PCF8553

40 × 4 LCD segment driver Rev. 3 — 27 March 2015

Product data sheet

1. **General description**

PCF8553 is an ultra low-power LCD segment driver with 4 backplane- and 40 segment-driver outputs, with either an I²C- or an SPI-bus interface. It comprises an internal oscillator, bias generation, instruction decoding, and display controller.

For a selection of NXP LCD segment drivers, see <u>Table 24 on page 45</u>.

2. Features and benefits

- Single chip LCD controller and driver
- Selectable backplane drive configuration: static, 2, 3, or 4 backplane multiplexing
- Selectable display bias configuration: static, $\frac{1}{2}$, or $\frac{1}{3}$
- Internal LCD bias generation with buffers
- 40 segment drives:
 - Up to 20 7-segment numeric characters
 - ◆ Up to 10 14-segment alphanumeric characters
 - Any graphics of up to 160 segments/elements
- Auto-incrementing display data and instruction loading
- Versatile blinking modes
- Independent supplies of V_{LCD} and V_{DD}
- Power supply ranges:
 - ◆ 1.8 V to 5.5 V for V_{LCD}
 - ◆ 1.8 V to 5.5 V for V_{DD}
- Ultra low-power consumption
- 400 kHz I²C-bus interface
- 5 MHz SPI-bus interface
- Internally generated or externally supplied clock signal

Applications 3.

- Metering equipment
- Small appliances
- Consumer healthcare devices
- Battery operated devices
- Measuring equipment



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4. Ordering information

Table 1. Ordering information

Type number	Package					
	Name	Description	Version			
PCF8553DTT		plastic thin shrink small outline package; 56 leads; body width 6.1 mm	SOT364-1			

4.1 Ordering options

Table 2. Ordering options

Product type number	Orderable part number	Sales item (12NC)	Delivery form	IC revision
PCF8553DTT/A	PCF8553DTT/AJ	935304762118	tape and reel, 13 inch	1

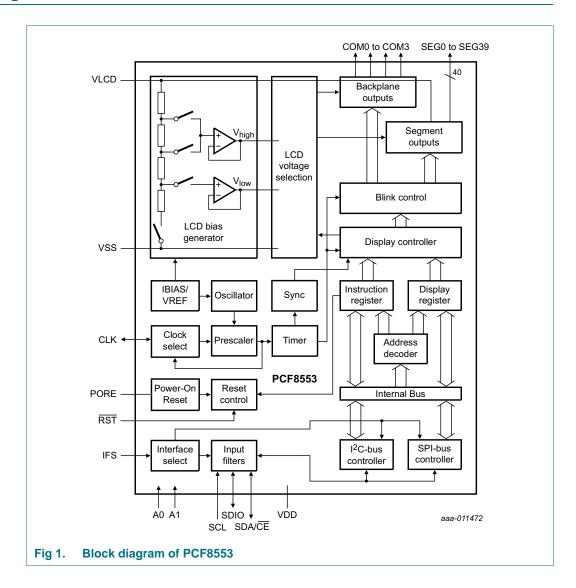
5. Marking

Table 3. Marking codes

Type number	Marking code
PCF8553DTT/A	PCF8553D

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6. Block diagram

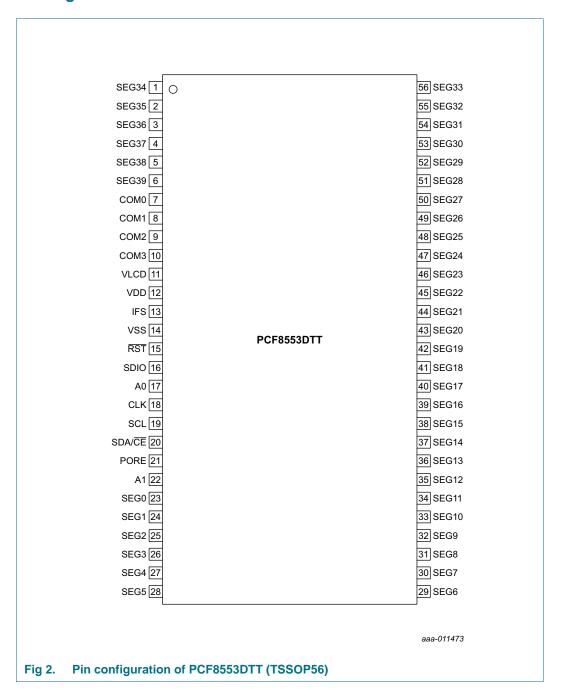


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7. Pinning information

7.1 Pinning



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7.2 Pin description

Table 4. Pin description of PCF8553DTT (TSSOP56)

Input or input/output pins must always be at a defined level (V_{SS} or V_{DD}) unless otherwise specified.

Symbol	Pin	Туре	Description					
Backplane and se	Backplane and segment outputs							
SEG34 to SEG39	1 to 6	output	LCD segments					
SEG0 to SEG33	23 to 56	-						
COM0 to COM3	7 to 10	output	LCD backplanes					
Supply pins								
VLCD	11	supply	LCD supply voltage					
VDD	12	supply	supply voltage					
VSS	14	supply	ground supply					
Clock and control	pins							
RST	15	input	reset input, active LOW					
PORE[1]	21	input	Power-On Reset (POR) enable					
			 connect to V_{DD} for enabling POR 					
			 connect to V_{SS} (or leave open) for 	disabling POR				
CLK	18	input/output	internal oscillator output, external oscillator input					
			 must be left open if unused 					
Bus-related pins			l ² C-bus	SPI-bus				
IFS[1]	13	input	interface selector input					
			 connect to V_{SS} (or leave open) 	• connect to V _{DD}				
SDIO	16	input/output	unused	serial data input/output				
A0[1]	17	input	hardware device address selection;	unused				
A1[1]	22	input	 connect to V_{SS} (or leave open) for logic 0 					
			 connect to V_{DD} for logic 1 					
SCL	19	input	serial clock input	serial clock input				
SDA/CE	20	input/output	serial data output	chip enable input, active LOW				

^[1] A series resistance between V_{DD} and the pin must not exceed 1 k Ω to ensure proper functionality, see Section 16.3.

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8. Functional description

8.1 Registers of the PCF8553

The registers of the PCF8553 are arranged in bytes with 8 bit, addressed by an address pointer. Table 5 depicts the layout.

Table 5. Registers of the PCF8553

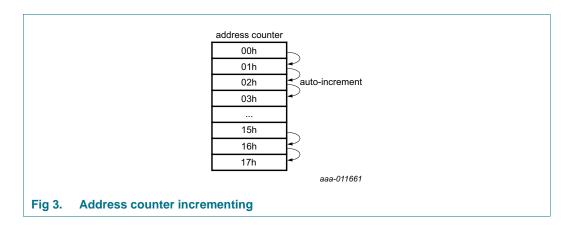
Bits labeled as 0 must always be written with logic 0.

Register name	Address	Bits								Reference
	AP[4:0]	7	6	5	4	3	2	1	0	
Command regis	ters								-	
Software_reset	00h	SR[7:0]								Table 9
Device_ctrl	01h	0	0	0	0	FF[1:0]		osc	COE	Table 6
Display_ctrl_1	02h	0	0	0	BOOST	MUX[1:0]	В	DE	Table 7
Display_ctrl_2	03h	0	0	0	0	0	BL[1:0]		INV	Table 8
Display data reg	jisters[1]	-			•	-			•	
COM0	04h	SEG7	SEG6	SEG5	SEG4	SEG3	SEG2	SEG1	SEG0	Table 10
	05h	SEG15	SEG14	SEG13	SEG12	SEG11	SEG10	SEG9	SEG8	
	06h	SEG23	SEG22	SEG21	SEG20	SEG19	SEG18	SEG17	SEG16	
	07h	SEG31	SEG30	SEG29	SEG28	SEG27	SEG26	SEG25	SEG24	
	08h	SEG39	SEG38	SEG37	SEG36	SEG35	SEG34	SEG33	SEG32	
COM1	09h	SEG7	SEG6	SEG5	SEG4	SEG3	SEG2	SEG1	SEG0	
	:	:				:	:	:	:	
	0Dh	SEG39	SEG38	SEG37	SEG36	SEG35	SEG34	SEG33	SEG32	
COM2	0Eh	SEG7	SEG6	SEG5	SEG4	SEG3	SEG2	SEG1	SEG0	
	:	:	:			:	:	:	:	
	12h	SEG39	SEG38	SEG37	SEG36	SEG35	SEG34	SEG33	SEG32	
COM3	13h	SEG7	SEG6	SEG5	SEG4	SEG3	SEG2	SEG1	SEG0	
	:	:	:	:	:	:	:	:	:	
	17h	SEG39	SEG38	SEG37	SEG36	SEG35	SEG34	SEG33	SEG32	

[1] See Table 10.

For writing to the registers, send the address byte first, then write the data to the register (see Section 11.1.4 and Section 11.2.1). The address byte works as an address pointer. For the succeeding registers, the address pointer is automatically incremented by 1 (see Figure 3) and all following data are written into these register addresses. After register 17h, the auto-incrementing will stop and data are ignored.

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8.2 Command registers of the PCF8553

8.2.1 Command: Device_ctrl

The Device_ctrl command sets the device into a defined state. It should be executed before enabling the display (see bit DE in <u>Table 7</u>).

Table 6. Device ctrl - device control command register (address 01h) bit description

Bit	Symbol	Value	Description
7 to 4	-	0000	default value
3 to 2	FF[1:0]		frame frequency selection
		00	f _{fr} = 32 Hz
		01[1]	f _{fr} = 64 Hz
		10	f _{fr} = 96 Hz
		11	f _{fr} = 128 Hz
1	OSC		internal oscillator control
		0[1]	enabled
		1	disabled
0	COE		clock output enable
		0[1]	clock signal not available on pin CLK;
			pin CLK is in 3-state
		1	clock signal available on pin CLK

^[1] Default value.

8.2.1.1 Internal oscillator and clock output

Bit OSC enables or disables the internal oscillator. When the internal oscillator is used, bit COE allows making the clock signal available on pin CLK. If this is not intended, pin CLK should be left open. The design ensures that the duty cycle of the clock output is 50:50 (% HIGH-level time: % LOW-level time).

In applications where an external clock has to be applied to the PCF8553, bit OSC must be set logic 1 and COE logic 0. In this case pin CLK becomes an input.

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In power-down mode (see Section 8.3.1)

- if pin CLK is configured as an output, there is no signal on CLK
- if pin CLK is configured as an input, the signal on CLK can be removed.

Remark: A clock signal must always be supplied to the device if the display is enabled (see bit DE in <u>Table 7 on page 8</u>). Removing the clock may freeze the LCD in a DC state, which is not suitable for the liquid crystal.

