



KMY22



KMY20



KMZ20

## KMY\_KMZ

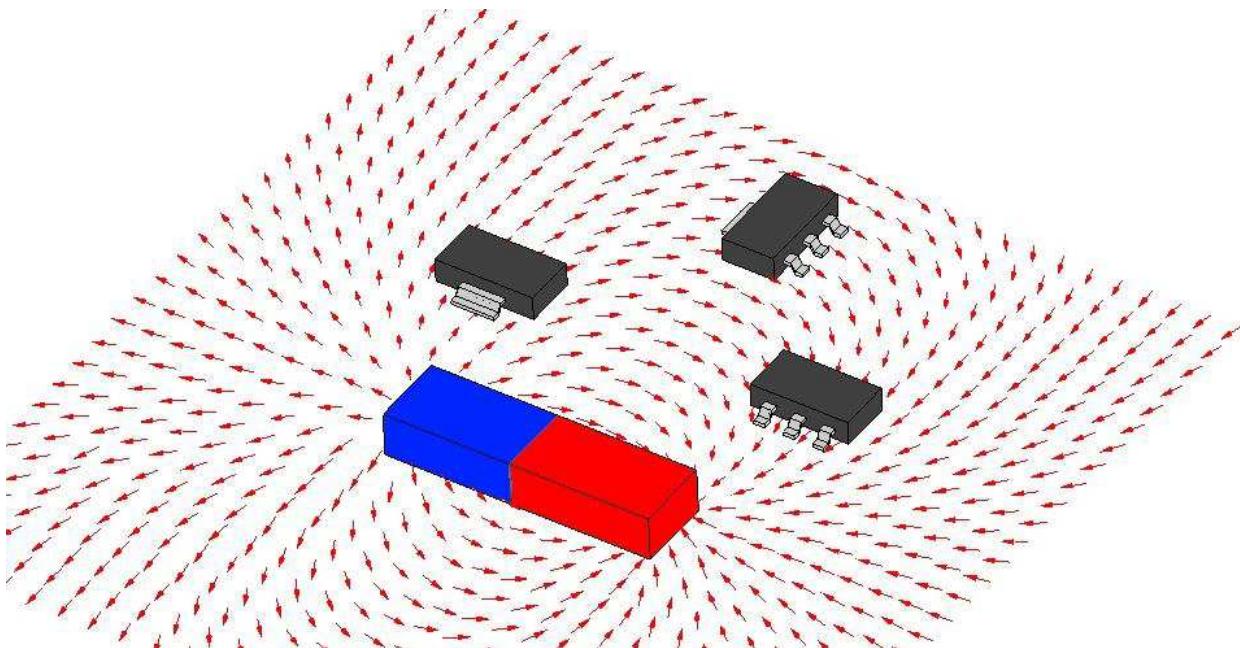
Linear Magnetic Field Sensors

### SPECIFICATIONS

- ♦ AMR sensor
- ♦ Very high sensitivity
- ♦ Almost no hysteresis
- ♦ Various applications
- ♦ Available with internal magnet
- ♦ Available in several packages

Due to its featured properties - high sensitivity and almost no hysteresis – the **KMY / KMZ** sensors are used in a wide range of applications, like magnetic field measurement, revolution counters, proximity detecting, and position measurement.

An uniaxial linear magnetic field will generate a linear output within the specified magnetic field range.



## FEATURES

- ◆ Output proportional to magnetic field strength with very high sensitivity
- ◆ Very small hysteresis
- ◆ Large operating temperature range, from -40°C up to +150 °C
- ◆ Highly reliable
- ◆ With / without internal magnet

## APPLICATIONS

- ◆ Detection of very weak magnetic fields, like earth magnetic field, or field generated by small magnetic particles
- ◆ Detection of objects that distort non-local magnetic fields
- ◆ Revolution measurement on ferromagnetic gears
- ◆ Contactless switch
- ◆ Contactless displacement / position sensor

