



# Product Specification

## Z8400/Z84C00 NMOS/CMOS Z80<sup>®</sup> CPU Central Processing Unit

### FEATURES

- The extensive instruction set contains 158 instructions, including the 8080A instruction set as a subset.
- NMOS version for low cost high performance solutions, CMOS version for high performance low power designs.
- NMOS Z840004 - 4 MHz, Z840006 - 6.17 MHz, Z840008 - 8 MHz.
- CMOS Z84C0006 - DC to 6.17 MHz, Z84C008 - DC to 8 MHz, Z84C0010 - DC to 10 MHz, Z84C0020 - DC - 20 MHz
- 6 MHz version can be operated at 6.144 MHz clock.
- The Z80 microprocessors and associated family of peripherals can be linked by a vectored interrupt system. This system can be daisy-chained to allow implementation of a priority interrupt scheme.
- Duplicate set of both general-purpose and flag registers.
- Two sixteen-bit index registers.
- Three modes of maskable interrupts: Mode 0—8080A similar; Mode 1—Non-Z80 environment, location 38H; Mode 2—Z80 family peripherals, vectored interrupts.
- On-chip dynamic memory refresh counter.



Figure 1. Pin Functions



Figure 2. 40-pin Dual-In-Line (DIP), Pin Assignments



Figure 2a. 44-Pin LQFP, Pin Assignments  
(Only available for 84C00)



Figure 2b. 44-Pin Chip Carrier Pin Assignments

### GENERAL DESCRIPTION

The CPUs are fourth-generation enhanced microprocessors with exceptional computational power. They offer higher system throughput and more efficient memory utilization than comparable second- and third-generation microprocessors. The internal registers contain 208 bits of read/write memory that are accessible to the programmer. These registers include two sets of six general-purpose registers which may be used individually as either 8-bit registers or as 16-bit register pairs. In addition, there are two sets of accumulator and flag registers. A group of "Exchange" instructions makes either set of main or alternate registers accessible to the programmer. The alternate set allows operation in foreground-background mode or it may be reserved for very fast interrupt response.

The CPU also contains a Stack Pointer, Program Counter, two index registers, a Refresh register (counter), and an Interrupt register. The CPU is easy to incorporate into a system since it requires only a single +5V power source. All output signals are fully decoded and timed to control standard memory or peripheral circuits; the CPU is supported by an extensive family of peripheral controllers. The internal block diagram (Figure 3) shows the primary functions of the processors. Subsequent text provides more detail on the I/O controller family, registers, instruction set, interrupts and daisy chaining, and CPU timing.



Figure 3. Z80C CPU Block Diagram

Table 1. Z80C CPU Registers

Register	Size (Bits)	Remarks	
A, A'	Accumulator	8	Stores an operand or the results of an operation.
F, F'	Flags	8	See Instruction Set.
B, B'	General Purpose	8	Can be used separately or as a 16-bit register with C.
C, C'	General Purpose	8	Can be used separately or as a 16-bit register with B.
D, D'	General Purpose	8	Can be used separately or as a 16-bit register with E.
E, E'	General Purpose	8	Can be used separately or as a 16-bit register with D.
H, H'	General Purpose	8	Can be used separately or as a 16-bit register with L.
L, L'	General Purpose	8	Can be used separately or as a 16-bit register with H.
Note: The (B,C), (D,E), and (H,L) sets are combined as follows:			
B — High byte    C — Low byte			
D — High byte    E — Low byte			
H — High byte    L — Low byte			
I	Interrupt Register	8	Stores upper eight bits of memory address for vectored interrupt processing.
R	Refresh Register	8	Provides user-transparent dynamic memory refresh. Automatically incremented and placed on the address bus during each instruction fetch cycle.
IX	Index Register	16	Used for indexed addressing.
IY	Index Register	16	Used for indexed addressing.
SP	Stack Pointer	16	Holds address of the top of the stack. See Push or Pop in instruction set.
PC	Program Counter	16	Holds address of next instruction.
IFF <sub>1</sub> -IFF <sub>2</sub>	Interrupt Enable	Flip-Flops	Set or reset to indicate interrupt status (see Figure 4).
IMFa-IMFb	Interrupt Mode	Flip-Flops	Reflect Interrupt mode (see Figure 4).

failure has been detected. After recognition of the  $\overline{\text{NMI}}$  signal (providing  $\overline{\text{BUSREQ}}$  is not active), the CPU jumps to restart location 0066H. Normally, software starting at this address contains the interrupt service routine.

