-	-	:

In the case described in [Table 7](#) the RAM has to be written entirely and BP2/S2, BP2/S5, BP2/S8 etc. have to be connected to elements on the display. This can be achieved by a combination of writing and rewriting the RAM like follows:

- In the first write to the RAM, bits a7 to a0 are written.
- In the second write, bits b7 to b0 are written, overwriting bits a1 and a0 with bits b7 and b6.
- In the third write, bits c7 to c0 are written, overwriting bits b1 and b0 with bits c7 and c6.

Depending on the method of writing to the RAM (standard or entire filling by rewriting), some elements remain unused or can be used, but it has to be considered in the module layout process as well as in the driver software design.

7.10.4 Output bank selector

The output bank selector (see [Table 14](#)) selects one of the four rows per display RAM address for transfer to the display register. The actual row selected depends on the particular LCD drive mode in operation and on the instant in the multiplex sequence.

- In 1:4 multiplex mode, all RAM addresses of row 0 are selected, these are followed by the content of row 1, 2, and then 3
- In 1:3 multiplex mode, rows 0, 1, and 2 are selected sequentially
- In 1:2 multiplex mode, rows 0 and 1 are selected
- In static mode, row 0 is selected

The PCF8562 includes a RAM bank switching feature in the static and 1:2 multiplex drive modes. In the static drive mode, the bank-select command may request the content of row 2 to be selected for display instead of the content of row 0. In the 1:2 multiplex mode, the content of rows 2 and 3 may be selected instead of rows 0 and 1. This gives the provision for preparing display information in an alternative bank and to be able to switch to it once it is assembled.

7.10.5 Input bank selector

The input bank selector loads display data into the display RAM in accordance with the selected LCD drive configuration.

The bank-select command (see [Table 14](#)) can be used to load display data in row 2 in static drive mode or in rows 2 and 3 in 1:2 mode. The input bank selector functions are independent of the output bank selector.

7.11 Blinking

The display blinking capabilities of the PCF8562 are very versatile. The whole display can blink at frequencies selected by the blink-select command (see [Table 15](#)). The blink frequencies are fractions of the clock frequency. The ratio between the clock and blink frequencies depends on the blink mode selected (see [Table 8](#)).

An additional feature is for an arbitrary selection of LCD elements to blink. This applies to the static and 1:2 multiplex drive modes and can be implemented without any communication overheads. By means of the output bank selector, the displayed RAM banks are exchanged with alternate RAM banks at the blink frequency. This mode can also be specified by the blink-select command.

In the 1:3 and 1:4 multiplex modes, where no alternative RAM bank is available, groups of LCD elements can blink by selectively changing the display RAM data at fixed time intervals.

Table 8. Blinking frequencies^[1]

Blink mode	Normal operating mode ratio	Nominal blink frequency
off	-	blinking off
1	$\frac{f_{clk}}{768}$	2 Hz
2	$\frac{f_{clk}}{1536}$	1 Hz
3	$\frac{f_{clk}}{3072}$	0.5 Hz

[1] Blink modes 1, 2, and 3 and the nominal blink frequencies 0.5 Hz, 1 Hz, and 2 Hz correspond to an oscillator frequency (f_{clk}) of 1536 Hz (see [Section 12](#)).

The entire display can blink at a frequency other than the nominal blink frequency. This can be effectively performed by resetting and setting the display enable bit E at the required rate using the mode-set command (see [Table 11](#)).

7.12 Command decoder

The command decoder identifies command bytes that arrive on the I²C-bus. The commands available to the PCF8562 are defined in [Table 9](#).

Table 9. Definition of PCF8562 commands

Command	Operation code								Reference
	7	6	5	4	3	2	1	0	
mode-set	C	1	0	-[1]	E	B	M[1:0]		Table 11
load-data-pointer	C	0	0	P[4:0]					Table 12
device-select	C	1	1	0	0	A[2:0]			Table 13
bank-select	C	1	1	1	1	0	I	O	Table 14
blink-select	C	1	1	1	0	AB	BF[1:0]		Table 15

[1] Not used.

All available commands carry a continuation bit C in their most significant bit position as shown in [Figure 18](#). When this bit is set, it indicates that the next byte of the transfer to arrive will also represent a command. If this bit is reset, it indicates that the command byte is the last in the transfer. Further bytes will be regarded as display data (see [Table 10](#)).

Table 10. C bit description

Bit	Symbol	Value	Description
7	C		continue bit
		0	last control byte in the transfer; next byte will be regarded as display data
		1	control bytes continue; next byte will be a command too

Table 11. Mode-set command bit description

Bit	Symbol	Value	Description
7	C	0, 1	see Table 10
6, 5	-	10	fixed value
4	-	-	unused
3	E		display status
		0	disabled (blank) ^[1]
		1	enabled
2	B		LCD bias configuration^[2]
		0	1/3 bias
		1	1/2 bias
1 to 0	M[1:0]		LCD drive mode selection
		01	static; BP0
		10	1:2 multiplex; BP0, BP1
		11	1:3 multiplex; BP0, BP1, BP2
		00	1:4 multiplex; BP0, BP1, BP2, BP3

[1] The possibility to disable the display allows implementation of blinking under external control.

[2] Not applicable for static drive mode.

Table 12. Load-data-pointer command bit description

Bit	Symbol	Value	Description
7	C	0, 1	see Table 10
6, 5	-	00	fixed value
4 to 0	P[4:0]	00000 to 11111	5 bit binary value, 0 to 31; transferred to the data pointer to define one of 32 display RAM addresses

Table 13. Device-select command bit description

Bit	Symbol	Value	Description
7	C	0, 1	see Table 10
6 to 3	-	1100	fixed value
2 to 0	A[2:0]	000 to 111	3 bit binary value, 0 to 7; transferred to the subaddress counter to define one of eight hardware subaddresses

Table 14. Bank-select command bit description

Bit	Symbol	Value	Description	
			Static	1:2 multiplex ^[1]
7	C	0, 1	see Table 10	
6 to 2	-	11110	fixed value	
1	I		input bank selection ; storage of arriving display data	
		0	RAM bit 0	RAM bits 0 and 1
		1	RAM bit 2	RAM bits 2 and 3
0	O		output bank selection ; retrieval of LCD display data	
		0	RAM bit 0	RAM bits 0 and 1
		1	RAM bit 2	RAM bits 2 and 3

[1] The bank-select command has no effect in 1:3 and 1:4 multiplex drive modes.

