



EEPROM-Programmable, Hex Power-Supply Supervisory Circuits

MAX6884/MAX6885

General Description

The MAX6884/MAX6885 EEPROM-configurable, multi-voltage power-supply supervisors monitor six voltage-detector inputs, one auxiliary input, and one watchdog input, and feature three programmable outputs for highly configurable power-supply monitoring applications. Manual reset and margin disable inputs offer additional flexibility.

Each voltage-detector input offers a programmable primary undervoltage and secondary undervoltage/over-voltage threshold. Voltage-detector inputs IN1–IN6 monitor voltages from 1V to 5.8V in 20mV increments or 0.5V to 3.05V in 10mV increments.

Programmable outputs $\overline{\text{RESET}}$, $\overline{\text{UV/OV}}$, and $\overline{\text{WDO}}$ provide system resets/interrupts. Programmable output options include open-drain or weak pullup. Programmable timing delay blocks configure each output to wait between 25 μ s and 1600ms after their respective assertion-causing conditions have been cleared. A fault register logs condition-causing events (undervoltage, overvoltage, manual reset, etc.).

An internal 10-bit, 1% accurate ADC (MAX6884 only) converts the voltages at IN1–IN6, AUXIN, and VCC through a multiplexer that automatically sequences through all inputs every 200ms. An SMBus™/I²C-compatible serial data interface programs and communicates with the configuration EEPROM, configuration registers, internal 512-bit user EEPROM, and reads the ADC registers (MAX6884 only) and fault registers.

The MAX6884/MAX6885 are available in a 5mm x 5mm x 0.8mm 20-pin thin QFN package and operate over the extended temperature range (-40°C to +85°C).

Applications

Telecommunications/Central-Office Systems
Networking Systems
Servers/Workstations
Base Stations
Storage Equipment
Multimicroprocessor/Voltage Systems

Features

- ◆ 6 Configurable Input Voltage Detectors
Programmable Thresholds 0.5V to 3.05V (in 10mV Increments) or 1V to 5.8V (in 20mV Increments)
Primary UV and Secondary UV/OV Thresholds
- ◆ One Configurable Watchdog Timer from 6.25ms to 102.4s
- ◆ Configurable $\overline{\text{RESET}}$, $\overline{\text{UV/OV}}$, and $\overline{\text{WDO}}$ Outputs
- ◆ Three Programmable Outputs
Open-Drain or Weak Pullup $\overline{\text{RESET}}$, $\overline{\text{UV/OV}}$, and $\overline{\text{WDO}}$
Active-Low Output Logic
Timing Delays from 25 μ s to 1600ms
- ◆ Margining Disable and Manual Reset Controls
- ◆ Internal 1.25V Reference or External Reference Input
- ◆ 10-Bit Internal ADC Samples the Input Voltage Detectors, VCC and Auxiliary Input
- ◆ 512-Bit User EEPROM
Endurance: 100,000 Erase/Write Cycles
Data Retention: 10 Years
- ◆ SMBus/I²C-Compatible Serial Configuration/Communication Interface
- ◆ $\pm 1\%$ Threshold Accuracy

Ordering Information

| PART | TEMP RANGE | PIN-PACKAGE | PKG CODE |
|------------|----------------|-------------|----------|
| MAX6884ETP | -40°C to +85°C | 20 Thin QFN | T2055-5 |
| MAX6885ETP | -40°C to +85°C | 20 Thin QFN | T2055-5 |

Pin Configurations and Typical Operating Circuit appear at end of data sheet.

Selector Guide

| PART | VOLTAGE-DETECTOR INPUTS | INTERNAL ADC | PROGRAMMABLE OUTPUTS | REFERENCE INPUT | AUXILIARY INPUT |
|------------|-------------------------|--------------|----------------------|-----------------|-----------------|
| MAX6884ETP | 6 | Yes | 3 | Yes | Yes |
| MAX6885ETP | 6 | No | 3 | No | No |

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ABSOLUTE MAXIMUM RATINGS

(All voltages referenced to GND.)

| | |
|-------------------------------------------------------|--------------|
| IN1–IN6, V _{CC} , RESET, UV/OV, WDO | -0.3V to +6V |
| WDI, MR, MARGIN, SDA, SCL, A0 | -0.3V to +6V |
| AUXIN, DBP, REFIN | -0.3V to +3V |
| Input/Output Current (all pins) | ±20mA |
| Continuous Power Dissipation (T _A = +70°C) | |
| 20-Pin (5mm x 5mm) Thin QFN | |
| (derate 21.3mW/°C above +70°C) | 1702mW |

| | |
|-----------------------------------|-----------------|
| Maximum Junction Temperature | +150°C |
| Operating Temperature Range | -40°C to +85°C |
| Storage Temperature Range | -65°C to +150°C |
| Lead Temperature (soldering, 10s) | +300°C |

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

ELECTRICAL CHARACTERISTICS

(V_{IN1}–V_{IN4} or V_{CC} = 2.7V to 5.8V, AUXIN = WDI = GND, MARGIN = MR = DBP, T_A = -40°C to +85°C, unless otherwise noted. Typical values are at T_A = +25°C.) (Notes 1, 2, 3)

| PARAMETER | SYMBOL | CONDITIONS | MIN | TYP | MAX | UNITS | |
|----------------------------|-------------------|--------------------------------------------------------------------------------------------------|----------------------------------------------------|-------|-------|-------|----|
| Operating Voltage Range | | Voltage on either one of IN1–IN4 or V _{CC} to guarantee the device is fully operational | 2.7 | | 5.8 | V | |
| Undervoltage Lockout | V _{UVLO} | Minimum voltage on one of IN1–IN4 or V _{CC} to guarantee device is EEPROM configured | | | 2.5 | V | |
| Digital Bypass Voltage | V _{DBP} | No load | 2.48 | 2.55 | 2.67 | V | |
| Supply Current | I _{CC} | V _{IN1} = 5.8V, IN2–IN6 = GND, no load | | 0.9 | 1.2 | mA | |
| | | Writing to configuration registers or EEPROM, no load | | 1.1 | 1.5 | mA | |
| Threshold Range | V _{TH} | V _{IN1} –V _{IN6} (in 20mV increments) | 1.0 | | 5.8 | V | |
| | | V _{IN1} –V _{IN6} (in 10mV increments) | 0.50 | | 3.05 | | |
| | | V _{IN1} –V _{IN6} (Inputs high impedance; in 3.3mV increments) | 0.167 | | 1.017 | | |
| IN1–IN6 Threshold Accuracy | | T _A = +25°C to +85°C, (V _{IN} falling) | V _{IN} = 2.5V to 5.8V (20mV increments) | -1 | | +1 | % |
| | | | V _{IN} = 1V to 2.5V (20mV increments) | -25 | | +25 | mV |
| | | | V _{IN} = 1.25V to 3.05V (10mV increments) | -1 | | +1 | % |
| | | | V _{IN} = 0.5V to 1.25V (10mV increments) | -12.5 | | +12.5 | mV |
| | | T _A = -40°C to +85°C, (V _{IN} falling) | V _{IN} = 2.5V to 5.8V (20mV increments) | -1.5 | | +1.5 | % |
| | | | V _{IN} = 1V to 2.5V (20mV increments) | -25 | | +25 | mV |
| | | | V _{IN} = 1.25V to 3.05V (10mV increments) | -1.5 | | +1.5 | % |
| | | | V _{IN} = 0.5V to 1.25V (10mV increments) | -12.5 | | +12.5 | mV |

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ELECTRICAL CHARACTERISTICS (continued)

(V_{IN1} – V_{IN4} or V_{CC} = 2.7V to 5.8V, $AUXIN$ = WDI = GND, \overline{MARGIN} = \overline{MR} = DBP, T_A = -40°C to +85°C, unless otherwise noted. Typical values are at T_A = +25°C.) (Notes 1, 2, 3)

| PARAMETER | SYMBOL | CONDITIONS | MIN | TYP | MAX | UNITS |
|----------------------------------------------------------------------------------------------|---------------------------|-----------------------------------------------------------------------------|-------|--------|-------|------------------|
| Threshold Hysteresis | $V_{TH-HYST}$ | | | 0.3 | | % V_{TH} |
| Threshold Tempco | $\Delta V_{TH}/^{\circ}C$ | | | 10 | | ppm/ $^{\circ}C$ |
| Threshold Differential Nonlinearity | V_{TH-DNL} | | -1 | | +1 | LSB |
| IN_ Input Impedance | R_{IN} | For $V_{IN_} <$ highest of V_{IN1} – V_{IN4} and $V_{IN_} <$ V_{CC} | 130 | 200 | 300 | k Ω |
| IN_ Input Leakage Current | I_{IN-LKG} | IN_ high impedance | -150 | | +150 | nA |
| Power-Up Delay | t_{D-PO} | $V_{CC} \geq V_{UVLO}$ | | | 2.5 | ms |
| IN_ to \overline{RESET} or UV/OV Delay | t_{D-R} | IN_ falling/rising, 100mV overdrive | | 20 | | μ s |
| \overline{RESET} and $\overline{UV/OV}$ Timeout Period (Tables 6 and 7) | t_{RP}, t_{UP} | 000 | | 0.025 | | ms |
| | | 001 | 1.406 | 1.5625 | 1.719 | |
| | | 010 | 5.625 | 6.25 | 6.875 | |
| | | 011 | 22.5 | 25 | 27.5 | |
| | | 100 | 45 | 50 | 55 | |
| | | 101 | 180 | 200 | 220 | |
| | | 110 | 360 | 400 | 440 | |
| | | 111 | 1440 | 1600 | 1760 | |
| \overline{RESET} , $\overline{UV/OV}$, \overline{WDO} Output Low | | $I_{SINK} = 4mA$, output asserted | | | 0.4 | V |
| \overline{RESET} , $\overline{UV/OV}$, \overline{WDO} Output Open-Drain Leakage Current | | Output high impedance | -1 | | +1 | μ A |
| \overline{RESET} , $\overline{UV/OV}$, \overline{WDO} Output Pullup Resistance | R_{PU} | $V_{\overline{RESET}}, V_{\overline{UV/OV}}, V_{\overline{WDO}} = 2V$ | 6.6 | 10 | 15.0 | k Ω |
| \overline{MR} , \overline{MARGIN} , \overline{WDI} Input Voltage | V_{IL} | | | | 0.6 | V |
| | V_{IH} | | 1.4 | | | |
| \overline{MR} Input Pulse Width | t_{MR} | | 1 | | | μ s |
| \overline{MR} Glitch Rejection | | | | 100 | | ns |

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ELECTRICAL CHARACTERISTICS (continued)

(V_{IN1} – V_{IN4} or V_{CC} = 2.7V to 5.8V, $AUXIN$ = WDI = GND, \overline{MARGIN} = \overline{MR} = DBP, T_A = -40°C to +85°C, unless otherwise noted. Typical values are at T_A = +25°C.) (Notes 1, 2, 3)

| PARAMETER | SYMBOL | CONDITIONS | MIN | TYP | MAX | UNITS |
|-------------------------------------------------------------------|-------------------------|--------------------------------------------------------------------|-------|---------|-----------|------------|
| \overline{MR} to \overline{RESET} or $\overline{UV/OV}$ Delay | $t_{D-\overline{MR}}$ | | | 200 | | ns |
| \overline{MR} to Internal V_{DBP} Pullup Current | $I_{\overline{MR}}$ | $V_{\overline{MR}} = 1.4V$ | 5 | 10 | 15 | μA |
| \overline{MARGIN} to DBP Pullup Current | $I_{\overline{MARGIN}}$ | $V_{\overline{MARGIN}} = 1.4V$ | 5 | 10 | 15 | μA |
| WDI Pulldown Current | I_{WDI} | $V_{WDI} = 0.6V$ | 5 | 10 | 15 | μA |
| WDI Input Pulse Width | t_{WDI} | | 50 | | | ns |
| Watchdog Timeout Period (Table 8) | t_{WD} | 000 | 5.625 | 6.25 | 6.875 | ms |
| | | 001 | 22.5 | 25 | 27.5 | |
| | | 010 | 90 | 100 | 110 | |
| | | 011 | 360 | 400 | 440 | |
| | | 100 | 1.44 | 1.60 | 1.76 | s |
| | | 101 | 5.76 | 6.40 | 7.04 | |
| | | 110 | 23.04 | 25.60 | 28.16 | |
| | | 111 | 92.16 | 102.40 | 112.64 | |
| Reference Input Voltage Range | V_{REF} | MAX6884 only | 1.225 | 1.25 | 1.275 | V |
| Reference Input Resistance | R_{REF} | $V_{REF} = 1.25V$, MAX6884 only | | 500 | | k Ω |
| ADC Range | ADC_{RANGE} | IN1–IN6, V_{CC} ; LSB = 7.32mV, MAX6884 only | 0 | | 5.8 | V |
| | | IN1–IN6; LSB = 3.66mV, MAX6884 only | 0 | | 3.746 | |
| | | AUXIN, IN1–IN6 high-impedance mode; LSB = 1.2mV, MAX6884 only | 0 | | 1.25 | |
| ADC Total Unadjusted Error (Note 4) | TUE | Internal reference, MAX6884 only | | | ± 1.0 | %FSR |
| | | External reference, MAX6884 only (Note 5) | | | ± 1.0 | |
| ADC Differential Nonlinearity | DNL | MAX6884 only (Note 6) | | ± 1 | | LSB |
| ADC Total Monitoring Cycle Time | t_C | Converts all six IN_* inputs, AUXIN, and V_{CC} , MAX6884 only | | 200 | 266 | ms |
| AUXIN Input Leakage Current | I_{AUXIN} | $V_{AUXIN} = 1.25V$, MAX6884 only | -1 | | +1 | μA |
| SERIAL INTERFACE LOGIC (SDA, SCL, A0) | | | | | | |
| Logic-Input Low Voltage | V_{IL} | | | | 0.8 | V |
| Logic-Input High Voltage | V_{IH} | | 2.0 | | | V |
| Input Leakage Current | I_{LKG} | | | | 1 | μA |
| Output-Voltage Low | V_{OL} | $I_{SINK} = 3mA$ | | | 0.4 | V |
| Input/Output Capacitance | $C_{I/O}$ | | | | 10 | pF |

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TIMING CHARACTERISTICS

($V_{IN1}-V_{IN4}$ or $V_{CC} = 2.7V$ to $5.8V$, $AUXIN = WDI = GND$, $\overline{MARGIN} = \overline{MR} = DBP$, $T_A = -40^\circ C$ to $+85^\circ C$, unless otherwise noted. Typical values are at $T_{IN1} = +25^\circ C$.) (Notes 1, 2, 3)

| PARAMETER | SYMBOL | CONDITIONS | MIN | TYP | MAX | UNITS |
|------------------------------------------|--------------|----------------------------|-----|------------------------------|-----|---------|
| TIMING CHARACTERISTICS (Figure 6) | | | | | | |
| Serial Clock Frequency | f_{SCL} | | | | 400 | kHz |
| Clock Low Period | t_{LOW} | | 1.3 | | | μs |
| Clock High Period | t_{HIGH} | | 0.6 | | | μs |
| Bus Free Time | t_{BUF} | | 1.3 | | | μs |
| START Setup Time | $t_{SU:STA}$ | | 0.6 | | | μs |
| START Hold Time | $t_{HD:STA}$ | | 0.6 | | | μs |
| STOP Setup Time | $t_{SU:STO}$ | | 0.6 | | | μs |
| Data In Setup Time | $t_{SU:DAT}$ | | 100 | | | ns |
| Data In Hold Time | $t_{HD:DAT}$ | | 30 | | 900 | ns |
| Receive SCL/SDA Minimum Rise Time | t_R | (Note 7) | | 20 + $0.1 \times C_{BUS}$ | | ns |
| Receive SCL/SDA Maximum Rise Time | t_R | (Note 7) | | 300 | | ns |
| Receive SCL/SDA Minimum Fall Time | t_F | (Note 7) | | 20 + $0.1 \times C_{BUS}$ | | ns |
| Receive SCL/SDA Maximum Fall Time | t_F | (Note 7) | | 300 | | ns |
| Transmit SDA Fall Time | t_F | $C_{BUS} = 400pF$ (Note 5) | | 20 + $0.1 \times C_{BUS}$ | 300 | ns |
| Pulse Width of Spike Suppressed | t_{SP} | (Note 8) | | 50 | | ns |
| EEPROM Byte Write Cycle Time | t_{WR} | (Note 9) | | | 11 | ms |

Note 1: 100% production tested at $T_A = +25^\circ C$ and $T_A = +85^\circ C$. Specifications at $T_A = -40^\circ C$ are guaranteed by design.

