

# AN12267

## FXPS7xxx series pressure sensor self-test features

Rev. 1 — 15 November 2018

Application note

### Document information

Information	Content
Keywords	self test, digital barometric absolute pressure (DBAP), absolute pressure sensor, engine management, comfort seating, exhaust gas recirculation (EGR), media resistant, media compatible, serial peripheral interface (SPI)
Abstract	This document describes the diagnostic features present in the NXP DBAP series of sensors. This document is an addition to the information present in the product data sheets and describes the internal working mechanism of all the self-test modes. This application note describes the self-test procedures and presents the diagnostic details. For further information, refer to the safety manual as well as to other functional safety documentation available upon request from NXP.



## Revision history

Rev	Date	Description
1	20181115	initial version

## 1 Introduction

This technical application note provides an overview of the self-test features of the FXPS7xxx digital barometric absolute pressure (DBAP) serial peripheral interface (SPI) based pressure sensors. The devices include analog and digital self-test features to verify the functionality of the transducer and signal chain.

The self-test features described in this application note assume that the user has reviewed the latest released data sheet for the applicable device and is familiar with the recommended application circuit and the register space definition. References to individual registers are made throughout this document and the definition for such registers is present in the product data sheet.

## 2 Applicable parts

**Table 1. Applicable parts**

Part number	Part name	Description
FXPS7115DS4T1	DBAP	40 kPa to 115 kPa SPI-based digital absolute pressure sensor
FXPS7250DS4T1	DBAP	20 kPa to 250 kPa SPI-based digital absolute pressure sensor
FXPS7400DS4T1	DBAP	20 kPa to 400 kPa SPI-based digital absolute pressure sensor
FXPS7550DS4T1	DBAP	20 kPa to 550 kPa SPI-based digital absolute pressure sensor

## 3 Self-test overview

The device includes analog and digital self-test functions to verify the functionality of the transducer and the signal chain. The self-test functions are selected by writing to the ST\_CTRL[3:0] bits in the DSP\_CFG\_U5 register. The ST\_CTRL bits determine the desired self test according to the description in the following sections.

Once the ENDINIT bit is set, the ST\_CTRL bits are forced to 0000b. Future writes to the ST\_CTRL bits are disabled until a device reset.

### 3.1 Startup $P_{abs}$ common mode verification

When the  $P_{abs}$  common mode self test is selected, the ST\_ACTIVE bit is set, the ST\_ERROR is cleared, and the device begins an internal measurement of the common mode signal of the P cells and compares the result against a pre-determined limit. If the result exceeds the limit, the ST\_ERROR bit is set.

The  $P_{abs}$  common mode self test repeats continuously every  $t_{ST\_INIT}$  when the ST\_CTRL bits are set to the specified value. Once the test is disabled, the ST\_ERROR bit is updated with the final test result within  $t_{ST\_INIT}$  of disabling the test. The ST\_ACTIVE bit remains set until the final test result is reported.

[Figure 1](#) shows an example of a user controlled self-test procedure.