Table 15. Blink-select command bit description

Bit	Symbol	Value	Description
7	C	0, 1	see Table 10
6 to 3	-	1110	fixed value
2	AB		blink mode selection
		0	normal blinking ^[1]
		1	alternate RAM bank blinking ^[2]
1 to 0	BF[1:0]		blink frequency selection
		00	off
		01	1
		10	2
		11	3

[1] Normal blinking is assumed when the LCD multiplex drive modes 1:3 or 1:4 are selected.

[2] Alternate RAM bank blinking does not apply in 1:3 and 1:4 multiplex drive modes.

7.13 Display controller

The display controller executes the commands identified by the command decoder. It contains the device's status registers and coordinates their effects. The display controller is also responsible for loading display data into the display RAM in the correct filling order.

8. Characteristics of the I²C-bus

The I²C-bus is for bidirectional, two-line communication between different ICs or modules. The two lines are a Serial DATA Line (SDA) and a Serial CLOCK line (SCL). Both lines must be connected to a positive supply via a pull-up resistor when connected to the output stages of a device. Data transfer may be initiated only when the bus is not busy.

8.1 Bit transfer

One data bit is transferred during each clock pulse. The data on the SDA line must remain stable during the HIGH period of the clock pulse as changes in the data line at this time will be interpreted as a control signal (see [Figure 13](#)).

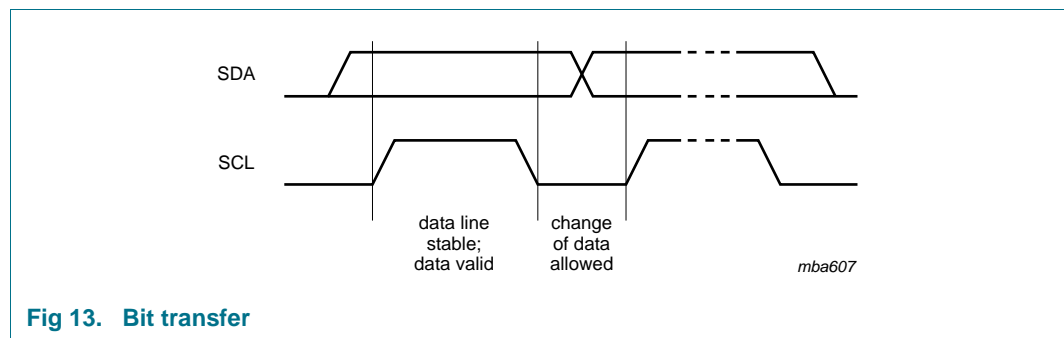


Fig 13. Bit transfer

8.2 START and STOP conditions

Both data and clock lines remain HIGH when the bus is not busy.

A HIGH-to-LOW transition of the data line while the clock is HIGH is defined as the START condition - S.

A LOW-to-HIGH transition of the data line while the clock is HIGH is defined as the STOP condition - P (see [Figure 14](#)).

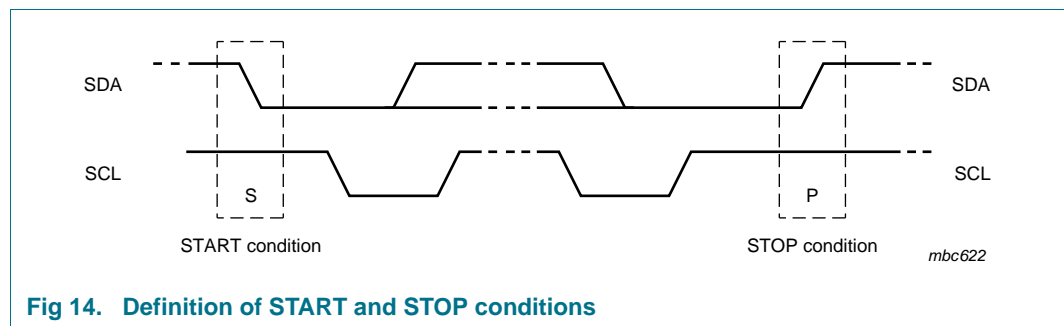


Fig 14. Definition of START and STOP conditions

8.3 System configuration

A device generating a message is a transmitter, a device receiving a message is the receiver. The device that controls the message is the master and the devices which are controlled by the master are the slaves (see [Figure 15](#)).

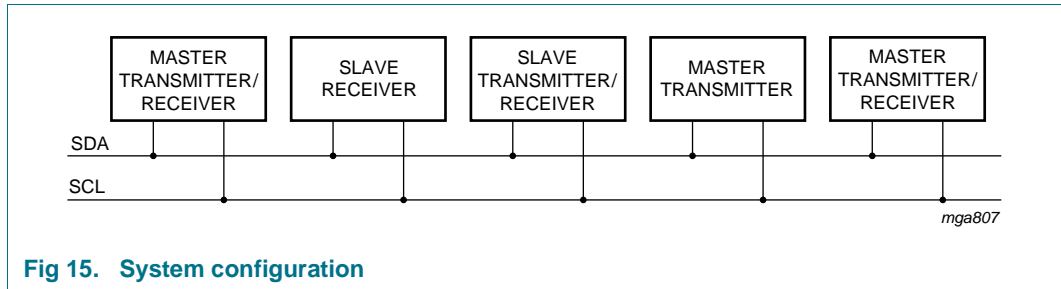


Fig 15. System configuration

8.4 Acknowledge

The number of data bytes transferred between the START and STOP conditions from transmitter to receiver is unlimited. Each byte of eight bits is followed by an acknowledge cycle.

- A slave receiver, which is addressed, must generate an acknowledge after the reception of each byte.
- A master receiver must generate an acknowledge after the reception of each byte that has been clocked out of the slave transmitter.
- The device that acknowledges must pull-down the SDA line during the acknowledge clock pulse, so that the SDA line is stable LOW during the HIGH period of the acknowledge related clock pulse (set-up and hold times must be taken into consideration).
- A master receiver must signal an end of data to the transmitter by not generating an acknowledge on the last byte that has been clocked out of the slave. In this event, the transmitter must leave the data line HIGH to enable the master to generate a STOP condition.

