

MP4410 **36V, 100mA Synchronous Step-Down Converter**

The Future of Analog IC Technology

DESCRIPTION

The MP4410 is a high-frequency, step-down, switching regulator with integrated highside/low-side, high-voltage power MOSFETs. It provides a highly efficient output of up to 100mA.

42V rated MOSFETs and 4.5V to 36V operation range accommodates a variety of step-down applications in automotive input environment. A 5μA shutdown mode quiescent current allows use in battery-powered applications.

It allows for high power conversion efficiency over a wide load range by scaling down the switching frequency under light-load condition to reduce the switching and gate driver losses.

The switching frequency during start-up and short circuit also can be scaled down to helps prevent inductor current runaway. Thermal shutdown provides reliable, fault-tolerant operation.

The MP4410 is available in a 3mmx3mm QFN10 package.

FEATURES

- 20μA Quiescent Current
- Wide 4.5V to 36V Operating Range
- 42V Integrated MOSFETs with 0.7Ω and 2.25Ω Ron
- Programmable Switching Frequency
- Stable with Ceramic Output Capacitors
- Low Output Ripple
- Programmable Soft-Start
- Adjustable Input UVLO Hysteresis
- Precision Peak Current Limit without Current-Sensing Resistor
- Programmable Peak Current Limit
- $>90\%$ Efficiency at 10V VIN to 5V V_{OUT}/2mA
- 1.0V Feedback Reference Voltage
- Low Shutdown Mode Current: <5μA
- 3mmx3mm QFN10 Package

APPLICATIONS

- 4mA to 20mA Current Loops
- Automotive Systems
- Industrial Power Systems
- Distributed Power Systems
- **Battery Powered Systems**

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TYPICAL APPLICATION

ORDERING INFORMATION

* For Tape & Reel, add suffix –Z (e.g. MP4410GQ–Z).

TOP MARKING

ANHY LLL

ANH: product code of MP4410GQ; Y: year code; LLL: lot number;

PACKAGE REFERENCE

ABSOLUTE MAXIMUM RATINGS (1)

Thermal Resistance **(4)** *θJA θJC*

QFN-10 (3mmx3mm) 50 12 ... °C/W

Notes:

- 1) Exceeding these ratings may damage the device.
- 2) The maximum allowable power dissipation is a function of the maximum junction temperature T_J (MAX), the junction-toambient thermal resistance θ_{JA} , and the ambient temperature T_A . The maximum allowable continuous power dissipation at any ambient temperature is calculated by P_D (MAX) = (TJ) $(MAX)-T_A)/\theta_{JA}$. Exceeding the maximum allowable power dissipation will cause excessive die temperature, and the regulator will go into thermal shutdown. Internal thermal shutdown circuitry protects the device from permanent damage.
- 3) The device is not guaranteed to function outside of its operating conditions.
- 4) Measured on JESD51-7, 4-layer PCB.

ELECTRICAL CHARACTERISTICS

V_{IN} = 12V, V_{EN} = 2V, T_J= 25°C, unless otherwise noted.

5) Derived from bench characterization. Not tested in production.

TYPICAL CHARACTERISTICS

TYPICAL CHARACTERISTICS *(continued)*

V_{IN}=12V, T_J=25°C, unless otherwise noted.

TYPICAL PERFORMANCE CHARACTERISTICS *(continued)*

100

90 80

70

60

50

40

30

20 10

> $\mathbf 0$ 0.1

Current

IN

Ш

Ш

 $\mathbf{1}$

†∨ŵ $=36V$ Ш

I_{PEAK}=110mA, L=220µH, V_{OUT}=5V

TITUL

THIII

Ш

 10

LOAD CURRENT (mA)

100

 V_{IN} =24V

 V_{IN} =

EFFICIENCY (%)

PIN FUNCTIONS

FUNCTIONAL BLOCK DIAGRAM

OPERATION

The MP4410 is a 36V, 100mA, synchronous, step-down switching regulator with integrated high-side and low-side high-voltage power MOSFETs (HS_FET and LS_FET, respectively). It provides a highly-efficient, 100mA output. It features a wide input voltage range, internal/external soft-start control, and precision current limit. Its very low operational quiescent current makes it suitable for battery-powered applications.

PWM Control

The ILIM comparator, FB comparator and zero current detector (ZCD) block control the PWM. If V_{FB} is below the 1V reference and the inductor current drops to zero, HS-FET turns on and the ILIM comparator starts to sense the HS-FET current: When the HS-FET current reaches the limit set by the ILIM pin, or FB reaches the OVP threshold, the HS-FET turns off and LS-FET turns on together with the ZCD block. Meanwhile, the ILIM comparator is turned off to reduce the quiescent current. The LS-FET turns off together with ZCD block after the inductor current drops to zero. If V_{FB} is less than the 1V reference at this time, the HS-FET turns on at once and commences another cycle. If V_{FB} is still higher than 1V reference, HS-FET would not turn on till V_{FB} drops below 1V.