Note 2: Device may be supplied from $IN1-IN4$ or V_{CC} .

Note 3: The internal supply voltage, measured at V_{CC} , equals the maximum of $IN1-IN4$.

Note 4: $V_{IN_} > 0.3 \times$ ADC range.

Note 5: Does not include the inaccuracy of the 1.25V input reference voltage (MAX6884 only).

Note 6: DNL is implicitly guaranteed by design in a $\Sigma\Delta$ converter.

Note 7: C_{BUS} = total capacitance of one bus line in picofarads. Rise and fall times are measured between $0.1 \times V_{BUS}$ and $0.9 \times V_{BUS}$.

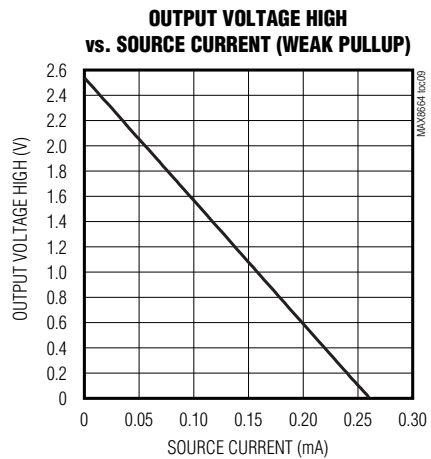
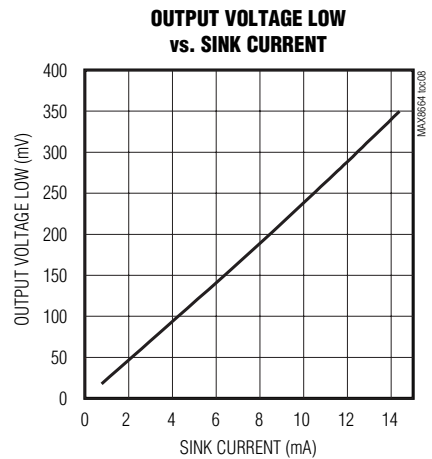
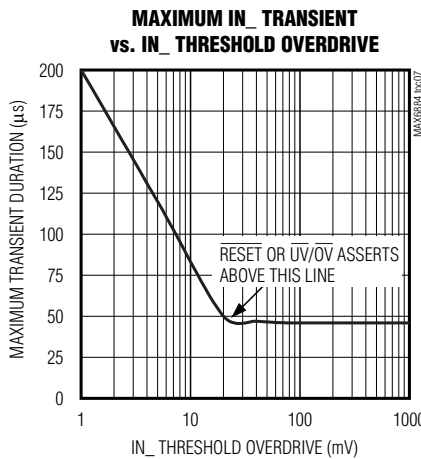
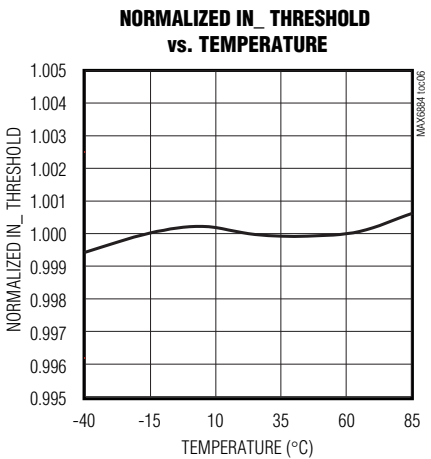
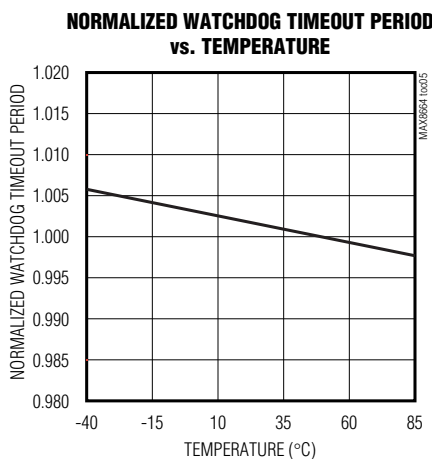
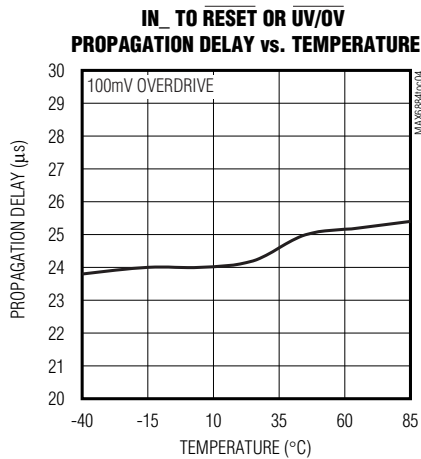
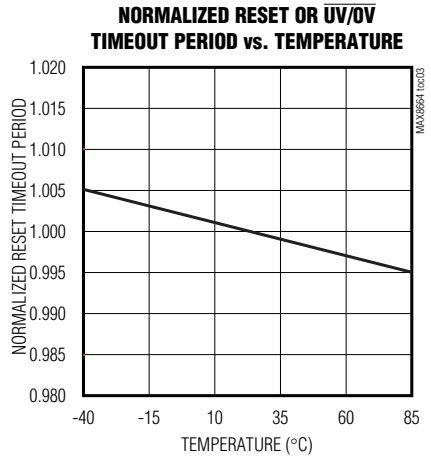
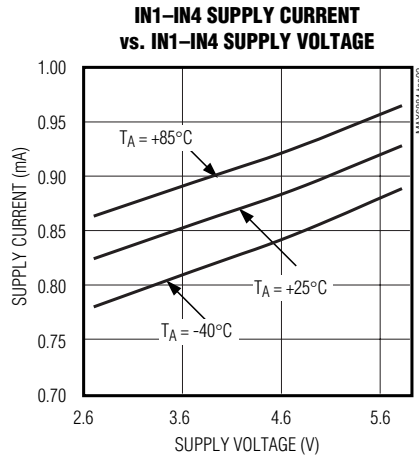
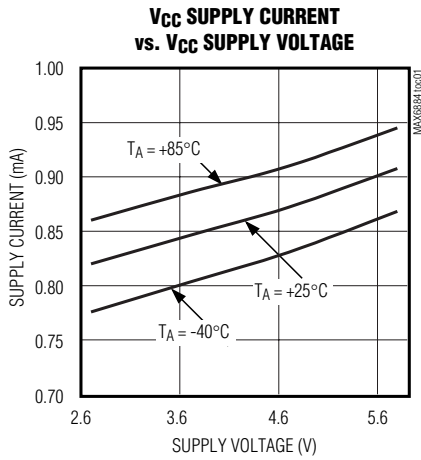
Note 8: Input filters on SDA, SCL, and A0 suppress noise spikes $< 50ns$.

Note 9: An additional cycle is required when writing to configuration memory for the first time.

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Typical Operating Characteristics

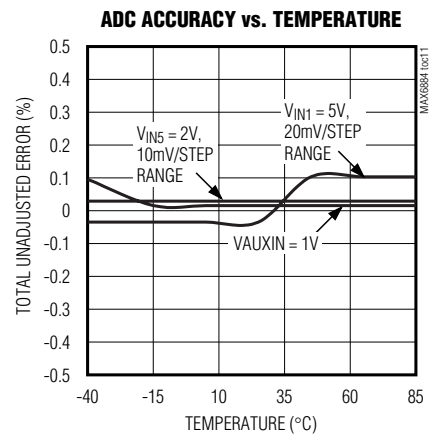
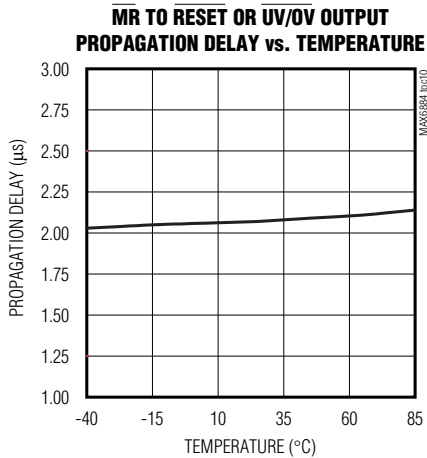
(VIN1–VIN4 or VCC = 5V, AUXIN = WDI = GND, MARGIN = MR = DBP. Typical values are at TA = +25°C, unless otherwise noted.)



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Typical Operating Characteristics (continued)

(V_{IN1} – V_{IN4} or V_{CC} = 5V, $AUXIN$ = WDI = GND, $MARGIN$ = \overline{MR} = DBP. Typical values are at T_A = +25°C, unless otherwise noted.)



MAX6884/MAX6885

Pin Description

| PIN | | NAME | FUNCTION |
|---------|---------|--------------------|-----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| MAX6884 | MAX6885 | | |
| 1 | 1 | \overline{RESET} | Reset Output. Configurable, active-low, open drain, or weak pullup. \overline{RESET} assumes its programmed conditional output state when V_{CC} exceeds UVLO (2.5V). |
| 2 | 2 | \overline{WDO} | Watchdog Timer Output. Configurable, active-low, open drain, or weak pullup. \overline{WDO} asserts when WDI is not toggled with a valid high-to-low or low-to-high transition within the watchdog timeout period. |
| 3 | 3 | $\overline{UV/OV}$ | Undervoltage/Overvoltage Output. Configurable, active-low, open drain, or weak pullup. $\overline{UV/OV}$ assumes its programmed conditional output state when V_{CC} exceeds UVLO (2.5V). |
| 4 | 4 | GND | Ground |
| 5 | 5 | WDI | Watchdog Timer Input. Logic input for the watchdog timer function. If \overline{WDI} is not toggled with a valid low-to-high or high-to-low transition within the watchdog timeout period, \overline{WDO} asserts. Program initial and normal watchdog timeout periods from 6.25ms to 102.4s. WDI is internally pulled down to GND through a 10µA current sink. |
| 6 | 6 | \overline{MR} | Manual Reset Input. Program \overline{MR} to assert \overline{RESET} and/or $\overline{UV/OV}$ when \overline{MR} is asserted. Leave \overline{MR} unconnected or connect to DBP if unused. \overline{MR} is internally pulled up to DBP through a 10µA current source. |

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Pin Description (continued)

| PIN | | NAME | FUNCTION |
|---------|---------|--------|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| MAX6884 | MAX6885 | | |
| 7 | 7 | MARGIN | Margin Input. MARGIN holds RESET, UV/OV, and WDO in their existing states when MARGIN is driven low. Leave MARGIN unconnected or connect to DBP if unused. MARGIN is internally pulled up to DBP through a 10µA current source. MARGIN overrides MR if both are asserted at the same time. |
| 8 | 8 | SDA | Serial Data Input/Output (Open Drain). SDA requires an external pullup resistor. |
| 9 | 9 | SCL | Serial-Interface Clock Input. SCL requires an external pullup resistor. |
| 10 | 10 | A0 | Serial Address Input 0. Allows up to 2 devices to share a common bus. Connect A0 to ground or the serial-interface power supply. |
| 11 | — | REFIN | Reference Voltage Input. Program the device for external or internal reference. Connect an external +1.225V to +1.275V reference to REFIN when using an external reference. Leave REFIN unconnected when using the internal reference. |
| 12 | — | AUXIN | Auxiliary Input. A 10-bit ADC converts the input voltage at AUXIN. The high-impedance AUXIN input accepts input voltages up to 1.25V. AUXIN does not affect programmable outputs. |
| — | 11, 12 | N.C. | No Connection. Not internally connected. |
| 13 | 13 | VCC | Internal Power-Supply Voltage. Bypass VCC to GND with a 1µF ceramic capacitor as close to the device as possible. VCC supplies power to the internal circuitry. VCC is internally powered from the highest of the monitored IN1–IN4 voltages. Do not use VCC to supply power to external circuitry. To externally supply VCC, see the <i>Powering the MAX6884/MAX6885</i> section. |
| 14 | 14 | DBP | Internal Digital Power-Supply Voltage. Bypass DBP to GND with a 1µF ceramic capacitor. DBP supplies power to the EEPROM memory, the internal logic circuitry, and the programmable outputs. Do not use DBP to supply power to external circuitry. |
| 15 | 15 | IN6 | Voltage-Detector Input 6. Program two thresholds per voltage-detector input (undervoltage UV and undervoltage/overvoltage UV/OV). Program IN6 detector thresholds from 1V to 5.8V in 20mV increments, 0.5V to 3.05V in 10mV increments. For improved noise immunity, bypass IN6 to GND with a 0.1µF capacitor installed as close to the device as possible. |
| 16 | 16 | IN5 | Voltage-Detector Input 5. Program two thresholds per voltage-detector input (undervoltage UV and undervoltage/overvoltage UV/OV). Program IN5 detector thresholds from 1V to 5.8V in 20mV increments, 0.5V to 3.05V in 10mV increments. For improved noise immunity, bypass IN5 to GND with a 0.1µF capacitor installed as close to the device as possible. |
| 17 | 17 | IN4 | Voltage-Detector Input 4. Program two thresholds per voltage-detector input (undervoltage UV and undervoltage/overvoltage UV/OV). Program IN4 detector thresholds from 1V to 5.8V in 20mV increments, 0.5V to 3.05V in 10mV increments. For improved noise immunity, bypass IN4 to GND with a 0.1µF capacitor installed as close to the device as possible. Program the device to receive power through IN1–IN4 inputs or VCC (see the <i>Powering the MAX6884/MAX6885</i> section). |

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Pin Description (continued)

| PIN | | NAME | FUNCTION |
|---------|---------|------|-----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| MAX6884 | MAX6885 | | |
| 18 | 18 | IN3 | Voltage-Detector Input 3. Program two thresholds per voltage-detector input (undervoltage UV and undervoltage/overvoltage UV/OV). Program IN3 detector thresholds from 1V to 5.8V in 20mV increments, or 0.5V to 3.05V in 10mV increments. For improved noise immunity, bypass IN3 to GND with a 0.1μF capacitor installed as close to the device as possible. Program the device to receive power through IN1–IN4 inputs or V _{CC} (see the <i>Powering the MAX6884/MAX6885</i> section). |
| 19 | 19 | IN2 | Voltage-Detector Input 2. Program two thresholds per voltage-detector input (undervoltage UV and undervoltage/overvoltage UV/OV). Program IN2 detector thresholds from 1V to 5.8V in 20mV increments, or 0.5V to 3.05V in 10mV increments. For improved noise immunity, bypass IN2 to GND with a 0.1μF capacitor installed as close to the device as possible. Program the device to receive power through IN1–IN4 inputs or V _{CC} (see the <i>Powering the MAX6884/MAX6885</i> section). |
| 20 | 20 | IN1 | Voltage-Detector Input 1. Program two thresholds per voltage-detector input (undervoltage UV and undervoltage/overvoltage UV/OV). Program IN1 detector thresholds from 1V to 5.8V in 20mV increments, or 0.5V to 3.05V in 10mV increments. For improved noise immunity, bypass IN1 to GND with a 0.1μF capacitor installed as close to the device as possible. Program the device to receive power through IN1–IN4 inputs or V _{CC} (see the <i>Powering the MAX6884/MAX6885</i> section). |
| — | — | EP | Exposed Paddle. Internally connected to GND. Connect EP to GND or leave floating. |

Detailed Description

The MAX6884/MAX6885 EEPROM-configurable, multi-voltage supply supervisors monitor six voltage-detector inputs, one auxiliary input, and one watchdog input, and feature three programmable outputs for highly configurable, power-supply monitoring applications (see Table 1 for programmable features). Manual reset and margin disable inputs offer additional flexibility.

Each voltage detector provides a programmable primary undervoltage and secondary undervoltage/overvoltage threshold. Program thresholds from 0.5V to 3.05V in 10mV increments, 1.0V to 5.8V in 20mV increments, or from 0.1667V to 1.0167V in 3.3mV increments. To achieve thresholds from 0.1667V to 1.0167V in 3.3mV increments, the respective input voltage detector must be programmed for high impedance and an external voltage-divider must be connected. A fault register logs undervoltage and overvoltage conditions for each voltage-detector input.

An internal 10-bit ADC (MAX6884 only) converts voltages at IN1–IN6, AUXIN, and V_{CC} through a multiplexer that automatically sequences through all inputs every 200ms. Access the device's internal 512-bit user EEPROM, configuration EEPROM, configuration registers, ADC registers, and fault registers through an SMBus/I²C-compatible serial interface (see the *SMBus/I²C-Compatible Serial Interface* section). The MAX6884/MAX6885 also feature an accurate internal 1.25V reference. For greater accuracy, connect an external 1.25V reference to REFIN (MAX6884 only).

