



# Tiny 16-/14-/12-Bit SPI *nano*DAC+, with $\pm 2$ (16-Bit) LSB INL and 2 ppm/°C Reference

## Data Sheet

## AD5683R/AD5682R/AD5681R/AD5683

### FEATURES

Ultrasmall package: 2 mm × 2 mm, 8-lead LFCSP  
High relative accuracy (INL):  $\pm 2$  LSB maximum at 16 bits  
[AD5683R/AD5682R/AD5681R](#)  
Low drift, 2.5 V reference: 2 ppm/°C typical  
Selectable span output: 2.5 V or 5 V  
[AD5683](#)  
External reference only  
Selectable span output:  $V_{REF}$  or  $2 \times V_{REF}$   
Total unadjusted error (TUE): 0.06% of FSR maximum  
Offset error:  $\pm 1.5$  mV maximum  
Gain error:  $\pm 0.05\%$  of FSR maximum  
Low glitch: 0.1 nV-sec  
High drive capability: 20 mA  
Low power: 1.2 mW at 3.3 V  
Independent logic supply: 1.62 V logic compatible  
Wide operating temperature range:  $-40^{\circ}\text{C}$  to  $+105^{\circ}\text{C}$   
Robust 4 kV HBM ESD protection

### APPLICATIONS

Process controls  
Data acquisition systems  
Digital gain and offset adjustment  
Programmable voltage sources

### GENERAL DESCRIPTION

The [AD5683R/AD5682R/AD5681R/AD5683](#), members of the *nano*DAC+® family, are low power, single-channel, 16-/14-/12-bit buffered voltage out digital-to-analog converters (DACs). The devices, except the [AD5683](#), include an enabled by default internal 2.5 V reference, offering 2 ppm/°C drift. The output span can be programmed to be 0 V to  $V_{REF}$  or 0 V to  $2 \times V_{REF}$ . All devices operate from a single 2.7 V to 5.5 V supply and are guaranteed monotonic by design. The devices are available in a 2.00 mm × 2.00 mm, 8-lead LFCSP or a 10-lead MSOP.

The internal power-on reset circuit ensures that the DAC register is written to zero scale at power-up while the internal output buffer is configured in normal mode. The [AD5683R/AD5682R/AD5681R/AD5683](#) contain a power-down mode that reduces the current consumption of the device to 2  $\mu\text{A}$  (maximum) at 5 V and provides software selectable output loads while in power-down mode.

The [AD5683R/AD5682R/AD5681R/AD5683](#) use a versatile 3-wire serial interface that operates at clock rates of up to 50 MHz. Some devices also include asynchronous RESET pin and  $V_{LOGIC}$  pin options, allowing 1.8 V compatibility.

### FUNCTIONAL BLOCK DIAGRAM

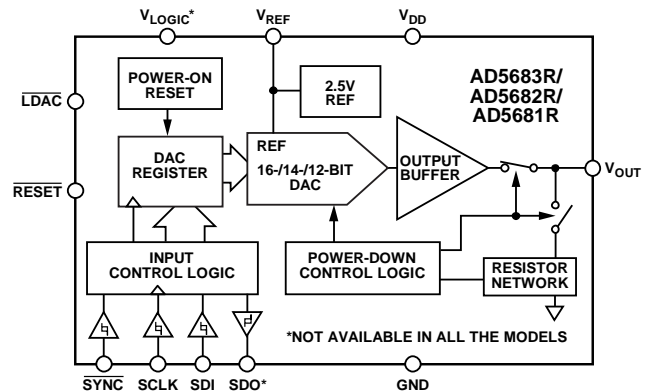


Figure 1. [AD5683R/AD5682R/AD5681R](#) MSOP  
(For more information, see the Functional Block Diagrams—LFCSP section.)

Table 1. Single-Channel *nano*DAC+ Portfolio

| Interface        | Reference | 16-Bit                  | 14-Bit                  | 12-Bit                  |
|------------------|-----------|-------------------------|-------------------------|-------------------------|
| SPI              | Internal  | <a href="#">AD5683R</a> | <a href="#">AD5682R</a> | <a href="#">AD5681R</a> |
|                  | External  | <a href="#">AD5683</a>  |                         |                         |
| I <sup>2</sup> C | Internal  | <a href="#">AD5693R</a> | <a href="#">AD5692R</a> | <a href="#">AD5691R</a> |
|                  | External  | <a href="#">AD5693</a>  |                         |                         |

### PRODUCT HIGHLIGHTS

- High Relative Accuracy (INL).  
[AD5683R/AD5683](#) (16-bit):  $\pm 2$  LSB maximum.
- Low Drift, 2.5 V On-Chip Reference.  
2 ppm/°C typical temperature coefficient.  
5 ppm/°C maximum temperature coefficient.
- Two Package Options.  
2.00 mm × 2.00 mm, 8-lead LFCSP.  
10-lead MSOP.

#### Rev. D

#### Document Feedback

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## REVISION HISTORY

### 12/2016—Rev. C to Rev. D

Changed 1.8 V to 1.62 V, 1.8 V – 10% to 1.62 V, 5 V + 10% to 5.5 V, and  $1.8\text{ V} \leq V_{\text{LOGIC}} \leq 2.7\text{ V}$  to  $1.62\text{ V} \leq V_{\text{LOGIC}} \leq 2.7\text{ V}$ .....Throughout  
 Changes to DC Power Supply Rejection Ratio, PSRR, Test Conditions/Comments Column, Table 2..... 4

### 3/2016—Rev. B to Rev. C

Changes to Features Section..... 1  
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### 10/2014—Rev. A to Rev. B

Changes to Table 1..... 1  
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 Added Recommended Regulator Section .....

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### 1/2014—Rev. 0 to Rev. A

Change to Features Section..... 1  
 Removed Endnote 2, Endnote 3, Endnote 5, and Endnote 6, Table 2; Renumbered Sequentially .....

5  
 Removed Endnote 2, Table 3; Renumbered Sequentially .....

6  
 Removed Endnote 1, Table 4; Renumbered Sequentially .....

6  
 Changes to Table 5.....

8  
 Removed Solder Heat Reflow Section and Figure 53;

Renumbered Sequentially .....

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### 12/2013—Revision 0: Initial Version

## FUNCTIONAL BLOCK DIAGRAMS—LFCSP

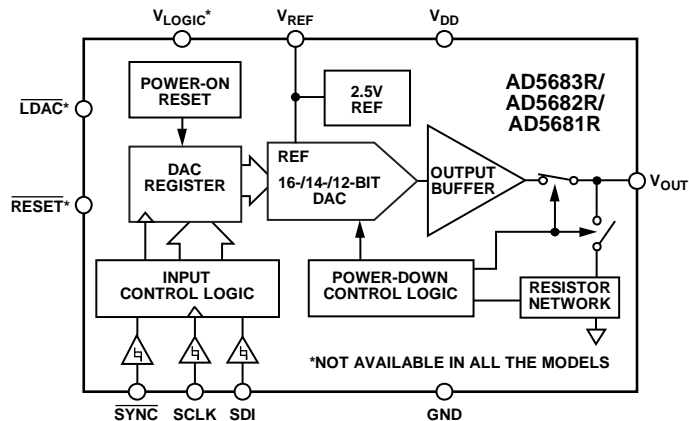


Figure 2. AD5683R/AD5682R/AD5681R LFCSP

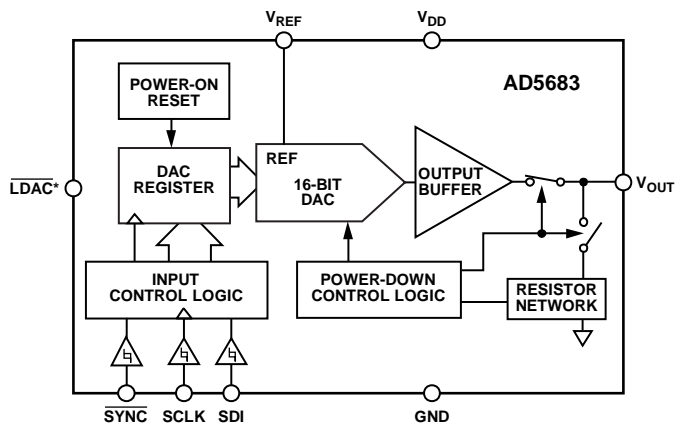


Figure 3. AD5683 LFCSP

## SPECIFICATIONS

$V_{DD} = 2.7\text{ V to }5.5\text{ V}$ ,  $R_L = 2\text{ k}\Omega\text{ to GND}$ ,  $C_L = 200\text{ pF to GND}$ ,  $V_{REF} = 2.5\text{ V}$ ,  $V_{LOGIC} = 1.62\text{ V to }5.5\text{ V}$ ,  $-40^\circ\text{C} < T_A < +105^\circ\text{C}$ , unless otherwise noted.

Table 2.

| Parameter                             | Min | Typ     | Max                | Unit                         | Test Conditions/Comments  |
|---------------------------------------|-----|---------|--------------------|------------------------------|---|
| STATIC PERFORMANCE <sup>1</sup>       |     |         |                    |                              |   |
| AD5683R                               |     |         |                    |                              |   |
| Resolution                            | 16  |         |                    | Bits                         |   |
| Relative Accuracy, INL                |     |         |                    | LSB                          |   |
| A Grade                               |     |         | $\pm 8$            | LSB                          |   |
| B Grade                               |     |         | $\pm 2$            | LSB                          | Gain = 2  |
|                                       |     |         | $\pm 3$            | LSB                          | Gain = 1  |
| Differential Nonlinearity, DNL        |     |         | $\pm 1$            | LSB                          | Guaranteed monotonic by design  |
| AD5683                                |     |         |                    |                              |   |
| Resolution                            | 16  |         |                    | Bits                         |   |
| Relative Accuracy, INL                |     |         | $\pm 2$            | LSB                          | Gain = 2  |
|                                       |     |         | $\pm 3$            | LSB                          | Gain = 1  |
| Differential Nonlinearity, DNL        |     |         | $\pm 1$            | LSB                          | Guaranteed monotonic by design  |
| AD5682R                               |     |         |                    |                              |   |
| Resolution                            | 14  |         |                    | Bits                         |   |
| Relative Accuracy, INL                |     |         | $\pm 1$            | LSB                          |   |
| Differential Nonlinearity, DNL        |     |         | $\pm 1$            | LSB                          | Guaranteed monotonic by design  |
| AD5681R                               |     |         |                    |                              |   |
| Resolution                            | 12  |         |                    | Bits                         |   |
| Relative Accuracy, INL                |     |         | $\pm 1$            | LSB                          |   |
| Differential Nonlinearity, DNL        |     |         | $\pm 1$            | LSB                          | Guaranteed monotonic by design  |
| Zero-Code Error                       |     |         | 1.25               | mV                           | All 0s loaded to DAC register   |
| Offset Error                          |     |         | $\pm 1.5$          | mV                           |   |
| Full-Scale Error                      |     |         | $\pm 0.075$        | % of FSR                     | All 1s loaded to DAC register   |
| Gain Error                            |     |         | $\pm 0.05$         | % of FSR                     |   |
| Total Unadjusted Error, TUE           |     |         | $\pm 0.16$         | % of FSR                     | Internal reference, gain = 1  |
|                                       |     |         | $\pm 0.14$         | % of FSR                     | Internal reference, gain = 2  |
|                                       |     |         | $\pm 0.075$        | % of FSR                     | External reference, gain = 1  |
|                                       |     |         | $\pm 0.06$         | % of FSR                     | External reference, gain = 2  |
| Zero-Code Error Drift                 |     | $\pm 1$ |                    | $\mu\text{V}/^\circ\text{C}$ |   |
| Offset Error Drift                    |     | $\pm 1$ |                    | $\mu\text{V}/^\circ\text{C}$ |   |
| Gain Temperature Coefficient          |     | $\pm 1$ |                    | $\text{ppm}/^\circ\text{C}$  |   |
| DC Power Supply Rejection Ratio, PSRR |     | 0.2     |                    | mV/V                         | DAC code = midscale; $V_{DD} = 5\text{ V}$                                |
| OUTPUT CHARACTERISTICS                |     |         |                    |                              |   |
| Output Voltage Range                  | 0   |         | $V_{REF}$          | V                            | Gain = 1  |
|                                       | 0   |         | $2 \times V_{REF}$ | V                            | Gain = 2  |
| Capacitive Load Stability             |     | 2       |                    | nF                           | $R_L = \infty$  |
|                                       |     | 10      |                    | nF                           | $R_L = 2\text{ k}\Omega$  |
| Resistive Load                        | 1   |         |                    | k $\Omega$                   | $C_L = 0\text{ }\mu\text{F}$  |
| Load Regulation                       |     | 10      |                    | $\mu\text{V}/\text{mA}$      | 5 V, DAC code = midscale; $-30\text{ mA} \leq I_{OUT} \leq +30\text{ mA}$ |
|                                       |     | 10      |                    | $\mu\text{V}/\text{mA}$      | 3 V, DAC code = midscale; $-20\text{ mA} \leq I_{OUT} \leq +20\text{ mA}$ |
| Short-Circuit Current                 | 20  | 30      | 50                 | mA                           |   |
| Load Impedance at Rails <sup>2</sup>  |     | 20      |                    | $\Omega$                     |   |

