

### GENERAL DESCRIPTION

The XRP7664 is a synchronous current-mode PWM step down (buck) regulator capable of a constant output current up to 2Amps. A wide 4.75V to 18V input voltage range allows for single supply operations from industry standard 5V and 12V power rails.

With a 340kHz constant operating frequency and integrated high and low side 120mΩ/110mΩ MOSFETs, the XRP7664 reduces the overall component count and solution footprint. Current-mode control provides fast transient response and cycle-by-cycle current limit. An adjustable soft-start prevents inrush current at turn-on, and in shutdown mode the supply current drops to 0.1uA.

Built-in output over voltage (open load), over temperature, cycle-by-cycle over current and under voltage lockout (UVLO) protections insure safe operations under abnormal operating conditions.

The XRP7664 is a pin and function compatible device to MP1482.

The XRP7664 is offered in a RoHS compliant, "green"/halogen free 8-pin SOIC package.

### APPLICATIONS

- Distributed Power Architectures
- Point of Load Converters
- Audio-Video Equipments
- Medical & Industrial Equipments

### FEATURES

- Pin/Function Compatible to MP1482
- 2A Continuous Output Current
- 4.75V to 18V Wide Input Voltage
- PWM Current Mode Control
  - 340kHz Constant Operations
  - Up to 93% Efficiency
- Adjustable Output Voltage
  - 0.925V to 16V Range
  - 3% Accuracy
- Programmable Soft-Start and Enable Function
- Built-in Thermal, Over Current, UVLO and Output Over Voltage Protections
- RoHS Compliant, "Green"/Halogen Free 8-Pin SOIC Package

### TYPICAL APPLICATION DIAGRAM

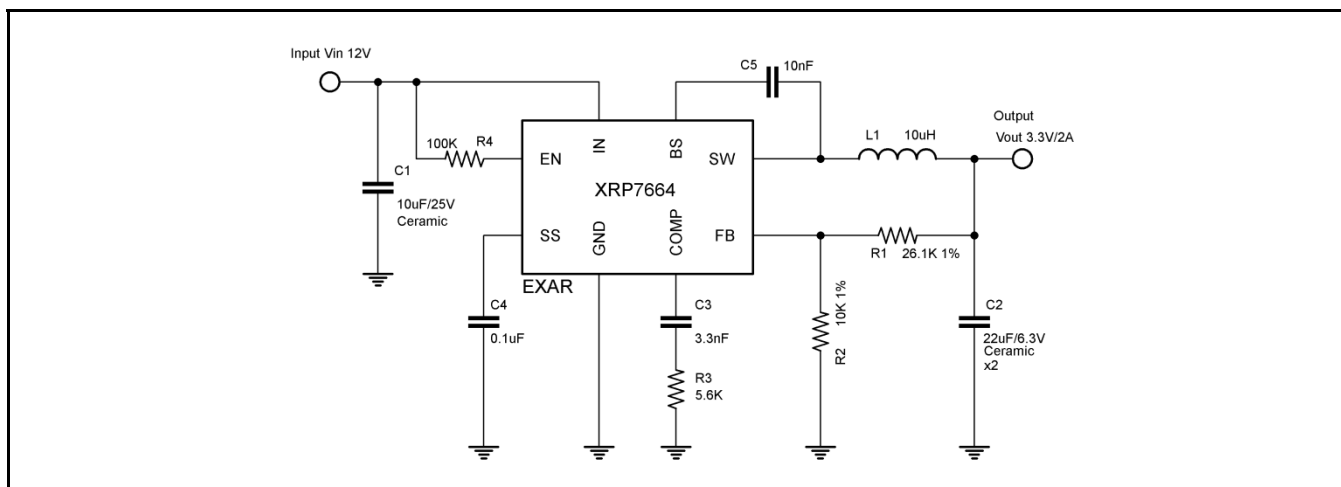


Fig. 1: XRP7664 Application Diagram

**ABSOLUTE MAXIMUM RATINGS**

These are stress ratings only and functional operation of the device at these ratings or any other above those indicated in the operation sections of the specifications below is not implied. Exposure to absolute maximum rating conditions for extended periods of time may affect reliability.

Supply Voltage  $V_{IN}$  ..... -0.3V to 20V  
 Switch Node Voltage  $V_{SW}$  ..... 21V  
 Boost Voltage  $V_{BS}$  ..... -0.3 to  $V_{SW}+6V$   
 Enable Voltage  $V_{EN}$  ..... -0.3 to  $V_{IN}$   
 All Other Pins ..... -0.3 to +6V  
 Junction Temperature ..... 150°C  
 Storage Temperature ..... -65°C to 150°C  
 Lead Temperature (Soldering, 10 sec) ..... 260°C  
 ESD Rating (HBM - Human Body Model) ..... 2kV  
 ESD Rating (MM - Machine Model) ..... 200V  
 Moisture Sensitivity Level (MSL) ..... 3

**OPERATING RATINGS**

Input Voltage  $V_{IN}$  ..... 4.75V to 18V  
 Ambient Operating Temperature ..... -40°C to 85°C  
 Maximum Output Current ..... 2A min  
 Thermal Resistance  $\theta_{JA}$  ..... 105°C/W