Program outputs $\overline{\text{RESET}}$, $\overline{\text{UV/OV}}$, and $\overline{\text{WDO}}$ for open-drain or weak pullup. Program $\overline{\text{RESET}}$ and $\overline{\text{UV/OV}}$ to assert on any voltage-detector input, $\overline{\text{MR}}$, or each other. $\overline{\text{RESET}}$ can also depend on $\overline{\text{WDO}}$. Programmable timing delay blocks configure each output to wait between 25μs and 1600ms before deasserting. Fault registers log the assertion of $\overline{\text{RESET}}$, $\overline{\text{UV/OV}}$, and $\overline{\text{WDO}}$.

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The MAX6884/MAX6885 feature a watchdog timer with programmable initial and normal timeout periods from 6.25ms to 102.4s. \overline{WDO} asserts when \overline{WDI} is not toggled from high-to-low or low-to-high within the appropriate watchdog timeout period. Program \overline{WDO} to assert \overline{RESET} .

Program the MAX6884/MAX6885 to receive power through IN1–IN4 or V_{CC} (see the *Powering the MAX6884/MAX6885* section). Outputs remain asserted while the voltage that is supplying the device is below UVLO (2.5V) and above 1V (see Figure 1).

Table 1. Programmable Features

| FEATURE | DESCRIPTION |
|----------------------------------------|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| Input Voltages IN1–IN6 | <ul style="list-style-type: none"> Primary undervoltage threshold Secondary undervoltage or overvoltage threshold 1V to 5.8V thresholds in 20mV increments 0.5V to 3.05V thresholds in 10mV increments 0.1667V to 1.017V thresholds in 3.3mV increments in high-impedance mode |
| Programmable Output \overline{RESET} | <ul style="list-style-type: none"> Dependency on IN1–IN6, \overline{MR}, $\overline{UV/OV}$, and/or \overline{WDO} Active-low, weak pullup, or open-drain output Programmable timeout periods of 25μs, 1.5625ms, 6.25ms, 25ms, 50ms, 200ms, 400ms, or 1.6s |
| Programmable Output $\overline{UV/OV}$ | <ul style="list-style-type: none"> Dependency on IN1–IN6, \overline{MR}, and/or \overline{RESET} Active-low, weak pullup, or open-drain output Programmable timeout periods of 25μs, 1.5625ms, 6.25ms, 25ms, 50ms, 200ms, 400ms, or 1.6s |
| Programmable Output \overline{WDO} | <ul style="list-style-type: none"> Active-low, weak pullup, or open-drain output |
| Watchdog Timer | <ul style="list-style-type: none"> Initial watchdog timeout period of 6.25ms, 25ms, 100ms, 400ms, 1.6s, 6.4s, 25.6s, or 102.4s Normal watchdog timeout period of 6.25ms, 25ms, 100ms, 400ms, 1.6s, 6.4s, 25.6s, or 102.4s Watchdog enable/disable |
| V_{CC} Power Mode | <ul style="list-style-type: none"> Programs whether the device is powered from the highest IN_ input or from an external supply connected to V_{CC} |
| Manual Reset Input \overline{MR} | <ul style="list-style-type: none"> Program \overline{RESET} or $\overline{UV/OV}$ to assert while \overline{MR} is asserted |
| Reference Input REFIN | <ul style="list-style-type: none"> Internal +1.25V reference voltage Goes high impedance when internal reference is selected External reference voltage input from 1.225V to 1.275V Sets ADC voltage range |
| 10-Bit ADC* | <ul style="list-style-type: none"> Samples voltages at IN1–IN6, AUXIN, and V_{CC} Completes conversion of all eight inputs in 200ms Reference voltage sets ADC range Read ADC data from SMBus/I²C interface |
| Write Disable | <ul style="list-style-type: none"> Locks user EEPROM based on \overline{RESET} or $\overline{UV/OV}$ assertion |
| Configuration Lock | <ul style="list-style-type: none"> Locks configuration registers and EEPROM |

*ADC does not affect programmable outputs.

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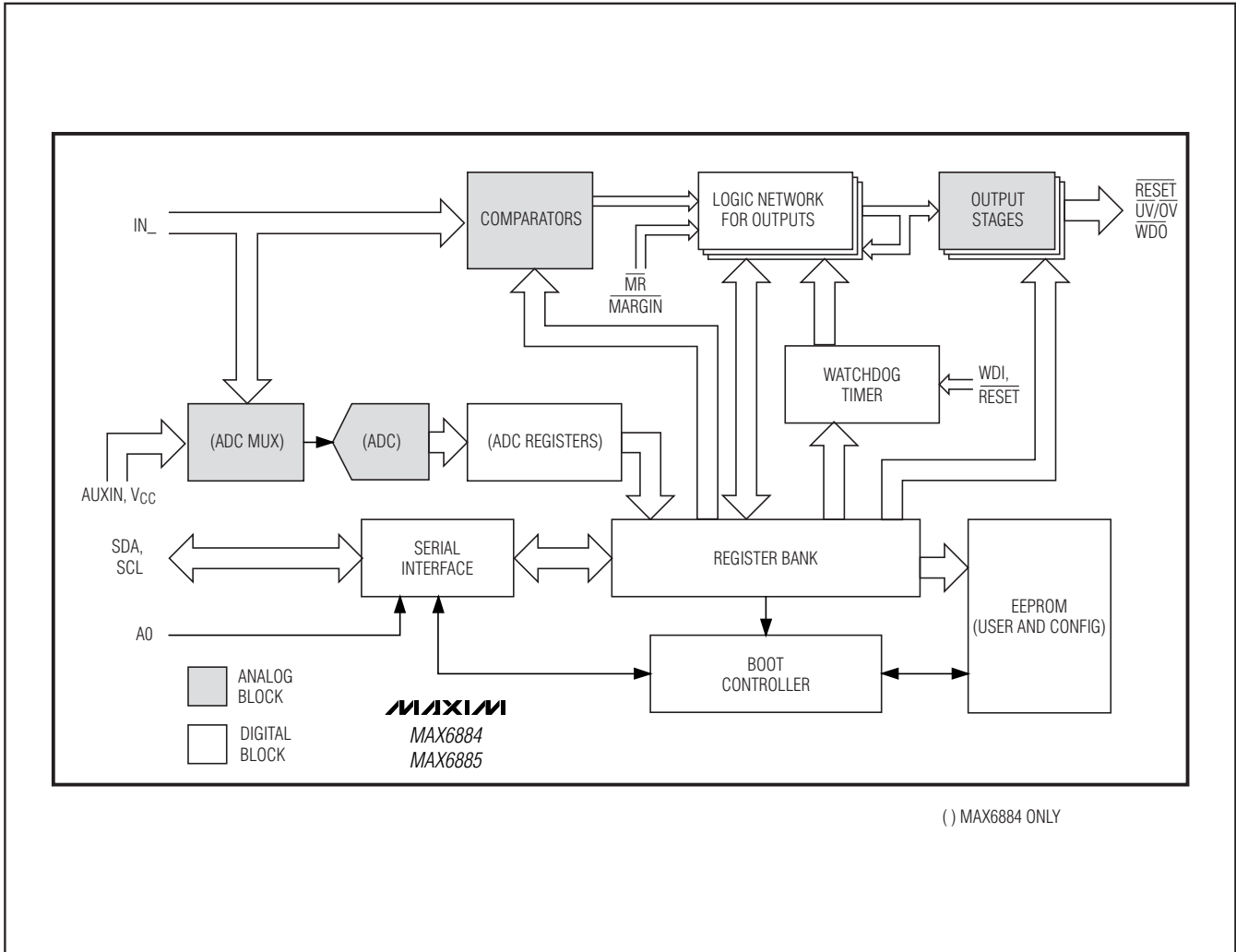
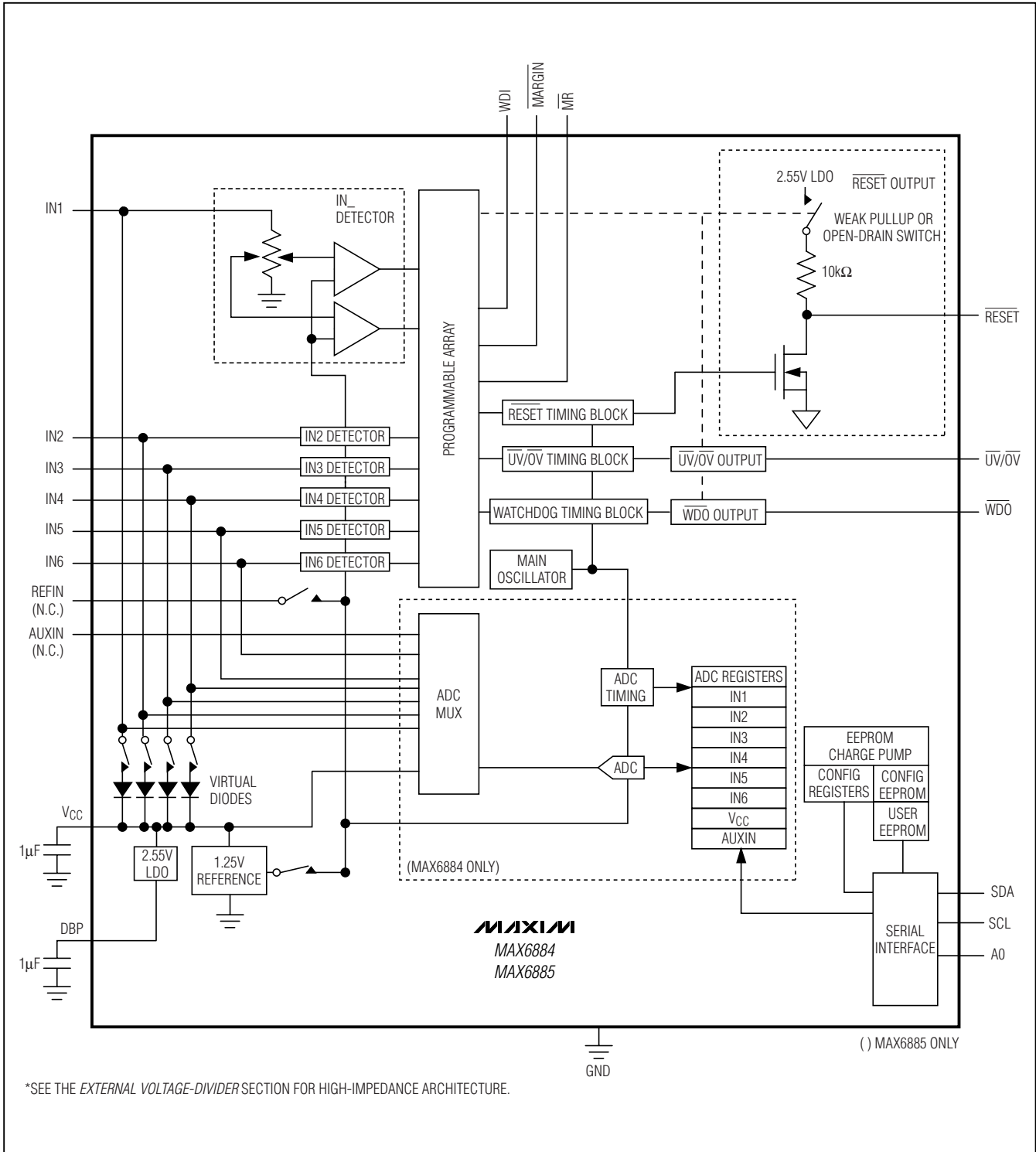


Figure 1. Top-Level Block Diagram

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Functional Diagram



*SEE THE EXTERNAL VOLTAGE-DIVIDER SECTION FOR HIGH-IMPEDANCE ARCHITECTURE.

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Powering the MAX6884/MAX6885

The MAX6884/MAX6885 derive power from the voltage-detector inputs: IN1–IN4 or through an externally supplied VCC. A virtual diode-ORing scheme selects the positive input that supplies power to the device (see the *Functional Diagram*). The highest input voltage on IN1–IN4 supplies power to the device. One of VIN1–VIN4 must be at least 2.7V to ensure proper operation.

Internal hysteresis ensures that the supply input that initially powered the device continues to power the device when multiple input voltages are within 50mV of each other.

VCC powers the analog circuitry and is the bypass connection for the MAX6884/MAX6885 internal supply. Bypass VCC to GND with a 1µF ceramic capacitor installed as close to the device as possible. The internal supply voltage, measured at VCC, equals the maximum of IN1–IN4. If VCC is externally supplied, VCC must be at least 200mV higher than any voltage applied to IN–IN4 and VCC must be brought up first. VCC always powers the device when all IN_ are factory set as “ADJ.” Do not use the internally generated VCC to provide power to external circuitry. Externally supply power through VCC. To externally supply power through VCC:

- 1) Apply a voltage to only one of VCC (2.7V to 5.5V) or IN1–IN4 (2.7V to 5.8V).
- 2) Program the internal/external VCC Power EEPROM at 96h, Bit[5] = 1 (see Table 2).
- 3) Power down the device.

Subsequent power-ups and software reboots require an externally supplied VCC to ensure the device is fully operational.

Table 2. Internal/External Vcc

| REGISTER ADDRESS | EEPROM MEMORY ADDRESS | BIT RANGE | DESCRIPTION |
|------------------|-----------------------|-----------|-----------------------------------------------|
| 16h | 96h | [5] | 1 = VCC Powered 0 = IN1–IN4 or VCC Powered |
| | | [2] | Not Used |
| | | [4] | Not Used |
| | | [6] | Not Used |

The MAX6884/MAX6885 also generate a digital supply voltage (DBP) for the internal logic circuitry and the EEPROM. Bypass DBP to GND with a 1µF ceramic capacitor installed as close to the device as possible. The nominal DBP output voltage is 2.55V. Do not use DBP to provide power to external circuitry.

ADC (MAX6884 Only)

An internal 10-bit ADC (MAX6884 only) converts voltages at IN1–IN4, AUXIN, and VCC through a multiplexer that automatically sequences through all inputs every 200ms. Registers 18h to 27h store the ADC data (see Table 3). Read the ADC data from the MAX6884 with the serial interface. The ADC has no effect on programmable outputs RESET, UV/OV, or WDO.

Inputs

The MAX6884/MAX6885 offer the following inputs: voltage-detector inputs IN1–IN4, auxiliary input AUXIN (MAX6884 only), manual reset input MR, margin input MARGIN, and reference input REFIN (MAX6884 only).

IN1–IN6

The MAX6884/MAX6885 offer six voltage-detector inputs: IN1–IN6. Each voltage-detector input offers a programmable primary undervoltage threshold and a secondary undervoltage/overvoltage threshold. Program thresholds from 0.5V to 3.05V in 10mV increments, 1.0V to 5.8V in 20mV increments, or from 0.1667V to 1.0167V in 3.3mV increments. Use the following equations to program thresholds in the appropriate registers:

$$X = \frac{V_{TH} - 1V}{0.02V}$$

for 1V to 5.8V range in 20mV increments (program bits R0Fh[5:0]).

$$X = \frac{V_{TH} - 0.5V}{0.01V}$$

for 0.5V to 3.05V range in 10mV increments (program bits R0Fh[5:0]).

$$X = \frac{V_{TH} - 0.1667V}{0.0033V}$$

for 0.1667V to 1.0167V in 3.3mV increments (see the *External Voltage-Divider* section).

where VTH is the desired threshold voltage and X is the decimal code for the desired threshold (see Table 4). To set a threshold for the 1V to 5.8V range, X must equal 240 or less. Set the secondary threshold for an undervoltage or overvoltage threshold by programming bits R0Eh[5:0]. To achieve thresholds in between the 10mV and 20mV steps or to monitor voltages higher than 5.8V, program a voltage-detector input for high impedance through bits R10h[5:0] and add a resistor voltage-divider (see the *External Voltage-Divider* section).

