ST Step Drive Family

ST Step Drive Family

The STM is part of a larger family of step drives sharing a common configuration interface and all supporting common programming lanuages and tools.

The family consist of :
STAC6 models - Available in 110VAC and 220VAC input versions. This offers the highest power output, driving even the largest HT34 motors to their full potential.
It also features RS-485 connection and encoder input as standard. The 110VAC version has UL recognicion.
ST-Q/Si models - 5 or 10A versions with bus voltages to 80V. Offered in a number of build options, including the addition of encoder feedback and RS-485.
ST-S models - 5A or 10A versions, bus voltages to 80VDC, offered in a compact 3.65" x 3.0" x 1.125" package. This is the step and direction input model for OEM applications.

For more information or to download a brochure, please visit our website.

Applied Motion Products
404 Westridge Dr.
Watsonville, CA 95076
Tel: 800-525-1609
Fax: 831-761 -6544
www.applied-motion.com

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STM
Drive+Motor

The STM is a Drive+Motor unit,fusing step motor and drive technologies into a single device, offering savings on space, wiring and cost over conventional motor and drive solutions. The STM also fits with the ST product family of step motors and drives for a complete motion control system.

Drive + Motor + Control

Specifications

OUTPUT TORQUE:

- **STM23x-2 - to 125 oz-in**
- **STM23x-3 - to 210 oz-in**

PROTECTION:

- **Over-Voltage**
- **Under voltage**
- **Over-Temp**
- **Motor Shorts**
- **Motor Open Phase**

- **Dynamic Current Control**
- **Anti-Resonance**
- **Torque Ripple Smoothing**
- **Microstep Emulation**

Ordering

STM23S-2AN

- Series: STM Series
- Frame Size: 23
- Control: S = Basic version; Q = Q Programmer
- Motor Size: 2 = 125 oz-in max; 3 = 210 oz-in max
- Feedback: N = None; E = 1000 line encoder
- Communications: A = RS-232; R = RS-485

Models

S

- Pulse & Direction
- CW/CCW Pulse
- A/B Quadrature
- Velocity (Oscillator) mode
- Host commands (SCL compatible)
- SiNet Hub compatible
- ST Configurator software for setup

Q

- Stand-alone Operation
- Q Programmer for complex motion
- Conditional Processing
- Math Functions
- Multi-tasking
- Register Manipulation
- Encoder Following
- "Generic" HMI compatibility

STM technical specs.

POWER AMPLIFIER: **All Models**

AMPLIFIER TYPE	Dual H-Bridge, 4 Quadrant
CURRENT CONTROL	4 state PWM at 20 Khz
OUTPUT TORQUE	**STM23x-2 Series** - TO 125 OZ.IN WITH SUITABLE POWER SUPPLY **STM23x-3 Series** - TO 210 OZ.IN WITH SUITABLE POWER SUPPLY
POWER SUPPLY	External 12 - 70 VDC Power Supply Required
INPUT VOLTAGE RANGE	24 - 75 VDC
PROTECTION	Over-Voltage, Under-voltage, Over-Temp, Motor/wiring shorts (Phase-to-Phase, Phase-to-Ground).
IDLE CURRENT REDUCTION	Reduction range of 0 – 90% of Running Current after delay selectable in milliseconds.
AMBIENT TEMPERATURE	0 to 40°C (32 - 104°F) (mounted to suitable heatsink)
HUMIDITY	90% non-condensing.