8.2.2 Command: Display_ctrl_1

The Display_ctrl_1 command allows configuring the basic display set-up.

Table 7. Display_ctrl_1 - display control command 1 register (address 02h) bit description

Bit	Symbol	Value	Description
7 to 5	-	000	default value
4	BOOST		large display mode support
		0[1]	standard power drive scheme
		1	enhanced power drive scheme for higher display loads
3 to 2	MUX[1:0]		multiplex drive mode selection
		00[1]	1:4 multiplex drive mode; COM0 to COM3 (n _{MUX} = 4)
		01	1:3 multiplex drive mode; COM0 to COM2 (n _{MUX} = 3)
		10	1:2 multiplex drive mode; COM0 and COM1 (n _{MUX} = 2)
		11	static drive mode; COM0 (n _{MUX} = 1)
1	B[2]		bias mode selection
		0[1]	$\frac{1}{3}$ bias (a _{bias} = 2)
		1	$\frac{1}{2}$ bias (a _{bias} = 1)
0	DE		display enable ^[3]
		0[1]	display disabled; device is in power-down mode
		1	display enabled; device is in power-on mode

- [1] Default value.
- [2] Not applicable for static drive mode.
- [3] See Section 8.3.1.

8.2.2.1 Enhanced power drive mode

By setting the BOOST bit to logic 1, the driving capability of the display signals is increased to cope with large displays with a higher effective capacitance. Setting this bit increases the current consumption on V_{LCD} .

8.2.2.2 Multiplex drive mode

MUX[1:0] sets the multiplex driving scheme and the associated backplane drive signals, which are active. For further details, see <u>Section 9.2 on page 16</u>.

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8.2.3 Command: Display_ctrl_2

Table 8. Display_ctrl_2 - display control command 2 register (address 03h) bit description

Bit	Symbol	Value	Description
7 to 3	-	00000	default value
2 to 1	BL[1:0]		blink control
		00[1]	blinking off
		01	blinking on, f _{blink} = 0.5 Hz
		10	blinking on, f _{blink} = 1 Hz
		11	blinking on, f _{blink} = 2 Hz
0	INV		inversion mode selection
		O[1]	line inversion (driving scheme A)
		1	frame inversion (driving scheme B)

^[1] Default value.

8.2.3.1 Blinking

The whole display blinks at frequencies selected by the blink control bits BL[1:0], see <u>Table 8</u>. The blink frequencies are derived from the clock frequency. During the blank-out phase of the blinking period, the display is turned off.

If an external clock with frequency $f_{clk(ext)}$ is used, the blinking frequency is determined by Equation 1. For notation, see Section 9.2.

$$f_{blink(eff)} = \frac{2 \times n_{MUX} \times f_{fr} \times f_{blink}}{f_{clk(ext)}} \tag{1}$$

8.2.3.2 Line inversion (driving scheme A) and frame inversion (driving scheme B)

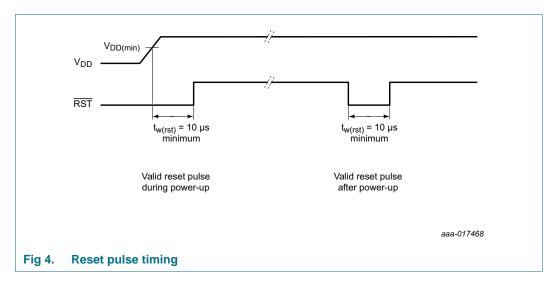
The waveforms used to drive LCD inherently produce a DC voltage across the display cell. The PCF8553 compensates for the DC voltage by inverting the waveforms on alternate frames or alternate lines. The choice of compensation method is determined with the INV bit.

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8.3 Starting and resetting the PCF8553

If the internal Power-On Reset (POR) is enabled by connecting pin PORE to V_{DD} , the chip resets automatically when V_{DD} rises above the minimum supply voltage. No further action is required.

If the internal POR is disabled by connecting pin PORE to V_{SS} , the chip must be reset by driving the \overline{RST} pin to logic 0 for at least 10 μ s, see Figure 4.



Alternatively a software reset can be applied (see Section 8.3.4).

Following a reset, the register 00h has to be rewritten with 0h by the next command byte or the address pointer AP[4:0] has to be set to the required address after a new START procedure.

8.3.1 Power-down mode

After a reset, the PCF8553 remains in power-down mode. In power-down mode the oscillator is switched off and there is no output on pin CLK. The register settings remain unchanged and the bus remains active. To enable the PCF8553, bit DE (command Display_ctrl_1, see <u>Table 7 on page 8</u>) must be set to logic 1.

8.3.2 Power-On Reset (POR)

If pin PORE is connected to V_{DD} , the PCF8553 comprises an internal POR, which puts the device into the following starting conditions:

- All backplane and segment outputs are set to V_{SS}
- The selected drive mode is: 1:4 multiplex with \(\frac{1}{3} \) bias
- · Blinking is switched off
- The address pointer is cleared (set to logic 0)
- · The display and the internal oscillator are disabled
- The display registers are set to logic 0

Remark: The internal POR can be disabled by connecting pin PORE to V_{SS} . In this case, the internal registers are not defined and require a hardware reset according to Section 8.3.3 or a software reset, see Section 8.3.4.

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8.3.3 Hardware reset: RST pin

At power-on the PCF8553 can be reset to the following starting conditions by pulling pin RST low:

- All backplane and segment outputs are set to V_{SS}
- The selected drive mode is: 1:4 multiplex with \(\frac{1}{3} \) bias
- · Blinking is switched off
- The bus interface is initialized
- The address pointer is cleared (set to logic 0)
- The display and the internal oscillator are disabled
- The display registers are set to logic 0

Remark: The hardware reset overrides the POR see Section 8.3.2.

8.3.4 Command: Software_reset

The internal registers including the display registers and the address pointer (set to logic 0) of the device are reset by the Software_reset command.

Table 9. Software reset - software reset command register (address 00h) bit description

Bit	Symbol	Value	Description				
7 to 0	SR[7:0]	software reset					
		00000000[1]	no reset				
		00101100	software reset				

^[1] Default value.

8.4 Display data register mapping

The example in <u>Table 10</u> and <u>Figure 5</u> illustrates the segment and backplane mapping of the display in relation to the display RAM.

For example, in 1:4 multiplex drive mode, the backplanes are served by signals COM0 to COM3 and the segments are driven by signals SEG0 to SEG39. Contents of addresses 04h to 08h are allocated to the first row (COM0) starting with the LSB driving the leftmost element and moving forward to the right with increasing bit position. If a bit is logic 0, the element is off, if it is logic 1 the element is turned on. All register content is LSB to MSB left to right. Addresses 09h to 0Dh serve COM1 signals, addresses 0Eh to 12h serve COM2 signals, and addresses 13h to 17h serve COM3 signals.

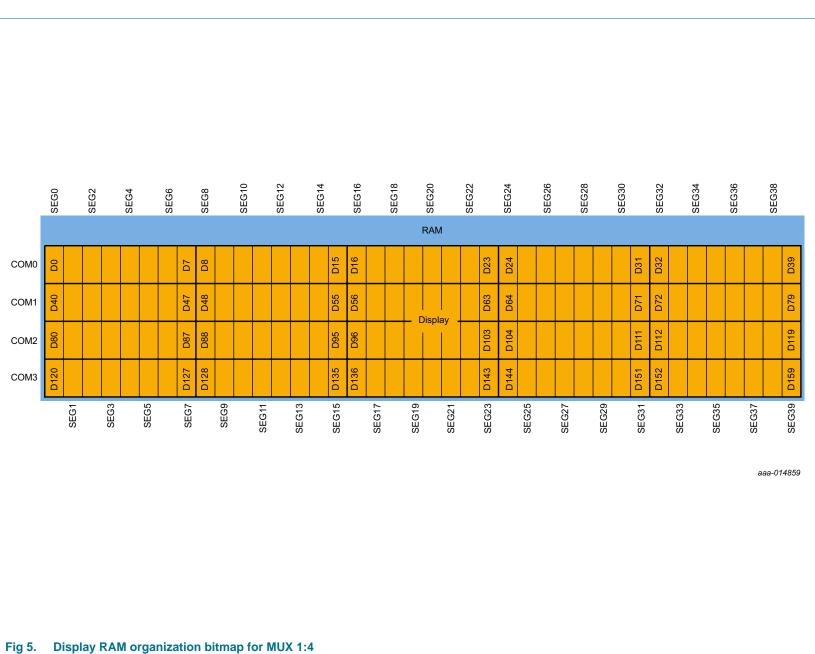
For displays with fewer segments/elements the unused bits are ignored.

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Table 10. Register to segment and backplane mapping

Backplanes[1]	Segments									
	SEG0 to SEG7		SEG8 to S	SEG15	SEG16 to	SEG23	SEG24 to	SEG31	SEG32 to	SEG39
	LSB	MSB	LSB	MSB	LSB	MSB	LSB	MSB	LSB	MSB
1:4 multiplex d	rive mode)								
COM0	content of	04h	content of	05h	content of	06h	content of	07h	content of	08h
COM1	content of	09h	content of	0Ah	content of	0Bh	content of	0Ch	content of	0Dh
COM2	content of	0Eh	content of	0Fh	content of	10h	content of	11h	content of	12h
COM3	content of	13h	content of	14h	content of	15h	content of	16h	content of	17h
1:3 multiplex d	rive mode)			·					
COM0	content of	04h	content of	05h	content of	06h	content of	07h	content of	08h
COM1	content of	09h	content of	0Ah	content of	0Bh	content of	0Ch	content of	0Dh
COM2	content of	0Eh	content of	0Fh	content of	10h	content of	11h	content of	12h
1:2 multiplex d	rive mode)			·					
COM0	content of	04h	content of	05h	content of	06h	content of	07h	content of	08h
COM1	content of	09h	content of	0Ah	content of	0Bh	content of	0Ch	content of	0Dh
static drive mo	de		•		·		•		•	
COM0	content of	04h	content of	05h	content of	06h	content of	07h	content of	08h

^[1] See also Section 9.3.1 on page 24.



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9. Possible display configurations

The possible display configurations of the PCF8553 depend on the number of active backplane outputs required. A selection of display configurations is shown in <u>Table 11</u>. All of these configurations can be implemented in the typical systems shown in <u>Figure 7</u> or <u>Figure 8</u>.