Figure 2 – PWM Control

Internal Regulator and BIAS

The 2.6V internal regulator powers most of the internal circuitry. This regulator takes V_{IN} and operates in the full V_{IN} range. When V_{IN} is greater than 3.0V, the output of the regulator is in full regulation. Lower values of V_{IN} result in lower output voltages.

When V_{BIAS} >2.9V, the BIAS supply overrides the input voltage and supplies power to the 2.6V internal regulator. When $V_{BIAS} > 4.5V$, it can power LS driver furthermore. Using BIAS to power internal regulator can improve the efficiency. It is recommended to connect BIAS to the regulated output voltage when it is in the range of 2.9V to 5.5V. When output voltage is out of above range, an external supply that is >2.9V or even better >4.5V is needed to power BIAS.

Enable Control

The MP4410 has a dedicated enable-control pin, EN: when V_{IN} goes high, the EN pin enables and disables the chip. This is HIGH effective logic. Its trailing threshold is 1.2V typically and its rising threshold is about 400mV higher. When floating, EN pin is internally pulled down to GND through a 2M resistor to disable the chip.

When $EN = 0V$, the chip goes into the lowest shutdown-current mode. When EN is higher than zero but lower than its rising threshold, the chip remains in a shutdown mode but with a slightly larger shutdown current.

Internally a zener diode is connected from EN pin to GND pin. The typical clamping voltage of the zener diode is 7.5V. So VIN can be connected to EN through a high ohm resistor if the system doesn't have another logic input acting as enable signal. The resistor needs to be designed to limit the EN pin sink current less than 100μA. Just note that there is an internal 2M resistor from EN to GND, so the external pull up resistor should be

smaller than 1.6V $\frac{[V_{IN(MIN)} - 1.6V] \times 2M}{[V]}$ to make sure the

part can EN on at the lowest operation VIN.

Under-Voltage Lockout

 V_{IN} under voltage lockout (UVLO) protects the chip from operating below the operational supply voltage range. The UVLO-rising threshold is about 4V while its trailing threshold is about 3.5V.

Soft-Start

Reference-type soft-start prevents the converter output voltage from overshooting during startup. When the chip starts, the internal circuitry generates a constant current to charge external SS capacitor. The soft-start (SS) voltage slowly ramps up from 0V at a slow pace set by the softstart time. When V_{SS} is less than the V_{REF} , V_{SS} overrides V_{REF} so the error amplifier uses V_{SS} instead of V_{REF} as the reference. When V_{SS} is higher than V_{RFE} , V_{RFE} resumes control.

 V_{SS} is also associated with V_{FB} . Though V_{SS} can be much smaller than V_{FB} , it can only barely exceed V_{FB} . If somehow V_{FB} drops, V_{SS} tracks V_{FB} . This function aides in short-circuit recovery: when a short-circuit is removed, the SS ramps up as if it is a fresh soft-start process. This prevents output voltage overshoot.

Thermal Shutdown

Thermal shutdown prevents the chip from thermally running away. When the silicon die temperature exceeds its upper threshold, the thermal shutdown feature shuts down the whole chip. When the temperature falls below its lower threshold, the chip resumes function.

Floating Driver and Bootstrap Charging

The external bootstrap capacitor powers the floating MOSFET driver. This floating driver has its own UVLO protection, with a rising threshold of about 2.4V with a hysteresis of about 300mV. During this UVLO, the SS voltage of the controller resets to zero. When the UVLO is disabled, the controller follows the soft-start process.

The dedicated internal bootstrap regulator charges and regulates the bootstrap capacitor to about 5V. When the voltage difference between

BST and SW falls below its working parameters, a PMOS pass transistor connected from V_{IN} to BST turns on to charge the bootstrap capacitor. The current path is from V_{IN} to BST and then to

SW. The external circuit must have enough voltage headroom to accommodate charging.

As long as V_{IN} is sufficiently higher than SW, the bootstrap capacitor can charge. When the power MOSFET is ON, V_{IN} is about equal to SW so the bootstrap capacitor cannot charge. The best charging period occurs when the external freewheeling diode is on so that V_{IN} - V_{SW} is at its largest. When there is no current in the inductor, V_{SW} equals V_{OUT} so the difference between V_{IN} and V_{OUT} can charge the bootstrap capacitor.

Under higher duty cycle operating conditions, the time period may not fully-charge the capacitor.