Acknowledgement on the I²C-bus is illustrated in [Figure 16](#).

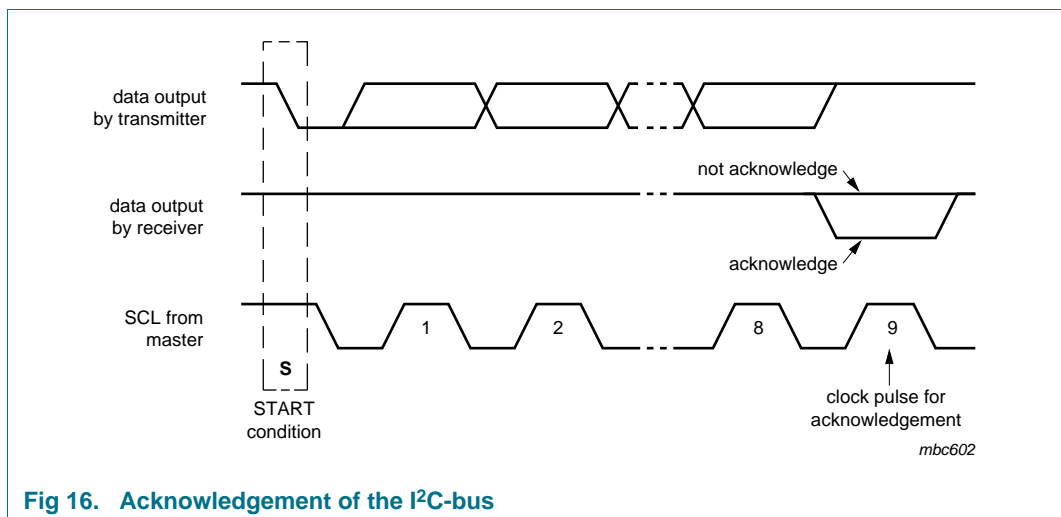


Fig 16. Acknowledgement of the I²C-bus

8.5 I²C-bus controller

The PCF8562 acts as an I²C-bus slave receiver. It does not initiate I²C-bus transfers or transmit data to an I²C-bus master receiver. The only data output from the PCF8562 are the acknowledge signals of the selected devices. Device selection depends on the I²C-bus slave address, on the transferred command data and on the hardware subaddress.

8.6 Input filters

To enhance noise immunity in electrically adverse environments, RC low-pass filters are provided on the SDA and SCL lines.

8.7 I²C-bus protocol

Two I²C-bus slave addresses (0111 000 and 0111 001) are reserved for the PCF8562. The least significant bit of the slave address that a PCF8562 will respond to is defined by the level tied to its SA0 input. The PCF8562 is a write-only device and will not respond to a read access.

The I²C-bus protocol is shown in [Figure 17](#). The sequence is initiated with a START condition (S) from the I²C-bus master which is followed by one of two possible PCF8562 slave addresses available. All PCF8562s whose SA0 inputs correspond to bit 0 of the slave address respond by asserting an acknowledge in parallel. This I²C-bus transfer is ignored by all PCF8562s whose SA0 inputs are set to the alternative level.

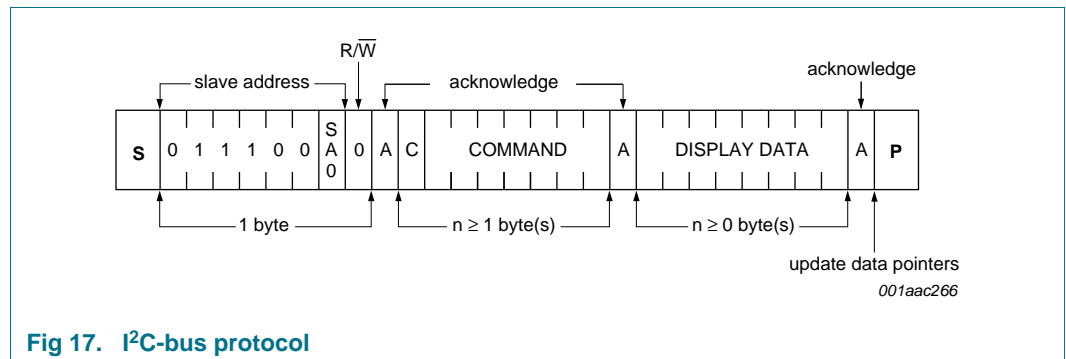


Fig 17. I²C-bus protocol

After an acknowledgement, one or more command bytes follow, that define the status of each addressed PCF8562.

The last command byte sent is identified by resetting its most significant bit, continuation bit C, (see [Figure 18](#)). The command bytes are also acknowledged by all addressed PCF8562s on the bus.

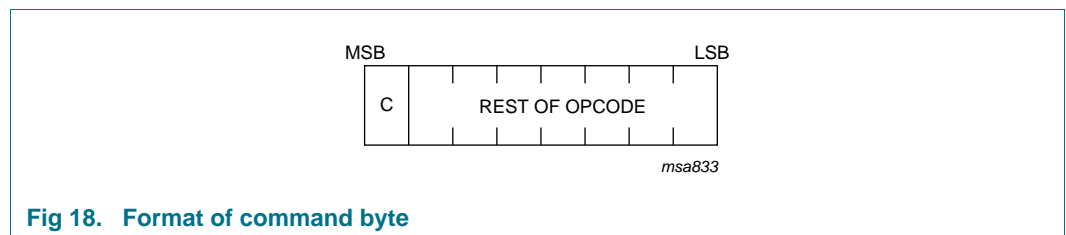


Fig 18. Format of command byte

After the last command byte, one or more display data bytes may follow. Display data bytes are stored in the display RAM at the address specified by the data pointer and the subaddress counter. Both data pointer and subaddress counter are automatically updated.

An acknowledgement, after each byte, is asserted only by the PCF8562s that are addressed via address lines A0, A1 and A2. After the last display byte, the I²C-bus master asserts a STOP condition (P). Alternately a START may be asserted to restart an I²C-bus access.

