

DESCRIPTION

The MP6960 is a synchronous rectified controller for a high-efficiency flyback converter circuit. The controller has integrated voltage and current regulators for the secondary side of the converter, making it suitable for battery charging and as a secondary controller for switching regulator systems.

The MP6960 regulates the forward drop of an external switch to about 70mV and switches it off as soon as the voltage goes negative. It also has a light-load sleep mode to reduce the quiescent current to $<300\mu$ A.

The MP6960 also compares the DC voltage and the current level at the output of a switching power supply to the voltage reference and current limitation, respectively. It provides feedback through an opto-coupler to the PWM controller IC at the primary side.

The MP6960 is available in an SOIC8 package.

FEATURES

- Works with 12V Standard and 5V Logic-Level FETS
- Compatible with Energy Star 1W Standby Requirements
- V_{DD} to V_{SS} Range from 8V to 24V
- V_D to GND Range from 4.5V to 36V
- Fast Turn-Off Total Delay of 20ns
- Max. 400kHz Switching Frequency
- <400µA Quiescent Current in Light-Load Mode
- Supports CCM, DCM and Quasi-Resonant Topologies
- Supports High-Side and Low-Side Rectification
- Power Savings of up to 1.5W in a Typical Notebook Adapter
- 2.5V Built-In Voltage Reference with ±0.5% Accuracy
- 25mV Built-In Current Reference with ±5% Accuracy
- Constant Voltage and Constant Current Control
- Two Operational Amplifier with ORED Output and 1MHz Bandwidth
- 8-Pin SOIC8 Package

APPLICATIONS

- Industrial Power Systems
- Distributed Power Systems
- Battery Powered Systems
- Flyback Converters

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TYPICAL APPLICATION





Part Number	Package	Top Marking
MP6960GS*	SOIC8	MP6960
MP6960CGS**	SOIC8	MP6960

ORDERING INFORMATION

* For Tape & Reel, add suffix –Z (e.g. MP6960GS–Z);

** For Tape & Reel, add suffix -Z (e.g. MP6960CGS-Z);



PACKAGE REFERENCE

ABSOLUTE MAXIMUM RATINGS (1)

V_{DD} to V_{SS} -0.3V to +27V
GND to V_{SS} 0.3V to +180V
V_{G} to V_{SS} 0.3V to +27V
V_{D} to V_{SS} 0.7V to +180V
V_{D} to GND0.7V to +40V
CTL to GND0.3V to +40V
VFB, IFB to GND0.3V to +6.5V
Maximum Operating Frequency 400 kHz
Continuous Power Dissipation $(T_A=+25^{\circ}C)^{(2)}$
Junction Temperature125°C
Lead Temperature (Solder)260°C
Storage Temperature55°C to +150°C
(0)

Thermal Resistance ⁽⁴⁾ θ_{JA} θ_{JC}

Notes:

- 1) Exceeding these ratings may damage the device.
- 2) The maximum allowable power dissipation is a function of the maximum junction temperature T_J (MAX), the junction-toambient thermal resistance θ_{JA} , and the ambient temperature T_A. The maximum allowable continuous power dissipation at any ambient temperature is calculated by P_D (MAX) = (T_J (MAX)-T_A)/ θ_{JA} . Exceeding the maximum allowable power dissipation will cause excessive die temperature, and the regulator will go into thermal shutdown. Internal thermal shutdown circuitry protects the device from permanent damage.
- The device is not guaranteed to function outside of its operating conditions.
- 4) Measured on JESD51-7, 4-layer PCB.

ELECTRICAL CHARACTERISTICS (5)

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 V_{DD} = 12V, T_A = +25°C, unless otherwise noted.

