

## microBUCK™ SiC417

### 10-A, 28-V Integrated Buck Regulator with Programmable LDO

#### DESCRIPTION

The Vishay Siliconix SiC417 is an advanced stand-alone synchronous buck regulator featuring integrated power MOSFETs, bootstrap diode, and a programmable LDO in a space-saving MLPQ 5 x 5 - 32 pin package.

The SiC417 is capable of operating with all ceramic solutions and switching frequencies up to 1 MHz. The programmable frequency, synchronous operation and selectable power-save allow operation at high efficiency across the full range of load current. The internal programmable LDO may be used to supply 5 V for the gate drive circuits or it may be bypassed with an external 5 V for optimum efficiency and used to drive external N-channel MOSFETs or other loads. Additional features include cycle-by-cycle current limit, voltage soft-start, under-voltage protection, programmable over-current protection, soft shutdown and selectable power-save. The Vishay Siliconix SiC417 also provides an enable input and a power good output.

#### FEATURES

- High efficiency > 92 %
- Internal power MOSFETs:  
High-side  $R_{DS(ON)} = 27 \text{ m}\Omega$   
Low-side  $R_{DS(ON)} = 9 \text{ m}\Omega$
- Integrated bootstrap diode
- Integrated configurable 150 mA LDO with bypass logic
- Temperature compensated current limit
- Pseudo fixed-frequency adaptive on-time control
- All ceramic solution enabled
- Programmable input UVLO threshold
- Independent enable pin for switcher and LDO
- Selectable ultra-sonic power-save mode
- Internal soft-start and soft-shutdown
- 1 % internal reference voltage
- Power good output and over voltage protection
- **Halogen-free according to IEC 61249-2-21 definition**
- **Compliant to RoHS directive 2002/95/EC**



**RoHS**  
COMPLIANT  
HALOGEN  
**FREE**

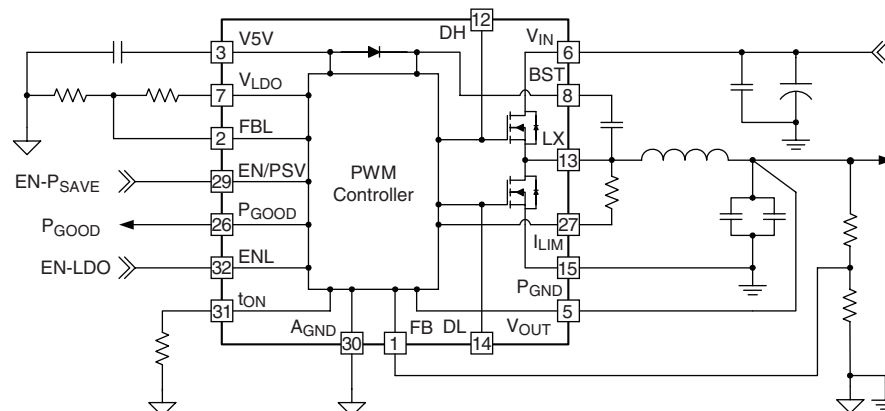
#### PRODUCT SUMMARY

Input Voltage Range	3 V to 28 V
Output Voltage Range	0.5 V to 5.5 V
Operating Frequency	200 kHz to 1 MHz
Continuous Output Current	10 A
Peak Efficiency	95 % at 300 kHz
Package	MLPQ 5 mm x 5 mm

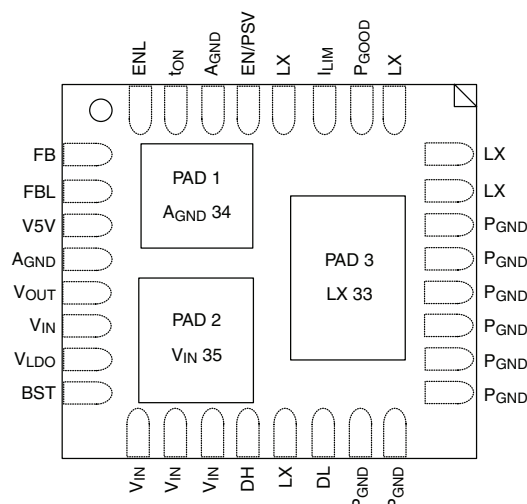
#### APPLICATIONS

- Notebook, desktop and server computers
- Digital HDTV and digital consumer applications
- Networking and telecommunication equipment
- Printers, DSL and STB applications
- Embedded applications
- Point of load power supplies

#### TYPICAL APPLICATION CIRCUIT



## PIN CONFIGURATION



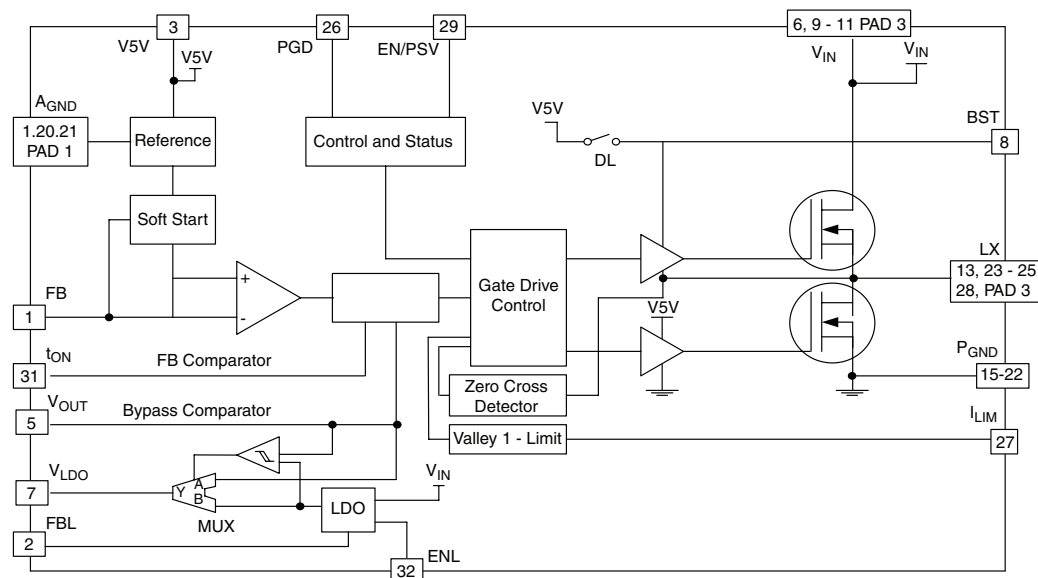
## PIN DESCRIPTION

Pin Number	Symbol	Description
1	FB	Feedback input for switching regulator. Connect to an external resistor divider from output to program the output voltage.
2	FBL	Feedback input for the LDO. Connect to an external resistor divider from $V_{LDO}$ to program the $V_{LDO}$ output.
3	V5V	5 V power input for internal analog circuits and gate drives. Connect to external 5 V supply or configure the LDO for 5 V and connect to $V_{LDO}$ .
4, 30, PAD 1	$A_{GND}$	Analog ground.
5	$V_{OUT}$	Output voltage input to the SiC417. Additionally, may be used to bypass LDO to supply $V_{LDO}$ directly.
6, 9 - 11, PAD 2	$V_{IN}$	Input supply voltage.
7	$V_{LDO}$	LDO output.
8	BST	Bootstrap pin. A capacitor is connected between BST to LX to develop the floating voltage for the high-side gate drive.
12	DH	High-side gate drive - do not connect this pin.
14	DL	Low-side gate drive - do not connect this pin.
13, 23 - 25, 28, PAD 3	LX	Switching (Phase) node.
15-22	$P_{GND}$	Power ground.
26	$P_{GOOD}$	Open-drain power good indicator. High impedance indicates power is good. An external pull-up resistor is required.
27	$I_{LIM}$	Current limit sense point - to program the current limit connect a resistor from $I_{LIM}$ to LX.
29	EN/PSV	Tri-state pin. Enable input for switching regulator. Connect EN to $A_{GND}$ to disable the switching regulator. Float pin for forced continuous and pull high for power-save mode.
31	$t_{ON}$	On-time set input. Set the on-time by a series resistor to the input supply voltage.
32	ENL	Enable input for the LDO. Connect ENL to $A_{GND}$ to disable the LDO.

## ORDERING INFORMATION

Part Number	Package
SiC417CD-T1-E3	MLPQ55-32
SiC417DB	Evaluation board

## FUNCTIONAL BLOCK DIAGRAM



**ABSOLUTE MAXIMUM RATINGS**  $T_A = 25\text{ }^{\circ}\text{C}$ , unless otherwise noted

Parameter	Symbol	Min.	Max.	Unit
LX to P <sub>GND</sub> Voltage	V <sub>LX</sub>	- 0.3	+ 30	V
LX to P <sub>GND</sub> Voltage (transient - 100 ns)	V <sub>LX</sub>	- 2	+ 30	
V <sub>IN</sub> to P <sub>GND</sub> Voltage	V <sub>IN</sub>	- 0.3	+ 30	
V <sub>EN</sub> Maximum Voltage	V <sub>EN</sub>	- 0.3	V <sub>IN</sub>	
BST Bootstrap to LX; V5V to P <sub>GND</sub>		- 0.3	+ 6.0	
A <sub>GND</sub> to P <sub>GND</sub>	V <sub>AG-PG</sub>	- 0.3	+ 0.3	
EN/PSV, P <sub>GOOD</sub> , I <sub>LIM</sub> , V <sub>OUT</sub> , V <sub>LDO</sub> , FB, FBL to GND		- 0.3	+ (V5V + 0.3)	
t <sub>ON</sub> to P <sub>GND</sub>		- 0.3	+ (V5V - 1.5)	
BST to P <sub>GND</sub>		- 0.3	+ 35	

*Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating/conditions for extended periods may affect device reliability.*

## RECOMMENDED OPERATING CONDITIONS

Parameter	Symbol	Min.	Typ.	Max.	Unit
Input Voltage	V <sub>IN</sub>	3.0		28	V
V5V to P <sub>GND</sub>	V5V	4.5		5.5	
V <sub>OUT</sub> to P <sub>GND</sub>	V <sub>OUT</sub>	0.5		5.5	

Note:

For proper operation, the device should be used within the recommended conditions.

## THERMAL RESISTANCE RATINGS

Parameter	Symbol	Min.	Typ.	Max.	Unit
Storage Temperature	T <sub>STG</sub>	- 40		+ 150	°C
Maximum Junction Temperature	T <sub>J</sub>	-		150	
Operation Junction Temperature	T <sub>J</sub>	- 25		+ 125	

**THERMAL RESISTANCE RATINGS**

Thermal Resistance, Junction-to-Ambient <sup>b</sup>			25 20 50		°C/W
High-Side MOSFET					
Low-Side MOSFET					
PWM Controller and LDO Thermal Resistance					
Peak IR Reflow Temperature	T <sub>Reflow</sub>	-		260	°C

Notes:

a. This device is ESD sensitive. Use of standard ESD handling precautions is required.

b. Calculated from package in still air, mounted to 3 x 4.5 (in), 4 layer FR4 PCB with thermal vias under the exposed pad per JE5D51 standards.

Exceeding the above specifications may result in permanent damage to the device or device malfunction. Operation outside of the parameters specified in the Electrical Characteristics section is not recommended.

