

# **AVR ONE!**

---

## **Quick-start Guide**

EVK1100 + Windows®



---

**Section 1**

Introduction.....	1-1
1.1 General .....	1-1
1.2 Requirements.....	1-1

---

**Section 2**

Quick-start guide (short version) .....	2-1
2.1 Install Hardware and software .....	2-1
2.2 Create a demonstration project .....	2-1
2.3 Configure target MCU for a debug session using trace .....	2-1
2.4 Start the debug session and configure AVR32 Studio 2.5 for trace.....	2-2
2.5 Start the trace debug session .....	2-2

---

**Section 3**

Hardware preparation.....	3-1
---------------------------	-----

---

**Section 4**

Software Installation.....	4-1
4.1 Download the software .....	4-1
4.2 Download the two installation files to your disk.....	4-2
4.3 Install AVR32 GNU Toolchain.....	4-2
4.4 Install AVR32 Studio 2.5.....	4-8
4.5 Connect the AVR ONE! to power and USB host .....	4-11
4.6 Install AVR ONE! Driver.....	4-12

---

**Section 5**

5.1 Connect the AVR ONE! to the EVK1100 .....	5-1
5.2 Connect the EVK1100 to power.....	5-2

---

**Section 6**

Create demo application .....	6-1
6.1 Start AVR32 Studio.....	6-1
6.2 Configure adapter and target .....	6-2
6.2.1 Add and configure the adapter (AVR ONE!).....	6-3
6.2.2 Configure target board and MCU.....	6-5
6.2.3 Target MCU Chip erase.....	6-7
6.3 Create a demonstration project .....	6-8
6.4 Configure AVR32 Studio for a debug session using trace.....	6-11
6.4.1 Create a new debug launch configuration .....	6-12
6.4.2 Configure the target trace module for program trace.....	6-13
6.4.3 Configure the target trace module for data trace .....	6-16
6.5 Start a debug session and configure the debugger for trace .....	6-17



6.5.1 Add start and stop trace-points..... 6-19

6.6 Start the trace debug session ..... 6-23

6.7 Modify the code and restart the debug session ..... 6-26

---

**Section 7**

Firmware Upgrade..... 7-1

7.1 Firmware upgrade overview..... 7-1

7.2 Firmware version test and upgrade ..... 7-1

7.3 Adapter in use..... 7-2





## Section 1

---

# Introduction

---

### 1.1 General

This document contains a quick-start guide describing how to get up and running using the AVR<sup>®</sup> ONE! debugger with AVR32 Studio. In addition to the AVR ONE! debugger, you need the following items:

- AVR32 Studio 2.5 software
- AVR32 GNU Toolchain 2.4
- EVK110x Evaluation board

Software and documents can be found at [www.atmel.com/avrone](http://www.atmel.com/avrone)

---

### 1.2 Requirements

This example was created on a PC running Microsoft<sup>®</sup> Windows<sup>®</sup> XP Professional. For other versions of Windows, the behaviour when installing software and drivers may be slightly different.

Please read the AVR32 Studio 2.5 release notes for information about support for other versions of Windows.



# Quick-start guide (short version)

## 2.1 Install Hardware and software

- Install the MICTOR38 connector on the EVK1100 board.
- Download and install avr32-gnu-toolchain-2.4.x and AVR32Studio-2.5.x.
- Connect AVR ONE! to power and USB and turn it on.
- Install AVR ONE! USB driver.
- Connect AVR ONE! to the EVK1100 using the MICTOR38 connector.
- Connect the EVK1100 to power and turn it on.
- Start AVR32 Studio.
- Select a suitable workspace folder to contain your projects.
- Exit from the welcome screen to workbench.
- Right-click in the *AVR32 Targets* view and select **Scan Targets**.
- Select the AVR ONE! and click on the *Properties*-tab.
- Select *Details*-tab. Set MCU to **UC3A0512** or **UC3A0512ES**, depending on what MCU is mounted on your EVK1100 and Board to **EVK1100**.
- Right-click on the AVR ONE! in the *AVR32 Target* view and select **Chip Erase**. This operation is only needed one time (when the EVK1100 is new).

## 2.2 Create a demonstration project

- Select *File>New>Example*.
- Select *EVK1100>Components>DIP204 example*, then **Next**.
- Enter a name for the project, and click **Finish**.
- Right-click on the project in *Project Explorer* view and select **Build Project** (or use Ctrl+B).

## 2.3 Configure target MCU for a debug session using trace

- When the build process is finished, right-click on the project in the *Project Explorer*-view and select *Debug As>Debug Configurations*.
- In the *Debug Configurations*-view, select **AVR32 Application** and click **New**. A new launch configuration will be created and default values will be filled into all fields.
- Select the *Trace*-tab and click **Enable Trace**.
- Select the preferred trace method. In this case we want **Buffered AUX Trace**.
- Select the preferred action when buffer is full. In this case we choose **Break, read out and halt**.
- Select Buffer Size. We use **16kB** for a quick test.

- Select Debugger tab and tick *Stop on startup at: main*.

---

## 2.4 Start the debug session and configure AVR32 Studio 2.5 for trace

- Click the **Debug**-button. Now the program will be loaded into the target, and run until `main()`.
- When the program halts, add at least a trace start-point (Right-click to the left of the source code line in the source code view).

---

## 2.5 Start the trace debug session

- Click **Resume** (green *Play* button in Debug view) and wait until the program halts.
- You can now look at the trace data in the *Trace*-view.



### Hardware preparation

In case you have an evaluation kit without the MICTOR38 connector, you need to install one. In case the connector is already mounted, you can skip this chapter.

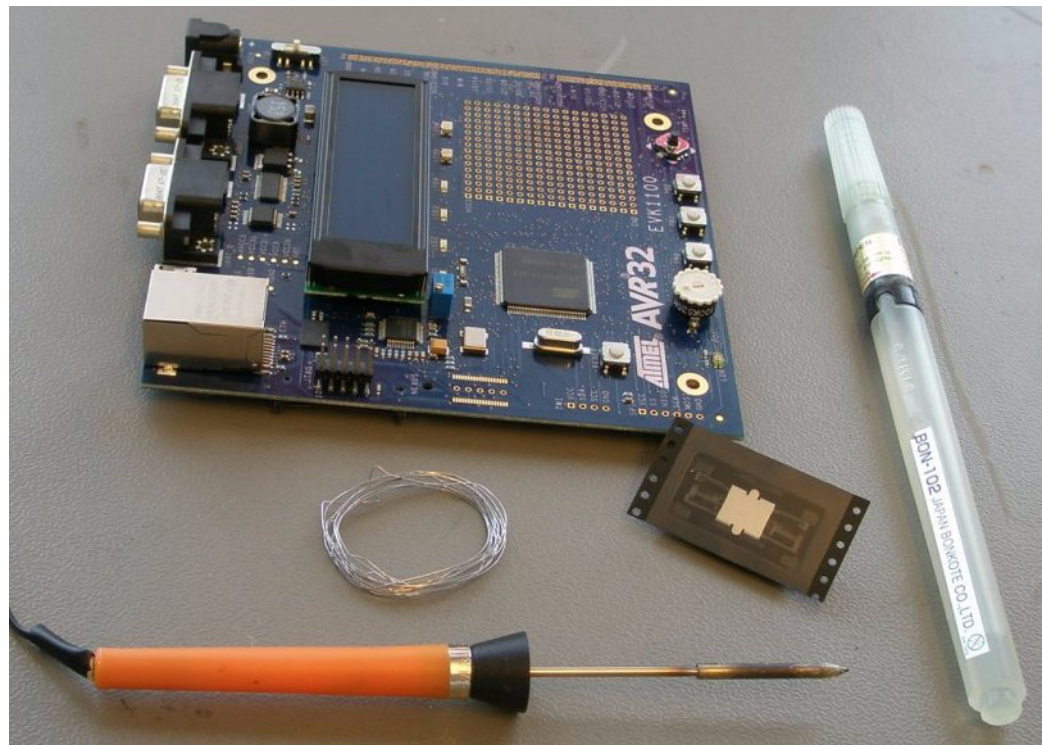
To be able to connect to the evaluation board AUX port, you need to solder a connector to the board. The AVR ONE! Kit contains one MICTOR38 connector for this purpose. If you need more connectors for other kits, or your own designs, you can buy more connectors from Atmel, or Tyco Electronics/AMP.

The Tyco Electronics/AMP Part number is 2-5767004-2.

To install the MICTOR38 connector, you only need a fine-tipped soldering iron, a small piece of fine solder (0,3mm is OK), and some extra flux. Also remember to provide proper ventilation to prevent inhaling the fumes from the flux.

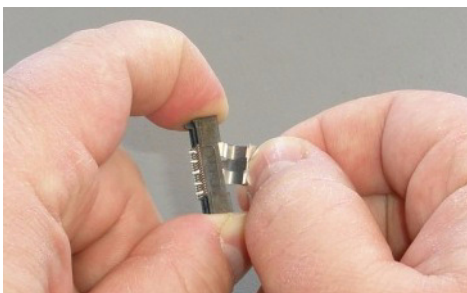
The soldering guide shows the EVK1100, but is applicable for all other kits that needs a MICTOR38 connector (like the EVK1101).

**Figure 3-1.** Required hardware and tools for installation of Mictor38



Unpack the Mictor38 connector and remove the pick-and-place pad

**Figure 3-2.** Remove the pick-and-place pad

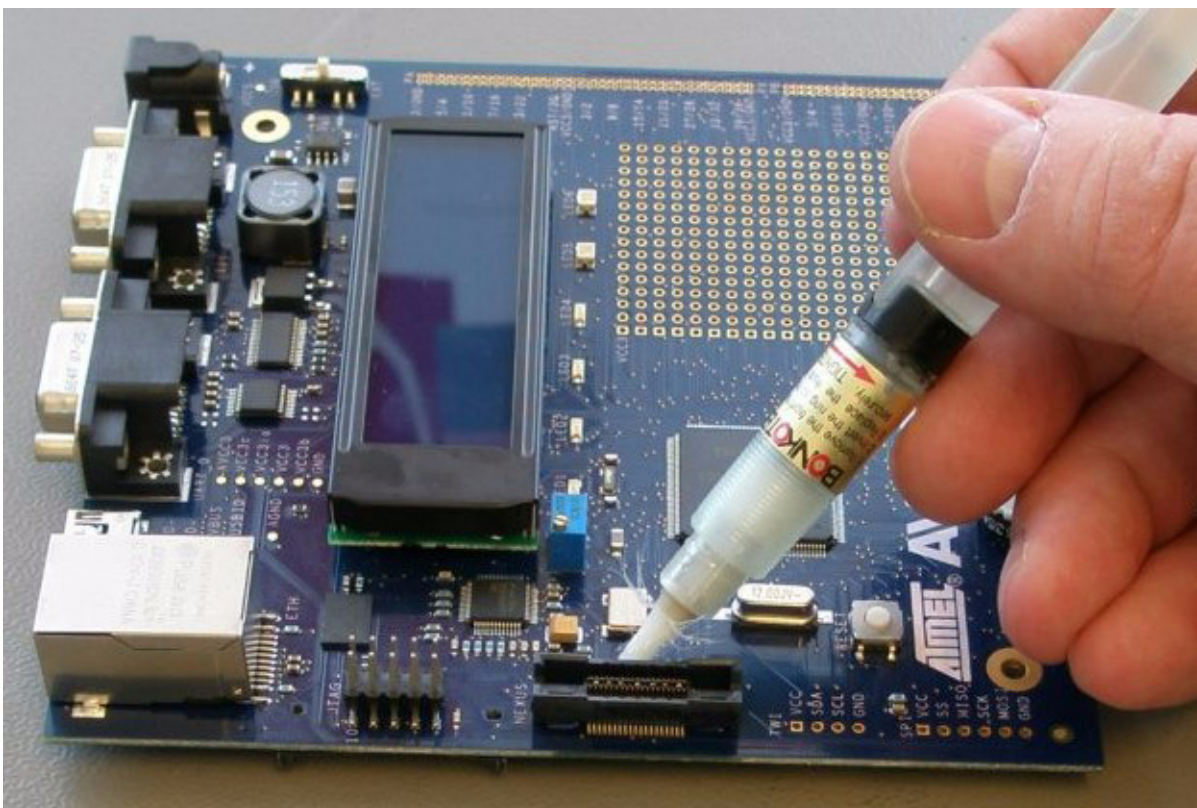


Place the connector onto the footprint on the evaluation board. Make sure that the guide tab beneath the connector fits into the guide hole in the PCB.

Add a fair amount of flux. The extra flux is very important for a good result. It is also very important to keep the tip of the soldering iron clean while mounting the connector.

Too thick solder, too little flux or solder-blobs on the tip of the soldering iron will give bad connections or short circuits.

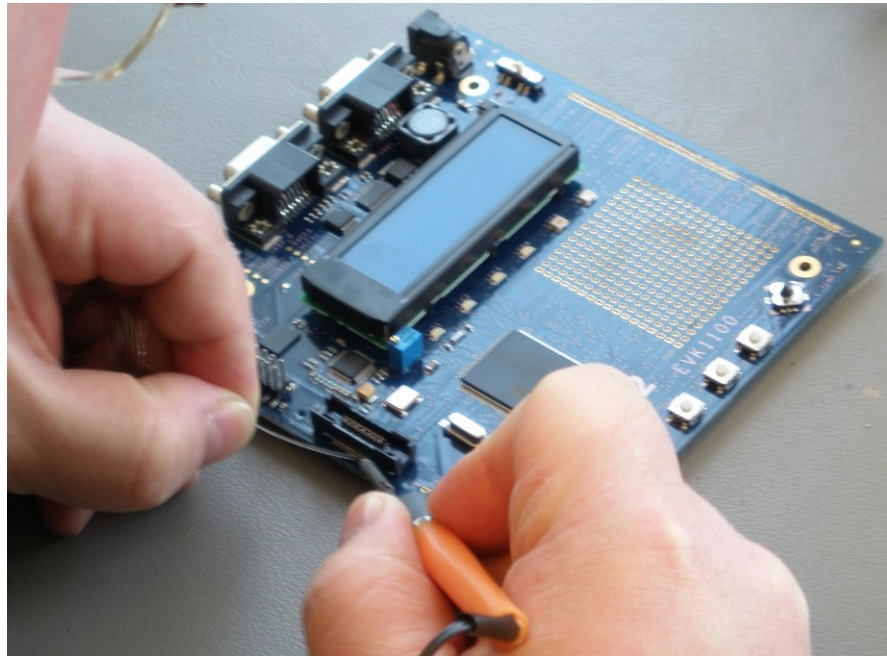
**Figure 3-3.** Place Mictor38 and apply flux





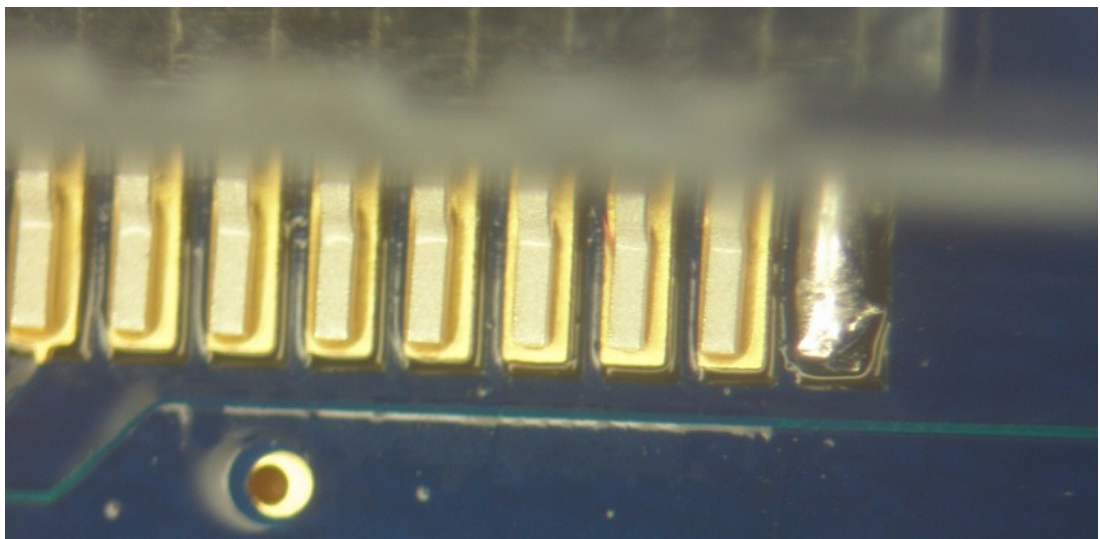
Make sure that the connector is firmly seated on the footprint, and start by soldering the corners.

**Figure 3-4.** Soldering the corners



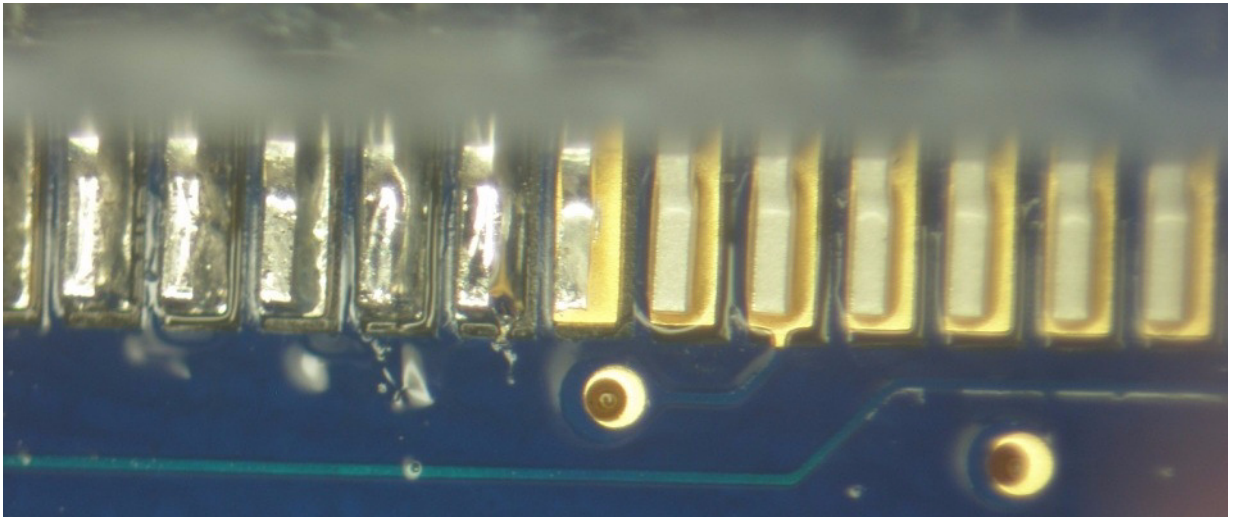
When all corners are soldered, check that connector is still firmly seated. It is still possible to push the connector down and re-heat corner pins if you need to adjust a bit.