Parameter		Conditions	Min	Тур	Max	Units
SYNCHRONOUS RECTIFIER CONTROLLER						
V _{DD} Voltage Range		V _{DD} - V _{SS}	8		24	V
V _{DD} UVLO Rising			4.5	5.6	7	V
V _{DD} UVLO Hysteresis			0.8	1	1.2	V
Operating Current	I _{CC}	C _{LOAD} =5nF, f _{SW} =100kHz		8	10	mA
Quiescent Current	l _q	$V_{SS}-V_{D}=0.5V$		2	3	mA
Shutdown Current of Synchronous Rectifier Controller	I _{shut_SR}	V _{DD} =4V,V _D =GND		170	220	μA
Light-Load Mode Current				260	360	μA
Thermal Shutdown				150		°C
Thermal Shutdown Hysteresis				30		°C
Turn-On Threshold (V _{SS} -V _D)	V _{fwd}		55	70	85	mV
Turn-on Delay	t _{Don}	$C_{LOAD} = 5nF$		150		ns
Turn-on Delay	t _{Don}	C _{LOAD} = 10nF		250		ns
Input Bias Current on V _D Pin		V _D = 180V			1	μA
Minimum On-Time ⁽⁵⁾	t _{MIN}	$C_{LOAD} = 5nF$		1.6		μs
Light-Load–Enter Delay	t _{LL-Delay}	$(R_{LL}=100k\Omega,integrated)$		100		μs
Light-Load–Enter Pulse Width	t _{LL}		1.3	2	2.6	μs
Light-Load–Enter Pulse Width Hysteresis	t _{LL-H}			0.2		μs
Light-Load Mode Exit Pulse Width Threshold (V _{DS})	V_{LL-DS}		-400	-250	-150	mV
Light-Load Mode Enter Pulse Width Threshold $(V_{GS})^{(5)}$	V_{LL-GS}			1.0		V
GATE DRIVER SECTION						
V _G (Low)		I _{LOAD} =1mA		0.05	0.1	V
V _G (High)		V _{DD} >17V	13	14	15	V
v _G (High)		V _{DD} <17V	V _{DD} -2.2			
Turn-off Threshold (V _{SS} -V _D)			20	30	40	mV
Turn-off Propagation Delay		$V_{D}=V_{SS}$ $V_{D} = V_{SS}, \qquad C_{LOAD}=5nF,$		15		ns
Turn-Off Total Delay	Total Delay			35		ns
Turn-On Total Delay	t _{Doff}	$V_D = V_{SS}$, C_{LOAD} =10nF, R_{GATE} =0 Ω		45		ns
Pull-Down Impedance				1	2	Ω
Pull-Down Current ⁽⁵⁾		3V <v<sub>G<10V</v<sub>		2		A
CC/CV CONTROLLER						
Supply Current of CC/CV Controller	Ι _D	V _D -GND = 15V, no load		90		μA
OPERATIONAL AMPLIFIER of						
Input Bias Current ⁽⁵⁾	I _B	$T_A = 25^{\circ}C$	-50	-10	0	nA
Output Sink Current	I _{CTL_SINK}	$T_A = 25^{\circ}C, V_{CTL} = 0.5V$ -20°C = $T_A = +85^{\circ}C$	8	15		mA
Large Signal Voltage Gain ⁽⁵⁾	A _{VO}	$R_L = 2k\Omega$	-	15		V/mV

ELECTRICAL CHARACTERISTICS ⁽⁵⁾ (continued)

 $V_{DD} = 12V$, $T_A = +25$ °C, unless otherwise noted.

Parameter	Symbol	Conditions	Min	Тур	Max	Units
Supply Voltage Rejection Ratio	SVR	Supply Voltage change of 1.0V	65	90		dB
Common Mode Rejection Ratio ⁽⁵⁾	CMRR			80		dB
Gain Bandwidth Product ⁽⁵⁾	GBW	$\label{eq:VD-GND=15V} \begin{array}{ll} V_{D}\text{-}GND=15V, & V_{FB}(I_{FB})\text{-}\\ V_{REF}(I_{REF})\text{=} & 10mV, \ R_{L} \ \text{=}2k\Omega, \\ C_{L} \ \text{=}100pF \end{array}$		1		MHz
Output Leakage Current	I _{CTL_LEAKAGE}	T _A = 25°C			2	μA
VOLTAGE REFERENCE (MP6960						
Reference Voltage	V	I _{OUT} = 1mA, T _A = 25°C	2.475	2.5	2.525	V
Relefence voltage	V _{REF}	0°C . T _A . 85°C ⁽⁵⁾	2.47	2.5	2.53	V
VOLTAGE REFERENCE (MP6960)C)					
Reference Voltage	V _{REF}	I _{OUT} = 1mA, T _A = 25°C	2.488	2.5	2.512	V
Reference voltage		0°C . T _A . 85°C ⁽⁵⁾	2.48	2.5	2.52	V
CURRENT REFERENCE		•				
Reference Current	V	I _{OUT} =1mA, T _A =25°C	24	25	26	mV
	V _{IREF}	T _A =0°C to 85°C ⁽⁵⁾	23.75	25	26.25	mV

Notes:

5) Guaranteed by Design and Characterization.



40ms/div.

V_{CTL} 1V/div.

I_{OUT} 500mA/div.

10ms/div.

V_{CTL} 1V/div.

I_{OUT} 2A/div.