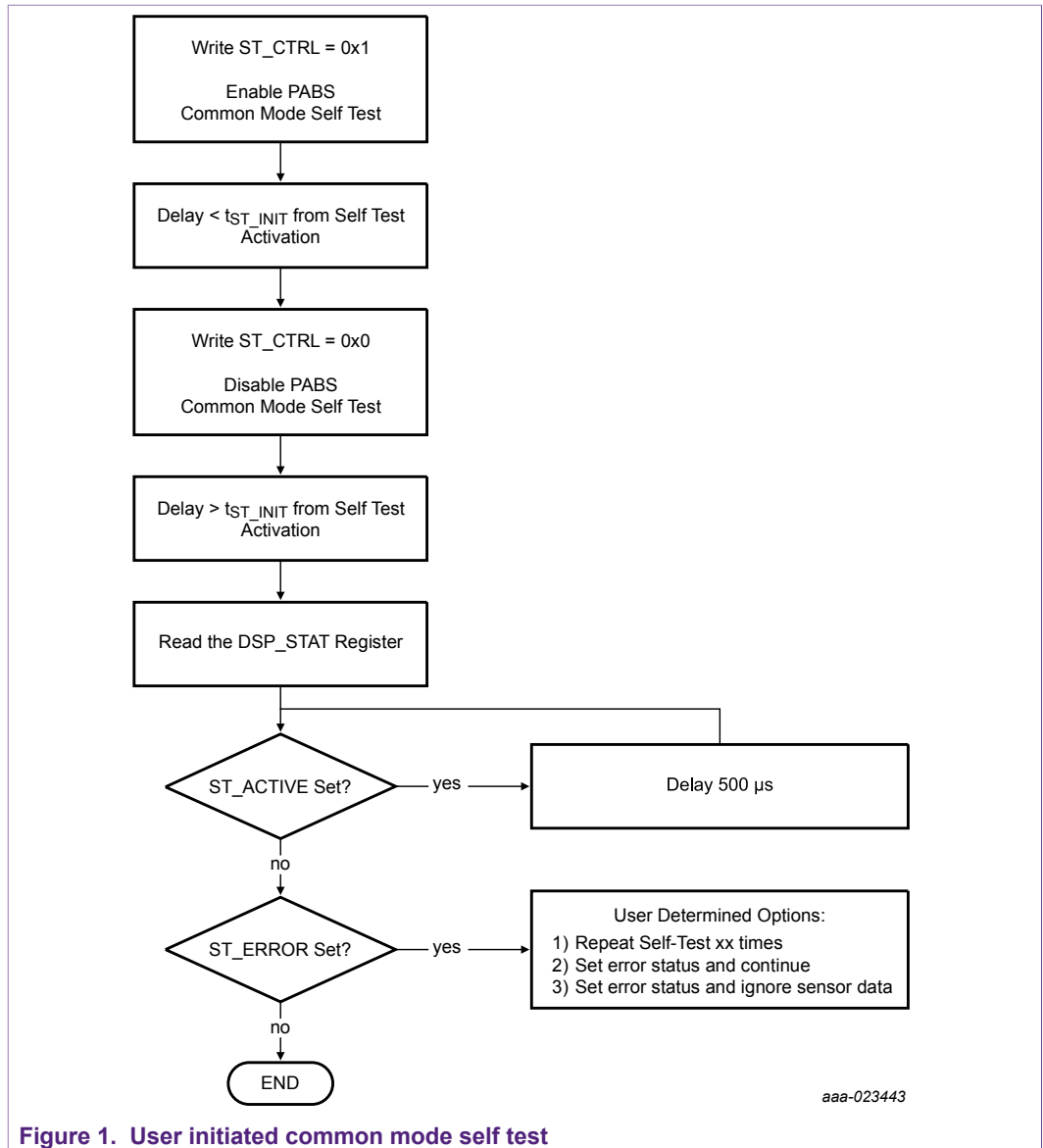


Figure 1. User initiated common mode self test

### 3.2 Startup digital self-test verification

Four unique fixed values can be forced at the output of the sync filter by writing to the ST\_CTRL bits; see [Table 2](#). The digital self-test values result in a constant value at the output of the signal chain. After a specified time, the SNS\_DATAx\_x register value can be verified against the values in [Table 2](#). When any of these self-test functions are selected, the ST\_ACTIVE bit is set. These signals can only be selected when the ENDINIT bit is not set.

**Table 2. Self-test control register values for digital self test**

ST_CTRL[3:0]				Function	SNS_DATAx_x register content
1	1	0	0	digital self test 1	0x8171
1	1	0	1	digital self test 2	0x6C95
1	1	1	0	digital self test 3	0x807A
1	1	1	1	digital self test 4	0x78AC

### 3.3 Startup sense data fixed value verification

Four unique fixed values can be forced to the SNS\_DATAx\_x registers by writing to the ST\_CTRL bits; see [Table 3](#). When any of these values are selected, the ST\_ACTIVE bit is set. These signals can only be selected when the ENDINIT bit is not set.

**Table 3. Self-test control bits for startup sense data fixed value verification**

ST_CTRL[3:0]				Function	SNS_DATAx_x register content
0	1	0	0	digital signal processor (DSP) write to SNS_DATAx_x registers inhibited	0x0000
0	1	0	1	digital self test 2	0xAAAA
0	1	1	0	digital self test 3	0x5555
0	1	1	1	digital self test 4	0xFFFF

### 3.4 Complete self test

The next step is to complete some or all of the various self-test functions available in the device. [Figure 2](#) shows an overview of an example recommended procedure for completing self test. Test repeats on failure are not shown in the diagrams. The user, based on the application, determines the number or test repeats for each test type. Typically test repeats are included at a minimum for the analog self-test procedures to provide immunity to potential misuse inputs that are common during startup.