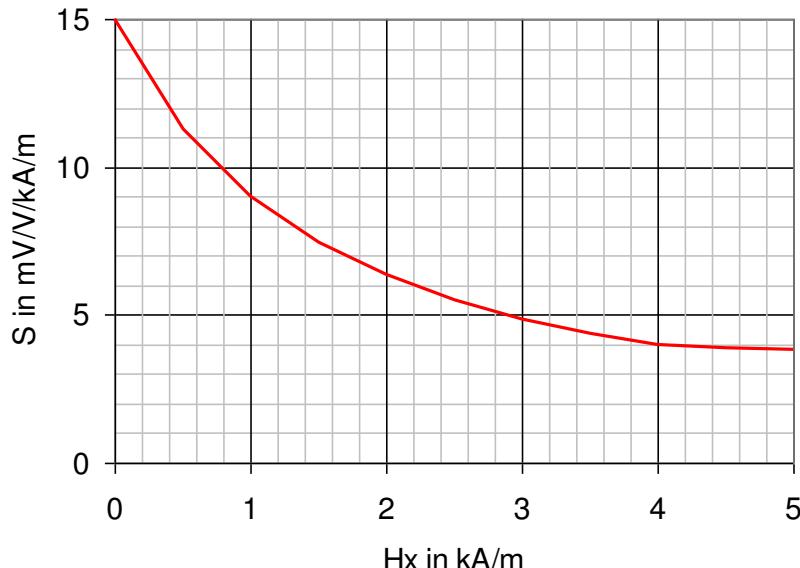
## DESCRIPTION

An uniaxial linear magnetic field (in y-direction) will generate a linear output within the specified magnetic field range. The sensor is available in two types: the **KMY 20 M**, **KMY 21 M** and **KMZ 20 M** sensor types contain intrinsic magnets which provide an auxiliary magnetic field (in x-direction) at the sensor die which prevents magnetic domains from flipping irregularly.

Auxiliary Field Dependence

If the dies **MR174B** or the components **KMY22**, **KMY20S** or **KMZ20S** are used, the auxiliary field has to be provided by the user. The dependence of the sensitivity with auxiliary field strength is depicted in the figure aside.

**Figure 1:** Sensitivity dependence on auxiliary field strength



Auxiliary field strengths below  $H_x < 1.5 \text{ kA/m}$  are not recommended, as small disturbances may flip the magnetization domains. Sometimes, the magnetic conditions in the application may provide enough  $H_x$  bias field stabilization. MEAS Germany can provide advice for customer specific magnet arrangements.

If a bias field  $H_x$  is not applied or

$H_x$  is less than  $2.5 \text{ kA/m}$ , the sensor may be used only in a limited field range  $H_y$ , depending on the present total bias field  $H_{x,\text{tot}}$ . In this case, it is strongly recommended to ' premagnetize' the sensor, i.e. align all magnetic domains consistently, prior to the measurement.

$H_{x,\text{tot}}$  is the sum of all acting magnetic fields in x direction at the sensor die.

**Do not use the sensor outside the safe operating area.** Leaving the save operating area can destroy an existing premagnetization and therefore will lead to unrepeatable sensor signals.