PIN FUNCTIONS

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Pin #	Name	Description
1	VG	Gate Drive Output
2	VSS	Reference for VD. Connect to MOSFET source pin.
3	CTL	Output Common. Reference for voltage regulation and current limitation loops. Drives the primary side of an opto-coupler.
4	GND	CC/CV controller ground.
5	VFB	Voltage Feedback. An external resistor divider from the output to GND tapped to the FB pin sets the output voltage.
6	IFB	Current Feedback. Connected to the sense resistor.
7	VD	MOSFET Drain Voltage Sense. Also the supply voltage of the CC/CV controller
8	VDD	Supply Voltage of the Synchronous Rectifier Controller

BLOCK DIAGRAM



Figure 1: Functional Block Diagram

OPERATION

The MP6960 is a synchronous rectified controller for use in constant-current mode (CCM), discontinuous-current mode (DCM), and quasiresonant topologies. MP6960 integrates a highprecision bandgap voltage reference, and two opamps to regulate and control the output voltage and current of the power supply.

Blanking

The control circuitry contains a blanking function that ensures that when the MOSFET turns on or off, it remains in that state for a minimal time period. The turn on blanking time is ~1.6 μ s, which determines the minimum on-time. During the turn-on blanking period, the turn-off threshold changes to approximately +50mV (instead of -30mV) to ensure that the part can always turn off even during the turn on blanking period (albeit slower, so do not set the synchronous period to less than 1.6 μ s in CCM for a flyback converter, or risk shoot through).

Under-Voltage Lockout (UVLO)

When the VDD drops below the UVLO threshold, the part enters sleep mode and the VG pin is pulled low by a $10k\Omega$ resistor.

Turn-On Phase

When the synchronous MOSFET is ON, the current flowing through its body diode generates a negative V_{DS} . Because this body diode voltage drop (<-500mV) is much smaller than the turn-on threshold of the control circuitry (-70mV), then MP6960 will then pull the gate driver voltage high to turn on the synchronous MOSFET after a 150ns turn-on delay (Defined in Figure 2).



Figure 2: Turn-On and Turn-Off Delay

Conducting Phase

When the synchronous MOSFET turns ON, V_{DS} rises according to its ON resistance. As soon as V_{DS} rises above the turn-on threshold (-70mV), the control circuitry stops pulling up the gate driver, so the internal pull-down resistor (10k Ω) pulls down the gate voltage to increase the ON resistance of the synchronous MOSFET to slow the V_{DS} rise. This adjusts V_{DS} to around -70mV even when the current through the MOSFET is fairly small, and drop the driver voltage to fairly low levels when the synchronous MOSFET turns off to speed up turn-off (this driver-self-regulating function is still active during the turn-on blanking time so that the gate driver can turn off even with a very small duty).

Turn-Off Phase

When V_{DS} rises to trigger the turn-off threshold (-30mV), the control circuitry causes the gate voltage to go low after a 20ns turn-off delay (as shown in Figure 2) by the control circuitry. A 200ns blanking time—similar to the turn-on phase—after the synchronous MOSFET turns off avoids erroneous triggering.

Figure 3 shows synchronous rectification at heavy loads. The gate driver initially saturates due to the high current. After V_{DS} rises above -70mV, gate driver voltage decreases to adjust V_{DS} to -70mV.

Figure 4 shows synchronous rectification under light loads. Due to the low current, the gate driver voltage never saturates but decreases as soon as the synchronous MOSFET turns on and adjusts V_{DS} .



Figure 3: Synchronous Rectification Operation at Heavy-Load



Figure 4: Synchronous Rectification Operation at Light-Load

Light-Load Latch-Off Function

The gate driver of the MP6960 latches to limit driver loss at light loads to improve efficiency. An internal resistor sets the light-load–enter pulse width, t_{LL} . When the synchronous MOSFET conducting period is less than t_{LL} for a longer than the light-load–enter delay ($t_{LL-Delay}$), the MP6960 enters light-load mode and latches off the gate driver. The synchronous MOSFET conducting period now starts when the gate driver turns on to when V_{GS} drops to the light-load–enter pulse width threshold (V_{LL-GS}).

During light-load mode, the MP6960 monitors the synchronous MOSFET body diode conducting

period by sensing V_{DS}. When V_{DS} exceeds the light-load–exit pulse width threshold—V_{LL-DS}—the synchronous MOSFET body diode conducting period has ended. If the conducting period is longer than $t_{LL}+t_{LL-H}$ (t_{LL-H} , light-load-enter pulse width hysteresis), the light-load mode has ended and the gate driver is unlatched to restart the synchronous rectification.