| Parameter  | Min                    | Typ  | Max                   | Unit   | Test Conditions/Comments  |
|--|------------------------|------|-----------------------|--------|---|
| <b>REFERENCE OUTPUT</b>                            |                        |      |                       |        |   |
| Output Voltage                                     | 2.4975                 |      | 2.5025                | V      | At ambient  |
| Voltage Reference TC <sup>3</sup>                  |                        |      |                       |        | See the Terminology section   |
| A-Grade  |                        | 5    | 20                    | ppm/°C |   |
| B-Grade  |                        | 2    | 5                     | ppm/°C |   |
| Output Impedance                                   |                        | 0.05 |                       | Ω      |   |
| Output Voltage Noise                               |                        | 16.5 |                       | μV p-p | 0.1 Hz to 10 Hz   |
| Output Voltage Noise Density                       |                        | 250  |                       | nV/√Hz | At ambient; f = 10 kHz, C <sub>L</sub> = 10 nF                          |
| Capacitive Load Stability                          |                        | 5    |                       | μF     | R <sub>L</sub> = 2 kΩ   |
| Load Regulation Sourcing                           |                        | 50   |                       | μV/mA  | At ambient; V <sub>DD</sub> ≥ 3 V                                       |
| Load Regulation Sinking                            |                        | 30   |                       | μV/mA  | At ambient  |
| Output Current Load Capability                     |                        | ±5   |                       | mA     | V <sub>DD</sub> ≥ 3 V   |
| Line Regulation                                    |                        | 80   |                       | μV/V   | At ambient  |
| Thermal Hysteresis                                 |                        | 125  |                       | ppm    | First cycle   |
|  |                        | 25   |                       | ppm    | Additional cycles   |
| <b>REFERENCE INPUT</b>                             |                        |      |                       |        |   |
| Reference Current                                  |                        | 26   |                       | μA     | V <sub>REF</sub> = V <sub>DD</sub> = V <sub>LOGIC</sub> = 5 V, gain = 1 |
|  |                        | 47   |                       | μA     | V <sub>REF</sub> = V <sub>DD</sub> = V <sub>LOGIC</sub> = 5 V, gain = 2 |
| Reference Input Range                              | 1                      |      | V <sub>DD</sub>       | V      |   |
| Reference Input Impedance                          |                        | 120  |                       | kΩ     | Gain = 1  |
|  |                        | 60   |                       | kΩ     | Gain = 2  |
| <b>LOGIC INPUTS</b>                                |                        |      |                       |        |   |
| I <sub>IN</sub> , Input Current                    |                        |      | ±1                    | μA     | Per pin   |
| V <sub>INL</sub> , Input Low Voltage <sup>4</sup>  |                        |      | 0.3 × V <sub>DD</sub> | V      |   |
| V <sub>INH</sub> , Input High Voltage <sup>4</sup> | 0.7 × V <sub>DD</sub>  |      |                       | V      |   |
| C <sub>IN</sub> , Pin Capacitance                  |                        | 2    |                       | pF     |   |
| <b>LOGIC OUTPUTS (SDO)<sup>5</sup></b>             |                        |      |                       |        |   |
| Output Low Voltage, V <sub>OL</sub>                |                        |      | 0.4                   | V      | I <sub>SINK</sub> = 200 μA  |
| Output High Voltage, V <sub>OH</sub>               | V <sub>DD</sub> – 0.4  |      |                       | V      | I <sub>SOURCE</sub> = 200 μA  |
| Pin Capacitance                                    |                        | 4    |                       | pF     |   |
| <b>POWER REQUIREMENTS</b>                          |                        |      |                       |        |   |
| V <sub>LOGIC</sub> <sup>5</sup>                    | 1.62                   |      | 5.5                   | V      |   |
| I <sub>LOGIC</sub> <sup>5</sup>                    |                        | 0.25 | 3                     | μA     | V <sub>IH</sub> = V <sub>LOGIC</sub> or V <sub>IL</sub> = GND           |
| V <sub>DD</sub>                                    | 2.7                    |      | 5.5                   | V      | Gain = 1  |
|  | V <sub>REF</sub> + 1.5 |      | 5.5                   | V      | Gain = 2  |
| I <sub>DD</sub> <sup>6</sup>                       |                        |      |                       |        | V <sub>IH</sub> = V <sub>DD</sub> , V <sub>IL</sub> = GND               |
| Normal Mode <sup>7</sup>                           |                        | 350  | 500                   | μA     | Internal reference enabled  |
|  |                        | 110  | 180                   | μA     | Internal reference disabled   |
| Power-Down Modes <sup>8</sup>                      |                        |      | 2                     | μA     |   |

<sup>1</sup> Linearity is calculated using a reduced code range: AD5683R and AD5683 (Code 512 to Code 65,535); AD5682R (Code 128 to Code 16,384); AD5681R (Code 32 to Code 4096). Output unloaded.

<sup>2</sup> When drawing a load current at either rail, the output voltage headroom, with respect to that rail, is limited by the 20 Ω typical channel resistance of the output devices; for example, when sinking 1 mA, the minimum output voltage = 20 Ω, 1 mA generates 20 mV. See Figure 38 (Headroom/Footroom vs. Load Current).

<sup>3</sup> Reference temperature coefficient is calculated as per the box method. See the Terminology section for more information.

<sup>4</sup> Substitute V<sub>LOGIC</sub> for V<sub>DD</sub> if device includes a V<sub>LOGIC</sub> pin.

<sup>5</sup> The V<sub>LOGIC</sub> and SDO pins are not available on all models.

<sup>6</sup> If the V<sub>LOGIC</sub> pin is not available, I<sub>DD</sub> = I<sub>DD</sub> + I<sub>LOGIC</sub>.

<sup>7</sup> Interface inactive. DAC active. DAC output unloaded.

<sup>8</sup> DAC powered down.

**AC CHARACTERISTICS**

$V_{DD} = 2.7\text{ V}$  to  $5.5\text{ V}$ ,  $R_L = 2\text{ k}\Omega$  to GND,  $C_L = 200\text{ pF}$  to GND,  $V_{REF} = 2.5\text{ V}$ ,  $V_{LOGIC} = 1.62\text{ V}$  to  $5.5\text{ V}$ ,  $-40^\circ\text{C} < T_A < +105^\circ\text{C}$ , unless otherwise noted.<sup>1</sup>

Table 3.

| Parameter                                     | Typ | Max | Unit                         | Test Conditions/Comments  |
|---|-----|-----|------------------------------|---|
| Output Voltage Settling Time <sup>2,3</sup>   | 5   | 7   | $\mu\text{s}$                | Gain = 1  |
| Slew Rate                                     | 0.7 |     | $\text{V}/\mu\text{s}$       |   |
| Digital-to-Analog Glitch Impulse <sup>2</sup> | 0.1 |     | $\text{nV}\cdot\text{sec}$   | $\pm 1\text{ LSB}$ change around major carry, gain = 2                    |
| Digital Feedthrough <sup>2</sup>              | 0.1 |     | $\text{nV}\cdot\text{sec}$   |   |
| Total Harmonic Distortion <sup>2</sup>        | −83 |     | dB                           | $V_{REF} = 2\text{ V} \pm 0.1\text{ V p-p}$ , frequency = 10 kHz          |
| Output Noise Spectral Density                 | 200 |     | $\text{nV}/\sqrt{\text{Hz}}$ | DAC code = midscale, 10 kHz   |
| Output Noise                                  | 6   |     | $\mu\text{V p-p}$            | 0.1 Hz to 10 Hz; internal reference, DAC = zero scale                     |
| SNR   | 90  |     | dB                           | At ambient, BW = 20 kHz, $V_{DD} = 5\text{ V}$ , $f_{OUT} = 1\text{ kHz}$ |
| SFDR  | 88  |     | dB                           | At ambient, BW = 20 kHz, $V_{DD} = 5\text{ V}$ , $f_{OUT} = 1\text{ kHz}$ |
| SINAD   | 82  |     | dB                           | At ambient, BW = 20 kHz, $V_{DD} = 5\text{ V}$ , $f_{OUT} = 1\text{ kHz}$ |

<sup>1</sup> Temperature range =  $-40^\circ\text{C}$  to  $+105^\circ\text{C}$ , typical at  $25^\circ\text{C}$ .

<sup>2</sup> See the Terminology section.

<sup>3</sup> AD5683R/AD5683 to  $\pm 2\text{ LSB}$ , AD5682R to  $\pm 1\text{ LSB}$ , AD5681R to  $\pm 0.5\text{ LSB}$ .

**TIMING CHARACTERISTICS**

$V_{DD} = 2.7\text{ V}$  to  $5.5\text{ V}$ ,  $V_{LOGIC} = 1.62\text{ V}$  to  $5.5\text{ V}$ ,  $-40^\circ\text{C} < T_A < +105^\circ\text{C}$ , unless otherwise noted.

Table 4.

| Parameter <sup>1</sup>   | Symbol                 | 1.62 V $\leq V_{LOGIC} \leq 2.7\text{ V}$ |     |     | 2.7 V $\leq V_{LOGIC} \leq 5.5\text{ V}$ |     |     | Daisy Chain and Readback |     |     | Unit          |
|--|------------------------|---|-----|-----|--|-----|-----|--------------------------|-----|-----|---------------|
|  |                        | Min                                       | Typ | Max | Min                                      | Typ | Max | Min                      | Typ | Max |               |
| SCLK Cycle Time  | $t_1$                  | 33  |     |     | 20                                       |     |     | 40                       |     |     | ns            |
| SCLK High Time   | $t_2$                  | 16  |     |     | 10                                       |     |     | 20                       |     |     | ns            |
| SCLK Low Time  | $t_3$                  | 16  |     |     | 10                                       |     |     | 20                       |     |     | ns            |
| $\overline{\text{SYNC}}$ to SCLK Falling Edge Setup Time                                   | $t_4$                  | 15  |     |     | 10                                       |     |     | 20                       |     |     | ns            |
| Data Setup Time  | $t_5$                  | 5   |     |     | 5  |     |     | 5                        |     |     | ns            |
| Data Hold Time   | $t_6$                  | 5   |     |     | 5  |     |     | 5                        |     |     | ns            |
| SCLK Falling Edge to $\overline{\text{SYNC}}$ Rising Edge                                  | $t_7$                  | 15  |     |     | 10                                       |     |     | 10                       |     |     | ns            |
| Minimum $\overline{\text{SYNC}}$ High Time   | $t_8$                  | 20  |     |     | 20                                       |     |     | 40                       |     |     | ns            |
| $\overline{\text{SYNC}}$ Falling Edge to SCLK Fall Ignore                                  | $t_9$                  | 16  |     |     | 10                                       |     |     | 10                       |     |     | ns            |
| SDO Data Valid from SCLK Rising Edge   | $t_{10}$               |   |     |     |  |     |     |                          |     | 35  | ns            |
| $\overline{\text{SYNC}}$ Rising Edge to SCLK Falling Edge                                  | $t_{11}$               |   |     |     |  |     |     | 10                       |     |     | ns            |
| $\overline{\text{SYNC}}$ Rising Edge to SDO Disabled                                       | $t_{12}$               |   |     |     |  |     |     |                          |     | 60  | ns            |
| $\overline{\text{SYNC}}$ Rising Edge to $\overline{\text{LDAC}}$ Falling Edge              | $t_{13}$               | 25  |     |     | 25                                       |     |     | 25                       |     |     | ns            |
| $\overline{\text{LDAC}}$ Pulse Width Low   | $t_{14}$               | 20  |     |     | 15                                       |     |     | 15                       |     |     | ns            |
| $\overline{\text{RESET}}$ Minimum Pulse Width Low  | $t_{15}$               | 75  |     |     | 75                                       |     |     | 75                       |     |     | ns            |
| $\overline{\text{RESET}}$ Pulse Activation Time  | $t_{16}$               | 150                                       |     |     | 150                                      |     |     | 150                      |     |     | ns            |
| $\overline{\text{SYNC}}$ Rising Edge to $\overline{\text{SYNC}}$ Rising Edge (DAC Updates) | $t_{17}$               | 1.9                                       |     |     | 1.7                                      |     |     | 1.7                      |     |     | $\mu\text{s}$ |
| $\overline{\text{LDAC}}$ Falling Edge to $\overline{\text{SYNC}}$ Rising Edge              | $t_{18}$               | 1.8                                       |     |     | 1.65                                     |     |     | 1.65                     |     |     | $\mu\text{s}$ |
| Reference Power-Up <sup>3</sup>  | $t_{REF\_POWER\_UP}^4$ |   | 600 |     |  | 600 |     |                          | 600 |     | $\mu\text{s}$ |
| Exit Shutdown <sup>3</sup>   | $t_{SHUTDOWN}^5$       |   |     | 6   |  |     | 6   |                          |     | 6   | $\mu\text{s}$ |

<sup>1</sup> All input signals are specified with  $t_R = t_F = 1\text{ ns/V}$  (10% to 90% of  $V_{DD}$ ) and timed from a voltage level of  $(V_{IL} + V_{IH})/2$ .

<sup>2</sup> Substitute  $V_{DD}$  for  $V_{LOGIC}$  on devices that do not include a  $V_{LOGIC}$  pin.

<sup>3</sup> Not shown in Figure 4.

<sup>4</sup> Same timing must be expected when powering up the device after  $V_{DD} = 2.7\text{ V}$ .

<sup>5</sup> Time required to exit power-down to normal mode of AD5683R/AD5682R/AD5681R operation;  $\overline{\text{SYNC}}$  rising edge to 90% of DAC midscale value, with output unloaded.

## Timing and Circuit Diagrams

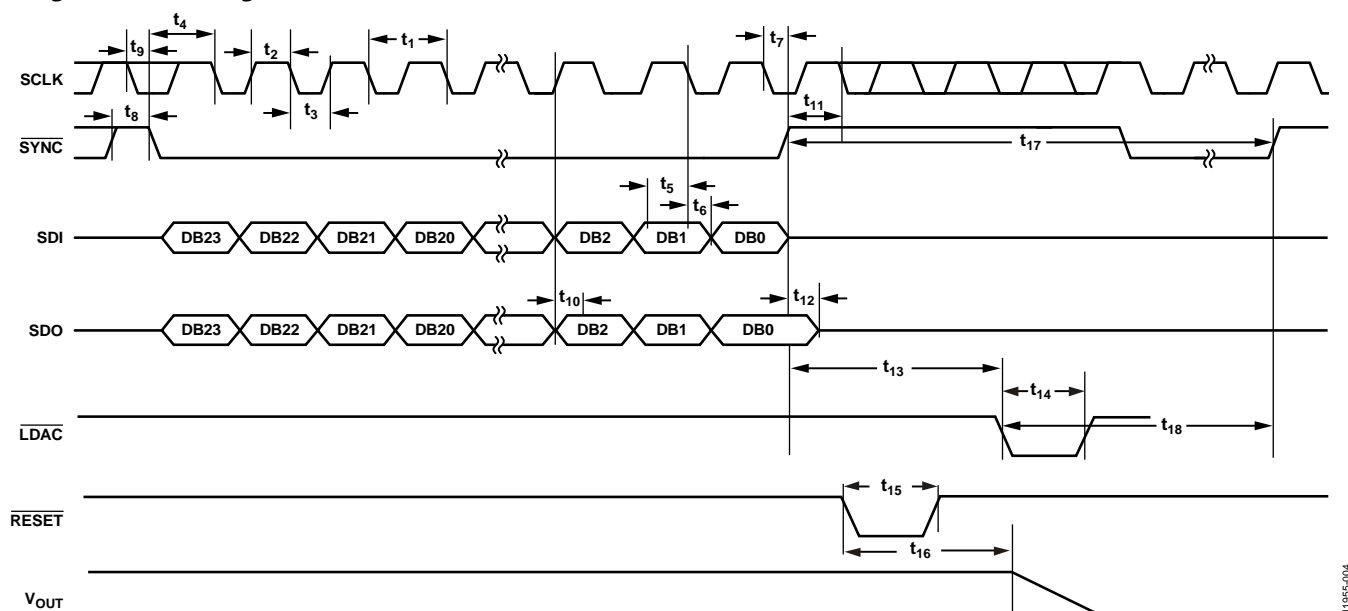
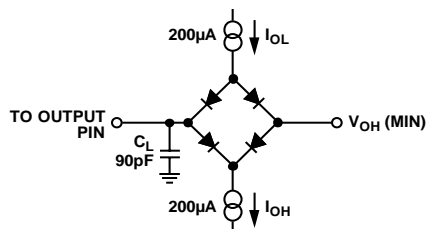
Figure 4. SPI Timing Diagram, Compatible with Mode 1 and Mode 2 (See the [AN-1248 Application Note](#))

Figure 5. Load Circuit for Digital Output (SDO) Timing Specifications

## ABSOLUTE MAXIMUM RATINGS

$T_A = 25^\circ\text{C}$ , unless otherwise noted.