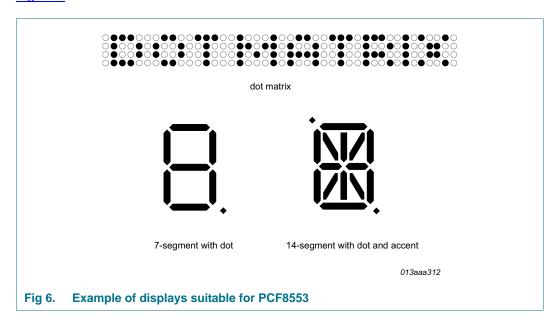


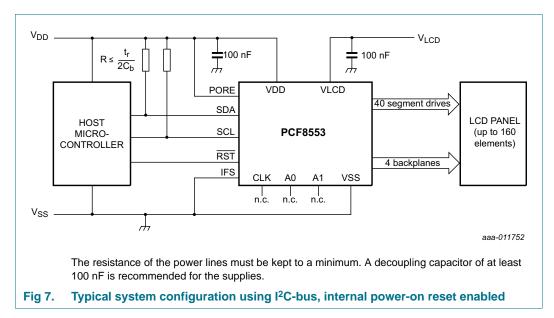
Table 11. Selection of possible display configurations

Number of							
Backplanes	Icons	Digits/Characte	Digits/Characters				
		7-segment ^[1]	14-segment[2]	segments/ elements			
4	160	20	10	160 dots (4 × 40)			
3	120	15	7	120 (3 × 40)			
2	80	10	5	80 dots (2 × 40)			
1	40	5	2	40 dots (1 × 40)			

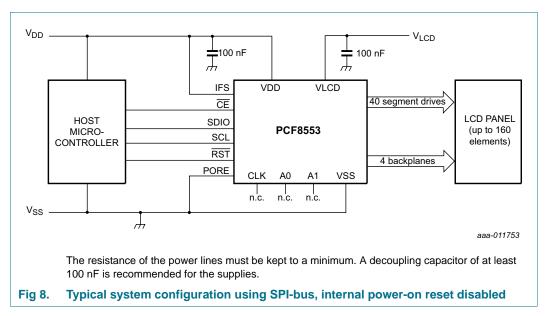
^{[1] 7} segment display has 8 segments/elements including the decimal point.

^{[2] 14} segment display has 16 segments/elements including decimal point and accent dot.

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The host microcontroller manages the 2-line I^2C -bus communication channel with the PCF8553. The internal oscillator is used and the internal POR is enabled in the example. The appropriate biasing voltages for the multiplexed LCD waveforms are generated internally. The only other connections required to complete the system are the reset, the power supplies (V_{DD} , V_{SS} , and V_{LCD}) and the LCD panel chosen for the application.



The host microcontroller manages the 3-line SPI-bus communication channel with the PCF8553. The internal oscillator is enabled. The appropriate biasing voltages for the multiplexed LCD waveforms are generated internally. The only other connections required to complete the system are reset, the power supplies (V_{DD} , V_{SS} , and V_{LCD}) and the LCD panel chosen for the application.

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9.1 LCD bias generator

Fractional LCD biasing voltages are obtained from an internal voltage divider of three impedances connected between V_{LCD} and V_{SS} . These intermediate levels are tapped off at positions of $\frac{1}{3}$ and $\frac{2}{3}$, or $\frac{1}{2}$, depending on the bias mode chosen. To keep current consumption to a minimum, on-chip low-power buffers provide these levels to the display.

9.2 LCD voltage selector

The LCD voltage selector coordinates the multiplexing of the LCD in accordance with the selected LCD drive configuration. The operation of the voltage selector is controlled by the Display_ctrl_1 command (see $\underline{\text{Table 7}}$). The biasing configurations that apply to the preferred modes of operation, together with the biasing characteristics as functions of V_{LCD} and the resulting discrimination ratios (D) are given in $\underline{\text{Table 12}}$.

Table 12. Biasing characteristics

LCD drive mode	Number of:		LCD bias	V _{off(RMS)}	$V_{on(RMS)}$	$D = \frac{V_{on(RMS)}}{}$
	Backplanes	Levels	configuration	V_{LCD}	V _{LCD}	$D = \frac{on(RMS)}{V_{off(RMS)}}$
static	1	2	static	0	1	∞
1:2 multiplex	2	3	1/2	0.354	0.791	2.236
1:2 multiplex	2	4	1/3	0.333	0.745	2.236
1:3 multiplex	3	4	1/3	0.333	0.638	1.915
1:4 multiplex	4	4	1/3	0.333	0.577	1.732

A practical value for V_{LCD} is determined by equating $V_{off(RMS)}$ with a defined LCD threshold voltage ($V_{th(off)}$), typically when the LCD exhibits approximately 10 % contrast. In the static drive mode, a suitable choice is $V_{LCD} > 3V_{th(off)}$.

Multiplex drive modes of 1:3 and 1:4 with $\frac{1}{2}$ bias are possible but the discrimination and hence the contrast ratios are smaller.

Bias is calculated with Equation 2

$$\frac{1}{1+a_{bias}} \tag{2}$$

The values for abias are:

$$a_{bias} = 1$$
 for $\frac{1}{2}$ bias

$$a_{bias} = 2 \text{ for } \frac{1}{3} \text{ bias}$$

The RMS on-state voltage (V_{on(RMS)}) for the LCD is calculated with Equation 3:

$$V_{on(RMS)} = V_{LCD} \sqrt{\frac{a_{bias}^2 + 2a_{bias} + n_{MUX}}{n_{MUX} \times (1 + a_{bias})^2}}$$
(3)

where the values for n are

 $n_{MUX} = 1$ for static drive mode

 $n_{MUX} = 2$ for 1:2 multiplex drive mode

 $n_{MUX} = 3$ for 1:3 multiplex drive mode

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 $n_{MUX} = 4$ for 1:4 multiplex drive mode

The RMS off-state voltage (V_{off(RMS)}) for the LCD is calculated with Equation 4:

$$V_{off(RMS)} = V_{LCD} \sqrt{\frac{a_{bias}^2 - 2a_{bias} + n_{MUX}}{n_{MUX} \times (1 + a_{bias})^2}}$$
(4)

Discrimination is a term which is defined as the ratio of the on and off RMS voltages $(V_{on(RMS)})$ to $V_{off(RMS)}$ across a segment. It can be thought of as a measurement of contrast. Discrimination is determined from Equation 5:

$$D = \frac{V_{on(RMS)}}{V_{off(RMS)}} = \sqrt{\frac{a_{bias}^2 + 2a_{bias} + n_{MUX}}{a_{bias}^2 - 2a_{bias} + n_{MUX}}}$$
(5)

Using Equation 5, the discrimination for an LCD drive mode of 1:3 multiplex with $\frac{1}{2}$ bias is $\sqrt{3} = 1.732$ and the discrimination for an LCD drive mode of 1:4 multiplex with $\frac{1}{2}$ bias is $\frac{\sqrt{21}}{3} = 1.528$.

The advantage of these LCD drive modes is a reduction of the LCD full scale voltage V_{LCD} as follows:

- 1:3 multiplex ($\frac{1}{2}$ bias): $V_{LCD} = \sqrt{6} \times V_{off(RMS)} = 2.449 V_{off(RMS)}$
- 1:4 multiplex (½ bias): $V_{LCD} = \left[\frac{(4 \times \sqrt{3})}{3}\right] = 2.309 V_{off(RMS)}$

These compare with $V_{LCD} = 3V_{off(RMS)}$ when $\frac{1}{3}$ bias is used.

V_{LCD} is sometimes referred as the LCD operating voltage.

9.2.1 Electro-optical performance

Suitable values for $V_{on(RMS)}$ and $V_{off(RMS)}$ are dependent on the LCD liquid used. The RMS voltage, at which a pixel will be switched on or off, determine the transmissibility of the pixel.

For any given liquid, there are two threshold values defined. One point is at 10 % relative transmission (at $V_{th(off)}$) and the other at 90 % relative transmission (at $V_{th(on)}$), see Figure 9. For a good contrast performance, the following rules should be followed:

$$V_{on(RMS)} \ge V_{th(on)} \tag{6}$$

$$V_{off(RMS)} \le V_{th(off)} \tag{7}$$

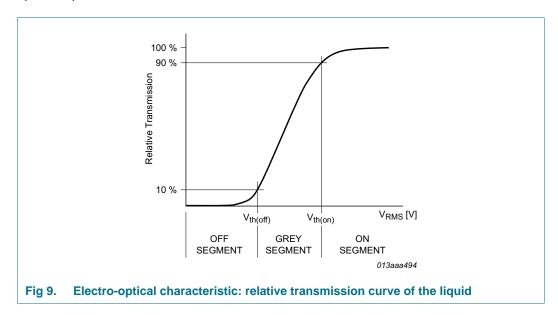
 $V_{on(RMS)}$ (see <u>Equation 3</u>) and $V_{off(RMS)}$ (see <u>Equation 5</u>) are properties of the display driver and are affected by the selection of a_{bias} , n_{MUX} , and the V_{LCD} voltage.

 $V_{th(off)}$ and $V_{th(on)}$ are properties of the LCD liquid and can be provided by the module manufacturer. $V_{th(off)}$ is sometimes named V_{th} . $V_{th(on)}$ is sometimes named saturation voltage V_{sat} .

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It is important to match the module properties to those of the driver in order to achieve optimum performance.

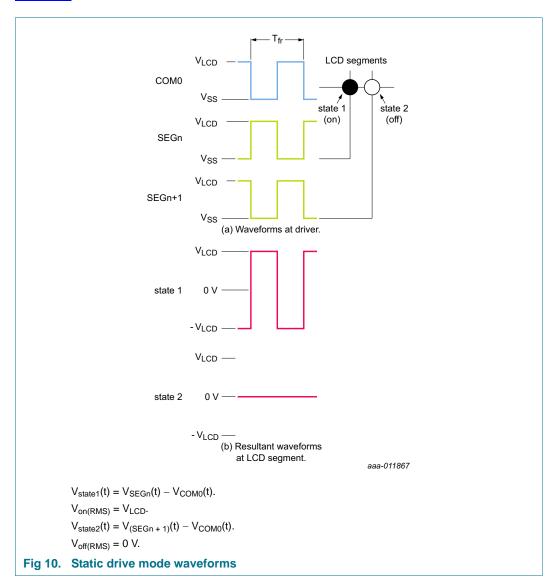


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9.2.2 LCD drive mode waveforms

9.2.2.1 Static drive mode

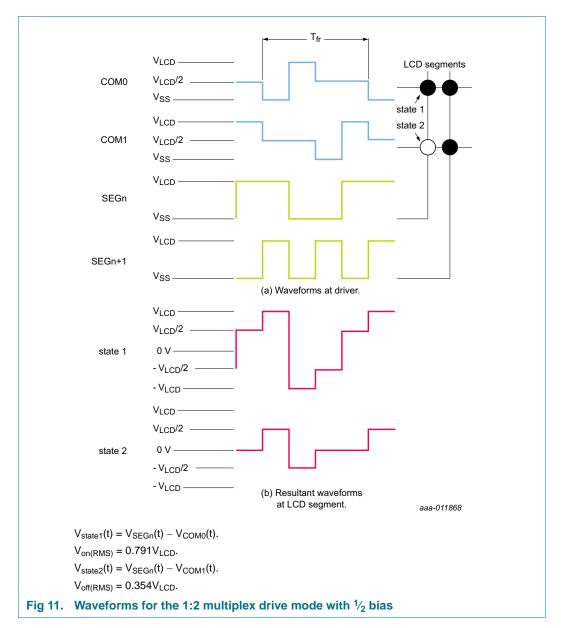
The static LCD drive mode is used when a single backplane is provided in the LCD. The backplane (COMn) and segment (SEGn) drive waveforms for this mode are shown in Figure 10.



