# E6H-C

CSM E6H-C DS E 3

# Hollow Shafts Eliminate the Need for a Coupling. Compact, High-resolution, General-purpose Rotary Encoder.

- Power supply voltage from 5 to 24 VDC (for Models with Open-collector Output).
- Resolution of up to 3,600 ppr in Encoders with an external diameter of only 40 mm.
- Only 26 mm thick.
- Line driver output also available (maximum cable length extension of 100 m).



Be sure to read *Safety Precautions* on page 4.



# **Ordering Information**

# Encoders [Refer to Dimensions on page 4.]

Power supply voltage	Output configuration	Resolution (pulses/rotation)	Model
5 to 24 VDC	Open-collector output	300, 360, 500, 600, 720, 800, 1,000, 1,024	E6H-CWZ6C (resolution) 0.5M Example: E6H-CWZ6C 300P/R 0.5M
		1,200, 1,500, 1,800, 2,000, 2,048	
		2,500, 3,600	
5 to 12 VDC	Voltage output	300, 360, 500, 600, 720, 800, 1,000, 1,024	E6H-CWZ3E (resolution) 0.5M Example: E6H-CWZ3E 300P/R 0.5M
		1,200, 1,500, 1,800, 2,000, 2,048	
		2,500, 3,600	
5 to 12 VDC	Line-driver output	300, 360, 500, 600, 720, 800, 1,000, 1,024	E6H-CWZ3X (resolution) 0.5M Example: E6H-CWZ3X 300P/R 0.5M
		1,200, 1,500, 1,800, 2,000, 2,048	
		2,500, 3,600	

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# **Ratings and Specifications**

Power supply voltage5 VDC –5% to 24 VDC +15%, ripple (p-p): 5% max.5 VDC –5% to 12 VDC +10%, ripple (p-p): 5% max.Current consumption*1100 mA max.150 mA max.Resolution pulses/rotation)300, 360, 500, 600, 720, 800, 1,000, 1,024, 1,200, 1,500, 1,800, 2,000, 2,048, 2,500, 3,600Output phasesPhases A, B, and ZPhases A, A, B, B, Z, and ZOutput configurationVoltage outputLine-driver output*4Output capacityApplied voltage: 35 VDC max. Sink current: 35 mA max. Residual voltage: 0.7 V max. (at sink output of 25 mA)Output resistance: 1 kΩ Sink current: 30 mA max. Residual voltage: 0.7 V max. (at sink output voltage: Vo = 2.5 V m	)=
100 mA max.   150 mA max.	) =
Pulses/rotation)       300, 360, 500, 600, 720, 800, 1,000, 1,024, 1,200, 1,500, 1,800, 2,000, 2,048, 2,500, 3,600         Pulses A, B, and Z       Phases A, B, B, Z, and Z         Dutput configuration       Open-collector output       Voltage output       Line-driver output*4         Applied voltage: 35 VDC max. Sink current: 35 mA max. Posidual voltage: 0.7 V max (et sink)       Sink current: 30 mA max. Posidual voltage: 0.7 V max (et sink)       Output resistance: 1 kΩ Sink current: 30 mA max. Posidual voltage: 0.7 V max (et sink)	) =
Output configuration         Open-collector output         Voltage output         Line-driver output*4           Applied voltage: 35 VDC max. Sink current: 35 mA max.         Output resistance: 1 kΩ         Output current: High level: Is sink current: 30 mA max.           Posidual voltage: 0.7 V max (et sink)         Posidual voltage: 0.7 V max (et sink)         Output resistance: 1 kΩ	) =
Applied voltage: 35 VDC max. Sink current: 35 mA max.  Sink current: 35 mA max.  Posidual voltage: 0.7 V max. (et sink.)  Sink current: 30 mA max.  Desidual voltage: 0.7 V max. (et sink.)	) =
Applied voltage: 35 VDC max.  Output resistance: 1 k2/2  Sink current: 35 mA max.  Sink current: 30 mA max.  Sink current: 30 mA max.  Posidual voltage: 0.7 V max (et sink)  Low level: Is	o =
current of 35 mA) current of 30 mA) Output voltage: vo = 2.5 v m	
Maximum response requency*2	
Phase difference petween outputs 90°±45° between A and B (1/4 T ± 1/8 T)	
Rise and fall times of output $1 \mu s$ max. (Control output voltage: 5 V, Load resistance: $1 k\Omega$ , Output cable: $1 \mu s$ max. (	10 mA,
Starting torque 1.5 mN·m max.	
Moment of inertia 2×10 <sup>-6</sup> kg·m² max.	
Shaft Radial 29.4 N	
oading Thrust 4.9 N	
Maximum permissible speed  10,000 r/min	
Ambient temperature Operating: -10 to 70°C (at 90% humidity max.), Storage: -30 to 85°C (with no icing)	
Ambient humidity operating/Storage: 90% max. (with no condensation)	
nsulation resistance Excluded because of capacitor ground.	
Dielectric strength Excluded because of capacitor ground.	
<b>/ibration resistance</b> Destruction: 10 to 500 Hz, 100 m/s² or 1.5-mm double amplitude for 2 hours each in X, Y, and Z directions	
Shock resistance 300 m/s² for 11 ms 3 times each in X, Y, and Z directions (excluding shock to the shaft)	
Degree of orotection*3 IEC 60529 IP50	
Connection method Pre-wired Models (Standard cable length: 0.5 m)	
Material Case: Iron, Main unit: Aluminum, Pressboard panel: SUS304	
Weight (packed state) Approx. 120 g	
Accessories Instruction manual	