**ELECTRICAL SPECIFICATIONS**

Specifications are for an Operating Ambient Temperature of  $T_A = 25^\circ\text{C}$  only; limits applying over the full Ambient Operating Temperature range are denoted by a "•". Minimum and Maximum limits are guaranteed through test, design, or statistical correlation. Typical values represent the most likely parametric norm at  $T_A = 25^\circ\text{C}$ , and are provided for reference purposes only. Unless otherwise indicated,  $V_{IN} = V_{EN} = 12V$ ,  $V_{OUT} = 3.3V$ .

| Parameter                                             | Min.  | Typ.  | Max.  | Units           | Conditions                                       |
|-------------------------------------------------------|-------|-------|-------|-----------------|--------------------------------------------------|
| Shutdown Supply Current                               |       | 0.1   | 10    | $\mu\text{A}$   | $V_{EN}=0V$                                      |
| Quiescent Current                                     |       | 1.0   | 1.2   | mA              | $V_{EN}=2V$ , $V_{FB}=1V$                        |
| Feedback Voltage $V_{FB}$                             | 0.900 | 0.925 | 0.950 | V               | •                                                |
| Feedback Overvoltage Threshold                        |       | 1.1   |       | V               |                                                  |
| Error Amplifier Voltage Gain $A_{EA}$<br>(Note 1)     |       | 400   |       | V/V             |                                                  |
| Error Amplifier Transconductance $G_{EA}$             |       | 800   |       | $\mu\text{A/V}$ |                                                  |
| High-Side switch On Resistance $R_{DS(ON)H}$ (Note 2) |       | 120   |       | m $\Omega$      | $I_{SW}=0.2A\&0.7A$                              |
| Low-Side switch On Resistance $R_{DS(ON)L}$ (Note 2)  |       | 110   |       | m $\Omega$      | $I_{SW}=-0.2A\&-0.7A$                            |
| High-Side switch Leakage Current                      |       | 0.1   | 10    | $\mu\text{A}$   | $V_{IN}=18V$ , $V_{EN}=0V$ , $V_{SW}=0V$         |
| High-Side Switch Current Limit                        | 2.7   | 3.5   | 4.3   | A               |                                                  |
| Low-Side Switch Current Limit                         |       | 1.4   |       | A               | From Drain to Source                             |
| COMP to Current Sense Transconductance $G_{CS}$       |       | 3.5   |       | A/V             |                                                  |
| Oscillator Frequency $F_{OSC1}$                       | 300   | 340   | 380   | kHz             |                                                  |
| Short Circuit Oscillator Frequency $F_{OSC2}$         |       | 90    |       | kHz             |                                                  |
| Maximum Duty Cycle $D_{MAX}$                          |       | 90    |       | %               | $V_{FB}=0.85V$                                   |
| Minimum Duty Cycle $D_{MIN}$                          |       |       | 0     | %               | $V_{FB}=1V$                                      |
| EN Threshold $V_{ENH}$                                | 1.5   |       |       | V               |                                                  |
| EN Threshold $V_{ENL}$                                |       |       | 0.5   | V               |                                                  |
| UVLO Threshold                                        | 3.65  | 4.00  | 4.45  | V               | $V_{IN}$ Rising                                  |
| UVLO Hysteresis                                       |       | 0.30  |       | V               |                                                  |
| Soft-start Current                                    |       | 6     |       | $\mu\text{A}$   |                                                  |
| Soft-start Time (Note 1)                              |       | 10    |       | ms              | $C_{SS}=0.1\mu\text{F}$ , $I_{OUT}=500\text{mA}$ |

| Parameter                            | Min. | Typ. | Max. | Units | Conditions  |
|--------------------------------------|------|------|------|-------|-------------|
| Thermal Shutdown (Note 1)            |      | 160  |      | °C    |             |
| Thermal Shutdown Hysteresis (Note 1) |      | 30   |      | °C    |             |
| Feedback Bias Current                | -0.1 |      | 0.1  | μA    | $V_{FB}=1V$ |

Note 1: Guaranteed by design.