**Figure 3-5.** Soldered corner pin



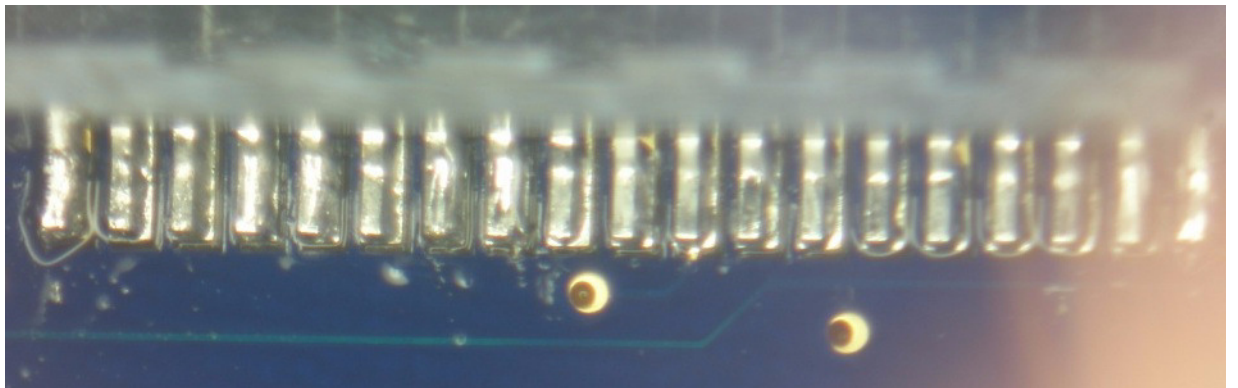
Solder the remaining pins.

**Figure 3-6.** Continuing with the remaining pins



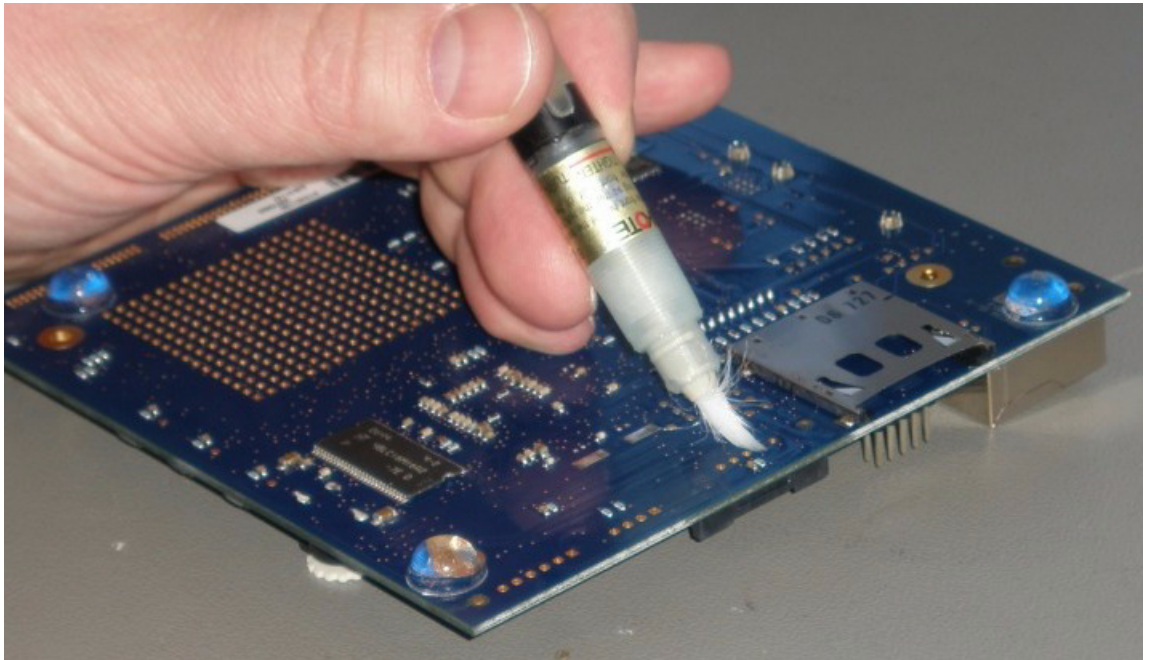
After soldering, you should make sure that there are no shorts circuits between pins.

**Figure 3-7.** All pins finished



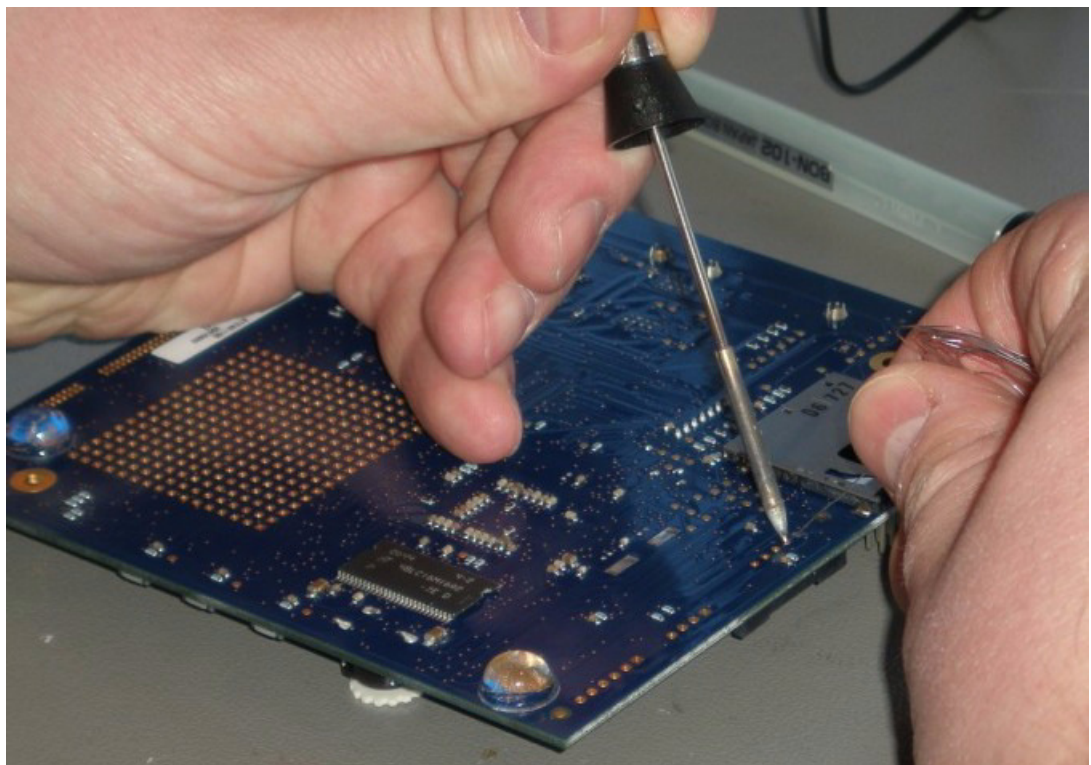
Turn the board and apply flux on the ground pins.

**Figure 3-8.** Apply flux on ground pins



Solder the five ground pins.

**Figure 3-9.** Solder ground pins





### 4.1 Download the software

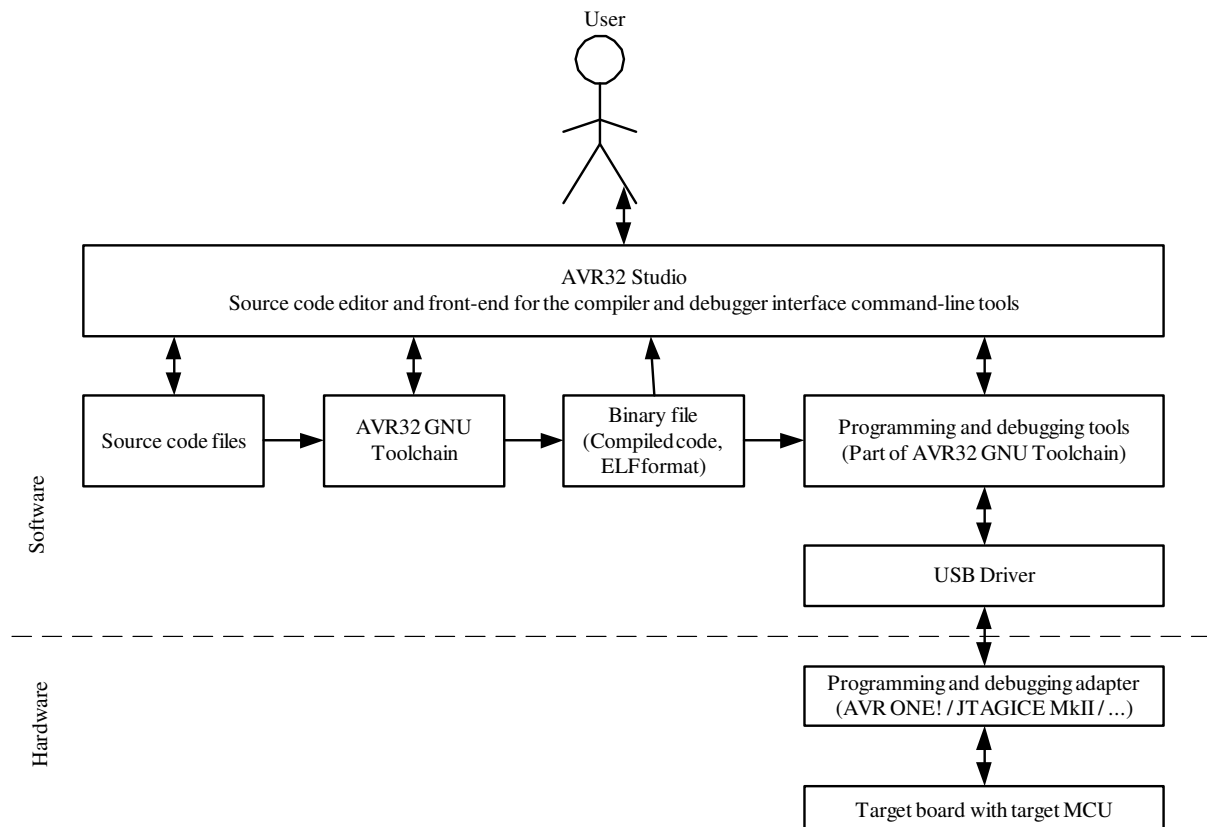
To use the AVR ONE!, you must download and install two software packages:

- avr32-gnu-toolchain-2.4.x.exe
- AVR32Studio-2.5.x.exe

The AVR32 Toolchain is a collection of tools that are required to be able to work with the AVR ONE!. It contains command-line tools for controlling the AVR ONE!, and tools to compile code for the AVR32 MCUs.

AVR32 Studio is the front end that uses the AVR32 GNU Toolchain to generate binary code for the target, program the target, and control the debug sessions.

**Figure 4-1.** Tools structure



---

## 4.2 Download the two installation files to your disk.

The installation files can be found at this location: [www.atmel.com/avrone](http://www.atmel.com/avrone)

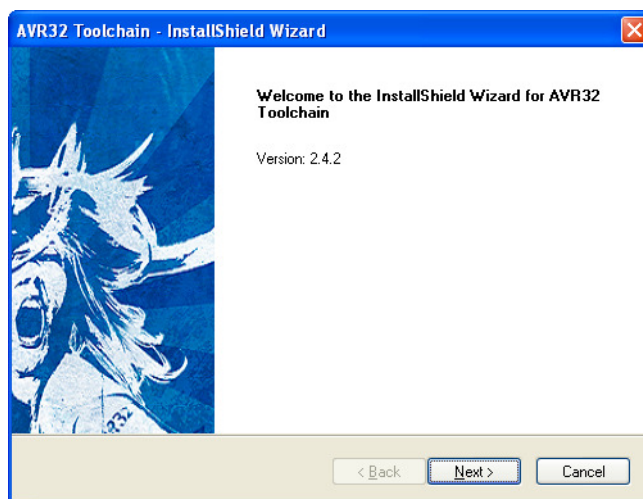
---

## 4.3 Install AVR32 GNU Toolchain

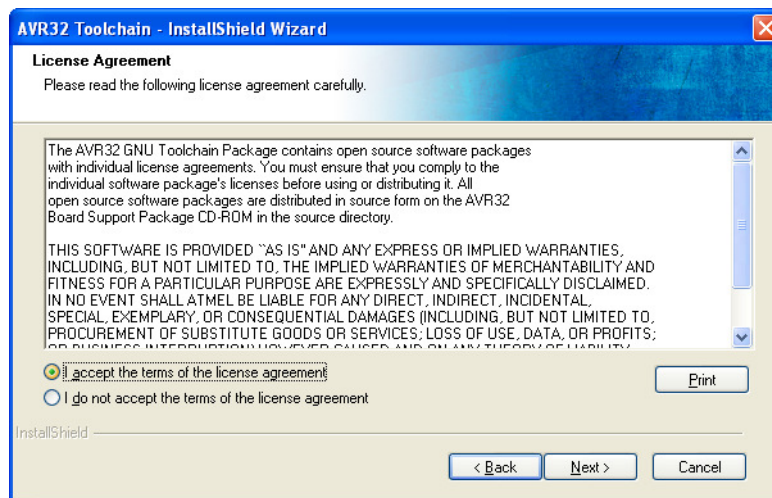
If you have any AVR tools connected to the USB hub, turn them off now. Otherwise the USB driver installation may fail.

Double-click on avr32-gnu-toolchain-2.4.x to start the installation process.

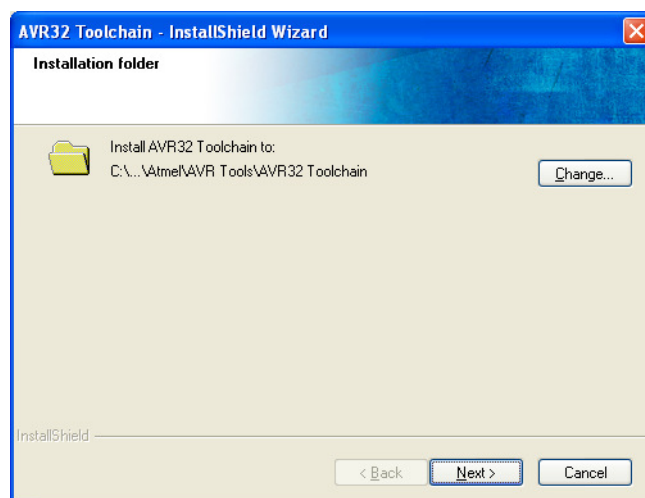
**Figure 4-2.** AVR32 GNU Toolchain installation welcome



Click **Next**.

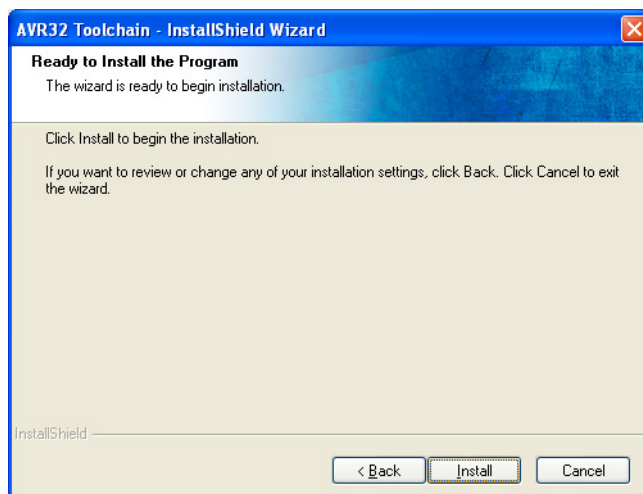
**Figure 4-3.** AVR32 GNU Toolchain License Agreement form

Select **I accept the terms of the licence agreement**, then click **Next**.

**Figure 4-4.** AVR32 GNU Toolchain installation folder select

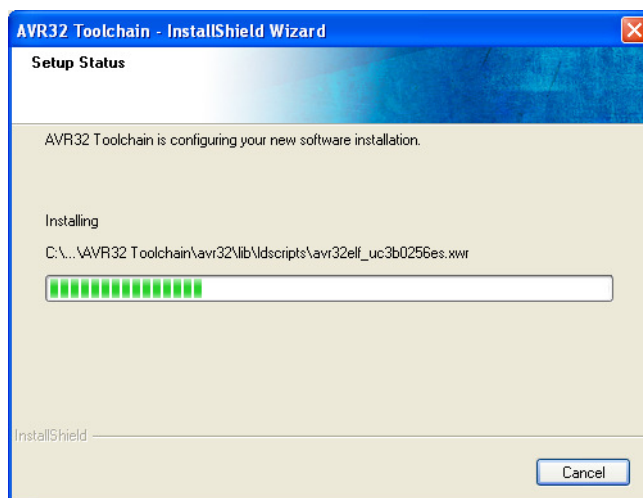
Check that the installation folder is correct and click **Next**.

**Figure 4-5.** AVR32 GNU Toolchain installer configuration finished



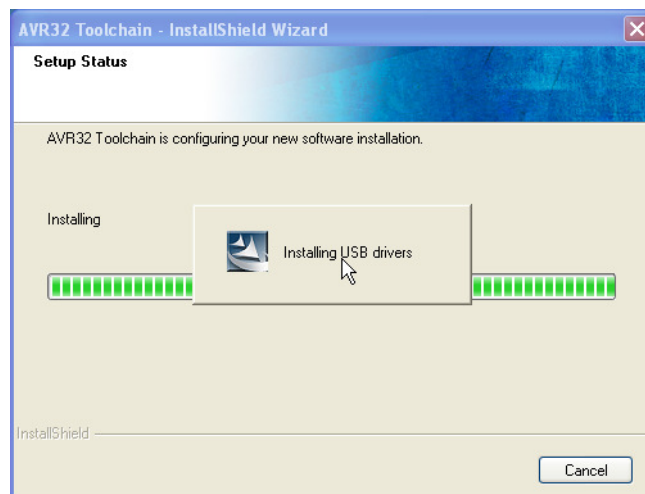
Click **Install**.

