

GENERAL DESCRIPTION

The XRT71D03 is a three channel, single chip Jitter Attenuator, that meets the Jitter transfer characteristics requirements specified in the ETSI TBR-24, Bellcore GR-499 and GR-253 standards.

In addition, the XRT71D03 also meets the Jitter and Wander specifications described in the ANSI T1.105.03b 1997, Bellcore GR-253 and GR-499 standards.

FEATURES

- Meets the E3/DS3/STS-1 jitter requirements
- No external components required
- Compliant with jitter transfer template outlined in ITU G.751, G.752, G.755, GR-235-CORE, GR-499-CORE, 1995 standards

- Meets output jitter requirement as specified by ETSI TBR24
- Meets the Jitter and Wander specifications described in T1.105.03b, GR-253 and GR-499 standards.
- Selectable buffer size of 16 and 32 bits
- Jitter attenuator can be disabled
- Available in a 64 pin LQFP package.
- Single 3.3V or 5.0V supply.
- Operates over - 40° C to 85° C temperature range.

APPLICATIONS

- E3/DS3 Access Equipment.
- DSLAMs

FIGURE 1. BLOCK DIAGRAM OF THE XRT71D03

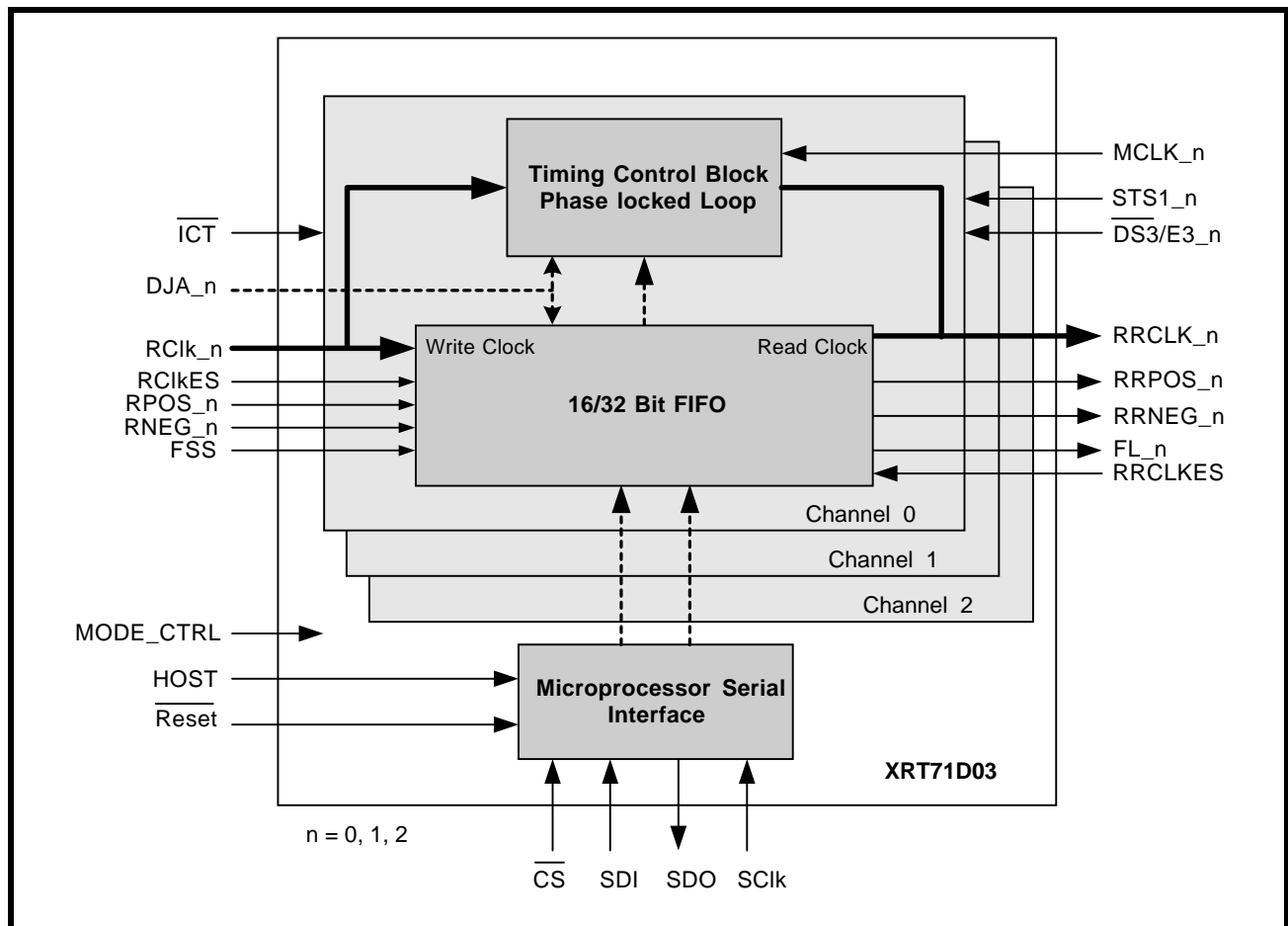
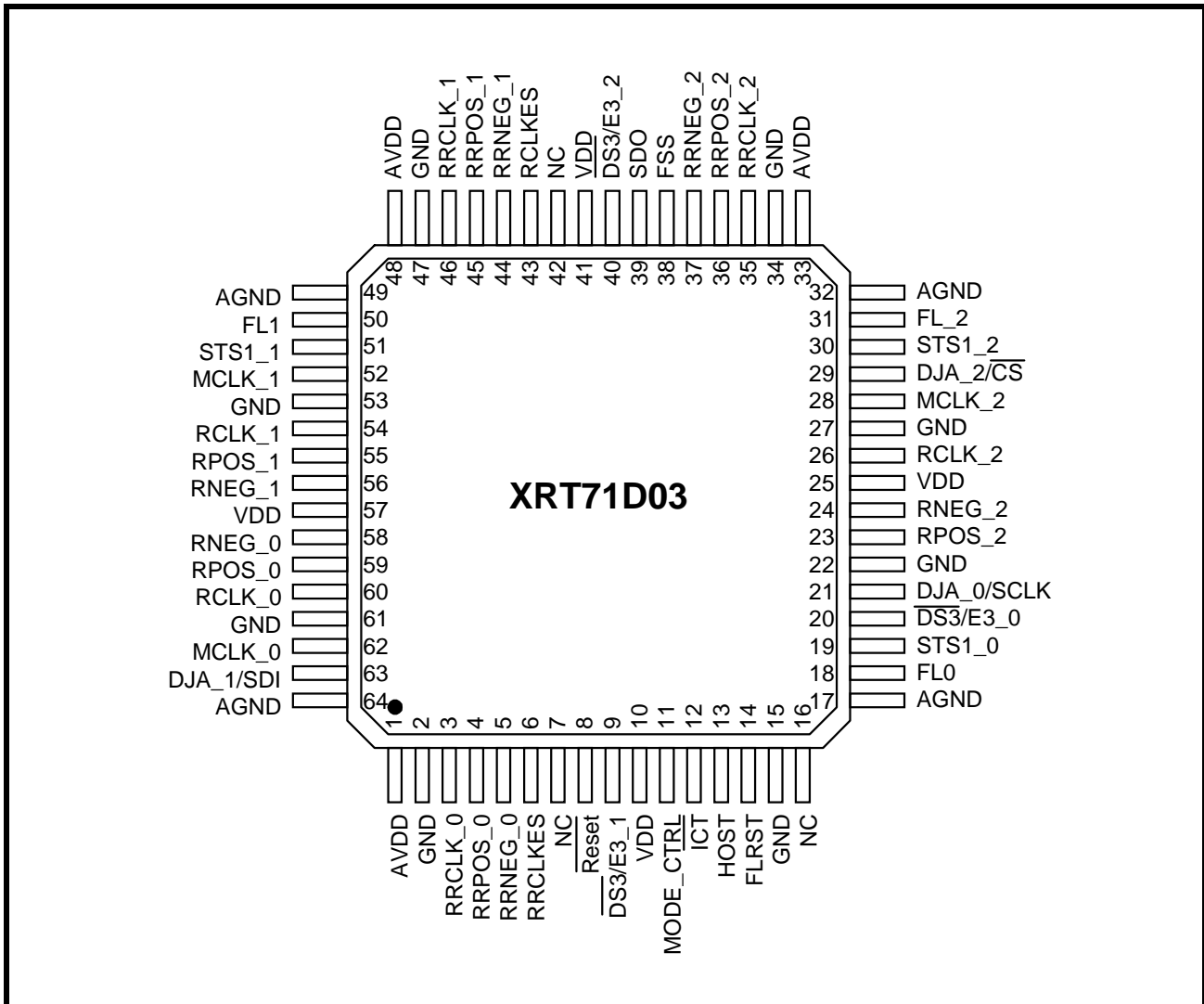


FIGURE 2. PIN OUT OF THE XRT71D03



ORDERING INFORMATION

| PART NUMBER | PACKAGE | OPERATING TEMPERATURE RANGE |
|-------------|-------------|-----------------------------|
| XRT71D03IV | 64 Pin TQFP | -40°C to +85°C |