Note 2:  $R_{DS(on)} = (V_{SW1} - V_{SW2}) / (I_{SW1} - I_{SW2})$

### BLOCK DIAGRAM

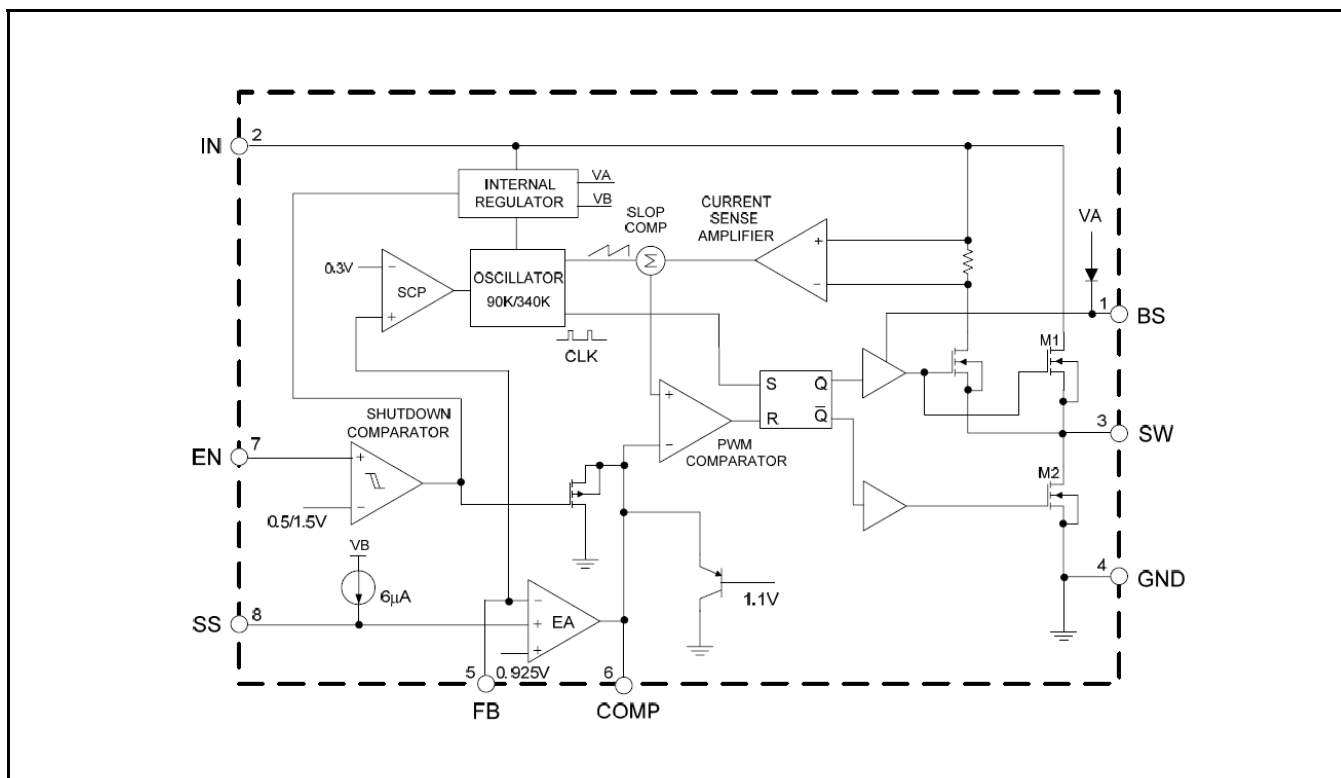


Fig. 2: XRP7664 Block Diagram

### PIN ASSIGNMENT

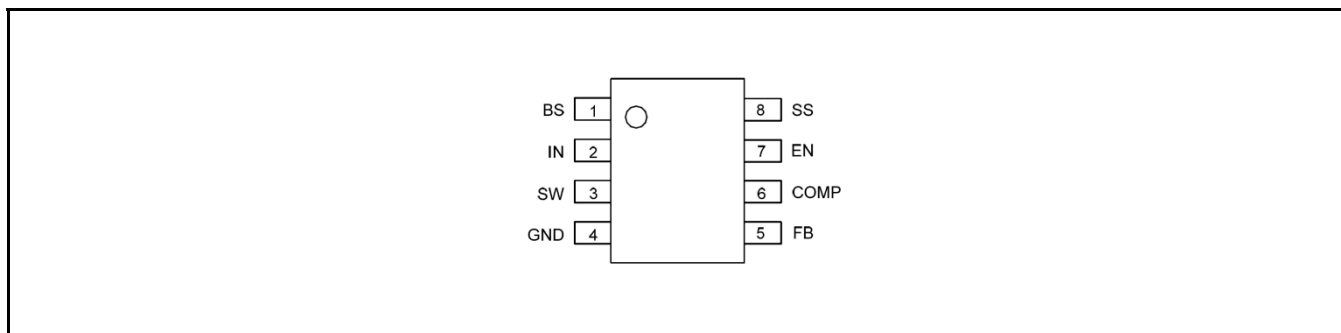


Fig. 3: XRP7664 Pin Assignment (SOIC-8)



# XRP7664

## 2A 18V Synchronous Step-Down Converter

### PIN DESCRIPTION

| Name | Pin Number | Description                                                                                                                                                                                                                                                                             |
|------|------------|-----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| BS   | 1          | Bootstrap pin.<br>Connect a 0.01 $\mu$ F or greater bootstrap capacitor between the BS pin and the SW pin. The voltage across the bootstrap capacitor drives the internal high-side power MOSFET.                                                                                       |
| IN   | 2          | Power input pin.<br>A capacitor should be connected between the IN pin and GND pin to keep the input voltage constant.                                                                                                                                                                  |
| SW   | 3          | Power switch output pin.<br>This pin is connected to the inductor and the bootstrap capacitor.                                                                                                                                                                                          |
| GND  | 4          | Ground signal pin.                                                                                                                                                                                                                                                                      |
| FB   | 5          | Feedback pin.<br>An external resistor divider connected to FB programs the output voltage. If the feedback pin exceeds 1.1V the over-voltage protection will trigger. If the feedback voltage drops below 0.3V the oscillator frequency is lowered to achieve short-circuit protection. |
| COMP | 6          | Compensation pin.<br>This is the output of transconductance error amplifier and the input to the current comparator. It is used to compensate the control loop. Connect an RC network from this pin to GND.                                                                             |
| EN   | 7          | Control input pin.<br>Forcing this pin above 1.5V enables the IC. Forcing this pin below 0.5V shuts down the IC. When the IC is in shutdown mode all functions are disabled to decrease the supply current below 1 $\mu$ A.                                                             |
| SS   | 8          | Soft-start control input pin.<br>Connect a capacitor from SS to GND to set the soft-start period. A 0.1 $\mu$ F capacitor sets the soft start period to 10ms. To disable the soft-start feature, leave SS unconnected.                                                                  |

### ORDERING INFORMATION

| Part Number   | Temperature Range                        | Marking                | Package | Packing Quantity | Note 1                         | Note 2 |
|---------------|------------------------------------------|------------------------|---------|------------------|--------------------------------|--------|
| XRP7664IDTR-F | -40°C $\leq$ T <sub>A</sub> $\leq$ +85°C | XRP7664I<br>YYWWF<br>X | SOIC-8  | 2.5K/Tape & Reel | RoHS Compliant<br>Halogen Free |        |
| XRP7664EVB    | XRP7664 Evaluation Board                 |                        |         |                  |                                |        |

“YY” = Year – “WW” = Work Week – “X” = Lot Number; when applicable.