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Table 3. ADC Registers (MAX6884 Only)

| REGISTER ADDRESS | BIT RANGE | DESCRIPTION |
|------------------|-----------|------------------------------------------------|
| 18h | [7:0] | ADC IN1 Conversion Result (8 MSBs) |
| 19h | [1:0] | ADC IN1 Conversion Result (2 LSBs) |
| | [7:2] | Not Used |
| 1Ah | [7:0] | ADC IN2 Conversion Result (8 MSBs) |
| 1Bh | [1:0] | ADC IN2 Conversion Result (2 LSBs) |
| | [7:2] | Not Used |
| 1Ch | [7:0] | ADC IN3 Conversion Result (8 MSBs) |
| 1Dh | [1:0] | ADC IN3 Conversion Result (2 LSBs) |
| | [7:2] | Not Used |
| 1Eh | [7:0] | ADC IN4 Conversion Result (8 MSBs) |
| 1Fh | [1:0] | ADC IN4 Conversion Result (2 LSBs) |
| | [7:2] | Not Used |
| 20h | [7:0] | ADC IN5 Conversion Result (8 MSBs) |
| 21h | [1:0] | ADC IN5 Conversion Result (2 LSBs) |
| | [7:2] | Not Used |
| 22h | [7:0] | ADC IN6 Conversion Result (8 MSBs) |
| 23h | [1:0] | ADC IN6 Conversion Result (2 LSBs) |
| | [7:2] | Not Used |
| 24h | [7:0] | ADC AUXIN Conversion Result (8 MSBs) |
| 25h | [1:0] | ADC AUXIN Conversion Result (2 LSBs) |
| | [7:2] | Not Used |
| 26h | [7:0] | ADC V _{CC} Conversion Result (8 MSBs) |
| 27h | [1:0] | ADC V _{CC} Conversion Result (2 LSBs) |
| | [7:2] | Not Used |

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Table 4. IN1–IN6 Threshold Register Settings

| REGISTER ADDRESS | EEPROM MEMORY ADDRESS | BIT RANGE | DESCRIPTION |
|------------------|-----------------------|-----------|---------------------------------------------------------------------------------------------------------|
| 00h | 80h | [7:0] | IN1 Primary Undervoltage Detector Threshold (see equations in the <i>IN1–IN6</i> section) |
| 01h | 81h | [7:0] | IN2 Primary Undervoltage Detector Threshold |
| 02h | 82h | [7:0] | IN3 Primary Undervoltage Detector Threshold |
| 03h | 83h | [7:0] | IN4 Primary Undervoltage Detector Threshold |
| 04h | 84h | [7:0] | IN5 Primary Undervoltage Detector Threshold |
| 05h | 85h | [7:0] | IN6 Primary Undervoltage Detector Threshold |
| 06h | 86h | [7:0] | IN1 Secondary Undervoltage/Overvoltage Detector Threshold (see equations in the <i>IN1–IN6</i> section) |
| 07h | 87h | [7:0] | IN2 Secondary Undervoltage/Overvoltage Detector Threshold |
| 08h | 88h | [7:0] | IN3 Secondary Undervoltage/Overvoltage Detector Threshold |
| 09h | 89h | [7:0] | IN4 Secondary Undervoltage/Overvoltage Detector Threshold |
| 0Ah | 8Ah | [7:0] | IN5 Secondary Undervoltage/Overvoltage Detector Threshold |
| 0Bh | 8Bh | [7:0] | IN6 Secondary Undervoltage/Overvoltage Detector Threshold |
| 0Eh | 8Eh | [0] | IN1 Secondary Undervoltage or Overvoltage Selection 0 = Undervoltage 1 = Overvoltage |
| | | [1] | IN2 Secondary Undervoltage or Overvoltage Selection |
| | | [2] | IN3 Secondary Undervoltage or Overvoltage Selection |
| | | [3] | IN4 Secondary Undervoltage or Overvoltage Selection |
| | | [4] | IN5 Secondary Undervoltage or Overvoltage Selection |
| | | [5] | IN6 Secondary Undervoltage or Overvoltage Selection |
| | | [7:6] | Not Used |
| 0Fh | 8Fh | [0] | IN1 Voltage Threshold Range 0 = 1V to 5.8V (20mV steps) 1 = 0.5V to 3.05V (10mV steps) |
| | | [1] | IN2 Voltage Threshold Range |
| | | [2] | IN3 Voltage Threshold Range |
| | | [3] | IN4 Voltage Threshold Range |
| | | [4] | IN5 Voltage Threshold Range |
| | | [5] | IN6 Voltage Threshold Range |
| | | [7:6] | Not Used |
| 10h | 90h | [0] | IN1 Input Impedance 0 = Normal Mode 1 = High-Z Mode (connect external resistor voltage-divider) |
| | | [1] | IN2 Input Impedance |
| | | [2] | IN3 Input Impedance |
| | | [3] | IN4 Input Impedance |
| | | [4] | IN5 Input Impedance |
| | | [5] | IN6 Input Impedance |
| | | [7:6] | Not Used |

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External Voltage-Divider

To achieve thresholds from 0.1667V to 1.0167V in 3.3mV increments, program the respective input voltage detector for high impedance and use an external voltage-divider (see Figure 2). Set voltage-detector inputs for high impedance by programming bits R10h[5:0]. Design the resistor voltage-divider to scale the input voltage to between 0.1667V and 1.0167V at the input of the device. In this way, voltages higher than 5.8V and in between the 10mV and 20mV steps can be monitored. Program R00h through R0Eh to adjust the thresholds between 0.1667V and 1.0167V in 3.3mV steps.

AUXIN (MAX6884 Only)

The AUXIN high-impedance analog input is intended to monitor additional system voltages not required for reset purposes. The internal 10-bit ADC converts the voltage at AUXIN and stores the data in the ADC registers (see Table 3). AUXIN does not affect any of the programmable outputs. The AUXIN input accepts power-supply voltages or other system voltages scaled to the 1.25V ADC input voltage range.

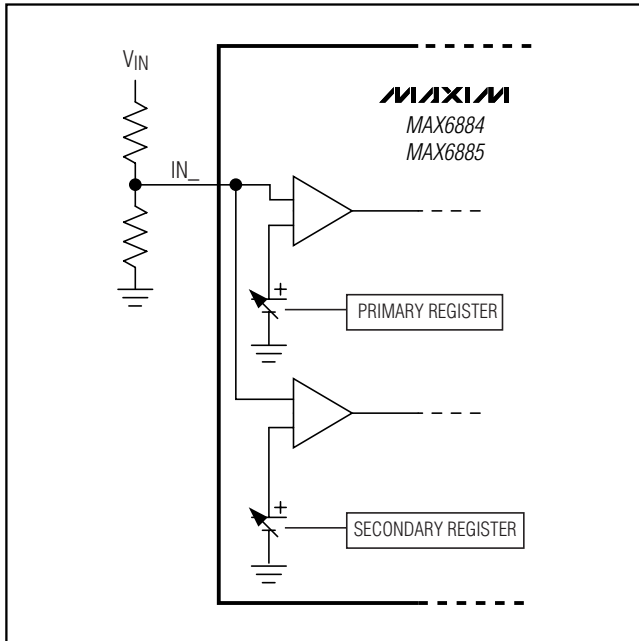


Figure 2. External Voltage-Divider Architecture

MR

Program $\overline{\text{RESET}}$ and/or $\overline{\text{UV/OV}}$ to assert when manual reset input $\overline{\text{MR}}$ is brought low (see Tables 5 and 6). Outputs programmed to assert when $\overline{\text{MR}}$ is brought low remain asserted after $\overline{\text{MR}}$ is brought high for their respective programmed timeout periods. An internal 10 μA current source pulls $\overline{\text{MR}}$ to V_{DBP} . Leave $\overline{\text{MR}}$ unconnected or connect to DBP if unused.

MARGIN

$\overline{\text{MARGIN}}$ allows system-level testing while power supplies exceed the normal ranges. Drive $\overline{\text{MARGIN}}$ low to hold the programmable outputs in their existing state while system-level testing occurs. Leave $\overline{\text{MARGIN}}$ unconnected or connect to DBP if unused. An internal 10 μA current source pulls $\overline{\text{MARGIN}}$ to V_{DBP} . The internal ADC continues to convert voltages while $\overline{\text{MARGIN}}$ is low. The state of each programmable output does not change while $\overline{\text{MARGIN}} = \text{GND}$. $\overline{\text{MARGIN}}$ overrides $\overline{\text{MR}}$ if both are asserted at the same time.

REFIN (MAX6884 Only)

The MAX6884/MAX6885 feature an internal 1.25V voltage reference. The voltage reference sets the threshold of the voltage detectors and provides a reference voltage for the internal ADC. Program the MAX6884 to use an internal or external reference by programming bit R16h[7] (see Table 5). Leave REFIN unconnected when using the internal reference. REFIN accepts an external reference in the 1.225V to 1.275V range.

Table 5. Internal/External Reference

| REGISTER ADDRESS | EEPROM MEMORY ADDRESS | BIT RANGE | DESCRIPTION |
|------------------|-----------------------|-----------|----------------------------------------------------------------|
| 16h | 96h | [7] | 1 = Enable External Reference 0 = Enable Internal Reference |

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Programmable Outputs

The MAX6884/MAX6885 feature three programmable active-low outputs: $\overline{\text{RESET}}$, $\overline{\text{UV/OV}}$, and $\overline{\text{WDO}}$. Program each output for open-drain or weak pullup. An internal $10\text{k}\Omega$ resistor connected from each output to a 2.55V internal LDO provides a weak pullup. During power-up, the outputs are held low for $1\text{V} < V_{\text{CC}} < V_{\text{UVLO}}$. Any output programmed to depend on no condition always remains in its active state. For example, if the state of $\overline{\text{UV/OV}}$ is not programmed to depend on any condition, $\overline{\text{UV/OV}}$ will always be low. Figure 3 shows a timing diagram of a typical relationship between a monitored input voltage and outputs $\overline{\text{RESET}}$ and $\overline{\text{UV/OV}}$. $\overline{\text{RESET}}$ and $\overline{\text{UV/OV}}$ are a function of only IN1 .

Program $\overline{\text{RESET}}$ to depend on $\overline{\text{MR}}$, $\overline{\text{UV/OV}}$, $\overline{\text{WDO}}$, or any programmable primary voltage-detector input (see

Table 6). As an example, $\overline{\text{RESET}}$ may depend on the IN3 primary undervoltage threshold, $\overline{\text{MR}}$, $\overline{\text{UV/OV}}$, and $\overline{\text{WDO}}$. Write 1's to $\text{R11h}[1:0]$, $\text{R11h}[4]$, and $\text{R12h}[7]$ to configure as indicated. IN3 must be above the undervoltage threshold, $\overline{\text{MR}}$ must be high, $\overline{\text{UV/OV}}$ must be deasserted, and $\overline{\text{WDO}}$ must be deasserted to be a logic "1," then $\overline{\text{RESET}}$ deasserts. The logic state of $\overline{\text{RESET}}$, in this example, is equivalent to the logical statement:

$$\text{IN3} \cdot \overline{\text{MR}} \cdot \overline{\text{UV/OV}} \cdot \overline{\text{WDO}}$$

$\overline{\text{RESET}}$ remains low for its programmed timeout period (t_{RP}) after all assertion-causing conditions are removed. Program timeout periods for $\overline{\text{RESET}}$ from $25\mu\text{s}$ to 1600ms (see Table 6). Configure $\overline{\text{RESET}}$ for open-drain or weak pullup through bit $\text{R12h}[0]$.

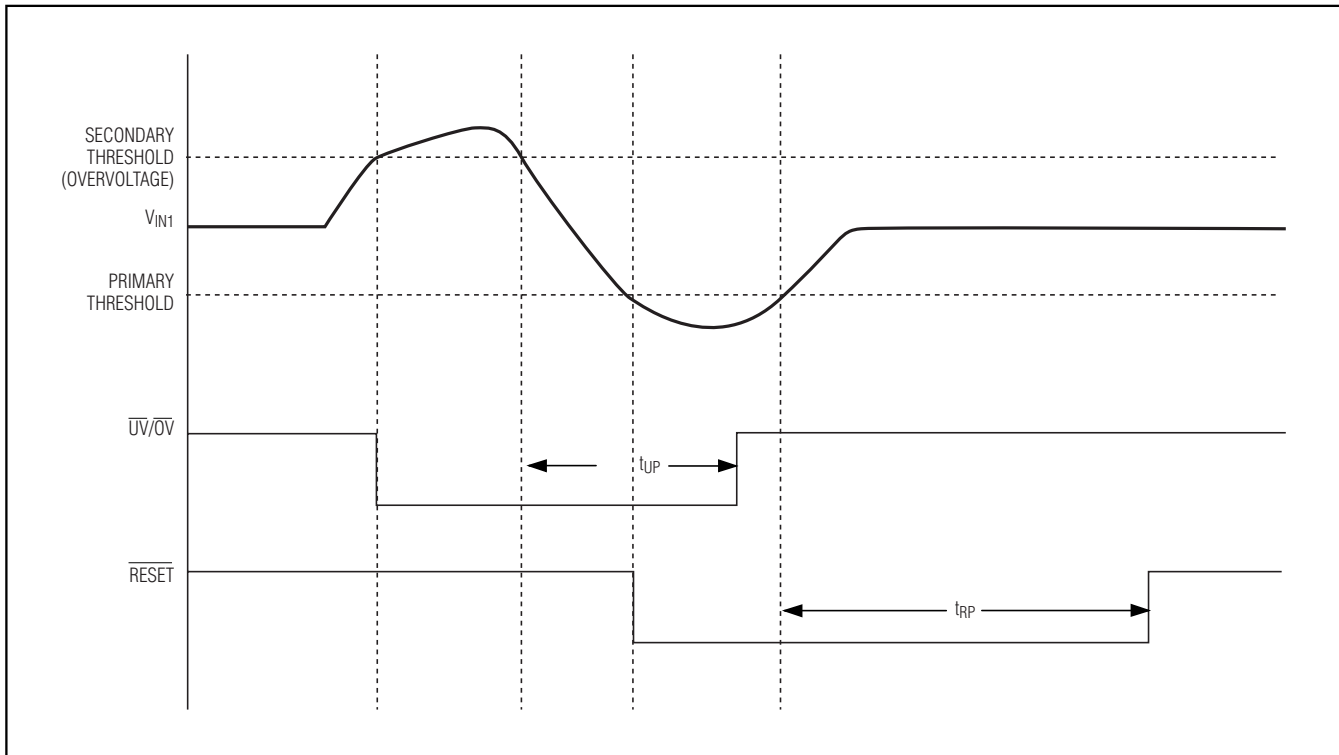


Figure 3. Output Timing Diagram

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Table 6. Programmable $\overline{\text{RESET}}$ Options

| REGISTER ADDRESS | EEPROM MEMORY ADDRESS | BIT RANGE | DESCRIPTION |
|------------------|-----------------------|-----------|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| 11h | 91h | [0] | 1 = $\overline{\text{RESET}}$ Assertion Depends on $\overline{\text{MR}}$ 0 = $\overline{\text{RESET}}$ Assertion Does Not Depend on $\overline{\text{MR}}$ |
| | | [1] | 1 = $\overline{\text{RESET}}$ Assertion Depends on $\overline{\text{UV/OV}}$ 0 = $\overline{\text{RESET}}$ Assertion Does Not Depend on $\overline{\text{UV/OV}}$ |
| | | [2] | 1 = $\overline{\text{RESET}}$ Assertion Depends on IN1 Primary Undervoltage 0 = $\overline{\text{RESET}}$ Assertion Does Not Depend on IN1 Primary Undervoltage |
| | | [3] | 1 = $\overline{\text{RESET}}$ Assertion Depends on IN2 Primary Undervoltage 0 = $\overline{\text{RESET}}$ Assertion Does Not Depend on IN2 Primary Undervoltage |
| | | [4] | 1 = $\overline{\text{RESET}}$ Assertion Depends on IN3 Primary Undervoltage 0 = $\overline{\text{RESET}}$ Assertion Does Not Depend on IN3 Primary Undervoltage |
| | | [5] | 1 = $\overline{\text{RESET}}$ Assertion Depends on IN4 Primary Undervoltage 0 = $\overline{\text{RESET}}$ Assertion Does Not Depend on IN4 Primary Undervoltage |
| | | [6] | 1 = $\overline{\text{RESET}}$ Assertion Depends on IN5 Primary Undervoltage 0 = $\overline{\text{RESET}}$ Assertion Does Not Depend on IN5 Primary Undervoltage |
| | | [7] | 1 = $\overline{\text{RESET}}$ Assertion Depends on IN6 Primary Undervoltage 0 = $\overline{\text{RESET}}$ Assertion Does Not Depend on IN6 Primary Undervoltage |
| 12h | 92h | [0] | $\overline{\text{RESET}}$ Output Type 1 = Open Drain 0 = Weak Pullup |
| | | [3:1] | $\overline{\text{RESET}}$ Deassertion Time Delay 000 = 25 μ s 001 = 1.56ms 010 = 6.25ms 011 = 25ms 100 = 50ms 101 = 200ms 110 = 400ms 111 = 1600ms |
| | | [6:4] | Not Used |
| | | [7] | 1 = $\overline{\text{RESET}}$ Assertion Depends on $\overline{\text{WDO}}$ Assertion 0 = $\overline{\text{RESET}}$ Assertion Does Not Depend on $\overline{\text{WDO}}$ Assertion |

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Program $\overline{UV/OV}$ to depend on \overline{MR} , \overline{RESET} , or any programmable secondary voltage detector input (see Table 7). As an example, $\overline{UV/OV}$ may depend on the IN1 secondary overvoltage threshold, \overline{MR} , and \overline{RESET} . Write 1's to R13h[2:0] and R0Eh[1] to configure as indicated. IN1 must be below the overvoltage threshold, \overline{MR} must be high, and \overline{RESET} must be deasserted to be a logic "1,"

then $\overline{UV/OV}$ deasserts. The logic state of $\overline{UV/OV}$, in this example, is equivalent to the logical statement:

$$IN1 \cdot \overline{MR} \cdot \overline{RESET}$$

$\overline{UV/OV}$ remains low for its programmed time delay (t_{UP}) after all assertion-causing conditions are removed. Program time delays for $\overline{UV/OV}$ from 25 μ s to 1600ms (see Table 7). Configure $\overline{UV/OV}$ for open drain or weak pullup through bit R14h[0].