TABLE OF CONTENTS

| | |
|---|------------------|
| GENERAL DESCRIPTION | 1 |
| FEATURES | 1 |
| APPLICATIONS | 1 |
| <i>Figure 1. Block Diagram of the XRT71D03</i> | <i>1</i> |
| <i>Figure 2. Pin Out of the XRT71D03</i> | <i>2</i> |
| ORDERING INFORMATION | 2 |
| TABLE OF CONTENTS..... | 1 |
| PIN DESCRIPTIONS | 3 |
| ELECTRICAL CHARACTERISTICS | 9 |
| <i>Figure 3. Input/Output Timing</i> | <i>9</i> |
| <i>Figure 4. Timing Diagram for the Microprocessor Serial Interface</i> | <i>10</i> |
| SYSTEM DESCRIPTION | 12 |
| <i>Figure 5. Illustration of a typical Channel_n of the XRT71D03 configured to operate in the Hardware Mode</i> | <i>12</i> |
| <i>Figure 6. Illustration of a typical Channel_n of the XRT71D03 (configured to operate in the Host Mode)</i> | <i>13</i> |
| 1.0 Jitter Attenuator PLL | 13 |
| 1.1 BACKGROUND INFORMATION DEFINITION OF JITTER | 13 |
| 1.2 JITTER TRANSFER CHARACTERISTICS..... | 13 |
| <i>Figure 7. Category 1 DS3 Jitter Transfer Mask</i> | <i>14</i> |
| 1.2.1 Jitter Tolerance | 14 |
| 1.2.2 Jitter Generation..... | 14 |
| 1.2.3 Jitter Attenuation | 14 |
| 1.3 XRT71D03 JITTER TRANSFER AND TOLERANCE..... | 15 |
| TABLE 1: XRT71D03 JITTER TRANSFER FUNCTION | 15 |
| <i>Figure 8. DS3 Jitter Transfer Characteristics</i> | <i>16</i> |
| <i>Figure 9. E3 Jitter Transfer Characteristics</i> | <i>16</i> |
| <i>Figure 10. STS-1 Jitter Transfer Characteristics</i> | <i>17</i> |
| TABLE 2: XRT71D03 MAXIMUM JITTER TOLERANCE | 18 |
| 2.0 Operating Modes | 19 |
| 2.1 HARDWARE MODE..... | 19 |
| TABLE 3: FUNCTIONS OF DUAL MODE PINS IN HARDWARE MODE CONFIGURATION | 19 |
| 2.2 HOST MODE..... | 19 |
| TABLE 4: ADDRESS AND BIT FORMATS OF THE COMMAND REGISTERS | 19 |
| 3.0 Microprocessor Serial Interface | 19 |
| 3.1 SERIAL INTERFACE OPERATION..... | 19 |
| 3.1.1 Bit 1—R/W (Read/Write) Bit..... | 19 |
| 3.1.2 Bits 2 through 5—A0, A1, A2, A3, and A4 | 19 |
| 3.1.3 Bit 7—A5 | 19 |
| 3.1.4 Bit 8—A6 | 19 |
| 3.1.5 Read Operation..... | 19 |
| 3.1.6 Write Operation..... | 20 |
| <i>Figure 11. Microprocessor Serial Interface Data Structure</i> | <i>20</i> |
| 3.1.7 Simplified Interface Option..... | 20 |
| <i>Figure 12. Timing Diagram for the Microprocessor Serial Interface</i> | <i>21</i> |
| ORDERING INFORMATION | 22 |
| PACKAGE DIMENSIONS | 22 |
| REVISION HISTORY | 23 |

PIN DESCRIPTIONS

PIN DESCRIPTION

| PIN # | NAME | TYPE | DESCRIPTION | | | | | | | | | | | | | | | |
|-------|------------------------------|-------------------------|---|-------|----------------------------|-------------------------|---|---|------------------|---|---|-----------------|---|---|-------------------|---|---|-----------------|
| 1 | AVDD | **** | Analog Power Supply = 5V±5% or 3.3V±5% | | | | | | | | | | | | | | | |
| 2 | GND | **** | Digital Power Supply = 5V±5% or 3.3V±5% | | | | | | | | | | | | | | | |
| 3 | RRCLK_0 | O | Received Recovered Output (De-jittered) Clock - channel 0: Output the de-jittered or smoothed clock if the jitter attenuator is enabled. The de-jittered data, RRPOS/RRNEG are clocked to this signal. If RRCLKES is "low", RRPOS/RRNEG will be updated at the falling edge of RRCLK. If RRCLKES is "high", RRPOS/RRNEG will be updated at the rising edge of RRCLK. | | | | | | | | | | | | | | | |
| 4 | RRPOS_0 | O | Received Recovered Positive Data (De-Jittered) Output - channel 0: De-jittered positive data output. Updated on the rising or falling edge of RRCLK, depending upon the state of the RRCLKES input pin (or bit-field setting). | | | | | | | | | | | | | | | |
| 5 | RRNEG_0 | O | Received Recovered Negative Data (De-Jittered) Output - channel 0: De-jittered negative data output. Updated on the rising or falling edge of RRCLK, depending upon the state of the RRCLKES input pin (or bit-field setting). | | | | | | | | | | | | | | | |
| 6 | RRCLKES | I | Received Recovered Clock Edge Select Input: Hardware Mode: 1. When RRCLKES = "0", then RRPOS and RRNEG are updated on the falling edge of RRCLK 2. When RRCLKES = "1", then RRPOS and RRNEG are updated on the rising edge of RRCLK NOTE: This applies to all channels. Host Mode Connect this pin to GND when the 71D03 is configured in the Host Mode. Internal 50 K Ohm pull-down resistor. | | | | | | | | | | | | | | | |
| 7 | NC | | No Connection | | | | | | | | | | | | | | | |
| 8 | $\overline{\text{Rest}}$ | I | Reset Input. (Active-Low): A high-low transition will re-center the internal FIFO, and will clear the Command Registers (for Host Mode operation). Resetting this pin may corrupt data within the device. For normal operation, pull this pin to VDD. Internal 50 K Ohm pull-up resistor. | | | | | | | | | | | | | | | |
| 9 | $\overline{\text{DS3/E3}}_1$ | I | DS3/E3 Select Input - channel 1: This pin along with the STS-1 mode select pin selects the operating mode. The following table provides the configuration: <table border="1" style="margin-left: auto; margin-right: auto;"> <thead> <tr> <th>STS-1</th> <th>$\overline{\text{DS3/E3}}$</th> <th>XRT71D04 Operating Mode</th> </tr> </thead> <tbody> <tr> <td>0</td> <td>0</td> <td>DS3 (44.736 MHz)</td> </tr> <tr> <td>0</td> <td>1</td> <td>E3 (34.368 MHz)</td> </tr> <tr> <td>1</td> <td>0</td> <td>STS-1 (51.84 MHz)</td> </tr> <tr> <td>1</td> <td>1</td> <td>E3 (34.368 MHz)</td> </tr> </tbody> </table> Internal 50 K Ohm pull-down resistor. | STS-1 | $\overline{\text{DS3/E3}}$ | XRT71D04 Operating Mode | 0 | 0 | DS3 (44.736 MHz) | 0 | 1 | E3 (34.368 MHz) | 1 | 0 | STS-1 (51.84 MHz) | 1 | 1 | E3 (34.368 MHz) |
| STS-1 | $\overline{\text{DS3/E3}}$ | XRT71D04 Operating Mode | | | | | | | | | | | | | | | | |
| 0 | 0 | DS3 (44.736 MHz) | | | | | | | | | | | | | | | | |
| 0 | 1 | E3 (34.368 MHz) | | | | | | | | | | | | | | | | |
| 1 | 0 | STS-1 (51.84 MHz) | | | | | | | | | | | | | | | | |
| 1 | 1 | E3 (34.368 MHz) | | | | | | | | | | | | | | | | |
| 10 | VDD | **** | Digital Power Supply = 5V±5% or 3.3V±5% | | | | | | | | | | | | | | | |

PIN DESCRIPTION

| PIN # | NAME | TYPE | DESCRIPTION | | | | | | | | | | | | | | | |
|-------|----------------------------|-------------------------|--|-------|----------------------------|-------------------------|---|---|------------------|---|---|-----------------|---|---|-------------------|---|---|-----------------|
| 11 | MODE_CTRL | I | Mode Control: When "High" in Multimode, all channels are independent. When "Low", the Master Channel (channel0) controls DS3/E3_n, STS1_n, RCLKES, FSS and MCLKn. DJA is NOT affected. Internal 50 K Ohm pull-up resistor. | | | | | | | | | | | | | | | |
| 12 | $\overline{\text{ICT}}$ | I | In Circuit Testing Input. (Active low): With this pin tied to ground, all output pins will be in high impedance mode for in-circuit-testing. For normal operation this input pin should be tied to VDD. Internal 50 K Ohm pull-up resistor. | | | | | | | | | | | | | | | |
| 13 | HOST | I | Host/Hardware Mode Select: An active-high input enables the Host mode. Data is written to the command registers to configure the XRT71D04. In the Host mode, the states of discrete input pins are inactive. An active-low input enables the Hardware Mode. In this mode, the discrete inputs are active. Internal 50 K Ohm pull-down resistor. | | | | | | | | | | | | | | | |
| 14 | FLRST | I | Fifo Limit Reset Hardware Mode Whenever the FIFO is within 2 bits of either underflow or overflow, the FLn) will be set high. This pin allows the user to reset the state of FL_n, (FIFO Limit) output pin. This pin when pulsed "High", resets the the FL_n output pin, (toggles to GND). <i>NOTE: The FL_n could be set "High" again if the FIFO is within 2 bits of either underflow or overflow.</i> Host Mode Reading the FL_n bits in the status registers clears the FL_n pin. Master RESET also clears the FL_n output. This pin is tied to GND. FLRST has no effect in this mode. Internal 50 K Ohm pull-down resistor. | | | | | | | | | | | | | | | |
| 15 | GND | **** | Digital Ground | | | | | | | | | | | | | | | |
| 16 | NC | | No Connection | | | | | | | | | | | | | | | |
| 17 | AGND | **** | Analog Ground | | | | | | | | | | | | | | | |
| 18 | FL_0 | O | FIFO Limit - channel 0: This output pin is driven high whenever the internal FIFO comes within two-bits of being underflow or overflow. | | | | | | | | | | | | | | | |
| 19 | STS1_0 | I | SONET STS1 Mode Select - channel 0: This pin along with the $\overline{\text{DS3/E3}}_0$ select pin configures the XRT71D03 either in E3, DS3 or STS-1 mode. A table relating to the setting of the pins is given below: <table border="1" style="margin-left: 20px;"> <thead> <tr> <th>STS-1</th> <th>$\overline{\text{DS3/E3}}$</th> <th>XRT71D03 Operating Mode</th> </tr> </thead> <tbody> <tr> <td>0</td> <td>0</td> <td>DS3 (44.736 MHz)</td> </tr> <tr> <td>0</td> <td>1</td> <td>E3 (34.368 MHz)</td> </tr> <tr> <td>1</td> <td>0</td> <td>STS-1 (51.84 MHz)</td> </tr> <tr> <td>1</td> <td>1</td> <td>E3 (34.368 MHz)</td> </tr> </tbody> </table> This input pin is active only in the Hardware Mode | STS-1 | $\overline{\text{DS3/E3}}$ | XRT71D03 Operating Mode | 0 | 0 | DS3 (44.736 MHz) | 0 | 1 | E3 (34.368 MHz) | 1 | 0 | STS-1 (51.84 MHz) | 1 | 1 | E3 (34.368 MHz) |
| STS-1 | $\overline{\text{DS3/E3}}$ | XRT71D03 Operating Mode | | | | | | | | | | | | | | | | |
| 0 | 0 | DS3 (44.736 MHz) | | | | | | | | | | | | | | | | |
| 0 | 1 | E3 (34.368 MHz) | | | | | | | | | | | | | | | | |
| 1 | 0 | STS-1 (51.84 MHz) | | | | | | | | | | | | | | | | |
| 1 | 1 | E3 (34.368 MHz) | | | | | | | | | | | | | | | | |