SR MOSFET Selection and Driver Ability

Selecting a power MOSFET requires trading off between R_{ON} and Q_G . For higher efficiency, chose a MOSFET with a smaller R_{ON} , though is typically Q_G is usually larger and slows turn-on/off speed and increases power loss. Because V_{DS} is regulated at -70mV during the driving period, avoid MOSFET with very small R_{ON} because a low gate driver level when the MOSFET current is still fairly high counters any efficiency gains from using a MOSFET with a low R_{ON} .

Figure 5 shows the typical waveform of QR flyback. Assume a 50% duty cycle and the output current is I_{OUT} .

To make use of the MOSFET's low $R_{\text{ON}},$ the MOSFET be fully on for at least 50% of the SR conduction period:

$$\mathsf{V}_{\mathsf{ds}} = -\mathsf{I}_{\mathsf{c}} imes \mathsf{R}_{\mathsf{on}} = -2 \cdot \mathsf{I}_{\mathsf{OUT}} imes \mathsf{R}_{\mathsf{on}} \leq -\mathsf{V}_{\mathsf{fwd}}$$

Where V_{DS} is the MOSFET drain-source voltage and V_{fwd} is the forward voltage threshold of the MP6960, which is ~70mV.

Based on these requirements, select a MOSFET with an R_{ON} no less than $35/I_{OUT}$ (m Ω). For example, for a 5A application, select R_{ON} no less than $7m\Omega$. Figure 6 shows the corresponding total delay during the turn-on period with different Q_G values. Driving a 120nC Q_G MOSFET, the MP6960 can pull up the MOSFET gate driver voltage to 5V in 300ns as soon as the body diode can conduct, which reduces turn-on power loss.



Figure 5: Synchronous Rectification of Typical Waveforms in QR Flyback



Figure 6: Total Turn-on Delay vs. QG

Voltage Regulation Loop

The voltage regulation is done by comparing the feedback output voltage (resistor divider R1 and R2) to the voltage reference (2.5V). If the feedback voltage exceeds 2.5V, the output of the voltage loop operational amplifier decreases. The opto-coupler current increases and reduces the output voltage by the way of the PWM controller.

Current-Limit Loop

Current limitation uses the voltage drop across the sense resistor, R_{SEN} , to measure the output current and compare it against the 25mV current reference. When the voltage across R_{SEN} exceeds 25mV, the output of the current loop operational amplifier decreases. The optocoupler current increases and reduces the output voltage by the way of the PWM controller.

APPLICATION INFORMATION COMPONENT SELECTION

Setting the Output Voltage

Select the resistive voltage divider ratio to set the output voltage. The voltage divider drops the output voltage to 2.5V—the internal voltage reference. For most applications, use a $10k\Omega$ low-side resistor for the voltage divider. Determine the high-side resistor using the equation:

$$R1 = R2 \times (\frac{V_{OUT}}{2.5V} - 1)$$

Where R1 is the high-side resistor, R2 is the low-side resistor and V_{OUT} is the output voltage.

Setting the Output Current

 $R_{\mbox{\scriptsize SEN}}$ is the sense resistor used for current measurement.

The current regulation is most effective when the voltage drop across R_{SEN} equals the voltage of the current reference, 25mV.

 R_{SEN} can be realized with standard low cost 0.5W resistors in parallel.

$$I_{OUT} = \frac{V_{REF}}{R_{SEN}}$$

Where I_{OUT} is the output current, and $V_{\text{REF}}\text{=}25mV.$

In case the voltage drop across R_{SEN} always exceeds the voltage of the current reference (25mV),CTL will send a signal to the PWM controller to shutdown the PWM driver so that V_{IFB} remains around V_{IREF} . Figure 7 shows typical application in this case.



Figure 7: Typical IFB Application $I_{\text{OUT}} = \frac{V_{\text{REF}}}{R_{\text{SEN}}} \times \frac{Rs1 + Rs2}{Rs2}$

Where RS1 is the high-side resistor, RS2 is the low-side resistor and I_{OUT} is the output current, $V_{\text{REF}}\text{=}25\text{mV}.$



PACKAGE INFORMATION



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Телефон: 8 (812) 309-75-97 (многоканальный) Факс: 8 (812) 320-03-32 Электронная почта: ocean@oceanchips.ru Web: http://oceanchips.ru/ Адрес: 198099, г. Санкт-Петербург, ул. Калинина, д. 2, корп. 4, лит. А