

1-Mbit (64K × 16) Automotive F-RAM Memory

Features

- 1-Mbit ferroelectric random access memory (F-RAM™) logically organized as 64K × 16
 - Configurable as 128K × 8 using \overline{UB} and \overline{LB}
 - High-endurance 100 trillion (10^{14}) read/writes
 - 151-year data retention (see the [Data Retention and Endurance](#) table)
 - NoDelay™ writes
 - Page-mode operation for 30-ns cycle time
 - Advanced high-reliability ferroelectric process
- SRAM compatible
 - Industry-standard 64K × 16 SRAM pinout
 - 60-ns access time, 90-ns cycle time
- Superior to battery-backed SRAM modules
 - No battery concerns
 - Monolithic reliability
 - True surface-mount solution, no rework steps
 - Superior for moisture, shock, and vibration
- Low power consumption
 - Active current 7 mA (typ)
 - Standby current 120 μ A (typ)
- Low-voltage operation: $V_{DD} = 2.0$ V to 3.6 V
- Automotive-A temperature: -40 °C to +85 °C

- 44-pin thin small outline package (TSOP) Type II
- Restriction of hazardous substances (RoHS)-compliant

Functional Description

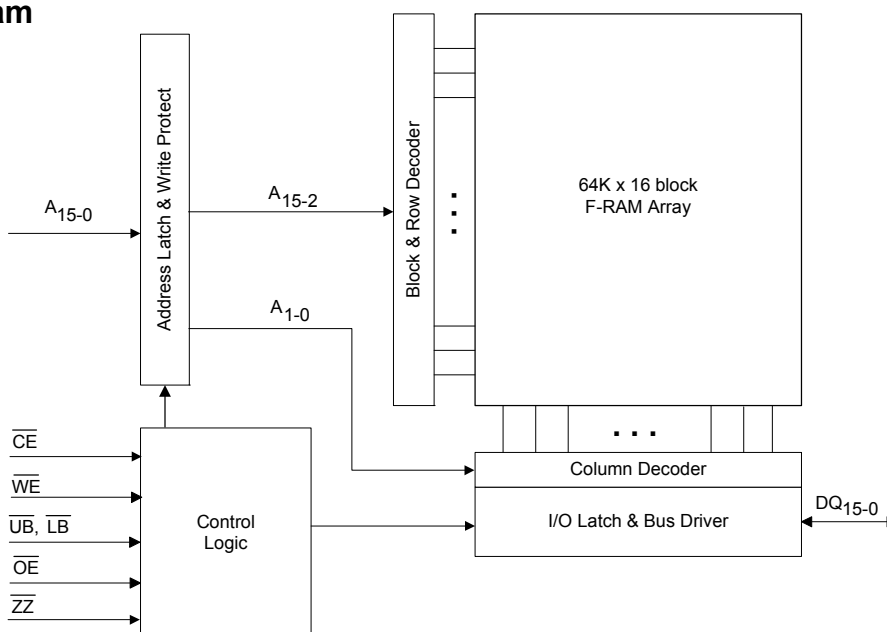
The CY15B101N is a 64K × 16 nonvolatile memory that reads and writes similar to a standard SRAM. A ferroelectric random access memory or F-RAM is nonvolatile, which means that data is retained after power is removed. It provides data retention for over 151 years while eliminating the reliability concerns, functional disadvantages, and system design complexities of battery-backed SRAM (BBSRAM). Fast write-timing and high write-endurance make the F-RAM superior to other types of memory.

The CY15B101N operation is similar to that of other RAM devices, and, therefore, it can be used as a drop-in replacement for a standard SRAM in a system. Read cycles may be triggered by \overline{CE} or simply by changing the address and write cycles may be triggered by \overline{CE} or \overline{WE} . The F-RAM memory is nonvolatile due to its unique ferroelectric memory process. These features make the CY15B101N ideal for nonvolatile memory applications requiring frequent or rapid writes.

The device is available in a 400-mil, 44-pin TSOP-II surface-mount package. Device specifications are guaranteed over the Automotive-A temperature range -40 °C to +85 °C.

For a complete list of related resources, [click here](#).

Logic Block Diagram

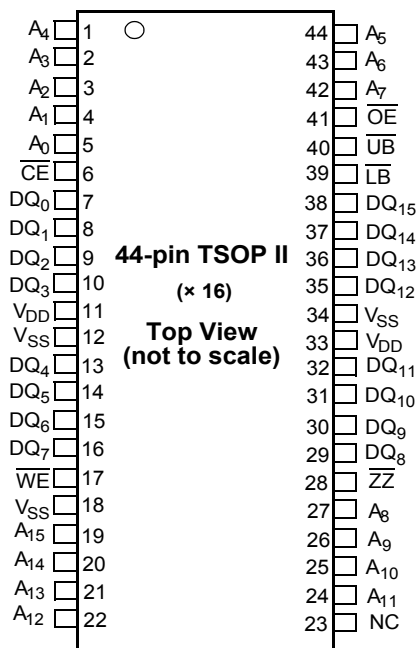


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Pinout

Figure 1. 44-Pin TSOP II Pinout



Pin Definitions

| Pin Name | I/O Type | Description |
|-----------------------------------|--------------|--|
| A ₀ –A ₁₅ | Input | Address inputs: The 16 address lines select one of 64K words in the F-RAM array. The lowest two address lines A ₁ –A ₀ may be used for page mode read and write operations. |
| DQ ₀ –DQ ₁₅ | Input/Output | Data I/O Lines: 16-bit bidirectional data bus for accessing the F-RAM array. |
| \overline{WE} | Input | Write Enable: A write cycle begins when \overline{WE} is asserted. The rising edge causes the CY15B101N to write the data on the DQ bus to the F-RAM array. The falling edge of \overline{WE} latches a new column address for page mode write cycles. |
| \overline{CE} | Input | Chip Enable: The device is selected and a new memory access begins on the falling edge of \overline{CE} . The entire address is latched internally at this point. Subsequent changes to the A ₁ –A ₀ address inputs allow page mode operation. |
| \overline{OE} | Input | Output Enable: When \overline{OE} is LOW, the CY15B101N drives the data bus when the valid read data is available. Deasserting \overline{OE} HIGH tristates the DQ pins. |
| \overline{UB} | Input | Upper Byte Select: Enables DQ ₁₅ –DQ ₈ pins during reads and writes. These pins are HI-Z if \overline{UB} is HIGH. If the user does not perform byte writes and the device is not configured as a 128K × 8, the \overline{UB} and \overline{LB} pins may be tied to ground. |
| \overline{LB} | Input | Lower Byte Select: Enables DQ ₇ –DQ ₀ pins during reads and writes. These pins are HI-Z if \overline{LB} is HIGH. If the user does not perform byte writes and the device is not configured as a 128K × 8, the \overline{UB} and \overline{LB} pins may be tied to ground. |
| \overline{ZZ} | Input | Sleep: When \overline{ZZ} is LOW, the device enters a low-power sleep mode for the lowest supply current condition. \overline{ZZ} must be HIGH for a normal read/write operation. This pin must be tied to V _{DD} if not used. |
| V _{SS} | Ground | Ground for the device. Must be connected to the ground of the system. |
| V _{DD} | Power supply | Power supply input to the device. |
| NC | No connect | No connect. This pin is not connected to the die. |