9. Internal circuitry

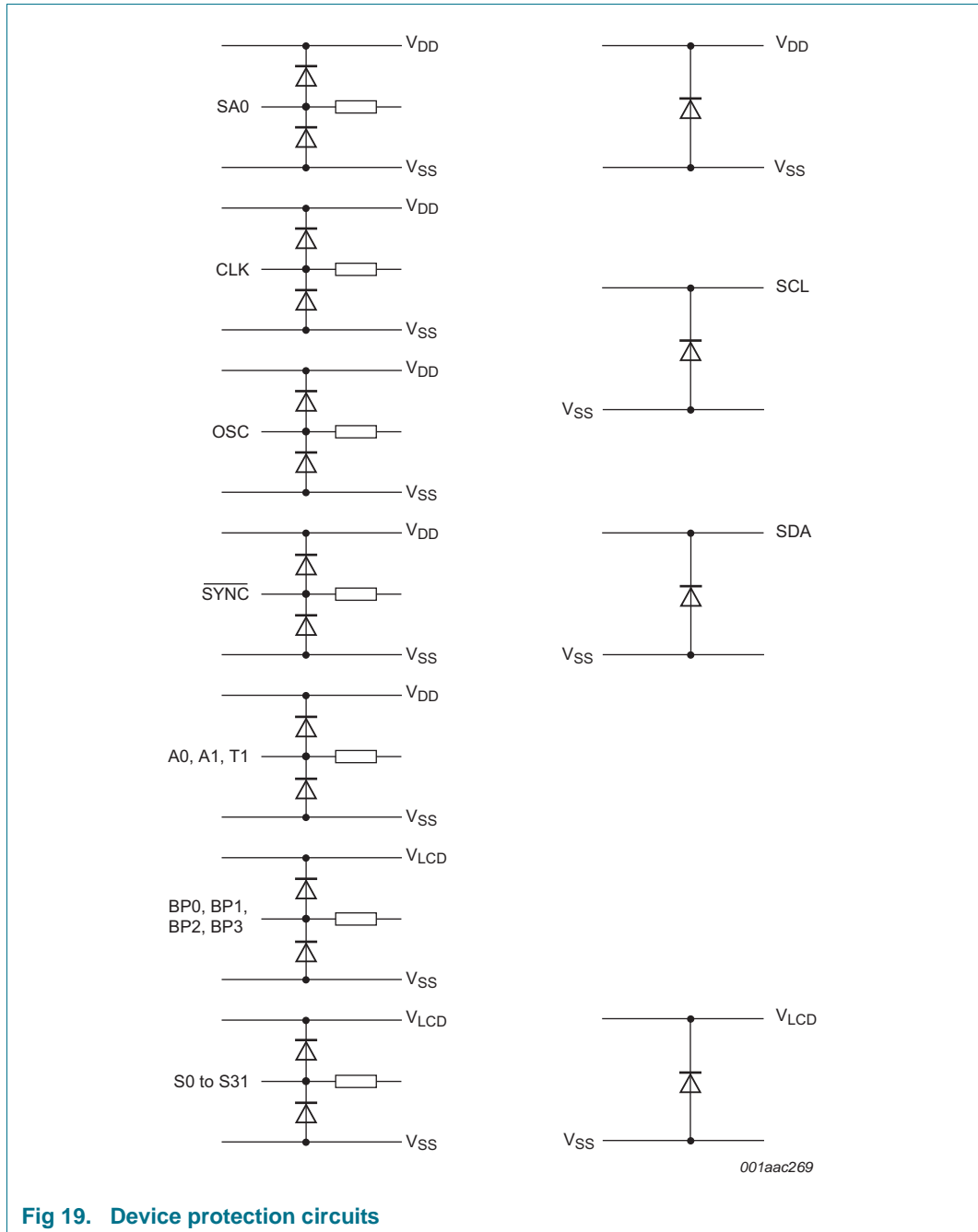


Fig 19. Device protection circuits

10. Limiting values

CAUTION



Static voltages across the liquid crystal display can build up when the LCD supply voltage (V_{LCD}) is on while the IC supply voltage (V_{DD}) is off, or vice versa. This may cause unwanted display artifacts. To avoid such artifacts, V_{LCD} and V_{DD} must be applied or removed together.

Table 16. Limiting values

In accordance with the Absolute Maximum Rating System (IEC 60134).

Symbol	Parameter	Conditions	Min	Max	Unit	
V_{DD}	supply voltage		-0.5	+6.5	V	
V_{LCD}	LCD supply voltage		-0.5	+7.5	V	
V_I	input voltage	on each of the pins CLK, SDA, SCL, SYNC, SA0, OSC, A0 to A2	-0.5	+6.5	V	
V_O	output voltage	on each of the pins S0 to S31, BP0 to BP3	-0.5	+7.5	V	
I_I	input current		-10	+10	mA	
I_O	output current		-10	+10	mA	
I_{DD}	supply current		-50	+50	mA	
$I_{DD(LCD)}$	LCD supply current		-50	+50	mA	
I_{SS}	ground supply current		-50	+50	mA	
P_{tot}	total power dissipation		-	400	mW	
P_o	output power		-	100	mW	
V_{esd}	electrostatic discharge voltage	HBM [1]	-	±5000	V	
		MM [2]	-	±200	V	
		CDM [3]	-	±1500	V	
I_{lu}	latch-up current		[4]	-	300	mA
T_{stg}	storage temperature		[5]	-65	+150	°C
T_{amb}	ambient temperature	operating device	-40	+85	°C	

[1] Pass level; Human Body Model (HBM), according to [Ref. 6 "JESD22-A114"](#).

[2] Pass level; Machine Model (MM), according to [Ref. 7 "JESD22-A115"](#).

[3] Pass level; Charged-Device Model (CDM), according to [Ref. 8 "JESD22-C101"](#).

[4] Pass level; latch-up testing according to [Ref. 9 "JESD78"](#) at maximum ambient temperature ($T_{amb(max)}$).