### TYPICAL PERFORMANCE CHARACTERISTICS

All data taken at  $V_{IN} = 12V$ ,  $V_{OUT}=3.3V$ ,  $T_J = T_A = 25^{\circ}C$ , unless otherwise specified - Schematic and BOM from Application Information section of this datasheet.

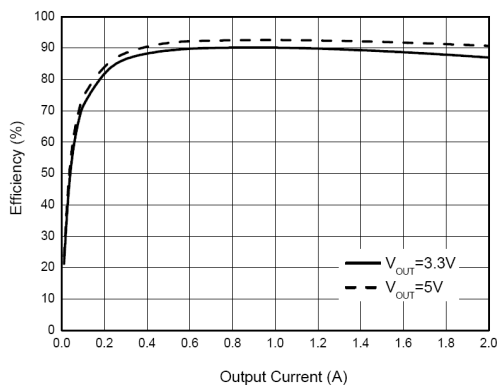


Fig. 4: Efficiency versus output current

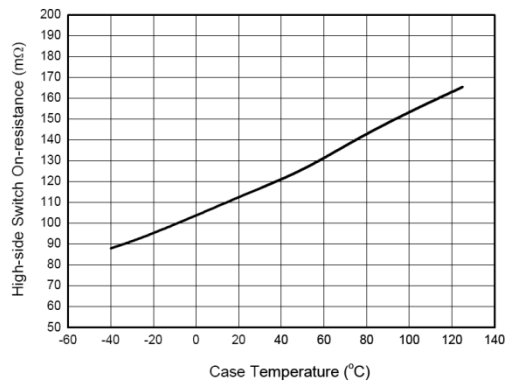


Fig. 5:  $R_{DS(on)}$  versus case temperature

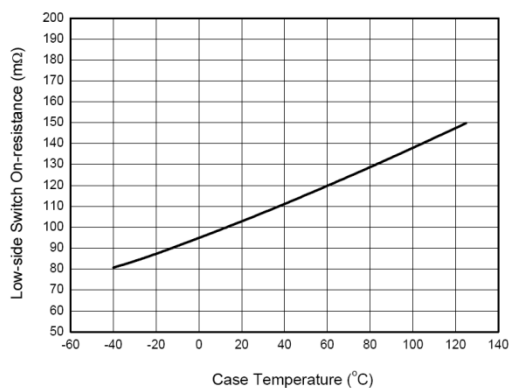


Fig. 6:  $R_{DS(on)}$  versus case temperature

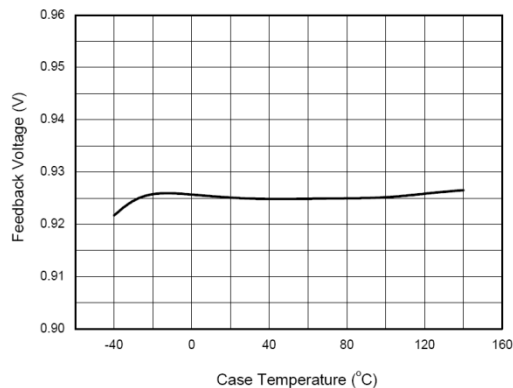


Fig. 7: Feedback voltage versus case temperature

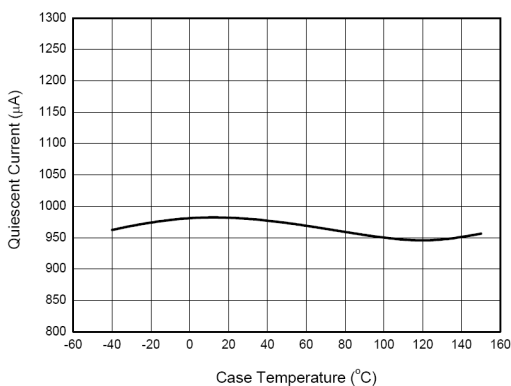


Fig. 8: Quiescent current versus case temperature

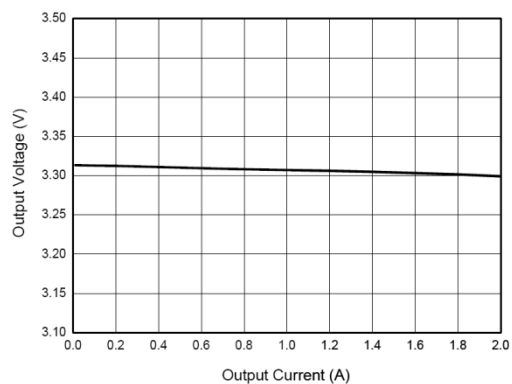


Fig. 9: Output voltage versus output current

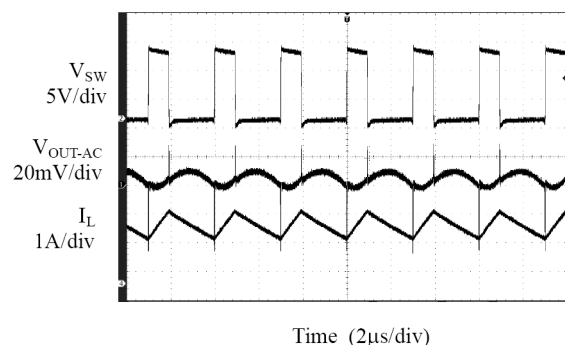


Fig. 10: Output voltage ripple,  $I_{OUT}=2A$

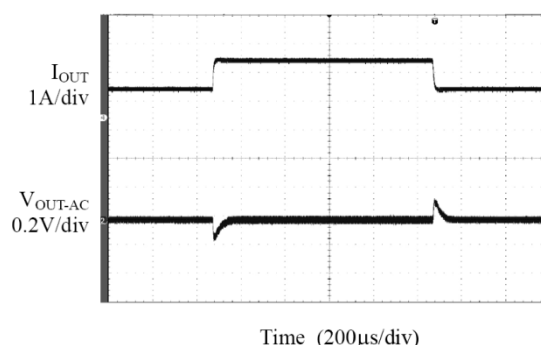


Fig. 11: Load transient ( $I_{OUT}=1A$  to  $2A$ )

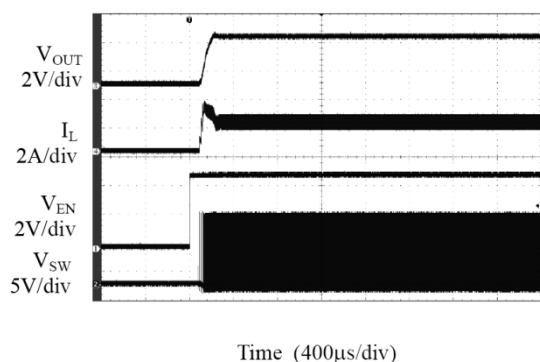


Fig. 12: Enable turn on ( $R_{LOAD}=1.6\Omega$ )

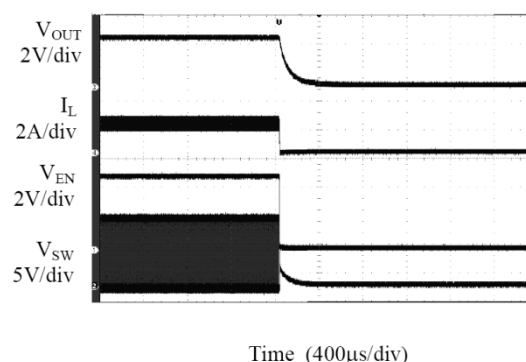


Fig. 13: Enable turn off ( $R_{LOAD}=1.6\Omega$ )

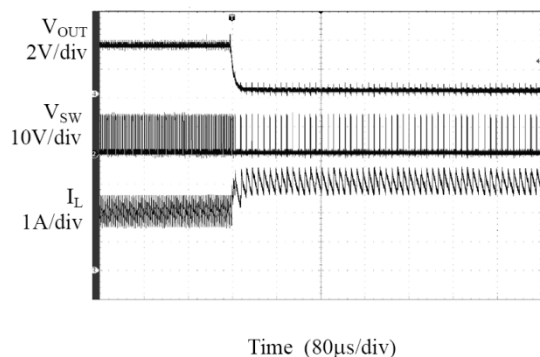


Fig. 14: Short-circuit protection,  $I_{OUT}=2A$

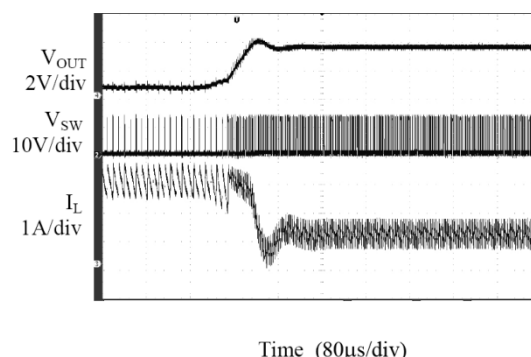


Fig. 15: Short-circuit recovery,  $I_{OUT}=2A$