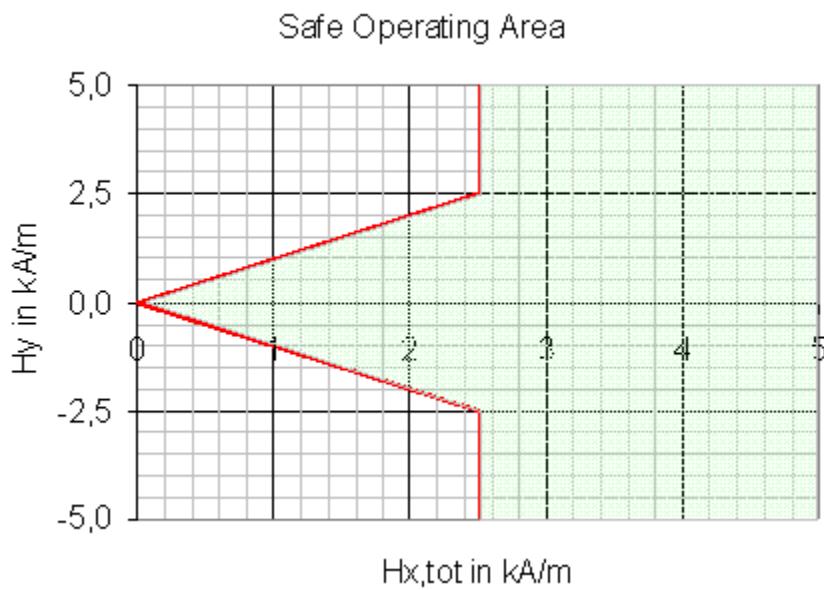


Figure 2: Safe operating area

## CHARACTERISTIC VALUES / SENSOR SPECIFICATIONS

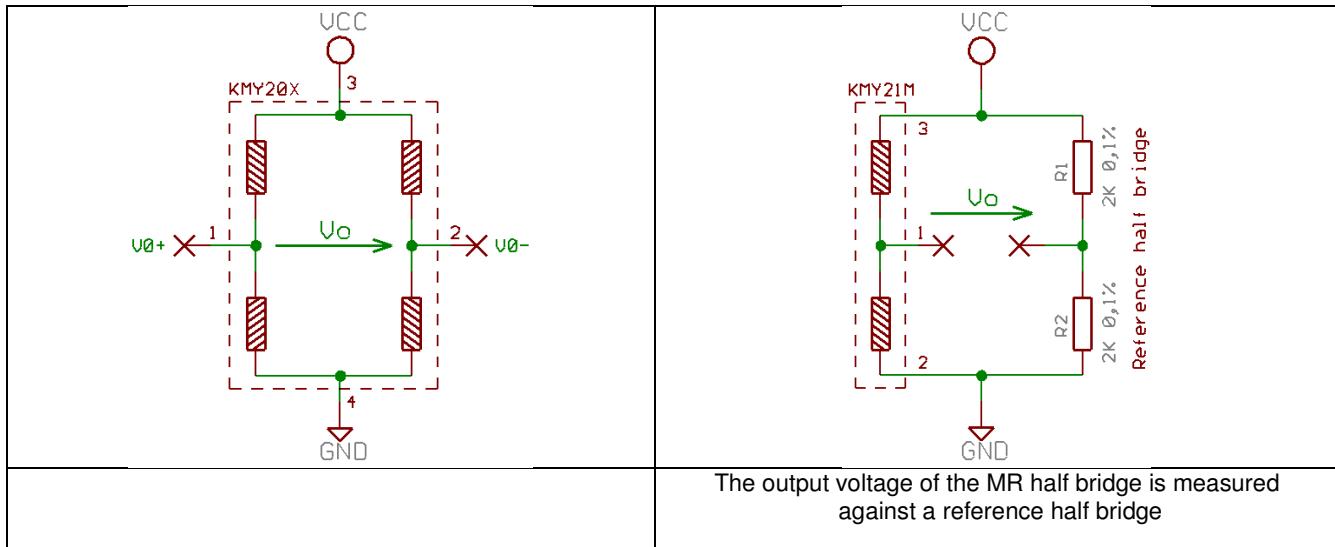
Parameter	Symbol	Condition	Min	Typ	Max	Unit
<b>Operating Limits</b>						
max. supply voltage	$V_{cc,\text{max}}$				<b>10</b>	V
max. current	$I_{cc,\text{max}}$				<b>9</b>	mA
operating temperature	$T_{op}$		<b>-40</b>		<b>+150</b>	→C
storage temperature	$T_{st}$		<b>-40</b>		<b>+150</b>	→C
<b>General Sensor Specifications</b>						
TC of amplitude	TCSV	Condition A, C		<b>-0.35</b>		%/K
TC of resistance	TCBR	Condition A, C		<b>+0.35</b>		%/K
TC of offset	TCVoff	Condition A, C	<b>-4</b>	<b>0</b>	<b>+4</b>	$\mu\text{V}/\text{V}/\text{K}$
<b>Sensor Specifications KMY 20 S, KMZ 20 S, KMY 22 (T=25 °C, <math>H_x=3 \text{ kA/m}</math> externally)</b>						
Supply voltage	$V_{cc}$	Condition A, B		<b>5</b>		V
Bridge resistance	$R_b$	Condition A, B	<b>1200</b>	<b>1700</b>	<b>2200</b>	~
Output signal range	$\Delta V_0/V_{cc}$	Condition A, B	<b>16</b>	<b>20</b>	<b>24</b>	mV/V
Offset voltage	$V_{off}/V_{cc}$	Condition A, B	<b>-1</b>	<b>0</b>	<b>+1</b>	mV/V
Sensitivity	$S$	Condition A, B	<b>3.7</b>	<b>4.7</b>	<b>5.7</b>	$\text{mV}/\text{V}/\text{kA}/\text{m}$
Hysteresis	$V_H/V_{cc}$	Condition A, B	-	-	<b>50</b>	$\mu\text{V}/\text{V}$