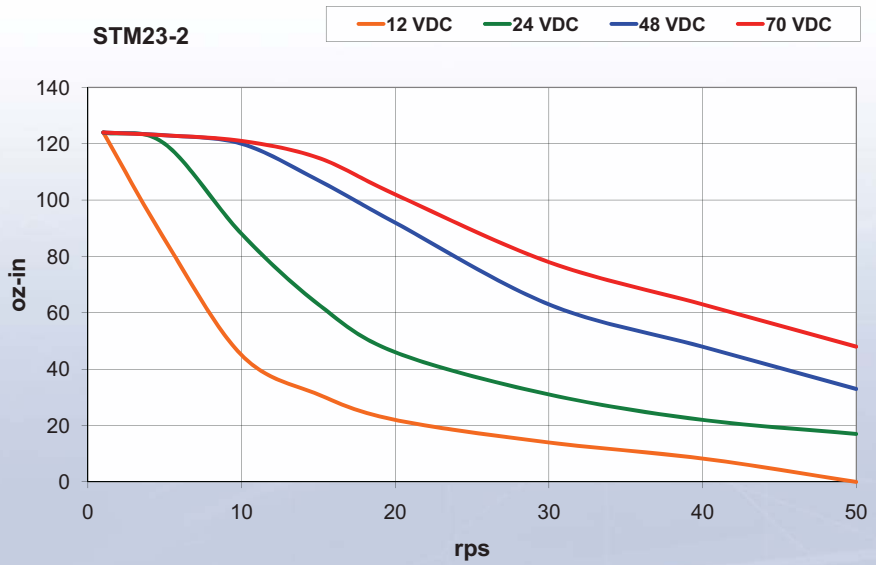
CONTROLLER: **All Models**

MICROSTEP RESOLUTION	Software selectable from 200 to 51200 steps/rev in increments of 2 steps/rev.
ANTI-RESONANCE (Electronic Damping)	Raises the system damping ratio to eliminate midrange instability and allow stable operation throughout the speed range and improves settling time.
TORQUE RIPPLE SMOOTHING	Allows for fine adjustment of phase current waveform harmonic content to reduce low-speed torque ripple in the range 0.25 to 1.5 rps
AUTO SETUP	Measures motor parameters and configures motor current control and anti-resonance gain settings
SELF TEST	Checks Internal & External Power supply voltages. Diagnoses open motor phases and motor resistance changes >40%. Detects encoder wiring and signal faults (differential encoder only).
MICROSTEP EMULATION	Performs high resolution stepping by synthesizing fine microsteps from coarse steps (Step & Direction Mode Only) .
COMMAND SIGNAL SMOOTHING	Software configurable filtering reduces jerk and excitation of extraneous system resonances (Step & Direction Mode Only).

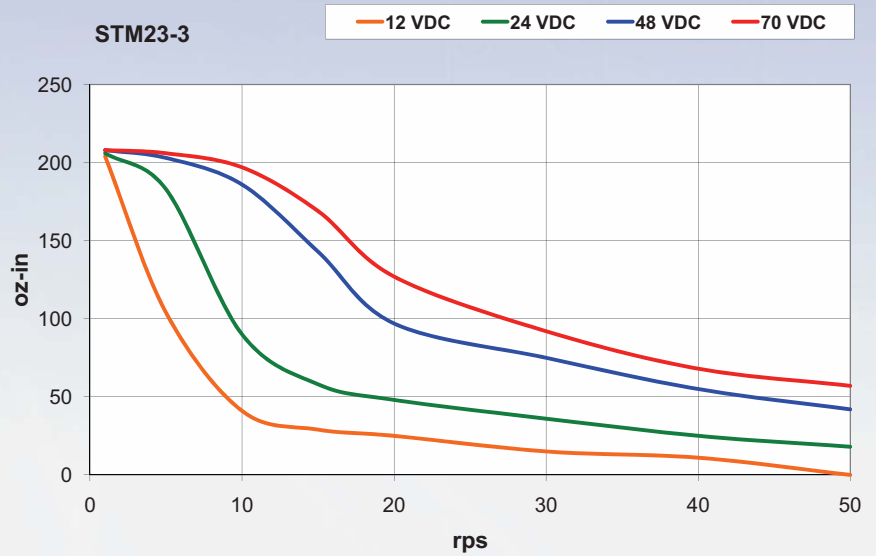
CONTROLLER: **S Models**

NON-VOLATILE STORAGE	Configurations are saved in FLASH memory on-board the DSP.
MODE OF OPERATION	Step & Direction, CW/CCW, A/B Quadrature, Oscillator, Joystick, SCL, Hub.
STEP AND DIRECTION INPUTS	STEP +/- Optically Isolated, 5-24 Volt. Minimum pulse width = 250 ns. Maximum pulse frequency = 3MHz. Function: Step, CW Step, A Quadrature, Encoder Following, CW Limit , CW Jog, START/STOP (Oscillator mode), DIR+/- Optically Isolated, 5-24 Volt. Minimum pulse width = 250 ns. Maximum pulse frequency = 3 MHz. Function: DIR, CCW Step, B Quadrature, Encoder Following, CCW Limit , CCW Jog, Sensor, DIR (Oscillator mode), Adjustable bandwidth digital noise rejection filter on all inputs
ENABLE INPUT	EN+/- Optically Isolated, 5-24 Volt. Minimum pulse width = 250 ns. Maximum pulse frequency = 3 MHz. Function: ENABLE, RESET , SPEED 1/SPEED 2 (Oscillator mode)
OUTPUT	Optically Isolated, 24V, 40mA MAX. Function: Fault, Motion, Tach.
ANALOG INPUT RANGE	0 to 5VDC
ANALOG INPUT RESOLUTION	12 bits
COMMUNICATION INTERFACE	RS-232 or RS-485