PIN DESCRIPTION

| PIN # | NAME | TYPE | DESCRIPTION |
|-------|------------|------|---|
| 20 | DS3/E3_0 | I | DS3/E3 Select Input - channel 0: See description pin 8. Internal 50 K Ohm pull-down resistor. |
| 21 | DJA_0/SCLK | I | Hardware Mode Disable Jitter Attenuator Input - Channel 0: An active-high disables the Jitter Attenuator. The RPOS/RNEG and RCLK will be passed through without jitter attenuation. Host Mode Microprocessor Serial Interface Clock Signal: This signal will be used to sample the data on the SDI pin, on the rising edge of this signal. Additionally, during "Read" operations, the Microprocessor Serial Interface will update the SDO output on the falling edge of this signal. Internal 50 K Ohm pull-down resistor. |
| 22 | GND | **** | Digital Ground |
| 23 | RPOS_2 | I | Received Positive Data (Jittery) Input: - channel 2: Data that is input on this pin is sampled on either the rising or falling edge of RCLK depending on the setting of the RCLKES pin (pin 10). If RCLKES is "high", then RPOS will be sampled on the falling edge of RCLK. If RCLKES is "low", then RPOS will be sampled on the rising edge of RCLK. Internal 50 K Ohm pull-up resistor. |
| 24 | RNEG_2 | I | Received Negative Data (Jittery) - channel 2: The input jittery negative data is sampled either on the rising or falling edge of RCLK depending on the setting of RCLKES. If RCLKES is "high", then RNEG will be sampled on the falling edge of RCLK. If RCLKES is "low", then RPOS will be sampled on the rising edge of RCLK. This pin is typically tied to the "RNEG" output pin of the LIU. Internal 50 K Ohm pull-up resistor. |
| 25 | VDD | **** | Digital Power Supply = 5V±5% or 3.3V±5% |
| 26 | RCLK_2 | I | Received Clock (Jittery) - channel 2: Clock input RCLK2 should be connected to the recovered clock. Internal 50 K Ohm pull-up resistor. |
| 27 | GND | **** | Digital Ground |
| 28 | MCLK_2 | I | Master Clock Input - channel 2: Reference clock for internal PLL. 44.736MHz±/-20ppm or 34.368MHz±/-20ppm. This clock must be continuous and jitter free with duty cycle between 30 to 70%. It is permissible to use the EXCLK signal or STS1 clock. Internal 50 K Ohm pull-up resistor. |
| 29 | DJA_2/CS | I | Hardware Mode Disable Jitter Attenuator Input - Channel 2: See description of pin 25 Host Mode Chip Select Input: An active-low input enables the serial interface. Internal 50 K Ohm pull-down resistor. |
| 30 | STS1_2 | I | SONET STS1 Mode Select - channel 2: See description pin 19 |

PIN DESCRIPTION

| PIN # | NAME | TYPE | DESCRIPTION |
|-------|-----------------------|------|--|
| 31 | FL_2 | O | FIFO Limit - channel 2: See description pin 18 |
| 32 | AGND | **** | Analog Ground |
| 33 | AVDD | **** | Analog Power Supply =$5\pm 5\%$ or $3.3V\pm 5\%$ |
| 34 | GND | **** | Digital Ground |
| 35 | RRCLK_2 | O | Received Recovered Output (De-jittered) Clock - channel 2: See description of pin 3 |
| 36 | RRPOS_2 | O | Received Recovered Positive Data (De-Jittered) Output - channel 2: See description of pin 4 |
| 37 | RRNEG_2 | O | Received Recovered Negative Data (De-Jittered) Output - channel 2: See description of pin 5 |
| 38 | FSS | I | FIFO Size Select Input: When "High": Selects 32 bits FIFO. When "Low": Selects 16 bits FIFO. Internal 50 K Ohm pull-down resistor. |
| 39 | SDO | O | Serial Data Output: This pin will serially output the contents of the specified Command Register, during "Read" Operations. The data, on this pin, will be updated on the falling edge of the SCLK input signal. This pin will be tri-stated upon completion of data transfer. |
| 40 | $\overline{DS3/E3}_2$ | I | $\overline{DS3/E3}$ Select Input - channel 2: See description pin 8 Internal 50 K Ohm pull-down resistor. |
| 41 | VDD | **** | Digital Power Supply = $5V\pm 5\%$ or $3.3V\pm 5\%$ |
| 42 | NC | | No Connection |
| 43 | RCLKES | I | Received Clock Edge Select Input: Hardware Mode 1. When RCLKES = "0", then RPOS and RNEG are updated on the falling edge of RCLK 2. When RCLKES = "1", then RPOS and RNEG are updated on the rising edge of RCLK NOTE: This applies to all channels. Host Mode Connect this pin to GND when the 71D03 is configured in the Host Mode. Internal 50 K Ohm pull-down resistor. |
| 44 | RRNEG_1 | O | Received Recovered Negative Data (De-Jittered) Output - channel 1: See description of pin 5 |
| 45 | RRPOS_1 | O | Received Recovered Positive Data (De-Jittered) Output - channel 1: See description of pin 4 |

PIN DESCRIPTION

| PIN # | NAME | TYPE | DESCRIPTION |
|-------|---------|------|--|
| 46 | RRCLK_1 | O | Received Recovered Output (De-jittered) Clock - channel 1: See description of pin 3. |
| 47 | GND | **** | Digital Ground |
| 48 | AVDD | **** | Analog Power Supply = 5 V±5% or 3.3V±5% |
| 49 | AGND | **** | Analog Ground |
| 50 | FL_1 | O | FIFO Limit - channel 1: See description pin 18 |
| 51 | STS1_1 | I | SONET STS1 Mode Select - channel 1: See description pin 19 |
| 52 | MCLK_1 | I | Master Clock Input - channel 1: See description pin 28. Internal 50 K Ohm pull-up resistor. |
| 53 | GND | **** | Digital Ground |
| 54 | RCLK_1 | I | Received Clock (Jittery) - channel 1: See description of pin 26. Internal 50 K Ohm pull-up resistor. |
| 55 | RPOS_1 | I | Received Positive Data (Jittery) Input: - channel 1: See description of pin 23. Internal 50 K Ohm pull-up resistor. |
| 56 | RNEG_1 | I | Received Negative Data (Jittery) - channel 1: See description of pin 24. Internal 50 K Ohm pull-up resistor. |
| 57 | VDD | **** | Digital Power Supply = 5V±5% or 3.3V±5% |
| 58 | RNEG_0 | I | Received Negative Data (Jittery) - channel 0: See description of pin 24. Internal 50 K Ohm pull-up resistor. |
| 59 | RPOS_0 | I | Received Positive Data (Jittery) Input: - channel 0: See description of pin 23. Internal 50 K Ohm pull-up resistor. |
| 60 | RCLK_0 | I | Received Clock (Jittery) - channel 0: See description of pin 26. Internal 50 K Ohm pull-up resistor. |
| 61 | GND | **** | Digital Ground |
| 62 | MCLK_0 | I | Master Clock Input - channel 0: See description pin 28. Internal 50 K Ohm pull-up resistor. |

