# ANALOG DEVICES

# 12 Channel, 8-Bit TrimDACs with Power Shutdown

# AD8802/AD8804

#### FEATURES

Low Cost Replaces 12 Potentiometers Individually Programmable Outputs 3-Wire SPI Compatible Serial Input Power Shutdown <55 μWatts Including I<sub>DD</sub> & I<sub>REF</sub> Midscale Preset, AD8802 Separate V<sub>REFL</sub> Range Setting, AD8804 +3 V to +5 V Single Supply Operation

### **APPLICATIONS**

Automatic Adjustment Trimmer Replacement Video and Audio Equipment Gain and Offset Adjustment Portable and Battery Operated Equipment

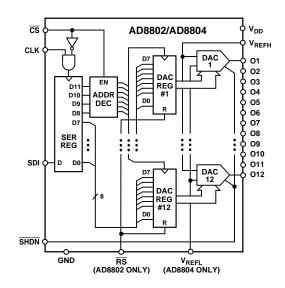
### **GENERAL DESCRIPTION**

The 12-channel AD8802/AD8804 provides independent digitallycontrollable voltage outputs in a compact 20-lead package. This potentiometer divider TrimDAC® allows replacement of the mechanical trimmer function in new designs. The AD8802/ AD8804 is ideal for dc voltage adjustment applications.

Easily programmed by serial interfaced microcontroller ports, the AD8802 with its midscale preset is ideal for potentiometer replacement where adjustments start at a nominal value. Applications such as gain control of video amplifiers, voltage controlled frequencies and bandwidths in video equipment, geometric correction and automatic adjustment in CRT computer graphic displays are a few of the many applications ideally suited for these parts. The AD8804 provides independent control of both the top and bottom end of the potentiometer divider allowing a separate zero-scale voltage setting determined by the  $V_{REFL}$  pin. This is helpful for maximizing the resolution of devices with a limited allowable voltage control range.

Internally the AD8802/AD8804 contains 12 voltage-output digital-to-analog converters, sharing a common reference-voltage input.

TrimDAC is a registered trademark of Analog Devices, Inc.



FUNCTIONAL BLOCK DIAGRAM

Each DAC has its own DAC latch that holds its output state. These DAC latches are updated from an internal serial-toparallel shift register that is loaded from a standard 3-wire serial input digital interface. The serial-data-input word is decoded where the first 4 bits determine the address of the DAC latches to be loaded with the last 8 bits of data. The AD8802/ AD8804 consumes only 10  $\mu$ A from 5 V power supplies. In addition, in shutdown mode reference input current consumption is also reduced to 10  $\mu$ A while saving the DAC latch settings for use after return to normal operation.

The AD8802/AD8804 is available in the 20-pin plastic DIP, the SOIC-20 surface mount package, and the 1 mm thin TSSOP-20 package.

### REV.0

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Parameter	Symbol	Conditions	Min	Typ <sup>1</sup>	Max	Units
STATIC ACCURACY Specifications apply to all DACs Resolution Differential Nonlinearity Error Integral Nonlinearity Error Full-Scale Error Zero Code Error DAC Output Resistance Output Resistance Match	N DNL INL G <sub>FSE</sub> V <sub>ZSE</sub> R <sub>OUT</sub> ΔR/R <sub>O</sub>	Guaranteed Monotonic	8 -1 -1.5 -1 -1 3	$\pm 1/4$ $\pm 1/2$ 1/2 1/4 5 1.5	+1 +1.5 +1 +1 8	Bits LSB LSB LSB LSB kΩ %
REFERENCE INPUT Voltage Range <sup>2</sup> REFH Input Resistance REFL Input Resistance <sup>3</sup> Reference Input Capacitance <sup>3</sup>	$f V_{REFH} \ V_{REFL} \ R_{REFH} \ R_{REFH} \ R_{REFL} \ C_{REF0} \ C_{REF1}$	Pin Available on AD8804 Only Digital Inputs = $55_H$ , $V_{REFH} = V_{DD}$ Digital Inputs = $55_H$ , $V_{REFL} = V_{DD}$ Digital Inputs all Zeros Digital Inputs all Ones	0 0	1.2 1.2 32 32	V <sub>DD</sub> V <sub>DD</sub>	V V kΩ pF pF
DIGITAL INPUTS Logic High Logic Low Logic High Logic Low Input Current Input Capacitance <sup>3</sup>	$\begin{array}{c} V_{IH} \\ V_{IL} \\ V_{IH} \\ V_{IH} \\ I_{IL} \\ C_{IL} \end{array}$	$V_{DD} = +5 V$ $V_{DD} = +5 V$ $V_{DD} = +3 V$ $V_{DD} = +3 V$ $V_{IN} = 0 V \text{ or } + 5 V$	2.4 2.1	5	0.8 0.6 ±1	V V V V μA pF
POWER SUPPLIES <sup>4</sup> Power Supply Range Supply Current (CMOS) Supply Current (TTL) Shutdown Current Power Dissipation Power Supply Sensitivity	$V_{DD} Range \\ I_{DD} \\ I_{DD} \\ I_{REFH} \\ P_{DISS} \\ PSRR$	$\begin{split} V_{IH} &= V_{DD} \text{ or } V_{IL} = 0 \text{ V} \\ V_{IH} &= 2.4 \text{ V or } V_{IL} = 0.8 \text{ V}, V_{DD} = +5.5 \text{ V} \\ \hline \text{SHDN} &= 0 \\ V_{IH} &= V_{DD} \text{ or } V_{IL} = 0 \text{ V}, V_{DD} = +5.5 \text{ V} \\ V_{DD} &= +5 \text{ V} \pm 10\% \end{split}$	2.7	0.01 1 0.2 0.001	5.5 10 4 10 55 0.002	V μΑ mΑ μΑ μW %/%
DYNAMIC PERFORMANCE <sup>3</sup> V <sub>OUT</sub> Settling Time Crosstalk	t <sub>s</sub> CT	±1/2 LSB Error Band Between Adjacent Outputs <sup>5</sup>		0.6 50		μs dB
SWITCHING CHARACTERISTICS3, 6Input Clock Pulse WidthData Setup Time $\overline{CS}$ Setup Time $\overline{CS}$ High Pulse WidthReset Pulse WidthCLK Rise to $\overline{CS}$ Rise Hold Time $\overline{CS}$ Rise to Clock Rise Setup	$t_{CH}$ , $t_{CL}$ $t_{DS}$ $t_{DH}$ $t_{CSS}$ $t_{CSW}$ $t_{RS}$ $t_{CSH}$ $t_{CS1}$	Clock Level High or Low	15 5 5 10 10 90 20 10			ns ns ns ns ns ns ns ns ns

NOTES

<sup>1</sup>Typicals represent average readings at +25°C. <sup>2</sup>V<sub>REFH</sub> can be any value between GND and V<sub>DD</sub>, for the AD8804 V<sub>REFL</sub> can be any value between GND and V<sub>DD</sub>. <sup>3</sup>Guaranteed by design and not subject to production test. <sup>4</sup>Digital Input voltages V<sub>IN</sub> = 0 V or V<sub>DD</sub> for CMOS condition. DAC outputs unloaded. P<sub>DISS</sub> is calculated from (I<sub>DD</sub> × V<sub>DD</sub>). <sup>5</sup>Measured at a V<sub>OUT</sub> pin where an adjacent V<sub>OUT</sub> pin is making a full-scale voltage change (f = 100 kHz).