[5] According to the NXP store and transport requirements (see [Ref. 11 "NX3-00092"](#)) the devices have to be stored at a temperature of +8 °C to +45 °C and a humidity of 25 % to 75 %. For long term storage products deviant conditions are described in that document.

11. Static characteristics

Table 17. Static characteristics
 $V_{DD} = 1.8\text{ V to }5.5\text{ V}; V_{SS} = 0\text{ V}; V_{LCD} = 2.5\text{ V to }6.5\text{ V}; T_{amb} = -40\text{ }^{\circ}\text{C to }+85\text{ }^{\circ}\text{C};$ unless otherwise specified.

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
Supplies						
V_{DD}	supply voltage		1.8	-	5.5	V
V_{LCD}	LCD supply voltage		[1] 2.5	-	6.5	V
I_{DD}	supply current	$f_{clk(ext)} = 1536\text{ Hz}$	[2] -	3.5	7	μA
$I_{DD(LCD)}$	LCD supply current	$f_{clk(ext)} = 1536\text{ Hz}$	[2] -	23	32	μA
Logic[3]						
$V_{P(POR)}$	power-on reset supply voltage		1.0	1.3	1.6	V
V_{IL}	LOW-level input voltage	on pins CLK, $\overline{\text{SYNC}}$, OSC, A0 to A2, SA0, SCL, SDA	V_{SS}	-	$0.3V_{DD}$	V
V_{IH}	HIGH-level input voltage	on pins CLK, $\overline{\text{SYNC}}$, OSC, A0 to A2, SA0, SCL, SDA	[4][5] $0.7V_{DD}$	-	V_{DD}	V
I_{OL}	LOW-level output current	output sink current; $V_{OL} = 0.4\text{ V}; V_{DD} = 5\text{ V}$				
		on pins CLK and $\overline{\text{SYNC}}$	1	-	-	mA
		on pin SDA	3	-	-	mA
$I_{OH(CLK)}$	HIGH-level output current on pin CLK	output source current; $V_{OH} = 4.6\text{ V}; V_{DD} = 5\text{ V}$	1	-	-	mA
I_L	leakage current	$V_I = V_{DD}$ or V_{SS} ; on pins CLK, SCL, SDA, A0 to A2 and SA0	-1	-	+1	μA
$I_{L(OSC)}$	leakage current on pin OSC	$V_I = V_{DD}$	-1	-	+1	μA
C_I	input capacitance		[6] -	-	7	pF
LCD outputs						
ΔV_O	output voltage variation	on pins BP0 to BP3 and S0 to S31	-100	-	+100	mV
R_O	output resistance	$V_{LCD} = 5\text{ V}$	[7]			
		on pins BP0 to BP3	-	1.5	-	k Ω
		on pins S0 to S31	-	6.0	-	k Ω

[1] $V_{LCD} > 3\text{ V}$ for $\frac{1}{3}$ bias.

[2] LCD outputs are open-circuit; inputs at V_{SS} or V_{DD} ; external clock with 50 % duty factor; I²C-bus inactive.

[3] The I²C-bus interface of PCF8562 is 5 V tolerant.

[4] When tested, I²C pins SCL and SDA have no diode to V_{DD} and may be driven to the V_I limiting values given in Table 16 (see Figure 19 as well).

[5] Propagation delay of driver between clock (CLK) and LCD driving signals.

[6] Periodically sampled, not 100 % tested.

[7] Outputs measured one at a time.

12. Dynamic characteristics

Table 18. Dynamic characteristics
 $V_{DD} = 1.8\text{ V to }5.5\text{ V}; V_{SS} = 0\text{ V}; V_{LCD} = 2.5\text{ V to }6.5\text{ V}; T_{amb} = -40\text{ }^{\circ}\text{C to }+85\text{ }^{\circ}\text{C};$ unless otherwise specified.

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
Clock						
$f_{\text{clk(int)}}$	internal clock frequency		[1] 1440	1850	2640	Hz
$f_{\text{clk(ext)}}$	external clock frequency		960	-	2640	Hz
$t_{\text{clk(H)}}$	HIGH-level clock time		60	-	-	μs
$t_{\text{clk(L)}}$	LOW-level clock time		60	-	-	μs
Synchronization						
$t_{\text{PD(SYNC_N)}}$	$\overline{\text{SYNC}}$ propagation delay		-	30	-	ns
$t_{\text{SYNC_NL}}$	$\overline{\text{SYNC}}$ LOW time		1	-	-	μs
$t_{\text{PD(drv)}}$	driver propagation delay	$V_{\text{LCD}} = 5\text{ V}$	[2] -	-	30	μs
I²C-bus[3]						
Pin SCL						
f_{SCL}	SCL clock frequency		-	-	400	kHz
t_{LOW}	LOW period of the SCL clock		1.3	-	-	μs
t_{HIGH}	HIGH period of the SCL clock		0.6	-	-	μs
Pin SDA						
$t_{\text{SU;DAT}}$	data set-up time		100	-	-	ns
$t_{\text{HD;DAT}}$	data hold time		0	-	-	ns
Pins SCL and SDA						
t_{BUF}	bus free time between a STOP and START condition		1.3	-	-	μs
$t_{\text{SU;STO}}$	set-up time for STOP condition		0.6	-	-	μs
$t_{\text{HD;STA}}$	hold time (repeated) START condition		0.6	-	-	μs
$t_{\text{SU;STA}}$	set-up time for a repeated START condition		0.6	-	-	μs
t_{r}	rise time of both SDA and SCL signals	$f_{\text{SCL}} = 400\text{ kHz}$	-	-	0.3	μs
		$f_{\text{SCL}} < 125\text{ kHz}$	-	-	1.0	μs
t_{f}	fall time of both SDA and SCL signals		-	-	0.3	μs
C_{b}	capacitive load for each bus line		-	-	400	pF
$t_{\text{w(spikes)}}$	spike pulse width	on the I ² C-bus	-	-	50	ns

[1] Typical output duty factor: 50 % measured at the CLK output pin.

[2] Not tested in production.

[3] All timing values are valid within the operating supply voltage and ambient temperature range and are referenced to V_{IL} and V_{IH} with an input voltage swing of V_{SS} to V_{DD} .