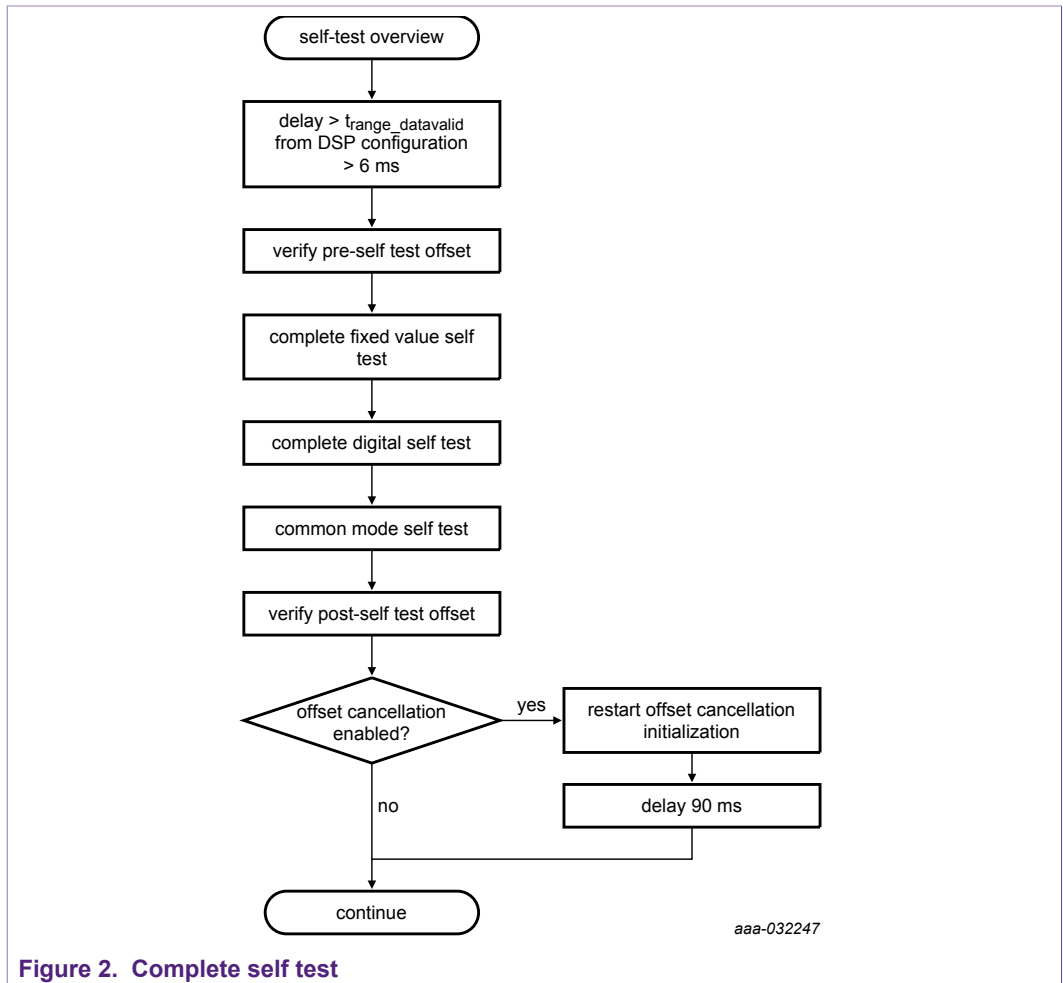
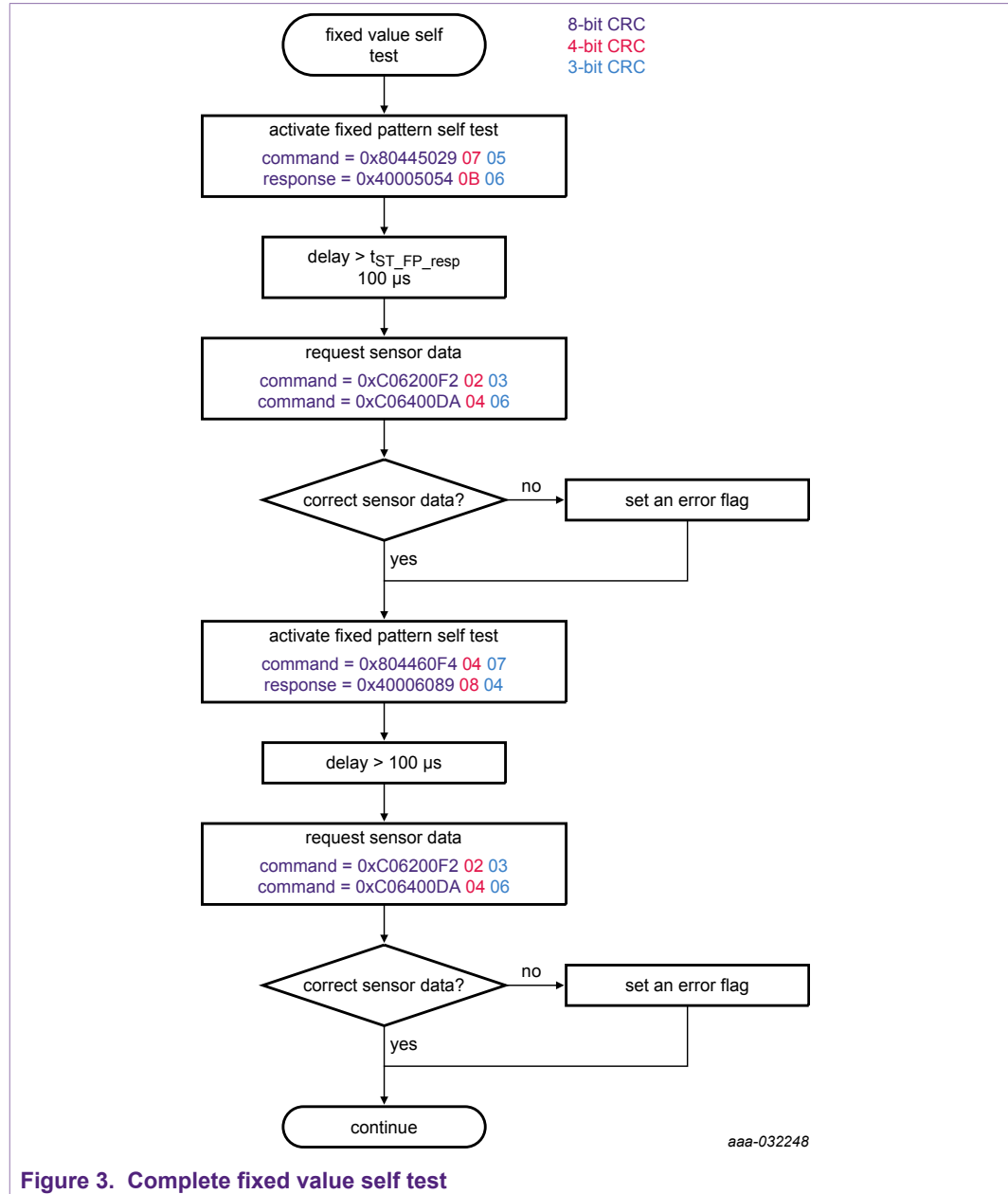