Table 5.

| Parameter                                 | Rating  |
|---|---|
| $V_{DD}$ to GND                           | −0.3 V to +7 V  |
| $V_{LOGIC}$ to GND                        | −0.3 V to +7 V  |
| $V_{OUT}$ to GND                          | −0.3 V to $V_{DD} + 0.3$ V or +7 V<br>(whichever is less) |
| $V_{REF}$ to GND                          | −0.3 V to $V_{DD} + 0.3$ V or +7 V<br>(whichever is less) |
| Digital Input Voltage to GND <sup>1</sup> | −0.3 V to $V_{DD} + 0.3$ V or +7 V<br>(whichever is less) |
| Operating Temperature Range<br>Industrial | −40°C to +105°C   |
| Storage Temperature Range                 | −65°C to +150°C   |
| Junction Temperature ( $T_J$ max)         | 135°C   |
| Power Dissipation                         | $(T_J \text{ max} - T_A)/\theta_{JA}$                     |
| ESD <sup>2</sup>                          | 4 kV  |
| FICDM <sup>3</sup>                        | 1.25 kV   |

<sup>1</sup> Substitute  $V_{DD}$  with  $V_{LOGIC}$  on devices that include a  $V_{LOGIC}$  pin.

<sup>2</sup> Human body model (HBM) classification.

<sup>3</sup> Field-Induced Charged-Device Model classification.

Stresses at or above those listed under Absolute Maximum Ratings may cause permanent damage to the product. This is a stress rating only; functional operation of the product at these or any other conditions above those indicated in the operational section of this specification is not implied. Operation beyond the maximum operating conditions for extended periods may affect product reliability.

### THERMAL RESISTANCE

$\theta_{JA}$  is defined by the JEDEC JESD51 standard, and the value is dependent on the test board and test environment.

Table 6. Thermal Resistance<sup>1</sup>

| Package Type | $\theta_{JA}$ | $\theta_{JC}$ | Unit |
|--------------|---------------|---------------|------|
| 8-Lead LFCSP | 90            | 25            | °C/W |
| 10-Lead MSOP | 135           | N/A           | °C/W |

<sup>1</sup> JEDEC 2S2P test board, still air (0 m/sec airflow).

### ESD CAUTION



#### ESD (electrostatic discharge) sensitive device.

Charged devices and circuit boards can discharge without detection. Although this product features patented or proprietary protection circuitry, damage may occur on devices subjected to high energy ESD. Therefore, proper ESD precautions should be taken to avoid performance degradation or loss of functionality.



## PIN CONFIGURATIONS AND FUNCTION DESCRIPTIONS

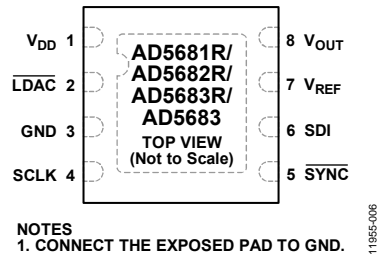
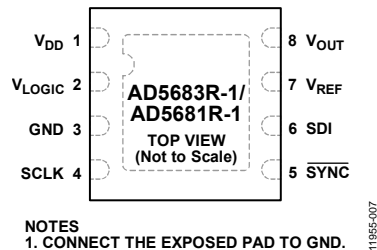
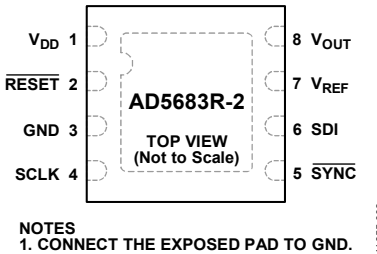
Figure 6. Pin Configuration, 8-Lead LFCSP,  $\overline{\text{LDAC}}$  OptionFigure 7. Pin Configuration, 8-Lead LFCSP,  $V_{\text{LOGIC}}$  OptionFigure 8. Pin Configuration, 8-Lead LFCSP,  $\overline{\text{RESET}}$  Option

Table 7. Pin Function Descriptions, 8-Lead LFCSP

| Pin No.                  |                    |                           | Mnemonic                  | Description  |
|--------------------------|--------------------|---------------------------|---------------------------|--|
| $\overline{\text{LDAC}}$ | $V_{\text{LOGIC}}$ | $\overline{\text{RESET}}$ |                           |  |
| 1                        | 1                  | 1                         | $V_{\text{DD}}$           | Power Supply Input. These devices can be operated from 2.7 V to 5.5 V. Decouple the supply to GND.   |
| 2                        | N/A                | N/A                       | $\overline{\text{LDAC}}$  | $\overline{\text{LDAC}}$ can be operated in asynchronous mode (see Figure 4). Pulsing this pin low allows the DAC register to be updated if the input register has new data. This pin can be tied permanently low; in this case, the DAC is automatically updated when new data is written to the input register.  |
| N/A                      | 2                  | N/A                       | $V_{\text{LOGIC}}$        | Digital Power Supply. Voltage ranges from 1.62 V to 5.5 V.   |
| N/A                      | N/A                | 2                         | $\overline{\text{RESET}}$ | Asynchronous Reset Input. The $\overline{\text{RESET}}$ input is low level sensitive. When $\overline{\text{RESET}}$ is low, all $\overline{\text{LDAC}}$ pulses are ignored, the input and DAC registers are at their default values, and the output is connected to GND. Data written to the AD5683R is ignored. If not used, this pin can be tied to $V_{\text{LOGIC}}$ . |
| 3                        | 3                  | 3                         | GND                       | Ground Reference Point for All Circuitry on the Device.  |
| 4                        | 4                  | 4                         | SCLK                      | Serial Clock Input. Data is clocked into the input shift register on the falling edge of the serial clock input. Data can be transferred at rates of up to 50 MHz.   |
| 5                        | 5                  | 5                         | $\overline{\text{SYNC}}$  | Active Low Control Input. This is the frame synchronization signal for the input data. When $\overline{\text{SYNC}}$ goes low, it powers on the SCLK and SDI buffers and enables the input shift register. Data is transferred in on the falling edges of the next 24 clocks.  |
| 6                        | 6                  | 6                         | SDI                       | Serial Data Input. This device has a 24-bit shift register. Data is clocked into the register on the falling edge of the serial clock input.   |
| 7                        | 7                  | 7                         | $V_{\text{REF}}$          | AD5683R/AD5682R/AD5681R Reference Output. When using the internal reference, this is the reference output pin. The default for this pin is as a reference output. It is recommended that this pin be decoupled to GND with a 10 nF capacitor.  |
| 8                        | 8                  | 8                         | $V_{\text{OUT}}$          | Analog Output Voltage from the DAC. The output amplifier has rail-to-rail operation.   |
| 0                        | 0                  | 0                         | EPAD                      | Exposed Pad. Connect the exposed pad to GND.   |

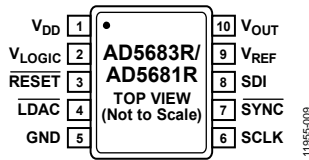
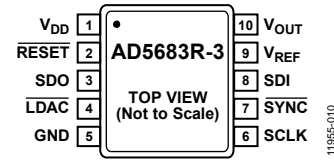
Figure 9. Pin Configuration, 10-Lead MSOP,  $V_{\text{LOGIC}}$  Option

Figure 10. Pin Configuration, 10-Lead MSOP, SDO Option

Table 8. Pin Function Descriptions, 10-Lead MSOP

| $V_{\text{LOGIC}}$ | SDO | Mnemonic                  | Description   |
|--------------------|-----|---------------------------|---|
| 1                  | 1   | $V_{\text{DD}}$           | Power Supply Input. These devices can be operated from 2.7 V to 5.5 V. Decouple this pin to GND.  |
| 2                  | N/A | $V_{\text{LOGIC}}$        | Digital Power Supply. Voltage ranges from 1.62 V to 5.5 V. Decouple this pin to GND.  |
| 3                  | 2   | $\overline{\text{RESET}}$ | Hardware Reset Pin. The $\overline{\text{RESET}}$ input is low level sensitive. When $\overline{\text{RESET}}$ is low, the device is reset and external pins are ignored. The input and DAC registers are loaded with a zero-scale value, and the write control register is loaded with default values. If not used, tie this pin to $V_{\text{LOGIC}}$ . |
| N/A                | 3   | $\overline{\text{SDO}}$   | Serial Data Output. Can be used for daisy chaining or readback commands.  |
| 4                  | 4   | $\overline{\text{LDAC}}$  | Load DAC. Transfers the content of the input register to the DAC register. It can be operated in asynchronous mode (see Figure 4). This pin can be tied permanently low; in this case, the DAC register is automatically updated when new data is written to the input register.  |
| 5                  | 5   | GND                       | Ground Reference.   |
| 6                  | 6   | SCLK                      | Serial Clock Input. Data is clocked into the input shift register on the falling edge of the serial clock input. Data can be transferred at rates of up to 50 MHz.  |
| 7                  | 7   | $\overline{\text{SYNC}}$  | Synchronization Data Input. When $\overline{\text{SYNC}}$ goes low, it enables the SCLK and SDI buffers and the input shift register.   |
| 8                  | 8   | SDI                       | Serial Data Input. Data is sampled on the falling edge of SCLK.   |
| 9                  | 9   | $V_{\text{REF}}$          | Reference Input/Output. When using the internal reference, this is the reference output pin. The default for this pin is as a reference output. It is recommended that this pin be decoupled to GND with a 10 nF capacitor.   |
| 10                 | 10  | $V_{\text{OUT}}$          | Analog Output Voltage from the DAC. The output amplifier has rail-to-rail operation.  |