## THEORY OF OPERATION

### FUNCTIONAL DESCRIPTION

The XRP7664 is a synchronous, current-mode, step-down regulator. It regulates input voltages from 4.75V to 18V and supplies up to 2A of load current. The XRP7664 uses current-mode control to regulate the output voltage. The output voltage is measured at FB through a resistive voltage divider and input to a transconductance error amplifier. The high-side switch current is compared to the output of the error amplifier to control the output voltage. The regulator utilizes internal N-channel MOSFETs to step-down the input voltage. A bootstrapping capacitor connected between BS and SW acts as a supply for high-side MOSFET. This capacitor is charged from the internal 5V supply when SW node is low. The XRP7664 has several powerful protection features including OCP, OVP, OTP, UVLO and output short-circuit.

### PROGRAMMABLE SOFT-START

The soft-start time is fully programmable via CSS capacitor, placed between the SS and GND pin. The CSS is charged by a 6μA constant-current source, generating a ramp signal fed into non-inverting input of the error amplifier. This ramp regulates the voltage on comp pin during the regulator startup, thus realizing soft-start. Calculate the required CSS from:

$$CSS = tss \times \frac{6\mu A}{V_{FB}}$$

Where:

tss is the required soft-start time

V<sub>FB</sub> is the feedback voltage (0.925V nominal)

### OVERCURRENT PROTECTION OCP

The OCP protects against accidental increase in load current that can cause the regulator to fail. The current of internal switch M1 is monitored. If this current reaches 3.5A then M1 is turned off until next switching cycle.