Figure 2. Complete self test

3.4.1 Complete fixed value self-test

The next step is to complete a fixed value self-test verification for each device. The purpose of the fixed value self-test is to confirm that the output data register and communication block have no stuck bit conditions. Figure 3 shows an example procedure for completing self-test with fixed values. Expected responses are included for each self-test request.

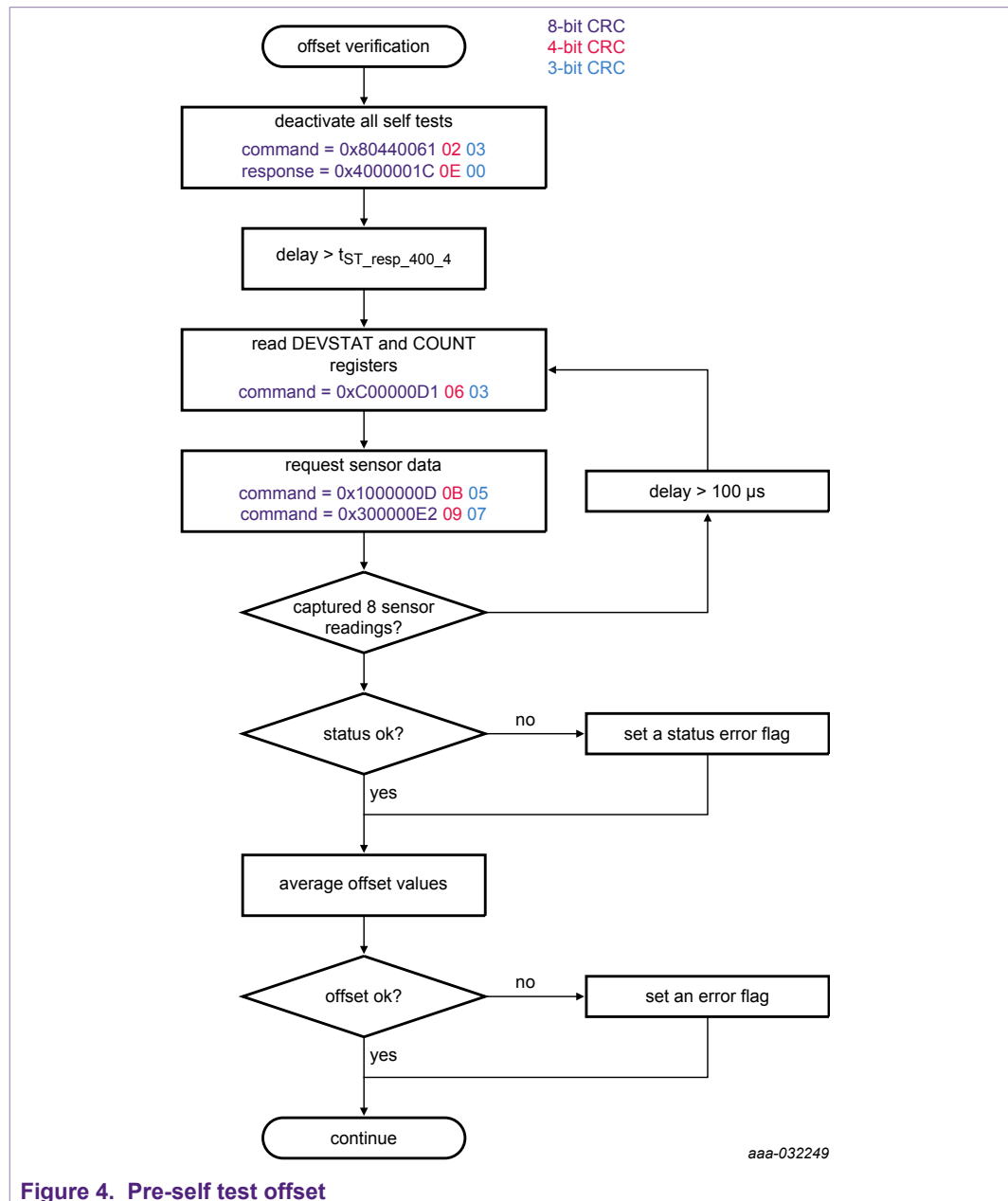


3.4.2 Complete pre-self test offset

The next step is to complete an offset verification. The purpose of the offset verification is to:

1. Verify the offset of the device and any change in offset before and after the self-test motion.
2. Capture the pre-self test offset that is subtracted from the measured self-test values during analog self-test.

The flowchart in [Figure 4](#) shows an example procedure for capturing the sensor offset.





### 3.4.3 Complete digital self test

The next step is to complete a digital self-test verification for each device. The purpose of the digital self test is to complete a more accurate verification of the digital signal chain. The digital self test forces a known value into the input of the digital signal chain. After a defined interval of time, dependent on the low-pass filter selected, the signal chain output can be verified against an expected value plus or minus a small tolerance. [Figure 5](#) shows an example procedure for completing self test of one digital value (digital self test 0xC) and confirming the expected output value.

If offset cancellation is planned to be used, it is recommended to bypass the offset cancellation filter for digital self test to eliminate the effects of the filter on the digital self-test result. The procedure below includes offset cancellation bypass during digital self test.