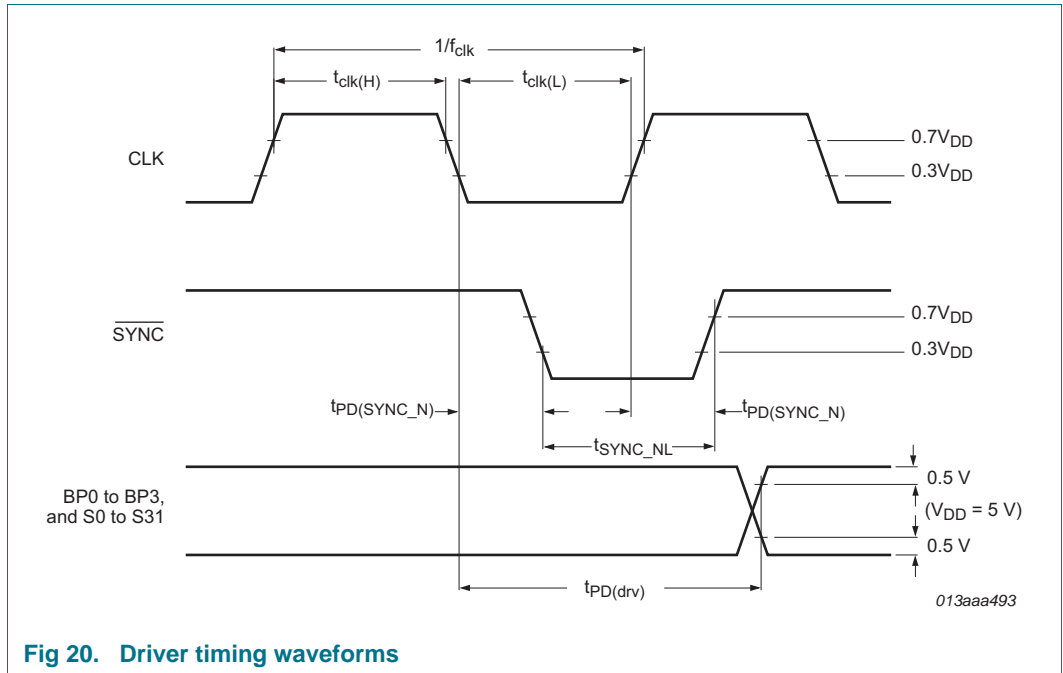


Fig 20. Driver timing waveforms

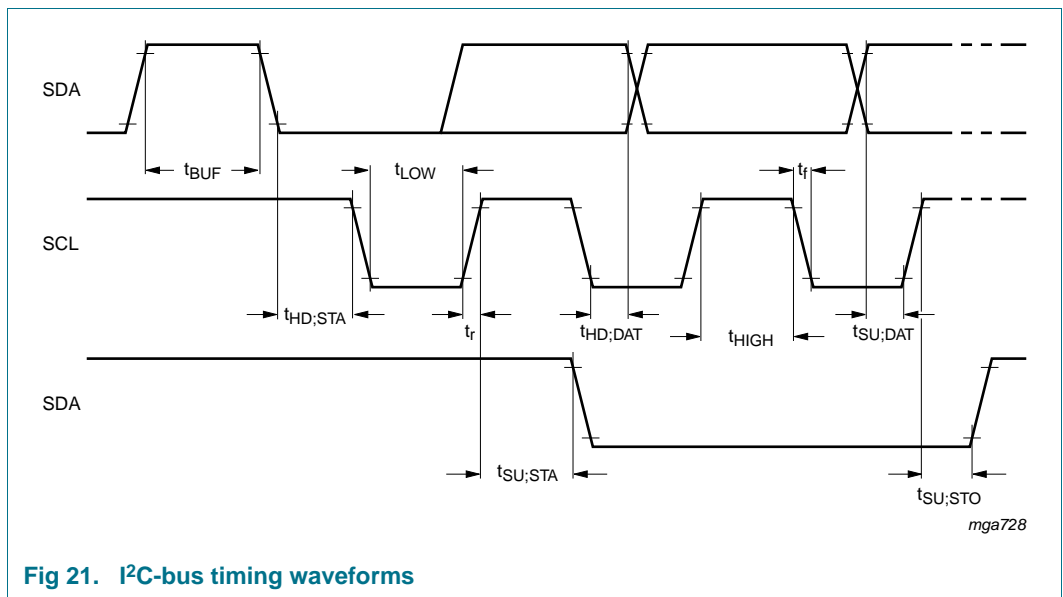


Fig 21. I²C-bus timing waveforms

13. Application information

13.1 Multiple chip operation

For large display configurations or for more segments (> 128 elements) to drive please refer to the PCF8576D device.

The contact resistance between the $\overline{\text{SYNC}}$ input/output on each cascaded device must be controlled. If the resistance is too high, the device will not be able to synchronize properly; this is particularly applicable to chip-on-glass applications. The maximum $\overline{\text{SYNC}}$ contact resistance allowed for the number of devices in cascade is given in [Table 19](#).

Table 19. $\overline{\text{SYNC}}$ contact resistance

Number of devices	Maximum contact resistance
2	6000 Ω
3 to 5	2200 Ω
6 to 10	1200 Ω
10 to 16	700 Ω

14. Test information

14.1 Quality information

This product has been qualified in accordance with the Automotive Electronics Council (AEC) standard *Q100 - Failure mechanism based stress test qualification for integrated circuits*, and is suitable for use in automotive applications.