<sup>\*1.</sup> An inrush current of approximately 6 A will flow for approximately 0.3 ms when the power is turned ON.

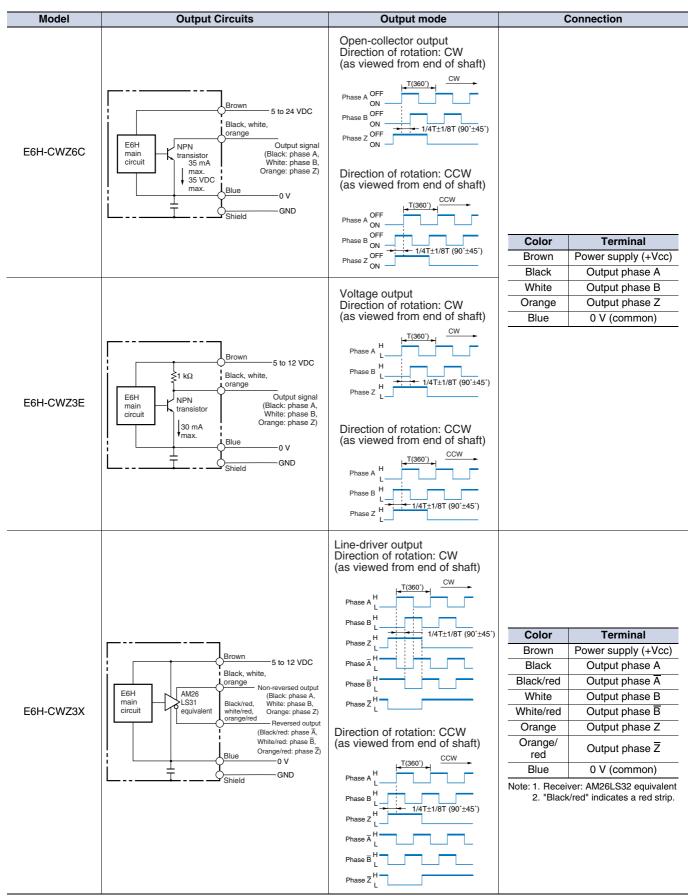
Maximum response frequency ×60 Maximum electrical response speed (rpm) = Resolution

<sup>\*2.</sup> The maximum electrical response speed is determined by the resolution and maximum response frequency as follows:

This means that the Rotary Encoder will not operate electrically if its speed exceeds the maximum electrical response speed. \*3. No protection is provided against water or oil.