<b>Sensor Specifications KMY 20 M, KMZ 20 M (T=25 °C, Hx=1.5±0.5 kA/m internally)</b>						
Supply voltage	V <sub>cc</sub>	Condition A, B		5		V
Bridge resistance	R <sub>b</sub>	Condition A, B	1200	1700	2200	~
Output signal range	±V <sub>0</sub> /V <sub>cc</sub>	Condition A, B	16	20	24	mV/V
Offset voltage	V <sub>off</sub> /V <sub>cc</sub>	Condition A, B	-1.5	0	+1.5	mV/V
Sensitivity	S	Condition A, B	4	5.5	7	mV/V/kA/m
Hysteresis	V <sub>H</sub> /V <sub>cc</sub>	Condition A, B	-	-	50	µV/V
<b>Sensor Specifications KMY 21 M (T=25 °C, Hx=2.5±1.0 kA/m internally)</b>						
Supply voltage	V <sub>cc</sub>	Condition A, B		5		V
Bridge resistance	R <sub>b</sub>	Condition A, B	1100	1500	1900	~
Output signal range	±V <sub>0</sub> /V <sub>cc</sub>	Condition A, B	8	9.5	12	mV/V
Offset voltage	V <sub>off</sub> /V <sub>cc</sub>	Condition A, B	48	50	52	%Vcc
Sensitivity	S	Condition A, B	2.05	2.50	3.10	mV/V/kA/m
Hysteresis	V <sub>H</sub> /V <sub>cc</sub>	Condition A, B	-	-	50	µV/V

Stress above one or more of the limiting values may cause permanent damage to the device. Exposure to limiting values for extended periods may affect device reliability.

## MEASUREMENT CONDITIONS

Parameter	Symbol	Unit	Condition
<b>Condition A: Set Up Conditions</b>			
Ambient temperature	T	°C	23±5 Measurement results are extrapolated to 25°C by using the given temperature coefficients
Supply voltage	V <sub>cc</sub>	V	5
Output voltage	V <sub>O</sub> V <sub>O</sub> /V <sub>cc</sub>	mV mV/V	V <sub>O</sub> =(V <sub>O+</sub> -V <sub>O-</sub> ) Output voltages are also given independently on supply voltage: example: V <sub>O</sub> /V <sub>cc</sub> =(V <sub>O+</sub> -V <sub>O-</sub> )/V <sub>cc</sub> ; measure MR half bridge against reference half bridge
Reference half bridge			2* 2 k, 0.1% (KMY21M only)
for full bridge sensors (KMY20S, KMY20M, KMY22, KMZ20S, KMZ20M)		for half bridge sensors (KMY 21 M)	

**Condition B: Sensor Specifications (T=25 °C, S-Type: Hx=3.0±0.5 kA/m)**

Output voltage range	$\Delta V_O/V_{cc}$	mV/V	$H_y \bullet 0 \dots 7 kA/m; \Delta V_O \bullet V_{o,max} - V_{o,min}$
Offset voltage	$V_{off}/V_{cc}$	mV/V	$H_y \bullet 0; V_{off} \bullet V_o \bullet H_y$
Sensitivity	S	(mV/V)/(kA/m)	$H_y \bullet 1 kA/m; S : \frac{V_0}{2} \bullet H_y \bullet V_0 \bullet H_y$
Hysteresis	$V_H/V_{cc}$	$\mu V/V$	$H_y \text{ in } kA/m$ $(V_0(H_y \bullet 0; H_y \bullet 1) \bullet V_0(H_y \bullet 0; H_y \bullet 1)) / V_{cc}$

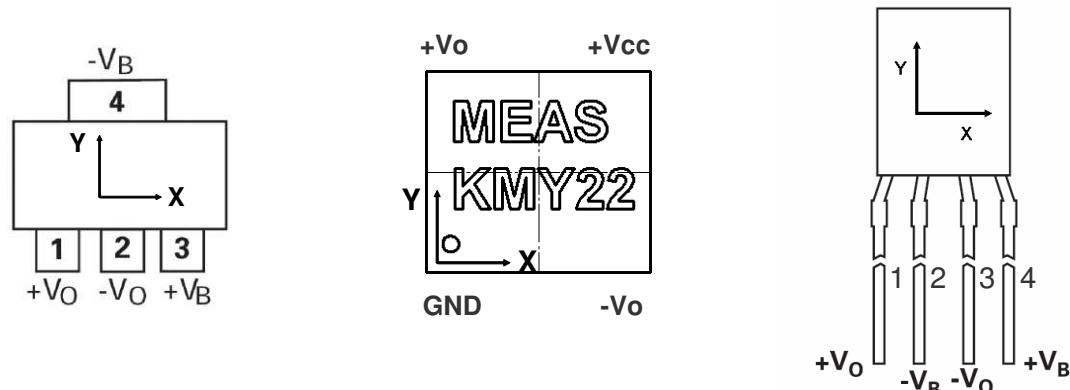
**Condition C: Sensor Specifications (reference temperatures T=-25°C, +125°C)**