**Figure 4-6.** AVR32 GNU Toolchain installation progress indicator

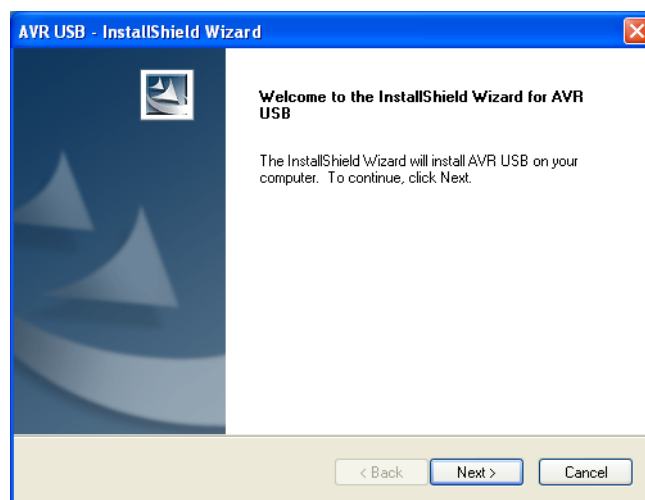


The AVR32 GNU Toolchain is now being installed. As a part of the installation process, USB drivers for all supported programming and debugging adapters are installed.

**Figure 4-7.** USB Drivers installation start

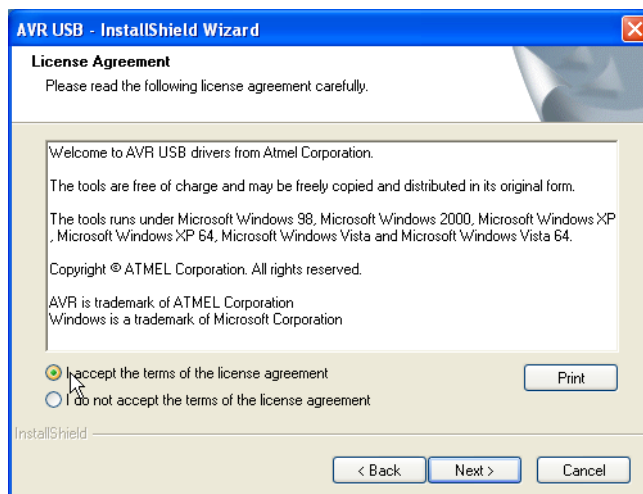


**Figure 4-8.** USB Driver installer welcome

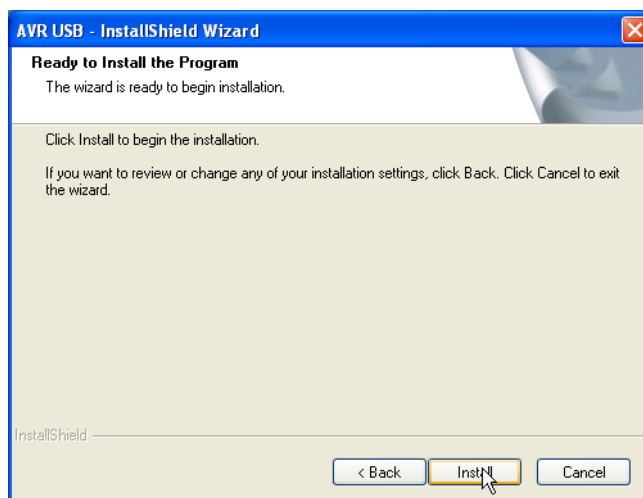


Click **Next**.

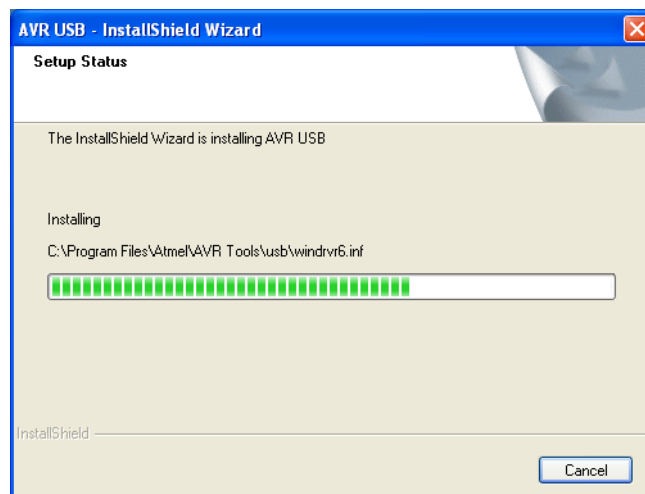
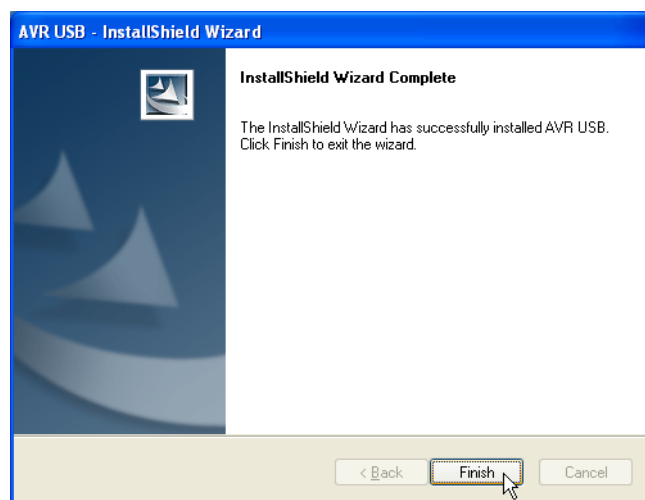


**Figure 4-9.** USB Drivers licence agreement form

Select **I accept the terms of the licence agreement**, then click **Next**.

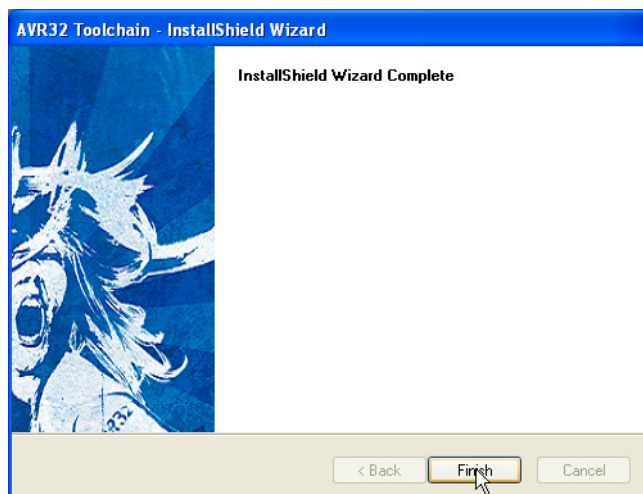
**Figure 4-10.** USB drivers installer configuration finished

Click **Install**.

**Figure 4-11.** USB Drivers installation progress indicator**Figure 4-12.** USB Drivers installation complete

Click **Finish**.

**Figure 4-13.** AVR32 GNU Toolchain installation complete



Click **Finish** to complete the AVR32 Toolchain installation process.

---

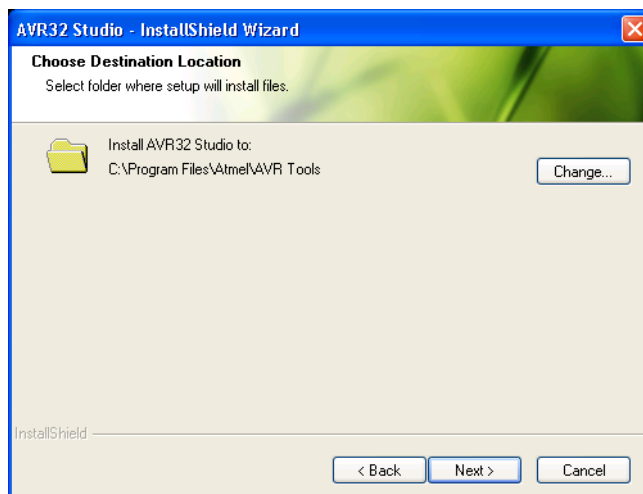
## 4.4 Install AVR32 Studio 2.5

Double-click on the AVR32Studio-2.5.x.exe file to start the installation process.

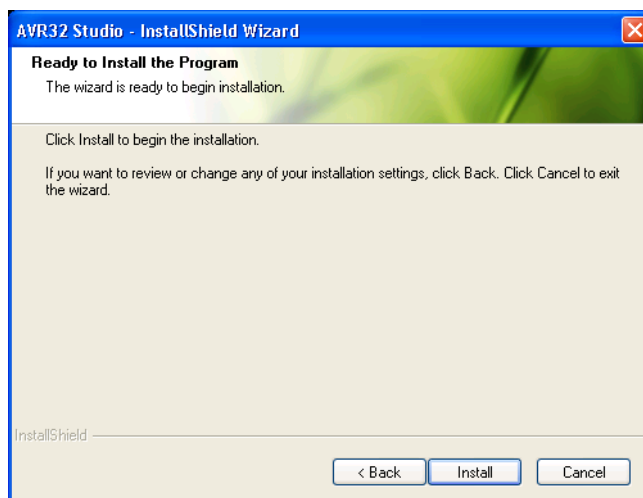
**Figure 4-14.** AVR32 Studio 2.5 installer welcome



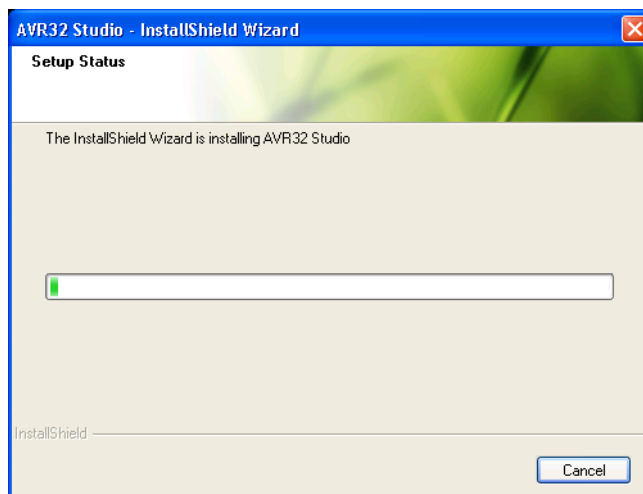
Click **Next**.

**Figure 4-15.** AVR32 Studio installation folder select

Check that the installation folder is correct and click **Next**.

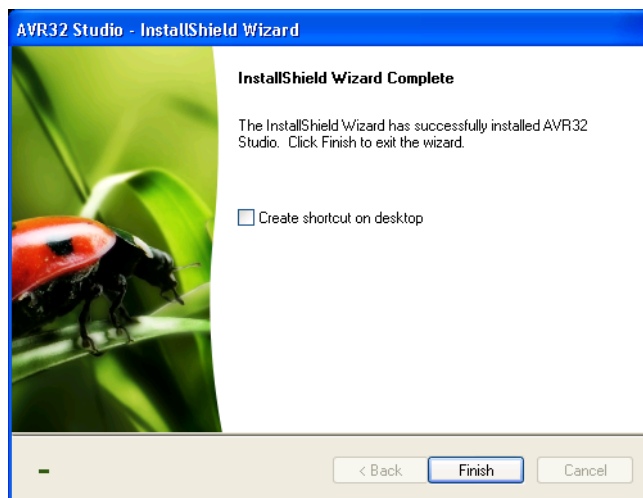
**Figure 4-16.** AVR32 Studio installer configuration finished

Click **Install** to start the installation.

**Figure 4-17.** AVR32 Studio installation progress indicator

Wait for the installation process to complete.

If a suitable Java™ runtime is not installed, a Java installer wizard will guide you through the installation procedure.

**Figure 4-18.** AVR32 Studio installation process complete

Tick **Create shortcut on desktop** if you want a shortcut to be created. Then click **Finish**.

## 4.5 Connect the AVR ONE! to power and USB host

- Connect the AVR ONE! to power using the supplied power supply.
- Connect the AVR ONE! to the USB host (PC) using the supplied USB cable
- Turn on the AVR ONE! using the power switch next to the power connector

**Figure 4-19.** AVR ONE! connected to power and USB



## 4.6 Install AVR ONE! Driver

When the AVR ONE! is powered up and connected to the PC for the first time, the proper USB driver must be installed. Since the PC is keeping track of the serial number of each USB device, this will happen every time a new AVR ONE! is connected to the PC, even if the driver is the same as for all other AVR ONE!s that have been connected previously. This is a property of the operating system, and is not controlled by any Atmel software installed.

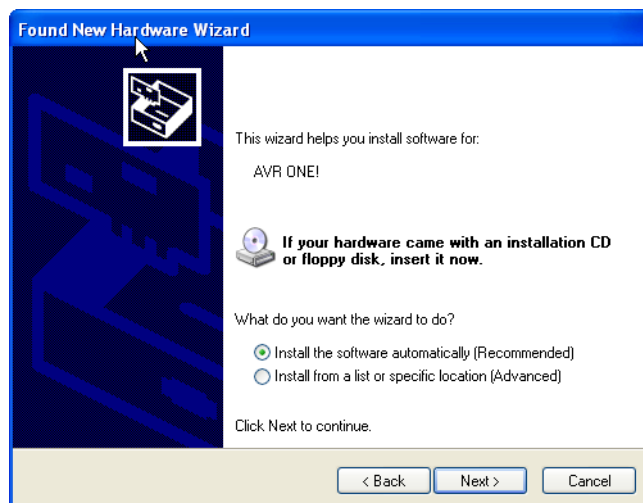
**Figure 4-20.** “New hardware” notification pop-up



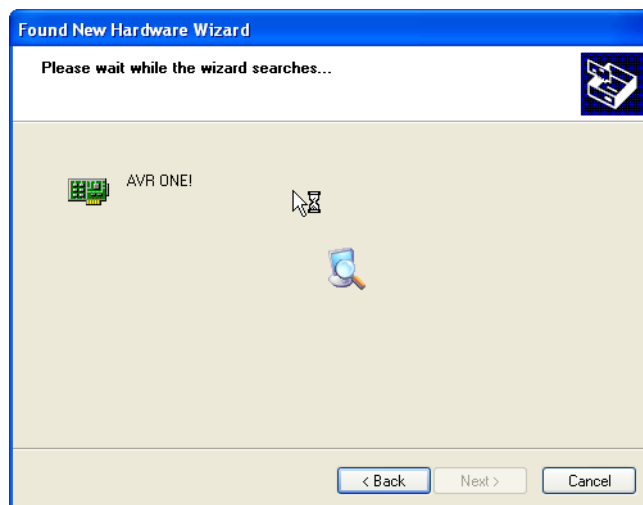
**Figure 4-21.** AVR ONE! Hardware installation wizard



When the hardware installation wizard pops up, select **No, not this time** and click **Next**.

**Figure 4-22.** Hardware installation wizard configuration

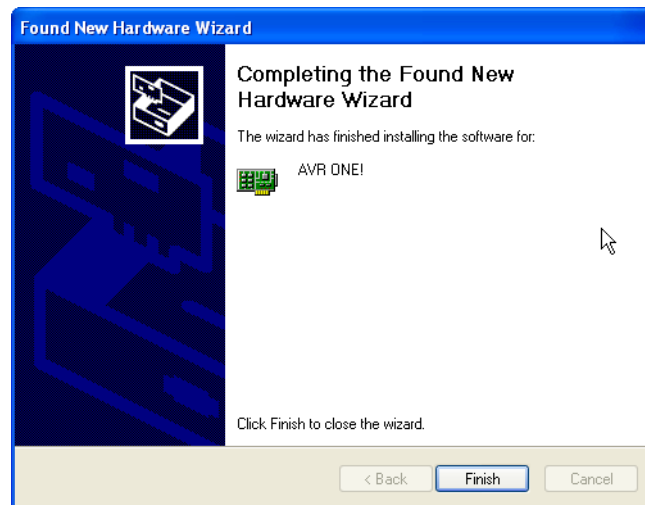
Select **Install the software automatically** and click **Next**.

**Figure 4-23.** Hardware installation in progress

Wait for the installation process to complete.



**Figure 4-24.** Hardware installation wizard complete

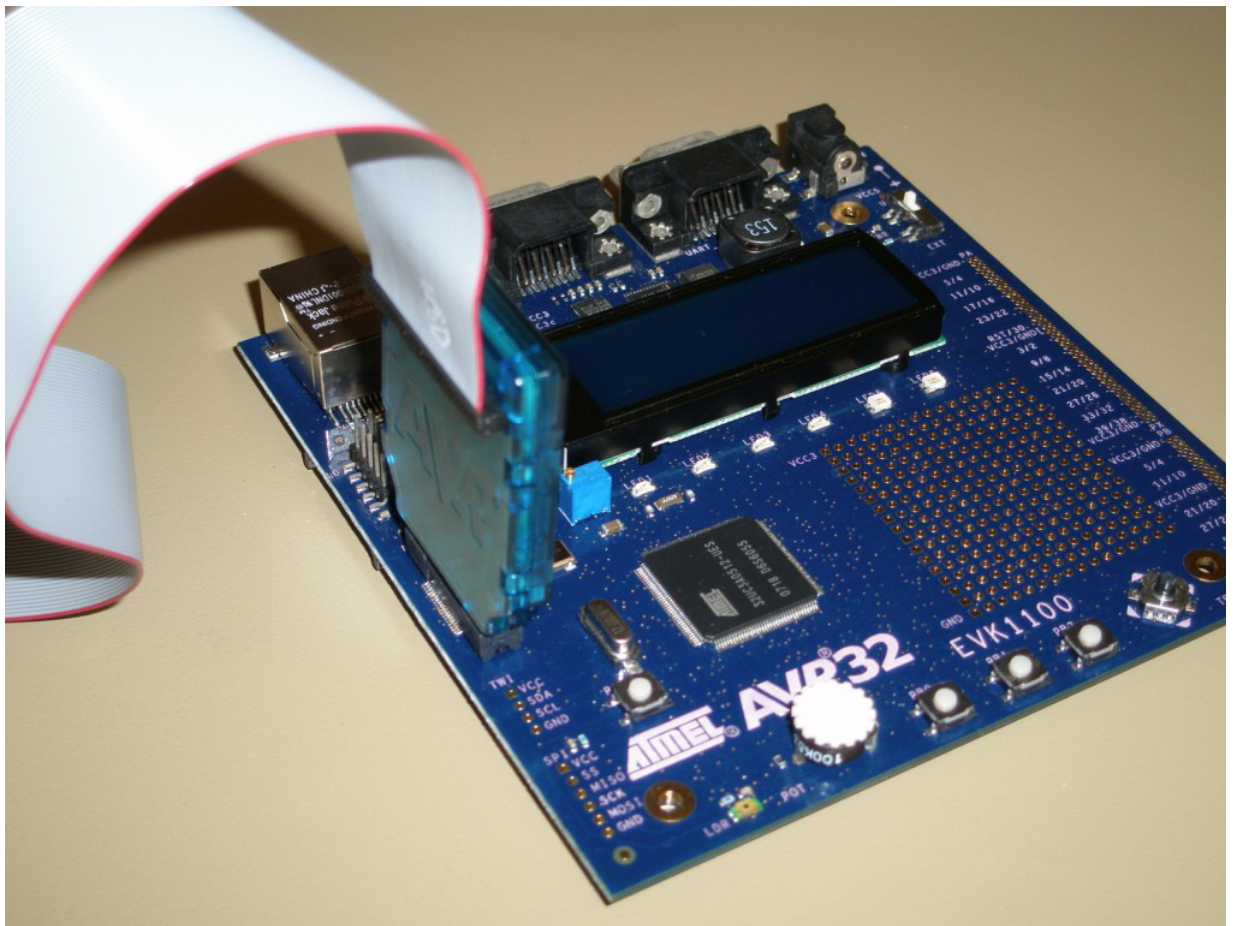


Click **Finish**.