<sup>6</sup>See timing diagram for location of measured values. All input control voltages are specified with  $t_R = t_F = 2$  ns (10% to 90% of  $V_{DD}$ ) and timed from a voltage level of 1.6 V.

Specifications subject to change without notice.

### ABSOLUTE MAXIMUM RATINGS

$(T_A = +25^{\circ}C, \text{ unless otherwise noted})$
$V_{DD}$ to GND $\ldots \ldots \ldots$
$V_{\text{REFX}}$ to GND $\ldots \ldots 0$ V, $V_{\text{DD}}$
Outputs (Ox) to GND 0 V, V <sub>DD</sub>
Digital Input Voltage to GND 0 V, +8 V
Operating Temperature Range40°C to +85°C
Maximum Junction Temperature ( $T_JMAX$ ) +150°C
Storage Temperature
Lead Temperature (Soldering, 10 sec) +300°C
Package Power Dissipation $(T_J MAX - T_A)/\theta_{JA}$
Thermal Resistance $\theta_{IA}$ ,
SOIC (SOL-20)
P-DIP (N-20)
TSSOP-20 (RU-20) 155°C/W

### AD8802 PIN DESCRIPTIONS

Pin	Name	Description
1	V <sub>REF</sub>	Common DAC Reference Input
2	01	DAC Output #1, addr = $0000_2$
3	O2	DAC Output #2, addr = $0001_2$
4	03	DAC Output #3, addr = $0010_2$
5	O4	DAC Output #4, addr = $0011_2$
6	O5	DAC Output #5, addr = $0100_2$
7	O6	DAC Output #6, addr = $0101_2$
8	SHDN	Reference input current goes to zero. DAC latch settings maintained
9	CS	Chip Select Input, Active Low. When $\overline{CS}$ returns high, data in the serial input register is decoded based on the address bits and loaded into the target DAC register
10	GND	Ground
11	CLK	Serial Clock Input, Positive Edge Triggered
12	SDI	Serial Data Input
13	07	DAC Output #7, addr = $0110_2$
14	08	DAC Output #8, addr = $0111_2$
15	O9	DAC Output #9, addr = $1000_2$
16	O10	DAC Output #10, addr = $1001_2$
17	011	DAC Output #11, addr = $1010_2$
18	O12	DAC Output #12, addr = $1011_2$
19	RS	Asynchronous Preset to Midscale Output Setting. Loads all DAC Registers with 80 <sub>H</sub>
20	V <sub>DD</sub>	Positive Power Supply, Specified for Operation at Both +3 V and +5 V

### PIN CONFIGURATIONS

V <sub>REFH</sub> 1 01 2 02 3 03 4 04 5 AD8802 05 6 (Not to Scale) 06 7 SHDN 8 CS 9 010	14 08 13 07 12 SDI	V <sub>REFH</sub> 1 01 2 02 3 03 4 04 5 AD8804 TOP VIEV (Not to Sca SHDN 8 CS 9 OND 50	W 15 08 14 07 13 SDI 12 CLK
GND 10	11 CLK	GND 10	11 V <sub>REFL</sub>

### AD8804 PIN DESCRIPTIONS

Pin	Name	Description
1	V <sub>REFH</sub>	Common High-Side DAC Reference Input
2	01	DAC Output #1, addr = $0000_2$
3	O2	DAC Output #2, addr = $0001_2$
4	03	DAC Output #3, addr = $0010_2$
5	04	DAC Output #4, addr = $0011_2$
6	05	DAC Output #5, addr = $0100_2$
7	O6	DAC Output #6, addr = $0101_2$
8	SHDN	Reference input current goes to zero DAC latch
		settings maintained
9	$\overline{\mathrm{CS}}$	Chip Select Input, Active Low. When $\overline{CS}$ returns
		high, data in the serial input register is decoded
		based on the address bits and loaded input the
		target DAC register
10	GND	Ground
11	V <sub>REFL</sub>	Common Low-Side DAC Reference Input
12	CLK	Serial Clock Input, Positive Edge Triggered
13	SDI	Serial Data Input
14	07	DAC Output #7, addr = $0110_2$
15	08	DAC Output #8, addr = $0111_2$
16	09	DAC Output #9, addr = $1000_2$
17	O10	DAC Output #10, addr = $1001_2$
18	011	DAC Output #11, addr = $1010_2$
19	O12	DAC Output #12, addr = $1011_2$
20	V <sub>DD</sub>	Positive power supply, specified for operation at
		both +3 V and +5 V

### **ORDERING GUIDE**

Model	FTN	Temperature Range	Package Description	Package Option
AD8802AN	RS	-40°C/+85°C	PDIP-20	N-20
AD8802AR	RS	-40°C/+85°C	SOL-20	R-20
AD8802ARU	RS	-40°C/+85°C	TSSOP-20	RU-20
AD8804AN	REFL	-40°C/+85°C	PDIP-20	N-20
AD8804AR	REFL	-40°C/+85°C	SOL-20	R-20
AD8804ARU	REFL	-40°C/+85°C	TSSOP-20	RU-20

### CAUTION\_

ESD (electrostatic discharge) sensitive device. Electrostatic charges as high as 4000 V readily accumulate on the human body and test equipment and can discharge without detection. Although these devices feature proprietary ESD protection circuitry, permanent damage may occur on devices subjected to high energy electrostatic discharges. Therefore, proper ESD precautions are recommended to avoid performance degradation or loss of functionality.