15. Package outline

TSSOP48: plastic thin shrink small outline package; 48 leads; body width 6.1 mm

SOT362-1

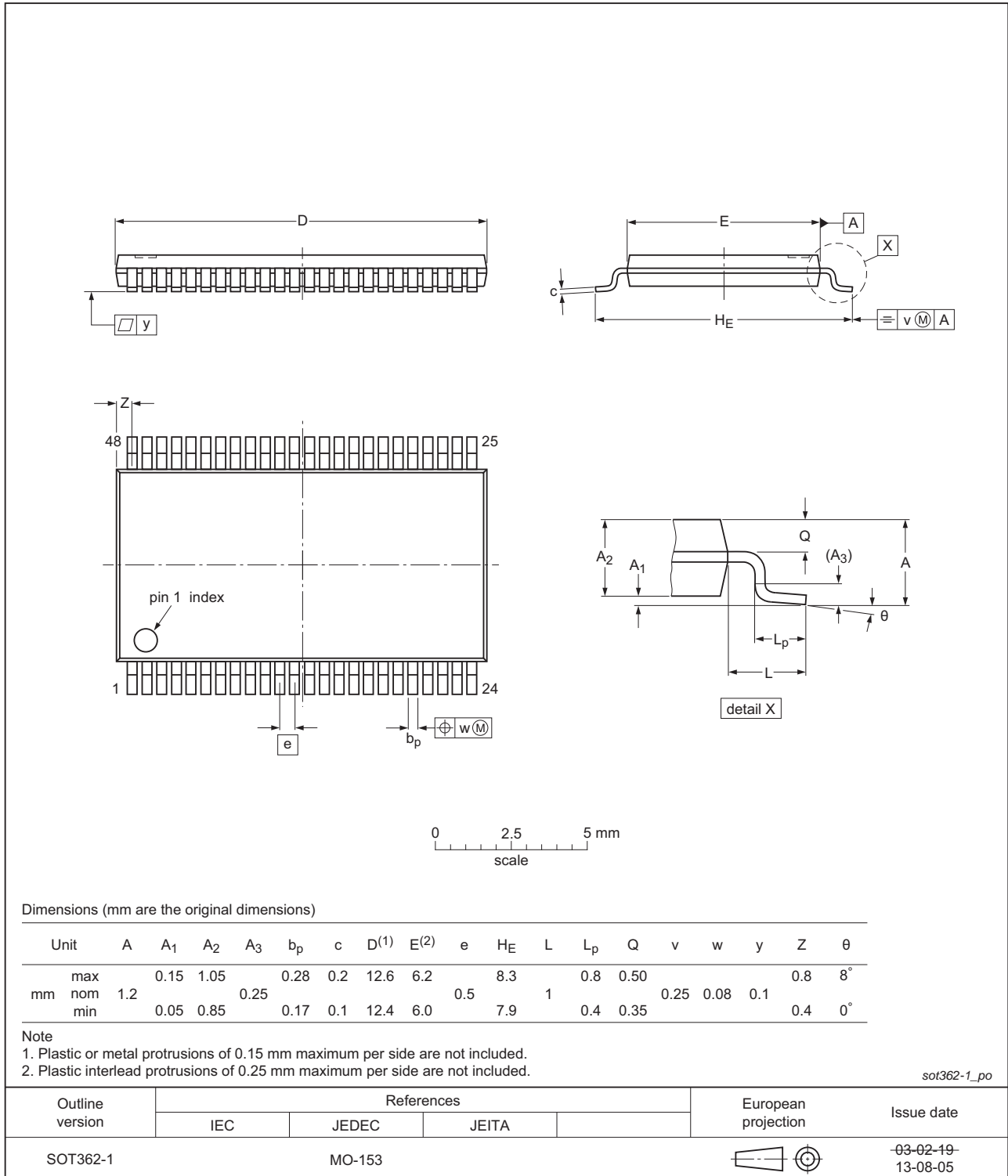


Fig 22. Package outline SOT362-1 (TSSOP48)

16. Handling information

All input and output pins are protected against ElectroStatic Discharge (ESD) under normal handling. When handling Metal-Oxide Semiconductor (MOS) devices ensure that all normal precautions are taken as described in *JESD625-A*, *IEC 61340-5* or equivalent standards.

17. Soldering of SMD packages

This text provides a very brief insight into a complex technology. A more in-depth account of soldering ICs can be found in Application Note *AN10365 "Surface mount reflow soldering description"*.

17.1 Introduction to soldering

Soldering is one of the most common methods through which packages are attached to Printed Circuit Boards (PCBs), to form electrical circuits. The soldered joint provides both the mechanical and the electrical connection. There is no single soldering method that is ideal for all IC packages. Wave soldering is often preferred when through-hole and Surface Mount Devices (SMDs) are mixed on one printed wiring board; however, it is not suitable for fine pitch SMDs. Reflow soldering is ideal for the small pitches and high densities that come with increased miniaturization.

17.2 Wave and reflow soldering

Wave soldering is a joining technology in which the joints are made by solder coming from a standing wave of liquid solder. The wave soldering process is suitable for the following:

- Through-hole components
- Leaded or leadless SMDs, which are glued to the surface of the printed circuit board

Not all SMDs can be wave soldered. Packages with solder balls, and some leadless packages which have solder lands underneath the body, cannot be wave soldered. Also, leaded SMDs with leads having a pitch smaller than ~0.6 mm cannot be wave soldered, due to an increased probability of bridging.

The reflow soldering process involves applying solder paste to a board, followed by component placement and exposure to a temperature profile. Leaded packages, packages with solder balls, and leadless packages are all reflow solderable.

Key characteristics in both wave and reflow soldering are:

- Board specifications, including the board finish, solder masks and vias
- Package footprints, including solder thieves and orientation
- The moisture sensitivity level of the packages
- Package placement
- Inspection and repair
- Lead-free soldering versus SnPb soldering

17.3 Wave soldering

Key characteristics in wave soldering are:

- Process issues, such as application of adhesive and flux, clinching of leads, board transport, the solder wave parameters, and the time during which components are exposed to the wave
- Solder bath specifications, including temperature and impurities

17.4 Reflow soldering

Key characteristics in reflow soldering are:

- Lead-free versus SnPb soldering; note that a lead-free reflow process usually leads to higher minimum peak temperatures (see [Figure 23](#)) than a SnPb process, thus reducing the process window
- Solder paste printing issues including smearing, release, and adjusting the process window for a mix of large and small components on one board
- Reflow temperature profile; this profile includes preheat, reflow (in which the board is heated to the peak temperature) and cooling down. It is imperative that the peak temperature is high enough for the solder to make reliable solder joints (a solder paste characteristic). In addition, the peak temperature must be low enough that the packages and/or boards are not damaged. The peak temperature of the package depends on package thickness and volume and is classified in accordance with [Table 20](#) and [21](#)