### 5.1 Connect the AVR ONE! to the EVK1100

Connect the AVR ONE! debugger to the EVK1100 evaluation board using the MICTOR38 connector.

**Figure 5-1.** AVR ONE! connected to the EVK1100

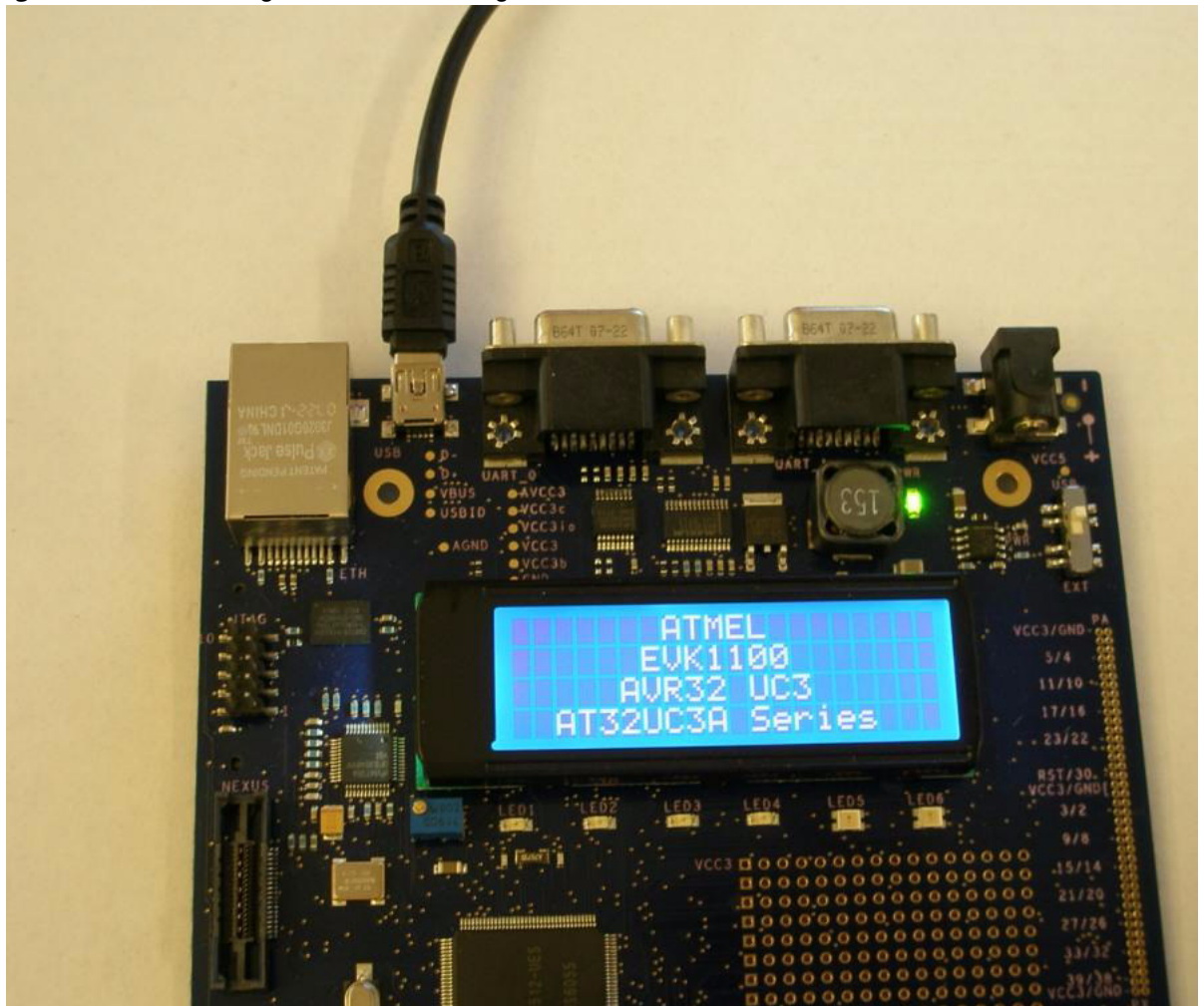


## 5.2 Connect the EVK1100 to power

Connect the EVK1100 to power and turn it on. The easiest way to provide power is to use the supplied USB cable.

Switch it on by setting the power switch to **USB**.

**Figure 5-2.** Powering the EVK1100 using the USB cable



# Create demo application

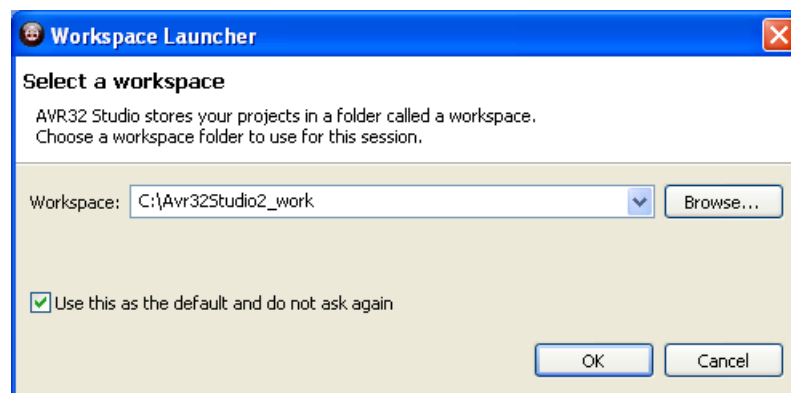
## 6.1 Start AVR32 Studio

Start AVR32 Studio. Start-up may take a while (because of all the Java libraries being loaded).

**Figure 6-1.** AVR32 Studio splash screen

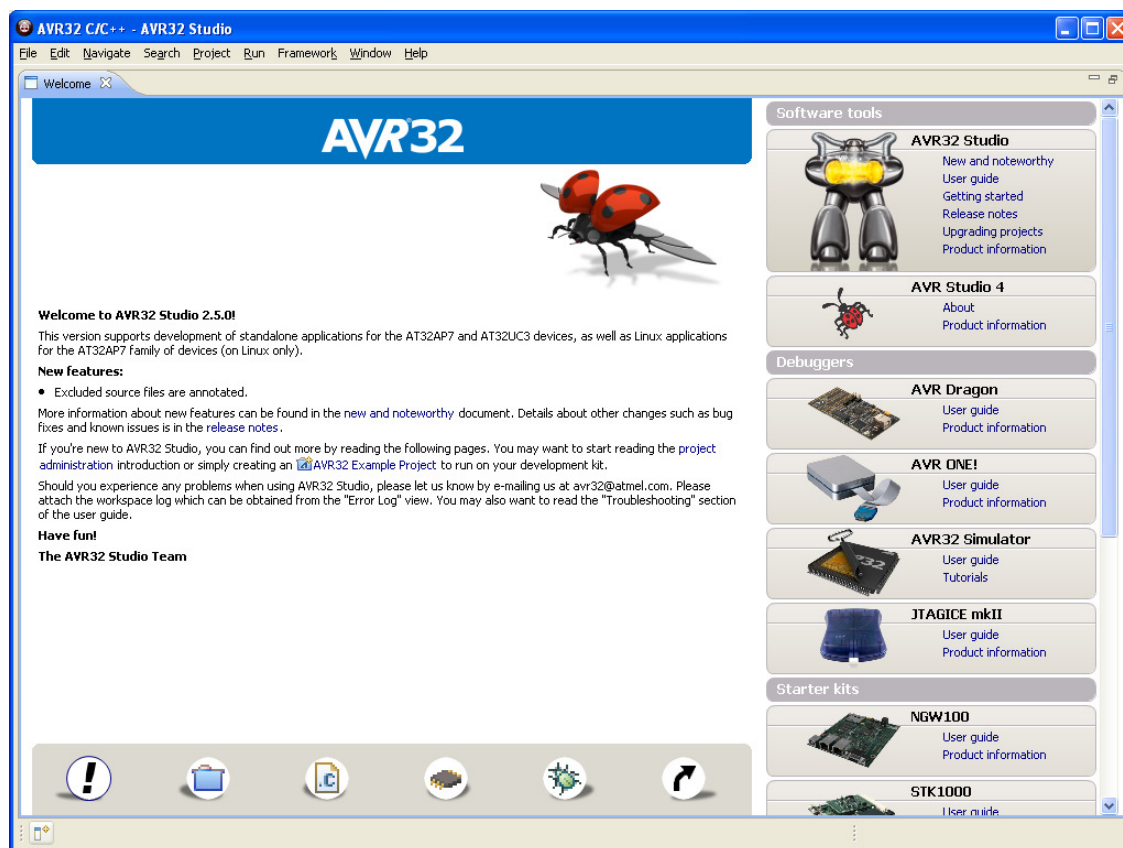


**Figure 6-2.** AVR32 Studio workspace selection



Select a suitable workspace folder for your project files. If you want to use the same folder for your workspace every time you start AVR32 Studio, you should tick the box before clicking **OK**.

Figure 6-3. AVR32 Studio Welcome view



Exit from the welcome screen to the workbench by clicking on the **Close Page** icon (Arrow).

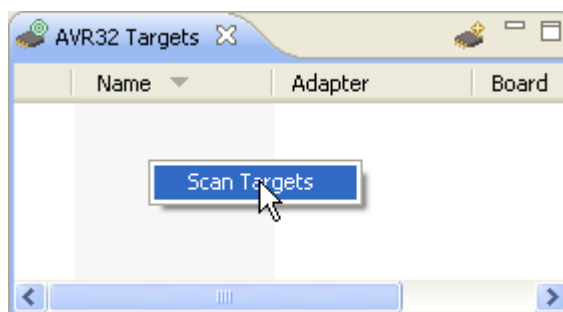
## 6.2 Configure adapter and target

Before you can use the AVR ONE! and the EVK1100, you have to tell AVR32 Studio what type of equipment is connected to your PC.

“Target” refers to the MCU on the EVK1100 evaluation board, and “Adapter” refers to the tool connecting the target to the PC (in this case, the AVR ONE!).

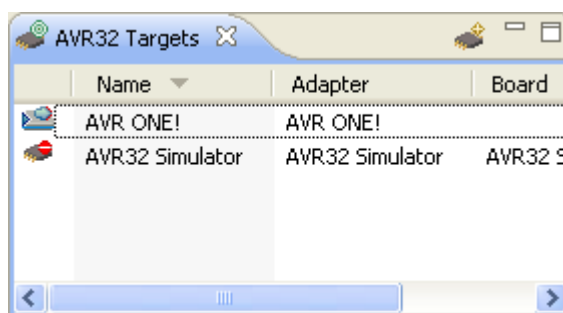
### 6.2.1 Add and configure the adapter (AVR ONE!)

**Figure 6-4.** Scan Targets



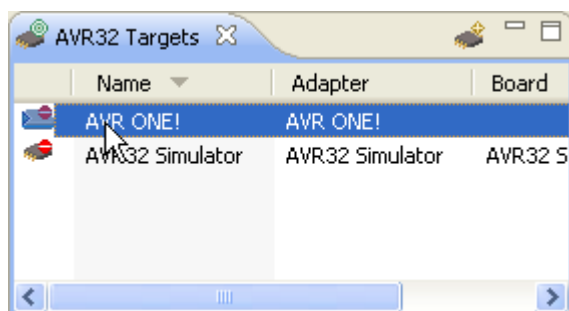
Right-click in the **AVR32 Target**-view and select **Scan Targets**.

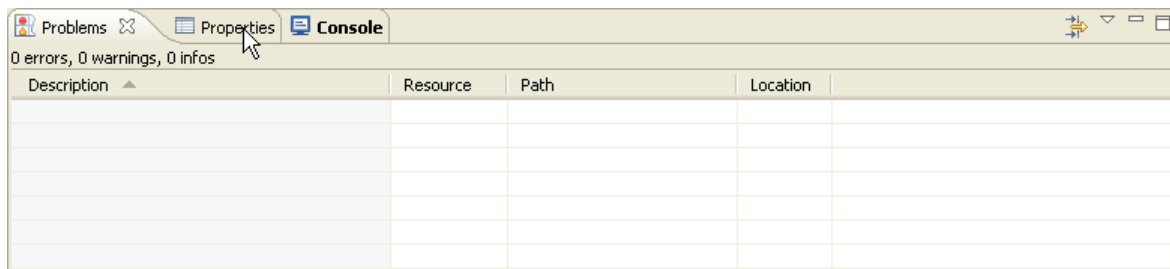
**Figure 6-5.** Available targets



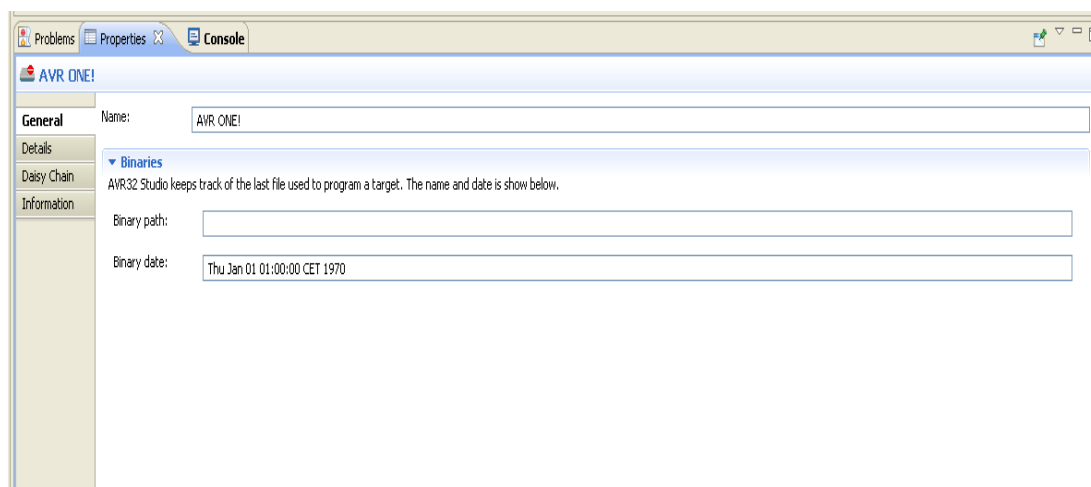
Select the AVR ONE!

**Figure 6-6.** AVR ONE! Selected



**Figure 6-7.** Selecting the properties view

Click on the **Properties** tab.

**Figure 6-8.** Properties view

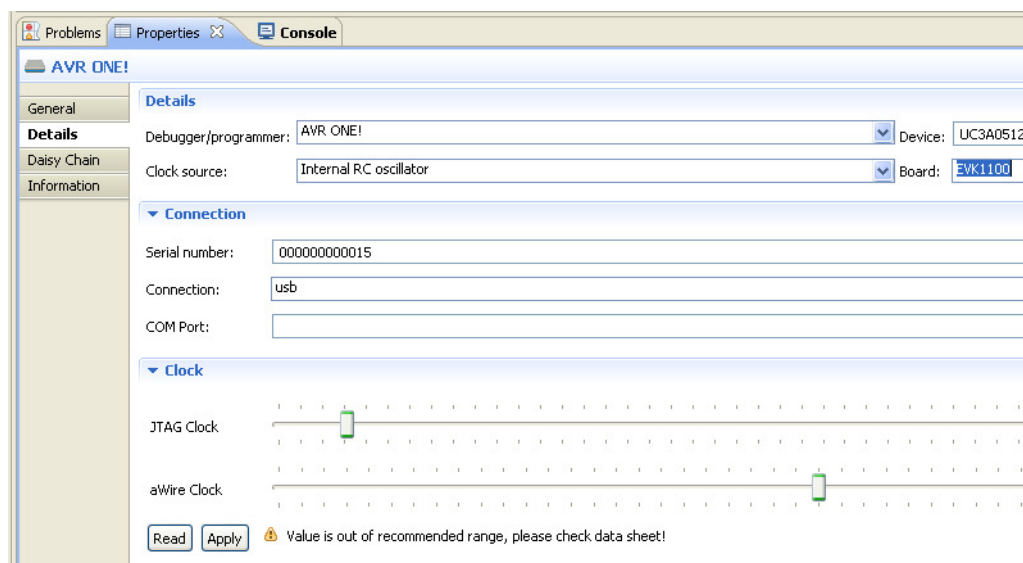
If you have several adapters connected at the same time, this is the place where you can give them unique names. Just type the name you want to use in the **Name** field.



## 6.2.2 Configure target board and MCU

Select the **Details** tab.

**Figure 6-9.** Setting the board and device type



Set MCU to **UC3A0512** or **UC3A0512ES**, depending on what MCU is installed on your EVK1100.