If the external circuit does not have sufficient voltage and time to charge the bootstrap capacitor, extra external circuitry can be used to ensure the bootstrap voltage in normal operation region.

Startup and Shutdown

If both V_{IN} and V_{EN} are higher than their appropriate thresholds, the chip starts operating. The reference block starts first, generating stable reference voltage and currents, and then enables the internal regulator. The regulator provides stable supply for the rest device.

While the internal supply rail is high, an internal timer holds the power MOSFET off for about 50µsec to blank startup glitches. When the internal soft-start block is enabled, it first holds its SS output low and then slowly ramps up.

Three events shut down the chip: V_{EN} low, V_{IN} low, and junction temperature triggers the thermal shutdown threshold. For shutdown, the signaling path is blocked first to avoid any fault triggering. Internal supply rail are pulled down then. The floating driver is not subject to this shutdown command, but its charging path is disabled.

APPLICATION INFORMATION

Setting Peak Current

The peak current can be programmed from 55mA to 260mA by changing the resistor between ILIM pin and ground. The peak current setting resistor R_{ILM} can be calculated by the formula:

$$
R_{\text{ILIM}} = \frac{22}{I_{\text{peak}}} (k\Omega)
$$

Where 55mA≤Ipeak≤260mA.

When $R_{ILIM} \leq 84k\Omega$, Ipeak is clamped at its maximum value 260mA; when $R_{\text{IUM}} \geq 400 \text{k}\Omega$, Ipeak is clamped to its minimum value 55mA. To be convenient, ILIM pin can be just shorted to GND when Ipeak is set at 260mA and floating when Ipeak is set at 55mA.

When setting Ipeak, be noticed that the maximum output current is equal to half of the Ipeak. Make sure the Ipeak is high enough for the output current requirement. Also be noticed that higher Ipeak would result in higher inductor current ripple, larger input and output voltage ripple, which means bigger components (inductor, input and output capacitors).

Selecting the Inductor

As the Ipeak is determined, for given input voltage and output voltage, the inductor value can be determined by the following formula:

$$
L = \frac{V_{\text{OUT}} \times (V_{\text{IN}} - V_{\text{OUT}})}{V_{\text{IN}} \times I_{\text{peak}} \times f_{\text{s}}}
$$

Where fs is the switching frequency at the maximal output current.

Larger inductor value results in lower switching frequency, as well as higher efficiency. However, the larger value inductor will have a larger physical size, higher series resistance, and/or lower saturation current as well as the slow load transient dynamic performance. There is also a lower limit of the inductor value, which is determined by the minimum on time. In order to

keep the inductor working under control, the inductor value should be chosen higher than Lmin that is derived from below formula:

$$
L_{\text{MIN}} = \frac{V_{\text{IN}(\text{MAX})} \times T_{\text{ON}(\text{MIN})}}{I_{\text{peak}}}
$$

Where $V_{IN(MAX)}$ is the max value of input voltage. $T_{ON(MIN)}$ is the designed 100ns minimum switch on time.

Switching Frquency

Switching frequency can be estimated by below equation.

$$
f_s = \frac{2 \times \log N_{\text{OUT}} \times (V_{\text{IN}} - V_{\text{OUT}})}{I_{\text{peak}}^2 \times V_{\text{IN}} \times L}
$$

Higher Ipeak and inductor can get lower fs. And fs inceases as Io increasing. When Io increases to its maximal value Ipeak/2, fs also reaches its highest value and can be derived by:

$$
f_{s(max)} = \frac{V_{OUT} \times (V_{IN} - V_{OUT})}{I_{peak} \times V_{IN} \times L}
$$

Below figures show the calculated fs(max) at different VIN and inductor with typical Vo (3.3V and 5V) and Ipeak (220mA).

Figure $3 - f_{s(max)}$ at $V_{OUT} = 3.3V$

Setting the Output Voltage

The output voltage is set using a resistive voltage divider from the output voltage to FB pin. To get the desired output voltage, divider resistor can be chosen through below formula:

$$
\frac{R1}{R2} = \frac{V_{\text{OUT}}}{V_{\text{REF}}} - 1
$$

Where V_{REF} is the FB reference voltage 1V.

The current flows into divider resistor would increase the supply current, especially at no load and light load condition. The Vin supply current caused by the feedback resistors can be calculated from:

$$
I_{IN_FB} = \frac{V_{OUT}}{R1 + R2} \times \frac{V_{OUT}}{V_{IN}} \times \frac{1}{\eta}
$$

 To reduce this current, resistors in the megohm range are recommended. The recommended value of the feedback resistors are shown in Table 1.