**ELECTRICAL SPECIFICATIONS**

Parameter	Symbol	Test Conditions Unless Specified V <sub>IN</sub> = 12 V, V <sub>5V</sub> = 5 V, T <sub>A</sub> = + 25 °C for typ., - 25 °C to + 85 °C for min. and max., T <sub>J</sub> = < 125 °C	Min.	Typ.	Max.	Unit
Input Supplies						
V <sub>IN</sub> Input Voltage	V <sub>IN</sub>		3		28	V
V <sub>5V</sub> Voltage	V <sub>5V</sub>		4.5		5.5	
V <sub>IN</sub> UVLO Threshold Voltage <sup>a</sup>	V <sub>IN_UV+</sub>	Sensed at ENL pin, rising edge	2.4	2.6	2.95	
	V <sub>IN_UV-</sub>	Sensed at ENL pin, falling edge	2.235	2.4	2.565	
V <sub>IN</sub> UVLO Hysteresis	V <sub>IN_UV_HY</sub>	EN/PSV = High		0.2		
V <sub>5V</sub> UVLO Threshold Voltage	V <sub>5V_UV+</sub>	Measured at V <sub>5V</sub> pin, rising edge	3.7	3.9	4.1	
	V <sub>5V_UV-</sub>	Measured at V <sub>5V</sub> pin, falling edge	3.5	3.6	3.75	
V <sub>5V</sub> UVLO Hysteresis	V <sub>5V_UV_HY</sub>			0.3		
V <sub>IN</sub> Supply Current	I <sub>IN</sub>	EN/PSV, ENL = 0 V, V <sub>IN</sub> = 28 V		8.5	20	μA
		Standby mode: ENL = V <sub>5V</sub> , EN/PSV = 0 V		130		
V <sub>5V</sub> Supply Current	I <sub>5V</sub>	EN/PSV, ENL = 0 V		3	7	mA
		EN/PSV = V <sub>5V</sub> , no load (f <sub>SW</sub> = 25 kHz), V <sub>FB</sub> > 500 mV <sup>b</sup>		2		
		f <sub>SW</sub> = 250 kHz, EN/PSV = floating, no load <sup>b</sup>		10		
Controller						
F <sub>B</sub> On-Time Threshold	V <sub>FB-TH</sub>	Static V <sub>IN</sub> and load, - 40 °C to + 85 °C	0.495	0.5	0.505	V
Frequency Range	F <sub>PWM</sub>	continuous mode	200		1000	kHz
Bootstrap Switch Resistance				10		Ω
Timing						
On-Time	t <sub>ON</sub>	Continuous mode operation V <sub>IN</sub> = 15 V, V <sub>OUT</sub> = 5 V, f <sub>SW</sub> = 300 kHz, R <sub>ton</sub> = 133 kΩ	999	1110	1220	ns
Minimum On-Time <sup>b</sup>	t <sub>ON</sub>			50		
Minimum Off-Time <sup>b</sup>	t <sub>OFF</sub>			250		
Soft Start						
Soft Start Time <sup>b</sup>	t <sub>SS</sub>	I <sub>OUT</sub> = I <sub>LIM</sub> /2		0.85		ms
Analog Inputs/Outputs						
V <sub>OUT</sub> Input Resistance	R <sub>O-IN</sub>			500		kΩ
Current Sense						
Zero-Crossing Detector Threshold Voltage	V <sub>Sense-th</sub>	LX-P <sub>GND</sub>	- 3	0	+ 3	mV
Power Good						
Power Good Threshold Voltage	PG_V <sub>TH</sub>	Internal reference 500 mV	- 10 %		+ 20 %	V
Start-Up Delay Time	PG_T <sub>d</sub>	V <sub>EN</sub> = 0 V		2		ms
Fault (noise-immunity) Delay Time <sup>b</sup>	PG_I <sub>CC</sub>	V <sub>EN</sub> = 0 V		5		μs
Power Good Leakage Current	PG_I <sub>LK</sub>	V <sub>EN</sub> = 0 V			1	μA
Power Good On-Resistance	PG_R <sub>DS-ON</sub>	V <sub>EN</sub> = 0 V		10		Ω

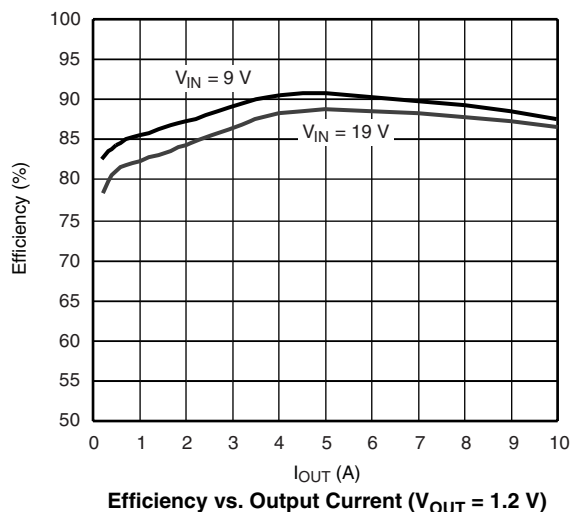
## ELECTRICAL SPECIFICATIONS

Parameter	Symbol	Test Conditions Unless Specified V <sub>IN</sub> = 12 V, V5V = 5 V, T <sub>A</sub> = + 25 °C for typ., - 25 °C to + 85 °C for min. and max., T <sub>J</sub> = < 125 °C	Min.	Typ.	Max.	Unit
Fault Protection						
I <sub>LIM</sub> Source Current	I <sub>LIM</sub>			10		μA
Valley Current Limit		R <sub>LIM</sub> = 5.9 kΩ	6	8	10	A
I <sub>LIM</sub> Comparator Offset Voltage	V <sub>ILM-LK</sub>	With respect to A <sub>GND</sub>	- 10	0	+ 10	mV
Output Under-Voltage Fault	V <sub>OUV_Fault</sub>	V <sub>FB</sub> with respect to Internal 500 mV reference, 8 consecutive clocks		- 25		%
Smart Power-Save Protection Threshold Voltage <sup>b</sup>	P <sub>SAVE_VTH</sub>	V <sub>FB</sub> with respect to internal 500 mV reference		+ 10		%
Over-Voltage Protection Threshold		V <sub>FB</sub> with respect to internal 500 mV reference		+ 20		
Over-Voltage Fault Delay <sup>b</sup>	t <sub>OV-Delay</sub>			5		μs
Over Temperature Shutdown <sup>b</sup>	T <sub>Shut</sub>	10 °C hysteresis		150		°C
Logic Inputs/Outputs						
Logic Input High Voltage	V <sub>IN+</sub>	EN, ENL, PSV	2			V
Logic Input Low Voltage	V <sub>IN-</sub>				0.4	
EN/PSV Input Bias Current	I <sub>EN-</sub>	EN/PSV = V5V or A <sub>GND</sub>	- 10		+ 10	μA
ENL Input Bias Current		V <sub>IN</sub> = 28 V		11	18	
FBL, FB Input Bias Current	FBL_I <sub>LK</sub>	FBL, FB = V5V or A <sub>GND</sub>	- 1		+ 1	
Linear Dropout Regulator						
FBL Accuracy	FBL <sub>ACC</sub>	V <sub>LDO</sub> load = 10 mA	0.735	0.75	0.765	V
LDO Current Limit	LDO_I <sub>LIM</sub>	Start-up and foldback, V <sub>IN</sub> = 12 V		85		mA
		Operating current limit, V <sub>IN</sub> = 12 V	135	200		
V <sub>LDO</sub> to V <sub>OUT</sub> Switch-Over Threshold <sup>c</sup>	V <sub>LDO-BPS</sub>		- 140		+ 140	mV
V <sub>LDO</sub> to V <sub>OUT</sub> Non-Switch-Over Threshold <sup>c</sup>	V <sub>LDO-NBPS</sub>		- 450		+ 450	
V <sub>LDO</sub> to V <sub>OUT</sub> Switch-Over Resistance	R <sub>LDO</sub>	V <sub>OUT</sub> = 5 V		2		Ω
LDO Drop Out Voltage <sup>d</sup>		From V <sub>IN</sub> to V <sub>VLDO</sub> , V <sub>VLDO</sub> = + 5 V, I <sub>VLDO</sub> = 100 mA		1.2		V

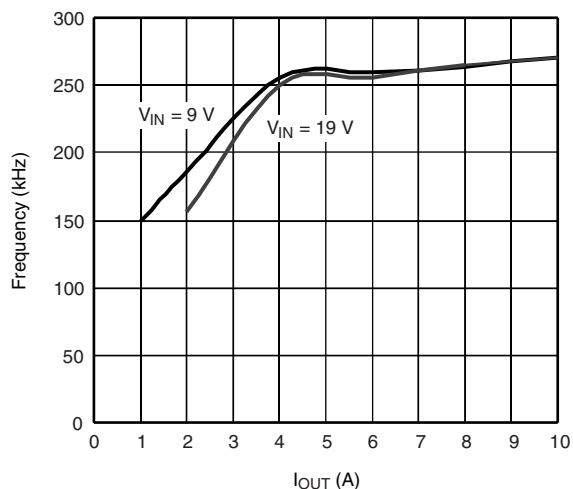
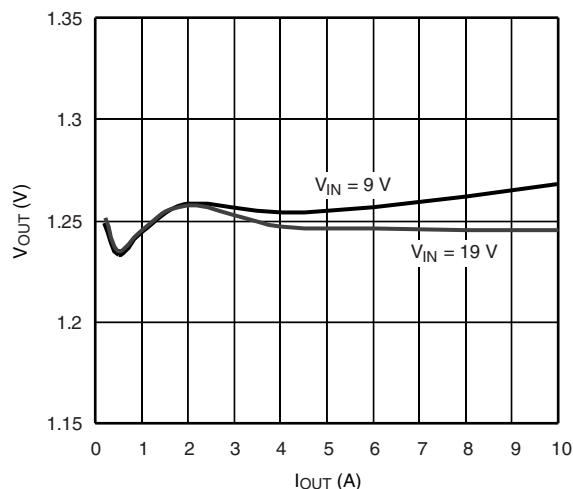
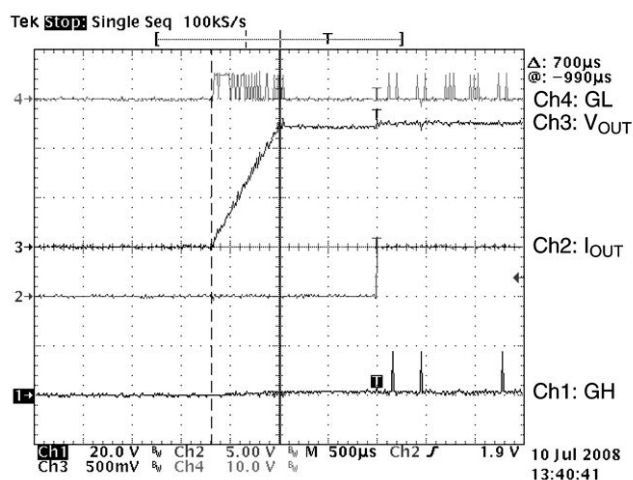
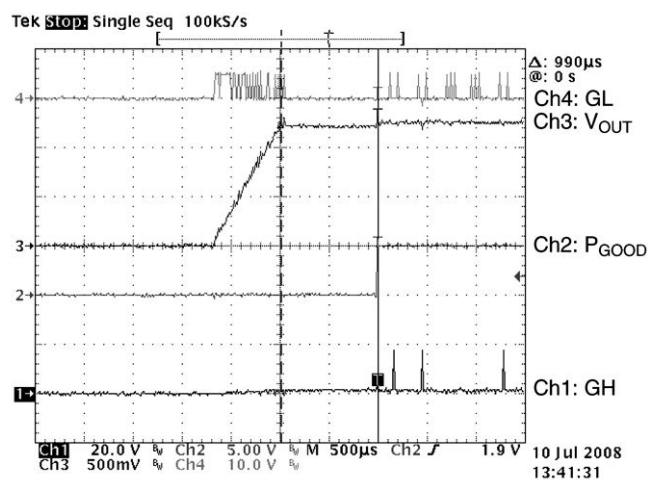
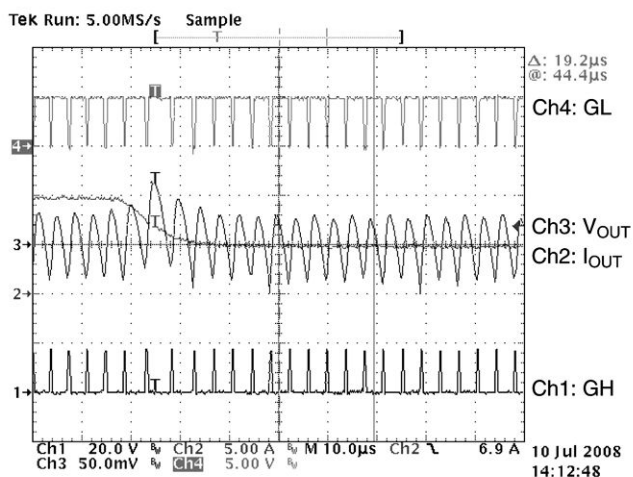
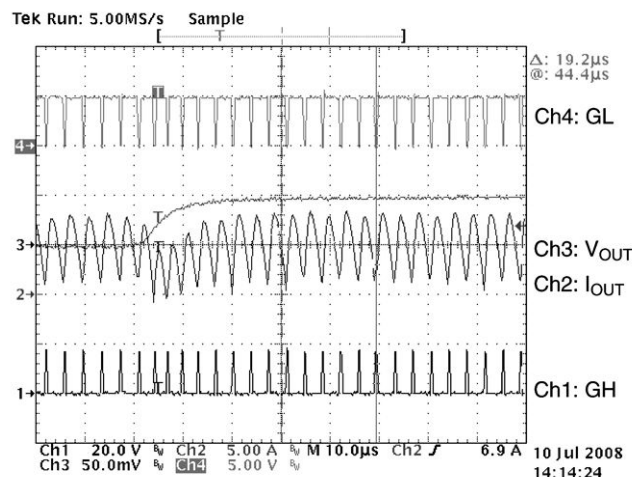
Notes:

- $V_{IN\ UVLO}$  is programmable using a resistor divider from  $V_{IN}$  to ENL to  $A_{GND}$ . The ENL voltage is compared to an internal reference.
- Guaranteed by design.
- The switch-over threshold is the maximum voltage differential between the  $V_{LDO}$  and  $V_{OUT}$  pins which ensures that  $V_{LDO}$  will internally switch-over to  $V_{OUT}$ . The non-switch-over threshold is the minimum voltage differential between the  $V_{LDO}$  and  $V_{OUT}$  pins which ensures that  $V_{LDO}$  will not switch-over to  $V_{OUT}$ .
- The LDO drop out voltage is the voltage at which the LDO output drops 2 % below the nominal regulation point.

## ELECTRICAL CHARACTERISTICS

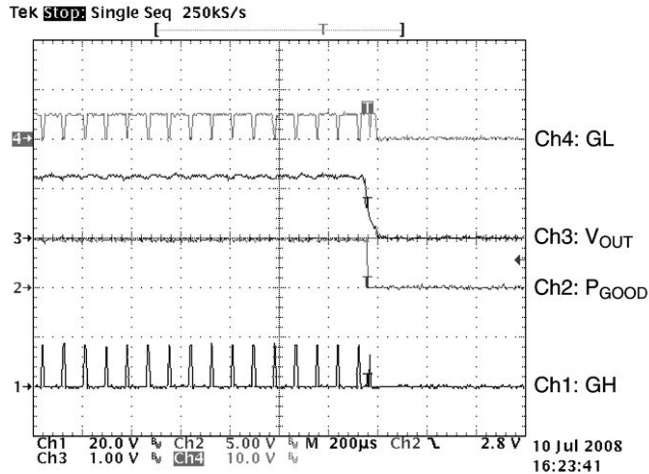


## ELECTRICAL CHARACTERISTICS

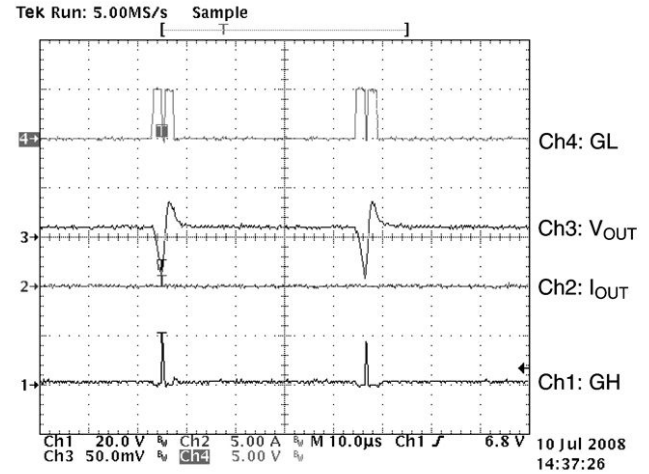
Frequency vs.  $I_{OUT}$ , ( $V_{OUT} = 1.2\text{ V}$ )Load Regulation, ( $V_{OUT} = 1.2\text{ V}$ )Start up Time:  $V_{IN} = 12\text{ V}$ ,  $V_{OUT} = 1.2\text{ V}$ ,  $I_{OUT} = 0\text{ A}$  $P_{GOOD}$  Delay after Start up Time:  
 $V_{IN} = 12\text{ V}$ ,  $V_{OUT} = 1.2\text{ V}$ ,  $I_{OUT} = 0\text{ A}$ Transient Response:  $V_{IN} = 12\text{ V}$ ,  $V_{OUT} = 1.2\text{ V}$ ,  
 $I_{OUT} = 10\text{ A to } 5\text{ A}$ ,  $dI/dt = 0.5\text{ A}/\mu\text{s}$ Transient Response:  $V_{IN} = 12\text{ V}$ ,  $V_{OUT} = 1.2\text{ V}$ ,  
 $I_{OUT} = 5\text{ A to } 10\text{ A}$ ,  $dI/dt = 0.5\text{ A}/\mu\text{s}$



## ELECTRICAL CHARACTERISTICS



Over Current Protection:  $V_{IN} = 12\text{ V}$ ,  $V_{OUT} = 1.2\text{ V}$



Ultra-Sonic Power-Save at  $I_{OUT} = 0\text{ A}$

## APPLICATIONS INFORMATION

### SiC417 Synchronous Buck Converter

The SiC417 is a step down synchronous buck dc-to-dc converter with integrated power FETs and programmable LDO. The SiC417 is capable of 10 A operation at very high efficiency in a tiny 5 mm x 5 mm - 32 pin package. The programmable operating frequency range of 200 kHz to 1 MHz, enables the user to optimize the solution for minimum board space and optimum efficiency.

The buck controller employs pseudo-fixed frequency adaptive on-time control. This control scheme allows fast transient response thereby lowering the size of the power components used in the system.

### Input Voltage Range

The SiC417 requires two input supplies for normal operation:  $V_{IN}$  and  $V5V$ .  $V_{IN}$  operates over the wide range from 3 V to 28 V.  $V5V$  requires a 5 V supply input that can be an external source or the internal LDO configured to supply 5 V. When  $V_{IN}$  is less than ~ 6 V then an external 5 V supply must be tied to  $V5V$ .

### Pseudo-Fixed Frequency Adaptive On-Time Control

The PWM control method used for the SiC417 is pseudo-fixed frequency, adaptive on-time, as shown in figure 1. The ripple voltage generated at the output capacitor ESR is used as a PWM ramp signal. This ripple is used to trigger the on-time of the controller.

The adaptive on-time is determined by an internal oneshot timer. When the one-shot is triggered by the output ripple, the device sends a single on-time pulse to the highside MOSFET. The pulse period is determined by  $V_{OUT}$  and  $V_{IN}$ ; the period is proportional to output voltage and inversely proportional to input voltage. With this adaptive on-time arrangement, the device automatically anticipates the on-time needed to regulate  $V_{OUT}$  for the present  $V_{IN}$  condition and at the selected frequency.

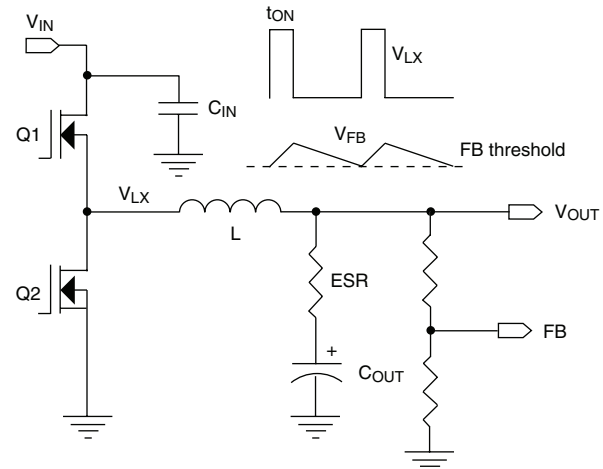


Figure 1 - Output Ripple and PWM Control Method

The adaptive on-time control has significant advantages over traditional control methods used in the controllers today.

- Reduced component count by eliminating DCR sense or current sense resistor as no need of a sensing inductor current.
- Reduced Saves external components used for compensation by eliminating the no error amplifier and other components.
- Ultra fast transient response because of fast loop, absence of error amplifier speeds up the transient response.
- Predictable frequency spread because of constant on-time architecture.
- Fast transient response enables operation with minimum output capacitance

Overall, superior performance compared to fixed frequency architectures.

### On-Time One-Shot Generator ( $t_{ON}$ ) and Operating Frequency

The SiC417 have an internal on-time one-shot generator which is a comparator that has two inputs. The FB Comparator output goes high when  $V_{FB}$  is less than the internal 500 mV reference. This feeds into the gate drive and turns on the high-side MOSFET, and also starts the one-shot timer. The one-shot timer uses an internal comparator and a capacitor. One comparator input is connected to  $V_{OUT}$ , the other input is connected to the capacitor. When the on-time begins, the internal capacitor charges from zero volts through a current which is proportional to  $V_{IN}$ . When the capacitor voltage reaches  $V_{OUT}$ , the on-time is completed and the high-side MOSFET turns off. The figure 2 shows the on-chip implementation of on-time generation.

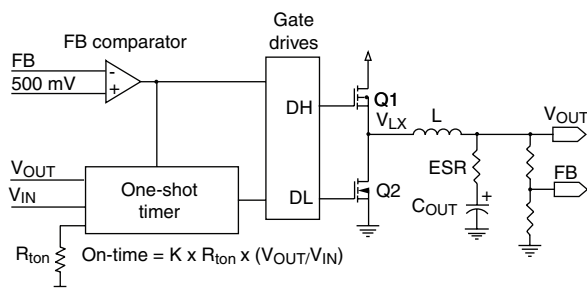


Figure 2 - On-Time Generation

This method automatically produces an on-time that is proportional to  $V_{OUT}$  and inversely proportional to  $V_{IN}$ . Under steady-state conditions, the switching frequency can be determined from the on-time by the following equation.

$$f_{SW} = \frac{V_{OUT}}{t_{ON} \times V_{IN}}$$

The SiC417 uses an external resistor to set the ontime which indirectly sets the frequency. The on-time can be programmed to provide operating frequency from 200 kHz to 1 MHz using a resistor between the  $t_{ON}$  pin and ground. The resistor value is selected by the following equation.

$$R_{ton} = \frac{(t_{ON} - 10 \text{ ns}) \times V_{IN}}{25 \text{ pF} \times V_{OUT}}$$

The maximum  $R_{TON}$  value allowed is shown by the following equation.

$$R_{ton\_MAX} = \frac{V_{IN\_MIN}}{15 \mu A}$$

### $V_{OUT}$ Voltage Selection

The switcher output voltage is regulated by comparing  $V_{OUT}$  as seen through a resistor divider at the FB pin to the internal 500 mV reference voltage, see figure 3.