**Figure 6-10.** MCU Markings



To check which type of MCU is mounted on your EVK1100 evaluation board, you can read the part number printed on the MCU. The picture shows the part number printed on an -ES part (-UES suffix).

Set **Board** to **EVK1100**.





Set **MCU Clock source** to **Crystal**.

Adjust the JTAG Clock to a suitable value (Usually 33MHz or less. Max speed depends on target board signal quality). Click **Apply**.

The target and adapter configuration process is now complete.



### 6.2.3 Target MCU Chip erase

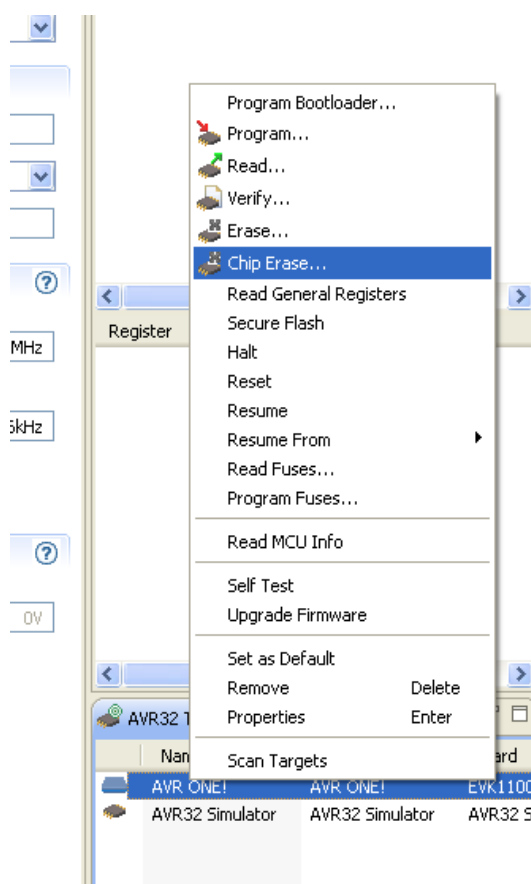
If the EVK1100 evaluation board is brand new, or if it still contains the original demo application (Control Panel Demo), the FLASH lock-bits need to be cleared. Right-click on the AVR ONE! In the *AVR32 Target* view and select **Chip Erase**.

**WARNING!** This process will erase the original demo application programmed at the factory. After this operation the EVK1100 evaluation board will be completely empty. If you need to keep the original application, you should not perform this operation.

If you would like to use your EVK1100 for this example, it is not difficult to restore the original “Control Panel Demo application”. All you have to do is to build the “Control Panel Demo example” enclosed with AVR32 Studio.

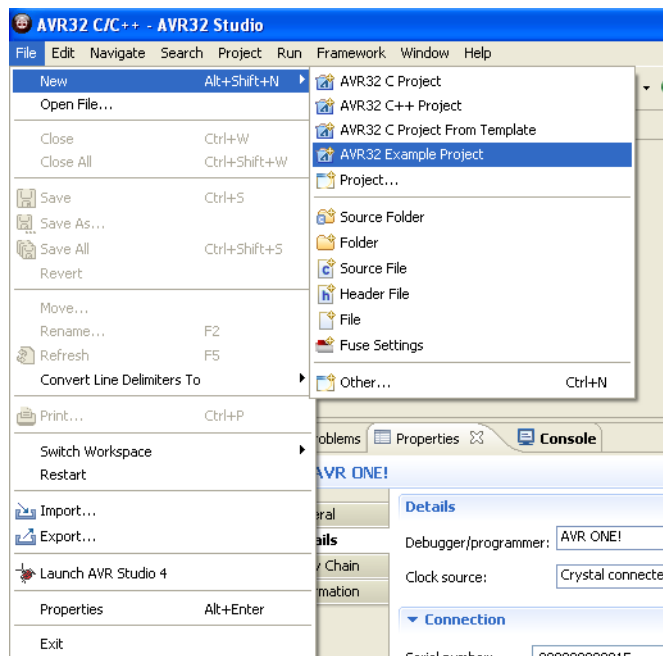
You should now perform the **Chip Erase** operation.

**Figure 6-11.** Chip erase operation



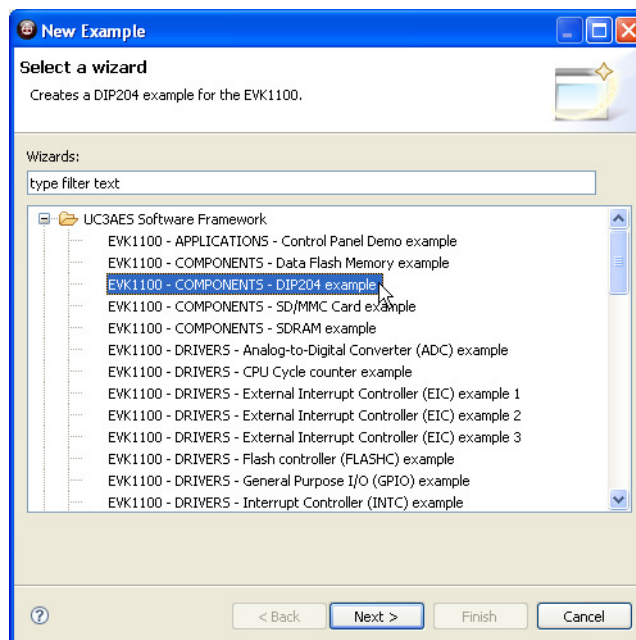
## 6.3 Create a demonstration project

**Figure 6-12.** Create new project



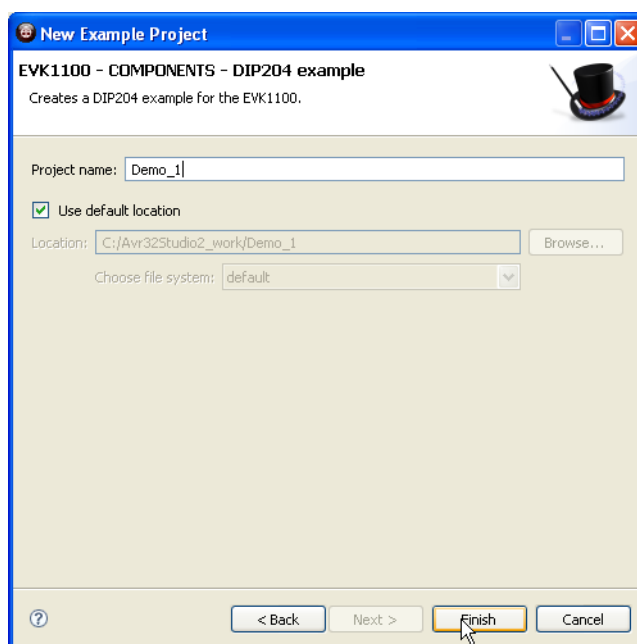
Create a new project by clicking *File>New>AVR32 Example Project*.

**Figure 6-13.** Select project example

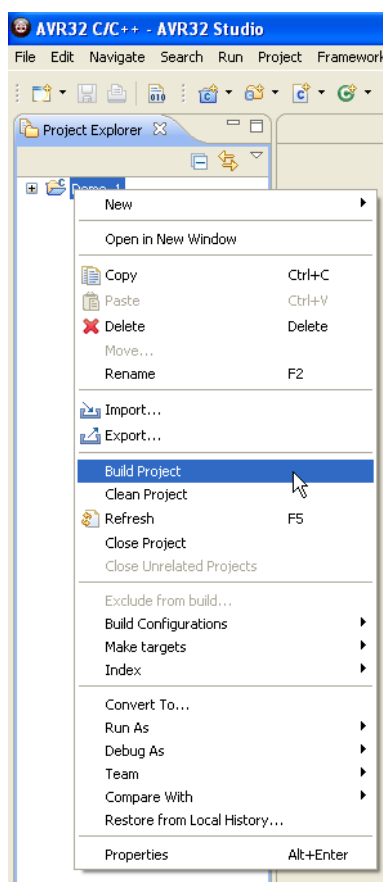


Select **EVK1100 – Components - DIP204 example**, then **Next**

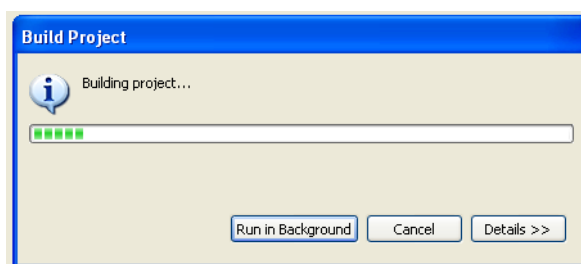
**Figure 6-14.** New project name



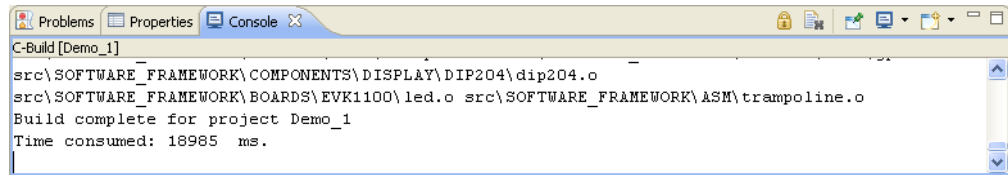
Enter a name for the project, and click **Finish**.

**Figure 6-15.** Build project

Right-click on the project in **Project Explorer**-view and select **Build Project** (or press CTRL+B).

**Figure 6-16.** Project build progress

Wait for the project build process to finish.

**Figure 6-17.** Console view


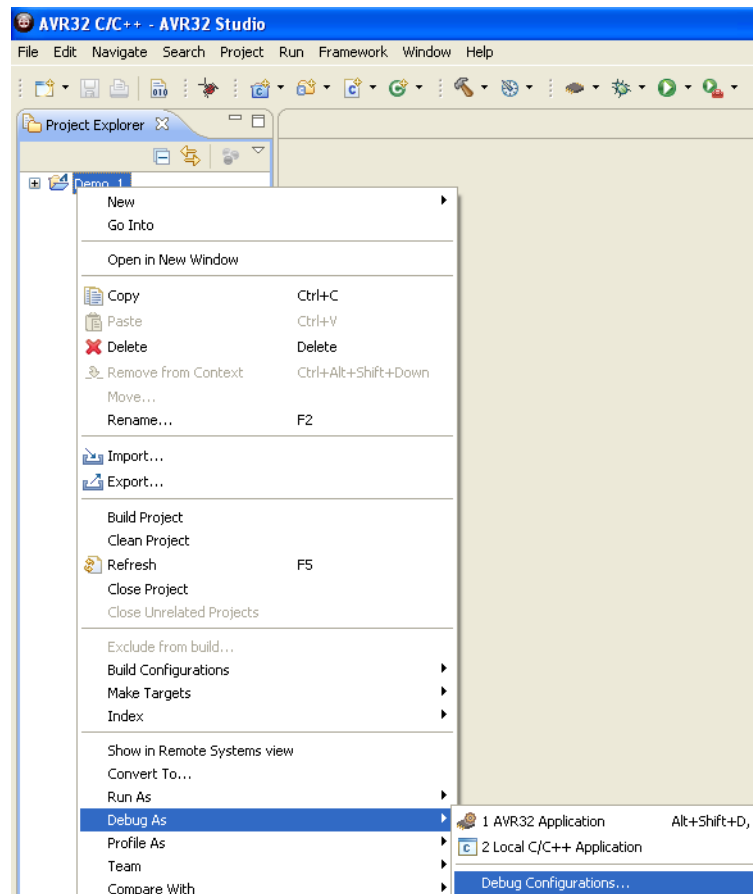
```

C-Build [Demo_1]
src\SOFTWARE_FRAMEWORK\COMPONENTS\DISPLAY\DIP204\dip204.o
src\SOFTWARE_FRAMEWORK\BOARDS\EVK1100\led.o src\SOFTWARE_FRAMEWORK\ASM\trampoline.o
Build complete for project Demo_1
Time consumed: 18985 ms.

```

The console shows output from the compiler. Make sure that this ends with a “Build complete ...” message (Except for the “Time consumed” message). If something is not working, you will see error messages in this view.

## 6.4 Configure AVR32 Studio for a debug session using trace

**Figure 6-18.** Open Debug Dialog

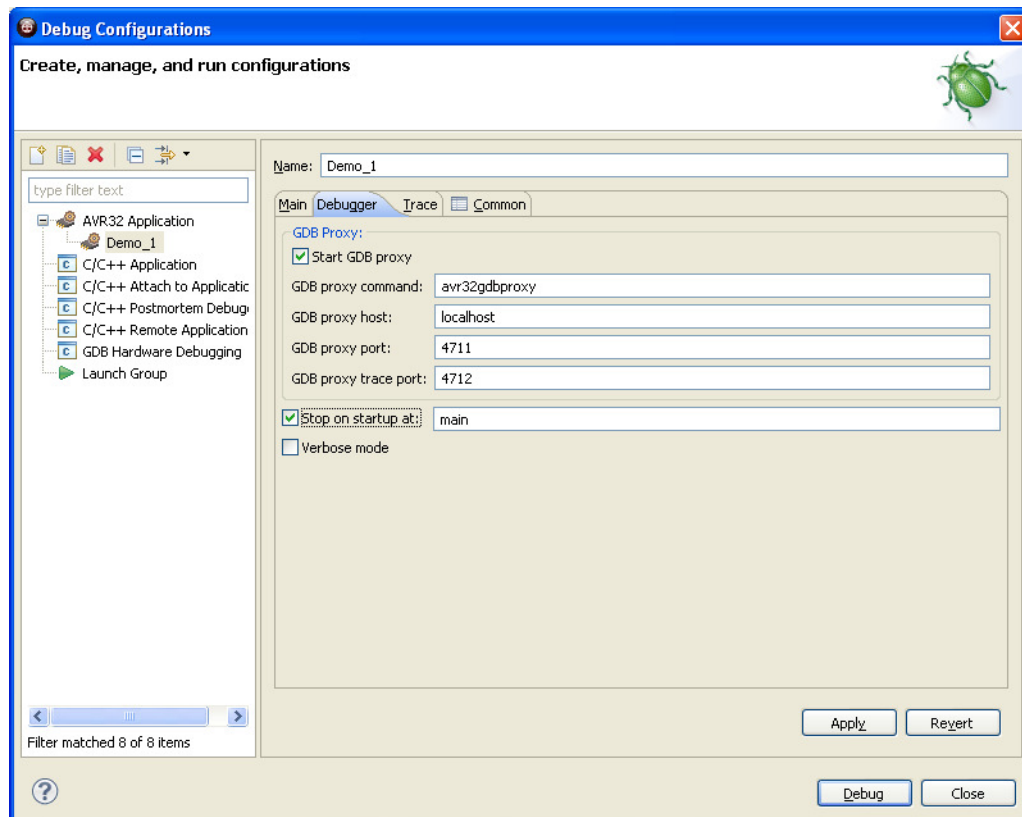
When the build process is finished, right-click on the project in the *Project Explorer* view and select *Debug As>Debug Configurations*.

### 6.4.1 Create a new debug launch configuration

In the *Debug Configurations* view, select **AVR32 Application** and right click and select **New**. A new launch configuration will be created and default values will be filled into all applicable fields.

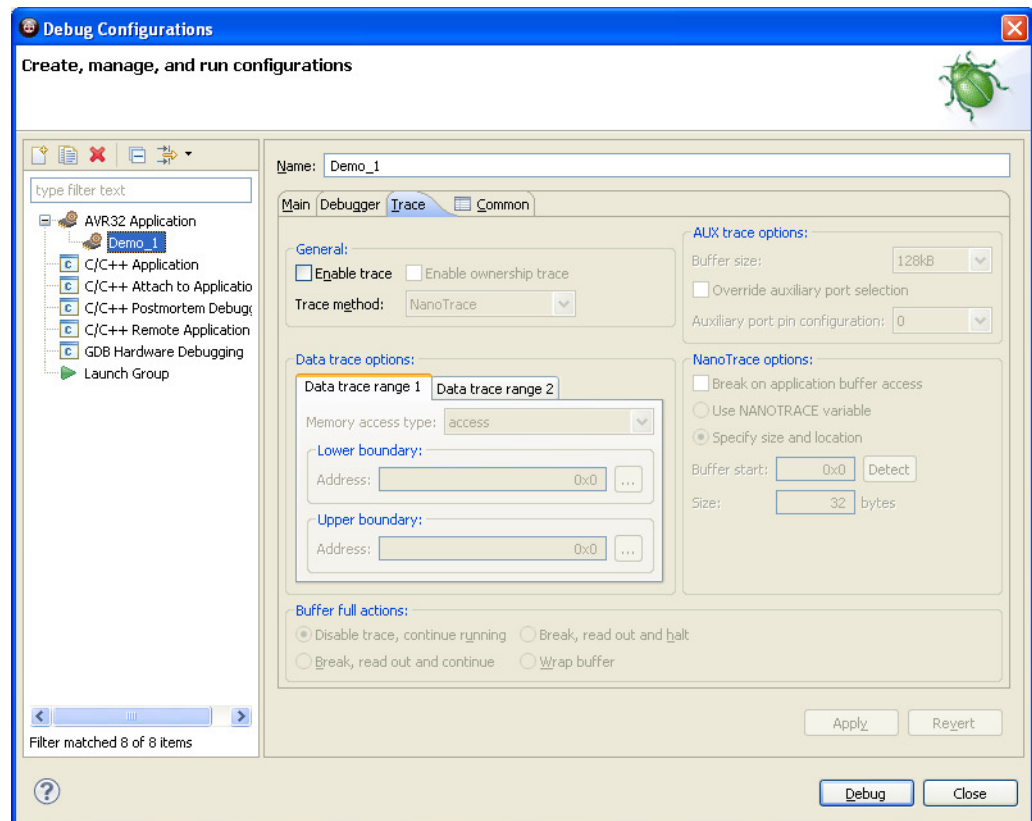
Select the *Debugger* tab and tick the **Stop on startup at: main** option.