Table 1—Resistor Selection for Common Output Voltages

$V_{\text{OUT}}(V)$	$R1$ (k Ω)	$R2 (k\Omega)$
3.3	1200	523
	1200	300

Under Voltage Lock Out Point Setting

MP4410 has internal fix under voltage lock out (UVLO) threshold: rising threshold is about 4V while trailing threshold is about 3.5V. For the application needs higher UVLO point, can use external resistor divider between EN and VIN as

shown in Figure 5 to get higher equivalent UVLO threshold.

Figure 5 – Adjustable UVLO using EN pin

The UVLO threshold can be computed from below two equations.

$$
UVLO_{\text{TH_Rising}} = (1 + \frac{R4}{2M/RS}) \times EN_{\text{TH_Rising}}
$$

$$
UVLO_{\text{TH_Falling}} = (1 + \frac{R4}{2M/RS}) \times EN_{\text{TH_Falling}}
$$

Furthermore, ENHY pin can be used to get additional UVLO hysteresis as shown in Figure 6.

Figure 6 – Adjustable UVLO using EN & ENHY pin

The ENHY pin is an open drain output that goes low when EN falls below its falling threshold 1.2V. The UVLO rising threshold in Figure 6 is same to the one in Figure 5. But the falling threshold is lowered by adding R6 and the detailed value can be calculated by below formula.

$$
UVLO_{\text{TH_Falling}} = [1 + \frac{R4}{2M/(R5 + R6)}] \times EN_{\text{TH_Rising}}
$$

Inversely, when the special UVLO threshold is determined, resistor divider also can be calculated by above equations. Just note again the current flows through this divider. To reduce the current, resistors in the megohm range are recommended.

Soft Start Capacitor

There is an internal 1ms soft start when float SS pin and this is the shortest soft start time. To get longer soft start, it needs to add capacitor between SS pin and GND. The soft start time is the duration when SS is charged from 0 to FB reference voltage 1V by an internal 3μA current source. So the capacitor at SS pin can be chosen according to below formula:

$$
C_{SS} = 3 \times T_{SS} (\mu F)
$$

To get the soft start time longer than 1ms, a capacitor bigger than 3nF is needed. When using a capacitor smaller than 3nF, the soft start time is the internal 1ms soft start.

Feedforward Capacitor

As described above that the PWM control scheme of MP4410 is very special and the HS turn on when FB drops lower than reference voltage. This brings good load transient performance. However, this also makes the HS turn on moment is very sensitive to the FB voltage. Once there is noise on FB, the moment HS turns on is easy to be affected, and then Fsw jitter would occur. The Fsw jitter is easy to happen especially when Vo ripple is very small. To improve the jitter performance, a small feedforward capacitor between Vo and FB can be used and typical 39pF is recommended.

PCB Layout

- 1) Keep the path of switching current short and minimize the loop area formed by input capacitor, high-side, low-side MOSFET and output capacitor.
- 2) Bypass ceramic capacitors should be as close as possible to the VIN pin.
- 3) Make sure that all feedback connections are short and direct. Place the feedback resistors as close to the chip as possible.
- 4) Keep SW away from sensitive analog areas such as FB.
- 5) For better thermal performance and long-term reliability consideration, VIN, SW and GND should be connected to a large copper area respectively to cool the chip.

Figure 7 – PCB Layout Example

Design Example

Below is a design example following the application guidelines for the specifications:

Table 2— Design Example

	. .
	$4.5V - 36V$
V _{ουτ}	3.3V
lo	100 _m A

The detailed application schematic is shown in Figure 8. The typical performance and circuit waveforms have been shown in the Typical Performance Characteristics section. For more device applications, please refer to the related Evaluation Board Datasheets.

Figure 8 — **Detailed Application Schematic**

TYPICAL APPLICATION CIRCUITS

Figure 9 – 3.3V/100mA Output Typical Application Circuit

Figure 10 – 3.3V/50mA Output Typical Application Circuit

Figure 11 – 5V/100mA Output Typical Application Circuit

PACKAGE INFORMATION

SIDE VIEW

DETAIL A

RECOMMENDED LAND PATTERN

NOTE:

 1) ALL DIMENSIONS ARE IN MILLIMETERS.

- **2) EXPOSED PADDLE SIZE DOES NOT INCLUDE MOLD FLASH.**
- **3) LEAD COPLANARITY SHALL BE 0.10 MILLIMETER MAX.**
- **4) DRAWING CONFORMS TO JEDEC MO-229, VARIATION VEED-5. 5) DRAWING IS NOT TO SCALE.**

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Телефон: 8 (812) 309-75-97 (многоканальный) Факс: 8 (812) 320-03-32 Электронная почта: ocean@oceanchips.ru Web: http://oceanchips.ru/ Адрес: 198099, г. Санкт-Петербург, ул. Калинина, д. 2, корп. 4, лит. А