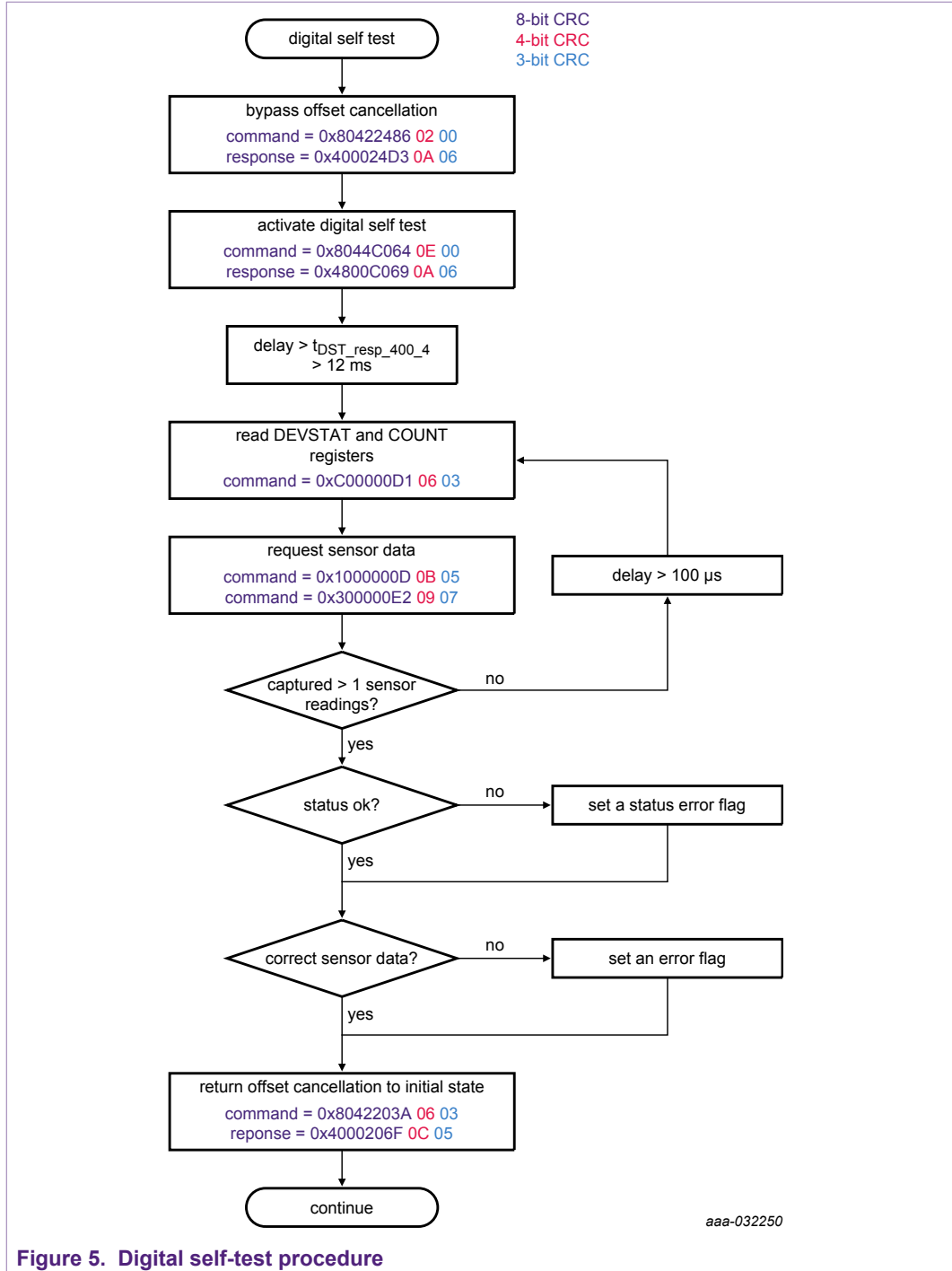


Figure 5. Digital self-test procedure

### 3.4.4 Complete common mode self test

The next step is to complete an offset and analog common mode self-test verification. The purpose of the analog self test is to:

1. Confirm the P cell health by monitoring the common mode signal of the two P cells implemented in the microelectromechanical system (MEMS) design.
2. Verify the sensitivity accuracy of the device. The FXPS7xxx devices contain multiple self-test capabilities and procedures that have different sensitivity accuracy verification capabilities.
3. Verify the offset of the device and any change in offset before and after the self-test motion.

The flowchart in [Figure 6](#) shows an example analog self-test procedure for measuring common mode self-test values.

When sensor data is read for any of the analog self-test functions, the sensor data can be accessed either by using the sensor data request commands or by reading the SNS\_DATAx\_x registers directly. For some user gain settings, the analog self test results in a potential railed sensor data output via the sensor data request commands. For these test cases, the data must be read via the SNS\_DATAx\_x registers.