## TYPICAL PERFORMANCE CHARACTERISTICS

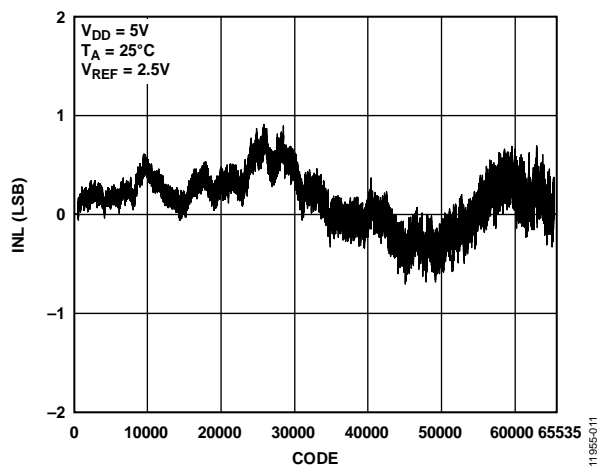


Figure 11. AD5683R/AD5683 INL

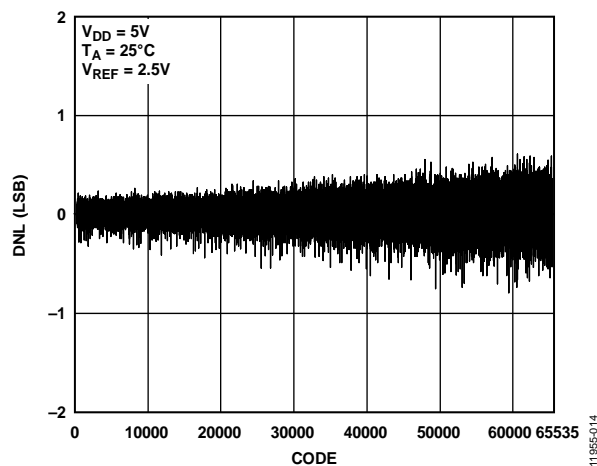


Figure 14. AD5683R/AD5683 DNL

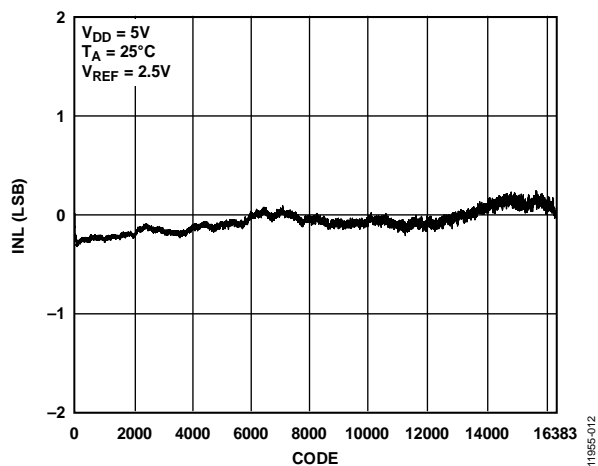


Figure 12. AD5682R INL

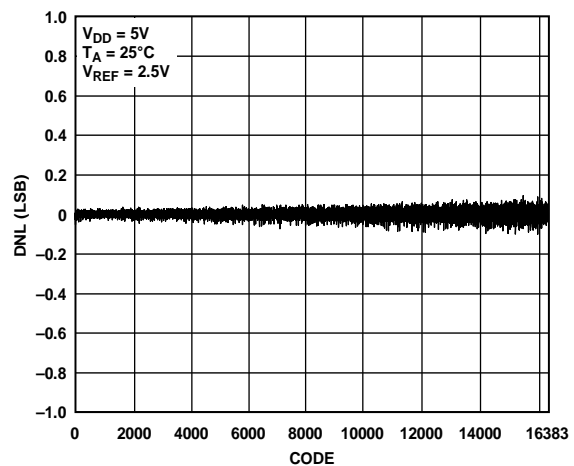


Figure 15. AD5682R DNL

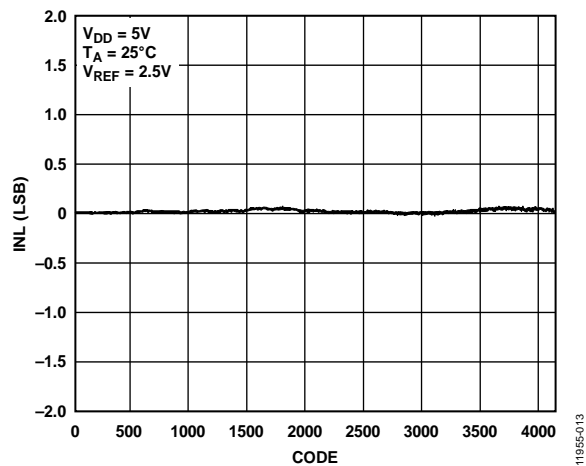


Figure 13. AD5681R INL

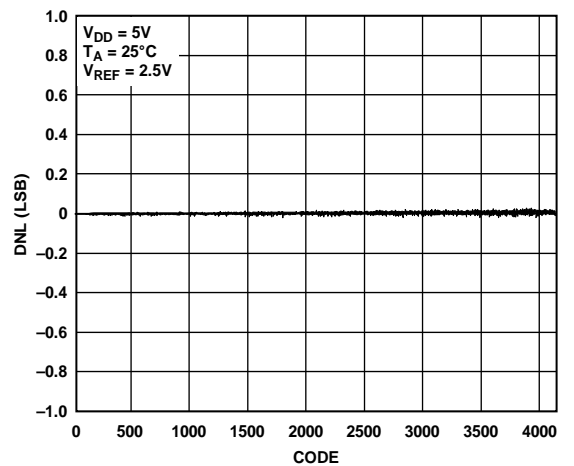


Figure 16. AD5681R DNL

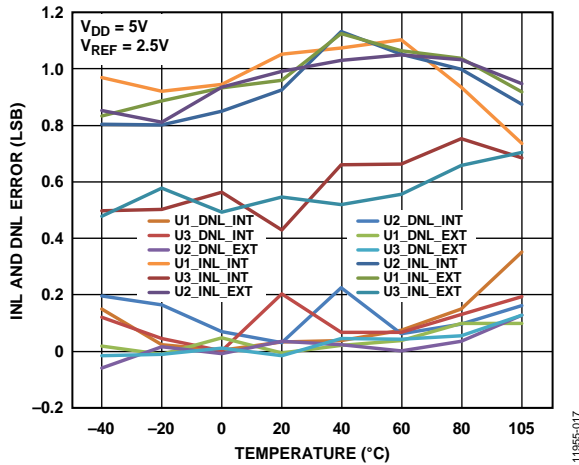


Figure 17. INL and DNL Error vs. Temperature (AD5683R/AD5683)

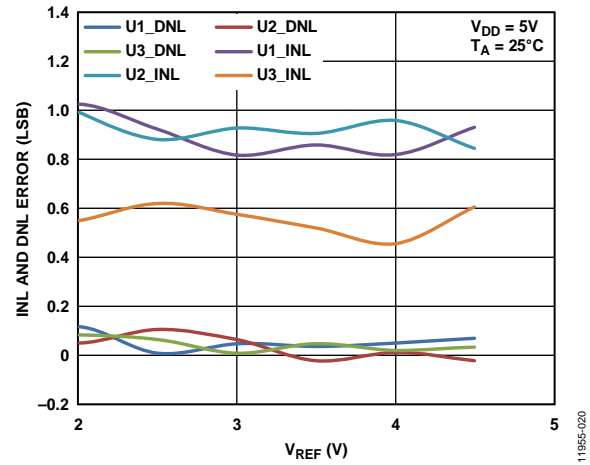


Figure 20. INL Error and DNL Error vs.  $V_{REF}$  (AD5683R/AD5683)

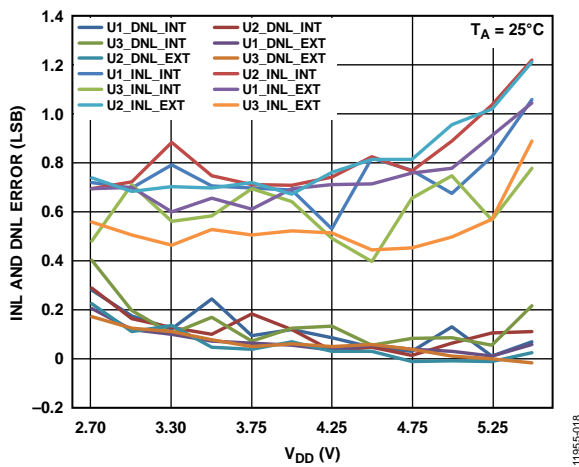


Figure 18. INL and DNL Error vs. Supply Voltage

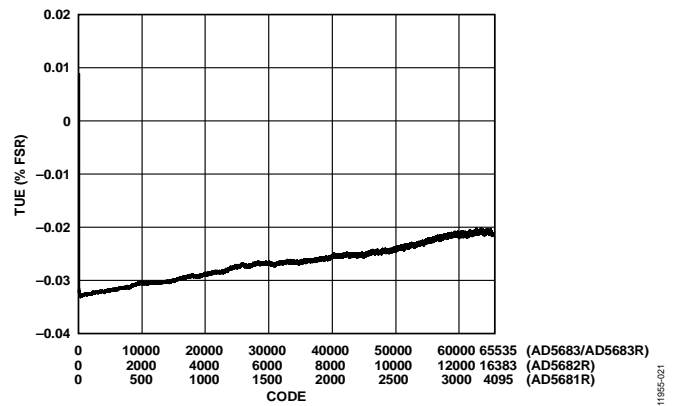


Figure 21. TUE vs. Code

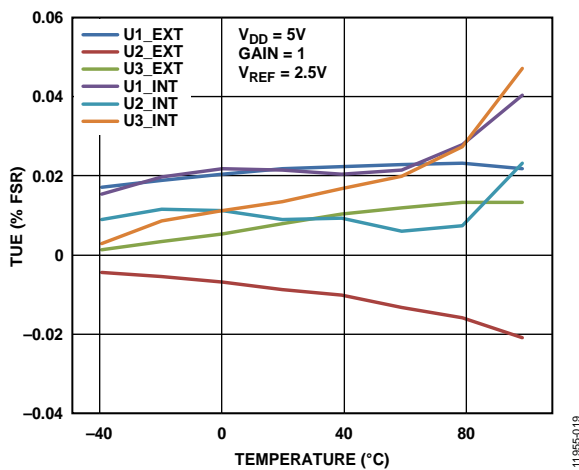


Figure 19. TUE vs. Temperature

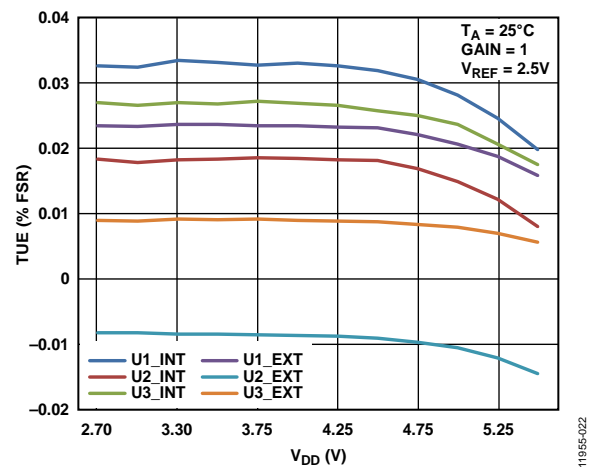


Figure 22. TUE vs. Supply

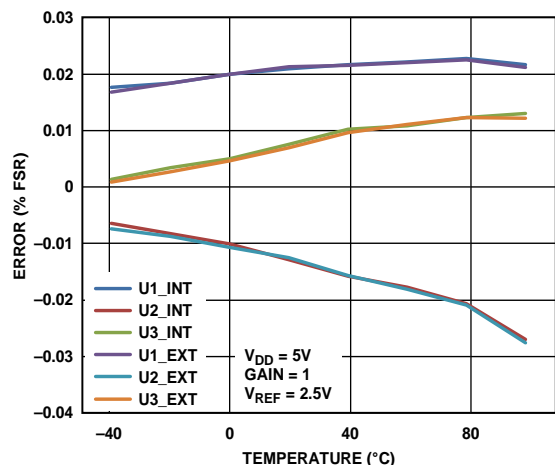


Figure 23. Gain Error and Full-Scale Error vs. Temperature

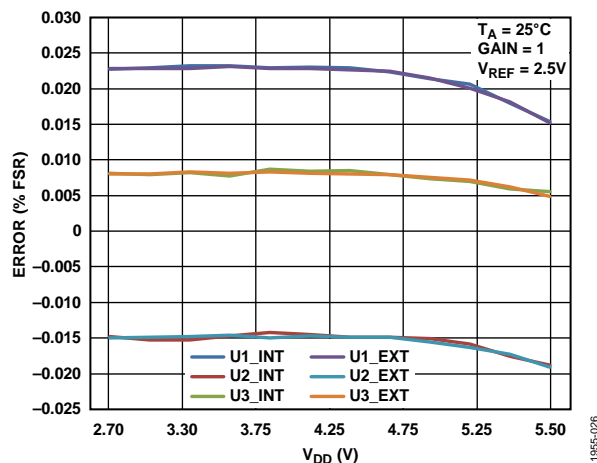


Figure 26. Gain Error and Full-Scale Error vs. Supply

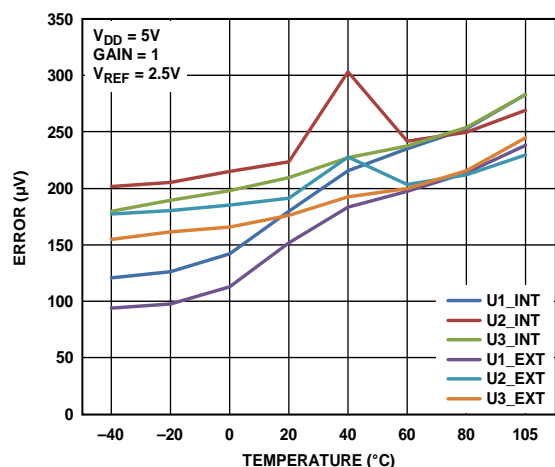


Figure 24. Zero Code Error and Offset Error vs. Temperature

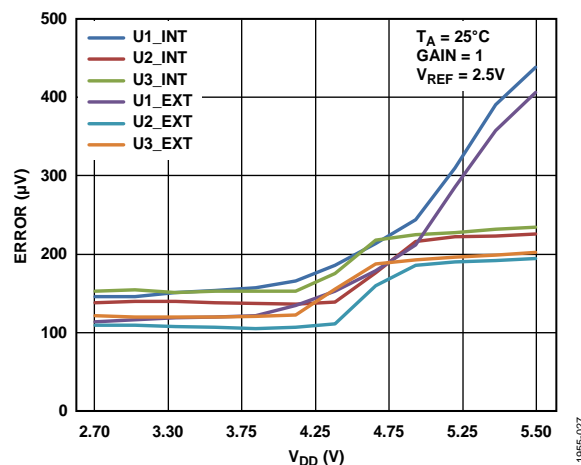


Figure 27. Zero Code Error and Offset Error vs. Supply

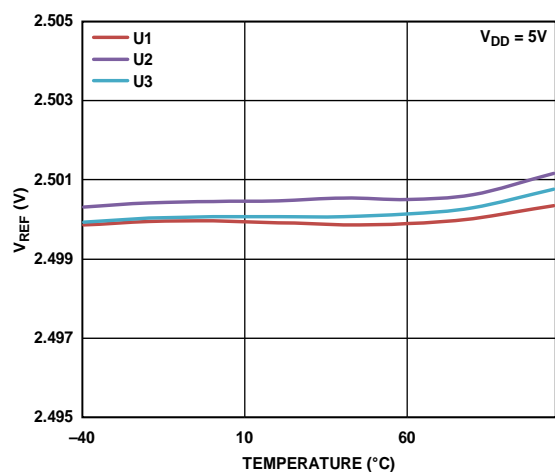


Figure 25. Internal Reference Voltage vs. Temperature (Grade B)