PIN DESCRIPTION

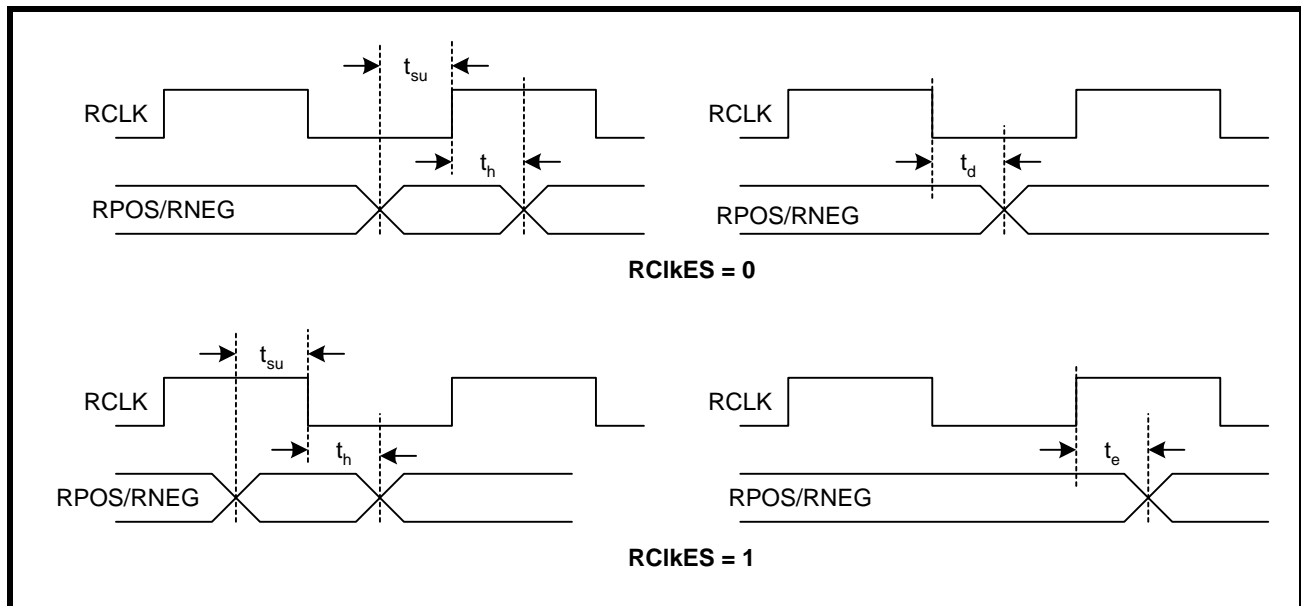
| PIN # | NAME | TYPE | DESCRIPTION |
|--------------|-------------|-------------|---|
| 63 | DJA_1/SDI | I | Hardware Mode Disable Jitter Attenuator Input - Channel 1: See description of pin 25 Host Mode Serial Data Input The address value (of the command registers) or the data value is either Read or Written through this pin. The input data will be sampled on the rising edge of the SCLK pin. Internal 50 K Ohm pull-down resistor. |
| 64 | AGND | **** | Analog Ground |

ELECTRICAL CHARACTERISTICS

AC Electrical Characteristics

| Electrical Characteristics (TA = 25°C, VDD = 3.3 V to 5.0 V ± 5% unless otherwise specified) | | | | | |
|--|--------------------------------------|-----|--------|-----|--------|
| SYMBOL | PARAMETER | MIN | TYP | MAX | UNITS. |
| MClk | Duty Cycle | 30 | 50 | 70 | % |
| MClk | Frequency E3 ± 20 ppm | | 34.368 | | MHz |
| MClk | Frequency DS3 ± 20 ppm | | 44.736 | | MHz |
| MClk | Frequency STS-1 ± 20 ppm | | 51.84 | | MHz |
| RClk | Duty Cycle | 30 | 50 | 70 | % |
| RClk | Rise Time | | | 5 | ns |
| RClk | Fall Time | | | 5 | ns |
| t _{su} | RPOS/RNEG to RClk rise time setup | 3 | 2 | | ns |
| t _h | RPOS/RNEG to RClk rising hold time | 1 | 2 | | ns |
| t _d | RRPOS/RRNEG delay from RRClk rising | | 3 | 5 | ns |
| t _e | RRPOS/RRNEG delay from RRClk falling | | 3 | 5 | ns |

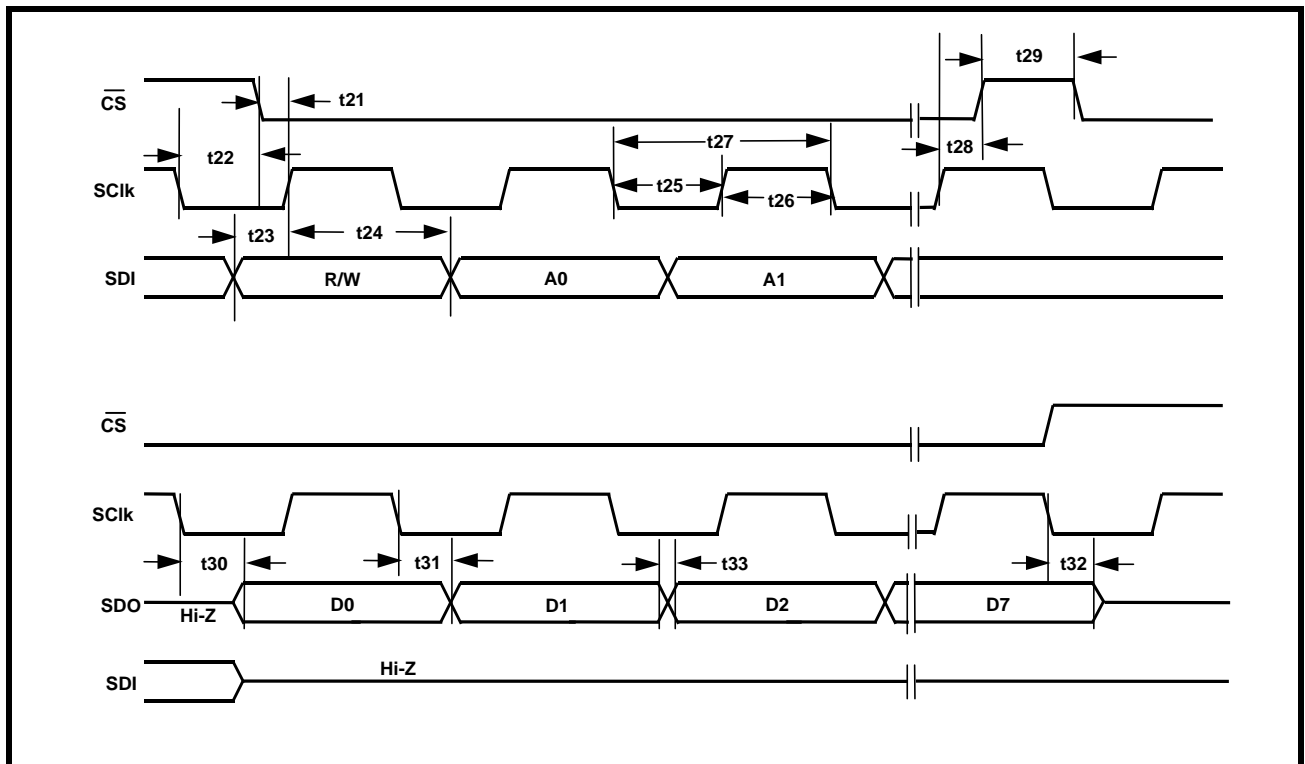
FIGURE 3. INPUT/OUTPUT TIMING



Microprocessor Serial Interface Timing (see Figure 4)

| Electrical Characteristics (TA = 25°C, VDD = 3.3 V t0 5.0 V± 5 % unless otherwise specified) | | | | | |
|---|---|------------|------------|------------|---------------|
| SYMBOL | PARAMETER | MIN | TYP | MAX | UNITS. |
| t21 | CS Low to Rising Edge of SClk Setup Time | 50 | | | ns |
| t22 | SClk to \overline{CS} Hold Time | 20 | | | ns |
| t23 | SDI to Rising Edge of SClk Setup Time | 50 | | | ns |
| t24 | SDI to Rising Edge of SClk Hold Time | 50 | | | ns |
| t25 | SClk "Low" Time | 240 | | | ns |
| t26 | SClk "High" Time | 240 | | | ns |
| t27 | SClk Period | 500 | | | ns |
| t28 | SClk to CSB Hold Time | 50 | | | ns |
| t29 | \overline{CS} "Inactive" Time | 250 | | | ns |
| t30 | Falling Edge of SClk to SDO Valid Time | | | 200 | ns |
| t31 | Falling Edge of SClk to SDO Invalid Time | | | 100 | ns |
| t32 | Falling Edge of SClk, or rising edge of \overline{CS} to High Z | | 100 | | ns |

FIGURE 4. TIMING DIAGRAM FOR THE MICROPROCESSOR SERIAL INTERFACE



DC Electrical Characteristics (TA = 25 °C, VDD = 3.3 V ± 5% unless otherwise specified)

| PARAMETER | SYMBOL | MIN | TYP | MAX | UNITS |
|--|-----------------|-------|-----|-------|-------|
| Power Supply Voltage | VDD | 3.135 | 3.3 | 3.465 | V |
| Input High Voltage | VIH | 2.0 | | 5.25 | V |
| Input Low Voltage | V _{IL} | -0.5 | | 0.8 | V |
| Output High Voltage @ IOH=-5mA | VOH | 2.4 | | | V |
| Output Low Voltage @ IOL=5mA | VOL | | | 0.4 | V |
| Supply Current (E3) @VDD = 3.465V | I _{cc} | | 75 | 85 | mA |
| Supply Current (DS3) @VDD = 3.465V | I _{cc} | | 95 | 109 | mA |
| Supply Current (STS-1) @VDD = 3.465V | I _{cc} | | 105 | 120 | |
| Input Leakage Current (except Input pins with Pull-up resistor). | IL | | | ± 10 | μA |
| Input Capacitance | CI | | 5.0 | | pF |
| Output Load Capacitance | C _L | | | 25 | pF |

DC Electrical Characteristics (TA = 25 °C, VDD = 5.0 V ± 5% unless otherwise specified)

| PARAMETER | SYMBOL | MIN | TYP | MAX | UNITS |
|--|-----------------|------|-----|------|-------|
| Power Supply Voltage | VDD | 4.75 | 5.0 | 5.25 | V |
| Input High Voltage | VIH | 2.0 | | 5.25 | V |
| Input Low Voltage | V _{IL} | -0.5 | | 0.8 | V |
| Output High Voltage @ IOH=-5mA | VOH | 2.4 | | | V |
| Output Low Voltage @ IOL=5mA | VOL | | | 0.4 | V |
| Supply Current (E3) @VDD = 5.25V | I _{cc} | | 120 | 136 | mA |
| Supply Current (DS3) @VDD = 5.25V | I _{cc} | | 145 | 160 | mA |
| Supply Current (STS-1) @VDD = 5.25V | I _{cc} | | 160 | 180 | |
| Input Leakage Current (except Input pins with Pull-up resistor). | IL | | | ± 10 | μA |
| Input Capacitance | CI | | 5.0 | | pF |
| Output Load Capacitance | C _L | | | 25 | pF |

ABSOLUTE MAXIMUM RATINGS:

| | |
|-----------------------|--|
| Supply Range | -0.5 V to + 6.0 V |
| ESD Rating | > 2000 V on all pins |
| Operating Temperature | -40 ⁰ C to +85 ⁰ C |
| Storage Temperature | -65 ⁰ C to + 150 ⁰ C |

SYSTEM DESCRIPTION

The XRT71D03 is an integrated 3-channel E3/DS3/STS-1 jitter attenuator that attenuates the jitter from the input clock and data. The jitter attenuation performance meets the latest specifications such as Bellcore GR-499 CORE, GR-253 CORE, ETSI TBR24, ITU-T G.751, ITU-T G.752 and ITU-T G.755 standards.