Ambient temperatures	T	°C	$T_1=-25^\circ\text{C}, T_0=+25^\circ\text{C}, T_2=+125^\circ\text{C}$
TC of amplitude	$TCSV$	%/K	$TCV \bullet \frac{1}{(T_2 - T_1)} \frac{\Delta V_0 / V_{cc}(T_2) - \Delta V_0 / V_{cc}(T_1)}{\Delta V_0 / V_{cc}(T_1)} \bullet 100\%$
TC of resistance	$TCBR$	%/K	$TCR \bullet \frac{1}{(T_2 - T_1)} \frac{R(T_2) - R(T_1)}{R(T_1)} \bullet 100\%$
TC of offset	$TCVoff$	$(\mu V/V)/K$	$TCVoff \bullet \frac{V_{off}(T_2) - V_{off}(T_1)}{(T_2 - T_1)}$

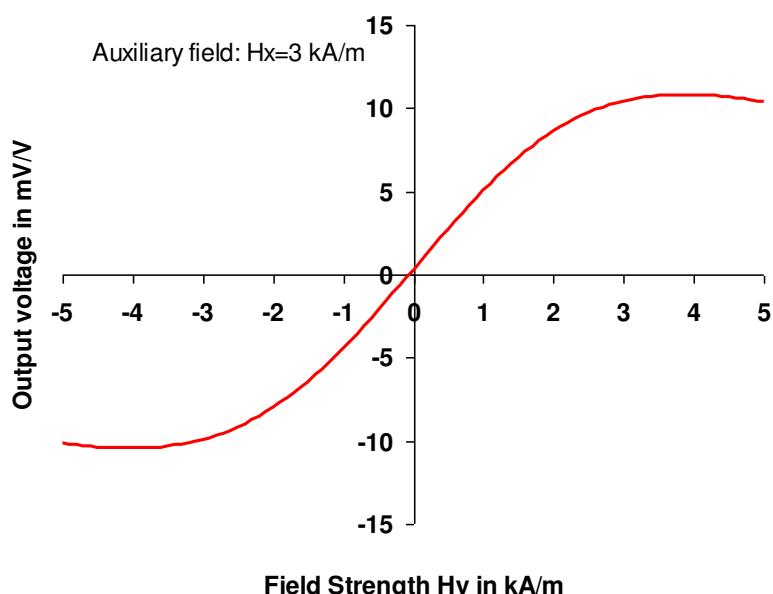
## SENSOR MODELS

### KMY 20 / KMY 22 / KMZ 20

The KMY and KMZ sensors are highly sensitive magnetic field sensors which utilize the anisotropic magneto resistance effect. The KMY 20 and KMZ 20 sensors contain a Wheatstone bridge.



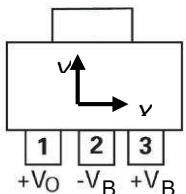
**Figure 3:** Pad annotation and definition of field direction for KMY & KMZ



**Figure 4:** Characteristic output curve of KMY 20 S / KMY 22 / KMZ 20 S for an auxiliary field strength of  $H_x=3 \text{ kA/m}$