# AD8802/AD8804–Typical Performance Characteristics

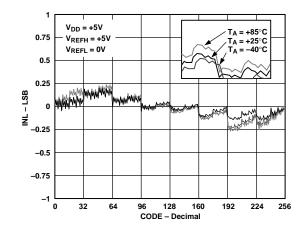


Figure 1. INL vs. Code

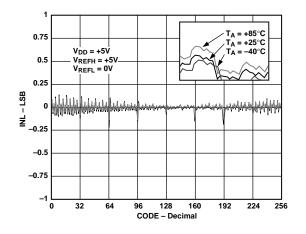


Figure 2. Differential Nonlinearity Error vs. Code

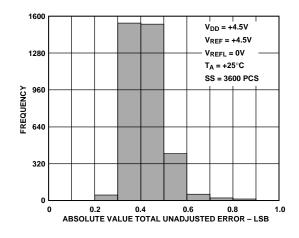


Figure 3. Total Unadjusted Error Histogram

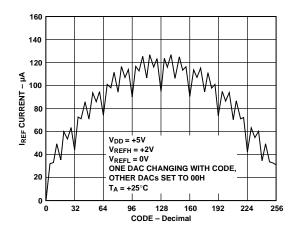


Figure 4. Input Reference Current vs. Code

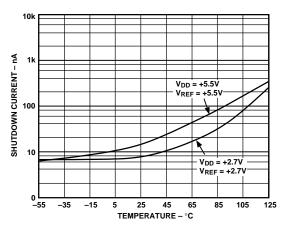


Figure 5. Shutdown Current vs. Temperature

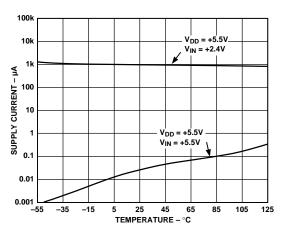


Figure 6. Supply Current vs. Temperature

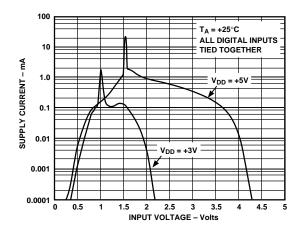


Figure 7. Supply Current vs. Logic Input Voltage

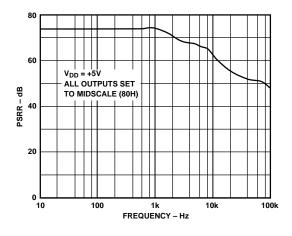


Figure 8. Power Supply Rejection vs. Frequency

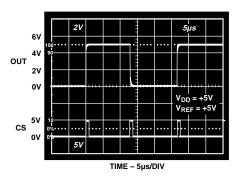


Figure 9. Large-Signal Settling Time

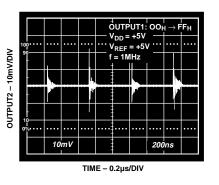


Figure 10. Adjacent Channel Clock Feedthrough

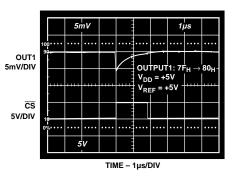


Figure 11. Midscale Transition

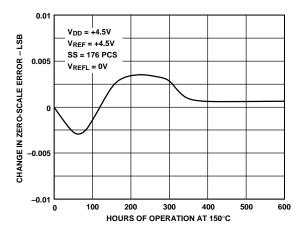


Figure 12. Zero-Scale Error Accelerated by Burn-In

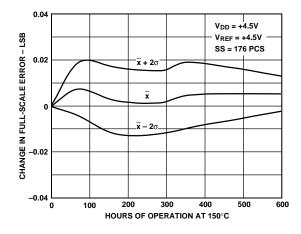


Figure 13. Full-Scale Error Accelerated by Burn-In

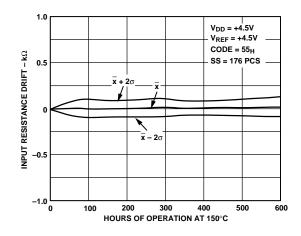


Figure 14. REF Input Resistance Accelerated by Burn-In

### **OPERATION**

The AD8802/AD8804 provides twelve channels of programmable voltage output adjustment capability. Changing the programmed output voltage of each DAC is accomplished by clocking in a 12-bit serial data word into the SDI (Serial Data Input) pin. The format of this data word is four address bits, MSB first, followed by 8 data bits, MSB first. Table I provides the serial register data word format. The AD8802/AD8804 has the following address assignments for the ADDR decode which determines the location of the DAC register receiving the serial register data in Bits B7 through B0:

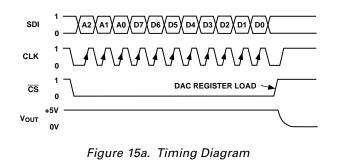
 $DAC\# = A3 \times 8 + A2 \times 4 + A1 \times 2 + A0 + 1$ 

DAC outputs can be changed one at a time in random sequence. The fast serial-data loading of 33 MHz makes it possible to load all 12 DACs in as little time as  $4.6 \,\mu\text{s}$  ( $13 \times 12 \times 30 \,\text{ns}$ ). The exact timing requirements are shown in Figure 15.

Table I. Serial-Data Word Format

ADE	DR				DA	ГА					
<b>B</b> 11	<b>B10</b>	<b>B9</b>	<b>B</b> 8	<b>B</b> 7	<b>B6</b>	<b>B</b> 5	<b>B</b> 4	<b>B</b> 3	<b>B</b> 2	<b>B</b> 1	<b>B</b> 0
A3	A2	A1	A0	D7	D6	D5	D4	D3	D2	D1	D0
MSB			LSB	MSI	В					]	LSB
$2^{11}$	$2^{10}$	2 <sup>9</sup>	2 <sup>8</sup>	27	2 <sup>6</sup>	2 <sup>5</sup>	$2^4$	$2^{3}$	$2^{2}$	$2^1$	$2^{0}$

The AD8802 offers a midscale preset activated by the  $\overline{\text{RS}}$  pin simplifying initial setting conditions at first power-up. The AD8804 has both a V<sub>REFH</sub> and a V<sub>REFL</sub> pin to establish independent positive full-scale and zero-scale settings to optimize resolution. Both parts offer a power shutdown  $\overline{\text{SHDN}}$  which places the DAC structure in a zero power consumption state resulting in only leakage currents being consumed from the power supply and V<sub>REF</sub> inputs. In shutdown mode the DACX register settings are maintained. When returning to operational mode from power shutdown the DAC outputs return to their previous voltage settings.



DETAIL SERIAL DATA INPUT TIMING  $\overline{RS}$  = "1")

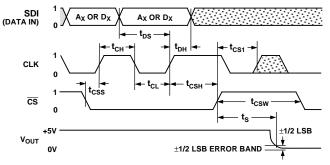


Figure 15b. Detail Timing Diagram

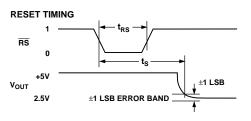


Figure 15c. Reset Timing Diagram

#### **PROGRAMMING THE OUTPUT VOLTAGE**

The output voltage range is determined by the external reference connected to  $V_{REFH}$  and  $V_{REFL}$  pins. See Figure 16 for a simplified diagram of the equivalent DAC circuit. In the case of the AD8802 its  $V_{REFL}$  is internally connected to GND and therefore cannot be offset.  $V_{REFH}$  can be tied to  $V_{DD}$  and  $V_{REFL}$ can be tied to GND establishing a basic rail-to-rail voltage output programming range. Other output ranges are established by the use of different external voltage references. The general transfer equation which determines the programmed output voltage is:

$$VO(Dx) = (Dx)/256 \times (V_{REFH} - V_{REFL}) + V_{REFL}$$
 Eq. 1

where Dx is the data contained in the 8-bit DACx register.