STM23-2 *TORQUE CURVES*



STM23-3 *-TORQUE CURVES*



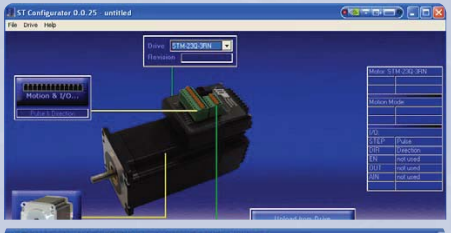
Connections

Input/Output connections

Inputs & Outputs

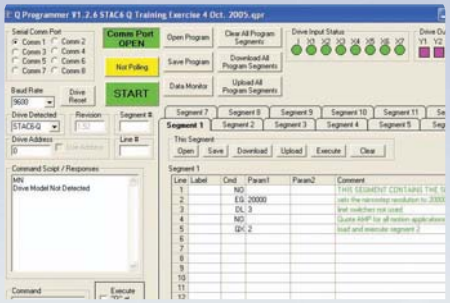
S	Q
3 digital inputs 1 digital output 1 analog input	3 digital inputs 1 digital output 1 analog input

Software



ST Configurator

Used for setup and configuration of the drive+motor. For more information about the ST Configurator visit the Applied Motion Products Website



Q Programmer

Q Programmer is used to create and edit stand-alone programs for Q version drives. The functions of these drives include multi-tasking, math, register manipulation, encoder following, and more.

Help Manuals

ST Configurator incorporates new on-line help menus. All the technical data, application information and advice on setting up the drive is now just a mouse click away.

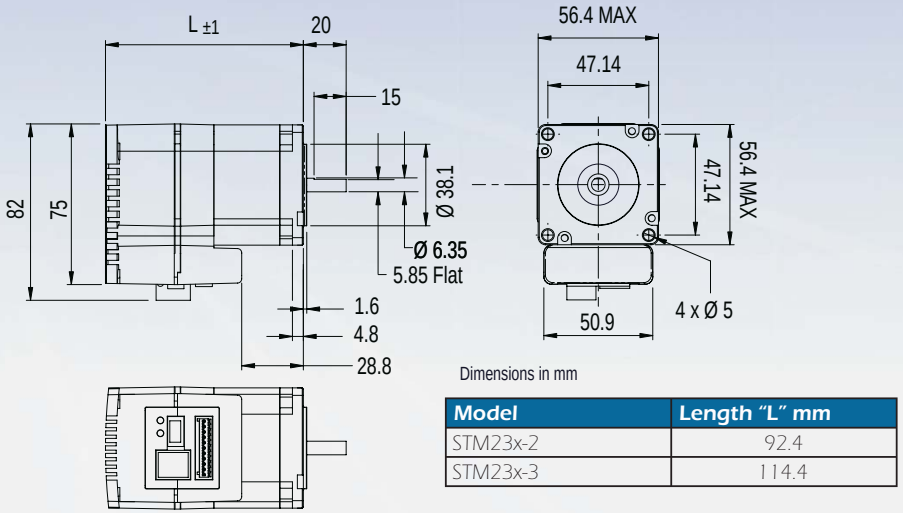
All software applications run on Windows Vista, XP, 2000, NT, ME, 98.

STM technical specs (cont)

CONTROLLER: **Q Models**

NON-VOLATILE STORAGE	Programs, Data and drive configuration are saved in FLASH and EEPROM memory
INPUTS	STEP +/- Optically Isolated, 5-24 Volt. Minimum pulse width = 250 ns. Maximum pulse frequency = 3 MHz. Function: Step, CW Step, A Quadrature, Encoder Following, CW Limit , CW Jog, START/STOP (Oscillator mode), General Purpose Input. DIR+/- Optically Isolated, 5-24 Volt. Minimum pulse width = 250 ns. Maximum pulse frequency = 3 MHz. Function: DIR, CCW Step, B Quadrature, Encoder Following, CCW Limit , CCW Jog, Sensor, DIR (Oscillator mode), General Purpose Input. EN+/- Optically Isolated, 5-24 Volt. Minimum pulse width = 250 ns. Maximum pulse frequency = 3 MHz. Function: ENABLE, RESET , SPEED 1 /SPEED 2 (Oscillator mode), General Purpose Input. Adjustable bandwidth digital noise rejection filter on all inputs
OUTPUT	Optically Isolated, 24V, 40mA MAX. NPN/sinking. Function: Fault, Motion, Tach or general purpose programmable
ANALOG INPUT RANGE	0 - 5 VDC
ANALOG INPUT RESOLUTION	12 bits
COMMUNICATION INTERFACE	RS-232 OR RS-485
AGENCY APPROVALS	RoHS CE, EN 61800-3 :2004, EN 61800-5-1 :2003

Dimensions



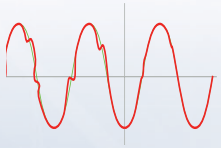
Dimensions in mm

Model	Length "L" mm
STM23x-2	92.4
STM23x-3	114.4

Features

Anti-Resonance/Electronic Damping

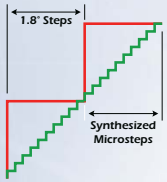
Step motor systems have a natural tendency to resonate at certain speeds. The STM drive+motor automatically calculates the system's natural frequency and apply damping to the control algorithm. This greatly improves midrange stability, allows higher speeds and greater torque utilization, and also improves settling times.