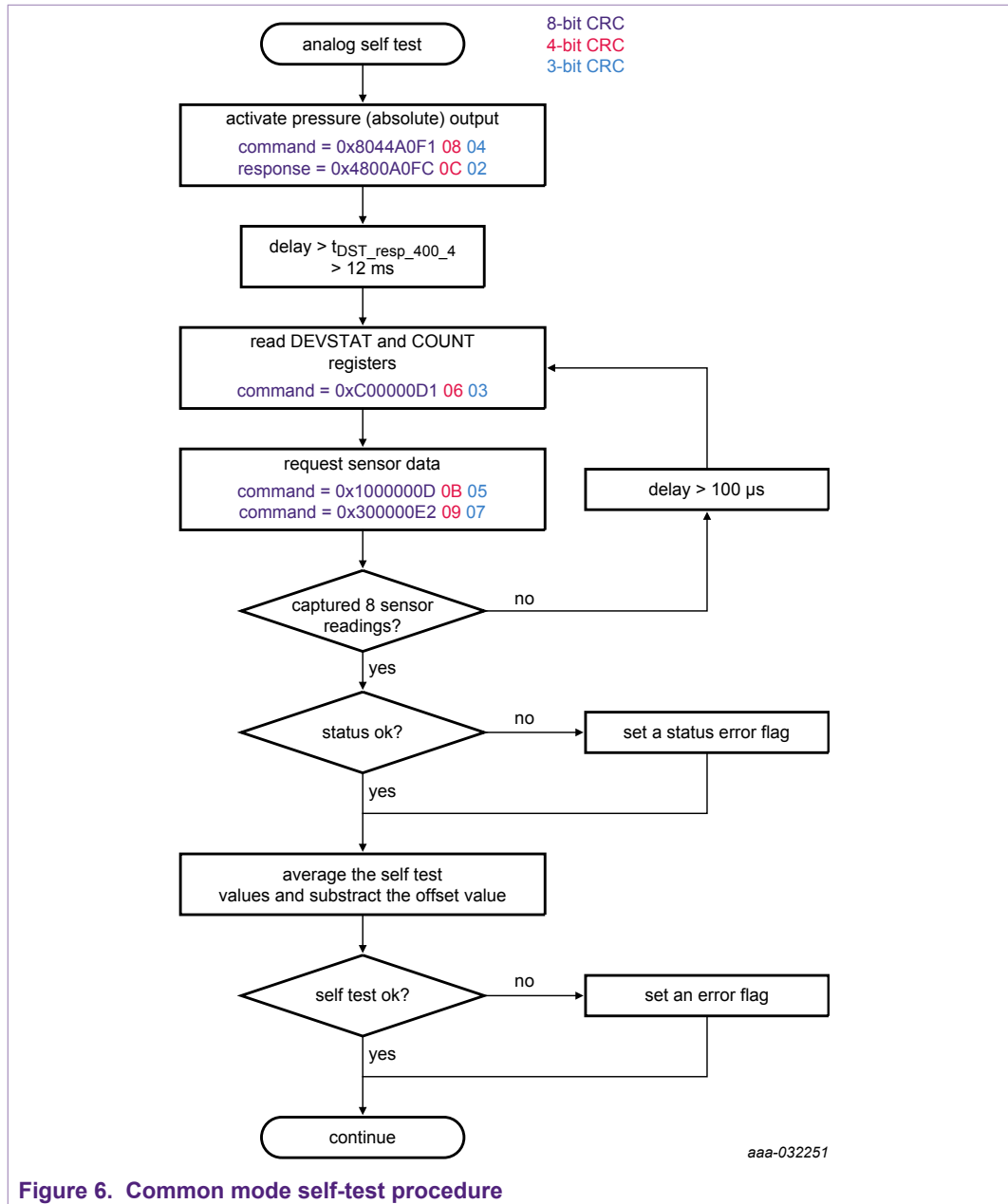


Figure 6. Common mode self-test procedure

## 4 Transition to normal mode

Once all self-test procedures are complete and verified, the system can transition the device from initialization to normal mode. This transition is done by setting the ENDINIT bit.

The typical time taken to complete all sensor self tests from power-on reset (POR) is ~ 54 ms.

## 5 Abbreviations

Table 4. Abbreviations

Acronym	Description
ADC	analog-to-digital converter
Analog self test	A method to test the analog signal chain by simulating the transducer input and measuring the device output.
DBAP	digital barometric absolute pressure
Digital self test	A method to test the digital portion of the pressure signal chain by forcing a value or a sequence of values at the output of the ADC and measuring the device output.
DSP	digital signal processor
EGR	exhaust gas recirculation
MEMS	microelectromechanical system
MISO	master input slave output
MOSI	master output slave input
POR	power-on reset
SCLK	SPI device clock
SPI	serial peripheral interface; a full-duplex, synchronous serial interface; the FXPS7xxx devices operate of a 32-bit implementation of SPI
SS_B	slave select bar, active LOW signal from the bus master to select the device
ST	self test

## 6 References

- [1] **Product summary page** — <http://www.nxp.com/FXPS7xxx>

## 7 Legal information

### 7.1 Definitions

**Draft** — The document is a draft version only. The content is still under internal review and subject to formal approval, which may result in modifications or additions. NXP Semiconductors does not give any representations or warranties as to the accuracy or completeness of information included herein and shall have no liability for the consequences of use of such information.

### 7.2 Disclaimers

**Limited warranty and liability** — Information in this document is believed to be accurate and reliable. However, NXP Semiconductors does not give any representations or warranties, expressed or implied, as to the accuracy or completeness of such information and shall have no liability for the consequences of use of such information. NXP Semiconductors takes no responsibility for the content in this document if provided by an information source outside of NXP Semiconductors. In no event shall NXP Semiconductors be liable for any indirect, incidental, punitive, special or consequential damages (including - without limitation - lost profits, lost savings, business interruption, costs related to the removal or replacement of any products or rework charges) whether or not such damages are based on tort (including negligence), warranty, breach of contract or any other legal theory. Notwithstanding any damages that customer might incur for any reason whatsoever, NXP Semiconductors' aggregate and cumulative liability towards customer for the products described herein shall be limited in accordance with the Terms and conditions of commercial sale of NXP Semiconductors.