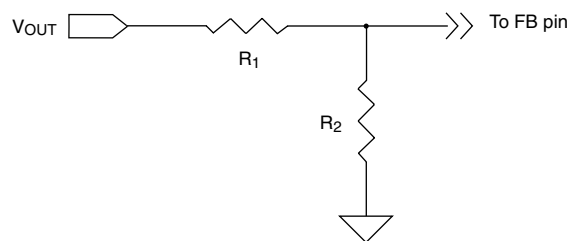


Figure 3 - Output Voltage Selection

As the control method regulates the valley of the output ripple voltage, the DC output voltage  $V_{OUT}$  is off set by the output ripple according to the following equation.

$$V_{OUT} = 0.5 \times (1 + R_1/R_2) + V_{RIPPLE}/2$$

### Enable and Power-Save Inputs

The EN/PSV and ENL inputs are used to enable or disable the switching regulator and the LDO.

When EN/PSV is low (grounded), the switching regulator is off and in its lowest power state. When off, the output of the switching regulator soft-discharges the output into a 15  $\Omega$  internal resistor via the  $V_{OUT}$  pin.

When EN/PSV is allowed to float, the pin voltage will float to 1.5 V. The switching regulator turns on with power-save disabled and all switching is in forced continuous mode.

When EN/PSV is high (above 2.0 V), the switching regulator turns on with ultra-sonic power-save enabled. The SiC417 ultra-sonic power-save operation maintains a minimum switching frequency of 25 kHz, for applications with stringent audio requirements.

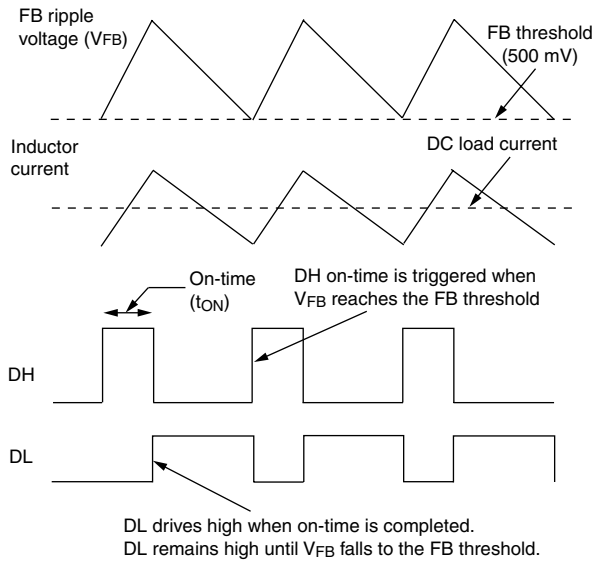
The ENL input is used to control the internal LDO. This input serves a second function by acting as a  $V_{IN}$  UVLO sensor for the switching regulator.

The LDO is off when ENL is low (grounded). When ENL is a logic high but below the  $V_{IN}$  UVLO threshold (2.6 V typical), then the LDO is on and the switcher is off. When ENL is above the  $V_{IN}$  UVLO threshold, the LDO is enabled and the switcher is also enabled if the EN/PSV pin is not grounded.

### Forced Continuous Mode Operation

The SiC417 operates the switcher in Forced Continuous Mode (FCM) by floating the EN/PSV pin (see figure 4). In this mode one of the power MOSFETs is always on, with no intentional dead time other than to avoid cross-conduction. This feature results in uniform frequency across the full load range with the trade-off being poor efficiency at light loads due to the high-frequency switching of the MOSFETs.



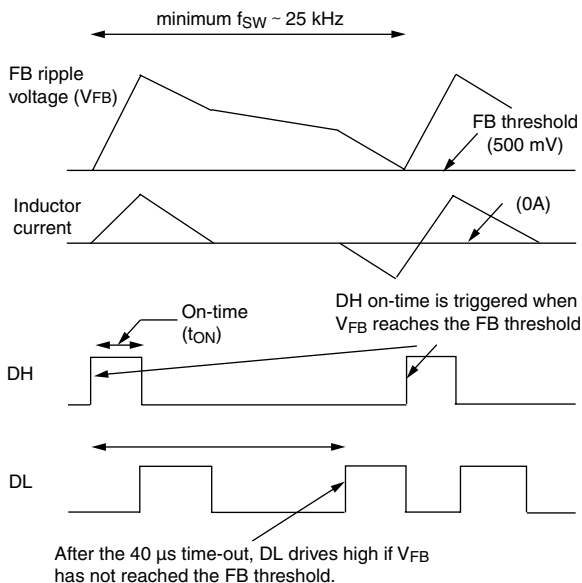


**Figure 4 - Forced Continuous Mode Operation**

### Ultrasonic Power-Save Operation

The SiC417 provides ultra-sonic power-save operation at light loads, with the minimum operating frequency fixed at 25 kHz. This is accomplished using an internal timer that monitors the time between consecutive high-side gate pulses.

If the time exceeds 40  $\mu$ s, DL drives high to turn the low-side MOSFET on. This draws current from  $V_{OUT}$  through the inductor, forcing both  $V_{OUT}$  and  $V_{FB}$  to fall. When  $V_{FB}$  drops to the 500 mV threshold, the next DH on-time is triggered. After the on-time is completed the high-side MOSFET is turned off and the low-side MOSFET turns on, the low-side MOSFET remains on until the inductor current ramps down to zero, at which point the low-side MOSFET is turned off.



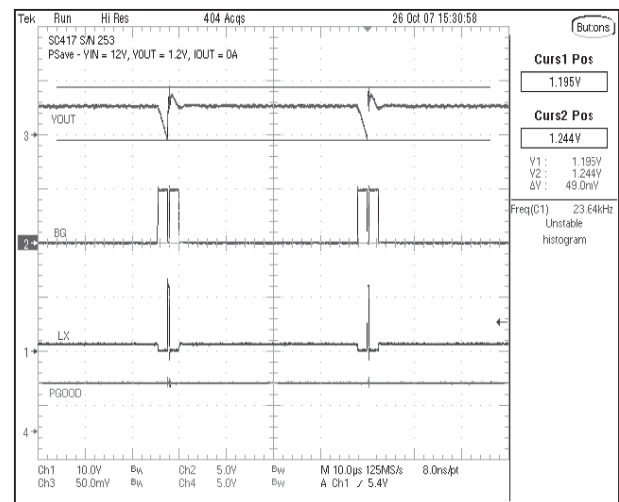
**Figure 5 - Ultrasonic power-save Operation**

Because the on-times are forced to occur at intervals no greater than 40  $\mu$ s, the frequency will not fall below ~ 25 kHz. Figure 5 shows ultra-sonic power-save operation.

### Benefits of Ultrasonic Power-Save

Having a fixed minimum frequency in power-save has some significant advantages as below:

- The minimum frequency of 25 kHz is outside the audible range of human ear. This makes the operation of the SiC417 very quiet.
- The output voltage ripple seen in power-save mode is significant lower than conventional power-save, which improves efficiency at light loads.
- Lower ripple in power-save also makes the power component selection easier.



**Figure 6 - Ultrasonic Power-Save Operation Mode**

Figure 6 shows the behavior under power-save and continuous conduction mode at light loads.

### Smart Power-Save Protection

Active loads may leak current from a higher voltage into the switcher output. Under light load conditions with power-save power-save enabled, this can force  $V_{OUT}$  to slowly rise and reach the over-voltage threshold, resulting in a hard shutdown. Smart power-save prevents this condition.

When the FB voltage exceeds 10 % above nominal (exceeds 550 mV), the device immediately disables power-save, and DL drives high to turn on the low-side MOSFET. This draws current from  $V_{OUT}$  through the inductor and causes  $V_{OUT}$  to fall. When  $V_{FB}$  drops back to the 500 mV trip point, a normal  $t_{ON}$  switching cycle begins.

This method prevents a hard OVP shutdown and also cycles energy from  $V_{OUT}$  back to  $V_{IN}$ . It also minimizes operating power by avoiding forced conduction mode operation. Figure 7 shows typical waveforms for the smart power-save feature.

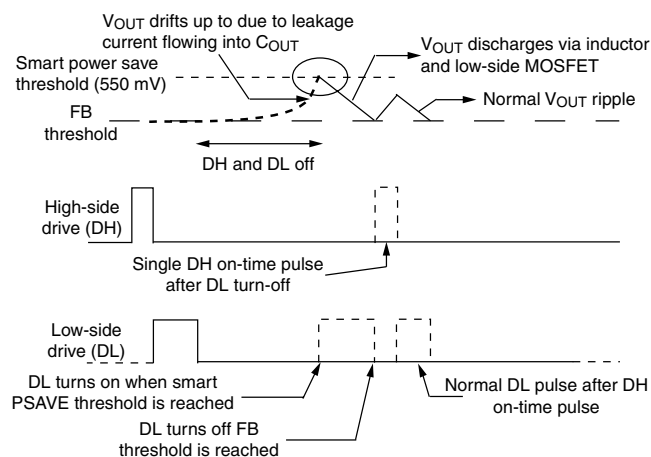


Figure 7 - Smart Power-Save

### Current Limit Protection

The SiC417 features programmable current limit capability, which is accomplished by using the  $R_{DS(ON)}$  of the lower MOSFET for current sensing. The current limit is set by  $R_{ILIM}$  resistor. The  $R_{ILIM}$  resistor connects from the  $I_{LIM}$  pin to the LX pin which is also the drain of the low-side MOSFET.

When the low-side MOSFET is on, an internal  $\sim 10 \mu A$  current flows from the  $I_{LIM}$  pin and the  $R_{ILIM}$  resistor, creating a voltage drop across the resistor. While the low-side MOSFET is on, the inductor current flows through it and creates a voltage across the  $R_{DS(ON)}$ . The voltage across the MOSFET is negative with respect to ground.

If this MOSFET voltage drop exceeds the voltage across  $R_{ILIM}$ , the voltage at the  $I_{LIM}$  pin will be negative and current limit will activate. The current limit then keeps the low-side MOSFET on and will not allow another high-side on-time, until the current in the low-side MOSFET reduces enough to bring the  $I_{LIM}$  voltage back up to zero. This method regulates the inductor valley current at the level shown by  $I_{LIM}$  in figure 8.

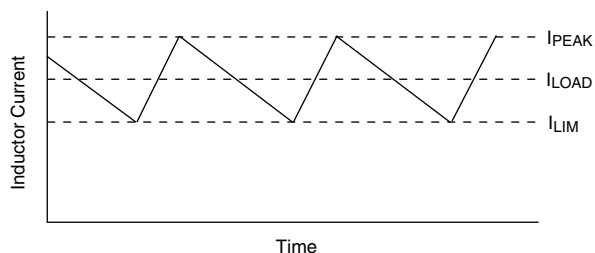


Figure 8 - Valley Current Limit

Setting the valley current limit to 10 A results in a 10 A peak inductor current plus peak ripple current. In this situation, the average (load) current through the inductor is 10 A plus one-half the peak-to-peak ripple current.

The internal  $10 \mu A$  current source is temperature compensated at 4100 ppm in order to provide tracking with the  $R_{DS(ON)}$ . The  $R_{ILIM}$  value is calculated by the following equation.

$$R_{ILIM} = 735 \times I_{LIM}$$

Note that because the low-side MOSFET with low  $R_{DS(ON)}$  is used for current sensing, the PCB layout, solder connections, and PCB connection to the LX node must be done carefully to obtain good results. Refer to the layout guidelines for information.

### Soft-Start of PWM Regulator

Soft-start is achieved in the PWM regulator by using an internal voltage ramp as the reference for the FB Comparator. The voltage ramp is generated using an internal charge pump which drives the reference from zero to 500 mV in  $\sim 1.2$  mV increments, using an internal  $\sim 500$  kHz oscillator. When the ramp voltage reaches 500 mV, the ramp is ignored and the FB comparator switches over to a fixed 500 mV threshold. During soft-start the output voltage tracks the internal ramp, which limits the start-up inrush current and provides a controlled softstart profile for a wide range of applications. Typical softstart ramp time is 850  $\mu s$ . During soft-start the regulator turns off the low-side MOSFET on any cycle if the inductor current falls to zero. This prevents negative inductor current, allowing the device to start into a pre-biased output.