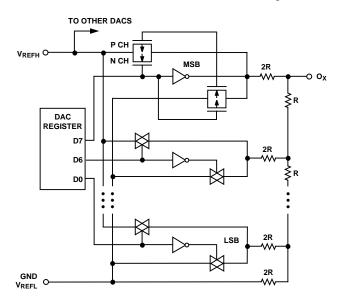


Figure 16. AD8802/AD8804 Equivalent TrimDAC Circuit For example, when  $V_{REFH} = +5$  V and  $V_{REFL} = 0$  V, the following output voltages will be generated for the following codes:

D	VOx	Output State (V <sub>REFH</sub> = +5 V, V <sub>REFL</sub> = 0 V)
255	4.98 V	Full Scale
128	2.50 V	Half Scale (Midscale Reset Value)
1	0.02 V	1 LSB
0	0.00 V	Zero Scale

#### **REFERENCE INPUTS (V<sub>REFH</sub>, V<sub>REFL</sub>)**

The reference input pins set the output voltage range of all twelve DACs. In the case of the AD8802 only the  $V_{REFH}$  pin is available to establish a user designed full-scale output voltage. The external reference voltage can be any value between 0 and  $V_{DD}$  but must not exceed the  $V_{DD}$  supply voltage. The AD8804 has access to the  $V_{REFL}$  which establishes the zero-scale output voltage, any voltage can be applied between 0 V and  $V_{DD}$ .  $V_{REFL}$ can be smaller or larger in voltage than  $V_{REFH}$  since the DAC design uses fully bidirectional switches as shown in Figure 16. The input resistance to the DAC has a code dependent variation which has a nominal worst case measured at 55<sub>H</sub>, which is approximately 1.2 k $\Omega$ . When  $V_{REFH}$  is greater than  $V_{REFL}$ , the REFL reference must be able to sink current out of the DAC ladder, while the REFH reference is sourcing current into the DAC ladder. The DAC design minimizes reference glitch current maintaining minimum interference between DAC channels during code changes.

### DAC OUTPUTS (O1-O12)

The twelve DAC outputs present a constant output resistance of approximately 5 k $\Omega$  independent of code setting. The distribution of R<sub>OUT</sub> from DAC-to-DAC typically matches within ±1%. However device-to-device matching is process lot dependent having a ±20% variation. The change in R<sub>OUT</sub> with temperature has a 500 ppm/°C temperature coefficient. During power shutdown all twelve outputs are open-circuited.

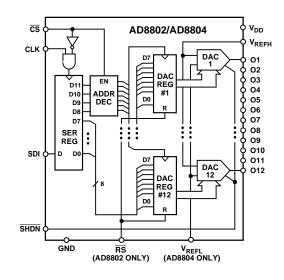


Figure 17. Block Diagram

#### DIGITAL INTERFACING

The AD8802/AD8804 contains a standard three-wire serial input control interface. The three inputs are clock (CLK),  $\overline{CS}$  and serial data input (SDI). The positive-edge sensitive CLK input requires clean transitions to avoid clocking incorrect data into the serial input register. Standard logic families work well. If mechanical switches are used for product evaluation, they should be debounced by a flip-flop or other suitable means. Figure 17 block diagram shows more detail of the internal digital circuitry. When  $\overline{CS}$  is taken active low, the clock can load data into the serial register on each positive clock edge, see Table II.

Table II. Input Logic Control Truth Table

<b>CS</b>	CLK	Register Activity
1	Х	No effect.
0	Р	Shifts Serial Register One bit loading the next bit in from the SDI pin.
P	1	Clock should be high when the $\overline{CS}$ returns to the inactive state.

P = Positive Edge, X = Don't Care.

The data setup and data hold times in the specification table determine the data valid time requirements. The last 12 bits of the data word entered into the serial register are held when  $\overline{CS}$  returns high. At the same time  $\overline{CS}$  goes high it gates the address decoder which enables one of the twelve positive-edge triggered DAC registers, see Figure 18 detail.

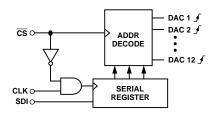


Figure 18. Equivalent Control Logic

The target DAC register is loaded with the last eight bits of the serial data-word completing one DAC update. Twelve separate 12-bit data words must be clocked in to change all twelve output settings.

All digital inputs are protected with a series input resistor and parallel Zener ESD structure shown in Figure 19. Applies to digital input pins  $\overline{CS}$ , SDI,  $\overline{RS}$ ,  $\overline{SHDN}$ , CLK

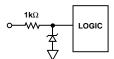


Figure 19. Equivalent ESD Protection Circuit

Digital inputs can be driven by voltages exceeding the AD8802/ AD8804  $V_{DD}$  supply value. This allows 5 V logic to interface directly to the part when it is operated at 3 V.

### APPLICATIONS

### **Supply Bypassing**

Precision analog products, such as the AD8802/AD8804, require a well filtered power source. Since the AD8802/AD8804 operate from a single +3 V to +5 V supply, it seems convenient to simply tap into the digital logic power supply. Unfortunately, the logic supply is often a switch-mode design, which generates noise in the 20 kHz to 1 MHz range. In addition, fast logic gates can generate glitches hundred of millivolts in amplitude due to wiring resistances and inductances.

If possible, the AD8802/AD8804 should be powered directly from the system power supply. This arrangement, shown in Figure 20, will isolate the analog section from the logic switching transients. Even if a separate power supply trace is not available, however, generous supply bypassing will reduce supply-line induced errors. Local supply bypassing consisting of a 10  $\mu$ F tantalum electrolytic in parallel with a 0.1  $\mu$ F ceramic capacitor is recommended (Figure 21).

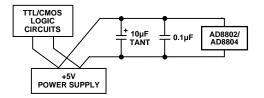


Figure 20. Use Separate Traces to Reduce Power Supply Noise

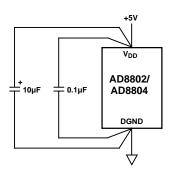


Figure 21. Recommended Supply Bypassing for the AD8802/AD8804

### Buffering the AD8802/AD8804 Output

In many cases, the nominal 5 k $\Omega$  output impedance of the AD8802/AD8804 is sufficient to drive succeeding circuitry. If a lower output impedance is required, an external amplifier can be added. Several examples are shown in Figure 22. One amplifier of an OP291 is used as a simple buffer to reduce the output resistance of DAC A. The OP291 was chosen primarily for its rail-to-rail input and output operation, but it also offers operation to less than 3 V, low offset voltage, and low supply current.

The next two DACs, B and C, are configured in a summing arrangement where DAC C provides the coarse output voltage setting and DAC B can be used for fine adjustment. The insertion of R1 in series with DAC B attenuates its contribution to the voltage sum node at the DAC C output.