**Figure 6-19. Debugger tab**



## 6.4.2 Configure the target trace module for program trace

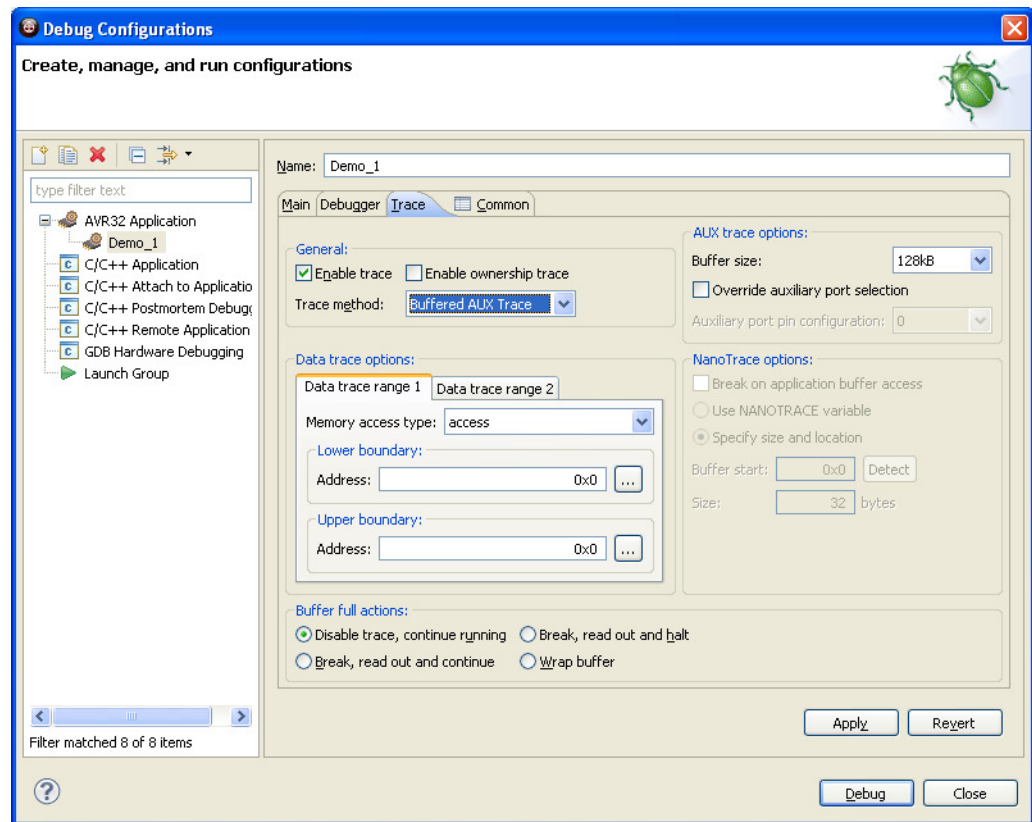
**Figure 6-20.** Debug configurations, **Trace** tab



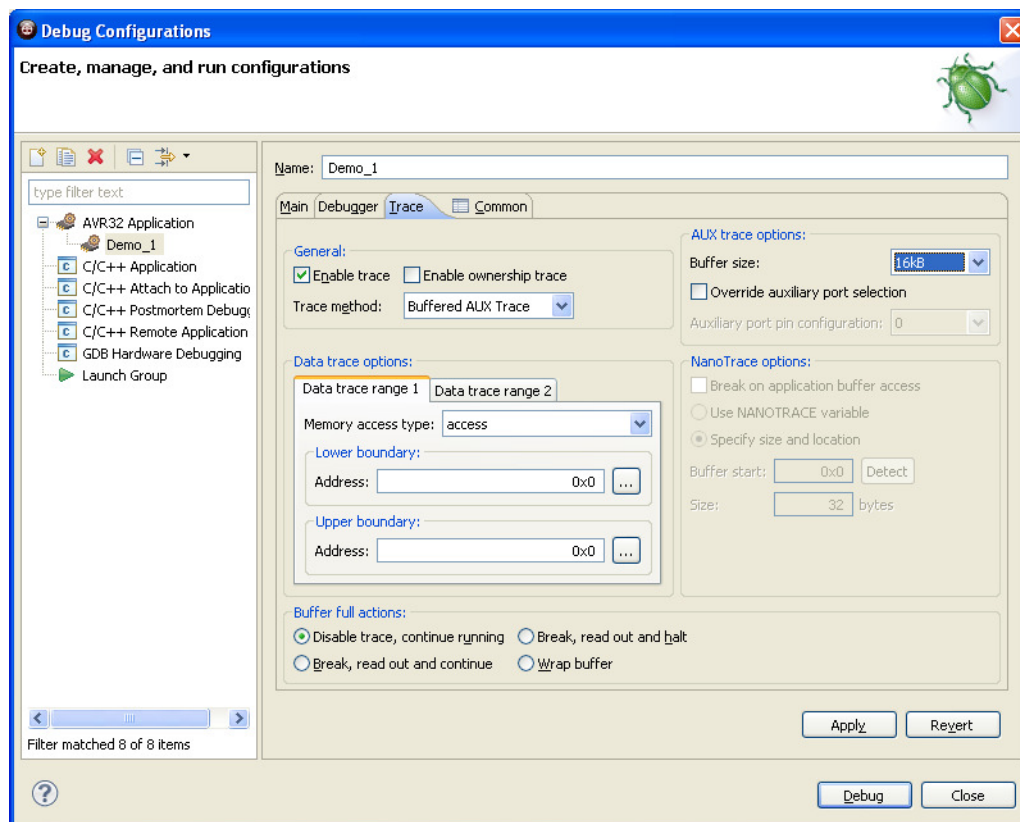
Select the **Trace** tab and click **Enable Trace**.



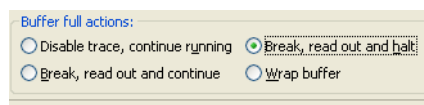
Figure 6-21. Preferred Trace method



Select the preferred trace method. In this case we want **Buffered AUX Trace**.

**Figure 6-22.** Trace buffer size

Select Buffer Size. We select **16kB** for a quick test.

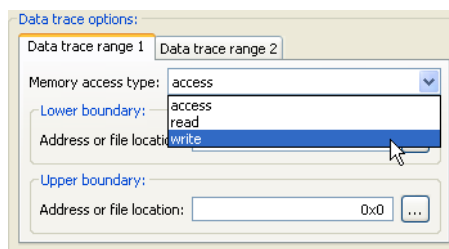
**Figure 6-23.** Buffer full action

Selected the preferred action when buffer is full. In this case we choose **Break, read out and halt**.

### 6.4.3 Configure the target trace module for data trace

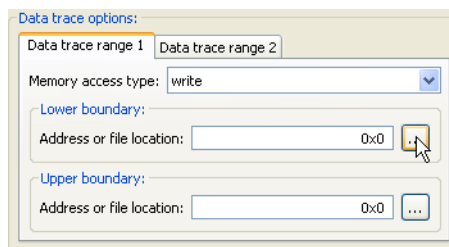
We would like to keep an eye on one of our variables. To do this, we configure a data trace range. In our case, we want a trace message each time the program writes to a variable called display.

**Figure 6-24.** Memory access type



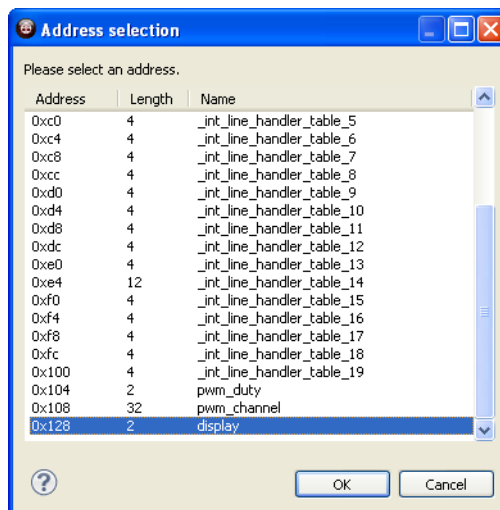
Set Memory access type to **write**.

**Figure 6-25.** Data trace boundaries



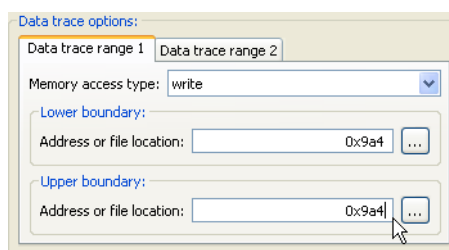
Select memory location for lower and upper boundaries.

**Figure 6-26.** Variable address selection dialogue



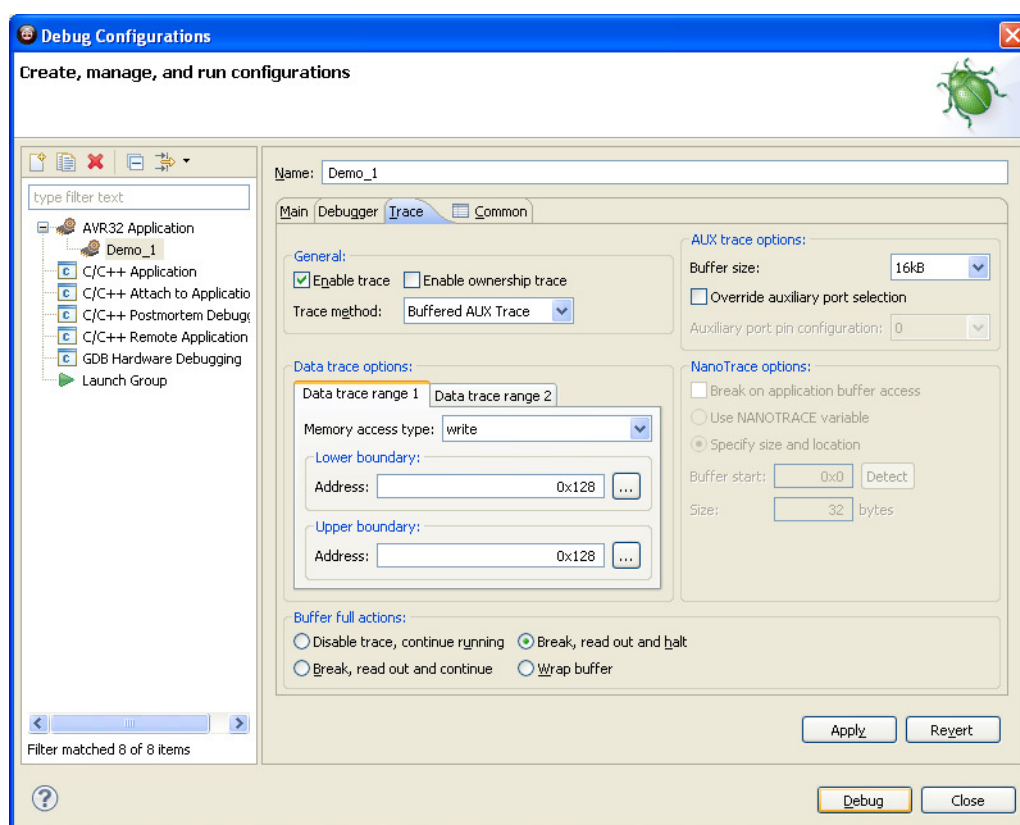
Select the start and stop addresses for the data range. Use the Address selection dialogue, or type the addresses.

Figure 6-27. Configured data trace range

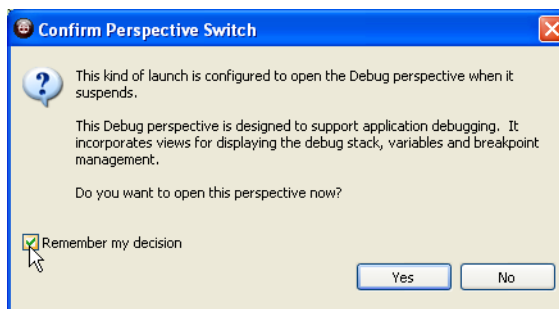


## 6.5 Start a debug session and configure the debugger for trace

Figure 6-28. Starting a debug session

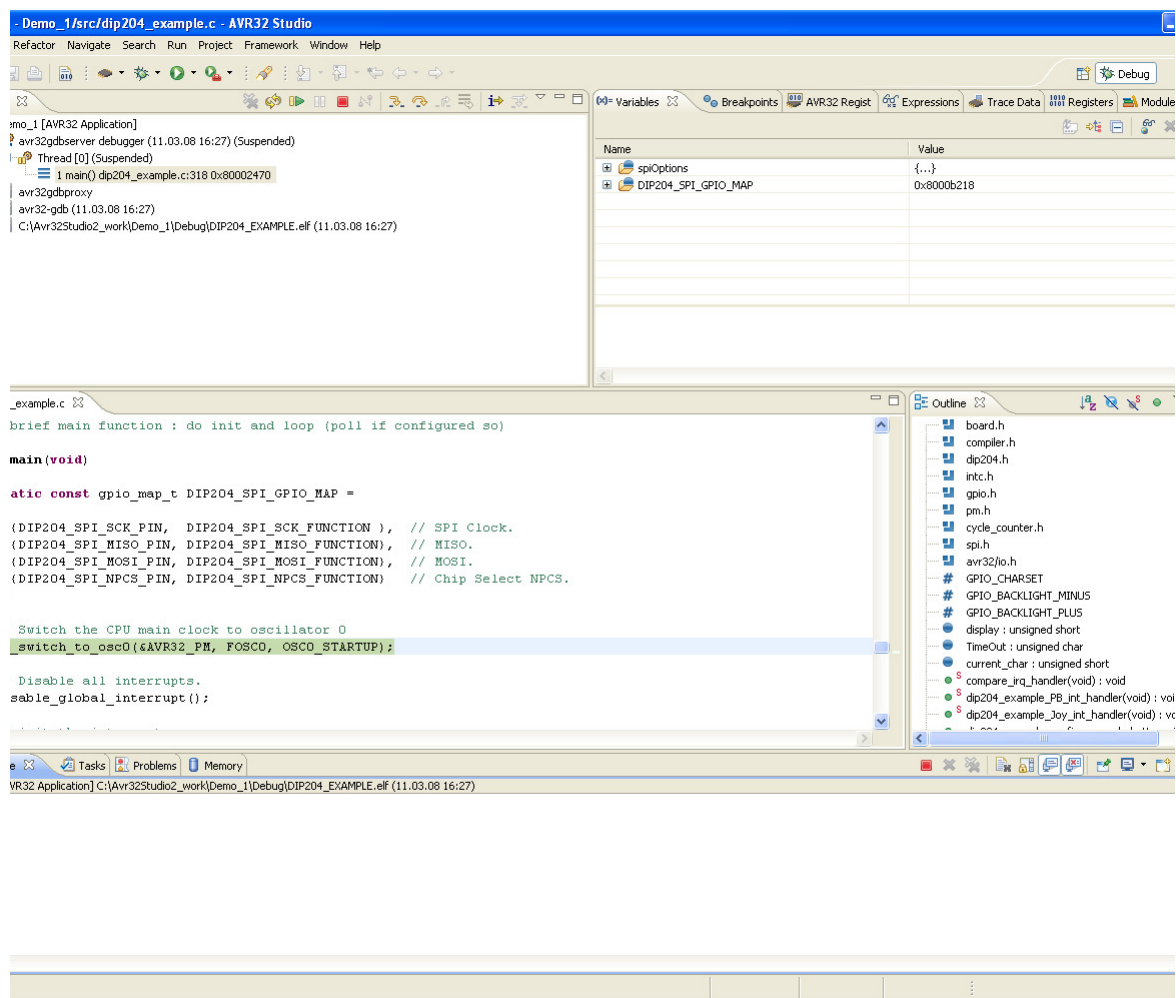


Click the **Debug** button. Now the program will be loaded into the target, and run until `main()`.

**Figure 6-29.** Switching perspective

When the debug session starts, AVR32 Studio 2.5 will change to the *Debug* perspective (desktop layout designed for use during debug sessions). You should click **Yes**. To avoid being asked every time you start a debug session, you should also click the **Remember my decision** box before answering **Yes**.

Wait until the target has stopped at the first instruction in the `main()` routine.

**Figure 6-30.** Program halted at `main()`

### 6.5.1 Add start and stop trace-points

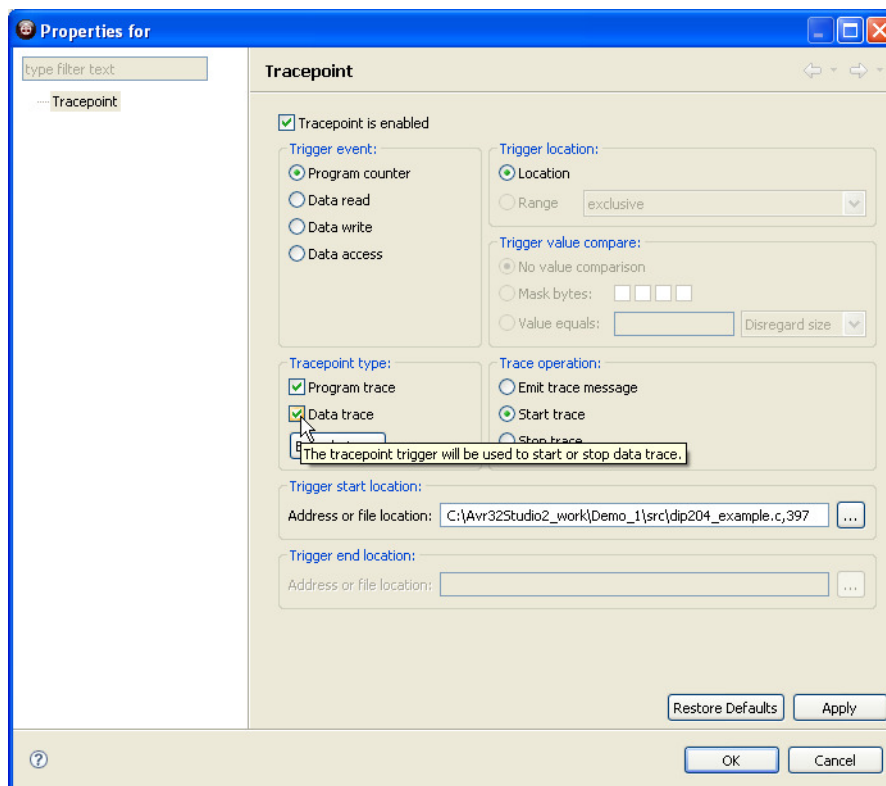
**Figure 6-31.** Source code editor

```
dip204_example.c
dip204_set_cursor_position(1,2);
dip204_write_string("EVK1100");
dip204_set_cursor_position(6,3);
dip204_write_string("AVR32 UC3");
dip204_set_cursor_position(3,4);
dip204_write_string("AT32UC3A Series");
dip204_hide_cursor();

/* do a loop */
while (1)
{
    if (display)
    {
        delay_ms(400); // A delay so that it is humanly possible to see the
                        // character(s) before they are cleared.
        // Clear line 1 column 19
        dip204_set_cursor_position(19,1);
        dip204_write_string(" ");
        // Clear line 2 from column 18 to column 20.
        dip204_set_cursor_position(18,2);
        dip204_write_string(" "); // 3 spaces
        // Clear line 3 column 19
        dip204_set_cursor_position(19,3);
        dip204_write_string(" ");
        display = 0;
    }
}
```

Scroll down to and select line 356 in the file DIP204\_Example.c and then select *Run>Toggle Trace Point*.