### Power Good Output

The power good ( $P_{GOOD}$ ) output is an open-drain output which requires a pull-up resistor. When the output voltage is 10 % below the nominal voltage,  $P_{GOOD}$  is pulled low. It is held low until the output voltage returns above  $-8$  % of nominal.  $P_{GOOD}$  is held low during start-up and will not be allowed to transition high until soft-start is completed (when  $V_{FB}$  reaches 500 mV) and typically 2 ms has passed.

$P_{GOOD}$  will transition low if the  $V_{FB}$  pin exceeds  $+20$  % of nominal, which is also the over-voltage shutdown threshold (600 mV).  $P_{GOOD}$  also pulls low if the EN/PSV pin is low when V5V is present.

### Output Over-Voltage Protection

Over-voltage protection becomes active as soon as the device is enabled. The threshold is set at 500 mV  $+20$  % (600 mV). When  $V_{FB}$  exceeds the OVP threshold, DL latches high and the low-side MOSFET is turned on. DL remains high and the controller remains off, until the EN/PSV input is toggled or V5V is cycled. There is a 5  $\mu s$  delay built into the OVP detector to prevent false transitions.  $P_{GOOD}$  is also low after an OVP event.

### Output Under-Voltage Protection

When  $V_{FB}$  falls 25 % below its nominal voltage (falls to 375 mV) for eight consecutive clock cycles, the switcher is shut off and the DH and DL drives are pulled low to tristate the MOSFETs. The controller stays off until EN/PSV is toggled or V5V is cycled.

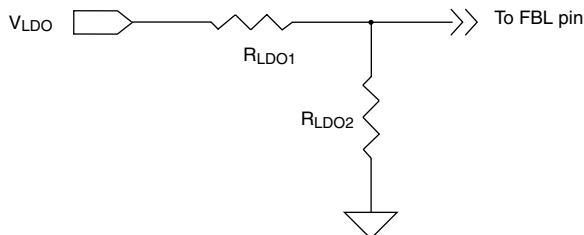
### V5V UVLO, and POR

Under-voltage lock-out (UVLO) circuitry inhibits switching and tri-states the DH/DL drivers until V5V rises above 3.9 V. An internal Power-On Reset (POR) occurs when V5V exceeds 3.9 V, which resets the fault latch and soft-start

counter to prepare for soft-start. The SiC417 then begins a soft-start cycle. The PWM will shut off if V5V falls below 3.6 V.

### LDO Regulator

The SiC417 features an integrated LDO regulator with a programmable output voltage from 0.75 V to 5.25 V using external resistors, when an external supply is used to power V5V. The feedback pin (FBL) for the LDO is regulated to 750 mV. There is also an enable pin (ENL) for the LDO that provides independent control. The LDO voltage can also be used to provide the bias voltage for the switching regulator, when V<sub>LDO</sub> is tied to V5V. More detail can be found in the On Chip LDO bias section coming up.



**Figure 9 - LDO Start-Up**

The LDO output voltage is set by the following equation.

$$V_{LDO} = 750 \text{ mV} \times 1 + \left( \frac{R_{LDO1}}{R_{LDO2}} \right)$$

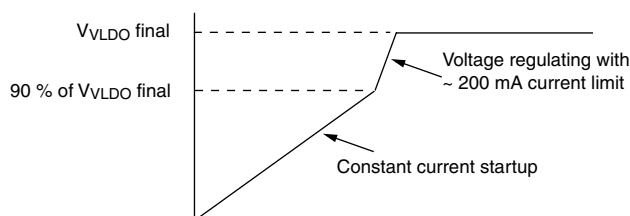
A minimum capacitance of 1  $\mu$ F referenced to AGND is normally required at the output of the LDO for stability. If the LDO is providing bias power to the device, then a minimum 0.1  $\mu$ F capacitor referenced to A<sub>GND</sub> is required along with a minimum 1.0  $\mu$ F capacitor referenced to P<sub>GND</sub> to filter the gate drive pulses. Refer to the layout guideline section.

### LDO Start-up

Before start-up, the LDO checks the status of the following signals to ensure proper operation can be maintained.

1. ENL pin
2. V<sub>LDO</sub> output
3. V<sub>IN</sub> input voltage

When the ENL pin is high and V<sub>IN</sub> is above the UVLO point, the LDO will begin start-up. During the initial phase, when the LDO output voltage is near zero, the LDO initiates a current-limited start-up (typically 85 mA) to charge the output capacitor. When V<sub>LDO</sub> has reached 90 % of the final value (as sensed at the FBL pin), the LDO current limit is increased to ~ 200 mA and the LDO output is quickly driven to the nominal value by the internal LDO regulator.



**Figure 10 - LDO Start-Up**

### LDO Switchover Function

The SiC417 includes a switch-over function for the LDO. The switch-over function is designed to increase efficiency by using the more efficient dc-to-dc converter to power the LDO output, avoiding the less efficient LDO regulator when possible. The switch-over function connects the V<sub>LDO</sub> pin directly to the V<sub>OUT</sub> pin using an internal switch. When the switch-over is complete the LDO is turned off, which results in a power savings and maximizes efficiency. If the LDO output is used to bias the SiC417, then after switch-over the device is self-powered from the switching regulator with the LDO turned off.

The switch-over logic waits for 32 switching cycles before it starts the switch-over. There are two methods that determine the switch-over of V<sub>LDO</sub> to V<sub>OUT</sub>.

In the first method, the LDO is already in regulation and the dc-to-dc converter is later enabled. As soon as the P<sub>GOOD</sub> output goes high, the 32 cycles are started. The voltages at the V<sub>LDO</sub> and V<sub>OUT</sub> pins are then compared; if the two voltages are within  $\pm 300$  mV of each other, the V<sub>LDO</sub> pin connects to the V<sub>OUT</sub> pin using an internal switch, and the LDO is turned off.

In the second method, the dc-to-dc converter is already running and the LDO is enabled. In this case the 32 cycles are started as soon as the LDO reaches 90 % of its final value. At this time, the V<sub>LDO</sub> and V<sub>OUT</sub> pins are compared, and if within  $\pm 300$  mV the switch-over occurs and the LDO is turned off.

### Benefits of having a switchover circuit

The switchover function is designed to get maximum efficiency out of the dc-to-dc converter. The efficiency for an LDO is very low especially for high input voltages. Using the switchover function we tie any rails connected to V<sub>LDO</sub> through a switch directly to V<sub>OUT</sub>. Once switchover is complete LDO is turned off which saves power. This gives us the maximum efficiency out of the SiC417.

If the LDO output is used to bias the SiC417, then after switchover the V<sub>OUT</sub> self biases the SiC417 and operates in self-powered mode.

Steps to follow when using the on chip LDO to bias the SiC417:

- Always tie the V5V to V<sub>LDO</sub> before enabling the LDO
- Enable the LDO before enabling the switcher
- LDO has a current limit of 85 mA at start-up with 12 V<sub>IN</sub>, so do not connect any load between V<sub>LDO</sub> and ground
- The current limit for the LDO goes up to 200 mA once the V<sub>LDO</sub> reaches 90 % of its final values and can easily supply the required bias current to the IC.

### Switch-over Limitations on V<sub>OUT</sub> and V<sub>LDO</sub>

Because the internal switch-over circuit always compares the V<sub>OUT</sub> and V<sub>LDO</sub> pins at start-up, there are limitations on permissible combinations of V<sub>OUT</sub> and V<sub>LDO</sub>. Consider the case where V<sub>OUT</sub> is programmed to 1.5 V and V<sub>LDO</sub> is programmed to 1.8 V. After start-up, the device would connect V<sub>OUT</sub> to V<sub>LDO</sub> and disable the LDO, since the two voltages are within the  $\pm 300$  mV switch-over window.

To avoid unwanted switch-over, the minimum difference between the voltages for  $V_{OUT}$  and  $V_{LDO}$  should be  $\pm 500$  mV.

It is not recommended to use the switch-over feature for an output voltage less than 3 V since this does not provide sufficient voltage for the gate-source drive to the internal p-channel switch-over MOSFET.

### Switch-Over MOSFET Parasitic Diodes

The switch-over MOSFET contains parasitic diodes that are inherent to its construction, as shown in figure 11.

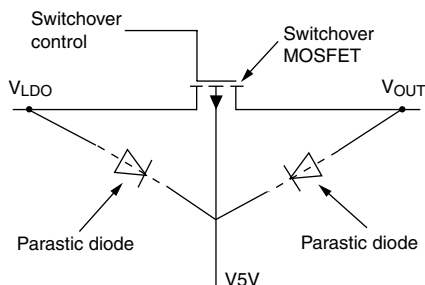


Figure 11 - Switch-over MOSFET Parasitic Diodes

There are some important design rules that must be followed to prevent forward bias of these diodes. The following two conditions need to be satisfied in order for the parasitic diodes to stay off.

- $V_{5V} \geq V_{LDO}$
- $V_{5V} \geq V_{OUT}$

If either  $V_{LDO}$  or  $V_{OUT}$  is higher than  $V_{5V}$ , then the respective diode will turn on and the SiC417 operating current will flow through this diode. This has the potential of damaging the device.

### ENL Pin and $V_{IN}$ UVLO

The ENL pin also acts as the switcher under-voltage lockout for the  $V_{IN}$  supply. The  $V_{IN}$  UVLO voltage is programmable via a resistor divider at the  $V_{IN}$ , ENL and  $A_{GND}$  pins.

ENL is the enable/disable signal for the LDO. In order to implement the  $V_{IN}$  UVLO there is also a timing requirement that needs to be satisfied.

If the ENL pin transitions low within 2 switching cycles and is  $< 1$  V, then the LDO will turn off but the switcher remains on. If ENL goes below the  $V_{IN}$  UVLO threshold and stays above 1 V, then the switcher will turn off but the LDO remains on. The  $V_{IN}$  UVLO function has a typical threshold of 2.6 V on the  $V_{IN}$  rising edge. The falling edge threshold is 2.4 V.

Note that it is possible to operate the switcher with the LDO disabled, but the ENL pin must be below the logic low threshold (0.4 V maximum).

### ENL Logic Control of PWM Operation

When the ENL input is driven above 2.6 V, it is impossible to determine if the LDO output is going to be used to power the device or not. In self-powered operation where the LDO will power the device, it is necessary during the LDO start-up to hold the PWM switching off until the LDO has reached 90 % of the final value. This is to prevent overloading the current-limited LDO output during the LDO start-up.

However, if the switcher was previously operating (with EN/PSV high but ENL at ground, and  $V_{5V}$  supplied externally), then it is undesirable to shut down the switcher.

To prevent this, when the ENL input is taken above 2.6 V (above the  $V_{IN}$  UVLO threshold), the internal logic checks the  $P_{GOOD}$  signal. If  $P_{GOOD}$  is high, then the switcher is already running and the LDO will run through the start-up cycle without affecting the switcher. If  $P_{GOOD}$  is low, then the LDO will not allow any PWM switching until the LDO output has reached 90 % of its final value.

### On-Chip LDO Bias the SiC417

The following steps must be followed when using the onchip LDO to bias the device.

- Connect  $V_{5V}$  to  $V_{LDO}$  before enabling the LDO.
- The LDO has an initial current limit of 85 mA at start-up with 12  $V_{IN}$ , therefore, do not connect any external load to  $V_{LDO}$  during start-up.
- When  $V_{LDO}$  reaches 90 % of its final value, the LDO current limit increases to 200 mA. At this time the LDO may be used to supply the required bias current to the device.
- Switching will be held off until  $V_{LDO}$  reaches regulation.