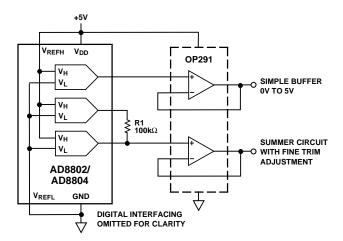


Figure 22. Buffering the AD8802/AD8804 Output

#### Increasing Output Voltage Swing

An external amplifier can also be used to extend the output voltage swing beyond the power supply rails of the AD8802/AD8804. This technique permits an easy digital interface for the DAC, while expanding the output swing to take advantage of higher voltage external power supplies. For example, DAC A of Figure 23 is configured to swing from -5 V to +5 V. The actual output voltage is given by:

$$V_{OUT} = \left(1 + \frac{R_F}{R_S}\right) \times \left(\frac{D}{256} \times 5V\right) - 5V$$

where D is the DAC input value (i.e., 0 to 255). This circuit can be combined with the "fine/coarse" circuit of Figure 22 if, for example, a very accurate adjustment around 0 V is desired.

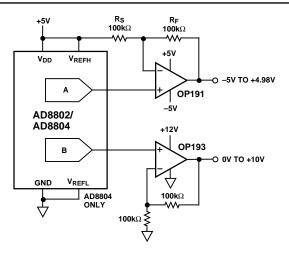


Figure 23. Increasing Output Voltage Swing

DAC B of Figure 24 is in a noninverting gain of two configurations, which increases the available output swing to +10 V. The feedback resistors can be adjusted to provide any scaling of the output voltage, within the limits of the external op amp power supplies.

### **Microcomputer Interfaces**

The AD8802/AD8804 serial data input provides an easy interface to a variety of single-chip microcomputers ( $\mu$ Cs). Many  $\mu$ Cs have a built-in serial data capability that can be used for communicating with the DAC. In cases where no serial port is provided, or it is being used for some other purpose (such as an RS-232 communications interface), the AD8802/AD8804 can easily be addressed in software.

Twelve data bits are required to load a value into the AD8802/ AD8804 (4 bits for the DAC address and 8 bits for the DAC value). If more than 12 bits are transmitted before the Chip Select input goes high, the extra (i.e., the most-significant) bits are ignored. This feature is valuable because most  $\mu$ Cs only transmit data in 8-bit increments. Thus, the  $\mu$ C will send 16 bits to the DAC instead of 12 bits. The AD8802/AD8804 will only respond to the last 12 bits clocked into the SDI port, however, so the serial data interface is not affected.

### An 8051 $\mu C$ Interface

A typical interface between the AD8802/AD8804 and an 8051  $\mu$ C is shown in Figure 24. This interface uses the 8051's internal serial port. The serial port is programmed for Mode 0 operation, which functions as a simple 8-bit shift register. The 8051's Port 3.0 pin functions as the serial data output, while Port 3.1 serves as the serial clock.

When data is written to the Serial Buffer Register (SBUF, at Special Function Register location  $99_{\rm H}$ ), the data is automatically converted to serial format and clocked out via Port 3.0 and Port 3.1. After 8 bits have been transmitted, the Transmit Interrupt flag (SCON.1) is set and the next 8 bits can be transmitted.

The AD8802 and AD8804 require the Chip Select to go low at the beginning of the serial data transfer. In addition, the SCLK input must be high when the Chip Select input goes high at the end of the transfer. The 8051's serial clock meets this requirement, since Port 3.1 both begins and ends the serial data in the high state.

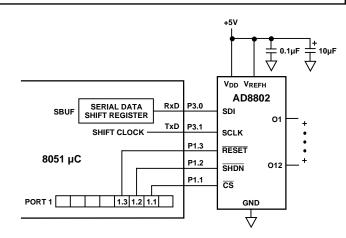


Figure 24. Interfacing the 8051  $\mu$ C to an AD8802/AD8804, Using the Serial Port

### Software for the 8051 Interface

A software for the AD8802/AD8804 to 8051 interface is shown in Listing 1. The routine transfers the 8-bit data stored at data memory location DAC\_VALUE to the AD8802/AD8804 DAC addressed by the contents of location DAC\_ADDR.

The subroutine begins by setting appropriate bits in the Serial Control register to configure the serial port for Mode 0 operation. Next the DAC's Chip Select input is set low to enable the AD8802/AD8804. The DAC address is obtained from memory location DAC\_ADDR, adjusted to compensate for the 8051's serial data format, and moved to the serial buffer register. At this point, serial data transmission begins automatically. When all 8 bits have been sent, the Transmit Interrupt bit is set, and the subroutine then proceeds to send the DAC value stored at location DAC\_VALUE. Finally the Chip Select input is returned high, causing the appropriate AD8802/AD8804 output voltage to change, and the subroutine ends.

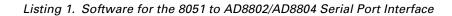
The 8051 sends data out of its shift register LSB first, while the AD8802/AD8804 require data MSB first. The subroutine therefore includes a BYTESWAP subroutine to reformat the data. This routine transfers the MSB-first byte at location SHIFT1 to an LSB-first byte at location SHIFT2. The routine rotates the MSB of the first byte into the carry with a Rotate Left Carry instruction, then rotates the carry into the MSB of the second byte with a Rotate Right Carry instruction. After 8 loops, SHIFT2 contains the data in the proper format.

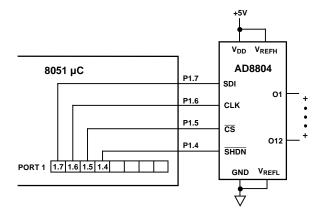
The BYTESWAP routine in Listing 1 is convenient because the DAC data can be calculated in normal LSB form. For example, producing a ramp voltage on a DAC is simply a matter of repeatedly incrementing the DAC\_VALUE location and calling the LD\_8802 subroutine.

If the  $\mu$ C's hardware serial port is being used for other purposes, the AD8802/AD8804 DAC can be loaded by using the parallel port. A typical parallel interface is shown in Figure 25. The serial data is transmitted to the DAC via the 8051's Port 1.6 output, while Port 1.6 acts as the serial clock.

Software for the interface of Figure 25 is contained in Listing 2. The subroutine will send the value stored at location DAC\_VALUE to the AD8802/AD8804 DAC addressed by location DAC\_ADDR. The program begins by setting the AD8802/AD8804's Serial Clock and Chip Select inputs high, then setting Chip Select low