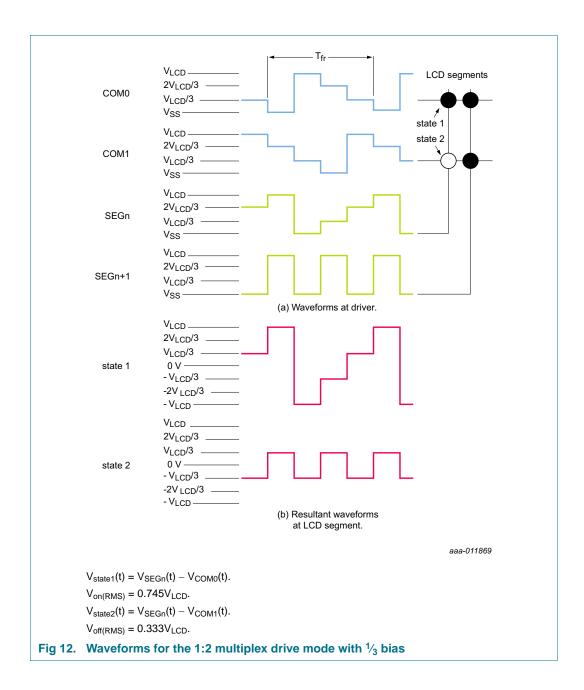
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9.2.2.2 1:2 Multiplex drive mode

When two backplanes are provided in the LCD, the 1:2 multiplex mode applies. The PCF8553 allows the use of $\frac{1}{2}$ bias or $\frac{1}{3}$ bias in this mode as shown in Figure 11 and Figure 12.



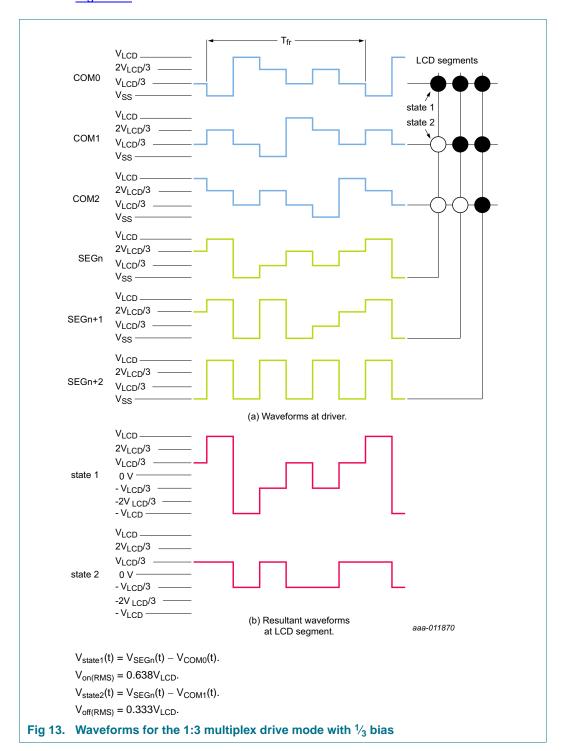
40 × 4 LCD segment driver



40 × 4 LCD segment driver

9.2.2.3 1:3 Multiplex drive mode

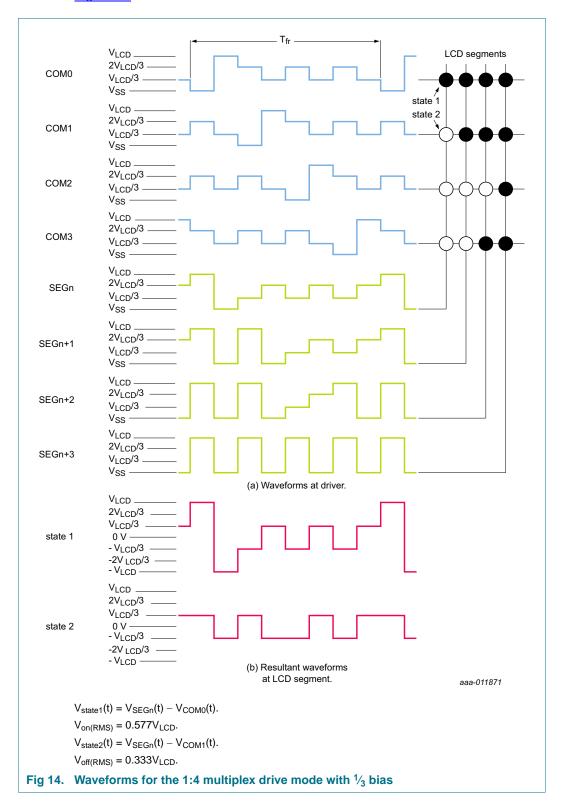
When three backplanes are provided in the LCD, the 1:3 multiplex drive mode applies, as shown in Figure 13.



40 x 4 LCD segment driver

9.2.2.4 1:4 Multiplex drive mode

When four backplanes are provided in the LCD, the 1:4 multiplex drive mode applies as shown in Figure 14.



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9.3 Backplane and segment outputs

9.3.1 Backplane outputs

The LCD drive section includes four backplane outputs COM0 to COM3, which must be directly connected to the LCD. The backplane output signals are generated in accordance with the selected LCD drive mode. If less than four backplane outputs are required, the unused outputs can be left open-circuit.

- In 1:3 multiplex drive mode, COM3 carries the same signal as COM1, therefore these two outputs can be tied together to give enhanced drive capabilities
- In 1:2 multiplex drive mode, COM0 and COM2, respectively, COM1 and COM3 all carry the same signals and may also be paired to increase the drive capabilities
- In static drive mode, the same signal is carried by all four backplane outputs and they
 can be connected in parallel for very high drive requirements

9.3.2 Segment outputs

The LCD drive section includes 40 segment outputs SEG0 to SEG39, which must be directly connected to the LCD. The segment output signals are generated in accordance with the multiplexed backplane signals and with data residing in the display registers. When less than 39 segment outputs are required, the unused segment outputs must be left open-circuit.

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10. Power Sequencing

10.1 Power-on

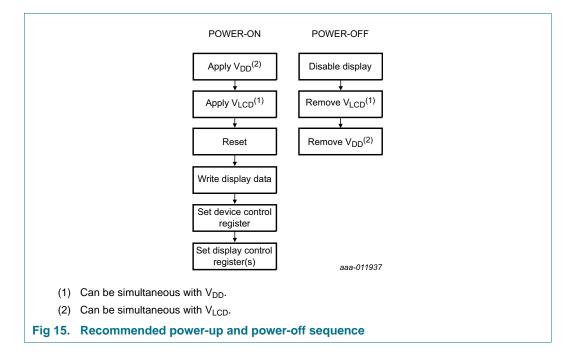
To avoid unwanted artifacts on the display, V_{LCD} must never be asserted before V_{DD} , it is permitted to assert V_{DD} and V_{LCD} at the same time.

10.2 Power-off

Before turning the power to the device off, the display must be disabled by setting bit DE to logic 0. To avoid unwanted artifacts on the display, V_{LCD} must never be connected, while V_{DD} is switched off. It is permitted to switch off V_{DD} and V_{LCD} simultaneously.

10.3 Power sequences

Figure 15 depicts the recommended power-up and power-off sequence.

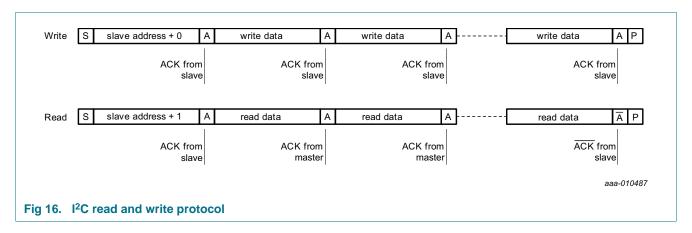


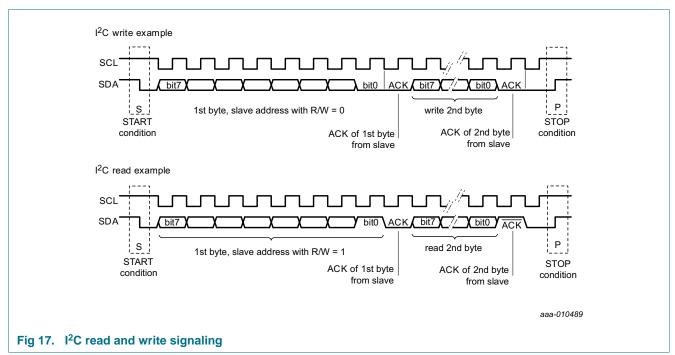
40 × 4 LCD segment driver

11. Bus interfaces

11.1 I²C-bus interface

The I²C-bus is for bidirectional, two-line communication between different ICs. The two lines are a Serial DAta line (SDA) and a Serial CLock line (SCL). Both lines must be connected to a positive supply via a pull-up resistor. Data transfer may be initiated only when the bus is not busy. Both data and clock lines remain HIGH when the bus is not busy. The PCF8553 acts as a slave receiver when being written to and as a slave transmitter when being read from.





11.1.1 Bit transfer

One data bit is transferred during each clock pulse. The data on the SDA line must remain stable during the HIGH period of the clock pulse, as changes in the data line at this time are interpreted as STOP or START conditions.

40 × 4 LCD segment driver

11.1.2 START and STOP conditions

A HIGH-to-LOW transition of the data line while the clock is HIGH is defined as the START condition - S.

A LOW-to-HIGH transition of the data line while the clock is HIGH is defined as the STOP condition - P (see Figure 17).

11.1.3 Acknowledge

Each byte of 8 bits is followed by an acknowledge cycle. An acknowledge is defined as logic 0. A not-acknowledge is defined as logic 1.