Device Operation

The CY15B101N is a word-wide F-RAM memory logically organized as $65,536 \times 16$ and accessed using an industry-standard parallel interface. All data written to the part is immediately nonvolatile with no delay. The device offers page-mode operation, which provides high-speed access to addresses within a page (row). Access to a different page requires that either \overline{CE} transitions LOW or the upper address (A_{15} – A_2) changes. See the [Functional Truth Table on page 14](#) for a complete description of read and write modes.

Memory Operation

Users access 65,536 memory locations, each with 16 data bits through a parallel interface. The F-RAM array is organized as eight blocks, each having 2048 rows. Each row has four column locations, which allow fast access in page-mode operation. When an initial address is latched by the falling edge of \overline{CE} , subsequent column locations may be accessed without the need to toggle \overline{CE} . When \overline{CE} is deasserted (HIGH), a precharge operation begins. Writes occur immediately at the end of the access with no delay. The \overline{WE} pin must be toggled for each write operation. The write data is stored in the nonvolatile memory array immediately, which is a feature unique to F-RAM called “NoDelay” writes.

Read Operation

A read operation begins on the falling edge of \overline{CE} . The falling edge of \overline{CE} causes the address to be latched and starts a memory read cycle if \overline{WE} is HIGH. Data becomes available on the bus after the access time is met. When the address is latched and the access completed, a new access to a random location (different row) may begin while \overline{CE} is still LOW. The minimum cycle time for random addresses is t_{RC} . Note that unlike SRAMs, the CY15B101N's \overline{CE} -initiated access time is faster than the address access time.

The CY15B101N will drive the data bus when \overline{OE} and at least one of the byte enables (\overline{UB} , \overline{LB}) is asserted LOW. The upper data byte is driven when \overline{UB} is LOW, and the lower data byte is driven when \overline{LB} is LOW. If \overline{OE} is asserted after the memory access time is met, the data bus will be driven with valid data. If \overline{OE} is asserted before completing the memory access, the data bus will not be driven until valid data is available. This feature minimizes the supply current in the system by eliminating transients caused by invalid data being driven to the bus. When \overline{OE} is deasserted HIGH, the data bus will remain in a HI-Z state.

Write Operation

In the CY15B101N, writes occur in the same interval as reads. The CY15B101N supports both \overline{CE} - and \overline{WE} -controlled write cycles. In both cases, the address A_{15} – A_2 is latched on the falling edge of \overline{CE} .

In a \overline{CE} -controlled write, the \overline{WE} signal is asserted before beginning the memory cycle. That is, \overline{WE} is LOW when \overline{CE} falls. In this case, the device begins the memory cycle as a write. The CY15B101N will not drive the data bus regardless of the state of \overline{OE} as long as \overline{WE} is LOW. Input data must be valid when \overline{CE} is deasserted HIGH. In a \overline{WE} -controlled write, the memory cycle begins on the falling edge of \overline{CE} . The \overline{WE} signal falls some time later. Therefore, the memory cycle begins as a read. The data bus will be driven if \overline{OE} is LOW; however, it will be HI-Z when \overline{WE} is asserted LOW. The \overline{CE} - and \overline{WE} -controlled write timing cases are shown on the [page 10](#) and [page 11](#).

Write access to the array begins on the falling edge of \overline{WE} after the memory cycle is initiated. The write access terminates on the rising edge of \overline{WE} or \overline{CE} , whichever comes first. A valid write operation requires the user to meet the access time specification before deasserting \overline{WE} or \overline{CE} . The data setup time indicates the interval during which data cannot change before the end of the write access (rising edge of \overline{WE} or \overline{CE}).

Unlike other nonvolatile memory technologies, there is no write delay with F-RAM. Because the read and write access times of the underlying memory are the same, the user experiences no delay through the bus. The entire memory operation occurs in a single bus cycle. Data polling, a technique used with EEPROMs to determine if a write is complete, is unnecessary.

Page Mode Operation

The F-RAM array is organized as eight blocks, each having 2048 rows. Each row has four column-address locations. Address inputs A_1 – A_0 define the column address to be accessed. An access can start on any column address, and other column locations may be accessed without the need to toggle the \overline{CE} pin. For fast access reads, after the first data byte is driven to the bus, the column address inputs A_1 – A_0 may be changed to a new value. A new data byte is then driven to the DQ pins no later than t_{AAP} , which is less than half the initial read access time. For fast access writes, the first write pulse defines the first write access. While \overline{CE} is LOW, a subsequent write pulse along with a new column address provides a page mode write access.

Precharge Operation

The precharge operation is an internal condition in which the memory state is prepared for a new access. Precharge is user-initiated by driving the \overline{CE} signal HIGH. It must remain HIGH for at least the minimum precharge time, t_{PC} .

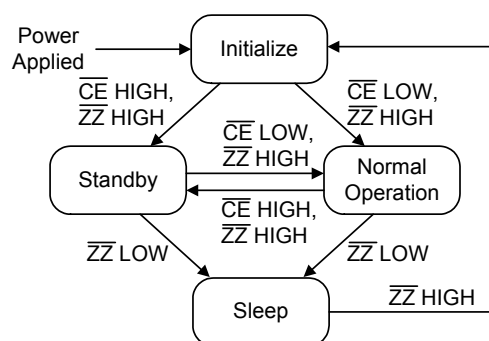
Precharge is also activated by changing the upper addresses, A_{15} – A_2 . The current row is first closed before accessing the new row. The device automatically detects an upper order address change, which starts a precharge operation. The new address is latched and the new read data is valid within the t_{AA} address access time; see [Figure 5 on page 10](#). A similar sequence occurs for write cycles; see [Figure 10 on page 11](#). The rate at which random addresses can be issued is t_{RC} and t_{WC} , respectively.