This subroutine loads an AD8802/AD8804 DAC from an 8051 microcomputer, using the 8051's serial port in MODE 0 (Shift Register Mode). The DAC value is stored at location DAC VAL The DAC address is stored at location DAC\_ADDR Variable declarations PORT1 DATA 90H ;SFR register for port 1 DAC\_VALUE 40H ;DAC Value DATA DAC\_ADDR DATA 41H ;DAC Address ;high byte of 16-bit answer 042H SHIFT1 DATA ;low byte of answer SHIFT2 DATA 043H SHIFT\_COUNT DATA 44H ; ORG ;arbitrary start 100H DO\_8802: CLR SCON.7 ;set serial SCON.6 ;data mode 0 CLR CLR SCON.5 CLR SCON.1 ;clr transmit flag ORL PORT1.1,#00001110B ;/RS, /SHDN, /CS high ;set the /CS low CLR PORT1.1 MOV SHIFT1, DAC ADDR ;put DAC value in shift register ACALL BYTESWAP SBUF, SHIFT2 ;send the address byte MOV ADDR WAIT: INB SCON.1, ADDR WAIT ;wait until 8 bits are sent CLR ;clear the serial transmit flag SCON.1 SHIFT1, DAC\_VALUE send the DAC value MOV ACALL BYTESWAP SBUF, SHIFT2 MOV JNB SCON.1,VALU\_WAIT VALU\_WAIT: ;wait again SCON.1 clear serial flag CLR ;/CS high, latch data SETB PORT1.1 ; into AD8801 RET BYTESWAP: SHIFT\_COUNT,#8 MOV ;Shift 8 bits SWAP\_LOOP: MOV A,SHIFT1 ;Get source byte Rotate MSB to carry RLC А MOV SHIFT1,A ;Save new source byte MOV A,SHIFT2 ;Get destination byte RRC А ;Move carry to MSB MOV SHIFT2,A ;Save SHIFT\_COUNT,SWAP\_LOOP DJNZ ;Done? RET





**END** 

Figure 25. An AD8802/AD8804-8051  $\mu C$  Interface Using Parallel Port 1

to start the serial interface process. The DAC address is loaded into the accumulator and four Rotate Right shifts are performed. This places the DAC address in the 4 MSBs of the accumulator. The address is then sent to the AD8802/AD8804 via the SEND\_SERIAL subroutine. Next, the DAC value is loaded into the accumulator and sent to the AD8802/AD8804. Finally, the Chip Select input is set high to complete the data transfer

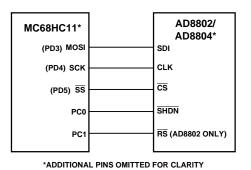
Unlike the serial port interface of Figure 24, the parallel port interface only transmits 12 bits to the AD8802/AD8804. Also, the BYTESWAP subroutine is not required for the parallel interface, because data can be shifted out MSB first. However, the results of the two interface methods are exactly identical. In most cases, the decision on which method to use will be determined by whether or not the serial data port is available for communication with the AD8802/AD8804.

; using the 8051's p ; The DAC value is			
, ; Variable declaration	ns		
PORT1	DATA	90H	;SFR register for port 1
DAC_VALUE	DATA	40H	;DAC Value
DAC_ADDR	DATA	41H	;DAC Address (0 through 7)
LOOPCOUNT	DATA	43H	;COUNT LOOPS
	;		,
	ORG	100H	;arbitrary start
LD_8804:	ORL	PORT1,#11110000B	;set CLK, /CS and /SHDN high
	CLR	PORT1.5	;Set Chip Select low
	MOV	LOOPCOUNT,#4	;Address is 4 bits
	MOV	A,DAC_ADDR	;Get DAC address
	RR	А	;Rotate the DAC
	RR	А	;address to the Most
	RR	А	;Significant Bits (MSBs)
	RR	А	;
	ACALL	SEND_SERIAL	;Send the address
	MOV	LOOPCOUNT,#8	;Do 8 bits of data
	MOV	A,DAC_VALUE	
	ACALL	SEND_SERIAL	;Send the data
	SETB	PORT1.5	;Set /CS high
	RET		;DONE
SEND_SERIAL:	RLC	А	;Move next bit to carry
OLIND_OLINIIL.	MOV	PORT1.7,C	;Move data to SDI
	CLR	PORT1.6	;Pulse the
	SETB	PORT1.6	;CLK input
	DJNZ	LOOPCOUNT,SEND_SERIAL	;Loop if not done
	RET;		
	END		
	=		

Listing 2. Software for the 8051 to AD8802/AD8804 Parallel Port Interface

#### An MC68HC11-to-AD8802/AD8804 Interface

Like the 8051  $\mu$ C, the MC68HC11 includes a dedicated serial data port (labeled SPI). The SPI port provides an easy interface to the AD8802/AD8804 (Figure 27). The interface uses three lines of Port D for the serial data, and one or two lines from Port C to control the SHDN and  $\overline{\text{RS}}$  (AD8802 only) inputs.



A software routine for loading the AD8802/AD8804 from a 68HC11 evaluation board is shown in Listing 3. First, the MC68HC11 is configured for SPI operation. Bits CPHA and CPOL define the SPI mode wherein the serial clock (SCK) is high at the beginning and end of transmission, and data is valid on the rising edge of SCK. This mode matches the requirements of the AD8802/AD8804. After the registers are saved on the stack, the DAC value and address are transferred to RAM and the AD8802/AD8804's  $\overline{CS}$  is driven low. Next, the DAC's address byte is transferred to the SPDR register, which automatically initiates the SPI data transfer. The program tests the SPIF bit and loops until the data transfer is complete. Then the DAC value is sent to the SPI. When transmission of the second byte is complete,  $\overline{CS}$  is driven high to load the new data and address into the AD8802/AD8804.

Figure 26. An AD8802/AD8804-to-MC68HC11 Interface

\* \* AD8802/AD8804 to M68HC11 Interface Assembly Program \*

\* M68HC11 Register definitions \*

*			
PORTC	EQU	\$1003	Port C control register
*		***	"0,0,0,0;0,0,RS/, SHDN/"
DDRC	EQU	\$1007	Port C data direction
PORTD *	EQU	\$1008	Port D data register
	FOU	#1000	"0,0,/CS,CLK;SDI,0,0,0"
DDRD	EQU	\$1009	Port D data direction
SPCR *	EQU	\$1028	SPI control register "SPIE,SPE,DWOM,MSTR;CPOL,CPHA,SPR1,SPR0"
SPSR	EQU	\$1029	SPIE, SPE, DWOM, MSTR, CPOL, CPHA, SPRI, SPRO
*	EQU	φ1029	"SPIF,WCOL,0,MODF;0,0,0,0"
SPDR	EQU	\$102A	SPI data register; Read-Buffer; Write-Shifter
*		n -	
* SDI RAM	variables:		SDI1 is encoded from 0H to 7H
*			SDI2 is encoded from 00H to FFH
*			AD8802/AD8804 requires two 8-bit loads; upper 4 bits
*			of SDI1 are ignored. AD8802/AD8804 address bits in last
*			four LSBs of SDI1.
SDI1	EQU	\$00	SDI packed byte 1 "0,0,0,0;A3,A2,A1,A0"
SDI1 SDI2	EQU	\$00 \$01	SDI packed byte 1 0,0,0,0,A3,A2,A1,A0 SDI packed byte 2 "DB7–DB4;DB3–DB0"
*	EQU	φ01	3DI packed byte 2 DB7-DB4,DB3-DB0
* Main Progr *	ram		
^	ORG	\$C000	Start of user's RAM in EVB
INIT	LDS	#\$CFFF	Top of C page RAM
*	220	11 ¥ 01 1 1	
* Initialize Po	ort C Outputs		
	LDAA	#\$03	0,0,0,0;0,0,1,1
*			/RS-Hi, /SHDN-Hi
	STAA	PORTC	Initialize Port C Outputs
	LDAA	#\$03	0,0,0,0;0,0,1,1
	STAA	DDRC	/RS and /SHDN are now enabled as outputs
* * Initialize Po	ort D Outputs		
*	_		
	LDAA	#\$20	0,0,1,0;0,0,0,0
*		DODTD	/CS-Hi,/CLK-Lo,SDI-Lo
	STAA	PORTD	Initialize Port D Outputs
	LDAA	#\$38 DDDD	0,0,1,1;1,0,0,0
*	STAA	DDRD	/CS,CLK, and SDI are now enabled as outputs
* Initialize SI	PI Interface		
*		##52	
	LDAA	#\$53	SPL is Master CPUA=0 CPOI=0 Cll rate= $E/22$
*	STAA	SPCR	SPI is Master, CPHA=0, CPOL=0, Clk rate=E/32
* Call update	e subroutine		
*	DOD		Vou 0.0 Literrards to AD0400
	BSR	UPDATE	Xfer 2 8-bit words to AD8402
*	JMP	\$E000	Restart BUFFALO
* Subroutine	UPDATE		
* UPDATE	PSHX	Save registers X	V and A
UDATE	PSHY	Save registers A	, 1, and 11
	PSHA		