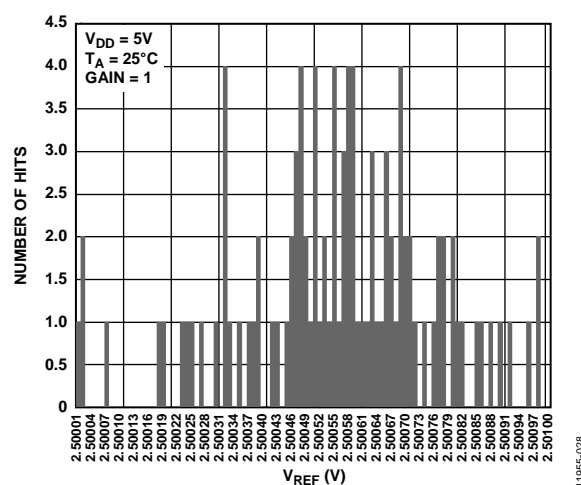


Figure 28. Reference Output Spread

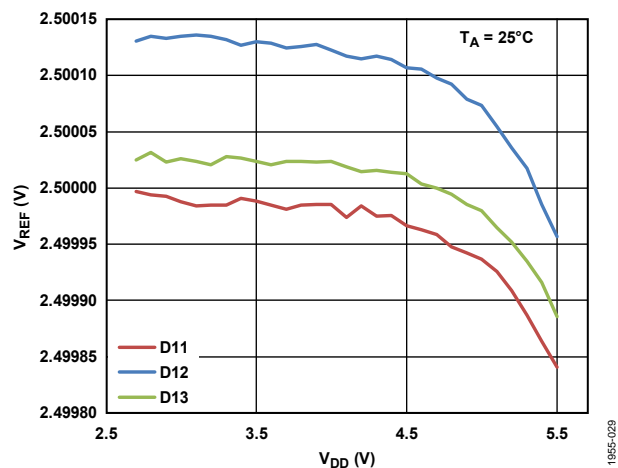


Figure 29. Internal Reference Voltage vs. Supply Voltage

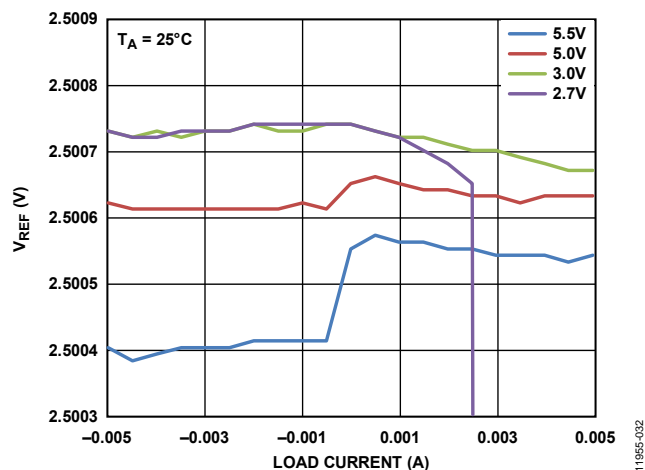


Figure 32. Internal Reference Voltage vs. Load Current

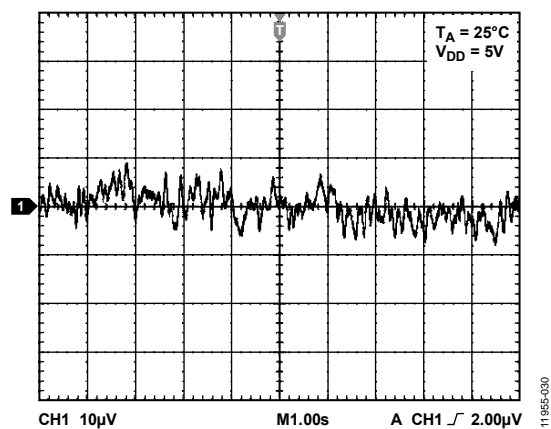


Figure 30. Internal Reference Noise, 0.1 Hz to 10 Hz

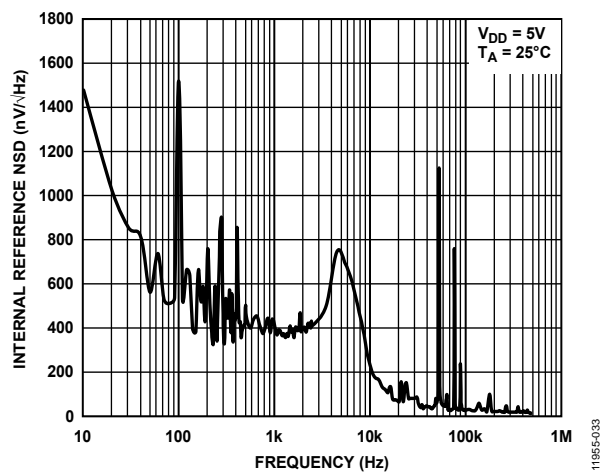


Figure 33. Internal Reference Noise Spectral Density vs. Frequency

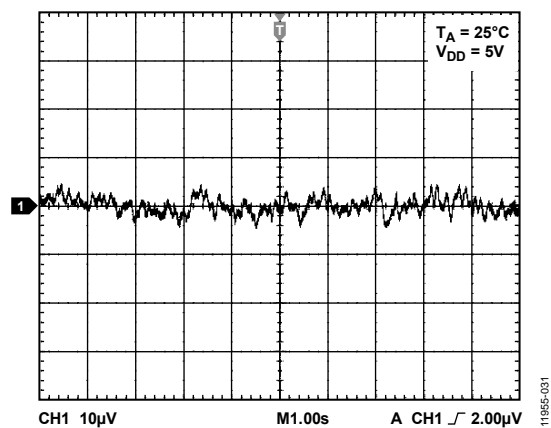


Figure 31. 0.1 Hz to 10 Hz Output Noise Plot, Internal Reference On

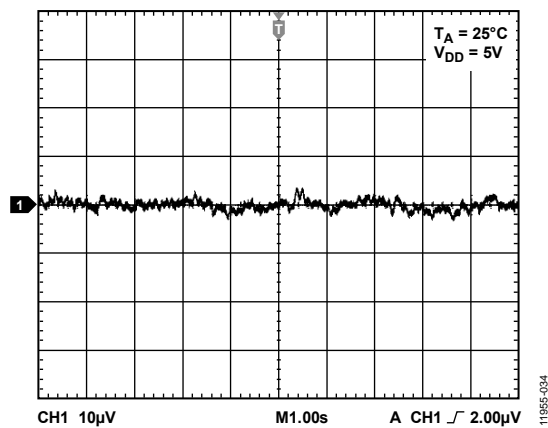


Figure 34. 0.1 Hz to 10 Hz Output Noise Plot, External Reference

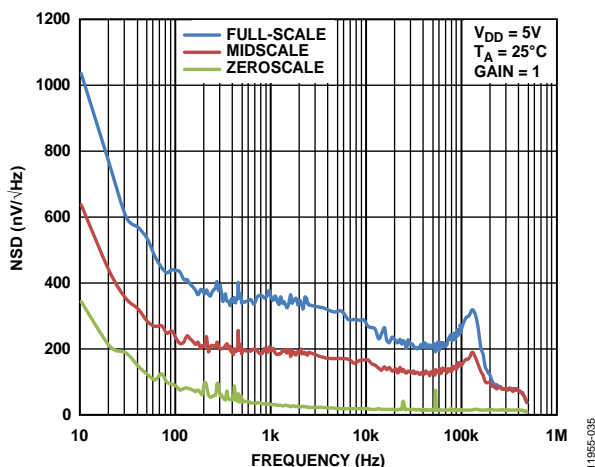


Figure 35. Noise Spectral Density vs. Frequency, Gain = 1

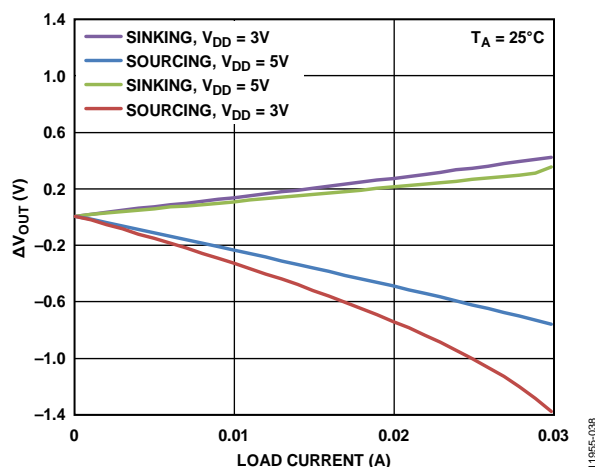


Figure 38. Headroom/Footroom vs. Load Current

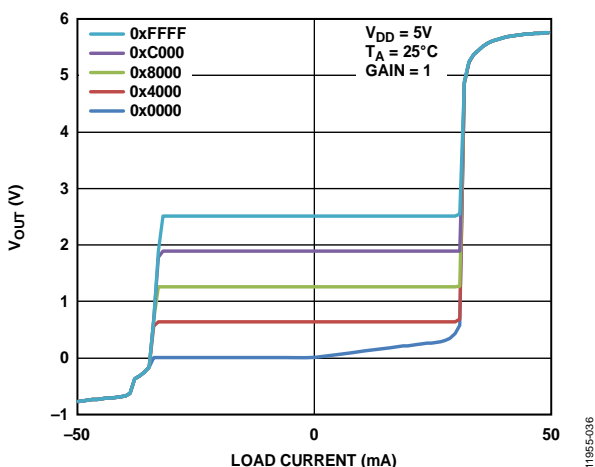


Figure 36. Source and Sink Capability, Gain = 1

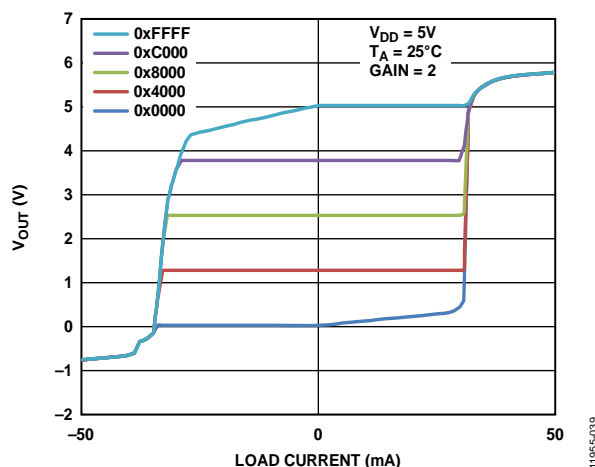


Figure 39. Source and Sink Capability, Gain = 2

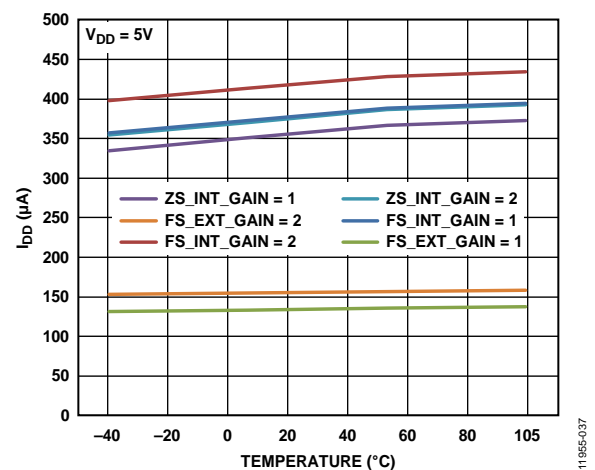


Figure 37. Supply Current vs. Temperature

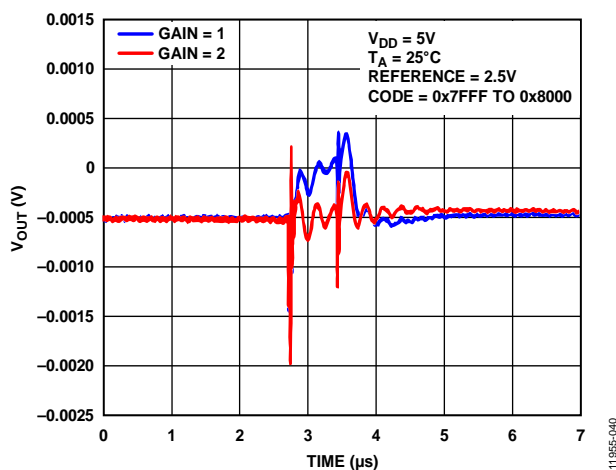


Figure 40. Digital-to-Analog Glitch Impulse

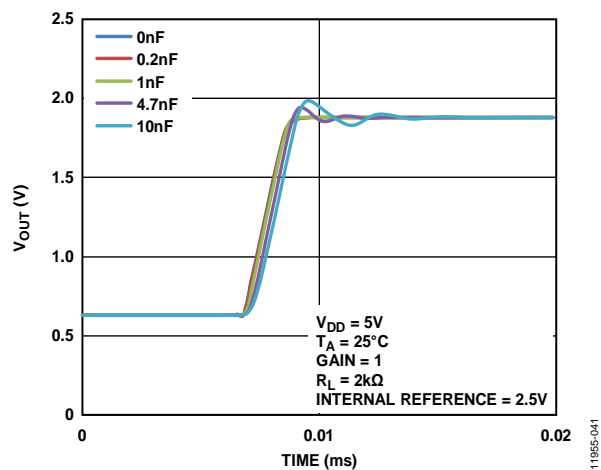


Figure 41. Capacitive Load vs. Settling Time, Gain = 1

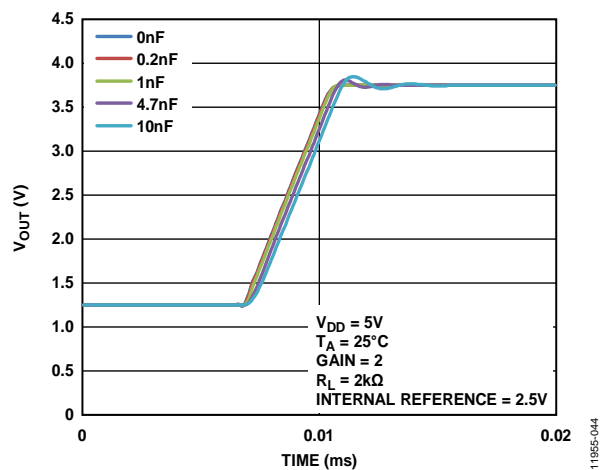


Figure 44. Capacitive Load vs. Settling Time, Gain = 2

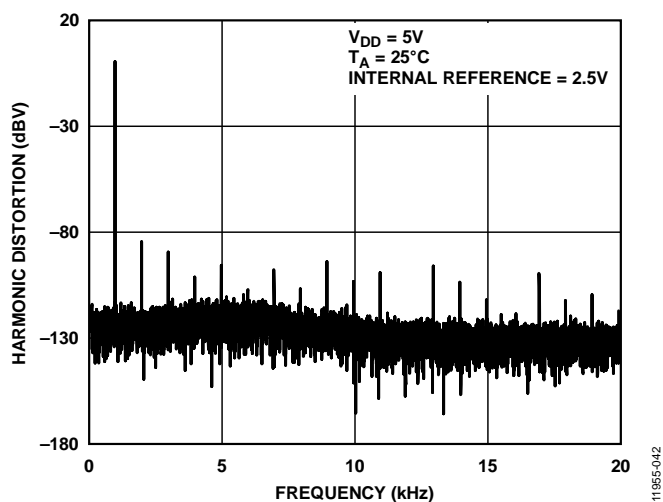


Figure 42. Total Harmonic Distortion at 1 kHz

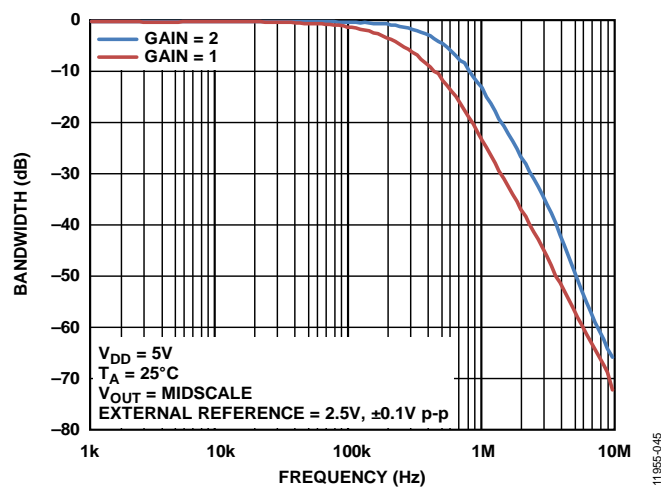


Figure 45. Multiplying Bandwidth, External Reference 2.5 V ± 0.1 V p-p, 10 kHz to 10 MHz