Sleep Mode

The device incorporates a sleep mode of operation, which allows the user to achieve the lowest-power-supply-current condition. It enters a low-power sleep mode by asserting the \overline{ZZ} pin LOW. Read and write operations must complete before the \overline{ZZ} pin going LOW. When \overline{ZZ} is LOW, all pins are ignored except the \overline{ZZ} pin. When \overline{ZZ} is deasserted HIGH, there is some time delay (t_{ZZEX}) before the user can access the device.

If sleep mode is not used, the \overline{ZZ} pin must be tied to V_{DD} .

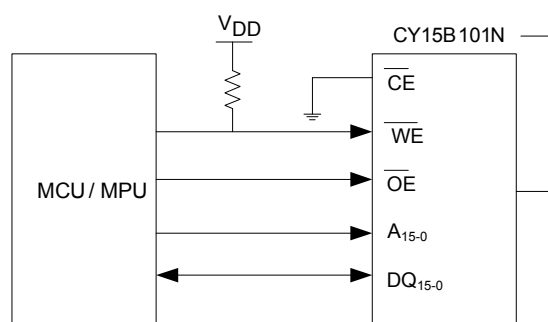
Figure 2. Sleep/Standby State Diagram



SRAM Drop-In Replacement

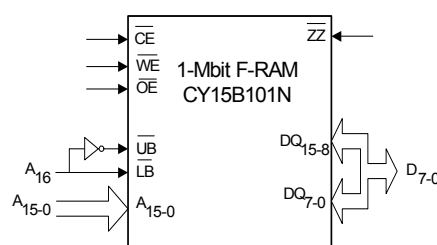
The CY15B101N is designed to be a drop-in replacement for standard asynchronous SRAMs. The device does not require \overline{CE} to toggle for each new address. \overline{CE} may remain LOW indefinitely. While \overline{CE} is LOW, the device automatically detects address changes and a new access begins. This functionality allows \overline{CE} to be grounded, similar to an SRAM. It also allows page mode operation at speeds up to 33 MHz. Note that if \overline{CE} is tied to ground, the user must be sure \overline{WE} is not LOW at power-up or power-down events. If \overline{CE} and \overline{WE} are both LOW during power cycles, data will be corrupted. Figure 3 shows a pull-up resistor on \overline{WE} , which will keep the pin HIGH during power cycles, assuming the MCU/MPU pin tristates during the reset condition. The pull-up resistor value should be chosen to ensure the \overline{WE} pin tracks V_{DD} to a high enough value, so that the current drawn when \overline{WE} is LOW is not an issue. A 10-k Ω resistor draws 330 μ A when \overline{WE} is LOW and $V_{DD} = 3.3$ V.

Figure 3. Use of Pull-up Resistor on \overline{WE}



For applications that require the lowest power consumption, the \overline{CE} signal should be active (LOW) only during memory accesses. The CY15B101N draws supply current while \overline{CE} is LOW, even if addresses and control signals are static. While \overline{CE} is HIGH, the device draws no more than the maximum standby current, I_{SB} . The \overline{UB} and \overline{LB} byte select pins are active for both read and write cycles. They may be used to allow the device to be wired as a 128K \times 8 memory. The upper and lower data bytes can be tied together and controlled with the byte selects. Individual byte enables or the next higher address line A_{16} may be available from the system processor.

Figure 4. CY15B101N Wired as 128 K \times 8



Endurance

The CY15B101N is capable of being accessed at least 10^{14} times – reads or writes. An F-RAM memory operates with a read and restore mechanism. Therefore, an endurance cycle is applied on a row basis. The F-RAM architecture is based on an array of rows and columns. Rows are defined by A_{15-2} and column addresses by A_{1-0} . The array is organized as 16K rows of four words each. The entire row is internally accessed once whether a single 16-bit word or all four words are read or written. Each word in the row is counted only once in an endurance calculation.

The user may choose to write CPU instructions and run them from a certain address space. Table 1 shows endurance calculations for a 256-byte repeating loop, which includes a starting address, three-page mode accesses, and a \overline{CE} precharge. The number of bus clock cycles needed to complete a four-word transaction is $4 + 1$ at lower bus speeds, but $5 + 2$ at 33 MHz due to initial read latency and an extra clock cycle to satisfy the device's precharge timing constraint t_{PC} . The entire loop causes each byte to experience only one endurance cycle. The F-RAM read and write endurance is virtually unlimited even at a 33-MHz system bus clock rate.

Table 1. Time to Reach 100 Trillion Cycles for Repeating 256-byte Loop

| Bus Freq (MHz) | Bus Cycle Time (ns) | 256-byte Transaction Time (μ s) | Endurance Cycles/sec | Endurance Cycles/year | Years to Reach 10^{14} Cycles |
|----------------|---------------------|--------------------------------------|----------------------|-----------------------|---------------------------------|
| 33 | 30 | 10.56 | 94,690 | 2.98×10^{12} | 33.5 |
| 25 | 40 | 12.8 | 78,125 | 2.46×10^{12} | 40.6 |
| 10 | 100 | 28.8 | 34,720 | 1.09×10^{12} | 91.7 |
| 5 | 200 | 57.6 | 17,360 | 5.47×10^{11} | 182.8 |

Maximum Ratings

Exceeding maximum ratings may shorten the useful life of the device. These user guidelines are not tested.

Storage temperature -55 °C to +125 °C

Maximum accumulated storage time

At 125 °C ambient temperature 1000 h

At 85 °C ambient temperature 10 Years

Ambient temperature

with power applied -55 °C to +125 °C

Supply voltage on V_{DD} relative to V_{SS} -1.0 V to + 4.5 V

Voltage applied to outputs

in High Z state -0.5 V to $V_{DD} + 0.5$ V

Input voltage -1.0 V to + 4.5 V and $V_{IN} < V_{DD} + 1.0$ V

Transient voltage (< 20 ns) on

any pin to ground potential -2.0 V to $V_{CC} + 2.0$ V

Package power dissipation

capability ($T_A = 25$ °C) 1.0 W

Surface mount Pb soldering

temperature (3 seconds) +260 °C

DC output current (1 output at a time, 1s duration) 15 mA

Static discharge voltage

Human Body Model (AEC-Q100-002 Rev. E) 2 kV

Charged Device Model (AEC-Q100-011 Rev. B) 500 V

Latch-up current > 140 mA

Operating Range

| Range | Ambient Temperature (T_A) | V_{DD} |
|--------------|-------------------------------|----------------|
| Automotive-A | -40 °C to +85 °C | 2.0 V to 3.6 V |