### SHORT-CIRCUIT PROTECTION

If there is short-circuit across the output, the feedback voltage V<sub>FB</sub> will droop. If V<sub>FB</sub> drops below 0.3V the XRP7664 will detect a short-circuit condition and reduce the switching frequency to 90kHz for system protection. The regulator will restart once the short-circuit has been removed.

### OVERVOLTAGE PROTECTION OVP

The XRP7664 has internal OVP. When V<sub>OUT</sub> exceeds the OVP threshold (when V<sub>FB</sub> exceeds 1.1V) the power switching will be turned off. The XRP7664 will restart when overvoltage condition is removed.

### OVER-TEMPERATURE PROTECTION OTP

If the junction temperature exceeds 160°C the OTP circuit is triggered, turning off the internal control circuit and switched M1 and M2. When junction temperature drops below 130°C the XRP7664 will restart.

## APPLICATION INFORMATION

### SETTING THE OUTPUT VOLTAGE

Use an external resistor divider to set the output voltage. Program the output voltage from:

$$R1 = R2 \times \left( \frac{V_{OUT}}{0.925V} - 1 \right)$$

Where:

R1 is the resistor between V<sub>OUT</sub> and FB

R2 is the resistor between FB and GND (nominally 10kΩ)

0.925V is the nominal feedback voltage.

### OUTPUT INDUCTOR

Select the output inductor for inductance L, DC current rating I<sub>DC</sub> and saturation current rating I<sub>SAT</sub>. I<sub>DC</sub> should be larger than regulator output current. I<sub>SAT</sub>, as a rule of thumb, should be 50% higher than the regulator output current. Since the regulator is rated at 2A then I<sub>DC</sub> ≥ 2A and I<sub>SAT</sub> ≥ 3A. Calculate the inductance from:

## 2A 18V Synchronous Step-Down Converter

$$L = (V_{IN} - V_{OUT}) \left( \frac{V_{OUT}}{\Delta I_L \times f_s \times V_{IN}} \right)$$

Where:

$\Delta I_L$  is peak-to-peak inductor current ripple nominally set to 30%-40% of  $I_{OUT}$

$f_s$  is nominal switching frequency (340kHz)

As an example, inductor values for several common output voltages are shown in tables 1 and 2. Note that example inductors shown in tables 1 and 2 are COOPER-Bussmann shielded inductors. If the target application is not sensitive to EMI then unshielded inductors may be used.

| VOUT(V) | $\Delta I_{L(p-p)}$ (A) | L( $\mu$ H) | Inductor Example |
|---------|-------------------------|-------------|------------------|
| 5.0     | 0.86                    | 10          | DR74-100-R       |
| 3.3     | 0.70                    | 10          | DR74-100-R       |
| 2.5     | 0.70                    | 8.2         | DR74-8R2-R       |
| 1.8     | 0.66                    | 6.8         | DR74-6R8-R       |
| 1.5     | 0.57                    | 6.8         | DR74-6R8-R       |
| 1.2     | 0.68                    | 4.7         | DR74-4R7-R       |

Table 1. Suggested inductor values for  $V_{IN}=12V$  and  $I_{OUT}=2A$

| VOUT(V) | $\Delta I_{L(p-p)}$ (A) | L( $\mu$ H) | Inductor Example |
|---------|-------------------------|-------------|------------------|
| 3.3     | 0.70                    | 4.7         | DR74-4R7-R       |
| 2.5     | 0.78                    | 4.7         | DR74-4R7-R       |
| 1.8     | 0.72                    | 4.7         | DR74-4R7-R       |
| 1.5     | 0.66                    | 4.7         | DR74-4R7-R       |
| 1.2     | 0.57                    | 4.7         | DR74-4R7-R       |

Table 2. Suggested inductor values for  $V_{IN}=5V$  and  $I_{OUT}=2A$

### OUTPUT CAPACITOR $C_{OUT}$

Select the output capacitor for voltage rating, capacitance  $C_{OUT}$  and Equivalent Series Resistance ESR. The voltage rating, as a rule of thumb, should be at least twice the output voltage. When calculating the required capacitance, usually the overriding requirement is current load-step transient. If the unloading transient (i.e., when load transitions from a high to a low current) is met, then usually the loading transient (when

load transitions from a low to a high current) is met as well. Therefore calculate the  $C_{OUT}$  based on the unloading transient requirement from:

$$C_{OUT} = L \times \left( \frac{I_{High}^2 - I_{Low}^2}{(V_{OUT} + V_{transient})^2 - V_{OUT}^2} \right)$$

Where:

L is the inductance calculated in the preceding step

$I_{High}$  is the value of load-step prior to unloading. This is nominally set equal to regulator current rating (2A).

$I_{Low}$  is the value of load-step after unloading. This is nominally set equal to 50% of regulator current rating (1A).

$V_{transient}$  is the maximum permissible voltage transient corresponding to the load step mentioned above.  $V_{transient}$  is typically specified from 3% to 5% of  $V_{OUT}$ .