When written to, the slave will generate an acknowledge after the reception of each byte. After the acknowledge, another byte may be transmitted. It is also possible to send a STOP or START condition.

When read from, the master receiver must generate an acknowledge after the reception of each byte. When the master receiver no longer requires bytes to be transmitted, it must generate a not-acknowledge. After the not-acknowledge, either a STOP or START condition must be sent.

Remark: The PCF8553 omits the not-acknowledge. After the last byte read, the end of transmission is indicated by a STOP or START condition from the master.

A detailed description of the I²C-bus specification is given in Ref. 12 "UM10204".

11.1.4 I²C interface protocol

The PCF8553 uses the I²C interface for data transfer. Interpretation of the data is determined by the interface protocol.

11.1.4.1 Write protocol

After the I²C slave address is transmitted, the PCF8553 requires that the register address pointer is defined. It can take the value 00h to 17h. Values outside of that range will result in the transfer being ignored, however the slave will still respond with acknowledge pulses.

After the register address has been transmitted, write data is transmitted. The minimum number of data write bytes is 0 and the maximum number is unlimited. After each write, the address pointer increments by one. After address 17h, the address pointer stops incrementing at 18h.

- I²C START condition
- I2C slave address + write
- start register pointer
- write data
- write data
- •
- write data
- I²C STOP condition; an I²C RE-START condition is also possible.

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11.1.4.2 Read protocol

When reading the PCF8553, reading starts at the current position of the address pointer. The address pointer for read data should first be defined by a write sequence.

- I²C START condition
- I²C slave address + write
- start address pointer
- I²C STOP condition; an I²C RE-START condition is also possible.

After setting the address pointer, a read can be executed. After the I²C slave address is transmitted, the PCF8553 will immediately output read data. After each read, the address pointer increments by one. After address 17h, the address pointer stops incrementing at 18h.

- I²C START condition
- I²C slave address + read
- read data (master sends acknowledge bit)
- · read data (master sends acknowledge bit)
- •

11.1.4.3 I²C-bus slave address

Device selection depends on the I²C-bus slave address. Four different I²C-bus slave addresses can be used to address the PCF8553 (see Table 13).

Table 13. I²C slave address byte

	Slave ad	lave address						
Bit	7 MSB	6	5	4	3	2	1	0 LSB
	0	1	1	1	0	A1	A0	R/W

The least significant bit of the slave address byte is bit R/\overline{W} (see Table 14).

Table 14. R/W-bit description

R/W	Description
0	write data
1	read data

Bit 1 and bit 2 of the slave address are defined by connecting the input pins A0 and A1 to either V_{SS} (logic 0) or V_{DD} (logic 1). Therefore, four instances of PCF8553 can be distinguished on the same I^2C -bus.

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11.2 SPI-bus interface

Data transfer to the device is made via a 3-line SPI-bus (see <u>Table 15</u>). There is no dedicated output data line. The SPI-bus is initialized whenever the chip enable line pin <u>CE</u> is pulled down.

Table 15. Serial interface

•	Function	Description				
CE	chip enable input[1]; active LOW	when HIGH, the interface is reset				
SCL	serial clock input	input may be higher than V _{DD}				
SDIO	serial data input/output	input data are sampled on the rising edge of SCL, output data are valid after the falling edge of SCL				

^[1] The chip enable must not be wired permanently LOW.

11.2.1 Data transmission

The chip enable signal is used to identify the transmitted data. Each data transfer is a byte with the Most Significant Bit (MSB) sent first.

The transmission is controlled by the active LOW chip enable signal \overline{CE} . The first byte transmitted is the register address comprising of the address pointer and the R/W bit.

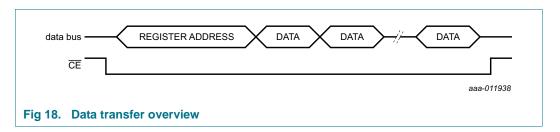


Table 16. Address byte definition

Bit	Symbol	Value	Description			
7	R/\overline{W}	data read or write selection				
		0	write data			
		1	read data			
6 to 5	-	00	default value			
4 to 0	AP[4:0]		pointer to register start address			
		00h to 17h	valid range; other addresses are ignored			

After the register address byte, the register contents follows with the address pointer being auto-incremented after every eighth bit sent (see Section 8.1 on page 6).

11.2.1.1 Write protocol

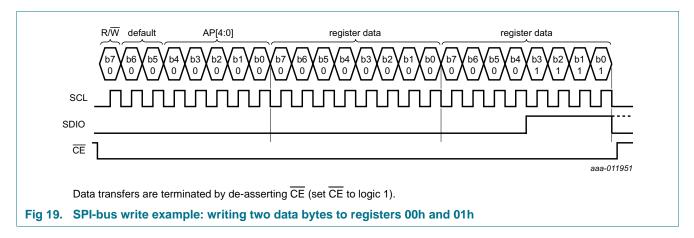
After the $\overline{\text{CE}}$ is set LOW, the PCF8553 requires that R/ $\overline{\text{W}}$ and the register address pointer is defined. It can take the value 00h to 17h. Values outside of that range will result in the transfer being ignored.

After the register address has been transmitted, write data is transmitted. The minimum number of data write bytes is 0 and the maximum number is unlimited. After each write, the address pointer increments by one. After address 17h, the address pointer stops incrementing at 18h.

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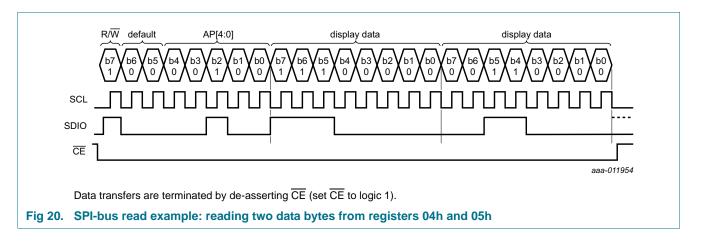
- CE set LOW
- $R/\overline{W} = 0$ and register address
- write data
- write data
- •
- write data
- CE set HIGH



11.2.1.2 Read protocol

When reading the PCF8553, reading starts at the defined position of the address pointer. After setting the address pointer, the read can be executed. After each read, the address pointer increments by one. After address 17h, the address pointer stops incrementing at 18h.

- CE set LOW
- $R/\overline{W} = 1$ and register address
- · read data
- read data
- •
- CE set HIGH



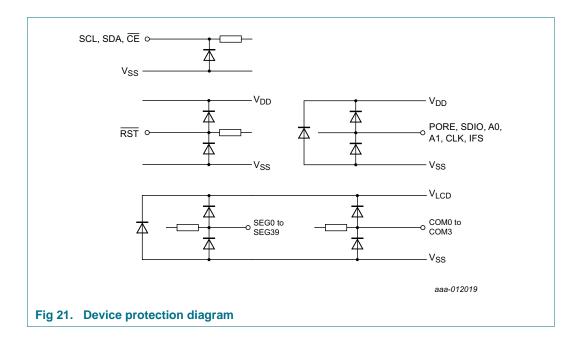
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11.3 EMC detection

The PCF8553 is ruggedized against EMC susceptibility; however it is not possible to cover all cases. To detect if a severe EMC event has occurred, it is possible to check the responsiveness of the device by reading its registers.

12. Internal circuitry



13. Safety notes

CAUTION



This device is sensitive to ElectroStatic Discharge (ESD). Observe precautions for handling electrostatic sensitive devices.

Such precautions are described in the ANSI/ESD S20.20, IEC/ST 61340-5, JESD625-A or equivalent standards.

CAUTION



Static voltages across the liquid crystal display can build up when the LCD supply voltage (V_{LCD}) is on while the IC supply voltage (V_{DD}) is off, or vice versa. This may cause unwanted display artifacts. To avoid such artifacts, V_{LCD} and V_{DD} must be applied or removed together.

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14. Limiting values

Table 17. Limiting values

In accordance with the Absolute Maximum Rating System (IEC 60134).

Symbol	Parameter	Conditions		Min	Max	Unit
V_{DD}	supply voltage			-0.5	+6.5	V
V_{LCD}	LCD supply voltage			-0.5	+6.5	V
VI	input voltage			-0.5	+6.5	V
Vo	output voltage			-0.5	+6.5	V
I _I	input current			-10	+10	mA
Io	output current			-10	+10	mA
I _{DD}	supply current			-50	+50	mA
I _{DD(LCD)}	LCD supply current			-50	+50	mA
I _{SS}	ground supply current			-50	+50	mA
P _{tot}	total power dissipation			-	100	mW
Po	output power			-	100	mW
V _{ESD}	electrostatic discharge	HBM	[1]			
	voltage	on pins SCL and SDA/CE		-	±2000	V
		on all other pins		-	±5000	V
		CDM	[2]	-	±1500	V
I _{lu}	latch-up current		[3]	-	200	mA
T _{stg}	storage temperature		[4]	-55	+150	°C
T _{amb}	ambient temperature	operating device		-40	+85	°C

^[1] Pass level; Human Body Model (HBM), according to Ref. 7 "JESD22-A114".

^[2] Pass level; Charged-Device Model (CDM), according to Ref. 8 "JESD22-C101".

^[3] Pass level; latch-up testing according to Ref. 9 "JESD78" at maximum ambient temperature (T_{amb(max)}).

^[4] According to the store and transport requirements (see Ref. 13 "UM10569") the devices have to be stored at a temperature of +8 °C to +45 °C and a humidity of 25 % to 75 %.

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15. Characteristics

Table 18. Electrical characteristics

 V_{DD} = 1.8 V to 5.5 V; V_{SS} = 0 V; V_{LCD} = 1.8 V to 5.5 V; T_{amb} = -40 °C to +85 °C; unless otherwise specified.