DC Electrical Characteristics

Over the [Operating Range](#)

| Parameter | Description | Test Conditions | | Min | Typ ^[1] | Max | Unit |
|------------------|--------------------------------|--|------------------------|-----------------------|--------------------|-----------------------|------|
| V _{DD} | Power supply voltage | | | 2.0 | 3.3 | 3.6 | V |
| I _{DD} | V _{DD} supply current | V _{DD} = 3.6 V, \overline{CE} cycling at min. cycle time. All inputs toggling at CMOS levels (0.2 V or V _{DD} − 0.2 V), all DQ pins unloaded. | | – | 7 | 12 | mA |
| I _{SB} | Standby current | V _{DD} = 3.6 V, \overline{CE} at V _{DD} , All other pins are static and at CMOS levels (0.2 V or V _{DD} − 0.2 V), \overline{ZZ} is HIGH | T _A = 25 °C | – | 120 | 150 | μA |
| | | | T _A = 85 °C | – | – | 250 | μA |
| I _{ZZ} | Sleep mode current | V _{DD} = 3.6 V, \overline{ZZ} is LOW, All other inputs V _{SS} or V _{DD} . | T _A = 25 °C | – | 3 | 5 | μA |
| | | | T _A = 85 °C | – | – | 8 | μA |
| I _{LI} | Input leakage current | V _{IN} between V _{DD} and V _{SS} | | – | – | ±1 | μA |
| I _{LO} | Output leakage current | V _{OUT} between V _{DD} and V _{SS} | | – | – | ±1 | μA |
| V _{IH1} | Input HIGH voltage | V _{DD} = 2.7 V to 3.6 V | | 2.2 | – | V _{DD} + 0.3 | V |
| V _{IH2} | Input HIGH voltage | V _{DD} = 2.0 V to 2.7 V | | 0.7 × V _{DD} | – | – | V |
| V _{IL1} | Input LOW voltage | V _{DD} = 2.7 V to 3.6 V | | – 0.3 | – | 0.8 | V |
| V _{IL2} | Input LOW voltage | V _{DD} = 2.0 V to 2.7 V | | – 0.3 | – | 0.3 × V _{DD} | V |
| V _{OH1} | Output HIGH voltage | I _{OH} = –1 mA, V _{DD} > 2.7 V | | 2.4 | – | – | V |
| V _{OH2} | Output HIGH voltage | I _{OH} = –100 μA | | V _{DD} – 0.2 | – | – | V |
| V _{OL1} | Output LOW voltage | I _{OL} = 2 mA, V _{DD} > 2.7 V | | – | – | 0.4 | V |
| V _{OL2} | Output LOW voltage | I _{OL} = 150 μA | | – | – | 0.2 | V |

Note

1. Typical values are at 25 °C, $V_{DD} = V_{DD}$ (typ). Not 100% tested.

Data Retention and Endurance

| Parameter | Description | Test condition | Min | Max | Unit |
|-----------------|----------------|----------------------------|------------------|-----|--------|
| T _{DR} | Data retention | T _A = 85 °C | 10 | – | Years |
| | | T _A = 75 °C | 38 | – | |
| | | T _A = 65 °C | 151 | – | |
| NV _C | Endurance | Over operating temperature | 10 ¹⁴ | – | Cycles |

Capacitance

| Parameter | Description | Test Conditions | Max | Unit |
|------------------|--|---|-----|------|
| C _{I/O} | Input/Output capacitance (DQ) | T _A = 25 °C, f = 1 MHz, V _{DD} = V _{DD(Typ)} | 8 | pF |
| C _{IN} | Input capacitance | | 6 | pF |
| C _{ZZ} | Input capacitance of \overline{ZZ} pin | | 8 | pF |

Thermal Resistance

| Parameter | Description | Test Conditions | 44-pin TSOP II | Unit |
|-----------------|--|---|----------------|------|
| Θ _{JA} | Thermal resistance (junction to ambient) | Test conditions follow standard test methods and procedures for measuring thermal impedance, in accordance with EIA/JESD51. | 107 | °C/W |
| Θ _{JC} | Thermal resistance (junction to case) | | 25 | °C/W |

AC Test Conditions

Input pulse levels 0 V to 3 V
 Input rise and fall times (10%–90%) ≤ 3 ns
 Input and output timing reference levels 1.5 V
 Output load capacitance 30 pF

AC Switching Characteristics

Over the [Operating Range](#)

| Parameters ^[2] | | Description | V _{DD} = 2.0 V to 2.7 V | | V _{DD} = 2.7 V to 3.6 V | | Unit |
|------------------------------------|-------------------|---|----------------------------------|-----|----------------------------------|-----|------|
| Cypress Parameter | Alt Parameter | | Min | Max | Min | Max | |
| SRAM Read Cycle | | | | | | | |
| t _{CE} | t _{ACE} | Chip enable access time | – | 70 | – | 60 | ns |
| t _{RC} | – | Read cycle time | 105 | – | 90 | – | ns |
| t _{AA} | – | Address access time, A ₁₅₋₂ | – | 105 | – | 90 | ns |
| t _{OH} | t _{OHA} | Output hold time, A ₁₅₋₂ | 20 | – | 20 | – | ns |
| t _{AAP} | – | Page mode access time, A ₁₋₀ | – | 40 | – | 30 | ns |
| t _{OHP} | – | Page mode output hold time, A ₁₋₀ | 3 | – | 3 | – | ns |
| t _{CA} | – | Chip enable active time | 70 | – | 60 | – | ns |
| t _{PC} | – | Precharge time | 35 | – | 30 | – | ns |
| t _{BA} | t _{BW} | \overline{UB} , \overline{LB} access time | – | 25 | – | 15 | ns |
| t _{AS} | t _{SA} | Address setup time (to \overline{CE} LOW) | 0 | – | 0 | – | ns |
| t _{AH} | t _{HA} | Address hold time (\overline{CE} Controlled) | 70 | – | 60 | – | ns |
| t _{OE} | t _{DOE} | Output enable access time | – | 25 | – | 15 | ns |
| t _{HZ} ^[3, 4] | t _{HZCE} | Chip enable to output HI-Z | – | 15 | – | 10 | ns |
| t _{OHZ} ^[3, 4] | t _{HZOE} | Output enable HIGH to output HI-Z | – | 15 | – | 10 | ns |
| t _{BHZ} ^[3, 4] | t _{HZBE} | \overline{UB} , \overline{LB} HIGH to output HI-Z | – | 15 | – | 10 | ns |

Notes

- Test conditions assume a signal transition time of 3 ns or less, timing reference levels of $0.5 \times V_{DD}$, input pulse levels of 0 to 3 V, output loading of the specified I_{OL}/I_{OH} and 30-pF load capacitance shown in [AC Test Conditions on page 7](#).
- t_{HZ}, t_{OHZ} and t_{BHZ} are specified with a load capacitance of 5 pF. Transition is measured when the outputs enter a high impedance state.
- This parameter is characterized but not 100% tested.