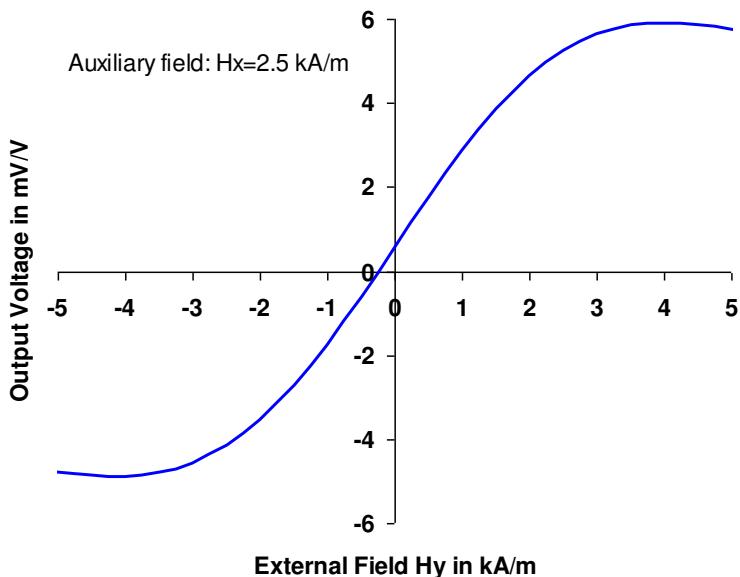
## KMY 21

In contrast to the KMY20 sensor products, the **KMY 21 M** consists of a half bridge, making the sensor well suited for dynamic measurements.

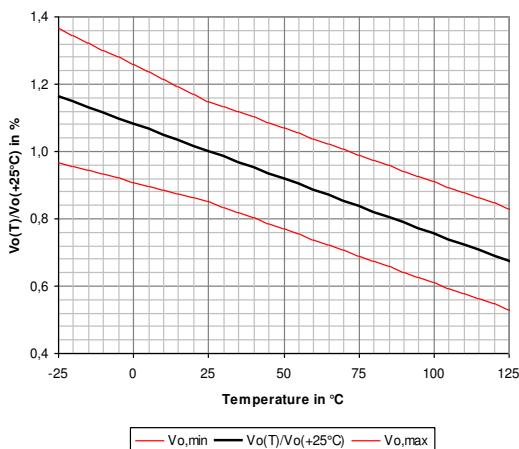


It contains an internal magnet, which provides an auxiliary field of approx. 2.5 kA/m.

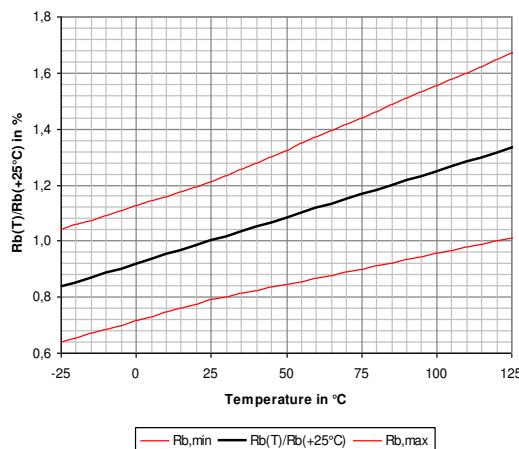
**Figure 5:** Characteristic curve for KMY21M