In addition, the XRT71D03 also meets both the mapping and pointer adjustment jitter generation criteria for both Category I and Category II interfaces as specified in Bellcore GR-253.

The XRT71D03 also meets the DS3 wander specification that apply to SONET and asynchronous interfaces as specified in the ANSI T1.105.03b 1997 standard.

Additionally, to support loop-timing applications, the XRT71D03 can also be used to reduce and limit the amount of jitter in the recovered line clock signal.

Figure 5 presents a simple block diagram of the XRT71D03, when it is configured to operate in the Hardware Mode and Figure 6 presents a simple block diagram of the XRT71D03, when it is configured to operate in the Host Mode.

FIGURE 5. ILLUSTRATION OF A TYPICAL CHANNEL_N OF THE XRT71D03 CONFIGURED TO OPERATE IN THE HARDWARE MODE

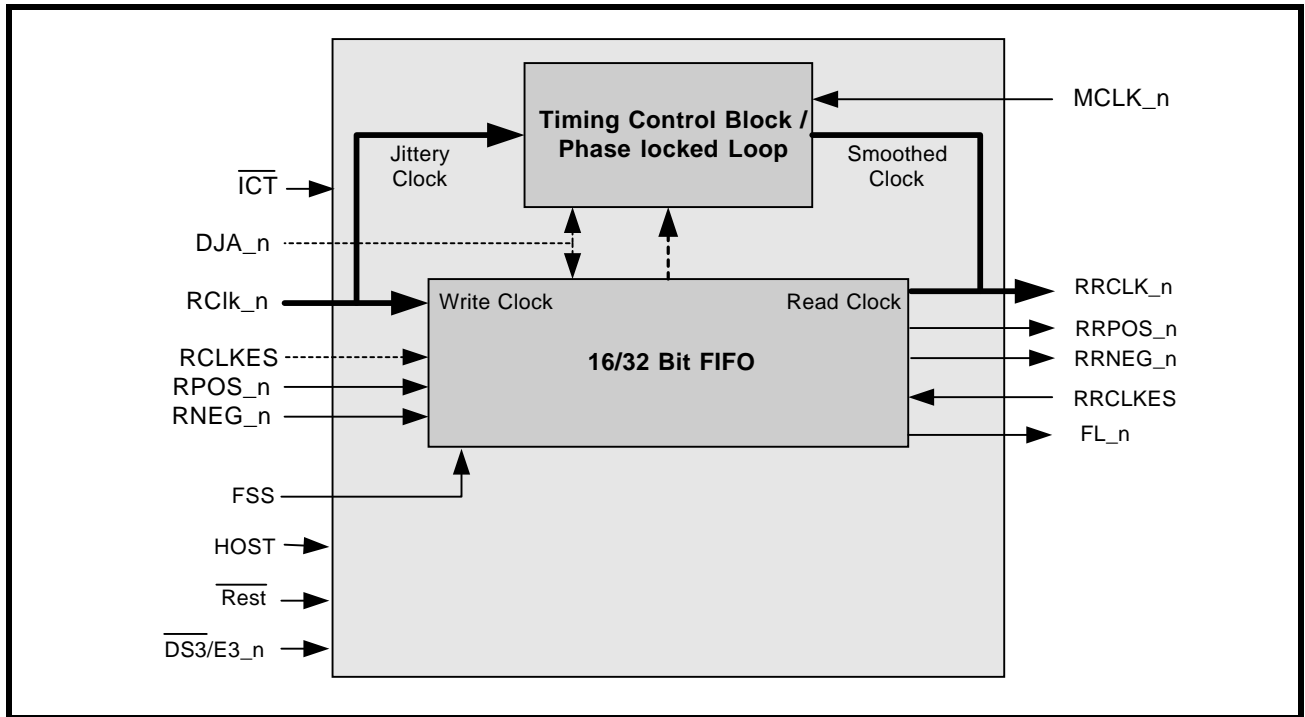
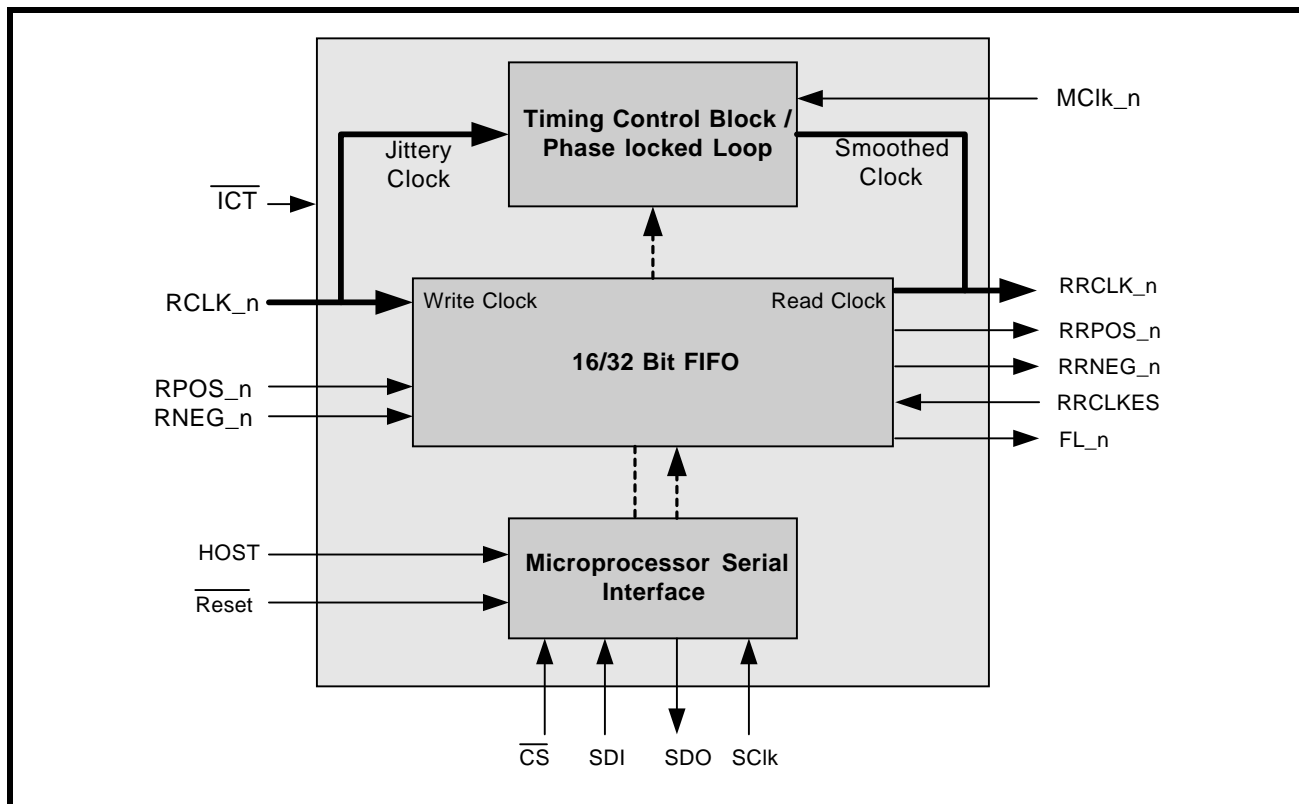


FIGURE 6. ILLUSTRATION OF A TYPICAL CHANNEL_N OF THE XRT71D03 (CONFIGURED TO OPERATE IN THE HOST MODE)



The XRT71D03 DS3/E3 Jitter Attenuator IC consists of the following functional blocks:

- The Jitter-Attenuator PLL
- Timing Control Block
- The 2-Channel 16/32 Bit FIFO
- Serial Microprocessor Interface

1.0 JITTER ATTENUATOR PLL

1.1 BACKGROUND INFORMATION DEFINITION OF JITTER

One of the most important and least understood measures of clock performance is jitter. The International Telecommunication Union defines jitter as short term variations of the significant instants of a digital signal