AC Switching Characteristics (continued)

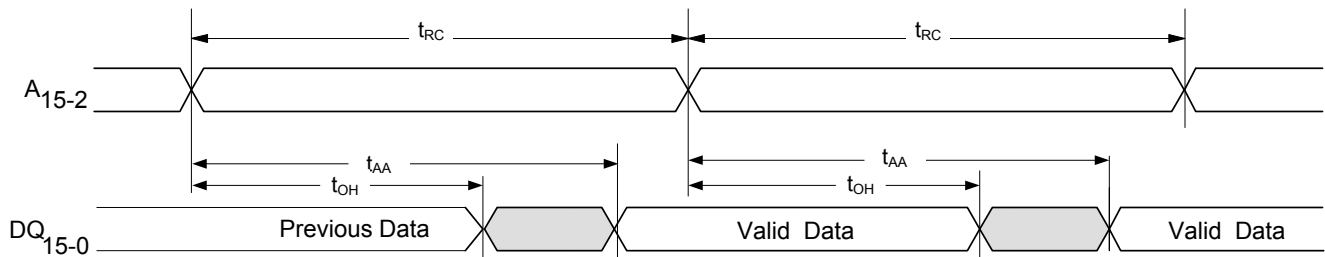
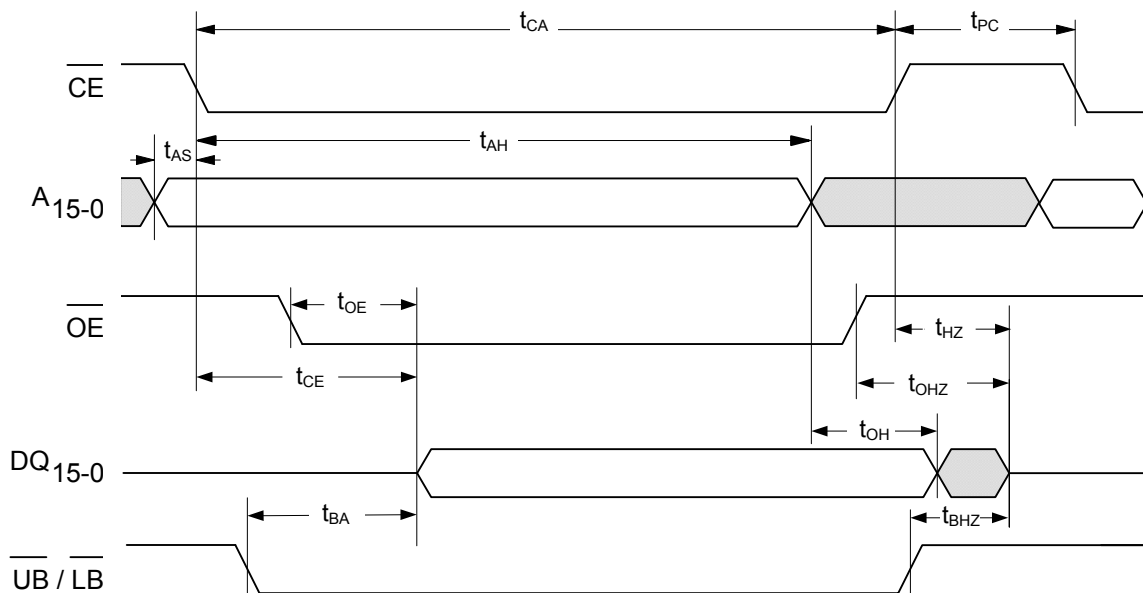
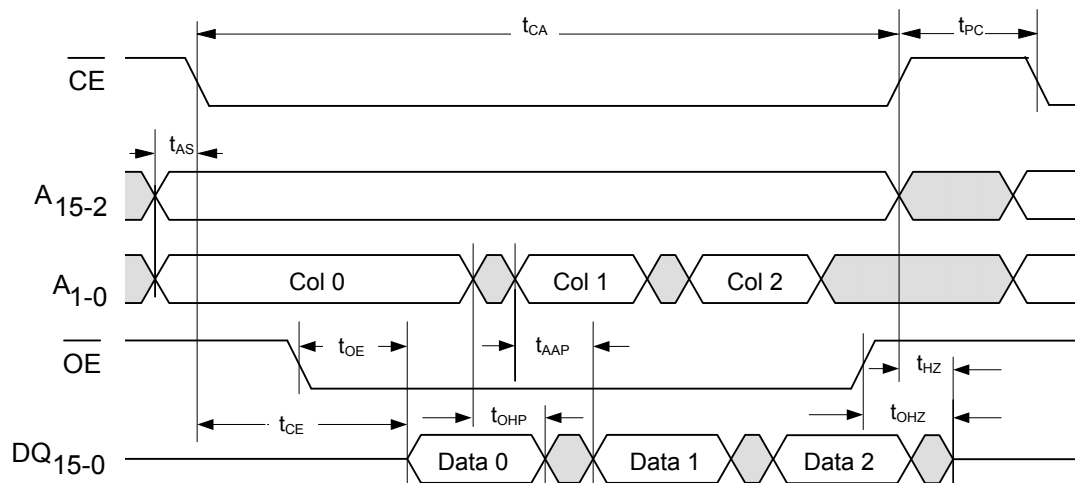
 Over the [Operating Range](#)