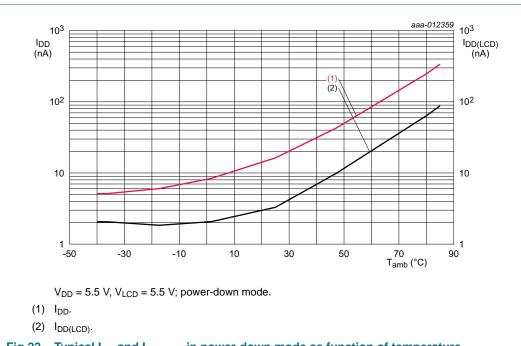
Symbol	Parameter	Conditions	Min	Тур	Max	Unit		
Supplies								
V_{DD}	supply voltage		1.8	-	5.5	V		
V_{LCD}	LCD supply voltage		1.8	-	5.5	V		
I _{DD}	supply current	f _{fr} = 64 Hz; no bus activity						
		V _{DD} = 3.3 V; T _{amb} = 25 °C	-	0.6	-	μΑ		
		V _{DD} = 5.5 V; T _{amb} = 85 °C	-	1.2	2.7	μΑ		
I _{DD(LCD)}	LCD supply current	$f_{fr} = 64 \text{ Hz}$; no bus activity						
		V_{LCD} = 5.5 V; T_{amb} = 85 °C; BOOST = 0; no display load	-	3.2	4.5	μΑ		
		V _{LCD} = 3.3 V; T _{amb} = 25 °C						
		BOOST = 0; no display load	-	2.5	-	μΑ		
		BOOST = 0; display enabled; display load C _L = 1.6 nF	-	5.0	-	μА		
		BOOST = 1; display enabled; display load C _L = 1.6 nF	-	6.0	-	μА		
V _{IL}	LOW-level input voltage		V _{SS}	-	$0.3V_{DD}$	V		
V _{IH}	HIGH-level input voltage	[2]	0.7V _{DD}	-	V_{DD}	V		
I _{OL}	LOW-level output current	output sink current; V _{OL} = 0.4 V; V _{DD} = 5 V				,		
		on pin CLK	2	-	-	mA		
		on pin SDIO	2	-	-	mA		
		on pin SDA	3	-	-	mA		
I _{OH}	HIGH-level output current	output source current; on pins SDIO, CLK; $V_{OH} = 4.6 \text{ V}; V_{DD} = 5 \text{ V}$	2	-	-	mA		
IL	leakage current	any input pin except for RST	-	0	-	nA		
		after ESD event	-500	-	+500	nA		
R _{pu(RST_n)}	pull-up resistance on pin RST_N		-	100	-	kΩ		
LCD outpu	its (pins SEG0 to SEG39 an	d COM0 to COM3)						
ΔV_{o}	output voltage variation	$V_{LCD} = 5 V$	-100	-	+100	mV		
R _o	output resistance	$V_{LCD} = 5 \text{ V}$	-	1.5	3	kΩ		

^[1] For typical values, also see Figure 22 to Figure 24.

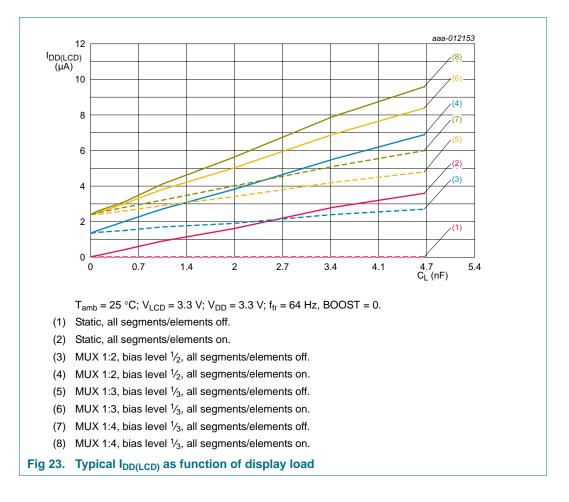
^[2] $\,$ I2C pins SCL and SDA have no diode to $\rm V_{DD}$ and may be driven up to 5.5 V.

^[3] Outputs measured one at a time.

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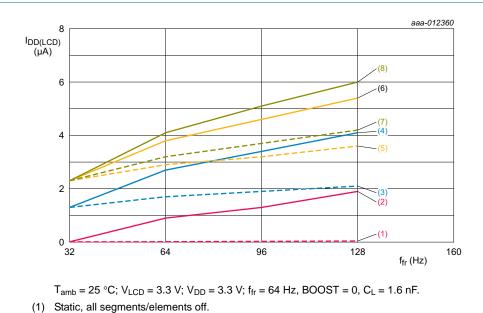






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- (2) Static, all segments/elements on.
- (3) MUX 1:2, bias level ½, all segments/elements off.
- (4) MUX 1:2, bias level ½, all segments/elements on.
- (5) MUX 1:3, bias level \(^1/_3\), all segments/elements off.
- (6) MUX 1:3, bias level \(\frac{1}{3} \), all segments/elements on.
- (7) MUX 1:4, bias level $\frac{1}{3}$, all segments/elements off.
- (8) MUX 1:4, bias level $\frac{1}{3}$, all segments/elements on.

Fig 24. Typical I_{DD(LCD)} as function of f_{fr}

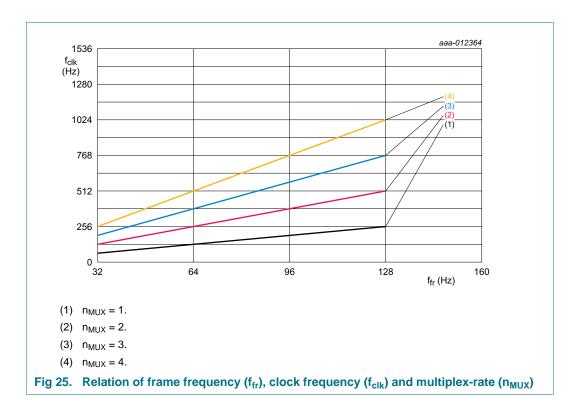
Table 19. Frequency characteristics

 V_{DD} = 1.8 V to 5.5 V; V_{SS} = 0 V; V_{LCD} = 1.8 V to 5.5 V; T_{amb} = -40 °C to +85 °C; unless otherwise specified.

Symbol	Parameter	Conditions		Min	Тур	Max	Unit
f _{fr}	frame frequency	FF[1:0] = 00		-	32	-	Hz
		FF[1:0] = 01		42	64	86	Hz
		FF[1:0] = 10		-	96	-	Hz
		FF[1:0] = 11		-	128	-	Hz
f _{clk(int)}	internal clock frequency	$f_{fr} = 64 \text{ Hz}, n_{MUX} = 4$	[1]	-	1024	-	Hz
f _{clk(ext)}	external clock frequency		[1]	-	-	4096	Hz
t _{clk(H)}	HIGH-level clock time	external clock		60	-	-	μS
t _{clk(L)}	LOW-level clock time	external clock		60	-	-	μS
t _{w(rst)}	reset pulse width	on pin RST		10	-	-	μS

[1] $f_{clk(int)} = 2 \cdot f_{fr} \cdot n_{MUX}$ or $f_{clk(ext)} = 2 \cdot f_{fr} \cdot n_{MUX}$ respectively (see <u>Table 6</u> and <u>Table 7</u>).

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Table 20. I²C-bus characteristics

 $V_{DD} = 1.8 \text{ V to } 5.5 \text{ V; } V_{SS} = 0 \text{ V; } T_{amb} = -40 \text{ °C to } +85 \text{ °C; } unless otherwise specified; all timing values are valid within the operating supply voltage and <math>T_{amb}$ range and are referenced to V_{IL} and V_{IH} with an input voltage swing of V_{SS} to V_{DD} .

Symbol	Parameter	Conditions	Min	Тур	Max	Unit
Pin SCL						'
f _{SCL}	SCL clock frequency		-	-	400	kHz
t _{LOW}	LOW period of the SCL clock		1.3	-	-	μS
t _{HIGH}	HIGH period of the SCL clock		0.6	-	-	μS
Pin SDA			<u> </u>			
t _{SU;DAT}	data set-up time		100	-	-	ns
t _{HD;DAT}	data hold time		0	-	-	ns
Pins SCL	and SDA					
t _{BUF}	bus free time between a STOP and START condition		1.3	-	-	μS
t _{SU;STO}	set-up time for STOP condition		0.6	-	-	μS
t _{HD;STA}	hold time (repeated) START condition		0.6	-	-	μS
t _{SU;STA}	set-up time for a repeated START condition		0.6	-	-	μS
t _r	rise time of both SDA and SCL signals	f _{SCL} = 400 kHz	-	-	0.3	μS
t _f	fall time of both SDA and SCL signals		-	-	0.3	μS
C _b	capacitive load for each bus line		-	-	400	pF
t _{w(spike)}	spike pulse width	on the I ² C-bus	-	-	50	ns

^[1] The I^2C -bus interface of PCF8553 is 5 V tolerant.

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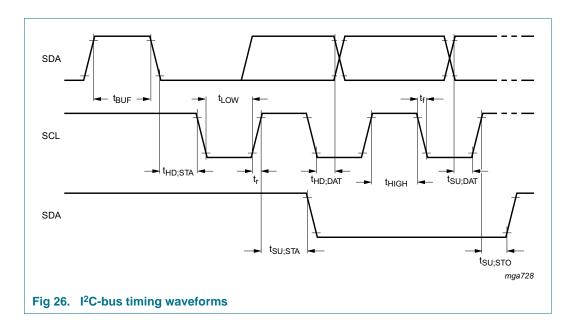
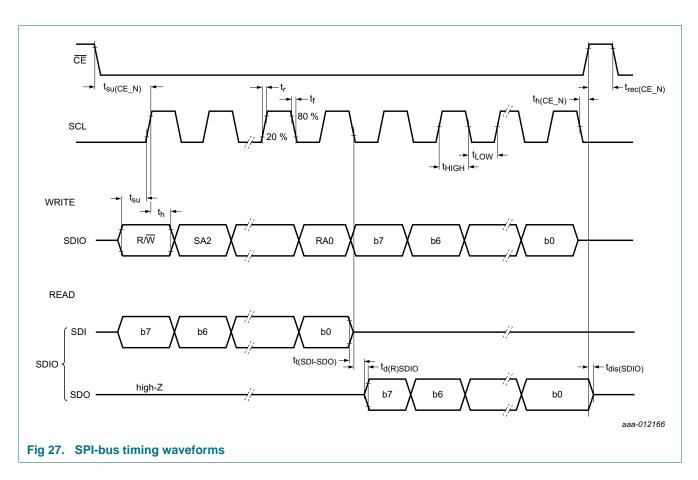


Table 21. SPI-bus characteristics

 $V_{DD} = 1.8 \text{ V}$ to 5.5 V; $V_{SS} = 0 \text{ V}$; $T_{amb} = -40 \text{ °C}$ to +85 °C; unless otherwise specified; all timing values are valid within the operating supply voltage and T_{amb} range and are referenced to V_{IL} and V_{IH} with an input voltage swing of V_{SS} to V_{DD} .