Figure 6-32. Tracepoint (Start)

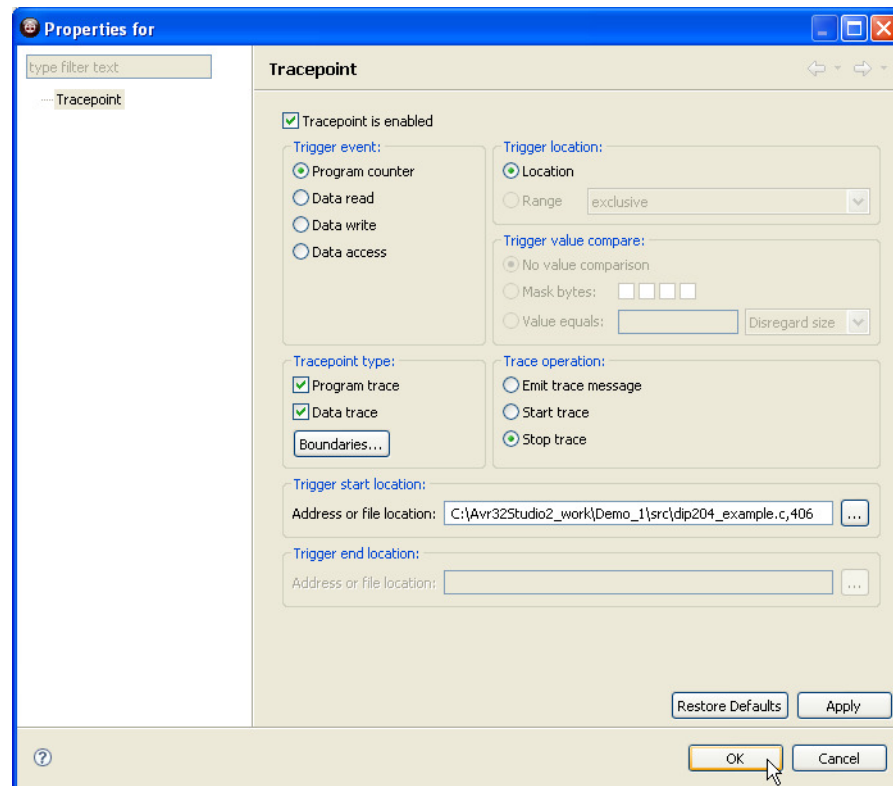


Set Tracepoint Configuration values:

- Set *Trigger Event* to *Program Counter*
- Set *Trace Operation* to *Start Trace*
- Set *Tracepoint type* to both *Program trace* and *Data trace*
- Click **OK**

This will create a tracepoint that starts both program and data trace when the program counter hits this code line.

Scroll down to and select line 364 in the file DIP204\_Example.c and then select *Run>Toggle Tracepoint*.

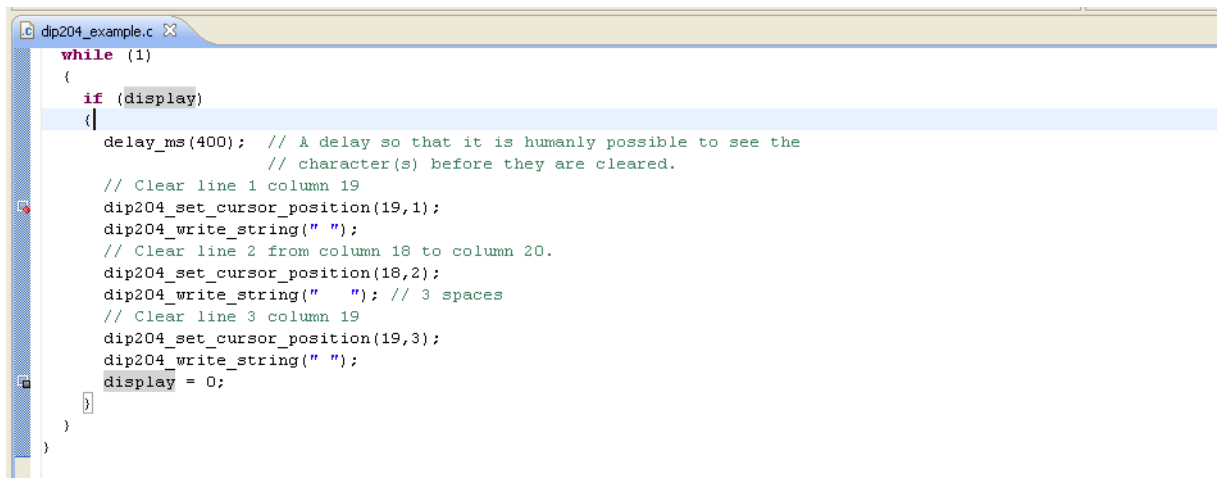
**Figure 6-33.** Tracepoint (Stop)

Set Tracepoint Configuration values:

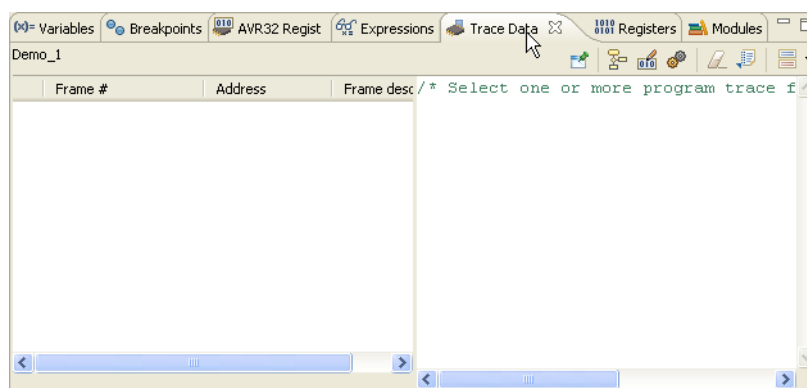
- Set *Trigger Event* to *Program Counter*
- Set *Trace Operation* to *Stop Trace*
- Set *Tracepoint type* to both *Program trace* and *Data trace*
- Click **OK**

This will create a tracepoint that stops both program and data trace when the program counter hits this code line.



**Figure 6-34.** Source editor with tracepoint indicators

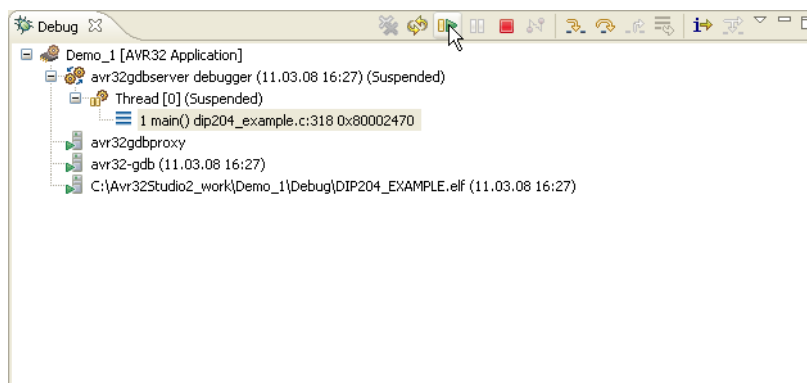
The source editor now has two tracepoint indicators next to the respective code lines.

**Figure 6-35.** Trace data view (empty)

Click on the **Trace Data** tab to bring the trace data view to the front.

## 6.6 Start the trace debug session

**Figure 6-36.** Resume debug session



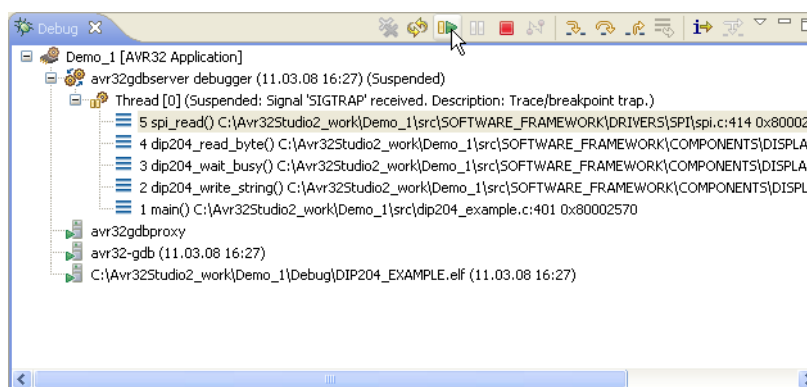
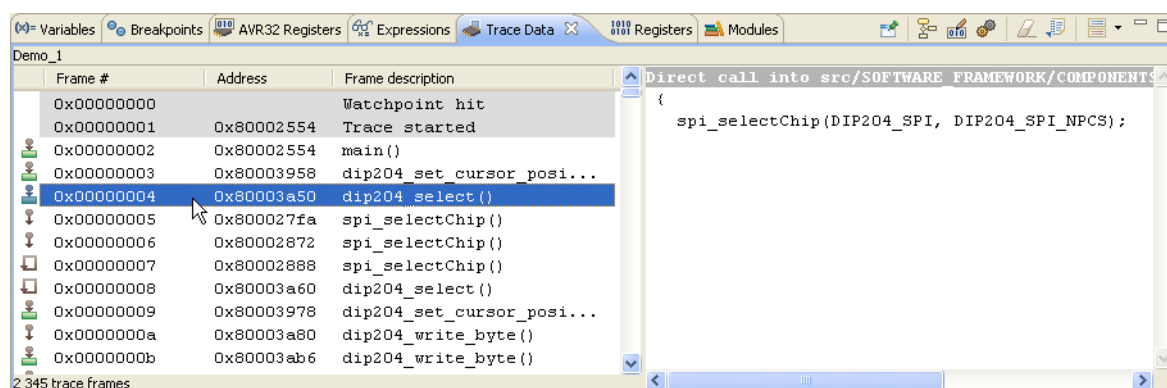
Make sure that the `main()` process is still selected in the *Debug* view before pressing the **Resume** button.

**Figure 6-37.** LCD Display showing original message

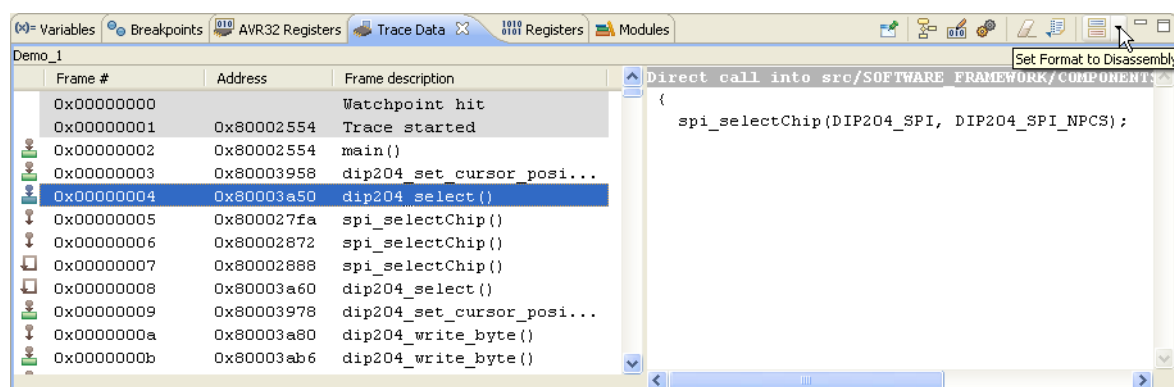


The display should look like this.

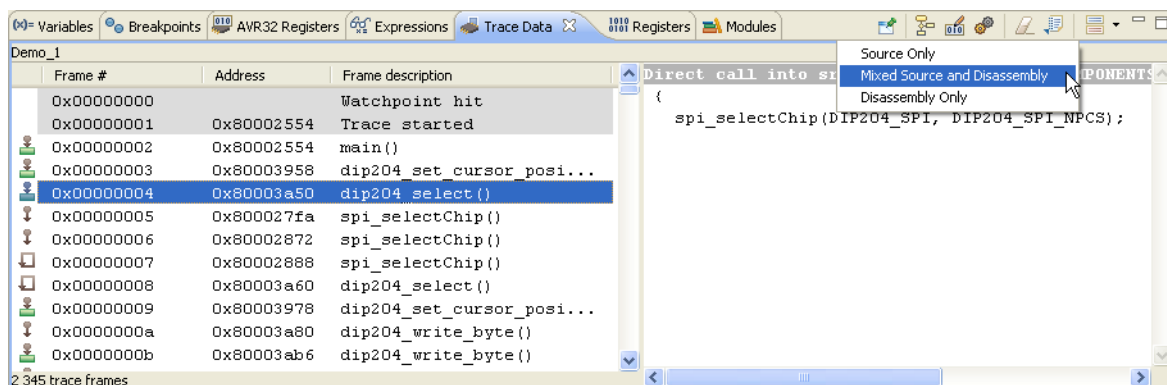
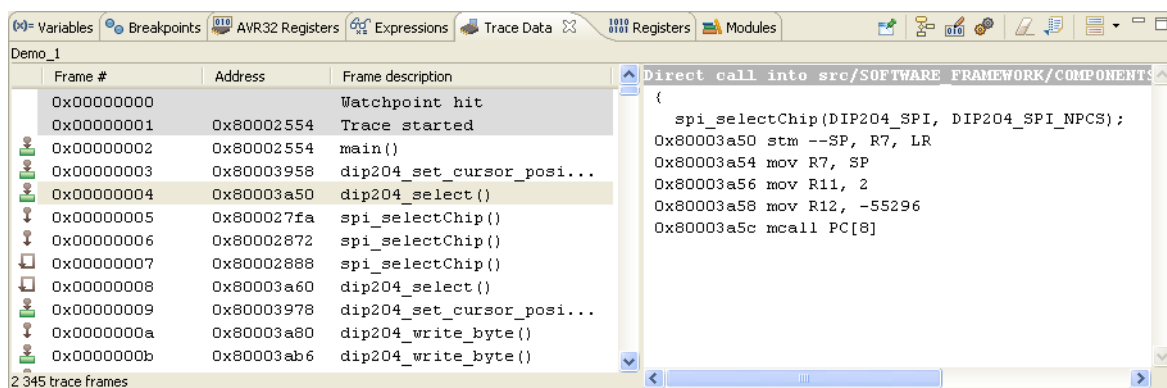
Push the joystick button on the EVK1100 evaluation board a few times, until the trace buffer is full and the target stops (6-7 button operations should be enough).

**Figure 6-38.** Target stopped because trace buffer full**Figure 6-39.** Trace data view (not empty)

Have a look at the trace data collected by clicking on a trace frame.

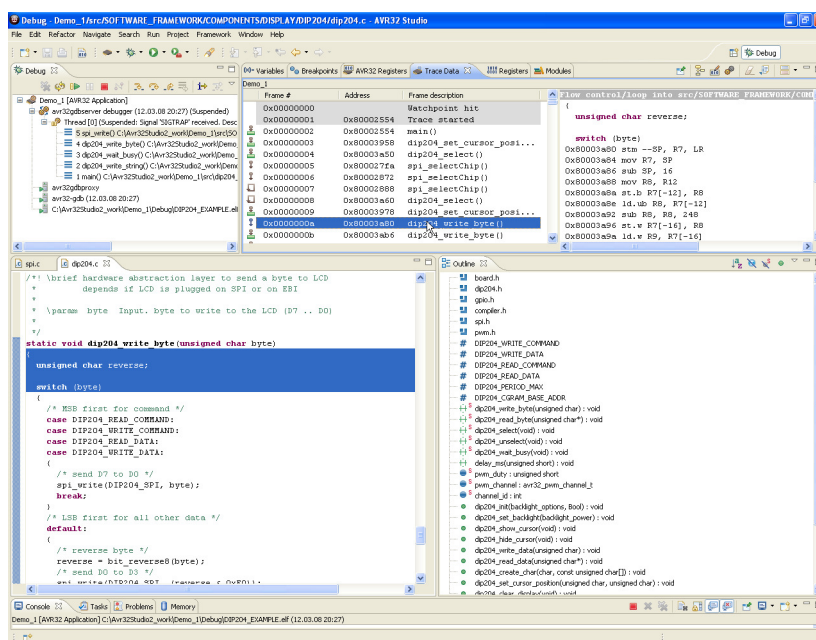
**Figure 6-40.** Changing trace view format

Change the format of the code view by opening the trace format menu (click the small arrow).

**Figure 6-41.** Set trace view format to *Mixed source and Disassembly***Figure 6-42.** Viewing Mixed source and disassembly trace data

Double-click on a trace frame to highlight source code in the source editor.