**Maskable Interrupt ( $\overline{\text{INT}}$ ).** Regardless of the interrupt mode set by the user, the CPU response to a maskable interrupt input follows a common timing cycle. After the interrupt has been detected by the CPU (provided that interrupts are enabled and  $\overline{\text{BUSREQ}}$  is not active) a special interrupt processing cycle begins. This is a special fetch ( $\overline{\text{M1}}$ ) cycle in which  $\overline{\text{IORQ}}$  becomes active rather than  $\overline{\text{MREQ}}$ , as in a normal  $\overline{\text{M1}}$  cycle. In addition, this special  $\overline{\text{M1}}$  cycle is automatically extended by two  $\overline{\text{WAIT}}$  states, to allow for the time required to acknowledge the interrupt request.

**Mode 0 Interrupt Operation.** This mode is similar to the 8080 microprocessor interrupt service procedures. The interrupting device places an instruction on the data bus. This is normally a Restart instruction, which will initiate a call

to the selected one of eight restart locations in page zero of memory. Unlike the 8080, the Z80 CPU responds to the Call instruction with only one interrupt acknowledge cycle followed by two memory read cycles.

**Mode 1 Interrupt Operation.** Mode 1 operation is very similar to that for the NMI. The principal difference is that the Mode 1 interrupt has only one restart location, 003BH.

**Mode 2 Interrupt Operation.** This interrupt mode has been designed to most effectively utilize the capabilities of the Z80 microprocessor and its associated peripheral family. The interrupting peripheral device selects the starting address of the interrupt service routine. It does this by placing an 8-bit vector on the data bus during the interrupt acknowledge cycle. The CPU forms a pointer using this byte as the lower 8 bits and the contents of the I register as the upper 8 bits. This points to an entry in a table of addresses for interrupt service routines. The CPU then jumps to the routine at that

address. This flexibility in selecting the interrupt service routine address allows the peripheral device to use several different types of service routines. These routines may be located at any available location in memory. Since the interrupting device supplies the low-order byte of the 2-byte vector, bit 0 ( $A_0$ ) must be a zero.

**Interrupt Enable/Disable Operation.** Two flip-flops, IFF<sub>1</sub> and IFF<sub>2</sub>, referred to in the register description, are used to signal the CPU interrupt status. Operation of the two flip-flops is described in Table 2. For more details, refer to the *Z80 CPU Technical Manual* (03-0029-01) and *Z80 Assembly Language Programming Manual* (03-0002-01).

Table 2. State of Flip-Flops

Action	IFF <sub>1</sub>	IFF <sub>2</sub>	Comments
CPU Reset	0	0	Maskable interrupt INT disabled
DI instruction execution	0	0	Maskable interrupt INT disabled
EI instruction execution	1	1	Maskable interrupt INT enabled
LD A,I instruction execution	•	•	IFF <sub>2</sub> → Parity flag
LD A,R instruction execution	•	•	IFF <sub>2</sub> → Parity flag
Accept NMI	0	•	Maskable interrupt INT disabled
RETN instruction execution	IFF <sub>2</sub>	•	IFF <sub>2</sub> → IFF <sub>1</sub> at completion of an NMI service routine.

## INSTRUCTION SET

The microprocessor has one of the most powerful and versatile instruction sets available in any 8-bit microprocessor. It includes such unique operations as a block move for fast, efficient data transfers within memory, or between memory and I/O. It also allows operations on any bit in any location in memory.