Table 7. Programmable $\overline{UV/OV}$ Options

| REGISTER ADDRESS | EEPROM MEMORY ADDRESS | BIT RANGE | DESCRIPTION |
|------------------|-----------------------|-----------|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| 13h | 93h | [0] | 1 = $\overline{UV/OV}$ Assertion Depends on \overline{MR} 0 = $\overline{UV/OV}$ Assertion Does Not Depend on \overline{MR} |
| | | [1] | 1 = $\overline{UV/OV}$ Assertion Depends on \overline{RESET} 0 = $\overline{UV/OV}$ Assertion Does Not Depend on \overline{RESET} |
| | | [2] | 1 = $\overline{UV/OV}$ Assertion Depends on IN1 Secondary Undervoltage/Overvoltage Threshold 0 = $\overline{UV/OV}$ Assertion Does Not Depend on IN1 Secondary Undervoltage/Overvoltage Threshold |
| | | [3] | 1 = $\overline{UV/OV}$ Assertion Depends on IN2 Secondary Undervoltage/Overvoltage Threshold 0 = $\overline{UV/OV}$ Assertion Does Not Depend on IN2 Secondary Undervoltage/Overvoltage Threshold |
| | | [4] | 1 = $\overline{UV/OV}$ Assertion Depends on IN3 Secondary Undervoltage/Overvoltage Threshold 0 = $\overline{UV/OV}$ Assertion Does Not Depend on IN3 Secondary Undervoltage/Overvoltage Threshold |
| | | [5] | 1 = $\overline{UV/OV}$ Assertion Depends on IN4 Secondary Undervoltage/Overvoltage Threshold 0 = $\overline{UV/OV}$ Assertion Does Not Depend on IN4 Secondary Undervoltage/Overvoltage Threshold |
| | | [6] | 1 = $\overline{UV/OV}$ Assertion Depends on IN5 Secondary Undervoltage/Overvoltage Threshold 0 = $\overline{UV/OV}$ Assertion Does Not Depend on IN5 Secondary Undervoltage/Overvoltage Threshold |
| | | [7] | 1 = $\overline{UV/OV}$ Assertion Depends on IN6 Secondary Undervoltage/Overvoltage Threshold 0 = $\overline{UV/OV}$ Assertion Does Not Depend on IN6 Secondary Undervoltage/Overvoltage Threshold |
| 14h | 94h | [0] | $\overline{UV/OV}$ Output Type 1 = Open Drain 0 = Weak Pullup |
| | | [3:1] | $\overline{UV/OV}$ Deassertion Time Delay 000 = 25 μ s 001 = 1.56ms 010 = 6.25ms 011 = 25ms 100 = 50ms 101 = 200ms 110 = 400ms 111 = 1600ms |
| | | [7:4] | Unused |

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The MAX6884/MAX6885 offer a separate output for the watchdog timer system. \overline{WDO} is active low and programmable for open-drain or weak pullup. Program \overline{WDO} to assert \overline{RESET} when the watchdog timer expires. See the *Configuring the Watchdog Timer* section for a complete description of the watchdog timer system.

Configuring the Watchdog Timer

A watchdog timer monitors microprocessor (μP) software execution for a stalled condition and resets the μP

if it stalls. The output of the watchdog timer (\overline{WDO}) connects to the reset input or a nonmaskable interrupt of the μP . Program R15h to configure the watchdog timer functions (see Table 8). The watchdog timer features independent initial and normal watchdog timeout periods between 6.25ms and 102.4s (see Figure 4).

The initial watchdog timeout period (t_{WDI}) is active immediately after power-up, after a reset event takes place, after enabling the watchdog timer, or after the watchdog timer expires. The initial watchdog timeout period allows the μP to perform its initialization process.

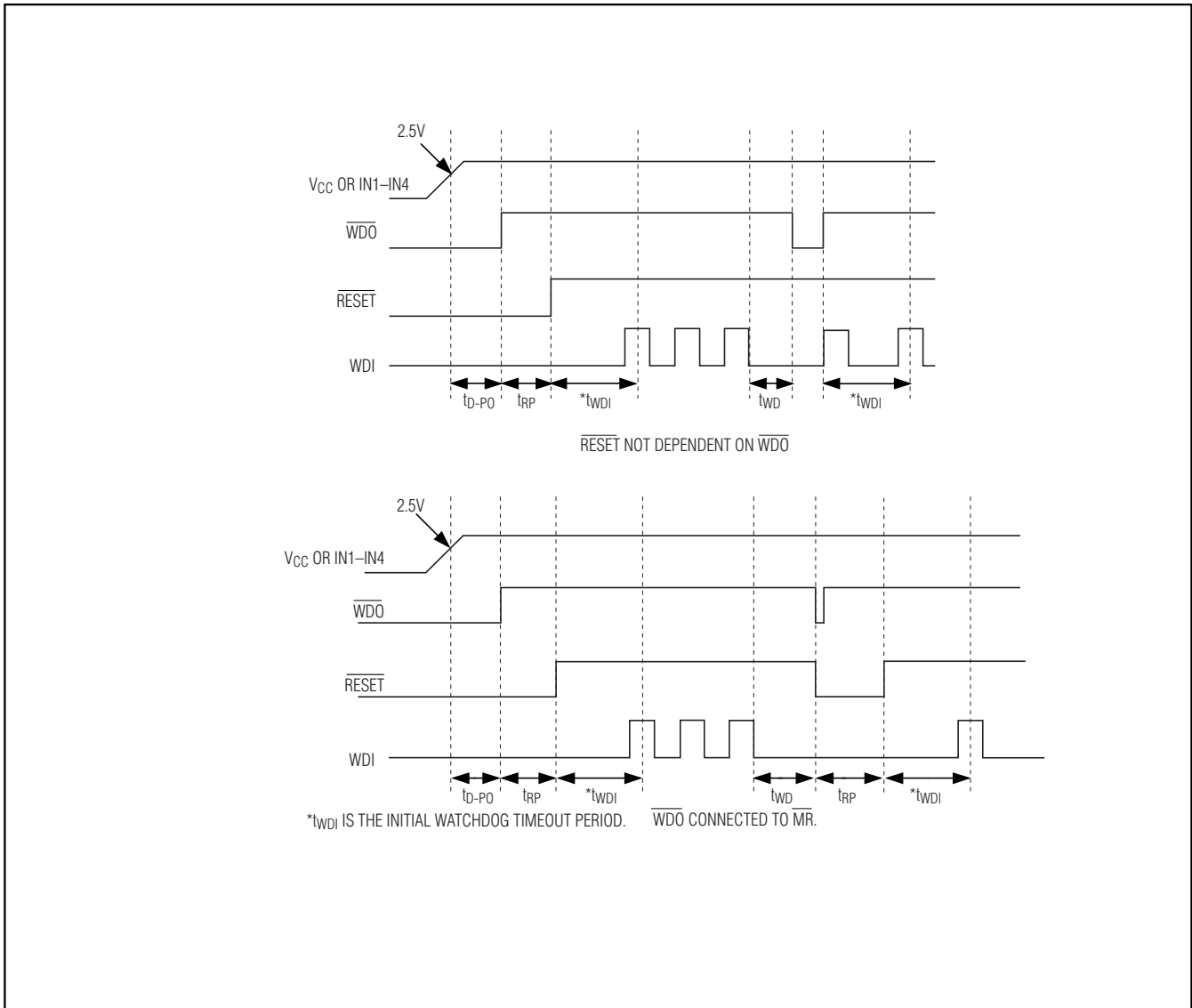


Figure 4. Watchdog Timing Diagrams

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The normal watchdog timeout period (tWD) is active after the initial watchdog timer and continues to be active until the watchdog timer expires. The normal watchdog timeout period monitors a pulsed output of the μ P that indicates when normal processor behavior occurs. If no pulse occurs during the normal watchdog timeout period, this indicates that the processor has stopped operating or is stuck in an infinite execution loop and \overline{WDO} asserts. Disable or enable the watchdog timer through R15h[7].

If \overline{RESET} is programmed to depend on \overline{WDO} and the watchdog timer expires, \overline{WDO} will assert for a short pulse, just long enough to assert \overline{RESET} (typically less

than 5 μ s; see Figure 4). If \overline{WDO} is not programmed to depend on \overline{RESET} and the watchdog timer expires, \overline{WDO} will remain asserted until a low-to-high or high-to-low edge occurs on WDI. Program \overline{WDO} for open-drain or weak pullup (see Table 8).

Fault Register

Registers 28h to 2Ah store all fault conditions including undervoltage, overvoltage, and watchdog timer faults (see Table 9). Fault registers are read-only and lose contents upon power removal. The first read command from the fault registers after power-up gives invalid data. Reading the fault register clears all fault flags in the register.

Table 8. Watchdog Register Settings

| REGISTER ADDRESS | EEPROM MEMORY ADDRESS | BIT RANGE | DESCRIPTION |
|------------------|-----------------------|-----------|--------------------------------------------------------------------------------------------------------------------------------------------------|
| 15h | 95h | [0] | \overline{WDO} Output Type 1 = Open Drain 0 = Weak Pullup |
| | | [3:1] | Initial Watchdog Timeout 000 = 6.25ms 001 = 25ms 010 = 100ms 011 = 400ms 100 = 1.6s 101 = 6.4ms 110 = 25.6s 111 = 102.4s |
| | | [6:4] | Normal Watchdog Timeout 000 = 6.25ms 001 = 25ms 010 = 100ms 011 = 400ms 1100 = 1.6s 101 = 6.4ms 110 = 25.6s 111 = 102.4s |
| | | [7] | Watchdog Enable 1 = Enabled 0 = Disabled |

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Table 9. Fault Registers (28h–2Ah)

| REGISTER ADDRESS | BIT RANGE | DESCRIPTION |
|------------------|-----------|------------------------------------------------------------|
| 28h | [0] | 1 = IN1 Voltage Falls Below Primary Undervoltage Threshold |
| | [1] | 1 = IN2 Voltage Falls Below Primary Undervoltage Threshold |
| | [2] | 1 = IN3 Voltage Falls Below Primary Undervoltage Threshold |
| | [3] | 1 = IN4 Voltage Falls Below Primary Undervoltage Threshold |
| | [4] | 1 = IN5 Voltage Falls Below Primary Undervoltage Threshold |
| | [5] | 1 = IN6 Voltage Falls Below Primary Undervoltage Threshold |
| | [7:6] | Unused |
| 29h | [0] | 1 = IN1* Voltage Falls Below Secondary Threshold |
| | [1] | 1 = IN2* Voltage Falls Below Secondary Threshold |
| | [2] | 1 = IN3* Voltage Falls Below Secondary Threshold |
| | [3] | 1 = IN4* Voltage Falls Below Secondary Threshold |
| | [4] | 1 = IN5* Voltage Falls Below Secondary Threshold |
| | [5] | 1 = IN6* Voltage Falls Below Secondary Threshold |
| | [7:6] | Unused |
| 2Ah | [0] | 1 = $\overline{UV/OV}$ Has Been Asserted |
| | [1] | 1 = \overline{RESET} Has Been Asserted |
| | [6:2] | Unused |
| | [7] | 1 = \overline{WDO} Has Been Asserted |

*Does not matter if set as undervoltage or overvoltage.

Configuration Lock

Lock the configuration register bank and configuration EEPROM contents after initial programming by setting the lock bit high (see Table 10). Locking the configuration prevents write operations to configuration EEPROM and configuration registers except the configuration lock bit. Set the lock bit to 0 to reconfigure the device.

Write Disable

A unique write disable feature protects the MAX6884/MAX6885 from inadvertent user EEPROM writes. As input voltages that power the serial interface, a μ P, or any other writing devices fall, unintentional data may be written onto the data bus. The user EEPROM write-disable function (see Table 11) ensures that unintentional data does not corrupt the MAX6884/MAX6885 user EEPROM data.

Table 10. Configuration Lock Bit

| REGISTER ADDRESS | EEPROM MEMORY ADDRESS | BIT RANGE | DESCRIPTION |
|------------------|-----------------------|-----------|--------------------------------------------------------|
| 16h | 96h | [3] | 1 = Configuration Locked 0 = Configuration Unlocked |

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Table 11. User EEPROM Write Disable Bits

| REGISTER ADDRESS | EEPROM MEMORY ADDRESS | BIT RANGE | DESCRIPTION |
|------------------|-----------------------|-----------|-------------------------------------------------------------------------------------------------------------------------------------------------|
| 16h | 96h | [1] | 1 = User EEPROM Writes Disabled on $\overline{\text{RESET}}$ Assertion 0 = User EEPROM Writes Enabled on $\overline{\text{RESET}}$ Assertion |
| | | [0] | 1 = User EEPROM Writes Disabled on $\overline{\text{UV/OV}}$ Assertion 0 = User EEPROM Writes Enabled on $\overline{\text{UV/OV}}$ Assertion |

Configuration Register Bank and EEPROM

The configuration registers can be directly modified by the serial interface without modifying the EEPROM after the power-up procedure terminates and the configuration EEPROM data has been loaded into the configuration register bank. Use the write byte or block write protocols to write directly to the configuration registers. Changes to the configuration registers take effect immediately and are lost upon power removal. At device power-up, the register bank loads configuration data from the EEPROM. Configuration data may be directly altered in the register bank during application development, allowing maximum flexibility. Transfer the new configuration data, byte by byte, to the configuration EEPROM with the write byte protocol. The next device power-up or software reboot automatically loads the new configuration. See Table 12 for a complete register map.

Configuration EEPROM

The configuration EEPROM addresses range from 80h to 97h. Write data to the configuration EEPROM to set up the MAX6884/MAX6885 automatically upon power-up. Data transfers from the configuration EEPROM to the

configuration registers when V_{CC} exceeds $UVLO$ during power-up or after a software reboot. After V_{CC} exceeds $UVLO$, an internal 1MHz clock starts after a 5 μ s delay, and data transfer begins. Data transfer disables access to the configuration registers and EEPROM. The data transfer from EEPROM to configuration registers takes 2.5ms maximum. Read configuration EEPROM and configuration register data any time after power-up or software reboot. Write commands to the configuration EEPROM and configuration registers are allowed at any time after power-up or software reboot unless the configuration lock bit is set (see Table 10). When the configuration lock bit is set, all write access to EEPROM and registers is disabled with the exception of the configuration lock bit itself. The maximum cycle time to write a single byte in EEPROM is 11ms (max).

User EEPROM

The 512-bit user EEPROM addresses range from 40h to 7Fh (see Figure 11). Store revision data, board revision data, or other data in these registers. The maximum cycle time to write a single byte is 11ms (max). Disable writes to the user EEPROM during $\overline{\text{RESET}}$ or $\overline{\text{UV/OV}}$ assertion by programming bit R16h[1] or R16h[0], respectively (see Table 11).