| Parameters ^[2] | | Description | V _{DD} = 2.0 V to 2.7 V | | V _{DD} = 2.7 V to 3.6 V | | Unit |
|-----------------------------------|-------------------|---|----------------------------------|-----|----------------------------------|-----|------|
| Cypress Parameter | Alt Parameter | | Min | Max | Min | Max | |
| SRAM Write Cycle | | | | | | | |
| t _{WC} | t _{WC} | Write cycle time | 105 | – | 90 | – | ns |
| t _{CA} | – | Chip enable active time | 70 | – | 60 | – | ns |
| t _{CW} | t _{SCE} | Chip enable to write enable HIGH | 70 | – | 60 | – | ns |
| t _{PC} | – | Precharge time | 35 | – | 30 | – | ns |
| t _{PWC} | – | Page mode write enable cycle time | 40 | – | 30 | – | ns |
| t _{WP} | t _{PWE} | Write enable pulse width | 22 | – | 18 | – | ns |
| t _{WP2} | t _{BW} | \overline{UB} , \overline{LB} pulse width | 22 | – | 18 | – | ns |
| t _{WP3} | t _{PWE} | \overline{WE} LOW to \overline{UB} , \overline{LB} HIGH | 22 | – | 18 | – | ns |
| t _{AS} | t _{SA} | Address setup time (to \overline{CE} LOW) | 0 | – | 0 | – | ns |
| t _{AH} | t _{HA} | Address hold time (\overline{CE} Controlled) | 70 | – | 60 | – | ns |
| t _{ASP} | – | Page mode address setup time (to \overline{WE} LOW) | 8 | – | 5 | – | ns |
| t _{AHP} | – | Page mode address hold time (to \overline{WE} LOW) | 20 | – | 15 | – | ns |
| t _{WLC} | t _{PWE} | Write enable LOW to chip disabled | 30 | – | 25 | – | ns |
| t _{BLC} | t _{BW} | \overline{UB} , \overline{LB} LOW to chip disabled | 30 | – | 25 | – | ns |
| t _{WLA} | – | Write enable LOW to address change, A ₁₅₋₂ | 30 | – | 25 | – | ns |
| t _{AWH} | – | Address change to write enable HIGH, A ₁₅₋₂ | 105 | – | 90 | – | ns |
| t _{DS} | t _{SD} | Data input setup time | 20 | – | 15 | – | ns |
| t _{DH} | t _{HD} | Data input hold time | 0 | – | 0 | – | ns |
| t _{WZ} ^[5, 6] | t _{HZWE} | Write enable LOW to output HI-Z | – | 10 | – | 10 | ns |
| t _{WX} ^[6] | – | Write enable HIGH to output driven | 8 | – | 5 | – | ns |
| t _{BDS} | – | Byte disable setup time (to \overline{WE} LOW) | 8 | – | 5 | – | ns |
| t _{BDH} | – | Byte disable hold time (to \overline{WE} HIGH) | 8 | – | 5 | – | ns |

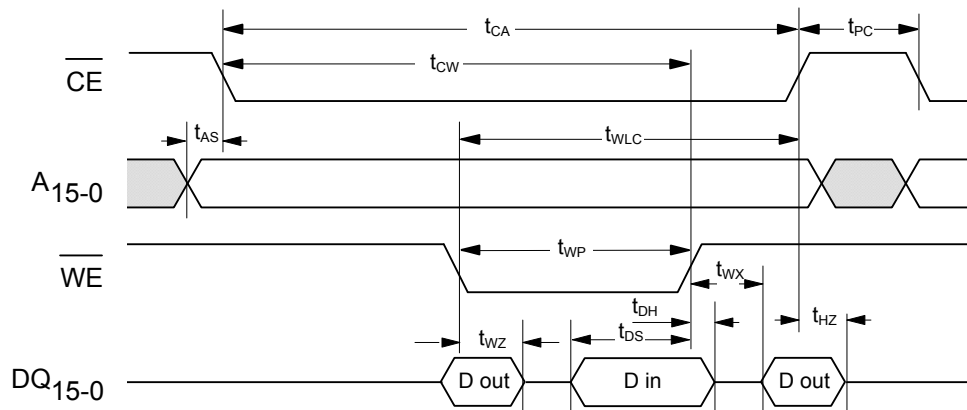
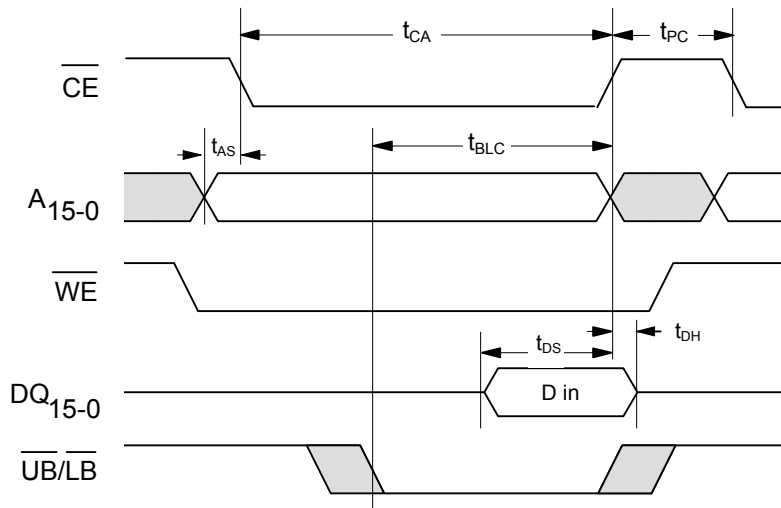
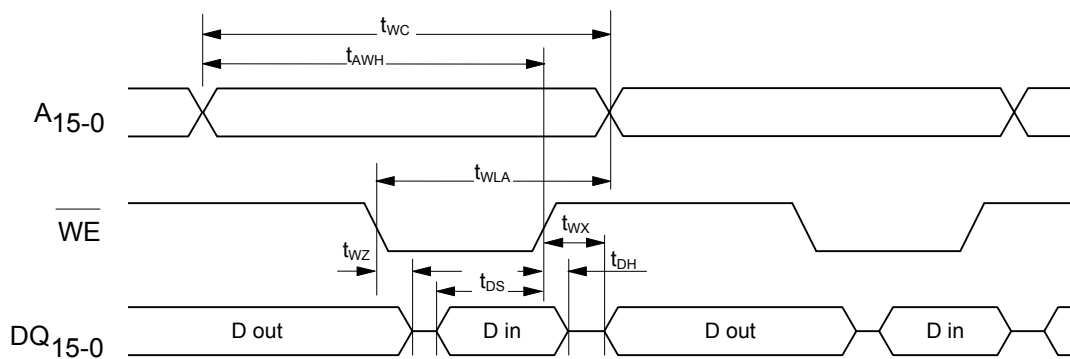
Notes

 5. t_{WZ} is specified with a load capacitance of 5 pF. Transition is measured when the outputs enter a high-impedance state.