Symbol	Parameter	Conditions	Min	Тур	Max	Unit
Pin SCL						,
f _{SCL}	SCL clock frequency		-	-	5	MHz
t _{LOW}	LOW period of the SCL clock		150	-	-	ns
t _{HIGH}	HIGH period of the SCL clock		80	-	-	ns
t _r	rise time		-	-	100	ns
t _f	fall time		-	-	100	ns
Pin CE			,	'		1
t _{su(CE_N)}	CE_N set-up time		30	-	-	ns
t _{h(CE_N)}	CE_N hold time		10	-	-	ns
t _{rec(CE_N)}	CE_N recovery time		70	-	-	ns
Pin SDIO						
t _{su}	set-up time	write data	5	-	-	ns
t _h	hold time	write data	50	-	-	ns
t _{d(R)SDIO}	SDIO read delay time	C _L = 50 pF	-	-	150	ns
t _{dis(SDIO)}	SDIO disable time	no load	-	-	50	ns
$t_{t(SDI\text{-}SDO)}$	transition time from SDI to SDO	write to read mode	0	-	-	ns

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16. Application information

16.1 Power-on with a slowly starting power supply

The built-in POR block acts on the rising edge of the V_{DD} supply voltage. It is designed to react to fast slopes. If the system supply starts slowly, it is recommended to initiate a software reset immediately after power-on.

16.2 I²C acknowledge after power-on

If the bus does not show an acknowledge at the first access, the command should be sent a second time.

16.3 Resistors on I/O pins

The pins A0, A1, PORE, and IFS comprise internal, latching pull-down devices, which keep these inputs at a low potential when left open. If an input is supposed to be at logic 0 potential, this pin can be either connected to V_{SS} or left open.

In case a pin is supposed to be at logic 1 potential, it must be connected to V_{DD} to avoid any cross-current during power-up. A series resistance between V_{DD} and the associated pin must not exceed 1 k Ω to ensure proper functionality.

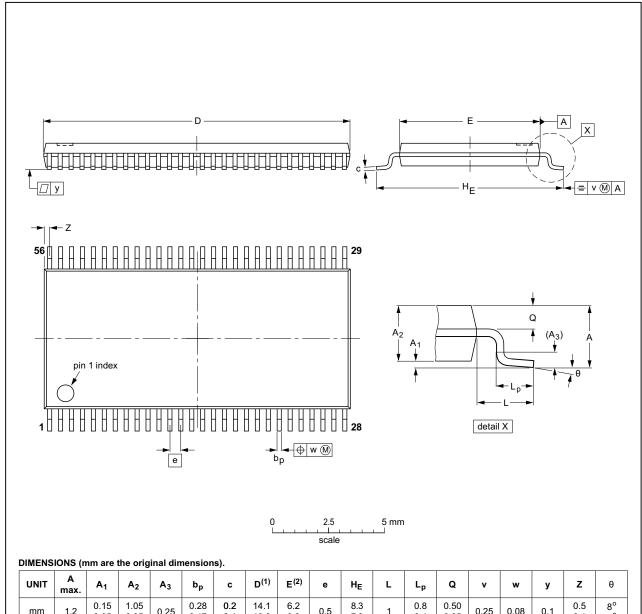
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17. Package outline

TSSOP56: plastic thin shrink small outline package; 56 leads; body width 6.1 mm

SOT364-1



	•					,												
UNIT	A max.	A ₁	A ₂	A ₃	b _p	С	D ⁽¹⁾	E ⁽²⁾	е	HE	L	Lp	Q	v	w	у	z	θ
mm	1.2	0.15 0.05	1.05 0.85	0.25	0.28 0.17	0.2 0.1	14.1 13.9	6.2 6.0	0.5	8.3 7.9	1	0.8 0.4	0.50 0.35	0.25	0.08	0.1	0.5 0.1	8° 0°

Notes

- 1. Plastic or metal protrusions of 0.15 mm maximum per side are not included.
- 2. Plastic interlead protrusions of 0.25 mm maximum per side are not included.

OUTLINE		REFER	EUROPEAN	ISSUE DATE			
VERSION	IEC	JEDEC	JEITA		PROJECTION	ISSUE DATE	
SOT364-1		MO-153				-99-12-27 03-02-19	

Fig 28. Package outline SOT364-1 (TSSOP56) of PCF8553DTT

All information provided in this document is subject to legal disclaimers.

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18. Handling information

All input and output pins are protected against ElectroStatic Discharge (ESD) under normal handling. When handling Metal-Oxide Semiconductor (MOS) devices ensure that all normal precautions are taken as described in *JESD625-A*, *IEC 61340-5* or equivalent standards.

19. Packing information

19.1 Tape and reel information

For tape and reel packing information, see Ref. 11 "SOT364-1_118" on page 48.

20. Soldering of SMD packages

This text provides a very brief insight into a complex technology. A more in-depth account of soldering ICs can be found in Application Note *AN10365* "Surface mount reflow soldering description".

20.1 Introduction to soldering

Soldering is one of the most common methods through which packages are attached to Printed Circuit Boards (PCBs), to form electrical circuits. The soldered joint provides both the mechanical and the electrical connection. There is no single soldering method that is ideal for all IC packages. Wave soldering is often preferred when through-hole and Surface Mount Devices (SMDs) are mixed on one printed wiring board; however, it is not suitable for fine pitch SMDs. Reflow soldering is ideal for the small pitches and high densities that come with increased miniaturization.

20.2 Wave and reflow soldering

Wave soldering is a joining technology in which the joints are made by solder coming from a standing wave of liquid solder. The wave soldering process is suitable for the following:

- Through-hole components
- Leaded or leadless SMDs, which are glued to the surface of the printed circuit board

Not all SMDs can be wave soldered. Packages with solder balls, and some leadless packages which have solder lands underneath the body, cannot be wave soldered. Also, leaded SMDs with leads having a pitch smaller than ~0.6 mm cannot be wave soldered, due to an increased probability of bridging.

The reflow soldering process involves applying solder paste to a board, followed by component placement and exposure to a temperature profile. Leaded packages, packages with solder balls, and leadless packages are all reflow solderable.

Key characteristics in both wave and reflow soldering are:

- Board specifications, including the board finish, solder masks and vias
- Package footprints, including solder thieves and orientation
- The moisture sensitivity level of the packages

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- Package placement
- Inspection and repair
- Lead-free soldering versus SnPb soldering

20.3 Wave soldering

Key characteristics in wave soldering are:

- Process issues, such as application of adhesive and flux, clinching of leads, board transport, the solder wave parameters, and the time during which components are exposed to the wave
- Solder bath specifications, including temperature and impurities

20.4 Reflow soldering

Key characteristics in reflow soldering are:

- Lead-free versus SnPb soldering; note that a lead-free reflow process usually leads to higher minimum peak temperatures (see <u>Figure 29</u>) than a SnPb process, thus reducing the process window
- Solder paste printing issues including smearing, release, and adjusting the process window for a mix of large and small components on one board
- Reflow temperature profile; this profile includes preheat, reflow (in which the board is heated to the peak temperature) and cooling down. It is imperative that the peak temperature is high enough for the solder to make reliable solder joints (a solder paste characteristic). In addition, the peak temperature must be low enough that the packages and/or boards are not damaged. The peak temperature of the package depends on package thickness and volume and is classified in accordance with Table 22 and 23

Table 22. SnPb eutectic process (from J-STD-020D)

Package thickness (mm)	Package reflow temperature (°C)						
	Volume (mm³)						
	< 350	≥ 350					
< 2.5	235	220					
≥ 2.5	220	220					

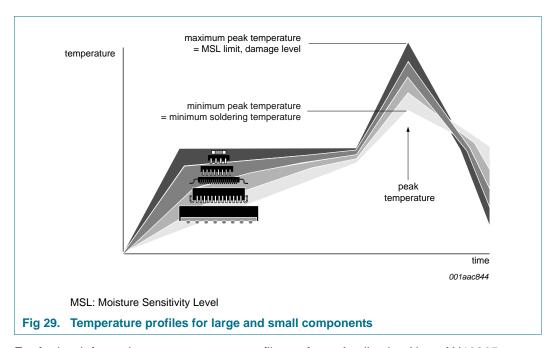
Table 23. Lead-free process (from J-STD-020D)

Package thickness (mm)	Package reflow temp	ackage reflow temperature (°C)						
	Volume (mm ³)							
	< 350	350 to 2000	> 2000					
< 1.6	260	260	260					
1.6 to 2.5	260	250	245					
> 2.5	250	245	245					

Moisture sensitivity precautions, as indicated on the packing, must be respected at all times.

Studies have shown that small packages reach higher temperatures during reflow soldering, see <u>Figure 29</u>.

40 × 4 LCD segment driver



For further information on temperature profiles, refer to Application Note *AN10365* "Surface mount reflow soldering description".

40 × 4 LCD segment driver

21. Footprint information

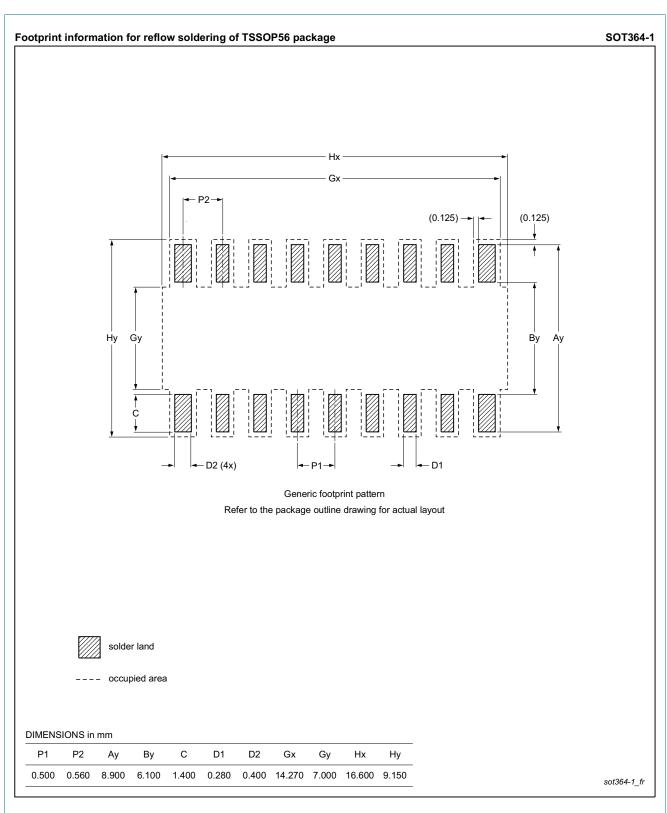


Fig 30. Footprint information for reflow soldering of SOT364-1 (TSSOP56) of PCF8553DTT

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22.1 LCD segment driver selection