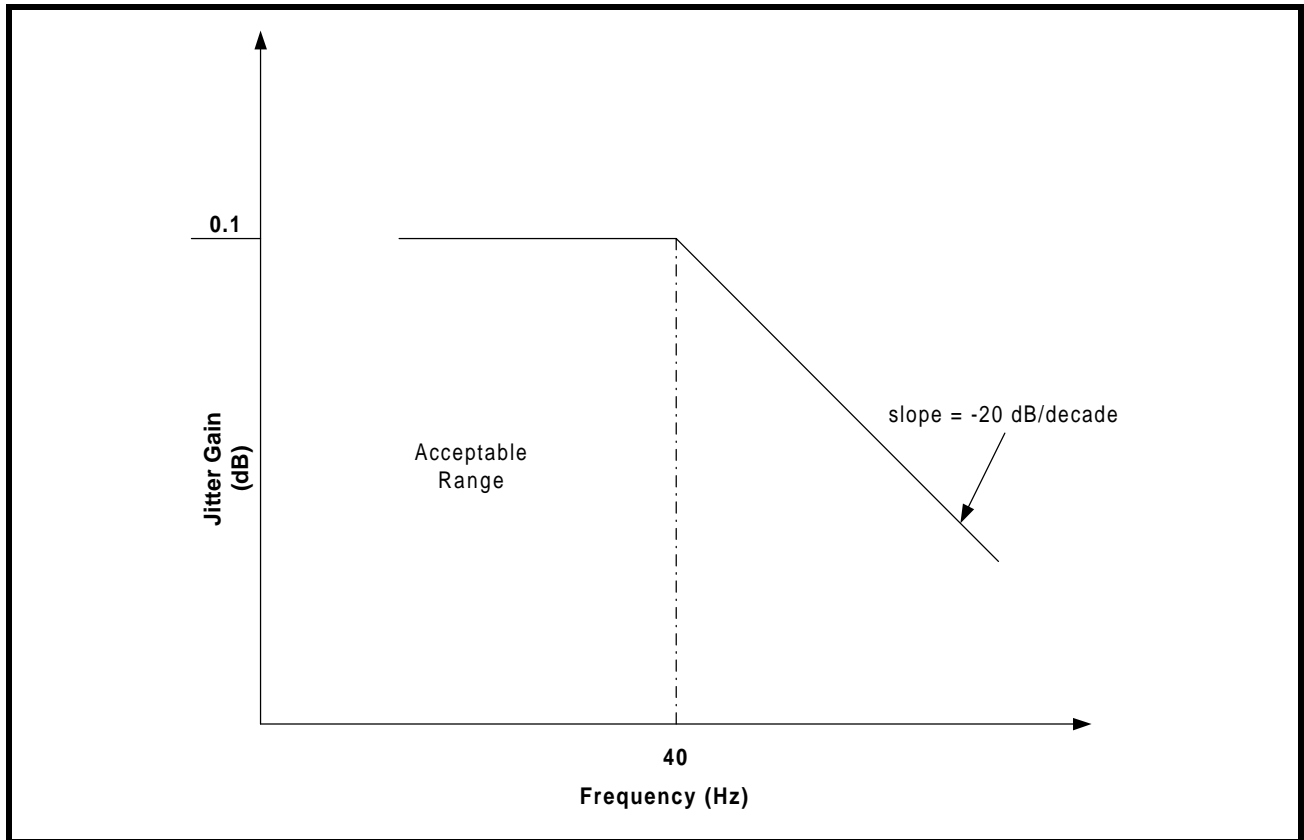
from their ideal positions in time. Jitter can occur due to any of the following:

- 1) Imperfect timing recovery circuit in the system
- 2) Cross-talk noise
- 3) Inter-symbol interference/Signal Distortion

1.2 JITTER TRANSFER CHARACTERISTICS

The primary purpose of jitter transfer requirements is to prevent performance degradations by limiting the accumulation of jitter through the system such that it does not exceed the network interface jitter requirements. Thus, it is more important that a system meet the jitter transfer criteria for relatively high input jitter amplitudes. The jitter transferred through the system must be under the jitter mask for any input jitter amplitude within the range as shown in Figure 7

FIGURE 7. CATEGORY 1 DS3 JITTER TRANSFER MASK



1.2.1 Jitter Tolerance

The jitter tolerance in the network element is defined as the maximum amount of jitter in the incoming signal that it can receive in an error-free manner.

1.2.2 Jitter Generation

Jitter generation is defined in Section 7.3.3 of GR-499-CORE. Jitter generation criteria exists for both Category I and II interfaces, which consist of mapping and pointer adjustment jitter generation.

Mapping jitter is the sum of the intrinsic payload mapping jitter and the jitter that is generated as a result of the bit stuffing mechanisms used in all of the asynchronous DS_n mapping into STS SPE.

1.2.3 Jitter Attenuation

A digital Jitter Attenuation loop combined with the FIFO provides Jitter attenuation. The Jitter Attenuator requires no external components except for the reference clock.

Data is clocked into the FIFO with the associated clock signal (TClk or RClk) and clocked out of the FIFO with the dejittered clock and data. When the

FIFO is within 2 bits of being completely full, the FIFO Limit (FL) will be set.

In Figure 5 and Figure 6, this de-jittered clock is labeled Smoothed Clock. This Smoothed Clock is now used to Read Out the Recovered Data from the 16/32 bit FIFO. This Smoothed Clock will also be output to the Terminal Equipment via the RRClk output pin. Likewise, the Smoothed Recovered Data will output to the Terminal Equipment via the RRPOS and RRNEG output pins.

The XRT71D03 is designed to work as a companion device with XRT73L03 (STS-1/DS3/E3) Line Interface Unit.

ETSI TBR24 specifies the maximum output jitter in loop timing must be no more than 0.4UIpp when measured between 100Hz to 800KHz with up to 1.5UI input jitter at 100Hz. This means a jitter attenuator with bandwidth less than 100Hz is required to be compliant with the standard. ITU G.751 is another application where low bandwidth jitter attenuator is needed to smooth the gapped clock output in the de-multiplexer system.

1.3 XRT71D03 JITTER TRANSFER AND TOLERANCE
 Table 1 summarizes the results of jitter transfer characteristics testing, performed on the XRT71D03.

Table 2 summarizes the results of jitter tolerance testing, performed on the XRT71D03.
 Graphs of the measured Jitter Transfer are shown in Figure 8, Figure 9 and Figure 10.

TABLE 1: XRT71D03 JITTER TRANSFER FUNCTION

| APPLICATION | DS3 | | E3 | | STS-1 | |
|--------------|------------------|--------|------------------|--------|------------------|--------|
| INPUT JITTER | 1UIPP | 10UIPP | 1UIPP | 10UIPP | 1UIPP | 10UIPP |
| FREQ. (HZ) | Jitter Gain (dB) | | Jitter Gain (dB) | | Jitter Gain (dB) | |
| 10 | -0.10 | -0.30 | -0.15 | -0.22 | 0.22 | 0.53 |
| 20 | -2.04 | -2.24 | -3.16 | -3.24 | -0.69 | -1.09 |
| 30 | -3.63 | -4.33 | -5.51 | -5.93 | -5.92 | -3.01 |
| 40 | -5.98 | -6.16 | -7.68 | -7.99 | -8.10 | -4.74 |
| 50 | -7.55 | -7.82 | -10.36 | -9.61 | -10.17 | -6.33 |
| 60 | -9.57 | -9.17 | -12.50 | -11.27 | -11.24 | -7.64 |
| 80 | -12.54 | -11.28 | -15.20 | -13.59 | -13.65 | -9.98 |
| 100 | -14.67 | -13.36 | -16.22 | -15.51 | -14.78 | -11.92 |
| 125 | -16.67 | -14.91 | -17.38 | -17.07 | -16.94 | -13.75 |
| 150 | -17.32 | -16.78 | -19.45 | -18.75 | -17.38 | -15.23 |
| 200 | -18.77 | -18.96 | -20.36 | -21.11 | -19.57 | -17.41 |
| 300 | -21.43 | -21.81 | -22.96 | -24.46 | -21.96 | -21.69 |
| 500 | -22.22 | -26.09 | -23.78 | -28.84 | -23.59 | -25.47 |
| >1000 | -25.42 | -33.44 | -23.51 | -35.77 | -25.76 | -32.99 |
| 2000 | | | | | -26.27 | -39.83 |
| 3000 | | | | | -27.41 | -41.95 |
| 5000 | | | | | -26.15 | -44.16 |