**Right to make changes** — NXP Semiconductors reserves the right to make changes to information published in this document, including without limitation specifications and product descriptions, at any time and without notice. This document supersedes and replaces all information supplied prior to the publication hereof.

**Applications** — Applications that are described herein for any of these products are for illustrative purposes only. NXP Semiconductors makes no representation or warranty that such applications will be suitable for the specified use without further testing or modification. Customers are responsible for the design and operation of their applications and products using NXP Semiconductors products, and NXP Semiconductors accepts no liability for any assistance with applications or customer product design. It is customer's sole responsibility to determine whether the NXP Semiconductors product is suitable and fit for the customer's applications and products planned, as well as for the planned application and use of

customer's third party customer(s). Customers should provide appropriate design and operating safeguards to minimize the risks associated with their applications and products. NXP Semiconductors does not accept any liability related to any default, damage, costs or problem which is based on any weakness or default in the customer's applications or products, or the application or use by customer's third party customer(s). Customer is responsible for doing all necessary testing for the customer's applications and products using NXP Semiconductors products in order to avoid a default of the applications and the products or of the application or use by customer's third party customer(s). NXP does not accept any liability in this respect.

**Suitability for use in automotive applications** — This NXP Semiconductors product has been qualified for use in automotive applications. Unless otherwise agreed in writing, the product is not designed, authorized or warranted to be suitable for use in life support, life-critical or safety-critical systems or equipment, nor in applications where failure or malfunction of an NXP Semiconductors product can reasonably be expected to result in personal injury, death or severe property or environmental damage. NXP Semiconductors and its suppliers accept no liability for inclusion and/or use of NXP Semiconductors products in such equipment or applications and therefore such inclusion and/or use is at the customer's own risk.