\* Enter Contents of SDI1 Data Register

*			
	LDAA	\$0000	Hi-byte data loaded from memory
*	STAA	SDI1	SDI1 = data in location 0000H
	ntents of SDI2 Da	ata Register	
*			
	LDAA	\$0001	Low-byte data loaded from memory
*	STAA	SDI2	SDI2 = Data in location 0001H
	LDX	#SDI1	Stack pointer at 1st byte to send via SDI
	LDY	#\$1000	Stack pointer at on-chip registers
*	0000 + 116		have a Decert in such
* Reset AD	8802 to one-half	scale (AD8804 does not )	nave a Reset input)
	BCLR	PORTC,Y \$02	Assert /RS
	BSET	PORTC,Y \$02	De-Assert /RS
* * Cot AD89	802/04 ready for c	lata input	
* Get AD80	502/04 ready for t	iata input	
	BCLR	PORTD,Y \$02	Assert /CS
		0.37	
TFRLP	LDAA STAA	0,X SPDR	Get a byte to transfer for SPI Write SDI data reg to start xfer
*	onni	01 D K	while obt data leg to start her
WAIT	LDAA	SPSR	Loop to wait for SPIF
*	BPL	WAIT	SPIF is the MSB of SPSR
~	INX		Increment counter to next byte for xfer
	CPX	#SDI2+1	Are we done yet ?
1	BNE	TFRLP	If not, xfer the second byte
* * Undate A	D8802 output		
*	Dooo2 output		
	BSET	PORTD,Y \$20	Latch register & update AD8802
*			
	PULA PULY		When done, restore registers X, Y & A
	PULX		
	RTS		** Return to Main Program **
	1:	cting 2 100002/1000	04 to MC69UC11 Interface Program Source

Listing 3. AD8802/AD8804 to MC68HC11 Interface Program Source Code

# An Intelligent Temperature Control System—Interfacing the $8051 \ \mu C$ with the AD8802/AD8804 and TMP14

Connecting the 80CL51  $\mu$ C, or any modern microcontroller, with the TMP14 and AD8802/AD8804 yields a powerful temperature control tool, as shown in Figure 27. For example, the 80CL51  $\mu$ C controls the TrimDACs allowing the user to automatically set the temperature setpoints voltages of the TMP14 via computer or touch pad, while the TMP14 senses the temperature and outputs four open-collector trip-points. Feeding these trip-point outputs back to the 80CL51  $\mu$ C allow it to sense whether or not a setpoint has been exceeded. Additional 80CL51  $\mu$ C port pins or TMP14 trip-point outputs may then be used to change fan speed (i.e., high, medium, low, off), or increase/decrease the power level to a heater. (Please refer to the TMP14 data sheet for more applications information.)

The  $\overline{\text{CS}}$  (Chip Select) on the AD8802/AD8804 makes applications that call for large temperature sensor arrays possible. In addition, the 12 channels of the AD8802/AD8804 allow independent setpoint control for all four trip-point outputs on up to three TMP14 temperature sensors. For example, assume that the 80CL51  $\mu$ C has eight free port pins available after all user interface lines, interrupts, and the serial port lines have been assigned. The eight port pins may be used as chip selects, in which case an array of eight AD8802/AD8804s controlling twenty-four TMP14 sensors is possible.

The AD8802/AD8804 and TMP14 are also ideal choices for low power applications. These devices have power shutdown modes and operate on a single 5 Volt supply. When their shutdown modes are activated current consumption is reduced to less than 35  $\mu$ A. However, at high operating frequencies (12 MHz) the 80CL51 consumes far more energy (18 mA typ) than the AD8802/AD8804 and TMP14 combined. Therefore, to achieve a low power design the 80CL51 should operate at its lowest possible frequency or be placed in its power-down mode at the end of each instruction sequence.

To use the power-down mode of the 80CL51  $\mu$ C set PCON.1 as the last instruction executed prior to going into the powerdown mode. If INT2 and INT9 are enabled, the 80CL51  $\mu$ C can be awakened from power-down mode with external interrupts. As shown in Figure 28, the TLC555 outputs a pulse every few seconds providing the interrupt to restart the 80CL51  $\mu$ C which then samples the user input pins, the outputs of the

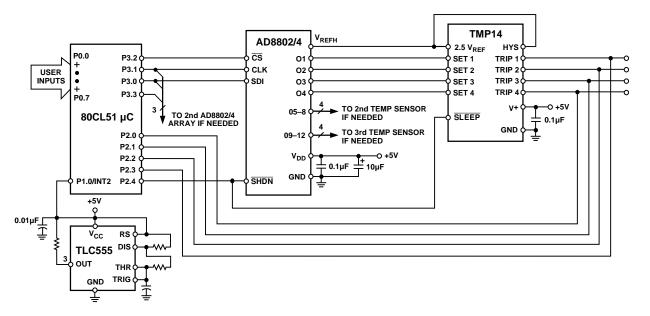


Figure 27. Temperature Sensor Array with Programmable Setpoints

TMP14, and makes the necessary adjustments to the AD8802/ AD8804 before shutting down again. The 80CL51 consumes only 50  $\mu$ A when operating at 32 kHz, in which case there would be no need for the TLC555, which consumes 1 mW typ.