FIGURE 8. DS3 JITTER TRANSFER CHARACTERISTICS

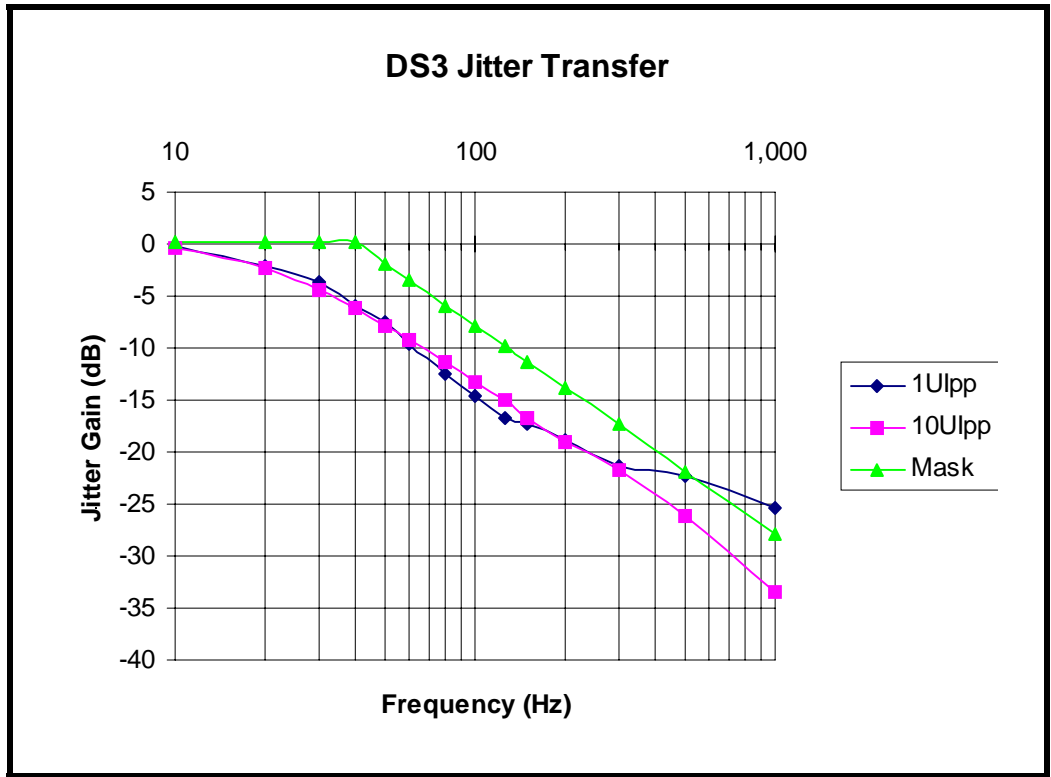


FIGURE 9. E3 JITTER TRANSFER CHARACTERISTICS

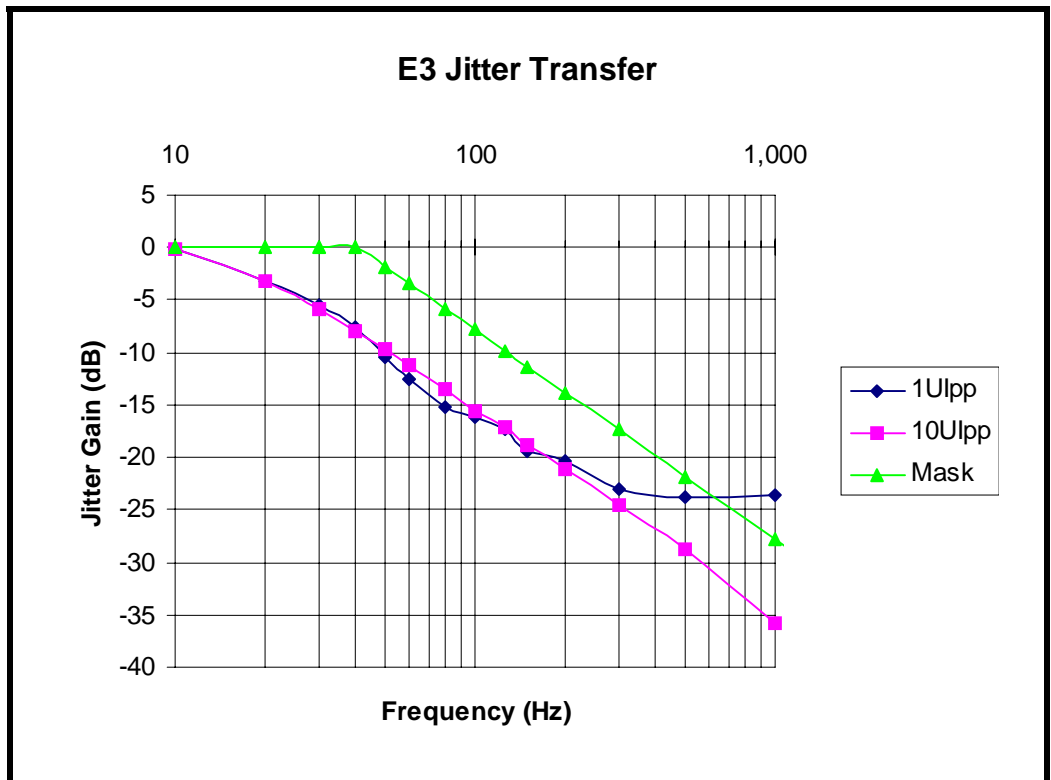


FIGURE 10. STS-1 JITTER TRANSFER CHARACTERISTICS

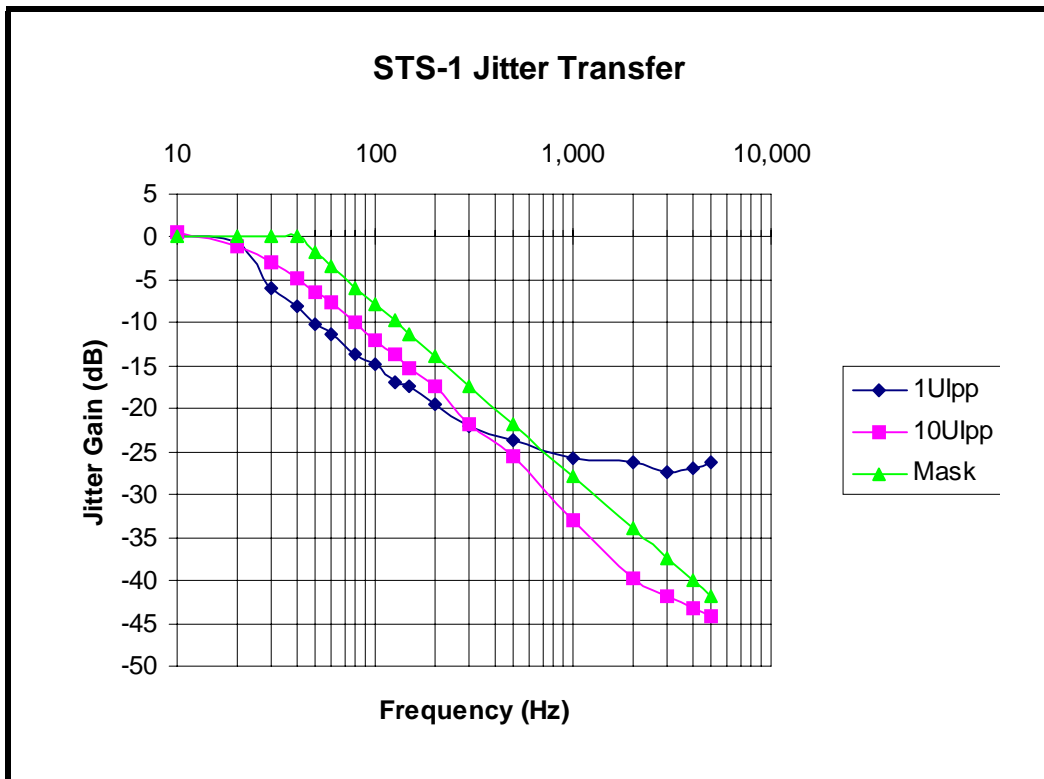


TABLE 2: XRT71D03 MAXIMUM JITTER TOLERANCE

| APPLICATION | DS3 | | E3 | | STS-1 | |
|-------------|-------------------|--------|-------------------|--------|-------------------|--------|
| FIFO SIZE | 16 | 32 | 16 | 32 | 16 | 32 |
| FREQ. (HZ) | UI (PEAK TO PEAK) | | UI (PEAK TO PEAK) | | UI (PEAK TO PEAK) | |
| 10 | 34.313 | >64 | 26.689 | 53.313 | 38.938 | >64 |
| 20 | 21.439 | 43.188 | 18.564 | 37.438 | 22.689 | 44.813 |
| 30 | 18.314 | 36.813 | 16.689 | 33.938 | 18.939 | 37.688 |
| 40 | 16.939 | 34.313 | 16.064 | 32.688 | 17.439 | 34.938 |
| 50 | 16.314 | 33.188 | 15.689 | 32.063 | 16.814 | 33.563 |
| 60 | 16.064 | 32.563 | 15.564 | 31.689 | 16.439 | 32.813 |
| 80 | 15.689 | 31.814 | 15.314 | 31.314 | 16.064 | 32.063 |
| 100 | 15.439 | 31.439 | 15.314 | 31.189 | 15.814 | 31.814 |
| 125 | 15.439 | 31.314 | 15.189 | 31.064 | 15.689 | 31.564 |
| 150 | 15.314 | 31.189 | 15.189 | 31.064 | 15.689 | 31.439 |
| 200 | 15.314 | 31.064 | 15.189 | 30.939 | 15.564 | 31.314 |
| 300 | 15.189 | 30.939 | 15.064 | 30.939 | 15.564 | 31.189 |
| 500 | 15.189 | 30.939 | 15.064 | 30.939 | 15.564 | 31.189 |
| >1000 | 15.0189 | 30.939 | 15.189 | 30.939 | 15.439 | 31.189 |
| | | | | | 15.439 | 31.189 |
| | | | | | 15.439 | 26.189 |
| | | | | | 15.439 | 16.189 |

2.0 OPERATING MODES

2.1 HARDWARE MODE

The HOST pin is used to select the operating mode of the XRT71D03. In Hardware mode (connect this pin to ground), the serial processor interface is disabled and hard-wired pins are used to control configuration and report status.

TABLE 3: FUNCTIONS OF DUAL MODE PINS IN HARDWARE MODE CONFIGURATION

| PIN # | PIN NAME | FUNCTION, WHILE IN THE HARDWARE MODE |
|-------|--------------------------|--------------------------------------|
| 63 | DJA_1/(SDI) | DJA_1 |
| 21 | DJA_0/SCLK | DJA_0 |
| 29 | DJA_2(\overline{CS}) | DJA_2 |

2.2 HOST MODE

In Host mode (connect the HOST pin to VDD), the serial port interface pins are used to control configuration and status report. In this mode, serial interface pins, SDI, SDO, SCLK and \overline{CS} are used.

A listing of these Command Registers, their Addresses and their bit-formats are listed below in Table 4.

TABLE 4: ADDRESS AND BIT FORMATS OF THE COMMAND REGISTERS

| ADDR | COMMAND REGISTER | TYPE | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|------|------------------|------|-----|-----|---------|-----------------------|-------|-----------|----------|-------|
| 0X06 | CR6 | R/W | *** | *** | STS-1_0 | $\overline{DS3/E3_0}$ | DJA_0 | RRCIKES_0 | RCIKES_0 | FSS_0 |
| 0x07 | CR7 | RO | *** | *** | *** | *** | *** | | *** | FL_0 |
| 0x0E | CR14 | R/W | *** | *** | STS-1_1 | $\overline{DS3/E3_1}$ | DJA_1 | RRCIKES_1 | RCIKES_1 | FSS_1 |
| 0x0F | CR15 | RO | *** | *** | *** | *** | *** | | *** | FL_1 |
| 0x16 | CR22 | R/W | *** | *** | STS-1_2 | $\overline{DS3/E3_2}$ | DJA_2 | RRCIKES_2 | RCIKES_2 | FSS_2 |
| 0x17 | CR23 | RO | *** | *** | *** | *** | *** | | *** | FL_2 |

3.0 MICROPROCESSOR SERIAL INTERFACE

The serial interface for the XRT71D03 and the XRT73L00 family of E3/DS3/STS-1 LIU's are the same, which makes it easy to configure both the XRT71D03 and the LIU with a single \overline{CS} , SDI, SDO and SCLK input and output pins.

3.1 SERIAL INTERFACE OPERATION.

Serial interface data structure and timings are provided in Figure 5 and 6 respectively.