ESR of the capacitor has to be selected such that the output voltage ripple requirement  $\Delta V_{OUT}$ , nominally 1% of  $V_{OUT}$ , is met. Voltage ripple  $\Delta V_{OUT}$  is mainly composed of two components: the resistive ripple due to ESR and capacitive ripple due to  $C_{OUT}$  charge transfer. For applications requiring low voltage ripple, ceramic capacitors are recommended because of their low ESR which is typically in the range of 5m $\Omega$ . Therefore  $\Delta V_{OUT}$  is mainly capacitive. For ceramic capacitors calculate the  $\Delta V_{OUT}$  from:

$$\Delta V_{OUT} = \frac{\Delta I_L}{8 \times C_{OUT} \times f_s}$$

Where:

$\Delta I_L$  is from table 1 or 2

$C_{OUT}$  is the value calculated above

$f_s$  is nominal switching frequency (340kHz)

If tantalum or electrolytic capacitors are used then  $\Delta V_{OUT}$  is essentially a function of ESR:

$$\Delta V_{OUT} = \Delta I_L \times ESR$$

### INPUT CAPACITOR $C_{IN}$

Select the input capacitor for voltage rating, RMS current rating and capacitance. The voltage rating should be at least 50% higher



than the regulator's maximum input voltage. Calculate the capacitor's current rating from:

$$I_{CIN,RMS} = I_{OUT} \times \sqrt{D \times (1 - D)}$$

Where:

$I_{OUT}$  is regulator's maximum current (2A)

D is duty cycle ( $D = V_{OUT}/V_{IN}$ )

Calculate the  $C_{IN}$  capacitance from:

$$C_{IN} = \frac{I_{OUT} \times V_{OUT} \times (V_{IN} - V_{OUT})}{f_s \times V_{IN}^2 \times \Delta V_{IN}}$$

Where:

$\Delta V_{IN}$  is the permissible input voltage ripple, nominally set at 1% of  $V_{IN}$

### OPTIONAL SCHOTTKY DIODE

An optional Schottky diode may be paralleled between the GND pin and SW pin to improve the regulator efficiency. Examples are shown in Table 3.

| Part Number | Voltage/Current Rating | Vendor                  |
|-------------|------------------------|-------------------------|
| B130        | 30V/1A                 | Diodes, Inc.            |
| SK13        | 30V/1A                 | Diodes, Inc.            |
| MBRS130     | 30V/1A                 | International Rectifier |

Table 3. Optional Schottky diode

### EXTERNAL BOOTSTRAP DIODE

A low-cost diode, such as 1N4148, is recommended for higher efficiency when the input voltage is 5V or the output is 5V or 3.3V. Circuit configuration is shown in figures 16 and 17. The external bootstrap diode is also recommended where duty cycle ( $V_{OUT}/V_{IN}$ ) is larger than 65%.

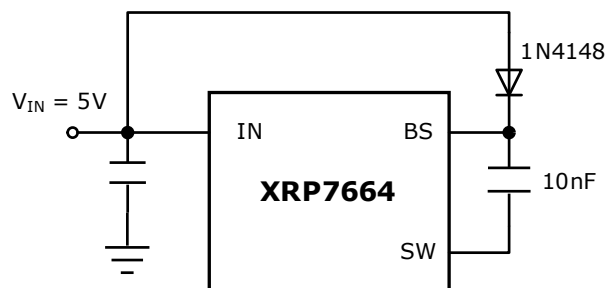


Figure 16. Optional external bootstrap diode where input voltage is fixed 5V

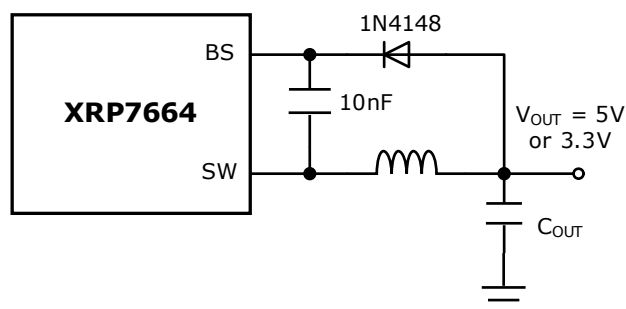


Figure 17. Optional external bootstrap diode where output voltage is 5V or 3.3V

### LOOP COMPENSATION

XRP7664 utilizes current-mode control. This allows using a minimum of external components to compensate the regulator. In general only two components are needed: RC and CC. Proper compensation of the regulator (determining RC and CC) results in optimum transient response. In terms of power supply control theory, the goals of compensation are to choose RC and CC such that the regulator loop gain has a crossover frequency  $f_c$  between 15kHz and 34kHz. The corresponding phase-margin should be between 45 degrees and 65 degrees. An important characteristic of current-mode buck regulator is its dominant pole. The frequency of the dominant pole is given by:

$$f_p = \frac{1}{2\pi \times C_{OUT} \times R_{load}}$$

where  $R_{load}$  is the output load resistance.

The uncompensated regulator has a constant gain up to its pole frequency, beyond which

the gain decreases at -20dB/decade. The zero arising from the output capacitor's ESR is inconsequential if ceramic  $C_{OUT}$  is used. This simplifies the compensation. The RC and CC, which are placed between the output of XRP7664's Error Amplifier and ground, constitute a zero. The frequency of this compensating zero is given by:

$$f_z = \frac{1}{2\pi \times RC \times CC}$$

For the typical application circuit,  $RC=5.6k\Omega$  and  $CC=3.3nF$  provide a satisfactory compensation. Please contact EXAR if you need assistance with the compensation of your particular circuit.