## TEMPERATURE DEPENDENCIES



**Figure 6:** signal amplitude related to room temperature value

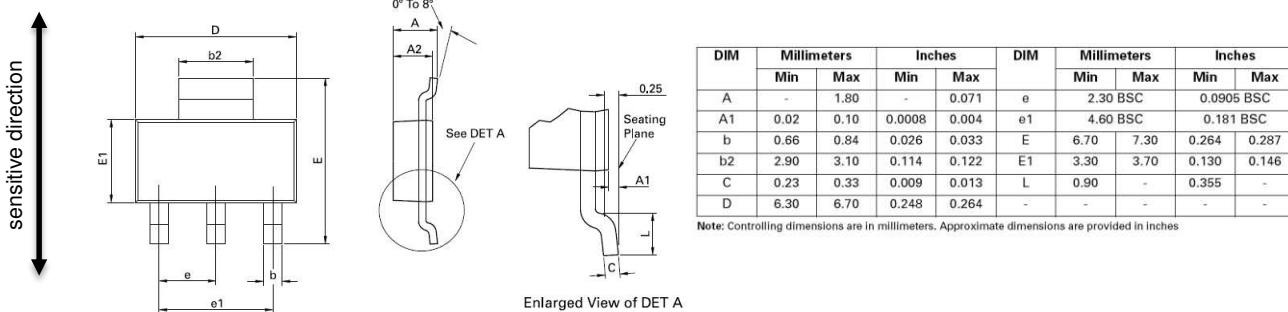


**Figure 7:** bridge resistance related to room temperature value

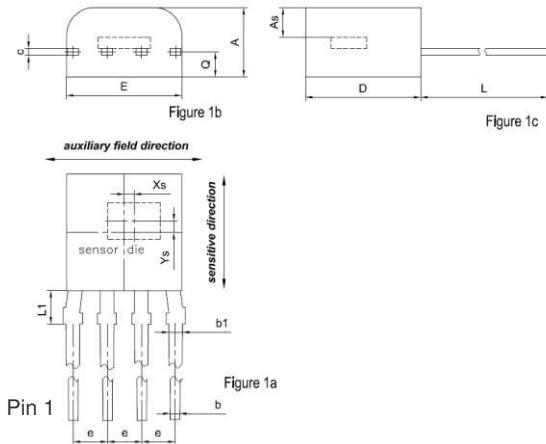
## PACKAGES

## SOT223

Recommended solder reflow process for all packages according to IPC/JEDEC J-STD-020D (Pb-Free Process)



## E-LINE 4 PIN

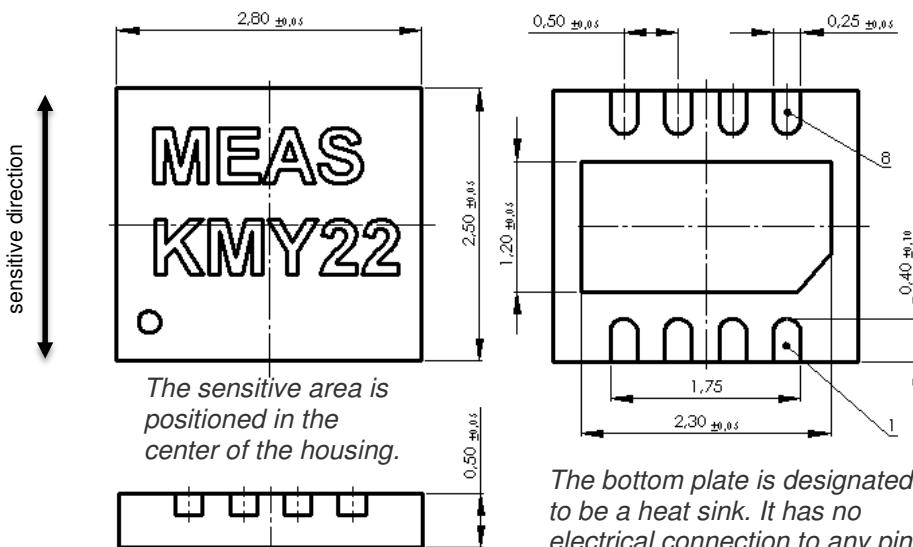


DIE POS.	Millimeter			Inches		
	KMZ20S	KMZ20M	tolerances	KMZ20S	KMZ20M	tolerances
Xs	+0.05	+0.05	+/-0.10	+0.002	+0.002	+/-0.004
Ys	+0.50	+0.50	+/-0.10	+0.02	+0.02	+/-0.004
As	1.05	1.05	+/-0.10	0.041	0.041	+/-0.004

DIM	Millimeter			Inches		
	min.	typ.	max.	min.	typ.	max.
A	2.4		2.8	0.094		0.110
b	0.35		0.48	0.0138		0.0189
b1	0.45		0.60	0.0178		0.024
c	0.25		0.35	0.0098		0.0138
D	4.0		4.4	0.157		0.173
E	3.8		4.4	0.150		0.173
L	12.0		14.0	0.472		0.551
e	NOM. 1.25			NOM. 0.049		
L1	1.1		1.3	0.043		0.051

## UTDFN8 2.5X2.8 MM



**ORDERING CODE**

DEVICE	DIE	PACKAGE	INTERNAL MAGNET	PART NUMBER
<b>KMY20 S</b>	full bridge	SOT-223	NO	<b>G-MRCO-006</b>
<b>KMY20 M</b>	full bridge	SOT-223	YES	<b>G-MRCO-001</b>
<b>KMY21 M</b>	half bridge	SOT-223	YES	<b>G-MRCO-011</b>
<b>KMZ20 S</b>	full bridge	E-Line	NO	<b>G-MRCO-007</b>
<b>KMZ20 M</b>	full bridge	E-Line	YES	<b>G-MRCO-003</b>
<b>KMY22</b>	full bridge	UTDFN8	NO	<i>on request</i>

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