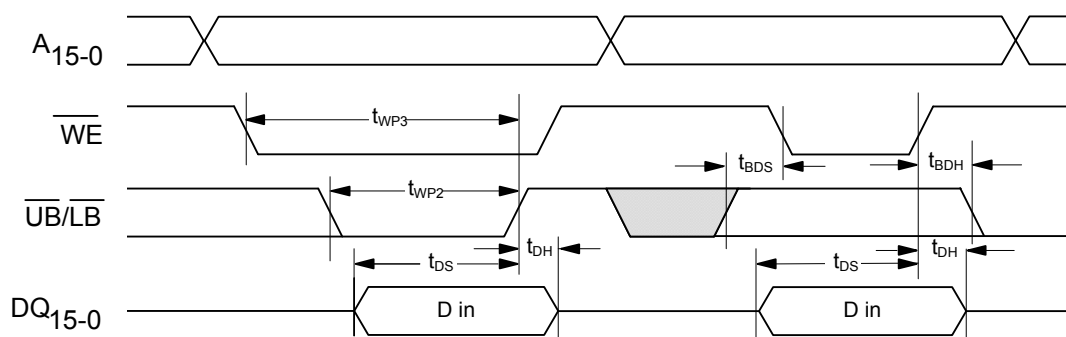
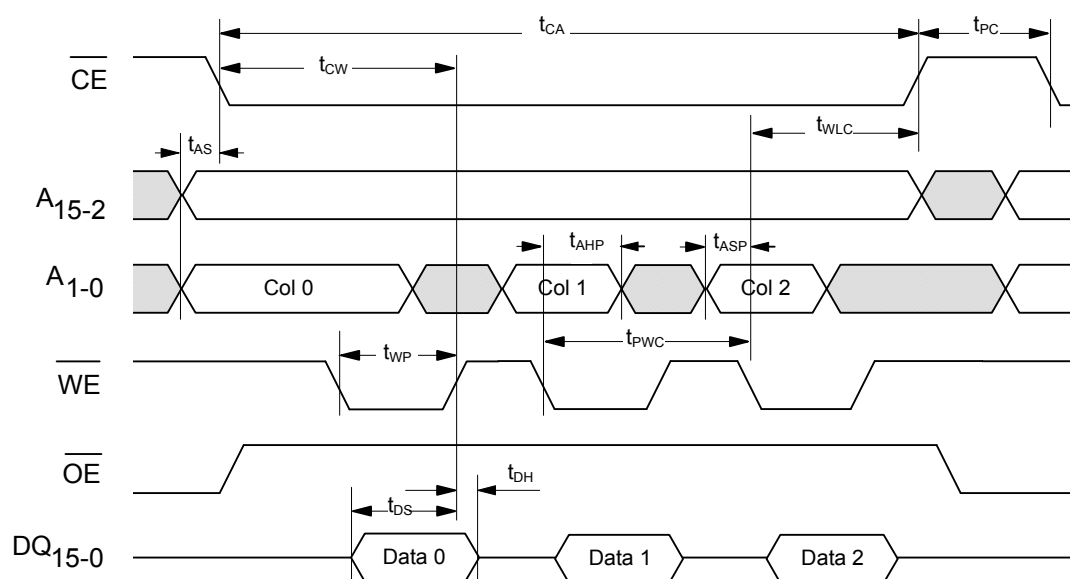
6. This parameter is characterized but not 100% tested.

Figure 5. Read Cycle Timing 1 ($\overline{\text{CE}}$ LOW, $\overline{\text{OE}}$ LOW)

Figure 6. Read Cycle Timing 2 ($\overline{\text{CE}}$ Controlled)

Figure 7. Page Mode Read Cycle Timing ^[7]

Note

7. Although sequential column addressing is shown, it is not required.

Figure 8. Write Cycle Timing 1 (\overline{WE} Controlled) [8]

Figure 9. Write Cycle Timing 2 (\overline{CE} Controlled)

Figure 10. Write Cycle Timing 3 (\overline{CE} LOW) [8]

Note

8. \overline{OE} (not shown) is LOW only to show the effect of \overline{WE} on DQ pins.

Figure 11. Write Cycle Timing 4 (\overline{CE} LOW) [9]

Figure 12. Page Mode Write Cycle Timing

Note

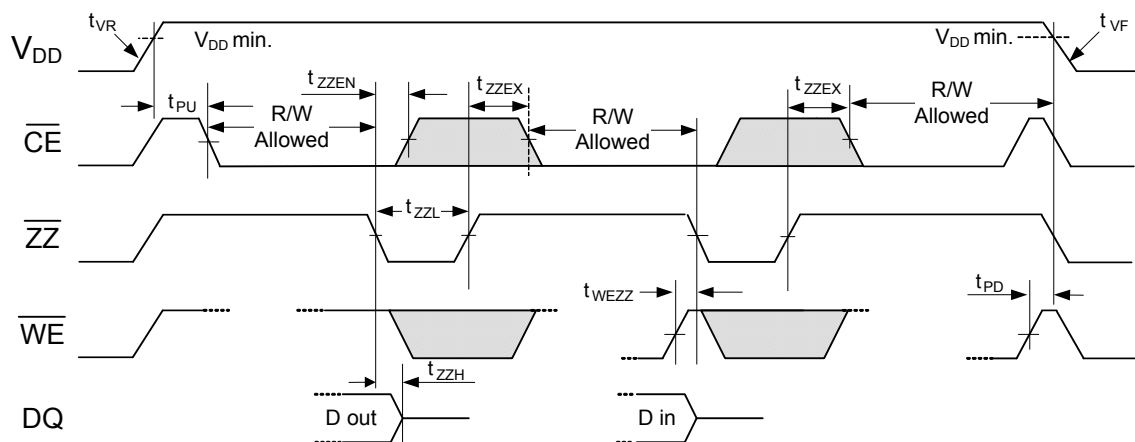
 9. \overline{UB} and \overline{LB} to show byte enable and byte masking cases.

Power Cycle and Sleep Mode Timing

Over the [Operating Range](#)

| Parameter | Description | Min | Max | Unit |
|-----------------|---|-----|-----|-----------------|
| t_{PU} | Power-up (after V_{DD} min. is reached) to first access time | 1 | – | ms |
| t_{PD} | Last write (\overline{WE} HIGH) to power down time | 0 | – | ms |
| $t_{VR}^{[10]}$ | V_{DD} power-up ramp rate | 50 | – | $\mu\text{s/V}$ |
| $t_{VF}^{[10]}$ | V_{DD} power-down ramp rate | 100 | – | $\mu\text{s/V}$ |
| t_{ZZH} | \overline{ZZ} active to DQ HI-Z time | – | 20 | ns |
| t_{WEZZ} | Last write to sleep mode entry time | 0 | – | μs |
| t_{ZZL} | \overline{ZZ} active LOW time | 1 | – | μs |
| t_{ZZEN} | Sleep mode entry time (\overline{ZZ} LOW to \overline{CE} don't care) | – | 0 | μs |
| t_{ZZEX} | Sleep mode exit time (\overline{ZZ} HIGH to 1 st access after wakeup) | – | 450 | μs |