## TYPICAL APPLICATIONS

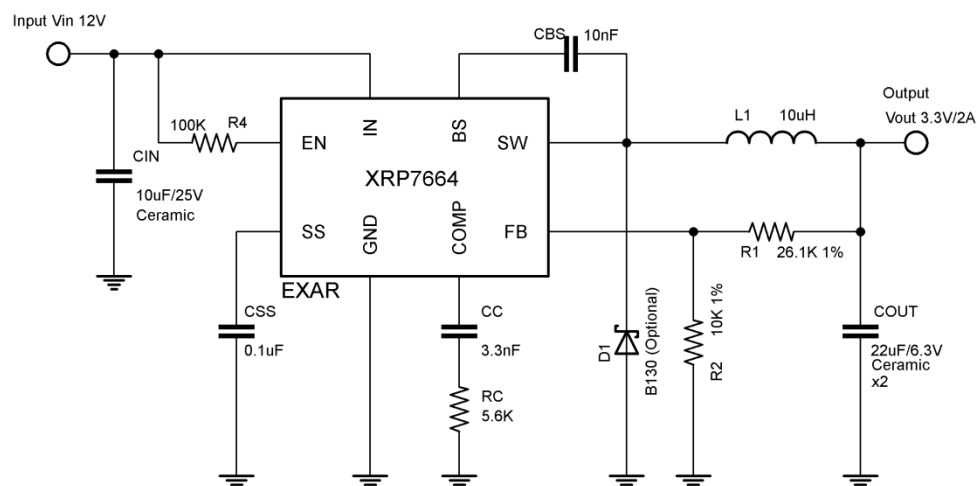
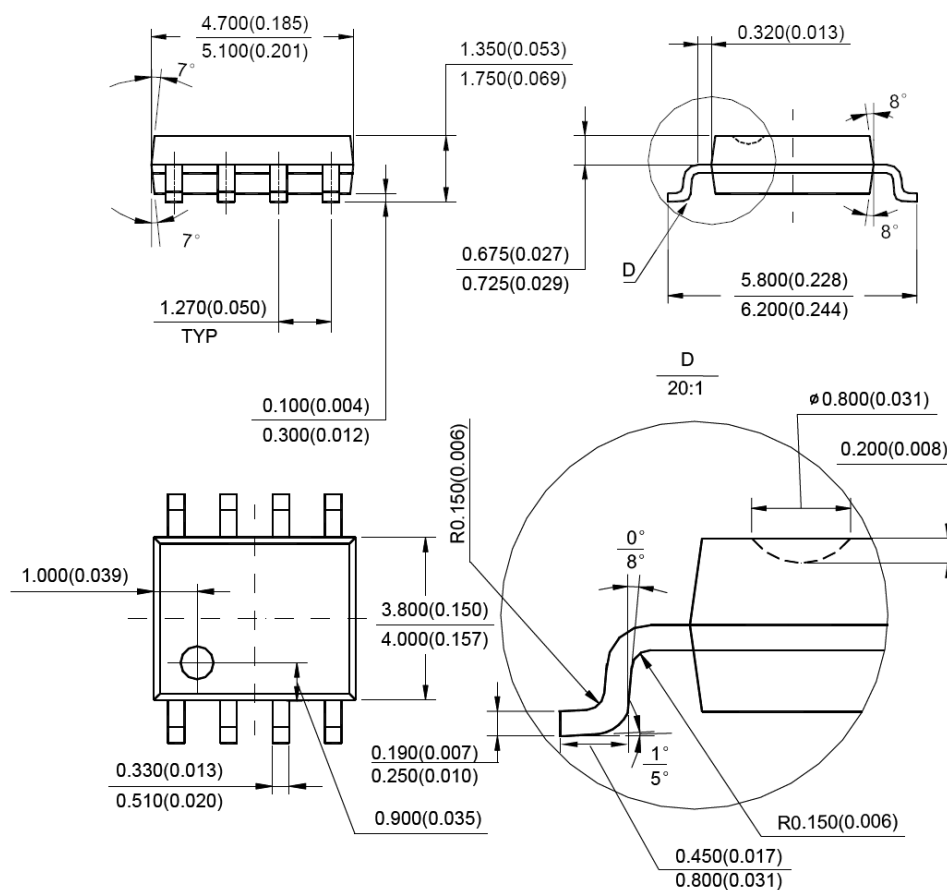


Fig. 16: XRP7664 Typical Application Diagram - 12V to 3.3V Conversion

## PACKAGE SPECIFICATION

## 8-PIN SOIC

Unit: mm (inch)





**XRP7664**

## **2A 18V Synchronous Step-Down Converter**

### **REVISION HISTORY**

| <b>Revision</b> | <b>Date</b> | <b>Description</b>                                                                                                                                         |
|-----------------|-------------|------------------------------------------------------------------------------------------------------------------------------------------------------------|
| 1.0.0           | 11/02/2010  | Initial release of data sheet                                                                                                                              |
| 1.1.0           | 12/17/2010  | RC(R3) changed from 2.2k $\Omega$ to 5.6k $\Omega$ - Updated schematics<br>Added the protection features to theory of operation<br>Added figures 16 and 17 |
| 1.2.0           | 10/13/2011  | Added MSL level information                                                                                                                                |

### **FOR FURTHER ASSISTANCE**

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## JONHON

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ВЧ соединители, коаксиальные кабели,  
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