Table 20. SnPb eutectic process (from J-STD-020D)

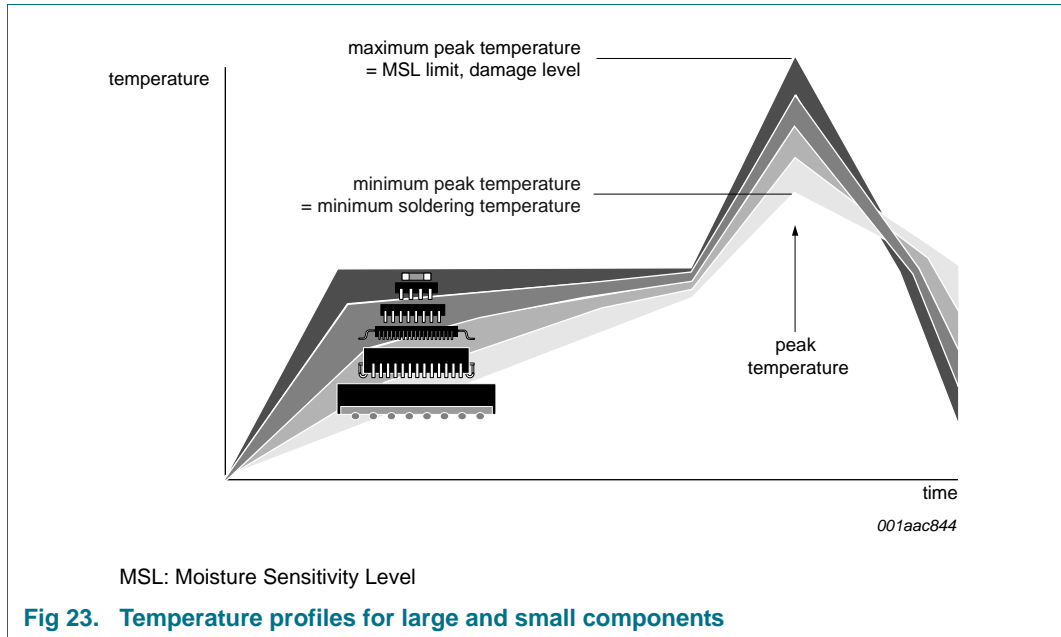
Package thickness (mm)	Package reflow temperature (°C)	
	Volume (mm ³)	
	< 350	≥ 350
< 2.5	235	220
≥ 2.5	220	220

Table 21. Lead-free process (from J-STD-020D)

Package thickness (mm)	Package reflow temperature (°C)		
	Volume (mm ³)		
	< 350	350 to 2000	> 2000
< 1.6	260	260	260
1.6 to 2.5	260	250	245
> 2.5	250	245	245

Moisture sensitivity precautions, as indicated on the packing, must be respected at all times.

Studies have shown that small packages reach higher temperatures during reflow soldering, see [Figure 23](#).



For further information on temperature profiles, refer to Application Note AN10365 “Surface mount reflow soldering description”.

18. Abbreviations

Table 22. Abbreviations

Acronym	Description
CMOS	Complementary Metal Oxide Semiconductor
CDM	Charged-Device Model
HBM	Human Body Model
ITO	Indium Tin Oxide
LCD	Liquid Crystal Display
LSB	Least Significant Bit
MM	Machine Model
MSB	Most Significant Bit
MSL	Moisture Sensitivity Level
PCB	Printed Circuit Board
RAM	Random Access Memory
RMS	Root Mean Square
SCL	Serial Clock Line
SDA	Serial Data line
SMD	Surface Mount Device

19. References

- [1] **AN10365** — Surface mount reflow soldering description
- [2] **AN10853** — ESD and EMC sensitivity of IC
- [3] **IEC 60134** — Rating systems for electronic tubes and valves and analogous semiconductor devices
- [4] **IEC 61340-5** — Protection of electronic devices from electrostatic phenomena
- [5] **IPC/JEDEC J-STD-020D** — Moisture/Reflow Sensitivity Classification for Nonhermetic Solid State Surface Mount Devices
- [6] **JESD22-A114** — Electrostatic Discharge (ESD) Sensitivity Testing Human Body Model (HBM)
- [7] **JESD22-A115** — Electrostatic Discharge (ESD) Sensitivity Testing Machine Model (MM)
- [8] **JESD22-C101** — Field-Induced Charged-Device Model Test Method for Electrostatic-Discharge-Withstand Thresholds of Microelectronic Components
- [9] **JESD78** — IC Latch-Up Test
- [10] **JESD625-A** — Requirements for Handling Electrostatic-Discharge-Sensitive (ESDS) Devices
- [11] **NX3-00092** — NXP store and transport requirements
- [12] **SNV-FA-01-02** — Marking Formats Integrated Circuits
- [13] **UM10204** — I²C-bus specification and user manual

20. Revision history

Table 23. Revision history

Document ID	Release date	Data sheet status	Change notice	Supersedes
PCF8562 v.7	20150721	Product data sheet	-	PCF8562 v.6
Modifications:	<ul style="list-style-type: none"> • Table 17: Replaced values (LCD) supply 			
PCF8562 v.6	20110616	Product data sheet	-	PCF8562 v.5
Modifications:	<ul style="list-style-type: none"> • Added design-in and replacement part information • Added Section 7.10.3 			
PCF8562 v.5	20100519	Product data sheet	-	PCF8562 v.4
PCF8562 v.4	20090318	Product data sheet	-	PCF8562 v.3
PCF8562 v.3	20081202	Product data sheet	-	PCF8562 v.2
PCF8562 v.2	20070122	Product data sheet	-	PCF8562 v.1
PCF8562 v.1	20050801	Product data sheet	-	-

21. Legal information

21.1 Data sheet status

Document status ^{[1][2]}	Product status ^[3]	Definition
Objective [short] data sheet	Development	This document contains data from the objective specification for product development.
Preliminary [short] data sheet	Qualification	This document contains data from the preliminary specification.
Product [short] data sheet	Production	This document contains the product specification.

[1] Please consult the most recently issued document before initiating or completing a design.

[2] The term 'short data sheet' is explained in section "Definitions".

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