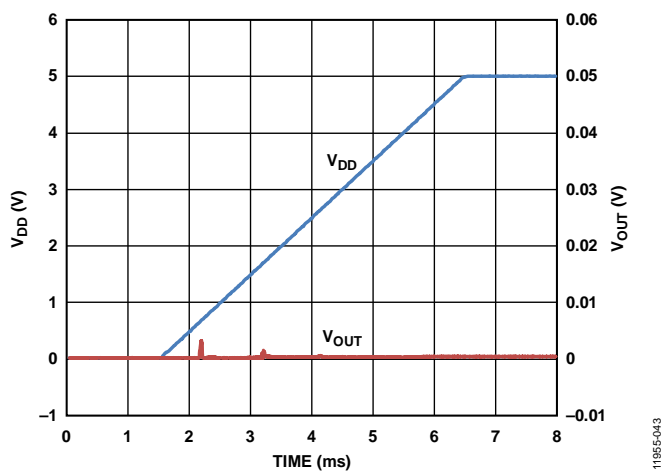


Figure 43. Power-On Reset to 0 V

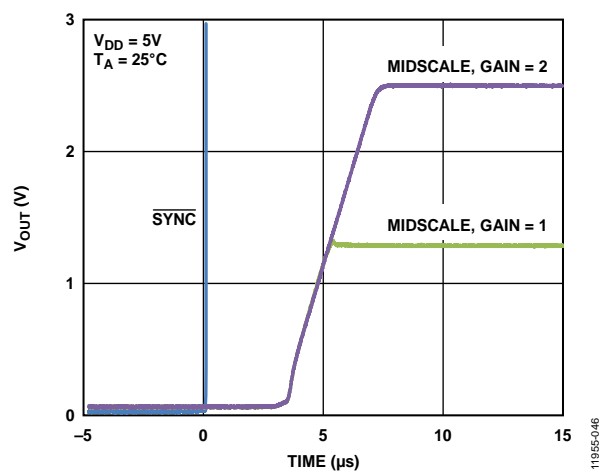


Figure 46. Exiting Power-Down to Midscale



## TERMINOLOGY

### Relative Accuracy or Integral Nonlinearity (INL)

For the DAC, relative accuracy or integral nonlinearity is a measurement of the maximum deviation, in LSBs, from a straight line passing through the endpoints of the DAC transfer function. See Figure 11, Figure 12, and Figure 13 for typical INL vs. code plots.

### Differential Nonlinearity (DNL)

Differential nonlinearity is the difference between the measured change and the ideal 1 LSB change between any two adjacent codes. A specified differential nonlinearity of  $\pm 1$  LSB maximum ensures monotonicity. This DAC is guaranteed monotonic by design. See Figure 14, Figure 15, and Figure 16 for typical DNL vs. code plots.

### Zero Code Error

Zero code error is a measurement of the output error when zero code (0x0000) is loaded to the DAC register. Ideally, the output must be 0 V. The zero code error is always positive in the [AD5683R/AD5682R/AD5681R](#) because the output of the DAC cannot fall below 0 V due to a combination of the offset errors in the DAC and the output amplifier. Zero code error is expressed in mV. A plot of zero code error vs. temperature is shown in Figure 24.

### Full-Scale Error

Full-scale error is a measurement of the output error when full-scale code (0xFFFF) is loaded to the DAC register. Ideally, the output must be  $V_{REF} - 1$  LSB or  $|2 \times V_{REF}| - 1$  LSB. Full-scale error is expressed in percent of full-scale range (% of FSR). See Figure 23 and Figure 26 for plots of full-scale error.

### Gain Error

Gain error is a measure of the span error of the DAC. It is the deviation in slope of the DAC transfer characteristic from the ideal expressed as % of FSR.

### Zero-Code Error Drift

Zero-code error drift is a measurement of the change in zero-code error with a change in temperature. It is expressed in  $\mu\text{V}/^\circ\text{C}$ .

### Gain Temperature Coefficient

Gain temperature coefficient is a measurement of the change in gain error with changes in temperature. It is expressed in ppm of FSR/ $^\circ\text{C}$ .

### Offset Error

Offset error is a measure of the difference between  $V_{OUT}$  (actual) and  $V_{OUT}$  (ideal) expressed in mV in the linear region of the transfer function. Offset error is measured on the [AD5683R](#) with Code 512 loaded in the DAC register. It can be negative or positive.

### DC Power Supply Rejection Ratio (PSRR)

PSRR indicates how the output of the DAC is affected by changes in the supply voltage. PSRR is the ratio of the change in  $V_{OUT}$  to a change in  $V_{DD}$  for mid-scale output of the DAC. It is measured in dB.  $V_{REF}$  is held at 2 V, and  $V_{DD}$  is varied by  $\pm 10\%$ .

### Output Voltage Settling Time

Output voltage settling time is the amount of time it takes for the output of a DAC to settle to a specified level for a  $\frac{1}{4}$  to  $\frac{3}{4}$  scale input change.

### Digital-to-Analog Glitch Impulse

Digital-to-analog glitch impulse is the impulse injected into the analog output when the input code in the DAC register changes state. It is normally specified as the area of the glitch in nV-sec and is measured when the digital input code is changed by 1 LSB at the major carry transition (0x7FFF to 0x8000), as shown in Figure 40.

### Digital Feedthrough

Digital feedthrough is a measure of the impulse injected into the analog output of the DAC from the digital inputs of the DAC, but it is measured when the DAC output is not updated. Digital feedthrough is specified in nV-sec and measured with a full-scale code change on the data bus, that is, from all 0s to all 1s and vice versa.

### Reference Feedthrough

Reference feedthrough is the ratio of the amplitude of the signal at the DAC output to the reference input when the DAC output is not being updated. It is expressed in dB.

### Output Noise Spectral Density

Noise spectral density is a measurement of the internally generated random noise. Random noise is characterized as a spectral density ( $\text{nV}/\sqrt{\text{Hz}}$ ). It is measured by loading the DAC to midscale and measuring noise at the output. It is measured in  $\text{nV}/\sqrt{\text{Hz}}$ . See Figure 31, Figure 34, and Figure 35 for a plot of noise spectral density. The noise spectral density for the internal reference is shown in Figure 30 and Figure 33.

### Multiplying Bandwidth

The amplifiers within the DAC have a finite bandwidth. The multiplying bandwidth is a measure of this finite bandwidth. A sine wave on the reference (with full-scale code loaded to the DAC) appears on the output. The multiplying bandwidth is the frequency at which the output amplitude falls to 3 dB below the input.

### Total Harmonic Distortion (THD)

THD is the difference between an ideal sine wave and the attenuated version using the DAC. The sine wave is used as the reference for the DAC, and the THD is a measurement of the harmonics present on the DAC output. It is measured in dB.

**Voltage Reference Temperature Coefficient (TC)**

Voltage reference TC is a measure of the change in the reference output voltage with a change in temperature. The reference TC is calculated using the box method, which defines the TC as the maximum change in the reference output over a given temperature range expressed in ppm/°C, as follows:

$$TC = \left[ \frac{V_{REFmax} - V_{REFmin}}{V_{REFnom} \times TempRange} \right] \times 10^6$$

where:

$V_{REFmax}$  is the maximum reference output measured over the total temperature range.

$V_{REFmin}$  is the minimum reference output measured over the total temperature range.

$V_{REFnom}$  is the nominal reference output voltage, 2.5 V.

$TempRange$  is the specified temperature range, -40°C to +105°C.

**Thermal Hysteresis**

Thermal hysteresis is the voltage difference induced on the reference voltage by sweeping the temperature from ambient to cold, to hot, and then back to ambient.

## THEORY OF OPERATION

### DIGITAL-TO-ANALOG CONVERTER

The AD5683R/AD5682R/AD5681R are single 16-bit, 14-bit, and 12-bit, serial input, voltage output DACs with a 2.5 V internal reference. The devices operate from supply voltages of 2.7 V to 5.5 V. Data is written to the AD5683R/AD5682R/AD5681R in a 24-bit word format via a 3-wire serial interface. The AD5683R/AD5682R/AD5681R incorporate a power-on reset circuit that ensures that the DAC output powers up to a zero scale. The devices also have a software power-down mode that reduces the typical current consumption to 2  $\mu$ A maximum.

### TRANSFER FUNCTION

The internal reference is on by default. For users that need an external reference, the AD5683 is available. The input coding to the DAC is straight binary. The ideal output voltage is given by the following equations:

For the AD5683R,

$$V_{OUT}(D) = Gain \times V_{REF} \times \left[ \frac{D}{65,536} \right]$$

For the AD5682R,

$$V_{OUT}(D) = Gain \times V_{REF} \times \left[ \frac{D}{16,384} \right]$$

For the AD5681R,

$$V_{OUT}(D) = Gain \times V_{REF} \times \left[ \frac{D}{4096} \right]$$

where:

$D$  is the decimal equivalent of the binary code that is loaded to the DAC register.

$Gain$  is the gain of the output amplifier. By default, it is set to  $\times 1$ . The gain can also be set to  $\times 2$  using the gain bit in the write control register.

### DAC ARCHITECTURE

The AD5683R/AD5682R/AD5681R/AD5683 implements segmented string DAC architecture with an internal output buffer. Figure 47 shows the internal block diagram.

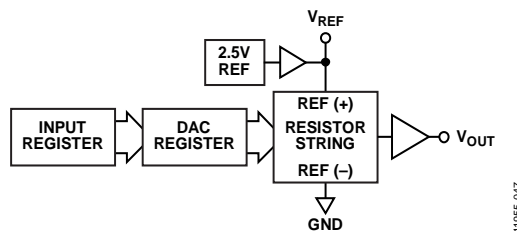


Figure 47. DAC Channel Architecture Block Diagram

The simplified segmented resistor string DAC structure is shown in Figure 48. The code loaded to the DAC register determines the switch on the string that is connected to the output buffer.

Because each resistance in the string has same value,  $R$ , the string DAC is guaranteed monotonic.

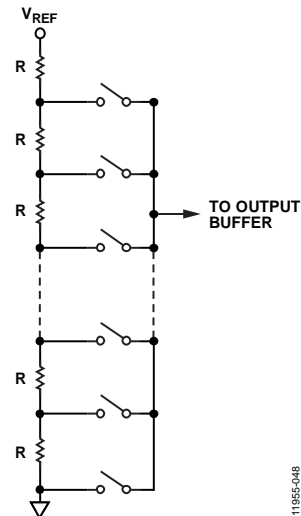


Figure 48. Simplified Resistor String Structure

### Internal Reference

The AD5683R/AD5682R/AD5681R on-chip reference is on at power-up but can be disabled via a write to the write control register.

The AD5683R/AD5682R/AD5681R each have a 2.5 V, 2 ppm/°C reference, giving a full-scale output of 2.5 V or 5 V, depending on the state of the gain bit.

The internal reference is available at the  $V_{REF}$  pin. It is internally buffered and capable of driving external loads of up to 50 mA.

### External Reference

The  $V_{REF}$  pin is an input pin in the AD5683. It can also be configured as an input pin on the AD5683R/AD5682R/AD5681R, allowing the use of an external reference if the application requires it.

In the AD5683R/AD5682R/AD5681R, the default condition of the on-chip reference is on at power-up. Before connecting an external reference to the pin, disable the internal reference by writing to the REF bit (Bit DB16) in the write control register.

**Output Buffer**

The output buffer is designed as an input/output rail-to-rail, which gives a maximum output voltage range of up to  $V_{DD}$ . The gain bit sets the segmented string DAC gain to  $\times 1$  or  $\times 2$ , as shown in Table 12.

The output buffer voltage is determined by  $V_{REF}$ , the gain bit, and the offset and gain errors.

The output buffer can drive a 10 nF capacitance with a 2 k $\Omega$  resistor in parallel, as shown in Figure 41 and Figure 44. If a higher capacitance load is required, use the snubber method or a shunt resistor to isolate the load from the output amplifier. The slew rate is 0.7 V/ $\mu$ s with a  $\frac{1}{4}$  to  $\frac{3}{4}$  scale settling time of 5  $\mu$ s.

## SERIAL INTERFACE

The [AD5683R/AD5682R/AD5681R/AD5683](#) uses a 3-wire serial interface that is compatible with some SPI modes, Mode 1 and Mode 2, as well as with completely synchronous interfaces such as SPORT. See Figure 4 for a timing diagram of a typical write sequence. See the [AN-1248 Application Note](#) for more information about the SPI interface.

### SPI SERIAL DATA INTERFACE

Pulling low  $\overline{\text{SYNC}}$  pin, the internal input shift register is enabled, the data in the SDI pin is sampled into the input shift register on the falling edge of SCLK. The  $\overline{\text{SYNC}}$  pin must be held low until the complete data-word (24-bits) is loaded from the SDI pin (see Figure 4). When  $\overline{\text{SYNC}}$  returns high, the serial data-word is decoded, following the instructions in Table 9.

Between consecutive data-words,  $\overline{\text{SYNC}}$  must be held high for a minimum of 20 ns. Between consecutive DAC updates,  $\overline{\text{SYNC}}$  must be held high for more than 20 ns to satisfy the DAC update condition as shown in Figure 4.

If  $\overline{\text{SYNC}}$  is brought high after 24 falling clock edges, it is interpreted as a valid write, and the first 24 bits are loaded to the input shift register.