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Table 12. Register Map

| REGISTER ADDRESS | EEPROM MEMORY ADDRESS | READ/ WRITE | DESCRIPTION |
|------------------|-----------------------|-------------|------------------------------------------------------------------------------------------------------------------------------------------------------|
| 00h | 80h | R/W | IN1 Primary Undervoltage Detector Threshold (Table 4) |
| 01h | 81h | R/W | IN2 Primary Undervoltage Detector Threshold (Table 4) |
| 02h | 82h | R/W | IN3 Primary Undervoltage Detector Threshold (Table 4) |
| 03h | 83h | R/W | IN4 Primary Undervoltage Detector Threshold (Table 4) |
| 04h | 84h | R/W | IN5 Primary Undervoltage Detector Threshold (Table 4) |
| 05h | 85h | R/W | IN6 Primary Undervoltage Detector Threshold (Table 4) |
| 06h | 86h | R/W | IN1 Secondary Undervoltage/Overvoltage Detector Threshold (Table 4) |
| 07h | 87h | R/W | IN2 Secondary Undervoltage/Overvoltage Detector Threshold (Table 4) |
| 08h | 88h | R/W | IN3 Secondary Undervoltage/Overvoltage Detector Threshold (Table 4) |
| 09h | 89h | R/W | IN4 Secondary Undervoltage/Overvoltage Detector Threshold (Table 4) |
| 0Ah | 8Ah | R/W | IN5 Secondary Undervoltage/Overvoltage Detector Threshold (Table 4) |
| 0Bh | 8Bh | R/W | IN6 Secondary Undervoltage/Overvoltage Detector Threshold (Table 4) |
| 0Ch | 8Ch | R | Unused. Returns 0h when read. |
| 0Dh | 8Dh | R | Unused. Returns 0h when read. |
| 0Eh | 8Eh | R/W | Secondary Threshold Undervoltage/Overvoltage Selection (Table 4) |
| 0Fh | 8Fh | R/W | Threshold Range Selection (Table 4) |
| 10h | 90h | R/W | High-Z Mode Selection (Table 4) |
| 11h | 91h | R/W | $\overline{\text{RESET}}$ Dependency Selection (Table 6) |
| 12h | 92h | R/W | $\overline{\text{RESET}}$ Output Type, Timeout Period, and $\overline{\text{WDO}}$ Dependency Selection (Table 6) |
| 13h | 93h | R/W | $\overline{\text{UV/OV}}$ Dependency Selection (Table 7) |
| 14h | 94h | R/W | $\overline{\text{UV/OV}}$ Output Type and Timeout Period (Table 7) |
| 15h | 95h | R/W | Watchdog Initial and Normal Timeout Selection (Table 8) |
| 16h | 96h | R/W | Internal/External V_{CC} (Table 2), Internal/External Reference (Table 5), Configuration Lock Bit (Table 10), User EEPROM Write Disable (Table 11) |
| 17h | 97h | R | Unused (Table 5) |
| 18h | — | R | ADC Conversion Data for IN1 (8 MSBs) (Table 3) |
| 19h | — | R | ADC Conversion Data for IN1 (2 LSBs) (Table 3) |
| 1Ah | — | R | ADC Conversion Data for IN2 (8 MSBs) (Table 3) |
| 1Bh | — | R | ADC Conversion Data for IN2 (2 LSBs) (Table 3) |
| 1Ch | — | R | ADC Conversion Data for IN3 (8 MSBs) (Table 3) |
| 1Dh | — | R | ADC Conversion Data for IN3 (2 LSBs) (Table 3) |
| 1Eh | — | R | ADC Conversion Data for IN4 (8 MSBs) (Table 3) |
| 1Fh | — | R | ADC Conversion Data for IN4 (2 LSBs) (Table 3) |
| 20h | — | R | ADC Conversion Data for IN5 (8 MSBs) (Table 3) |
| 21h | — | R | ADC Conversion Data for IN5 (2 LSBs) (Table 3) |
| 22h | — | R | ADC Conversion Data for IN6 (8 MSBs) (Table 3) |
| 23h | — | R | ADC Conversion Data for IN6 (2 LSBs) (Table 3) |
| 24h | — | R | ADC Conversion Data for AUXIN (8 MSBs) (Table 3) |

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Table 12. Register Map (continued)

| REGISTER ADDRESS | EEPROM MEMORY ADDRESS | READ/ WRITE | DESCRIPTION |
|------------------|-----------------------|-------------|---------------------------------------------------------------------------------------------------------------|
| 25h | — | R | ADC Conversion Data for AUXIN (2 LSBs) (Table 3) |
| 26h | — | R | ADC Conversion Data for V _{CC} (8 MSBs) (Table 3) |
| 27h | — | R | ADC Conversion Data for V _{CC} (2 LSBs) (Table 3) |
| 28h | — | R | Fault Flags for Primary Voltage Detectors (Table 9) |
| 29h | — | R | Fault Flags for Secondary Voltage Detectors (Table 9) |
| 2Ah | — | R | Fault Flags for $\overline{\text{RESET}}$, $\overline{\text{UV/OV}}$, and $\overline{\text{WDO}}$ (Table 9) |

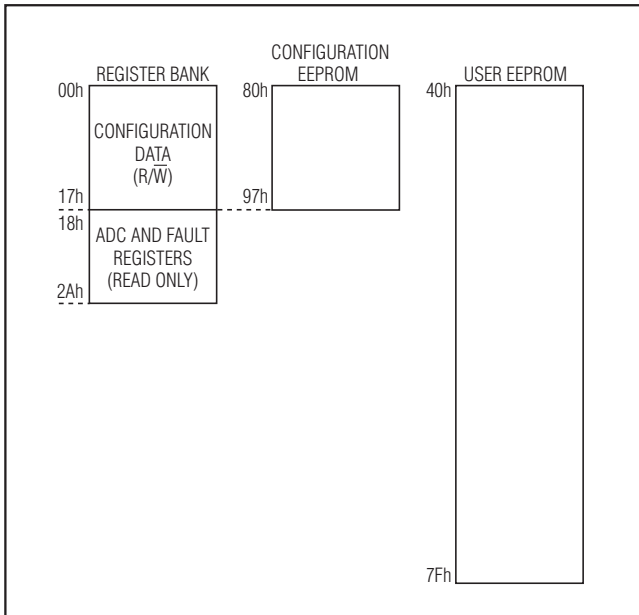


Figure 5. Memory Map

Configuring the MAX6884/MAX6885

The MAX6884/MAX6885 factory-default configuration sets all registers to 00h except for bits R91h[0], R92h[0], R93h[0], R94h[0], R95h[0], which are set to 1. This configuration sets all three programmable outputs ($\overline{\text{RESET}}$, $\overline{\text{UV/OV}}$, $\overline{\text{WDO}}$) as open drain, and $\overline{\text{RESET}}$ and $\overline{\text{UV/OV}}$ dependent on $\overline{\text{MR}}$ (putting all outputs into high-

impedance states until the device is reconfigured by the user). Each device requires configuration before full power is applied to the system. Below is a general step-by-step procedure for programming the MAX6884/MAX6885:

- 1) Apply a supply voltage to IN1–IN4 or V_{CC}, depending on the programmed configuration (see the *Powering the MAX6884/MAX6885* section). The applied voltage must be 2.7V or higher.
- 2) Transmit data through the serial interface. Write to the configuration registers first to ensure the device is configured properly (see the *Write Byte* and *Block Write* sections).
- 3) Use the read word protocol to read back the data from the configuration registers to verify the data was written (see the *Receive Byte* and *Block Read* sections).
- 4) Write the same data written to the configuration registers to the appropriate configuration EEPROM registers. After completing EEPROM configuration, apply full power to the system to begin normal operation. The nonvolatile EEPROM stores the configuration information while power is off.

Software Reboot

A software reboot restores the EEPROM configuration to the volatile registers without cycling the power supplies. Use the send byte command with data byte C4h to initiate a software reboot. The 2.5ms (max) power-up delay also applies after a software reboot.

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SMBus/I²C-Compatible Serial Interface

The MAX6884/MAX6885 feature an I²C/SMBus-compatible 2-wire serial interface consisting of a serial data line (SDA) and a serial clock line (SCL). SDA and SCL facilitate bidirectional communication between the MAX6884/MAX6885 and the master device at clock rates up to 400kHz. Figure 6 shows the 2-wire interface timing diagram. The MAX6884/MAX6885 are transmit/receive slave-only devices, relying upon a master device to generate a clock signal. The master device (typically a microcontroller) initiates data transfer on the bus and generates SCL to permit that transfer.

A master device communicates to the MAX6884/MAX6885 by transmitting the proper address followed by command and/or data words. Each transmit sequence is

framed by a START (S) or REPEATED START (SR) condition and a STOP (P) condition. Each word transmitted over the bus is 8 bits long and is always followed by an acknowledge pulse.

SCL is a logic input, while SDA is an open-drain input/output. SCL and SDA both require external pullup resistors to generate the logic-high voltage. Use 4.7kΩ resistors for most applications.

Bit Transfer

Each clock pulse transfers one data bit. The data on SDA must remain stable while SCL is high (see Figure 7), otherwise the MAX6884/MAX6885 register a START or STOP condition (see Figure 8) from the master. SDA and SCL idle high when the bus is not busy.

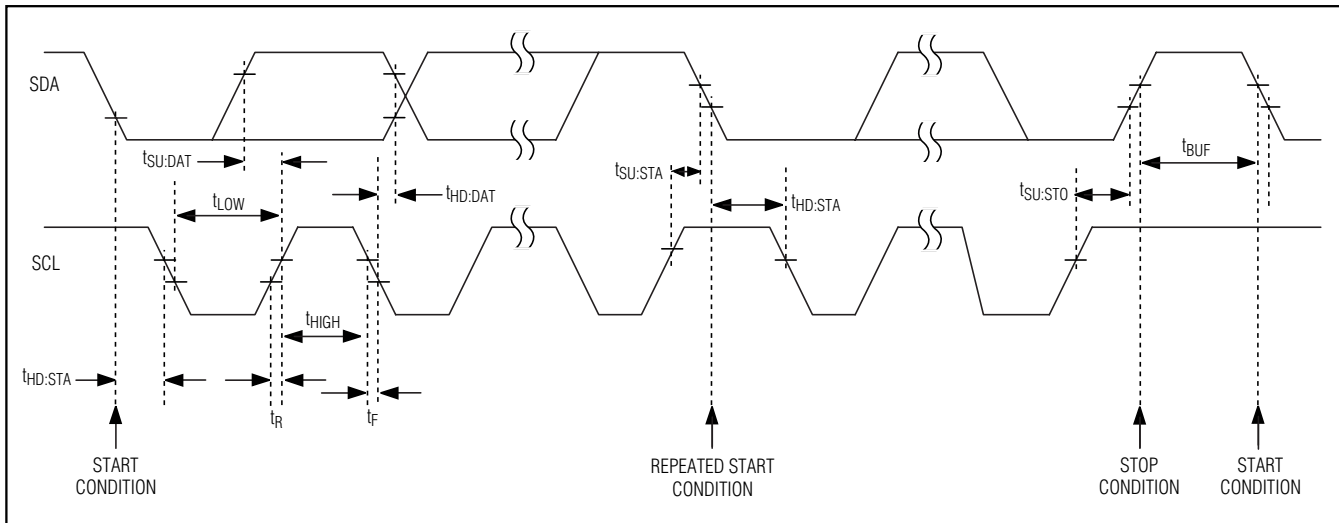


Figure 6. Serial Interface Timing

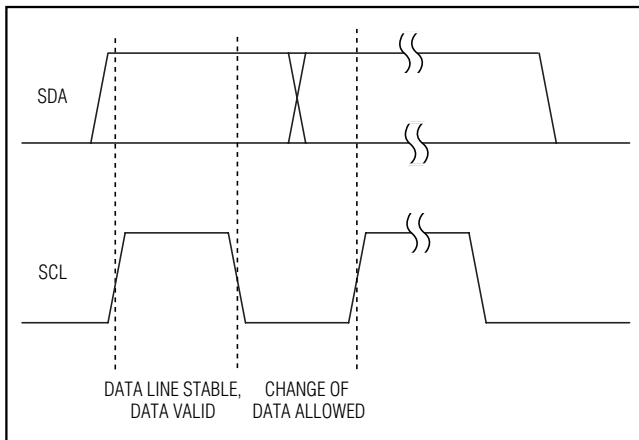


Figure 7. Bit Transfer

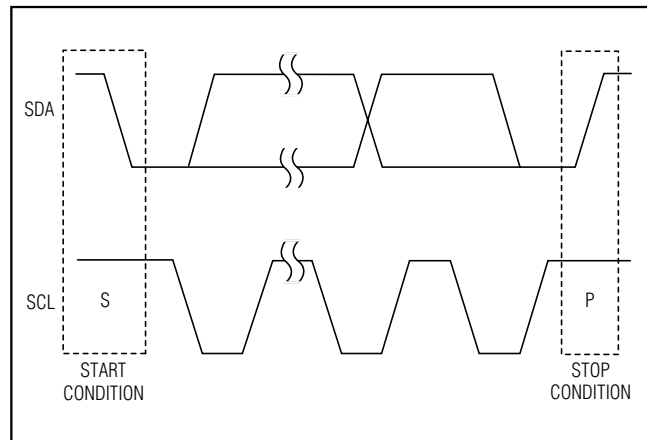


Figure 8. Start and Stop Conditions

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Start and Stop Conditions

Both SCL and SDA idle high when the bus is not busy. A master device signals the beginning of a transmission with a START (S) condition (see Figure 8) by transitioning SDA from high to low while SCL is high. The master device issues a STOP (P) condition (see Figure 8) by transitioning SDA from low to high while SCL is high. A STOP condition frees the bus for another transmission. The bus remains active if a REPEATED START condition is generated, such as in the block read protocol (see Figure 11).

Early STOP Conditions

The MAX6884/MAX6885 recognize a STOP condition at any point during transmission except if a STOP condition occurs in the same high pulse as a START condition. This condition is not a legal I²C format; at least one clock pulse must separate any START and STOP condition.

Repeated START Conditions

A REPEATED START (SR) condition may indicate a change of data direction on the bus. Such a change occurs when a command word is required to initiate a read operation (see Figure 11). SR may also be used when the bus master is writing to several I²C devices and does not want to relinquish control of the bus. The MAX6884/MAX6885 serial interface supports continuous write operations with or without an SR condition separating them. Continuous read operations require SR conditions because of the change in direction of data flow.

Acknowledge

The acknowledge bit (ACK) is the 9th bit attached to any 8-bit data word. The receiving device always generates an ACK. The MAX6884/MAX6885 generate an ACK when receiving an address or data by pulling SDA low during the 9th clock period (see Figure 9). When transmitting data, such as when the master device reads data back from the MAX6884/MAX6885, the MAX6884/MAX6885 wait for the master device to generate an ACK. Monitoring ACK allows for detection of unsuccessful data transfers. An unsuccessful data transfer occurs if the receiving device is busy or if a system fault has occurred. In the event of an unsuccessful data transfer, the bus master should reattempt communication at a later time. The MAX6884/MAX6885 generate a NACK after the command byte during a software reboot, while writing to the EEPROM, or when receiving an illegal memory address.

Slave Address

The MAX6884/MAX6885 slave address conforms to the following table:

| SA7 (MSB) | SA6 | SA5 | SA4 | SA3 | SA2 | SA1 | SA0 (LSB) |
|-----------|-----|-----|-----|-----|-----|-----|-----------|
| 1 | 0 | 1 | 0 | 0 | A0 | X | R/W |

X = Don't care.

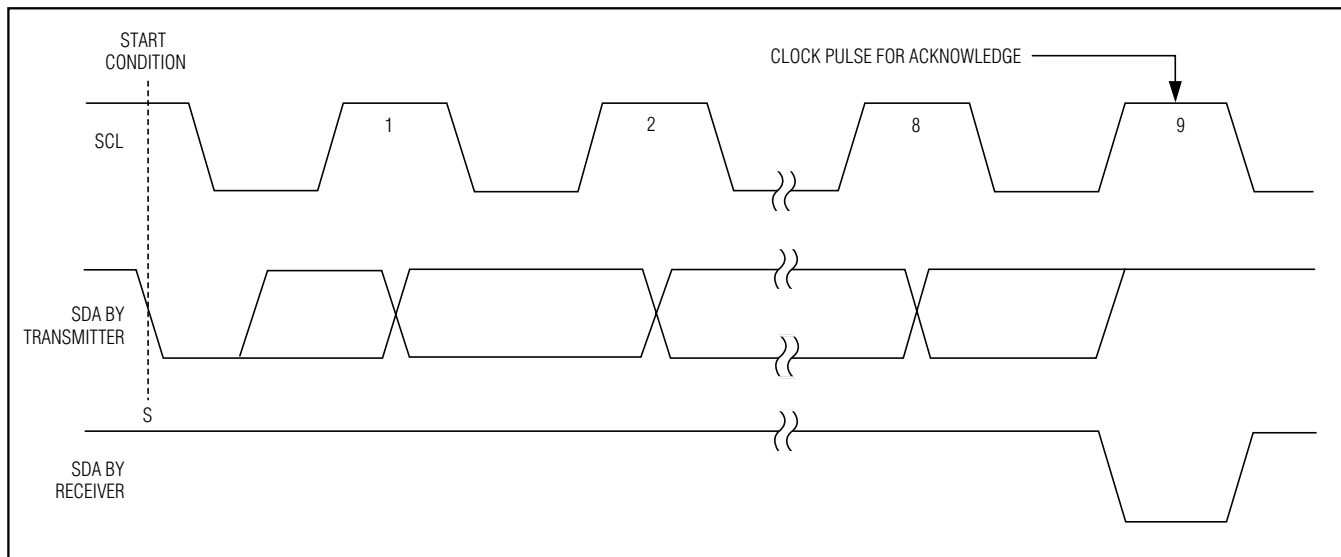


Figure 9. Acknowledge

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SA7 through SA4 represent the standard 2-wire interface address (1010); for devices with EEPROM, SA2 corresponds to the A0 address inputs of the MAX6884/MAX6885 (hardwired as logic-low or logic-high). SA0 is a read/write flag bit (0 = write, 1 = read).