Attempting to operate in self-powered mode in any other configuration can cause unpredictable results and may damage the device.

### Design Procedure

When designing a switch mode power supply, the input voltage range, load current, switching frequency, and inductor ripple current must be specified.

The maximum input voltage ( $V_{INMAX}$ ) is the highest specified input voltage. The minimum input voltage ( $V_{INMIN}$ ) is determined by the lowest input voltage after evaluating the voltage drops due to connectors, fuses, switches, and PCB traces.

The following parameters define the design:

- Nominal output voltage ( $V_{OUT}$ )
- Static or DC output tolerance
- Transient response
- Maximum load current ( $I_{OUT}$ )

There are two values of load current to evaluate - continuous load current and peak load current. Continuous load current relates to thermal stresses which drive the selection of the inductor and input capacitors. Peak load current determines instantaneous component stresses and filtering requirements such as inductor saturation, output capacitors, and design of the current limit circuit.

The following values are used in this design:

- $V_{IN} = 12 \text{ V} \pm 10 \%$
- $V_{OUT} = 1.05 \text{ V} \pm 4 \%$
- $f_{SW} = 250 \text{ kHz}$
- Load = 10 A maximum

### Frequency Selection

Selection of the switching frequency requires making a trade-off between the size and cost of the external filter components (inductor and output capacitor) and the power conversion efficiency.

The desired switching frequency is 250 kHz which results from using component selected for optimum size and cost. A resistor ( $R_{TON}$ ) is used to program the on-time (indirectly setting the frequency) using the following equation.

$$R_{ton} = \frac{(t_{on} - 10 \text{ ns}) \times V_{IN}}{25 \text{ pF} \times V_{OUT}}$$

To select  $R_{TON}$ , use the maximum value for  $V_{IN}$ , and for  $t_{ON}$  use the value associated with maximum  $V_{IN}$ .

$$t_{ON} = \frac{V_{OUT}}{V_{INMAX} \times f_{SW}}$$

$t_{ON} = 318 \text{ ns}$  at  $13.2 V_{IN}$ ,  $1.05 V_{OUT}$ ,  $250 \text{ kHz}$   
Substituting for  $R_{TON}$  results in the following solution  
 $R_{TON} = 154.9 \text{ k}\Omega$ , use  $R_{TON} = 154 \text{ k}\Omega$ .

### Inductor Selection

In order to determine the inductance, the ripple current must first be defined. Low inductor values result in smaller size but create higher ripple current which can reduce efficiency. Higher inductor values will reduce the ripple current and voltage and for a given DC resistance are more efficient. However, larger inductance translates directly into larger packages and higher cost. Cost, size, output ripple, and efficiency are all used in the selection process.

The ripple current will also set the boundary for power-save operation. The switching will typically enter power-save mode when the load current decreases to 1/2 of the ripple current. For example, if ripple current is 4 A then power-save operation will typically start for loads less than 2 A. If ripple current is set at 40 % of maximum load current, then power-save will start for loads less than 20 % of maximum current. The inductor value is typically selected to provide a ripple current that is between 25 % to 50 % of the maximum load current. This provides an optimal trade-off between cost, efficiency, and transient performance.

During the DH on-time, voltage across the inductor is  $(V_{IN} - V_{OUT})$ . The equation for determining inductance is shown next.

$$L = \frac{(V_{IN} - V_{OUT}) \times t_{ON}}{I_{RIPPLE}}$$

### Example

In this example, the inductor ripple current is set equal to 50 % of the maximum load current. Thus ripple current will be  $50 \% \times 10 \text{ A}$  or 5 A. To find the minimum inductance needed, use the  $V_{IN}$  and  $T_{ON}$  values that correspond to  $V_{INMAX}$ .

$$L = \frac{(13.2 - 1.05) \times 318 \text{ ns}}{5 \text{ A}} = 77 \text{ }\mu\text{H}$$

A slightly larger value of  $0.88 \text{ }\mu\text{H}$  is selected. This will decrease the maximum  $I_{RIPPLE}$  to 4.4 A.

Note that the inductor must be rated for the maximum DC load current plus 1/2 of the ripple current. The ripple current under minimum  $V_{IN}$  conditions is also checked using the following equations.

$$T_{ON\_VINMIN} = \frac{25 \text{ pF} \times R_{TON} \times V_{OUT}}{V_{INMIN}}$$

$$I_{RIPPLE} = \frac{(V_{IN} - V_{OUT}) \times T_{ON}}{L}$$

$$I_{RIPPLE\_VIN} = \frac{(10.8 - 1.05) \times 384 \text{ ns}}{0.88 \text{ }\mu\text{H}} = 4.25 \text{ A}$$

### Capacitor Selection

The output capacitors are chosen based on required ESR and capacitance. The maximum ESR requirement is controlled by the output ripple requirement and the DC tolerance. The output voltage has a DC value that is equal to the valley of the output ripple plus 1/2 of the peak-to-peak ripple. Change in the output ripple voltage will lead to a change in DC voltage at the output.

The design goal is that the output voltage regulation be  $\pm 4 \%$  under static conditions. The internal 500 mV reference tolerance is 1 %. Allowing 1 % tolerance from the FB resistor divider, this allows 2 % tolerance due to  $V_{OUT}$  ripple.

Since this 2 % error comes from 1/2 of the ripple voltage, the allowable ripple is 4 %, or 42 mV for a 1.05 V output.

The maximum ripple current of 4.4 A creates a ripple voltage across the ESR. The maximum ESR value allowed is shown by the following equations.

$$ESR_{MAX} = \frac{V_{RIPPLE}}{I_{RIPPLEMAX}} = \frac{42 \text{ mV}}{4.4 \text{ A}}$$

$$ESR_{MAX} = 9.5 \text{ m}\Omega$$

The output capacitance is usually chosen to meet transient requirements. A worst-case load release, from maximum load to no load at the exact moment when inductor current is at the peak, determines the required capacitance. If the load release is instantaneous (load changes from maximum to zero in  $< 1 \text{ }\mu\text{s}$ ), the output capacitor must absorb all the inductor's stored energy. This will cause a peak voltage on the capacitor according to the following equation.

$$C_{OUTMIN} = \frac{L (I_{OUT} + \frac{1}{2} \times I_{RIPPLEMAX})^2}{(V_{PEAK})^2 - (V_{OUT})^2}$$

Assuming a peak voltage  $V_{PEAK}$  of 1.150 (100 mV rise upon load release), and a 10 A load release, the required capacitance is shown by the next equation.

$$C_{OUTMIN} = \frac{0.88 \text{ }\mu\text{H} (10 + \frac{1}{2} \times 4.4)^2}{(1.15)^2 - (1.05)^2}$$

$$C_{OUTMIN} = 595 \text{ }\mu\text{F}$$

If the load release is relatively slow, the output capacitance can be reduced. At heavy loads during normal switching, when the FB pin is above the 500 mV reference, the DL



output is high and the low-side MOSFET is on. During this time, the voltage across the inductor is approximately  $-V_{OUT}$ . This causes a down-slope or falling  $di/dt$  in the inductor. If the load  $di/dt$  is not much faster than the  $-di/dt$  in the inductor, then the inductor current will tend to track the falling load current. This will reduce the excess inductive energy that must be absorbed by the output capacitor, therefore a smaller capacitance can be used.

The following can be used to calculate the needed capacitance for a given  $di_{LOAD}/dt$ :

Peak inductor current is shown by the next equation.

$$I_{LPK} = I_{MAX} + 1/2 \times I_{RIPPLEMAX}$$

$$I_{LPK} = 10 + 1/2 \times 4.4 = 12.2 \text{ A}$$

$$\text{Rate of change of load current} = di_{LOAD}/dt$$

$$I_{MAX} = \text{maximum load release} = 10 \text{ A}$$

$$C_{OUT} = I_{LPK} \times \frac{L \times \frac{I_{LPK}}{V_{OUT}} - \frac{I_{MAX}}{di_{LOAD}} \times dt}{2 (V_{PK} - V_{OUT})}$$

### Example

$$\text{Load } \frac{di_{LOAD}}{dt} = \frac{2.5 \text{ A}}{\mu s}$$

This would cause the output current to move from 10 A to zero in 4  $\mu s$  as shown by the following equation.

$$C_{OUT} = 12.2 \times \frac{0.88 \mu H \times \frac{12.2}{1.05} - \frac{10}{2.5} \times 1 \mu s}{2 (1.15 - 1.05)}$$

$$C_{OUT} = 379 \mu F$$

Note that  $C_{OUT}$  is much smaller in this example, 379  $\mu F$  compared to 595  $\mu F$  based on a worst-case load release. To meet the two design criteria of minimum 379  $\mu F$  and maximum 9 m $\Omega$  ESR, select two capacitors rated at 220  $\mu F$  and 15 m $\Omega$  ESR.

It is recommended that an additional small capacitor be placed in parallel with  $C_{OUT}$  in order to filter high frequency switching noise.

### Stability Considerations

Unstable operation is possible with adaptive on-time controllers, and usually takes the form of double-pulsing or ESR loop instability.

Double-pulsing occurs due to switching noise seen at the FB input or because the FB ripple voltage is too low. This causes the FB comparator to trigger prematurely after the 250 ns minimum off-time has expired. In extreme cases the noise can cause three or more successive on-times. Double-pulsing will result in higher ripple voltage at the output, but in most applications it will not affect operation.

This form of instability can usually be avoided by providing the FB pin with a smooth, clean ripple signal that is at least 10 mV<sub>p-p</sub>, which may dictate the need to increase the ESR of the output capacitors. It is also imperative to provide a proper PCB layout as discussed in the Layout Guidelines section.

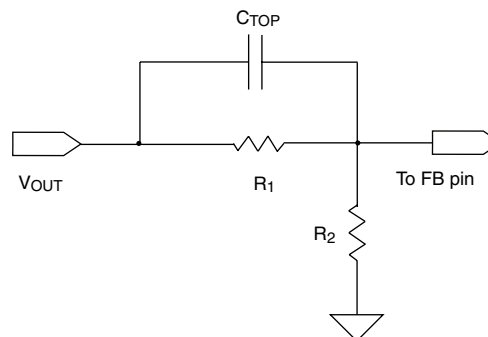


Figure 13 - Capacitor Coupling to FB Pin

Another way to eliminate doubling-pulsing is to add a small ( $\sim 10$  pF) capacitor across the upper feedback resistor, as shown in figure 13. This capacitor should be left unpopulated until it can be confirmed that double-pulsing exists. Adding the  $C_{TOP}$  capacitor will couple more ripple into FB to help eliminate the problem. An optional connection on the PCB should be available for this capacitor.

ESR loop instability is caused by insufficient ESR. The details of this stability issue are discussed in the ESR Requirements section. The best method for checking stability is to apply a zero-to-full load transient and observe the output voltage ripple envelope for overshoot and ringing. Ringing for more than one cycle after the initial step is an indication that the ESR should be increased.

One simple way to solve this problem is to add trace resistance in the high current output path. A side effect of adding trace resistance is output decreased load regulation.

### ESR Requirements

A minimum ESR is required for two reasons. One reason is to generate enough output ripple voltage to provide 10 mV<sub>p-p</sub> at the FB pin (after the resistor divider) to avoid double-pulsing.