To minimize power consumption, it is recommended that all serial interface pins be operated close to the supply rails.

### SHORT WRITE OPERATION (AD5681R ONLY)

The [AD5681R](#) SPI serial interface allows data to be transferred using a smaller number of clocks, if required. The last eight bits are don't care bits if the input or DAC registers are written as shown in Table 9. To increase the DAC update rate, the size of the data-word can be reduced.

If  $\overline{\text{SYNC}}$  is brought high between 16 and 24 clock edges, this is interpreted as a valid write and only the first 16 bits are decoded, as shown in Figure 49. If  $\overline{\text{SYNC}}$  is brought high before 16 falling clock edges, the serial write is ignored and the write sequence is considered invalid. If the DCEN bit is enabled, this functionality is not available (see Table 11).

### SDO Pin

The serial data output pin (SDO), which is available only in the [AD5683R](#), serves two purposes: to read back the contents of the DAC registers and to connect the device in daisy-chain mode.

The SDO pin contains a push-pull output that internally includes a weak pull-down resistor. The data is clocked out of SDO on the rising edge of SCLK, as shown in Figure 4, and the pin is active only when the DCEN bit is enabled in the write control register or automatically enabled during a readback command. In standby mode, the internal pull-down resistor forces a Logic 0 on the bus. Due to the high value of the internal pull-down resistor, other devices can have control over the SDO line if a parallel connection is made.

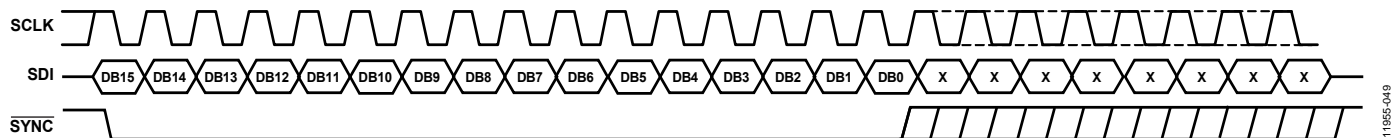


Figure 49. Short Write on the [AD5681R](#)

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Daisy-Chain Connection

Daisy chaining minimizes the number of pins required from the controlling IC. As shown in Figure 50, the SDO pin of one package must be tied to the SDI pin of the next package. The clock period may need to be increased, as shown in Table 4, because of the propagation delay of the line between subsequent devices.

By default, the SDO pin is disabled. To enable daisy-chain operation, the DCEN bit must be set in the write control register (see Table 10).

When the daisy-chain mode is enabled (DCEN = 1), the AD5683R/AD5682R/AD5681R/AD5683 accept as a valid frame any data-word larger than 24 bits, decoding the last 24 bits received, as shown in Figure 51.

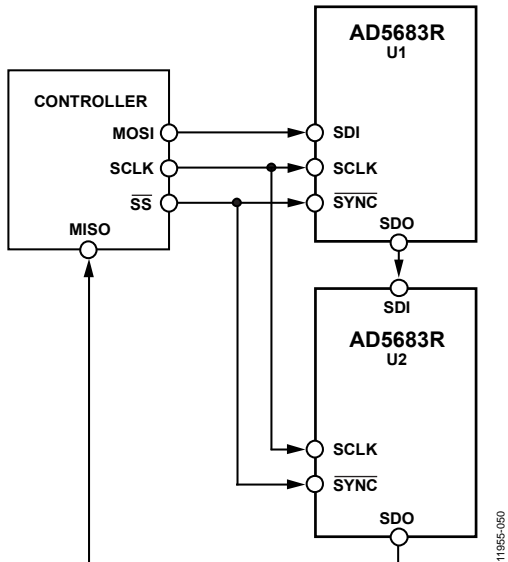


Figure 50. Daisy-Chain Connection

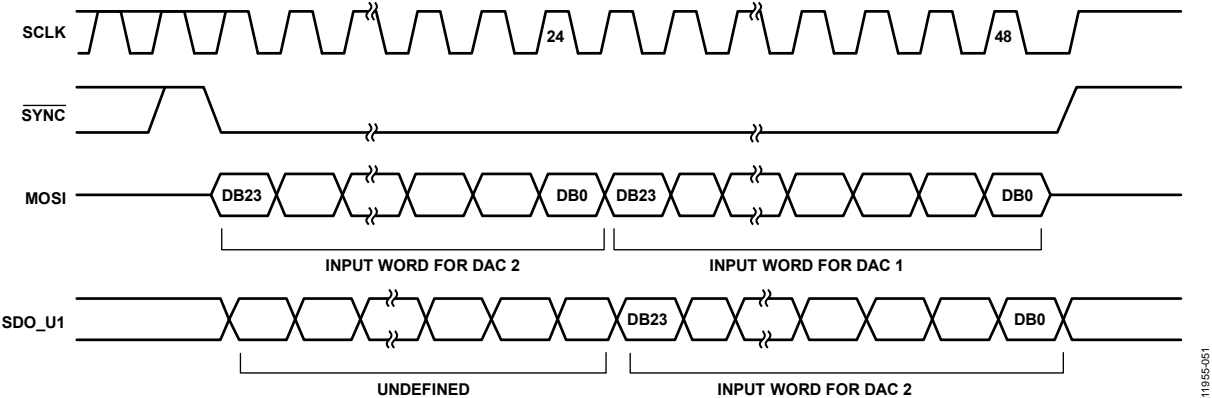


Figure 51. Daisy-Chain Timing Diagram

## INTERNAL REGISTERS

### Input Shift Register

The shift register of the [AD5683R/AD5682R/AD5681R/AD5683](#) is 24 bits wide. Serial data is loaded MSB first (DB23) and the first four bits are the command bits, C3 to C0, followed by the data bits.

The data bits comprise a 20-bit, 18-bit, or 16-bit input code, followed by a number of don't care bits as shown in Table 9. The command is decoded on the rising edge of SYNC.

### Input Register

The input register acts as a buffer to preload new data. This register does not control the voltage in the  $V_{OUT}$  pin. There are two different ways to transfer the contents of the input register to the DAC register: by software or by hardware.

### DAC Register

The DAC register controls the voltage in the  $V_{OUT}$  pin. This register can be updated by issuing a command or by transferring the contents of the input register to the DAC register.

## COMMANDS

### Write Input Register

The input register allows the preloading of a new value for the DAC register. The transfer from the input register to the DAC register can be triggered by hardware, by the  $\overline{LDAC}$  pin, or by software using Command 2.

If new data is loaded into the DAC register directly using Command 3, the DAC register automatically overwrites the input register.

### Update DAC Register

This command transfers the contents of the input register to the DAC register and, consequently, the  $V_{OUT}$  pin is updated.

This operation is equivalent to a software  $\overline{LDAC}$ .

### Write DAC Register

The DAC register controls the output voltage in the DAC. This command updates the DAC register on completion of the write operation. The input register is refreshed automatically with the DAC register value.

Table 9. Command Operation

| Command [DB23:DB20] |    |    |    | Data Bits [DB19:DB0] <sup>1</sup> |      |      |      |      |      |            |                  |                  |                    |                    |           | Operation                           |
|---------------------|----|----|----|-----------------------------------|------|------|------|------|------|------------|------------------|------------------|--------------------|--------------------|-----------|-------------------------------------|
| C3                  | C2 | C1 | C0 | DB19                              | DB18 | DB17 | DB16 | DB15 | DB14 | [DB13:DB8] | DB7              | DB6              | DB5                | DB4                | [DB3:DB0] |                                     |
| 0                   | 0  | 0  | 0  | X                                 | X    | X    | X    | X    | X    | X...X      | X                | X                | X                  | X                  | X...X     | Do nothing                          |
| 0                   | 0  | 0  | 1  | DB15                              | DB14 | DB13 | DB12 | DB11 | DB10 | DB9...DB4  | DB3 <sup>2</sup> | DB2 <sup>2</sup> | DB1 <sup>2,3</sup> | DB0 <sup>2,3</sup> | X...X     | Write input register                |
| 0                   | 0  | 1  | 0  | X                                 | X    | X    | X    | X    | X    | X...X      | X                | X                | X                  | X                  | X...X     | Update DAC register (software LDAC) |
| 0                   | 0  | 1  | 1  | DB15                              | DB14 | DB13 | DB12 | DB11 | DB10 | DB9...DB4  | DB3 <sup>2</sup> | DB2 <sup>2</sup> | DB1 <sup>2,3</sup> | DB0 <sup>2,3</sup> | X...X     | Write DAC and input register        |
| 0                   | 1  | 0  | 0  | DB19                              | DB18 | DB17 | DB16 | DB15 | DB14 | 0...0      | 0                | 0                | 0                  | 0                  | 0...0     | Write control register              |
| 0                   | 1  | 0  | 1  | X                                 | X    | X    | X    | X    | X    | X...X      | X                | X                | X                  | X                  | X...X     | Readback input register             |

<sup>1</sup> X means don't care.

<sup>2</sup> This bit is a don't care bit for the [AD5681R](#) only.

<sup>3</sup> This bit is a don't care bit for the [AD5682R](#) only.

**Write Control Register**

The write control register sets the power-down and gain functions. It also enables/disables the internal reference and perform a software reset. See Table 10 for the write control register functionality.

**Table 10. Write Control Register Bits**

| DB19  | DB18 | DB17 | DB16 | DB15 | DB14 |
|-------|------|------|------|------|------|
| Reset | PD1  | PD0  | REF  | Gain | DCEN |

**DCEN Bit**

The daisy-chain enable bit (DCEN, Bit DB14) enables the SDO pin, allowing the device to operate in daisy-chain mode. This bit is automatically disabled when a readback command is executed. Enabling this bit disables the write short command feature in the [AD5681R](#).

**Table 11. Daisy-Chain Enable Bit (DCEN)**

| DB0 | Mode                      |
|-----|---------------------------|
| 0   | Standalone mode (default) |
| 1   | DCEN mode                 |

**Gain Bit**

The gain bit selects the gain of the output amplifier. Table 12 shows how the output voltage range corresponds to the state of the gain bit.

**Table 12. Gain Bit**

| Gain | Output Voltage Range       |
|------|----------------------------|
| 0    | 0 V to $V_{REF}$ (default) |
| 1    | 0 V to $2 \times V_{REF}$  |

**REF Bit**

The on-chip reference is on at power-up by default. This reference can be turned on or off by setting a software-programmable bit, DB16, in the write control register. Table 13 shows how the state of the bit corresponds to the mode of operation.

To reduce the power consumption, it is recommended to disable the internal reference if the device is placed in power-down mode.

**Table 13. Reference Bit (REF)**

| REF | Reference Function          |
|-----|-----------------------------|
| 0   | Reference enabled (default) |
| 1   | Reference disabled          |

**PD0 and PD1 Bits**

The [AD5683R/AD5682R/AD5681R](#) contain two separate mode of operation that are accessed by writing to the write control register.

In normal mode, the output buffer is directly connected to the  $V_{OUT}$  pin.

In power-down mode, the output buffer is internally disabled and the  $V_{OUT}$  pin output impedance can be selected to a well-known value, as shown in Table 14.

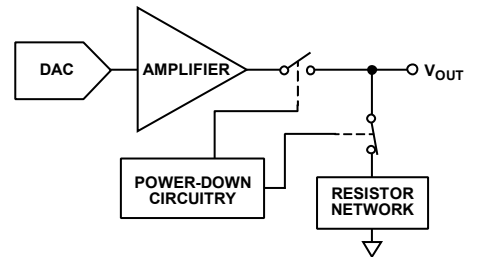
**Table 14. Operation Modes**

| Operating Mode                  | PD1 | PD0 |
|---------------------------------|-----|-----|
| Normal Mode                     | 0   | 0   |
| Power-Down Modes                |     |     |
| 1 k $\Omega$ Output Impedance   | 0   | 1   |
| 100 k $\Omega$ Output Impedance | 1   | 0   |
| Three-State Output Impedance    | 1   | 1   |

In power-down mode, the device disables the output buffer but does not disable the internal reference. To achieve maximum power savings, it is recommend to disable the REF bit, if possible.

Disabling both the internal reference and the output buffer results in the supply current falling to 2  $\mu$ A at 5 V.

The output stage is shown in Figure 52.

**Figure 52. Output Stage During Power-Down**

The output amplifier is shut down when the power-down mode is activated. However, unless the internal reference is powered down (using Bit DB16 in the write control register), the bias generator, reference, and resistor string remain on. When in power-down mode, the weak SDO resistor is also disconnected. The supply current falls to 2  $\mu$ A at 5 V. The contents of the DAC register are unaffected when in power-down mode, and the DAC register can continue to be updated. The time that is required to exit power-down is typically 4  $\mu$ s for  $V_{DD} = 5$  V, or 600  $\mu$ s if the reference is disabled.

**Reset Bit**

The write control register of the [AD5683R/AD5682R/AD5681R](#) contains a software reset function that resets the input and DAC registers to zero scale and resets the write control register to the default value. A software reset is initiated by setting the reset bit (Bit DB19) in the write control register to 1. When the software reset is complete, the reset bit is cleared to 0 automatically.



### Readback Input Register

The AD5683R allows readback of the contents of the input register through the SDO pin by using Command 5 (see Table 9), as shown in Figure 53.

The SDO pin is automatically enabled for the duration of the read operation, after which it is disabled again, as shown in Table 15. If the DCEN bit was enabled before the read operation, the bit is reset after a readback operation. If the AD5683R was operating in daisy-chain mode, the user must enable the DCEN bit again.

**Table 15. Write and Readback sequence**

| SDI      | SDO                   | Action                                    |
|----------|-----------------------|---|
| 0x180000 | 0x000000              | Write 0x8000 to the input register        |
| 0x500000 | 0x000000              | Prepare data read from the input register |
| 0x000000 | 0xX8000X <sup>1</sup> | Clock out the data                        |

<sup>1</sup> X mean don't care.

### HARDWARE LDAC

The DACs of the AD5683R/AD5682R/AD5681R/AD5683 have a double buffered interface consisting of an input register and a DAC register. The LDAC transfers data from the input register to the DAC register and, consequently, the output is updated.

Hold LDAC high while data is clocked into the input shift register. The DAC output is updated by taking LDAC low after SYNC is taken high. The output DAC is updated on the falling edge of LDAC.

If LDAC is pulsed while the data is being clocked, the pulse is ignored.