The A0 address input allows up to two MAX6884/MAX6885s to connect to one bus. Connect A0 to GND or to the 2-wire serial-interface power supply (see Figure 10).

Send Byte

The send byte protocol allows the master device to send one byte of data to the slave device (see Figure 11). The send byte presets a register pointer address for a subsequent read or write. The slave sends a NACK instead of an ACK if the master tries to send an address that is not allowed or if the device is writing data to EEPROM or is booting. If the master sends C0h, the data is ACK, because this could be the start of the block write protocol, and the slave expects following data byte. If the master sends a STOP condition, the internal address pointer does not change. If the master sends C1h, this signifies that the block read protocol is expected, and a repeated START condition should follow. The device reboots if the master sends C4h. The send byte procedure follows:

- 1) The master sends a START condition.
- 2) The master sends the 7-bit slave address and a write bit (low).
- 3) The addressed slave asserts an ACK on SDA.
- 4) The master sends an 8-bit data byte.
- 5) The addressed slave asserts an ACK on SDA.
- 6) The master sends a STOP condition.

Write Byte

The write byte protocol allows the master device to write a single byte in the register bank or in the EEPROM (see Figure 11). The write byte/word procedure follows:

- 1) The master sends a START condition.
- 2) The master sends the 7-bit slave address and a write bit (low).
- 3) The addressed slave asserts an ACK on SDA.
- 4) The master sends an 8-bit command code.

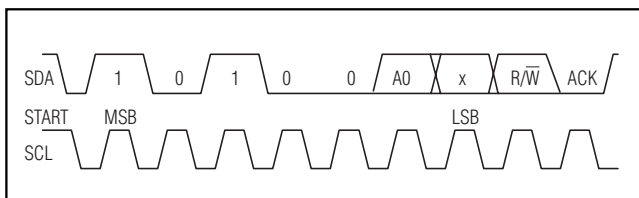


Figure 10. Slave Address

- 5) The addressed slave asserts an ACK on SDA.
- 6) The master sends an 8-bit data byte.
- 7) The addressed slave asserts an ACK on SDA.
- 8) The master sends a STOP condition.

To write a single byte to the register bank, only the 8-bit command code and a single 8-bit data byte are sent. The command code must be in the 00h to 2Fh range. The data byte is written to the register bank if the command code is valid. The slave generates a NACK at step 5 if the command code is invalid or any internal operations are ongoing. To write a single byte of data to the user or configuration EEPROM, the 8-bit command code and a single 8-bit data byte are sent.

Block Write

The block write protocol allows the master device to write a block of data (1 to 16 bytes) to the EEPROM or to the register bank (see Figure 11). The destination address must already be set by the send byte protocol and the command code must be C0h. If the number of bytes to be written causes the address pointer to exceed 2Fh for the configuration register or 9Fh for the configuration EEPROM, the address pointer stops incrementing, overwriting the last memory address with the remaining bytes of data. Only the last data byte sent is stored in 17h (as 2Fh is read only and a write cause no change in the content). If the number of bytes to be written exceeds the address pointer 9Fh for the user EEPROM, the address pointer stops incrementing and continues writing exceeding data to the last address. Only the last data is actually written to 9Fh. The block write procedure follows:

- 1) The master sends a START condition.
- 2) The master sends the 7-bit slave address and a write bit (low).
- 3) The addressed slave asserts an ACK on SDA.
- 4) The master sends the 8-bit command code for block write (C0h).
- 5) The addressed slave asserts an ACK on SDA.
- 6) The master sends the 8-bit byte count (1 to 16 bytes) N.
- 7) The addressed slave asserts an ACK on SDA.
- 8) The master sends 8 bits of data.
- 9) The addressed slave asserts an ACK on SDA.
- 10) Repeat steps 8 and 9 N - 1 times.
- 11) The master generates a STOP condition.

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Read Byte

The read byte protocol allows the master device to read the register or an EEPROM location (user or configuration) content of the MAX6884/MAX6885 (see Figure 11). The read byte procedure follows:

- 1) The master sends a START condition.
- 2) The master sends the 7-bit slave address and a write bit (low).
- 3) The addressed slave asserts an ACK on the data line.
- 4) The master sends 8 data bits.
- 5) The active slave asserts an ACK on the data line.
- 6) The master sends a repeated start condition.
- 7) The master sends the 7-bit slave ID plus a read bit (high).
- 8) The addressed slave asserts an ACK on the data line.
- 9) The slave sends 8 data bits.
- 10) The master asserts a NACK on the data line.
- 11) The master generates a STOP condition.

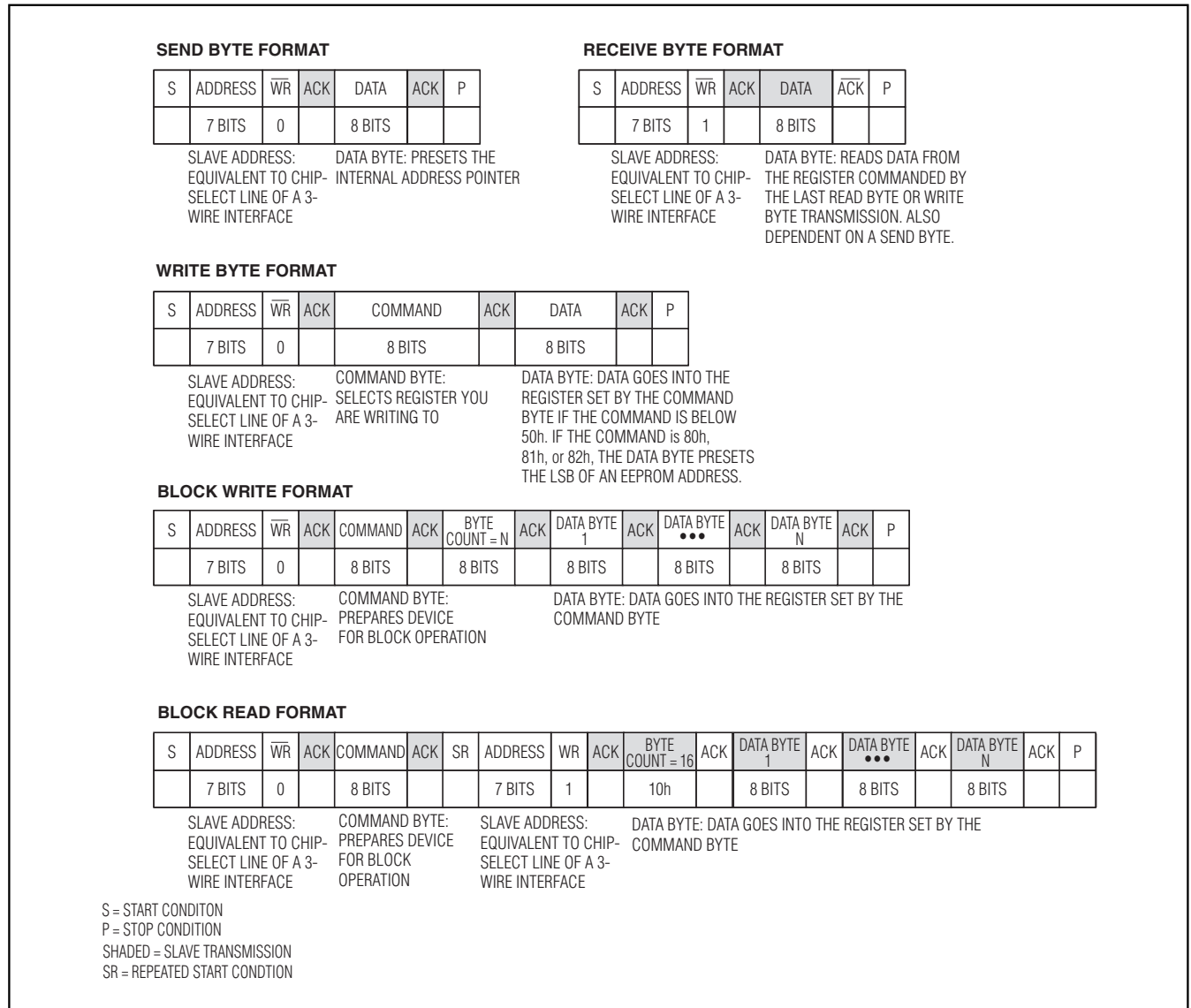


Figure 11. SMBus/I²C Protocols

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Note that once the read has been done, the internal pointer is increased by one, unless a memory boundary is hit. If the device is busy or if the address is not an allowed one, the command code is NACKed and the internal address pointer is not altered. The master must then interrupt the communication issuing a STOP condition.

Block Read

The block read protocol allows the master device to read a block of 16 bytes from the EEPROM or register bank (see Figure 11). Read fewer than 16 bytes of data by issuing an early STOP condition from the master, or by generating a NACK with the master. Previous actions through the serial interface predetermine the first source address. It is suggested to use a send byte protocol, before the block read, to set the initial read address. The block read protocol is initiated with a command code of C1h. The block read procedure follows:

- 1) The master sends a START condition.
- 2) The master sends the 7-bit slave address and a write bit (low).
- 3) The addressed slave asserts an ACK on SDA.
- 4) The master sends 8 bits of the block read command (C1h).
- 5) The slave asserts an ACK on SDA, unless busy.
- 6) The master generates a repeated START condition.
- 7) The master sends the 7-bit slave address and a read bit (high).
- 8) The slave asserts an ACK on SDA.
- 9) The slave sends the 8-bit byte count (16).
- 10) The master asserts an ACK on SDA.
- 11) The slave sends 8 bits of data.
- 12) The master asserts an ACK on SDA.
- 13) Repeat steps 8 and 9 15 times.
- 14) The master generates a STOP condition.

Address Pointers

Use the send byte protocol to set the register address pointers before read and write operations. For the configuration registers, valid address pointers range from 00h to 2Fh. Register addresses outside of this range result in a NACK being issued from the MAX6884/MAX6885. When using the block write protocol, the address pointer automatically increments after each data byte, except when the address pointer is already at 2Fh. If the address pointer is already 2Fh, and more

data bytes are being sent, these subsequent bytes overwrite address 2Fh repeatedly, but no data will be left in 2Fh as this is a read-only address.

For the configuration EEPROM, valid address pointers range from 80h to 9Fh. When using the block write protocol, the address pointer automatically increments after each data byte, except when the address pointer is already at 9Fh. If the address pointer is already 9Fh, and more data bytes are being sent, these subsequent bytes overwrite address 9Fh repeatedly, leaving only the last data byte sent stored at this register address.

For the user EEPROM, valid address pointers range from 40h to 7Fh. As for the configuration EEPROM, block write and block read protocols can also be used. The internal address pointer will automatically increment up to the user EEPROM boundary 7Fh where the pointer moves to the first address of the configuration memory section 80h, as there is no forbidden address in the middle.

Applications Information

Configuration Download at Power-Up

The configuration of the MAX6884/MAX6885 (undervoltage/overvoltage thresholds, reset time delays, watchdog behavior, programmable output conditions and configurations, etc.) at power-up depends on the contents of the EEPROM. The EEPROM is comprised of buffered latches that store the configuration. The local volatile memory latches lose their contents at power-down. Therefore, at power-up, the device configuration must be restored by downloading the contents of the EEPROM (nonvolatile memory) to the local latches. This download occurs in a number of steps:

- 1) Programmable outputs are high impedance with no power applied to the device.
- 2) When V_{CC} or IN1–IN4 (see the *Powering the MAX6884/MAX6885* section) exceeds +1V, all programmable outputs are asserted low.
- 3) When V_{CC} or IN1–IN4 exceeds UVLO (2.5V), the configuration EEPROM starts to download its contents to the volatile configuration registers. The download takes 2.5ms (max). The programmable outputs assume their programmed conditional output state when V_{CC} or IN1–IN4 exceeds the UVLO (see the *Powering the MAX6884/MAX6885* section).
- 4) Any attempt to communicate with the device prior to this download completion results in a NACK being issued from the MAX6884/MAX6885.

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Layout and Bypassing

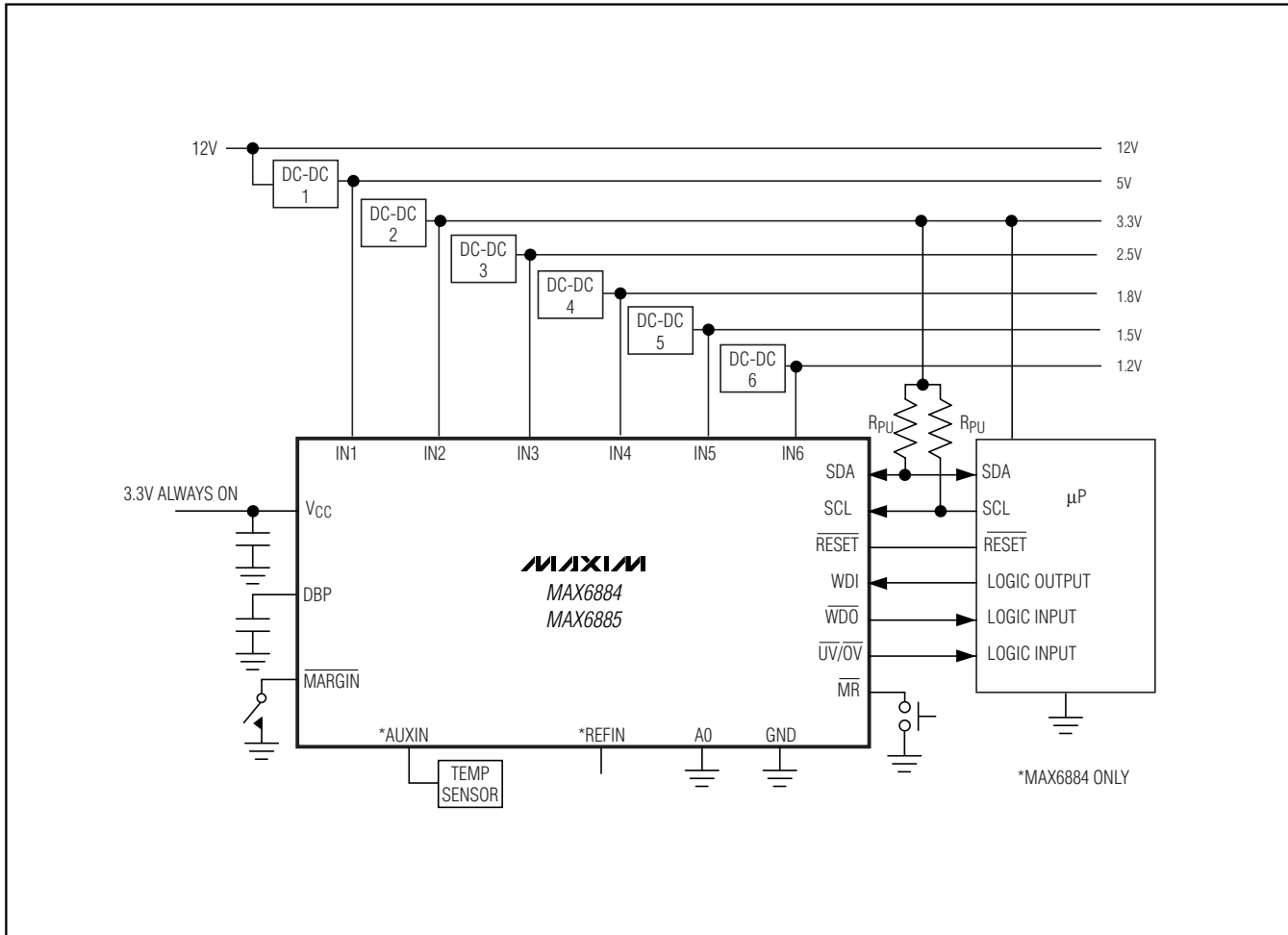
For better noise immunity, bypass each of the voltage-detector inputs to GND with a 0.1µF capacitor installed as close to the device as possible. Bypass VCC and DBP to GND with 1µF capacitors installed as close to the device as possible. VCC (when not externally supplied) and DBP are internally generated voltages and should not be used to supply power to external circuitry.