**12 Channel Programmable Voltage Controlled Amplifier** The SSM2018T is a trimless Voltage Controlled Amplifier (VCA) for volume control in audio systems. The SSM2018T is the first professional quality audio VCA in the marketplace that does not require an external trimming potentiometer to minimize distortion. The TrimDAC shown in Figure 28 is not being used to trim distortion, but rather to control the gain of the amplifier. In this configuration up to twelve SSM2018T can be digitally controlled. (Please refer to the SSM2018T data sheet for more specifications and applications information.) The gain of the SSM2018T is controlled by the voltage at Pin 11. For maximum attenuation of -100 dB a control signal of 3.0 V typ is necessary. The control signal has a scale of -30 mV/dB centered around 0 dB gain for 0 V of control voltage, therefore, for a maximum gain of 40 dB a control voltage of -1.2 volts is necessary. Now notice that the normal +5 V to GND voltage range of the AD8802/AD8804 does not cover the 3.0 V to -1.2 V operational gain control range of the SSM2018T. To cover the operating gain range fully and not exceed the maximum specified power supply rating requires the O1 output of AD8802/AD8804 to be level shifted down. In Figure 28, the level shifting is accomplished by a Zener diode and 1/4 of an OP420 quad op amp. For applications that require only

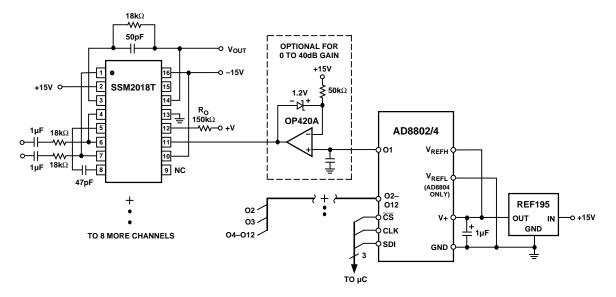


Figure 28. 12-Channel Programmable Voltage Controlled Amplifier

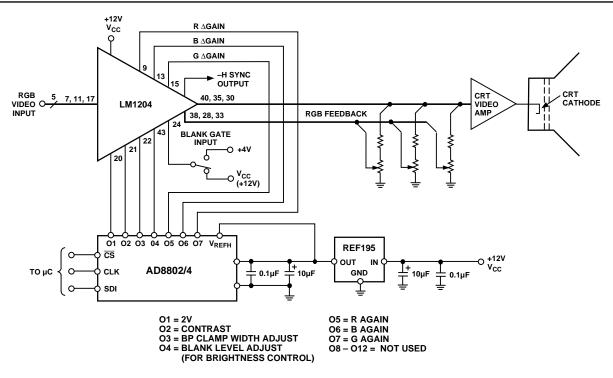


Figure 29. A Digitally Controlled LM1204—150 MHz RGB Amplifier System

attenuation the optional circuitry inside the dashed box may be removed and replaced with a direct connection from O1 of AD8802/AD8804 to Pin 11 of SSM2018T.

When high gain resolution is desired,  $V_{REFH}$  and  $V_{REFL}$  may be decoupled from the power rails and shifted closer together. This technique increases the gain resolution with the unfortunate penalty of decreased gain range.

#### A Digitally Controlled LM1204 150 MHz RGB Amplifier System

The LM1204 is an industry standard video amplifier system. Figure 29 illustrates a configuration that removes the usual seven level setting potentiometers and replaces them with only one IC. The AD8802/AD8804, in addition to being smaller and more reliable than mechanical potentiometers, has the added feature of digital control.

The REF195 is a 5.0 V reference used to supply both the power and reference voltages to the AD8802/AD8804. This is possible because of the high reference output current available (30 mA typical) together with the low power consumption of the AD8802/AD8804.

### A Low Noise 90 MHz Programmable Gain Amplifier

The AD603 is a low noise, voltage-controlled amplifier for use in RF and IF AGC systems. It provides accurate, pin selectable gains of -11 dB to +31 dB with a bandwidth of 90 MHz or +9 dB to +51 dB with a bandwidth of 9 MHz. Any intermediate gain range may be arranged using one external resistor between Pins 5 and 7. The input referred noise spectral density is only 1.3 nV $\sqrt{\text{Hz}}$  and power consumption is 125 mW at the recommended  $\pm 5$  V supplies.

The decibel gain is "linear in dB," accurately calibrated, and stable over temperature and supply. The gain is controlled at a high impedance (50 MΩ), low bias (200 nA) differential input; the scaling is 25 mV/dB, requiring a gain-control voltage of only 1 V to span the central 40 dB of the gain range. An overrange and underrange of 1 dB is provided whatever the selected range. The gain-control response time is less than 1  $\mu$ s for a 40 dB change. The settling time of the AD8802/AD8804 to within a ±1/2 LSB band is 0.6  $\mu$ s making it an excellent choice for control of the AD603.

The differential gain-control interface allows the use of either differential or single-ended positive or negative control voltages, where the common-mode range is -1.2 V to 2.0 V. Once again the AD8802/AD8804 is ideally suited to provide the differential input range of 1 V within the common-mode range of 0 V to 2 V. To accomplish this, place V<sub>REFH</sub> at 2.0 V and V<sub>REFL</sub> at 1.0 V, then all 256 voltage levels of the AD8804 will fall within the gain-control range of the AD603. Please refer to the AD603 data sheet for further information regarding gain control, layout, and general operation.

The dual OP279 is a rail-to-rail op amp used in Figure 30 to drive the inputs  $V_{REFH}$  and  $V_{REFL}$  because these reference inputs are low impedance (2 k $\Omega$  typical).

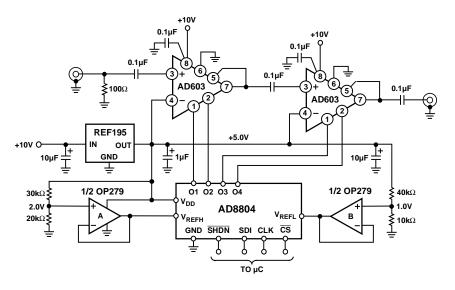


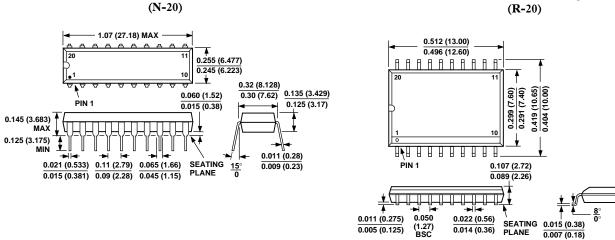
Figure 30. A Low Noise 90 MHz PGA

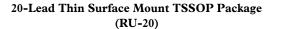
### **OUTLINE DIMENSIONS**

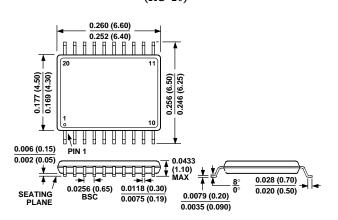
Dimensions shown in inches and (mm)

20-Lead SOIC Package

20-Pin Plastic DIP Package (N-20)







-16-

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->||-

0.034 (0.86) 0.018 (0.46)



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