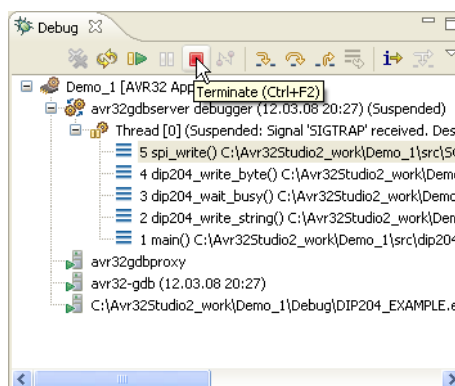
Figure 6-43. Trace frame highlighting source code registers in the editor



## 6.7 Modify the code and restart the debug session

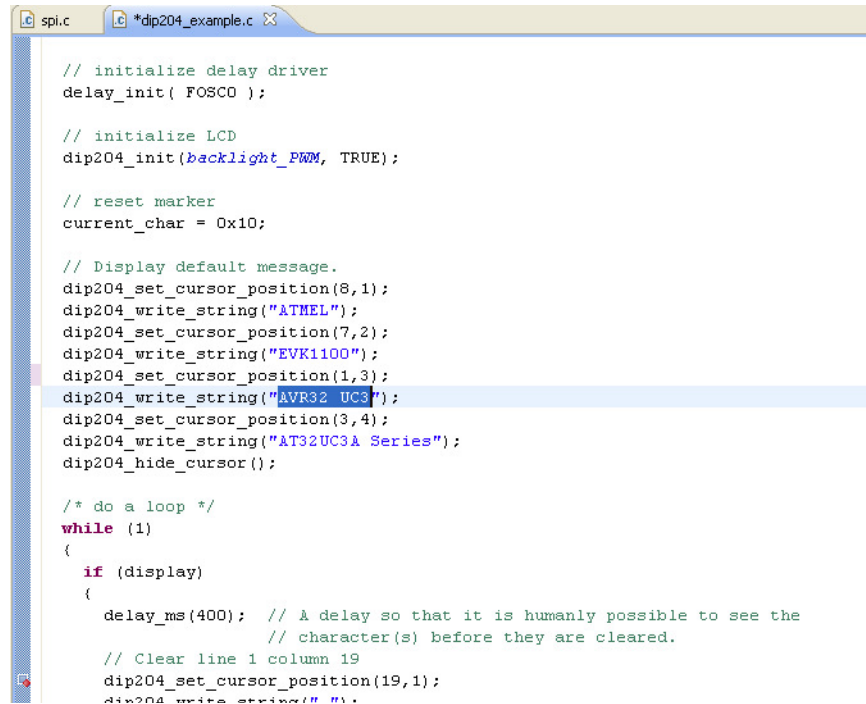
If we want to make changes to our code, we must stop the debug session, edit, rebuild and start the debug session again.

Figure 6-44. Terminating the debug session



Edit the source code. This example changes the cursor position in line 342 from (6,3) to (1,3), then the text in line 343.

**Figure 6-45.** Editing source code line 343



```

spi.c  *dip204_example.c
// initialize delay driver
delay_init( FOSCO );

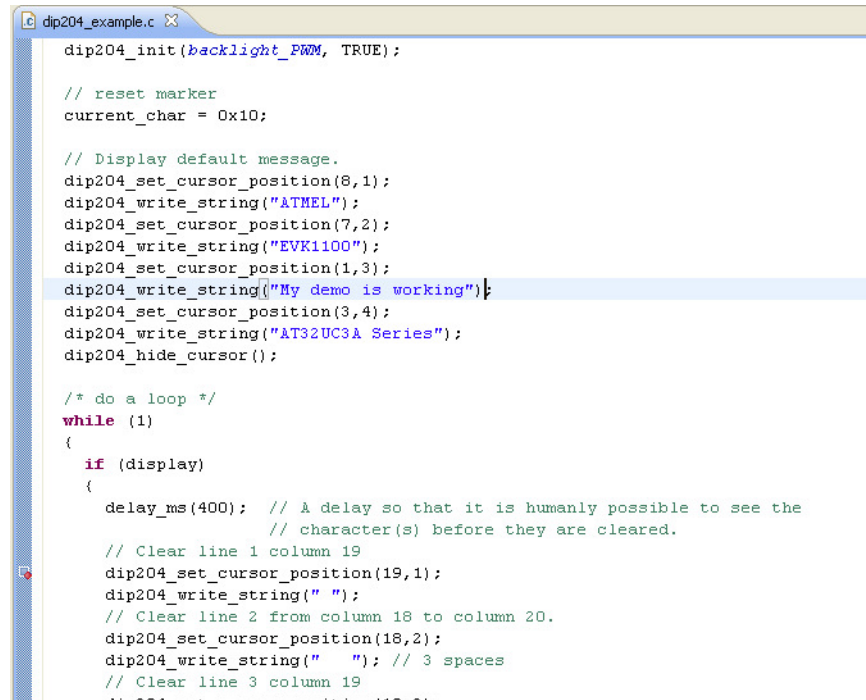
// initialize LCD
dip204_init(backlight_PWM, TRUE);

// reset marker
current_char = 0x10;

// Display default message.
dip204_set_cursor_position(8,1);
dip204_write_string("ATMEL");
dip204_set_cursor_position(7,2);
dip204_write_string("EVK1100");
dip204_set_cursor_position(1,3);
dip204_write_string("AVR32 UC3");
dip204_set_cursor_position(3,4);
dip204_write_string("AT32UC3A Series");
dip204_hide_cursor();

/* do a loop */
while (1)
{
    if (display)
    {
        delay_ms(400); // A delay so that it is humanly possible to see the
                      // character(s) before they are cleared.
        // Clear line 1 column 19
        dip204_set_cursor_position(19,1);
        dip204_write_string(" ");
    }
}

```

**Figure 6-46.** Source code edit finished


```

dip204_init(backlight_FWM, TRUE);

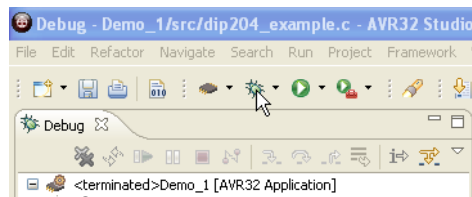
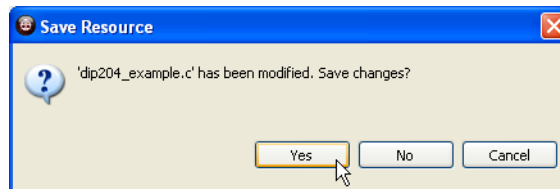
// reset marker
current_char = 0x10;

// Display default message.
dip204_set_cursor_position(8,1);
dip204_write_string("ATMEL");
dip204_set_cursor_position(7,2);
dip204_write_string("EVK1100");
dip204_set_cursor_position(1,3);
dip204_write_string("My demo is working");
dip204_set_cursor_position(3,4);
dip204_write_string("AT32UC3A Series");
dip204_hide_cursor();

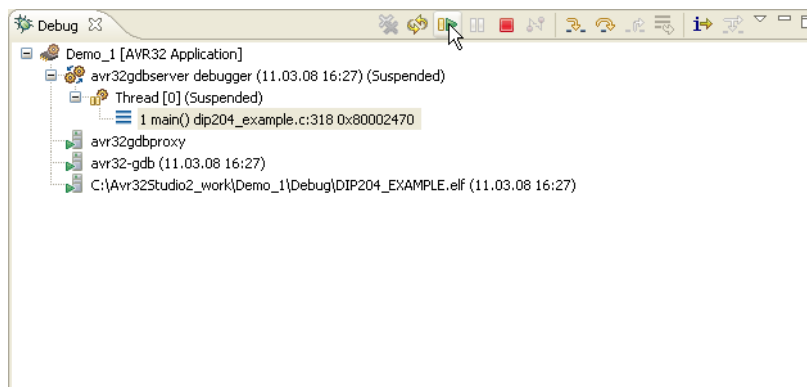
/* do a loop */
while (1)
{
    if (display)
    {
        delay_ms(400); // A delay so that it is humanly possible to see the
                      // character(s) before they are cleared.
        // Clear line 1 column 19
        dip204_set_cursor_position(19,1);
        dip204_write_string(" ");
        // Clear line 2 from column 18 to column 20.
        dip204_set_cursor_position(18,2);
        dip204_write_string("   "); // 3 spaces
        // Clear line 3 column 19
        dip204_set_cursor_position(19,3);
    }
}

```

Start a new debug session. AVR32 Studio uses the previous Launch Configuration if you just press the Debug button.

**Figure 6-47.** The Debug button**Figure 6-48.** Save edited source code dialog

Confirm saving the edited source code file. AVR32 Studio2.5 will now rebuild the project and program the target MCU FLASH. The code will run from start to main() and halt.

**Figure 6-49.** Resume button

Click “Resume” to start the application.

**Figure 6-50.** LCD Display showing edited message

The LCD display should now contain the edited message.

Congratulations! You have now created your first AVR32 application and collected real time trace data from the target MCU running your program using the AVR ONE!



### 7.1 Firmware upgrade overview

The tools (adapters) used to provide the physical connection between PC and target MCU contains firmware. This firmware needs to be compatible with the gnu toolchain and AVR32 Studio installed on the PC.

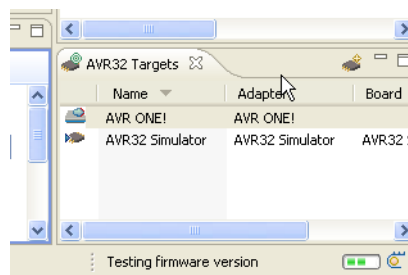
When AVR32 Studio is started, or when a new adapter is detected, AVR32 Studio will perform a firmware version check to determine if the adapter firmware needs to be upgraded.

If AVR32 Studio contains a newer firmware than present in the adapter, the adapter will be upgraded.

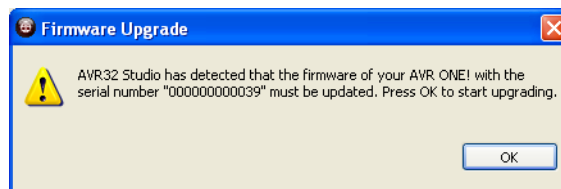
### 7.2 Firmware version test and upgrade

When AVR32 Studio is testing the firmware version of connected adapters, you can see a progress indicator in the status line.

**Figure 7-1.** Firmware version test



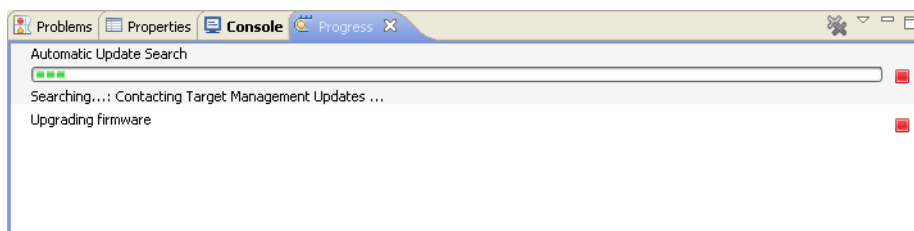
**Figure 7-2.** Firmware upgrade message



If the adapter firmware must be upgraded, you will be notified by a pop-up. Click **OK** to continue.

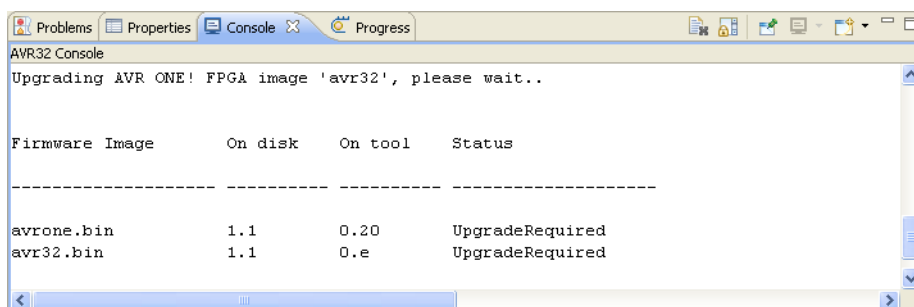
Firmware upgrade progress can be monitored by activating the *Progress* view.

**Figure 7-3.** Firmware upgrade progress



A firmware upgrade report can be found in the *Console* view.

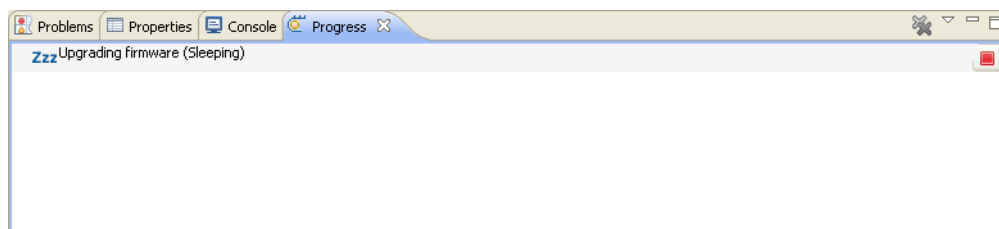
**Figure 7-4.** Firmware upgrade report



## 7.3 Adapter in use

The firmware version test is a process that is running in the background. This may cause a situation where the adapter is busy (debug session active) when AVR32 Studio determines that the firmware should be upgraded. In this case, the firmware upgrade process will wait until the adapter is not busy anymore (debug session terminated).

**Figure 7-5.** Firmware upgrade process waiting for adapter





## Headquarters

---

**Atmel Corporation**  
2325 Orchard Parkway  
San Jose, CA 95131  
USA  
Tel: 1(408) 441-0311  
Fax: 1(408) 487-2600

## International

---

**Atmel Asia**  
Room 1219  
Chinachem Golden Plaza  
77 Mody Road Tsimshatsui  
East Kowloon  
Hong Kong  
Tel: (852) 2721-9778  
Fax: (852) 2722-1369

**Atmel Europe**  
Le Krebs  
8, Rue Jean-Pierre Timbaud  
BP 309  
78054 Saint-Quentin-en-  
Yvelines Cedex  
France  
Tel: (33) 1-30-60-70-00  
Fax: (33) 1-30-60-71-11

**Atmel Japan**  
9F, Tonetsu Shinkawa Bldg.  
1-24-8 Shinkawa  
Chuo-ku, Tokyo 104-0033  
Japan  
Tel: (81) 3-3523-3551  
Fax: (81) 3-3523-7581

## Product Contact

---

**Web Site**  
[www.atmel.com/avrone](http://www.atmel.com/avrone)

**Technical Support**  
[avr32@atmel.com](mailto:avr32@atmel.com)

**Sales Contact**  
[www.atmel.com/contacts](http://www.atmel.com/contacts)

**Literature Requests**  
[www.atmel.com/literature](http://www.atmel.com/literature)

---

**Disclaimer:** The information in this document is provided in connection with Atmel products. No license, express or implied, by estoppel or otherwise, to any intellectual property right is granted by this document or in connection with the sale of Atmel products. **EXCEPT AS SET FORTH IN ATMEL'S TERMS AND CONDITIONS OF SALE LOCATED ON ATMEL'S WEB SITE, ATMEL ASSUMES NO LIABILITY WHATSOEVER AND DISCLAIMS ANY EXPRESS, IMPLIED OR STATUTORY WARRANTY RELATING TO ITS PRODUCTS INCLUDING, BUT NOT LIMITED TO, THE IMPLIED WARRANTY OF MERCHANTABILITY, FITNESS FOR A PARTICULAR PURPOSE, OR NON-INFRINGEMENT. IN NO EVENT SHALL ATMEL BE LIABLE FOR ANY DIRECT, INDIRECT, CONSEQUENTIAL, PUNITIVE, SPECIAL OR INCIDENTAL DAMAGES (INCLUDING, WITHOUT LIMITATION, DAMAGES FOR LOSS OF PROFITS, BUSINESS INTERRUPTION, OR LOSS OF INFORMATION) ARISING OUT OF THE USE OR INABILITY TO USE THIS DOCUMENT, EVEN IF ATMEL HAS BEEN ADVISED OF THE POSSIBILITY OF SUCH DAMAGES.** Atmel makes no representations or warranties with respect to the accuracy or completeness of the contents of this document and reserves the right to make changes to specifications and product descriptions at any time without notice. Atmel does not make any commitment to update the information contained herein. Unless specifically provided otherwise, Atmel products are not suitable for, and shall not be used in, automotive applications. Atmel's products are not intended, authorized, or warranted for use as components in applications intended to support or sustain life.

© 2008 Atmel Corporation. All rights reserved. Atmel®, logo and combinations thereof, AVR® and others, are the registered trademarks or trademarks of Atmel Corporation or its subsidiaries. Windows® and others are registered trademarks or trademarks of Microsoft Corporation in the US and/or other countries. Other terms and product names may be trademarks of others.

Компания «Океан Электроники» предлагает заключение долгосрочных отношений при поставках импортных электронных компонентов на взаимовыгодных условиях!

Наши преимущества:

- Поставка оригинальных импортных электронных компонентов напрямую с производств Америки, Европы и Азии, а так же с крупнейших складов мира;
- Широкая линейка поставок активных и пассивных импортных электронных компонентов (более 30 млн. наименований);
- Поставка сложных, дефицитных, либо снятых с производства позиций;
- Оперативные сроки поставки под заказ (от 5 рабочих дней);
- Экспресс доставка в любую точку России;
- Помощь Конструкторского Отдела и консультации квалифицированных инженеров;
- Техническая поддержка проекта, помощь в подборе аналогов, поставка прототипов;
- Поставка электронных компонентов под контролем ВП;
- Система менеджмента качества сертифицирована по Международному стандарту ISO 9001;
- При необходимости вся продукция военного и аэрокосмического назначения проходит испытания и сертификацию в лаборатории (по согласованию с заказчиком);
- Поставка специализированных компонентов военного и аэрокосмического уровня качества (Xilinx, Altera, Analog Devices, Intersil, Interpoint, Microsemi, Actel, Aeroflex, Peregrine, VPT, Syfer, Eurofarad, Texas Instruments, MS Kennedy, Miteq, Cobham, E2V, MA-COM, Hittite, Mini-Circuits, General Dynamics и др.);

Компания «Океан Электроники» является официальным дистрибьютором и эксклюзивным представителем в России одного из крупнейших производителей разъемов военного и аэрокосмического назначения «JONHON», а так же официальным дистрибьютором и эксклюзивным представителем в России производителя высокотехнологичных и надежных решений для передачи СВЧ сигналов «FORSTAR».



## JONHON

«JONHON» (основан в 1970 г.)

Разъемы специального, военного и аэрокосмического назначения:

(Применяются в военной, авиационной, аэрокосмической, морской, железнодорожной, горно- и нефтедобывающей отраслях промышленности)

«FORSTAR» (основан в 1998 г.)

ВЧ соединители, коаксиальные кабели,  
кабельные сборки и микроволновые компоненты:

(Применяются в телекоммуникациях гражданского и специального назначения, в средствах связи, РЛС, а так же военной, авиационной и аэрокосмической отраслях промышленности).



Телефон: 8 (812) 309-75-97 (многоканальный)

Факс: 8 (812) 320-03-32

Электронная почта: [ocean@oceanchips.ru](mailto:ocean@oceanchips.ru)

Web: <http://oceanchips.ru/>

Адрес: 198099, г. Санкт-Петербург, ул. Калинина, д. 2, корп. 4, лит. А