<sup>\*4.</sup> The line driver output is a data transmission circuit compatible with RS-422A and long-distance transmission is possible with a twisted-pair cable. The quality is equivalent to AM26LS31.

# I/O Circuit Diagrams



Note: Normally connect GND to 0 V or to an external ground.

# **Safety Precautions**

## Refer to Warranty and Limitations of Liability.

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#### WARNING

This product is not designed or rated for ensuring safety of persons either directly or indirectly. Do not use it for such purposes.



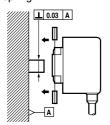
# **Precautions for Correct Use**

Do not use the Encoder under ambient conditions that exceed the ratings.

#### Mounting

- The diameter of the mating shaft must be 8  $^{-0.012}_{-0.004}$  mm and 8 to 11 mm long from the mounting surface.
- The allowable displacement in the mating shaft must 0.05 mm in the radial direction and 0.3 mm in the thrust direction.
- The mounting surface and shaft must be perpendicular to within 0.03 mm.
- When securing the Encoder, do not allow force to be applied to the leaf spring.

length: 500 mm



Eccentricity will develop in the Encoder if the above values are not satisfied, and the mounting leaf spring may be destroyed.

- When securing the Encoder, use two M3 screws to secure the leaf spring to the mounting surface.
- Use the Allen set screw provided with the hollow shaft to secure the shaft. Use a tightening torque of 0.4 N·m and apply screw lock glue to the screw to prevent it from becoming loose.
- If wiring after securing the Encoder, do not pull on the cable. Also, do not apply shock to the Encoder or hollow shaft.
- If the Encoder phase Z must be aligned with the origin of the installation device, mount the Encoder while checking the phase Z output.

#### Wiring

Spurious pulses may be generated when power is turned ON and OFF. Wait at least 0.1 s after turning ON the power to the Encoder before using the connected device, and stop using the connected device at least 0.1 s before turning OFF the power to the Encoder. Also, turn ON the power to the load only after turning ON the power to the Encoder.

Rotary Encoder Recommended Power Supplies: Consult your OMRON representative for details.

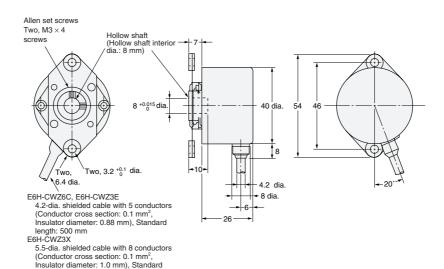
(Unit: mm)

# **Dimensions**

Tolerance class IT16 applies to dimensions in this datasheet unless otherwise specified.

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#### **Read and Understand This Catalog**

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#### WARRANTY

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The following are some examples of applications for which particular attention must be given. This is not intended to be an exhaustive list of all possible uses of the products, nor is it intended to imply that the uses listed may be suitable for the products:

- Outdoor use, uses involving potential chemical contamination or electrical interference, or conditions or uses not described in this catalog.
- Nuclear energy control systems, combustion systems, railroad systems, aviation systems, medical equipment, amusement machines, vehicles, safety equipment, and installations subject to separate industry or government regulations.
- Systems, machines, and equipment that could present a risk to life or property.

Please know and observe all prohibitions of use applicable to the products.

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#### **CHANGE IN SPECIFICATIONS**

Product specifications and accessories may be changed at any time based on improvements and other reasons.

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#### **DIMENSIONS AND WEIGHTS**

Dimensions and weights are nominal and are not to be used for manufacturing purposes, even when tolerances are shown.

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Performance data given in this catalog is provided as a guide for the user in determining suitability and does not constitute a warranty. It may represent the result of OMRON's test conditions, and the users must correlate it to actual application requirements. Actual performance is subject to the OMRON Warranty and Limitations of Liability.

#### **ERRORS AND OMISSIONS**

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