Figure 13. Power Cycle and Sleep Mode Timing



Note

10. Slope measured at any point on the V_{DD} waveform.

Functional Truth Table

| \overline{CE} | \overline{WE} | A_{15-2} | A_{1-0} | \overline{ZZ} | Operation ^[11, 12] |
|-----------------|-----------------|------------|-----------|-----------------|---|
| X | X | X | X | L | Sleep Mode |
| H | X | X | X | H | Standby/Idle |
| ↓ L | H H | V V | V V | H H | Read |
| L | H | No Change | Change | H | Page Mode Read |
| L | H | Change | V | H | Random Read |
| ↓ L | L L | V V | V V | H H | \overline{CE} -Controlled Write ^[12] |
| L | ↓ | V | V | H | \overline{WE} -Controlled Write ^[12, 13] |
| L | ↓ | No Change | V | H | Page Mode Write ^[14] |
| ↑ L | X X | X X | X X | H H | Starts precharge |

Byte Select Truth Table

| \overline{WE} | \overline{OE} | \overline{LB} | \overline{UB} | Operation ^[15] |
|-----------------|-----------------|-----------------|-----------------|-----------------------------------|
| H | H | X | X | Read; Outputs disabled |
| | X | H | H | |
| H | L | H | L | Read upper byte; HI-Z lower byte |
| | | L | H | Read lower byte; HI-Z upper byte |
| | | L | L | Read both bytes |
| L | X | H | L | Write upper byte; Mask lower byte |
| | | L | H | Write lower byte; Mask upper byte |
| | | L | L | Write both bytes |

Notes

11. H = Logic HIGH, L = Logic LOW, V = Valid Data, X = Don't Care, ↓ = toggle LOW, ↑ = toggle HIGH.

12. For write cycles, data-in is latched on the rising edge of \overline{CE} or \overline{WE} , whichever comes first.

13. \overline{WE} -controlled write cycle begins as a Read cycle and then A_{15-2} is latched.

14. Addresses A_{1-0} must remain stable for at least 15 ns during page mode operation.

15. The \overline{UB} and \overline{LB} pins may be grounded if 1) the system does not perform byte writes and 2) the device is not configured as a 128K x 8.

Ordering Information

| Access Time (ns) | Ordering Code | Package Diagram | Package Type | Operating Range |
|------------------|-------------------|-----------------|--------------------------------|-----------------|
| 60 | CY15B101N-ZS60XAT | 51-85087 | 44-pin TSOP II with sleep mode | Automotive-A |
| | CY15B101N-ZS60XA | | | |

All the above parts are Pb-free.

Ordering Code Definitions

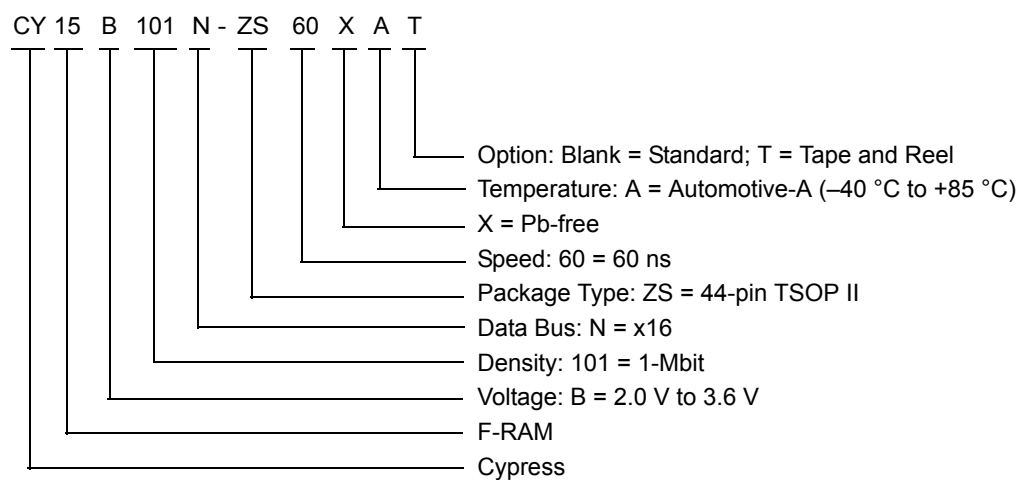
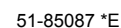


Figure 14. 44-pin TSOP Package Outline, 51-85087



Acronyms

| Acronym | Description |
|---------|---|
| UB | Upper Byte |
| LB | Lower Byte |
| CE | Chip Enable |
| CMOS | Complementary Metal Oxide Semiconductor |
| EIA | Electronic Industries Alliance |
| F-RAM | Ferroelectric Random Access Memory |
| I/O | Input/Output |
| OE | Output Enable |
| RoHS | Restriction of Hazardous Substances |
| RW | Read and Write |
| SRAM | Static Random Access Memory |
| TSOP | Thin Small Outline Package |
| WE | Write Enable |

Document Conventions

Units of Measure

| Symbol | Unit of Measure |
|--------|-----------------|
| °C | degree Celsius |
| Hz | hertz |
| kHz | kilohertz |
| kΩ | kilohm |
| MHz | megahertz |
| μA | microampere |
| μF | microfarad |
| μs | microsecond |
| mA | milliampere |
| ms | millisecond |
| MΩ | megaohm |
| ns | nanosecond |
| Ω | ohm |
| % | percent |
| pF | picoFarad |
| V | volt |
| W | watt |

Document History Page

| Document Title: CY15B101N, 1-Mbit (64K × 16) Automotive F-RAM Memory Document Number: 001-96058 | | | | |
|--|---------|-----------------|-----------------|--|
| Rev. | ECN No. | Orig. of Change | Submission Date | Description of Change |
| ** | 4630415 | ZSK / LIZB | 01/21/2015 | New data sheet. |
| *A | 4746319 | GVCH | 04/28/2015 | Changed status from Advance to Preliminary. |
| *B | 4774256 | GVCH | 06/04/2015 | Changed status from Preliminary to Final. |
| *C | 4766039 | GVCH | 06/22/2015 | Updated Functional Truth Table : Fixed typo (Included "Toggle LOW" and "Toggle HIGH" condition in " \overline{CE} " and " \overline{WE} " columns). |
| *D | 4883462 | ZSK / PSR | 09/04/2015 | Updated Functional Description : Added "For a complete list of related resources, click here ." at the end. Updated Maximum Ratings : Removed "Maximum junction temperature". Added "Maximum accumulated storage time". Added "Ambient temperature with power applied". |
| *E | 6033841 | GVCH | 01/16/2018 | Updated to the new template. Completing the Sunset review. |

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