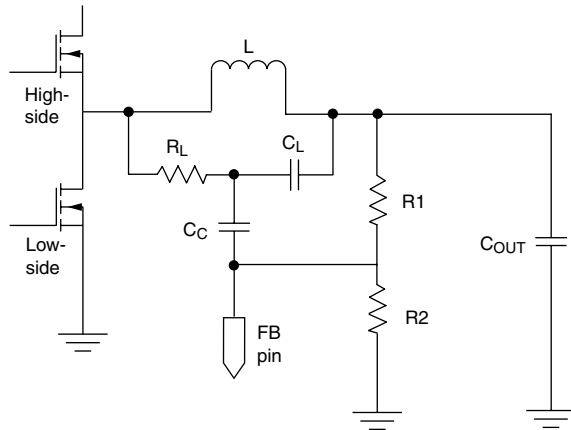
The second reason is to prevent instability due to insufficient ESR. The on-time control regulates the valley of the output ripple voltage. This ripple voltage is the sum of the two voltages. One is the ripple generated by the ESR, the other is the ripple due to capacitive charging and discharging during the switching cycle. For most applications the minimum ESR ripple voltage is dominated by the output capacitors, typically SP or POSCAP devices. For stability the ESR zero of the output capacitor should be lower than approximately one-third the switching frequency. The formula for minimum ESR is shown by the following equation.

$$ESR_{MIN} = \frac{3}{2 \times \pi \times C_{OUT} \times f_{SW}}$$

For applications using ceramic output capacitors, the ESR is normally too small to meet the above ESR criteria. In these applications it is necessary to add a small virtual ESR network composed of two capacitors and one resistor, as shown in figure 14. This network creates a ramp voltage



across  $C_L$ , analogous to the ramp voltage generated across the ESR of a standard capacitor. This ramp is then capacitive-coupled into the FB pin via capacitor  $C_C$ .



**Figure 14 - Virtual ESR Ramp Current**

### Dropout Performance

The output voltage adjusts range for continuous-conduction operation is limited by the fixed 250 ns (typical) minimum off-time of the one-shot. When working with low input voltages, the duty-factor limit must be calculated using worst-case values for on and off times. The duty-factor limitation is shown by the next equation.

$$\text{DUTY} = \frac{T_{\text{ON(MIN)}}}{T_{\text{ON(MIN)}} \times T_{\text{OFF(MAX)}}$$

The inductor resistance and MOSFET on-state voltage drops must be included when performing worst-case dropout duty-factor calculations.

### System DC Accuracy ( $V_{\text{OUT}}$ Controller)

Three factors affect  $V_{\text{OUT}}$  accuracy: the trip point of the FB error comparator, the ripple voltage variation with line and load, and the external resistor tolerance. The error comparator off set is trimmed so that under static conditions it trips when the feedback pin is 500 mV, 1 %.

The on-time pulse from the SiC417 in the design example is calculated to give a pseudo-fixed frequency of 250 kHz. Some frequency variation with line and load is expected. This variation changes the output ripple voltage. Because constant on-time converters regulate to the valley of the output ripple,  $\frac{1}{2}$  of the output ripple appears as a DC regulation error. For example, if the output ripple is 50 mV with  $V_{\text{IN}} = 6$  V, then the measured DC output will be 25 mV above the comparator trip point. If the ripple increases to 80 mV with  $V_{\text{IN}} = 25$  V, then the measured DC output will be 40 mV above the comparator trip. The best way to minimize this effect is to minimize the output ripple.

To compensate for valley regulation, it may be desirable to use passive droop. Take the feedback directly from the output side of the inductor and place a small amount of trace resistance between the inductor and output capacitor.

This trace resistance should be optimized so that at full load the output droops to near the lower regulation limit. Passive droop minimizes the required output capacitance because the voltage excursions due to load steps are reduced as seen at the load.

The use of 1 % feedback resistors contributes up to 1 % error. If tighter DC accuracy is required, 0.1 % resistors should be used.

The output inductor value may change with current. This will change the output ripple and therefore will have a minor effect on the DC output voltage. The output ESR also affects the output ripple and thus has a minor effect on the DC output voltage.

### Switching Frequency Variations

The switching frequency will vary depending on line and load conditions. The line variations are a result of fixed propagation delays in the on-time one-shot, as well as unavoidable delays in the external MOSFET switching. As  $V_{\text{IN}}$  increases, these factors make the actual DH on-time slightly longer than the ideal on-time. The net effect is that frequency tends to falls slightly with increasing input voltage. The switching frequency also varies with load current as a result of the power losses in the MOSFETs and the inductor. For a conventional PWM constant-frequency converter, as load increases the duty cycle also increases slightly to compensate for IR and switching losses in the MOSFETs and inductor.

A constant on-time converter must also compensate for the same losses by increasing the effective duty cycle (more time is spent drawing energy from  $V_{\text{IN}}$  as losses increase). The on-time is essentially constant for a given  $V_{\text{OUT}}/V_{\text{IN}}$  combination, to off set the losses the off-time will tend to reduce slightly as load increases. The net effect is that switching frequency increases slightly with increasing load.

## SiC417 EVALUATION BOARD SCHEMATIC

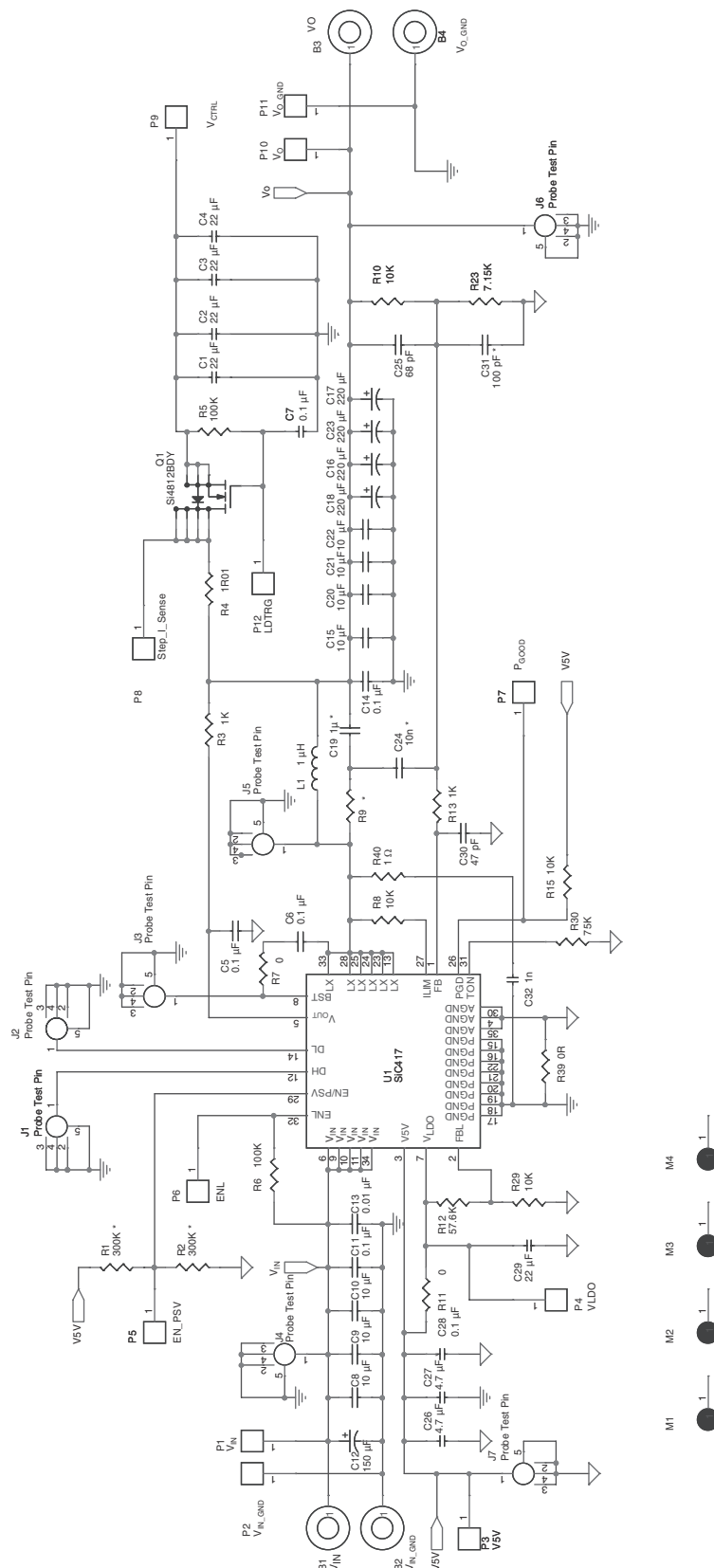


Figure 15. Evaluation Board Schematic

**BILL OF MATERIALS**

Reference Designator	Value	Voltage	Footprint	Part Number	Manufacturer
B1, B2, B3, B4			SOLDER-BANANA	575-4	Keystone
C29	22 $\mu$ F	16 V	SM/C_1210	GRM32ER71C226ME18L	Murata
C5	0.1 $\mu$ F	10 V	SM/C_0402	C0402C104K8RAC7867	Vishay
C6	0.1 $\mu$ F	10 V	SM/C_0805	C0402C104K8RAC7867	Vishay
C11, C14, C28	0.1 $\mu$ F	50 V	SM/C_0603	VJ0603Y104KXACW1BC	Vishay
C8, C9, C10	10 $\mu$ F	25 V	SM/C_1210	TMK325B7106MN-T	Taiyo Yuden
C12	150 $\mu$ F	35 V	D8X11.5-D0.6X3.5	EEU-FM1V151	Panasonic
C13	0.01 $\mu$ F	50 V	SM/C_0402	VJ0402Y103KXACW1BC	Vishay
C15, C20, C21, C22	10 $\mu$ F	16 V	SM/C_1206	GRM31CR71C106KAC7L	
C16, C17, C18, C23	220 $\mu$ F	10 V	595D-D	593D227X0010E2TE3	Vishay
C19	1 $\mu$ F		SM/C_0603		
C24	10 nF		SM/C_0603		
C25	100 pF	50 V	SM/C_0402	VJ0402A101JXACW1BC	Vishay
C26	4.7 $\mu$ F	10 V	SM/C_0805	LMK212B7475KG-T	Taiyo Yuden
C27	4.7 $\mu$ F	10 V	SM/C_0805	LMK212B7475KG-T	Taiyo Yuden
C30	47 pF		SM/C_0402	VJ0402A470JXACW1BC	
C31	100 pF		SM/C_0402	VJ0402Y101KXQCW1BC	Vishay
C32	1000 pF	50 V	SM/C_0805	VJ0805A102KXA	Vishay
J1, J2, J3, J4, J5, J6, J7	Probe test pin		Lecroy Probe Pin	PK007-015	Lecroy
L1	1 $\mu$ H		IHLP4040	IHLP4040DZER1R0M01	Vishay
M1, M2, M3, M4	M HOLE2		Stacking Spacer	8834	Keystone
P1, P2, P3, P4, P5, P6, P7, P8, P9, P10, P11, P12	V <sub>IN</sub> , GND etc.		Probe Hook	1540-2	Keystone
R1	300K	50 V	SM/C_0603	CRCW060310K0FKEA	Vishay
R2	300K	50 V	SM/C_0603	CRCW06030000FKEA	Vishay
R3, R13	1K		SM/C_0402	CRCW04021K00FKED	Vishay
R6	100K	50 V	SM/C_0603	CRCW0603100KFKEA	Vishay
R7, R11	0R		SM/C_0603	CRCW06030000Z0EA	Vishay
R8, R10, R15, R29	10K		SM/C_0603	MCR03EZHF1002	ROHM
R9			SM/C_0603		
R12	57.6K		SM/C_0603	CRCW060357K6FKEA	Vishay
R23	7.15K		SM/C_0603	CRCW06037K15FKEA	Vishay
R30	75K		SM/C_0603	CRCW0603154KFKEA	Vishay
R39	0R		SM/C_0402	CRCW04020000Z0ED	Vishay
R40	1 $\Omega$		SM/C_0805	CRCW08051R00FNEA	Vishay
U1	SiC417		QFN5X5_32 leads + 3 pads		Vishay
<b>Optional Ciciutry for Transient Response Testing</b>					
Q1	Si4812BDY	30 V	SO-8	Si4812BDY	Vishay
R4	1R01	200 V	C_2512	CRCW25121R00FKTA	Vishay
R5	100K	50 V	SM/C_0603	CRCW0603100KFKEA	Vishay
C7	0.1 $\mu$ F	50 V	SM/C_0603	VJ0603Y104KXACW1BC	Vishay
C1, C2, C3, C4	22 $\mu$ F	16 V	SM/C_1210	GRM32ER71C226ME18L	Murata