The clock signal is provided to the SCLK and the \overline{CS} is asserted for 50 ns prior to the first rising edge of the SCLK.

3.1.1 Bit 1—R/W (Read/Write) Bit

This bit will be clocked into the SDI input, on the first rising edge of SCLK (after \overline{CS} has been asserted). This bit indicates whether the current operation is a Read or Write operation.

A "1" in this bit specifies a Read operation, a "0" in this bit specifies a Write operation.

3.1.2 Bits 2 through 5—A0, A1, A2, A3, and A4

The five (5) bit Address Values (labeled A0, A1, A2, A3, and A4).

The next five rising edges of the SCLK signal will clock in the 5-bit address value for this particular Read (or Write) operation. The address selects the Command Register for reading data from, or writing data to. The address bits to the SDI input pin is applied in ascending order with the LSB (least significant bit) first.

3.1.3 Bit 7—A5

A5 must be set to "0", as shown in Figure 11.

3.1.4 Bit 8—A6

The value of A6 is a don't care.

Once these first 8 bits have been written into the Serial Interface, the subsequent action depends upon whether the current operation is a Read or Write operation.

3.1.5 Read Operation

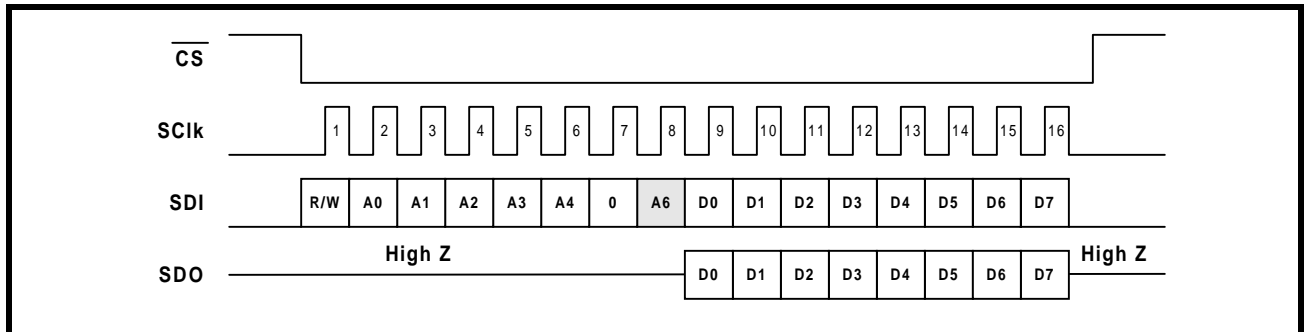
Once the last address bit (A4) has been clocked into the SDI input, the Read operation will proceed through an idle period, lasting three SCLK periods. On

the falling edge of SClk Cycle #8 (see Figure 11) the serial data output signal (SDO) becomes active. At this point the user can begin reading the data contents of the addressed Command Register (at Address [A4, A3, A2, A1, A0]) via the SDO output pin. The Serial Interface will output this eight bit data word (D0 through D7) in ascending order (with the LSB first), on the falling edges of the SClk. The data (on the SDO output pin) is stable for reading on the very next rising edge of the SClk.

3.1.6 Write Operation

Once the last address bit (A4) has been clocked into the SDI input, the Write operation will proceed through an idle period, lasting three SClk periods. Prior to the rising edge of SClk Cycle #9, the eight bit data word is applied to SDI input. Data on SDI is latched on the rising edge of SClk.

FIGURE 11. MICROPROCESSOR SERIAL INTERFACE DATA STRUCTURE



NOTES:

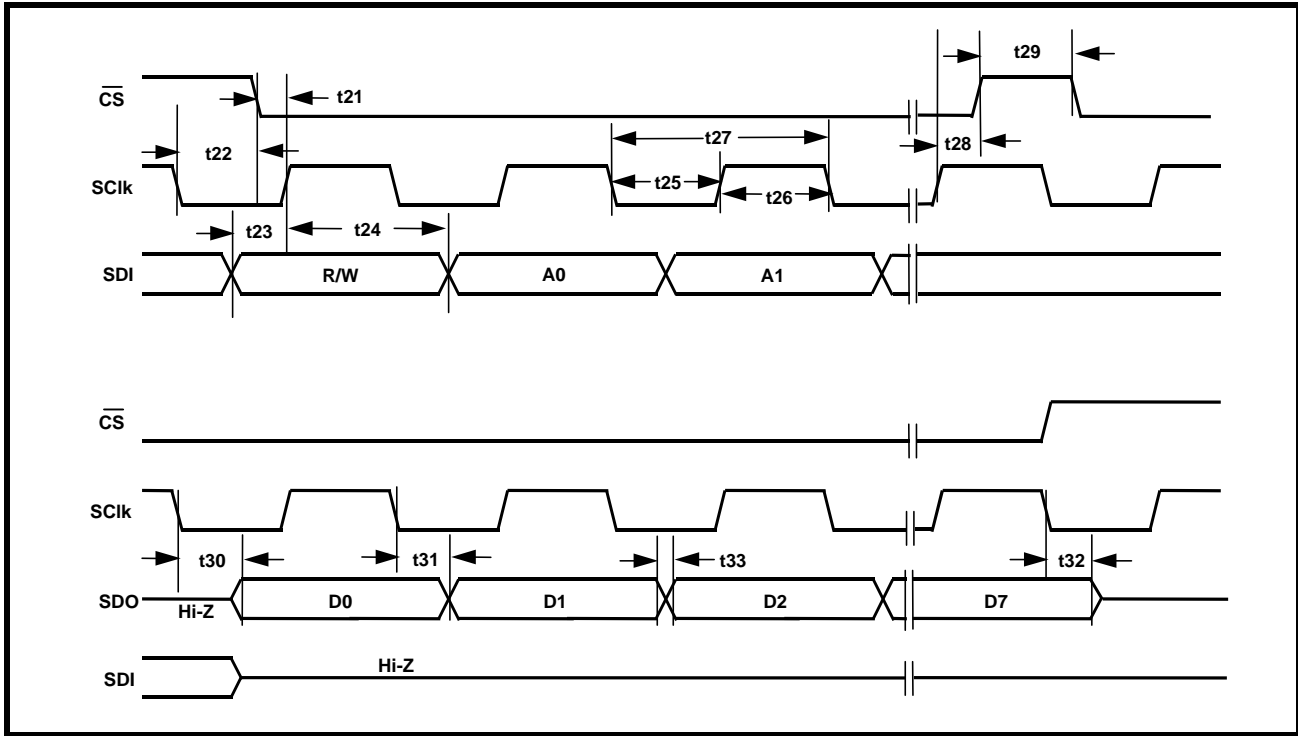
1. A5 is always "0".
2. R/W = "1" for Read Operations
3. R/W = "0" for Write Operations
4. Denotes a "don't care" value (shaded areas)

3.1.7 Simplified Interface Option

The user can simplify the design of the circuitry connecting to the Microprocessor Serial Interface by tying both the SDO and SDI pins together, and reading data from and/or writing data to this combined signal. This simplification is possible because only one of

these signals are active at any given time. The inactive signal will be tri-stated.

FIGURE 12. TIMING DIAGRAM FOR THE MICROPROCESSOR SERIAL INTERFACE



ORDERING INFORMATION

| PART # | PACKAGE | OPERATING TEMPERATURE RANGE |
|---------------------|----------------------------------|-------------------------------|
| XRT71D03IV | 64 Pin TQFP | -40°C to +85°C |
| THERMAL INFORMATION | Theta - J _A = 38° C/W | Theta J _C = 7° C/W |

PACKAGE DIMENSIONS

**64 Lead Thin Quad Flat Pack
(10 x 10 x 1.4 mm LQFP)**

The drawing shows a top view of the package with dimensions D, D1, 48, 33, 49, 32, 64, 17, 1, 18, e, and B. The side view shows dimensions A, A1, A2, C, L, alpha, and beta. A detail of the lead profile shows dimension aaa.

| SYMBOL | INCHES | | MILLIMETERS | |
|--------|------------|-------|-------------|-------|
| | MIN | MAX | MIN | MAX |
| A | 0.055 | 0.063 | 1.40 | 1.60 |
| A1 | 0.002 | 0.006 | 0.05 | 0.15 |
| A2 | 0.053 | 0.057 | 1.35 | 1.45 |
| B | 0.007 | 0.011 | 0.17 | 0.27 |
| C | 0.004 | 0.008 | 0.09 | 0.20 |
| D | 0.465 | 0.480 | 11.80 | 12.20 |
| D1 | 0.390 | 0.398 | 9.90 | 10.10 |
| e | 0.0020 BSC | | 0.05 BSC | |
| L | 0.018 | 0.050 | 0.45 | 0.75 |
| α | 0° | 7° | 0° | 7° |
| β | 7° typ | | 7° typ | |
| aaa | - | 0.003 | - | 0.08 |

Note: Control Dimensions are the Millimeter Column

REVISION HISTORY

Rev. P1.0.1; Revised pull-up/pull-down resistors on various pins.

Rev. P1.0.2; Changed date and made minor edits to page 1.

Rev. P1.0.3; Corrected Pin List descriptions. Modified pin names to be consistent, ie MCLK0, RPOS0, RNEG0, etc. changed to MCLK_0, RPOS_0, RNEG_0, etc. Changed VSS to GND. Changed figures to reflect pin name changes.

Rev. 1.1.0 Removed preliminary designation. Added electrical tables.

Rev. 1.1.1 Corrected Table 4 adding RRCIkES_n as data D2, STS-1_n as D5, added D7. Corrected the description of the section 3 Serial Microprocessor Interface. Moved figure 9 into Electrical Characteristics Section. Moved Jitter Transfer/Tolerance tables into Jitter Attenuator Section 1. Edited electrical tables.

Rev. 1.1.2 Corrected ordering information from XRT71D03 to 71D03IV.

Rev. 1.2.0 Removed all reference to STS-1 to DS3 desynchronizer.

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