Configuration Latency Period

A delay of less than 5µs occurs between writing to the configuration registers and the time when these changes actually take place, except when changing one of the voltage-detector thresholds. Changing a voltage-detector threshold typically takes 150µs. When changing EEPROM contents, a software reboot or cycling of power is required for these changes to transfer to volatile memory.

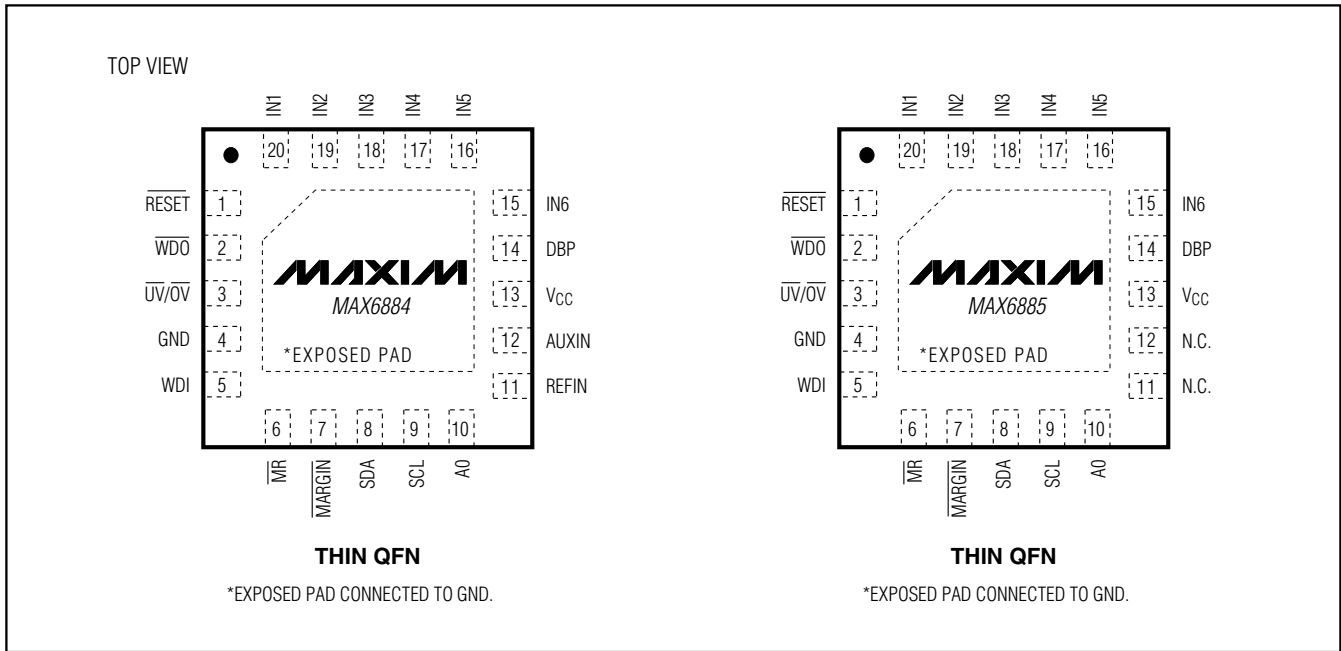
MAX6884/MAX6885

Typical Operating Circuit



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Pin Configurations



Chip Information

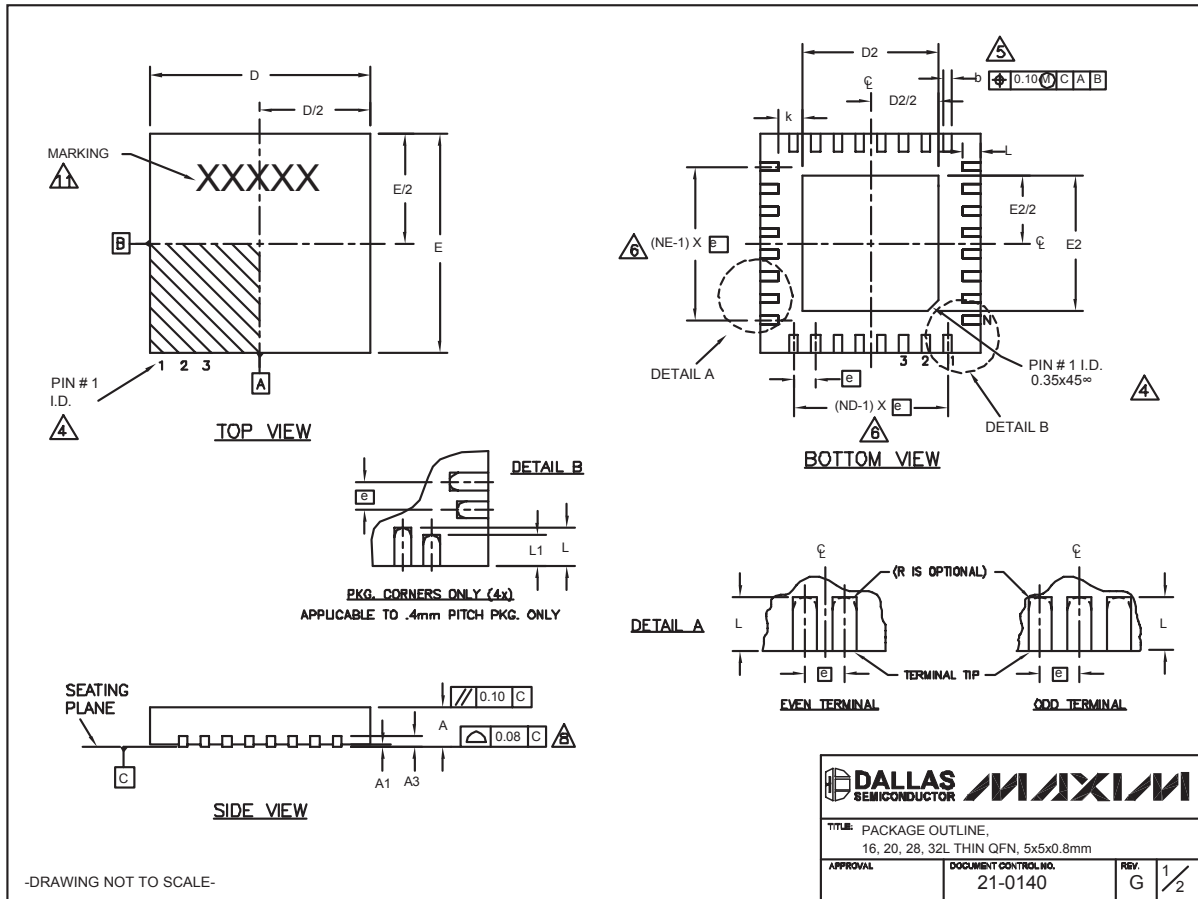
PROCESS: BICMOS

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Package Information

(The package drawing(s) in this data sheet may not reflect the most current specifications. For the latest package outline information go to www.maxim-ic.com/packages.)

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Package Information (continued)

(The package drawing(s) in this data sheet may not reflect the most current specifications. For the latest package outline information go to www.maxim-ic.com/packages.)

| COMMON DIMENSIONS | | | | | | | | | | | | |
|-------------------|-----------|------|------|-----------|------|------|-----------|------|------|-----------|------|------|
| PKG. | 16L 5x5 | | | 20L 5x5 | | | 28L 5x5 | | | 32L 5x5 | | |
| SYMBOL | MIN. | NOM. | MAX. | MIN. | NOM. | MAX. | MIN. | NOM. | MAX. | MIN. | NOM. | MAX. |
| A | 0.70 | 0.75 | 0.80 | 0.70 | 0.75 | 0.80 | 0.70 | 0.75 | 0.80 | 0.70 | 0.75 | 0.80 |
| A1 | 0 | 0.02 | 0.05 | 0 | 0.02 | 0.05 | 0 | 0.02 | 0.05 | 0 | 0.02 | 0.05 |
| A3 | 0.20 REF. | | | 0.20 REF. | | | 0.20 REF. | | | 0.20 REF. | | |
| b | 0.25 | 0.30 | 0.35 | 0.25 | 0.30 | 0.35 | 0.20 | 0.25 | 0.30 | 0.20 | 0.25 | 0.30 |
| D | 4.90 | 5.00 | 5.10 | 4.90 | 5.00 | 5.10 | 4.90 | 5.00 | 5.10 | 4.90 | 5.00 | 5.10 |
| E | 4.90 | 5.00 | 5.10 | 4.90 | 5.00 | 5.10 | 4.90 | 5.00 | 5.10 | 4.90 | 5.00 | 5.10 |
| e | 0.80 BSC. | | | 0.65 BSC. | | | 0.50 BSC. | | | 0.50 BSC. | | |
| k | 0.25 | - | - | 0.25 | - | - | 0.25 | - | - | 0.25 | - | - |
| L | 0.30 | 0.40 | 0.50 | 0.45 | 0.55 | 0.65 | 0.45 | 0.55 | 0.65 | 0.30 | 0.40 | 0.50 |
| L1 | - | - | - | - | - | - | - | - | - | - | - | - |
| N | 16 | | | 20 | | | 28 | | | 32 | | |
| ND | 4 | | | 5 | | | 7 | | | 8 | | |
| NE | 4 | | | 5 | | | 7 | | | 8 | | |
| JEDEC | WHHB | | | WHHC | | | WHHD-1 | | | WHHD-2 | | |

| EXPOSED PAD VARIATIONS | | | | | | | | | |
|------------------------|------|------|------|------|------|------|------------|--------------------|--|
| PKG. CODES | D2 | | | E2 | | | L ±0.15 | DOWN BONDS ALLOWED | |
| | MIN. | NOM. | MAX. | MIN. | NOM. | MAX. | | | |
| T1655-1 | 3.00 | 3.10 | 3.20 | 3.00 | 3.10 | 3.20 | ** | NO | |
| T1655-2 | 3.00 | 3.10 | 3.20 | 3.00 | 3.10 | 3.20 | ** | YES | |
| T1655N-1 | 3.00 | 3.10 | 3.20 | 3.00 | 3.10 | 3.20 | ** | NO | |
| T2055-2 | 3.00 | 3.10 | 3.20 | 3.00 | 3.10 | 3.20 | ** | NO | |
| T2055-3 | 3.00 | 3.10 | 3.20 | 3.00 | 3.10 | 3.20 | ** | YES | |
| T2055-4 | 3.00 | 3.10 | 3.20 | 3.00 | 3.10 | 3.20 | ** | NO | |
| T2055-5 | 3.15 | 3.25 | 3.35 | 3.15 | 3.25 | 3.35 | 0.40 | Y | |
| T2855-1 | 3.15 | 3.25 | 3.35 | 3.15 | 3.25 | 3.35 | ** | NO | |
| T2855-2 | 2.60 | 2.70 | 2.80 | 2.60 | 2.70 | 2.80 | ** | NO | |
| T2855-3 | 3.15 | 3.25 | 3.35 | 3.15 | 3.25 | 3.35 | ** | YES | |
| T2855-4 | 2.60 | 2.70 | 2.80 | 2.60 | 2.70 | 2.80 | ** | YES | |
| T2855-5 | 2.60 | 2.70 | 2.80 | 2.60 | 2.70 | 2.80 | ** | NO | |
| T2855-6 | 3.15 | 3.25 | 3.35 | 3.15 | 3.25 | 3.35 | ** | NO | |
| T2855-7 | 2.60 | 2.70 | 2.80 | 2.60 | 2.70 | 2.80 | ** | YES | |
| T2855-8 | 3.15 | 3.25 | 3.35 | 3.15 | 3.25 | 3.35 | 0.40 | Y | |
| T2855N-1 | 3.15 | 3.25 | 3.35 | 3.15 | 3.25 | 3.35 | ** | N | |
| T3255-2 | 3.00 | 3.10 | 3.20 | 3.00 | 3.10 | 3.20 | ** | NO | |
| T3255-3 | 3.00 | 3.10 | 3.20 | 3.00 | 3.10 | 3.20 | ** | YES | |
| T3255-4 | 3.00 | 3.10 | 3.20 | 3.00 | 3.10 | 3.20 | ** | NO | |
| T3255N-1 | 3.00 | 3.10 | 3.20 | 3.00 | 3.10 | 3.20 | ** | NO | |

**SEE COMMON DIMENSIONS TABLE

NOTES:

- DIMENSIONING & TOLERANCING CONFORM TO ASME Y14.5M-1994.
- ALL DIMENSIONS ARE IN MILLIMETERS. ANGLES ARE IN DEGREES.
- N IS THE TOTAL NUMBER OF TERMINALS.
- THE TERMINAL #1 IDENTIFIER AND TERMINAL NUMBERING CONVENTION SHALL CONFORM TO JESD 95-1 SPP-012. DETAILS OF TERMINAL #1 IDENTIFIER ARE OPTIONAL, BUT MUST BE LOCATED WITHIN THE ZONE INDICATED. THE TERMINAL #1 IDENTIFIER MAY BE EITHER A MOLD OR MARKED FEATURE.
- DIMENSION b APPLIES TO METALLIZED TERMINAL AND IS MEASURED BETWEEN 0.25 mm AND 0.30 mm FROM TERMINAL TIP.
- ND AND NE REFER TO THE NUMBER OF TERMINALS ON EACH D AND E SIDE RESPECTIVELY.
- DEPOPULATION IS POSSIBLE IN A SYMMETRICAL FASHION.
- COPLANARITY APPLIES TO THE EXPOSED HEAT SINK SLUG AS WELL AS THE TERMINALS.
- DRAWING CONFORMS TO JEDEC MO220, EXCEPT EXPOSED PAD DIMENSION FOR T2855-1, T2855-3 AND T2855-6.
- WARPAGE SHALL NOT EXCEED 0.10 mm.
- MARKING IS FOR PACKAGE ORIENTATION REFERENCE ONLY.
- NUMBER OF LEADS SHOWN ARE FOR REFERENCE ONLY.

-DRAWING NOT TO SCALE-

| | |
|----------------------------------------------------------------|---------------------------------|
| | |
| TITLE: PACKAGE OUTLINE, 16, 20, 28, 32L THIN QFN, 5x5x0.8mm | |
| APPROVAL | DOCUMENT CONTROL NO. 21-0140 |
| REV. G | 2/2 |

Maxim cannot assume responsibility for use of any circuitry other than circuitry entirely embodied in a Maxim product. No circuit patent licenses are implied. Maxim reserves the right to change the circuitry and specifications without notice at any time.

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Компания «Океан Электроники» предлагает заключение долгосрочных отношений при поставках импортных электронных компонентов на взаимовыгодных условиях!

Наши преимущества:

- Поставка оригинальных импортных электронных компонентов напрямую с производств Америки, Европы и Азии, а так же с крупнейших складов мира;
- Широкая линейка поставок активных и пассивных импортных электронных компонентов (более 30 млн. наименований);
- Поставка сложных, дефицитных, либо снятых с производства позиций;
- Оперативные сроки поставки под заказ (от 5 рабочих дней);
- Экспресс доставка в любую точку России;
- Помощь Конструкторского Отдела и консультации квалифицированных инженеров;
- Техническая поддержка проекта, помощь в подборе аналогов, поставка прототипов;
- Поставка электронных компонентов под контролем ВП;
- Система менеджмента качества сертифицирована по Международному стандарту ISO 9001;
- При необходимости вся продукция военного и аэрокосмического назначения проходит испытания и сертификацию в лаборатории (по согласованию с заказчиком);
- Поставка специализированных компонентов военного и аэрокосмического уровня качества (Xilinx, Altera, Analog Devices, Intersil, Interpoint, Microsemi, Actel, Aeroflex, Peregrine, VPT, Syfer, Eurofarad, Texas Instruments, MS Kennedy, Miteq, Cobham, E2V, MA-COM, Hittite, Mini-Circuits, General Dynamics и др.);

Компания «Океан Электроники» является официальным дистрибьютором и эксклюзивным представителем в России одного из крупнейших производителей разъемов военного и аэрокосмического назначения «**JONHON**», а так же официальным дистрибьютором и эксклюзивным представителем в России производителя высокотехнологичных и надежных решений для передачи СВЧ сигналов «**FORSTAR**».



JONHON

«**JONHON**» (основан в 1970 г.)

Разъемы специального, военного и аэрокосмического назначения:

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«**FORSTAR**» (основан в 1998 г.)

ВЧ соединители, коаксиальные кабели, кабельные сборки и микроволновые компоненты:

(Применяются в телекоммуникациях гражданского и специального назначения, в средствах связи, РЛС, а так же военной, авиационной и аэрокосмической отраслях промышленности).



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