**Export control** — This document as well as the item(s) described herein may be subject to export control regulations. Export might require a prior authorization from competent authorities.

**Translations** — A non-English (translated) version of a document is for reference only. The English version shall prevail in case of any discrepancy between the translated and English versions.

**Security** — While NXP Semiconductors has implemented advanced security features, all products may be subject to unidentified vulnerabilities. Customers are responsible for the design and operation of their applications and products to reduce the effect of these vulnerabilities on customer's applications and products, and NXP Semiconductors accepts no liability for any vulnerability that is discovered. Customers should implement appropriate design and operating safeguards to minimize the risks associated with their applications and products.

### 7.3 Trademarks

Notice: All referenced brands, product names, service names and trademarks are the property of their respective owners.

**POR** — is a trademark of NXP B.V.

## Contents

---

<b>1</b>	<b>Introduction</b> .....	<b>3</b>
<b>2</b>	<b>Applicable parts</b> .....	<b>3</b>
<b>3</b>	<b>Self-test overview</b> .....	<b>3</b>
3.1	Startup Pabs common mode verification .....	3
3.2	Startup digital self-test verification .....	5
3.3	Startup sense data fixed value verification .....	5
3.4	Complete self test .....	6
3.4.1	Complete fixed value self-test .....	7
3.4.2	Complete pre-self test offset .....	8
3.4.3	Complete digital self test .....	9
3.4.4	Complete common mode self test .....	11
<b>4</b>	<b>Transition to normal mode</b> .....	<b>12</b>
<b>5</b>	<b>Abbreviations</b> .....	<b>13</b>
<b>6</b>	<b>References</b> .....	<b>13</b>
<b>7</b>	<b>Legal information</b> .....	<b>14</b>

---

Please be aware that important notices concerning this document and the product(s) described herein, have been included in section 'Legal information'.

---

© NXP B.V. 2018.

All rights reserved.

For more information, please visit: <http://www.nxp.com>

For sales office addresses, please send an email to: [salesaddresses@nxp.com](mailto:salesaddresses@nxp.com)

Date of release: 15 November 2018  
Document identifier: AN12267

Компания «Океан Электроники» предлагает заключение долгосрочных отношений при поставках импортных электронных компонентов на взаимовыгодных условиях!

Наши преимущества:

- Поставка оригинальных импортных электронных компонентов напрямую с производств Америки, Европы и Азии, а так же с крупнейших складов мира;
- Широкая линейка поставок активных и пассивных импортных электронных компонентов (более 30 млн. наименований);
- Поставка сложных, дефицитных, либо снятых с производства позиций;
- Оперативные сроки поставки под заказ (от 5 рабочих дней);
- Экспресс доставка в любую точку России;
- Помощь Конструкторского Отдела и консультации квалифицированных инженеров;
- Техническая поддержка проекта, помощь в подборе аналогов, поставка прототипов;
- Поставка электронных компонентов под контролем ВП;
- Система менеджмента качества сертифицирована по Международному стандарту ISO 9001;
- При необходимости вся продукция военного и аэрокосмического назначения проходит испытания и сертификацию в лаборатории (по согласованию с заказчиком);
- Поставка специализированных компонентов военного и аэрокосмического уровня качества (Xilinx, Altera, Analog Devices, Intersil, Interpoint, Microsemi, Actel, Aeroflex, Peregrine, VPT, Syfer, Eurofarad, Texas Instruments, MS Kennedy, Miteq, Cobham, E2V, MA-COM, Hittite, Mini-Circuits, General Dynamics и др.);

Компания «Океан Электроники» является официальным дистрибьютором и эксклюзивным представителем в России одного из крупнейших производителей разъемов военного и аэрокосмического назначения «JONHON», а так же официальным дистрибьютором и эксклюзивным представителем в России производителя высокотехнологичных и надежных решений для передачи СВЧ сигналов «FORSTAR».



## JONHON

«JONHON» (основан в 1970 г.)

Разъемы специального, военного и аэрокосмического назначения:

(Применяются в военной, авиационной, аэрокосмической, морской, железнодорожной, горно- и нефтедобывающей отраслях промышленности)

«FORSTAR» (основан в 1998 г.)

ВЧ соединители, коаксиальные кабели,  
кабельные сборки и микроволновые компоненты:

(Применяются в телекоммуникациях гражданского и специального назначения, в средствах связи, РЛС, а так же военной, авиационной и аэрокосмической отраслях промышленности).



Телефон: 8 (812) 309-75-97 (многоканальный)

Факс: 8 (812) 320-03-32

Электронная почта: [ocean@oceanchips.ru](mailto:ocean@oceanchips.ru)

Web: <http://oceanchips.ru/>

Адрес: 198099, г. Санкт-Петербург, ул. Калинина, д. 2, корп. 4, лит. А