Table 24. Selection of LCD segment drivers

Type name	Num	ber c	of eler	ments	at M	UX		V _{DD} (V)	V _{LCD} (V)	f _{fr} (Hz)	V _{LCD} (V)	V _{LCD} (V)	T _{amb} (°C)	Interface	Package	AEC-
	1:1	1:2	1:3	1:4	1:6	1:8	1:9				charge pump	temperature compensat.				Q100
PCA8553DTT	40	80	120	160	-	-	-	1.8 to 5.5	1.8 to 5.5	32 to 256[1]	N	N	-40 to 105	I ² C / SPI	TSSOP56	Υ
PCA8546ATT	-	-	-	176	-	-	-	1.8 to 5.5	2.5 to 9	60 to 300[1]	N	N	-40 to 95	I ² C	TSSOP56	Υ
PCA8546BTT	-	-	-	176	-	-	-	1.8 to 5.5	2.5 to 9	60 to 300[1]	N	N	-40 to 95	SPI	TSSOP56	Υ
PCA8547AHT	44	88	-	176	-	-	-	1.8 to 5.5	2.5 to 9	60 to 300[1]	Υ	Υ	-40 to 95	I ² C	TQFP64	Υ
PCA8547BHT	44	88	-	176	-	-	-	1.8 to 5.5	2.5 to 9	60 to 300[1]	Υ	Υ	-40 to 95	SPI	TQFP64	Υ
PCF85134HL	60	120	180	240	-	-	-	1.8 to 5.5	2.5 to 6.5	82	N	N	-40 to 85	I ² C	LQFP80	N
PCA85134H	60	120	180	240	-	-	-	1.8 to 5.5	2.5 to 8	82	N	N	-40 to 95	I ² C	LQFP80	Υ
PCA8543AHL	60	120	-	240	-	-	-	2.5 to 5.5	2.5 to 9	60 to 300[1]	Υ	Υ	-40 to 105	I ² C	LQFP80	Υ
PCF8545ATT	-	-	-	176	252	320	-	1.8 to 5.5	2.5 to 5.5	60 to 300 ¹¹	N	N	-40 to 85	I ² C	TSSOP56	N
PCF8545BTT	-	-	-	176	252	320	-	1.8 to 5.5	2.5 to 5.5	60 to 300[1]	N	N	-40 to 85	SPI	TSSOP56	N
PCF8536AT	-	-	-	176	252	320	-	1.8 to 5.5	2.5 to 9	60 to 300[1]	N	N	-40 to 85	I ² C	TSSOP56	N
PCF8536BT	-	-	-	176	252	320	-	1.8 to 5.5	2.5 to 9	60 to 300[1]	N	N	-40 to 85	SPI	TSSOP56	N
PCA8536AT	-	-	-	176	252	320	-	1.8 to 5.5	2.5 to 9	60 to 300[1]	N	N	-40 to 95	I ² C	TSSOP56	Υ
PCA8536BT	-	-	-	176	252	320	-	1.8 to 5.5	2.5 to 9	60 to 300[1]	N	N	-40 to 95	SPI	TSSOP56	Υ
PCF8537AH	44	88	-	176	276	352	-	1.8 to 5.5	2.5 to 9	60 to 300[1]	Υ	Υ	-40 to 85	I ² C	TQFP64	N
PCF8537BH	44	88	-	176	276	352	-	1.8 to 5.5	2.5 to 9	60 to 300[1]	Υ	Υ	-40 to 85	SPI	TQFP64	N
PCA8537AH	44	88	-	176	276	352	-	1.8 to 5.5	2.5 to 9	60 to 300[1]	Υ	Υ	-40 to 95	I ² C	TQFP64	Υ
PCA8537BH	44	88	-	176	276	352	-	1.8 to 5.5	2.5 to 9	60 to 300[1]	Υ	Υ	-40 to 95	SPI	TQFP64	Υ
PCA9620H	60	120	-	240	320	480	-	2.5 to 5.5	2.5 to 9	60 to 300[1]	Υ	Υ	-40 to 105	I ² C	LQFP80	Υ
PCA9620U	60	120	-	240	320	480	-	2.5 to 5.5	2.5 to 9	60 to 300[1]	Υ	Υ	-40 to 105	I ² C	Bare die	Υ
PCF8576DU	40	80	120	160	-	-	-	1.8 to 5.5	2.5 to 6.5	77	N	N	-40 to 85	I ² C	Bare die	N
PCF8576EUG	40	80	120	160	-	-	-	1.8 to 5.5	2.5 to 6.5	77	N	N	-40 to 85	I ² C	Bare die	N
PCA8576FUG	40	80	120	160	-	-	-	1.8 to 5.5	2.5 to 8	200	N	N	-40 to 105	I ² C	Bare die	Υ
PCF85133U	80	160	240	320	-	-	-	1.8 to 5.5	2.5 to 6.5	82, 110 ^[2]	N	N	-40 to 85	I ² C	Bare die	N
PCA85133U	80	160	240	320	-	-	-	1.8 to 5.5	2.5 to 8	82, 110 ^[2]	N	N	-40 to 95	I ² C	Bare die	Υ

Table 24. Selection of LCD segment drivers ...continued

Type name Number of elements at MUX			V _{DD} (V)	(V) V_{LCD} (V) f_{fr} (Hz)		V _{LCD} (V)	V _{LCD} (V)	T _{amb} (°C)	Interface	Package	AEC-					
	1:1	1:2	1:3	1:4	1:6	1:8	1:9				charge pump	temperature compensat.				Q100
PCA85233UG	80	160	240	320	-	-	-	1.8 to 5.5	2.5 to 8	150, 220 ^[2]	N	N	-40 to 105	I ² C	Bare die	Υ
PCF85132U	160	320	480	640	-	-	-	1.8 to 5.5	1.8 to 8	60 to 90[1]	N	N	-40 to 85	I ² C	Bare die	N
PCA8530DUG	102	204	-	408	-	-	-	2.5 to 5.5	4 to 12	45 to 300[1]	Y	Υ	-40 to 105	I ² C / SPI	Bare die	Υ
PCA85132U	160	320	480	640	-	-	-	1.8 to 5.5	1.8 to 8	60 to 90[1]	N	N	-40 to 95	I ² C	Bare die	Υ
PCA85232U	160	320	480	640	-	-	-	1.8 to 5.5	1.8 to 8	117 to 176[1]	N	N	-40 to 95	I ² C	Bare die	Υ
PCF8538UG	102	204	-	408	612	816	918	2.5 to 5.5	4 to 12	45 to 300[1]	Y	Υ	-40 to 85	I ² C / SPI	Bare die	N
PCA8538UG	102	204	-	408	612	816	918	2.5 to 5.5	4 to 12	45 to 300[1]	Y	Υ	-40 to 105	I ² C / SPI	Bare die	Υ

^[1] Software programmable.

^[2] Hardware selectable.

40 × 4 LCD segment driver

23. Abbreviations

Table 25. Abbreviations

Acronym	Description
CDM	Charged-Device Model
DC	Direct Current
EMC	ElectroMagnetic Compatibility
ESD	ElectroStatic Discharge
HBM	Human Body Model
I ² C	Inter-Integrated Circuit bus
IC	Integrated Circuit
LCD	Liquid Crystal Display
LSB	Least Significant Bit
MSB	Most Significant Bit
MSL	Moisture Sensitivity Level
MUX	Multiplexer
PCB	Printed-Circuit Board
POR	Power-On Reset
RC	Resistance-Capacitance
RMS	Root Mean Square
SCL	Serial CLock line
SDA	Serial DAta line
SMD	Surface-Mount Device
SPI	Serial Peripheral Interface

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24. References

- [1] AN10365 Surface mount reflow soldering description
- [2] AN10853 ESD and EMC sensitivity of IC
- [3] AN11267 EMC and system level ESD design guidelines for LCD drivers
- [4] IEC 60134 Rating systems for electronic tubes and valves and analogous semiconductor devices
- [5] IEC 61340-5 Protection of electronic devices from electrostatic phenomena
- [6] IPC/JEDEC J-STD-020D Moisture/Reflow Sensitivity Classification for Nonhermetic Solid State Surface Mount Devices
- [7] JESD22-A114 Electrostatic Discharge (ESD) Sensitivity Testing Human Body Model (HBM)
- [8] JESD22-C101 Field-Induced Charged-Device Model Test Method for Electrostatic-Discharge-Withstand Thresholds of Microelectronic Components
- [9] JESD78 IC Latch-Up Test
- [10] JESD625-A Requirements for Handling Electrostatic-Discharge-Sensitive (ESDS) Devices
- [11] SOT364-1_118 TSSOP56; Reel pack; SMD, 13", packing information
- [12] UM10204 I²C-bus specification and user manual
- [13] UM10569 Store and transport requirements

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25. Revision history

Table 26. Revision history

Document ID	Release date	Data sheet status	Change notice	Supersedes							
PCF8553 v.3	20150327	Product data sheet	-	PCF8553 v.2							
Modifications:	Fixed type)									
	Added Fig.	• Added Figure 4									
PCF8553 v.2	20150216	Product data sheet	-	PCF8553 v.1							
PCF8553 v.1	20141205	Objective data sheet	-	-							

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26. Legal information

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Document status[1][2]	Product status[3]	Definition
Objective [short] data sheet	Development	This document contains data from the objective specification for product development.
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40 × 4 LCD segment driver

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- Помощь Конструкторского Отдела и консультации квалифицированных инженеров;
- Техническая поддержка проекта, помощь в подборе аналогов, поставка прототипов;
- Поставка электронных компонентов под контролем ВП;
- Система менеджмента качества сертифицирована по Международному стандарту ISO 9001;
- При необходимости вся продукция военного и аэрокосмического назначения проходит испытания и сертификацию в лаборатории (по согласованию с заказчиком);
- Поставка специализированных компонентов военного и аэрокосмического уровня качества (Xilinx, Altera, Analog Devices, Intersil, Interpoint, Microsemi, Actel, Aeroflex, Peregrine, VPT, Syfer, Eurofarad, Texas Instruments, MS Kennedy, Miteq, Cobham, E2V, MA-COM, Hittite, Mini-Circuits, General Dynamics и др.);

Компания «Океан Электроники» является официальным дистрибьютором и эксклюзивным представителем в России одного из крупнейших производителей разъемов военного и аэрокосмического назначения «JONHON», а так же официальным дистрибьютором и эксклюзивным представителем в России производителя высокотехнологичных и надежных решений для передачи СВЧ сигналов «FORSTAR».



«JONHON» (основан в 1970 г.)

Разъемы специального, военного и аэрокосмического назначения:

(Применяются в военной, авиационной, аэрокосмической, морской, железнодорожной, горно- и нефтедобывающей отраслях промышленности)

«**FORSTAR**» (основан в 1998 г.)

ВЧ соединители, коаксиальные кабели, кабельные сборки и микроволновые компоненты:

(Применяются в телекоммуникациях гражданского и специального назначения, в средствах связи, РЛС, а так же военной, авиационной и аэрокосмической отраслях промышленности).



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