Delivers better motor performance and higher speeds

Microstep Emulation

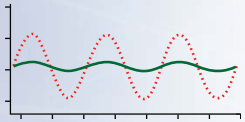
With Microstep Emulation, low resolution systems can still provide smooth motion. The drive can take low-resolution step pulses and create fine resolution micro-step motion.



Delivers smoother motion in any application

Torque Ripple Smoothing

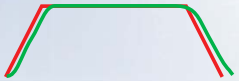
All step motors have an inherent low speed torque ripple that can affect the motion of the motor. By analyzing this torque ripple the system can apply a negative harmonic to negate this effect, which gives the motor much smoother motion at low speed.



Delivers smoother motion at lower speeds

Command Signal Smoothing

Command Signal smoothing can soften the effect of immediate changes in velocity and direction, making the motion of the motor less jerky. An added advantage is that it can reduce the wear on mechanical components.



Delivers smoother system performance

Dynamic Current Control

Allows for three current settings to help the motor run cooler and reduce power consumption.

- Running Current - the current the drive will deliver for continuous motion.
- Accel Current - the current the drive will deliver when accelerating or decelerating.
- Idle Current - reduces current draw when motor is stationary.

System Runs Cooler

Self Test & Auto Setup

At start-up the drive measures motor parameters, including the resistance and inductance, then uses this information to optimize the system performance.

For more information go to www.applied-motion.com/STM

CE

RS232 Model

RS485 Model

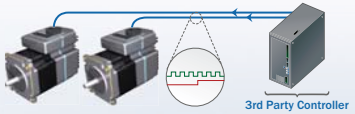
Encoder Option

The STM drive+motor is offered with an optional 1000 line encoder that is integrated into the housing of the motor, without increasing the size of the unit.
The encoder feedback option provides the following functionality:

- **Stall Detection**: The drive detects if the motor has stalled and triggers a fault.
- **Stall Prevention**: The drive automatically senses rotor lag and reduces motor speed to avoid stalling. This feature also includes Position Maintenance which is used when the motor is stopped.

Control Options

Step & Direction



S

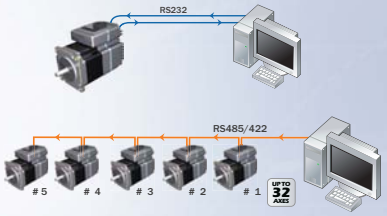
- Step & Direction
- CW & CCW Pulse
- A/B Quadrature (Master Encoder)

Oscillator / Run-Stop

S

- Software Configuration
- Two Speeds
- Vary speed with analog input
- Joystick Compatible

Host Control

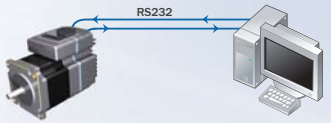


S Q

RS-232 Model
- Accepts Serial Commands from host PC or PLC

RS-485 Model
- Accepts Serial Commands from host PC or PLC
- Multi-axis Capable

Stand-Alone Programmable



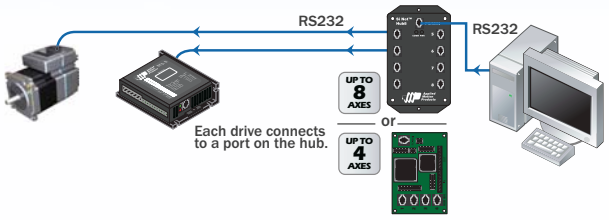
Q

- Comprehensive text based language
- Download, store & execute programs
- High Level Features: Multi-Tasking, Conditional Programming, & Math Functions
- Host Interface While Executing Internal programs

Multi-axis Systems

S Q

Use SiNet Hub Programmer software to develop your sequence of events, then download them to a SiNet Hub for a stand-alone system or stream serial commands to the drives from a PC, PLC, HMI, or other host controller.



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Телефон: 8 (812) 309-75-97 (многоканальный)
Факс: 8 (812) 320-03-32
Электронная почта: ocean@oceanchips.ru
Web: http://oceanchips.ru/
Адрес: 198099, г. Санкт-Петербург, ул. Калинина, д. 2, корп. 4, лит. А