### HARDWARE RESET

RESET is an active low signal that sets the input and DAC registers to zero scale and the control registers to their default values. It is necessary to keep RESET low for 75 ns to complete the operation. When the RESET signal returns high, the output remains at the zero scale until a new value is programmed. While the RESET pin is low, the AD5683R/AD5681R ignore any new command.

If RESET is held low at power-up, the internal reference is not initialized correctly until the RESET pin is released.

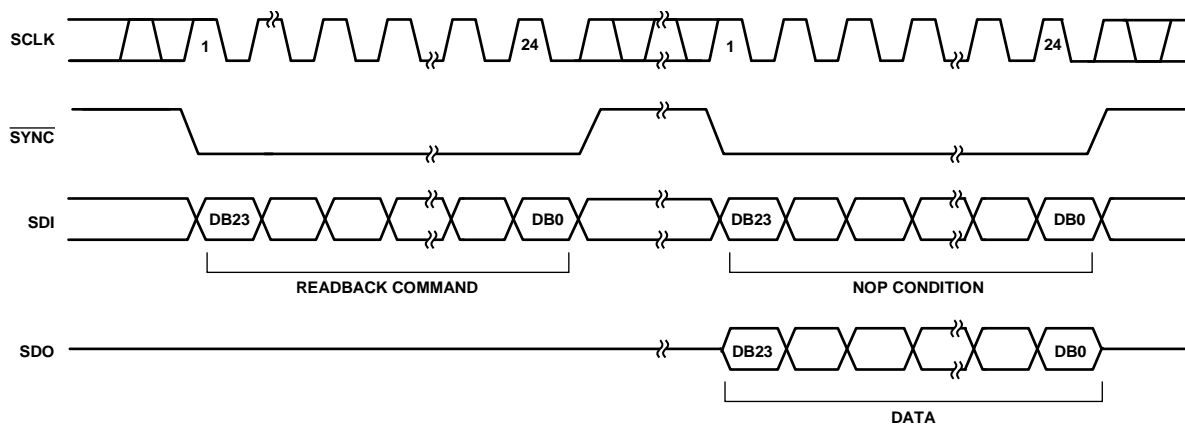


Figure 53. Readback Operation

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## THERMAL HYSTERESIS

Thermal hysteresis is the voltage difference induced on the reference voltage by sweeping the temperature from ambient to cold, to hot, and then back to ambient.

The thermal hysteresis data is shown in Figure 54. It is measured by sweeping the temperature from ambient to  $-40^{\circ}\text{C}$ , then to  $+105^{\circ}\text{C}$ , and finally returning to ambient. The  $V_{\text{REF}}$  delta is next measured between the two ambient measurements; the result is shown in a solid line in Figure 54. The same temperature sweep and measurements were immediately repeated; the results are shown in a patterned line in Figure 54.

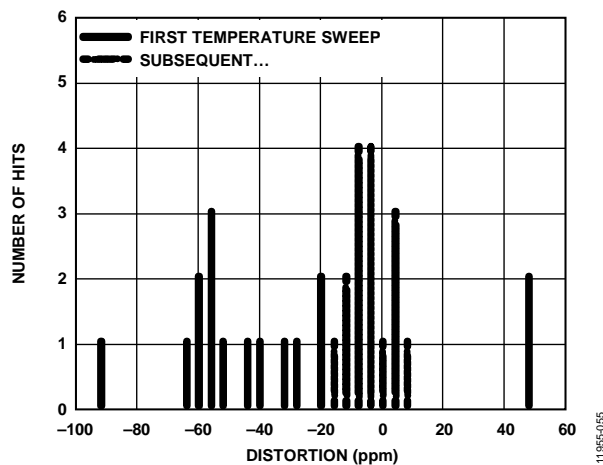


Figure 54. Thermal Hysteresis

## POWER-UP SEQUENCE

Because there are diodes to limit the voltage compliance at the digital pins and analog pins, it is important to power GND first before applying any voltage to  $V_{\text{DD}}$ ,  $V_{\text{OUT}}$ , and  $V_{\text{LOGIC}}$ . Otherwise, the diode is forward-biased such that  $V_{\text{DD}}$  is powered unintentionally. The ideal power-up sequence is GND,  $V_{\text{DD}}$ ,  $V_{\text{LOGIC}}$ ,  $V_{\text{REF}}$ , followed by the digital inputs.

## RECOMMENDED REGULATOR

The AD5683R/AD5682R/AD5681R/AD5683 use a 5 V ( $V_{\text{DD}}$ ) supply as well as a digital logic supply ( $V_{\text{LOGIC}}$ ).

The analog and digital supplies required for the AD5683R/AD5682R/AD5681R/AD5683 can be generated using Analog Devices, Inc., low dropout (LDO) regulators such as the ADP7118 and the ADP162, respectively, for analog and digital supplies.

## LAYOUT GUIDELINES

In any circuit where accuracy is important, careful consideration of the power supply and ground return layout helps to ensure the rated performance. The printed circuit board (PCB) on which the ADCs are mounted must be designed such that the AD5683R/AD5682R/AD5681R/AD5683 lie on the analog plane.

Ensure that the AD5683R/AD5682R/AD5681R/AD5683 have ample supply bypassing of 10  $\mu\text{F}$  in parallel with a 0.1  $\mu\text{F}$  capacitor on each supply that is located as near to the package as possible (ideally, right up against the device). The 10  $\mu\text{F}$  capacitors are of the tantalum bead type. The 0.1  $\mu\text{F}$  capacitor must have low effective series resistance (ESR) and low effective series inductance (ESI), such as the common ceramic types, which provide a low impedance path to ground at high frequencies to handle transient currents due to internal logic switching.

In systems where there are many devices on one board, it is often useful to provide some heat sinking capability to allow the power to dissipate easily.

The LFCSP packages of the AD5683R/AD5682R/AD5681R/AD5683 have an exposed pad beneath the device. Connect this pad to the GND supply of the device. For optimum performance, use special consideration when designing the motherboard and mounting the package. For enhanced thermal, electrical, and board level performance, solder the exposed pad on the bottom of the package to the corresponding thermal land pad on the PCB. Design thermal vias into the PCB land pad area to further improve heat dissipation.

The GND plane on the device can be increased (as shown in Figure 55) to provide a natural heat sinking effect.

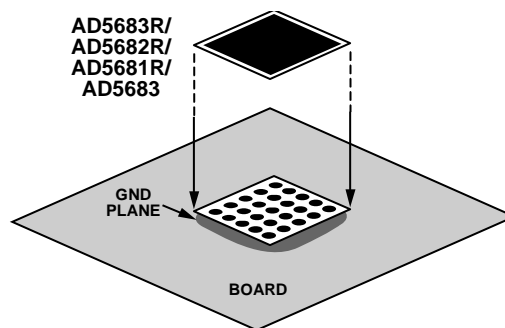


Figure 55. Pad Connection to Board

## OUTLINE DIMENSIONS

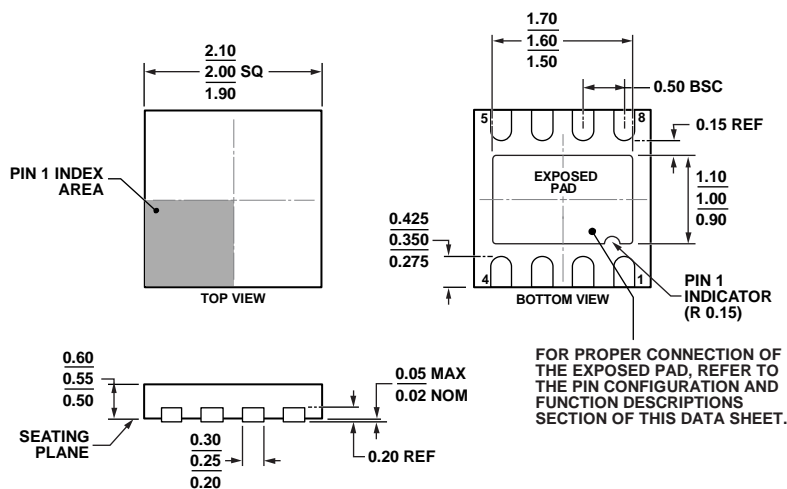
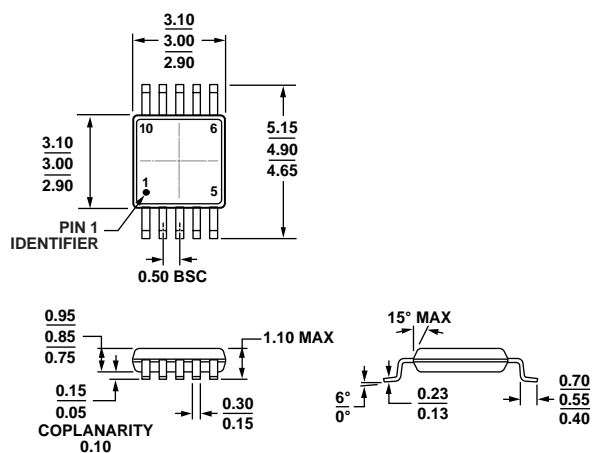


Figure 56. 8-Lead Lead Frame Chip Scale Package [LFCSP\_UD]  
2.00 mm × 2.00 mm Body, Ultrathin, Dual Lead  
(CP-8-10)

Dimensions shown in millimeters



COMPLIANT TO JEDEC STANDARDS MO-187-BA

Figure 57. 10-Lead Mini Small Outline Package [MSOP]  
(RM-10)

Dimensions shown in millimeters

## ORDERING GUIDE

| Model <sup>1</sup> | Resolution (Bits) | Pinout             | Temperature Range | Performance | Package Description | Package Option | Branding |
|--------------------|-------------------|--------------------|-------------------|-------------|---------------------|----------------|----------|
| AD5683RACPZ-RL7    | 16                | LDAC               | −40°C to +105°C   | A Grade     | 8-Lead LFCSP_UD     | CP-8-10        | 94       |
| AD5683RACPZ-1RL7   | 16                | V <sub>LOGIC</sub> | −40°C to +105°C   | A Grade     | 8-Lead LFCSP_UD     | CP-8-10        | 95       |
| AD5683RACPZ-2RL7   | 16                | RESET              | −40°C to +105°C   | A Grade     | 8-Lead LFCSP_UD     | CP-8-10        | 96       |
| AD5683RARMZ        | 16                | V <sub>LOGIC</sub> | −40°C to +105°C   | A Grade     | 10-Lead MSOP        | RM-10          | DHY      |
| AD5683RARMZ-RL7    | 16                | V <sub>LOGIC</sub> | −40°C to +105°C   | A Grade     | 10-Lead MSOP        | RM-10          | DHY      |
| AD5683RBRMZ        | 16                | V <sub>LOGIC</sub> | −40°C to +105°C   | B Grade     | 10-Lead MSOP        | RM-10          | DHZ      |
| AD5683RBRMZ-RL7    | 16                | V <sub>LOGIC</sub> | −40°C to +105°C   | B Grade     | 10-Lead MSOP        | RM-10          | DHZ      |
| AD5683RBRMZ-3      | 16                | SDO                | −40°C to +105°C   | B Grade     | 10-Lead MSOP        | RM-10          | DJ0      |
| AD5683RBRMZ-3-RL7  | 16                | SDO                | −40°C to +105°C   | B Grade     | 10-Lead MSOP        | RM-10          | DJ0      |
| AD5683RBCPZ-RL7    | 16                | LDAC               | −40°C to +105°C   | B Grade     | 8-Lead LFCSP_UD     | CP-8-10        | 97       |
| AD5683RBCPZ-1RL7   | 16                | V <sub>LOGIC</sub> | −40°C to +105°C   | B Grade     | 8-Lead LFCSP_UD     | CP-8-10        | DX       |
| AD5683BCPZ-RL7     | 16                | LDAC               | −40°C to +105°C   | B Grade     | 8-Lead LFCSP_UD     | CP-8-10        | 9A       |
| AD5682RBCPZ-RL7    | 14                | LDAC               | −40°C to +105°C   | B Grade     | 8-Lead LFCSP_UD     | CP-8-10        | 9B       |
| AD5681RBCPZ-RL7    | 12                | LDAC               | −40°C to +105°C   | B Grade     | 8-Lead LFCSP_UD     | CP-8-10        | 98       |
| AD5681RBCPZ-1RL7   | 12                | V <sub>LOGIC</sub> | −40°C to +105°C   | B Grade     | 8-Lead LFCSP_UD     | CP-8-10        | 99       |
| AD5681RBRMZ        | 12                | V <sub>LOGIC</sub> | −40°C to +105°C   | B Grade     | 10-Lead MSOP        | RM-10          | DHX      |
| AD5681RBRMZ-RL7    | 12                | V <sub>LOGIC</sub> | −40°C to +105°C   | B Grade     | 10-Lead MSOP        | RM-10          | DHX      |
| EVAL-AD5683RSDZ    |                   |                    |                   |             | Evaluation Board    |                |          |

<sup>1</sup> Z = RoHS Compliant Part.

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- При необходимости вся продукция военного и аэрокосмического назначения проходит испытания и сертификацию в лаборатории (по согласованию с заказчиком);
- Поставка специализированных компонентов военного и аэрокосмического уровня качества (Xilinx, Altera, Analog Devices, Intersil, Interpoint, Microsemi, Actel, Aeroflex, Peregrine, VPT, Syfer, Eurofarad, Texas Instruments, MS Kennedy, Miteq, Cobham, E2V, MA-COM, Hittite, Mini-Circuits, General Dynamics и др.);

Компания «Океан Электроники» является официальным дистрибьютором и эксклюзивным представителем в России одного из крупнейших производителей разъемов военного и аэрокосмического назначения «JONHON», а так же официальным дистрибьютором и эксклюзивным представителем в России производителя высокотехнологичных и надежных решений для передачи СВЧ сигналов «FORSTAR».



## JONHON

«JONHON» (основан в 1970 г.)

Разъемы специального, военного и аэрокосмического назначения:

(Применяются в военной, авиационной, аэрокосмической, морской, железнодорожной, горно- и нефтедобывающей отраслях промышленности)

«FORSTAR» (основан в 1998 г.)

ВЧ соединители, коаксиальные кабели,  
кабельные сборки и микроволновые компоненты:

(Применяются в телекоммуникациях гражданского и специального назначения, в средствах связи, РЛС, а так же военной, авиационной и аэрокосмической отраслях промышленности).



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