## PCB LAYOUT OF THE EVALUATION BOARD

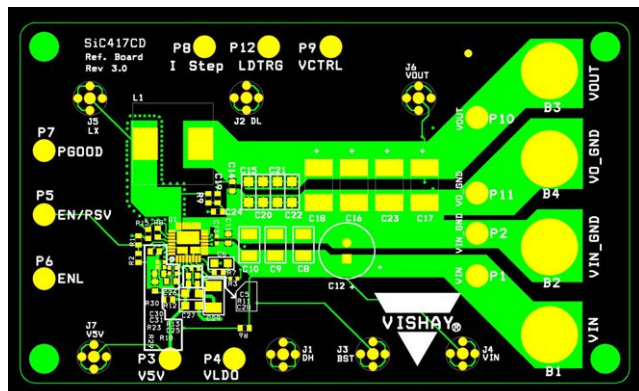


Figure 16. PCB Layout - Top Layer

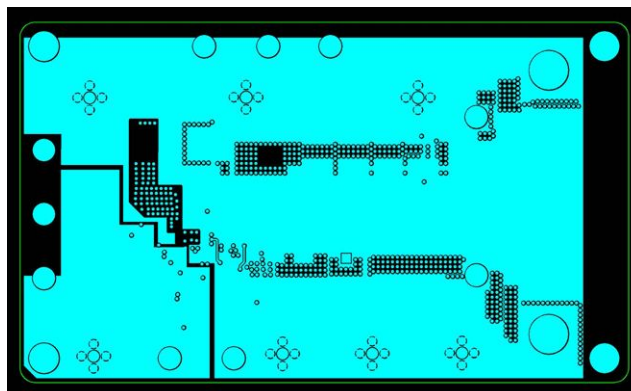


Figure 17. PCB Layout - MidLayer1

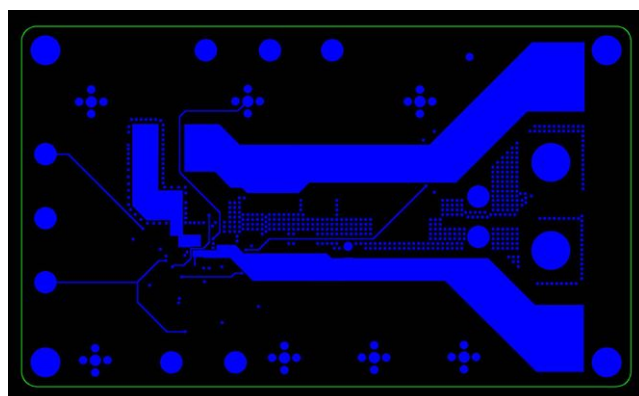


Figure 18. PCB Layout - MidLayer2

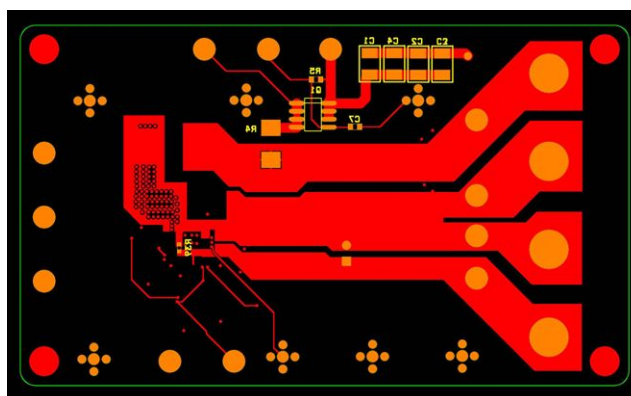
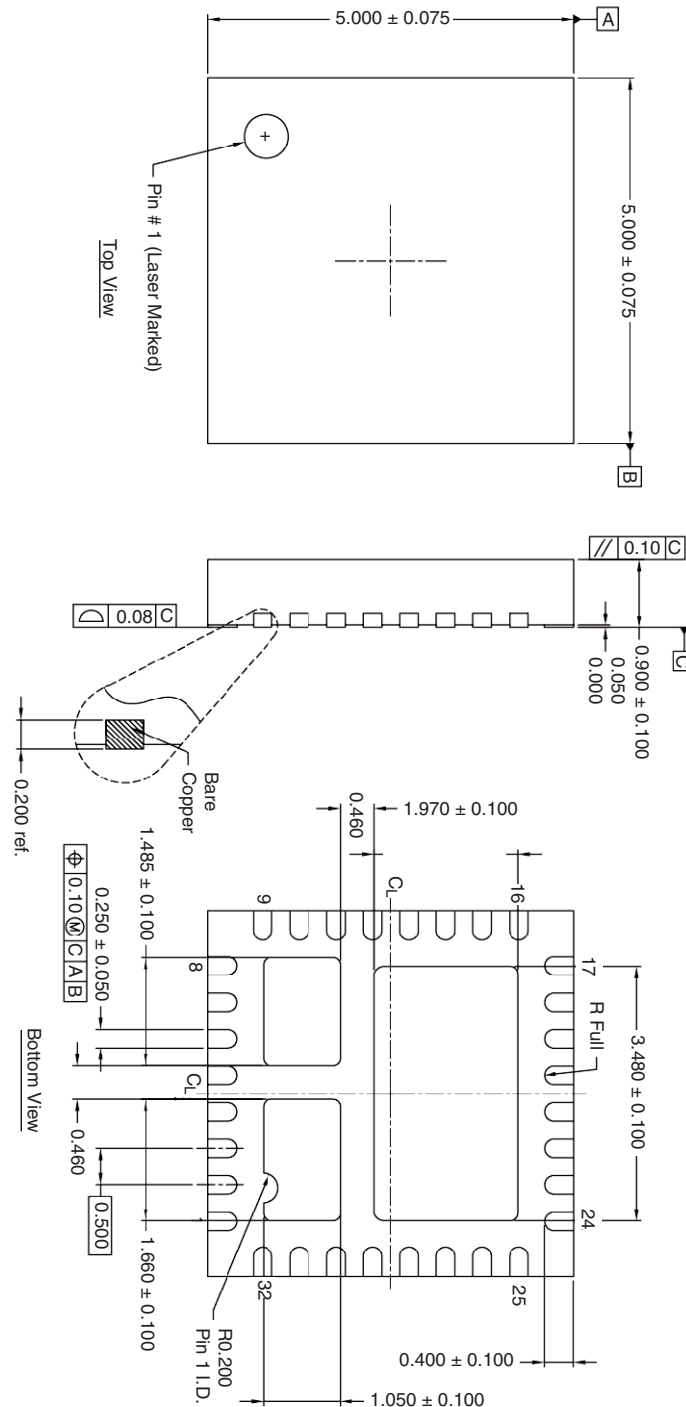
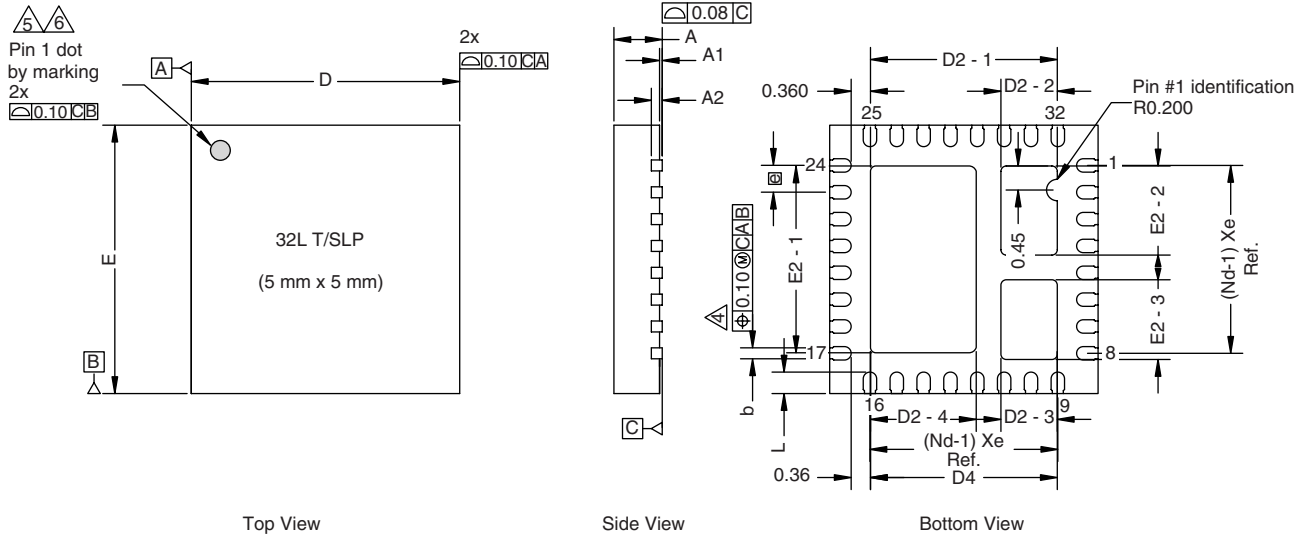



Figure 19. PCB Layout - Bottom Layer

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## PowerPAK® MLP55-32L CASE OUTLINE



DIM	MILLIMETERS			INCHES		
	MIN.	NOM.	MAX.	MIN.	NOM.	MAX.
A	0.80	0.85	0.90	0.031	0.033	0.035
A1 <sup>(8)</sup>	0.00	-	0.05	0.000	-	0.002
A2	0.20 REF.			0.008 REF.		
b <sup>(4)</sup>	0.20	0.25	0.30	0.078	0.098	0.011
D	5.00 BSC			0.196 BSC		
	0.50 BSC			0.019 BSC		
E	5.00 BSC			0.196 BSC		
L	0.35	0.40	0.45	0.013	0.015	0.017
N <sup>(3)</sup>	32			32		
Nd <sup>(3)</sup>	8			8		
Ne <sup>(3)</sup>	8			8		
D2 - 1	3.43	3.48	3.53	0.135	0.137	0.139
D2 - 2	1.00	1.05	1.10	0.039	0.041	0.043
D2 - 3	1.00	1.05	1.10	0.039	0.041	0.043
D2 - 4	1.92	1.97	2.02	0.075	0.077	0.079
E2 - 1	3.43	3.48	3.53	0.135	0.137	0.139
E2 - 2	1.61	1.66	1.71	0.063	0.065	0.067
E2 - 3	1.43	1.48	1.53	0.056	0.058	0.060
ECN: T-08957-Rev. A, 29-Dec-08 DWG: 5983						

### Notes

- Use millimeters as the primary measurement.
- Dimensioning and tolerances conform to ASME Y14.5M. - 1994.
- N is the number of terminals.  
Nd is the number of terminals in X-direction and Ne is the number of terminals in Y-direction.
- Dimension b applies to plated terminal and is measured between 0.20 mm and 0.25 mm from terminal tip.
- The pin #1 identifier must be existed on the top surface of the package by using indentation mark or other feature of package body.
- Exact shape and size of this feature is optional.
- Package warpage max. 0.08 mm.
- Applied only for terminals.





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Телефон: 8 (812) 309-75-97 (многоканальный)

Факс: 8 (812) 320-03-32

Электронная почта: [ocean@oceanchips.ru](mailto:ocean@oceanchips.ru)

Web: <http://oceanchips.ru/>

Адрес: 198099, г. Санкт-Петербург, ул. Калинина, д. 2, корп. 4, лит. А