The following is a summary of the instruction set which shows the assembly language mnemonic, the operation, the flag status, and gives comments on each instruction. For an explanation of flag notations and symbols for mnemonic tables, see the Symbolic Notations section which follows these tables. The *Z80 CPU Technical Manual* (03-0029-01), the *Programmer's Reference Guide* (03-0012-03), and *Assembly Language Programming Manual* (03-0002-01) contain significantly more details for programming use.

The instructions are divided into the following categories:

- 8-bit loads
- 16-bit loads
- Exchanges, block transfers, and searches
- 8-bit arithmetic and logic operations
- General-purpose arithmetic and CPU control
- 16-bit arithmetic operations
- Rotates and shifts

- Bit set, reset, and test operations
- Jumps
- Calls, returns, and restarts
- Input and output operations

A variety of addressing modes are implemented to permit efficient and fast data transfer between various registers, memory locations, and input/output devices. These addressing modes include:

- Immediate
- Immediate extended
- Modified page zero
- Relative
- Extended
- Indexed
- Register
- Register indirect
- Implied
- Bit

## 8-BIT LOAD GROUP

Mnemonic	Symbolic Operation	S	Z	Flags			Opcode			Hex	No. of Bytes	No. of M Cycles	No. of T States	Comments		
				H	P/V	N	C	76	543						210	
LD r, r'	r ← r'	•	•	X	•	X	•	•	•	01	r	r'	1	1	4	r, r' Reg.
LD r, n	r ← n	•	•	X	•	X	•	•	•	00	r	n	2	2	7	000 B
																← n →
LD r, (HL)	r ← (HL)	•	•	X	•	X	•	•	•	01	r	(HL)	1	2	7	010 D
LD r, (IX+d)	r ← (IX+d)	•	•	X	•	X	•	•	•	11	011	(IX+d)	3	5	19	011 E
																010 H
																← d →
LD r, (IY+d)	r ← (IY+d)	•	•	X	•	X	•	•	•	11	111	(IY+d)	3	5	19	101 L
																111 A
																← d →
LD (HL), r	(HL) ← r	•	•	X	•	X	•	•	•	01	110	r	1	2	7	
LD (IX+d), r	(IX+d) ← r	•	•	X	•	X	•	•	•	11	011	(IX+d)	3	5	19	
																010 r
																← d →
LD (IY+d), r	(IY+d) ← r	•	•	X	•	X	•	•	•	11	111	(IY+d)	3	5	19	
																010 r
																← d →
LD (HL), n	(HL) ← n	•	•	X	•	X	•	•	•	00	110	n	2	3	10	
																← n →
LD (IX+d), n	(IX+d) ← n	•	•	X	•	X	•	•	•	11	011	(IX+d)	4	5	19	
																000 36
																← d →
																← n →

### 8-BIT LOAD GROUP (Continued)

Mnemonic	Symbolic Operation	S	Z	Flags			Opcode				No. of Bytes	No. of M Cycles	No. of T States	Comments			
				H	P/V	N	C	76	543	210					Hex		
LD (Y+d), n	(Y+d) ← n	•	•	X	•	X	•	•	•	11 00	111 110	101 110	FD 36	4	5	19	
LDA, (BC)	A ← (BC)	•	•	X	•	X	•	•	•	00	001 010	010 0A	0A	1	2	7	
LDA, (DE)	A ← (DE)	•	•	X	•	X	•	•	•	00	011 010	010 1A	1A	1	2	7	
LDA, (nn)	A ← (nn)	•	•	X	•	X	•	•	•	00	111 010	010 3A	3A	3	4	13	
LD (BC), A	(BC) ← A	•	•	X	•	X	•	•	•	00	000 010	010 02	02	1	2	7	
LD (DE), A	(DE) ← A	•	•	X	•	X	•	•	•	00	010 010	010 12	12	1	2	7	
LD (nn), A	(nn) ← A	•	•	X	•	X	•	•	•	00	110 010	010 32	32	3	4	13	
LDA, I	A ← I	‡	‡	X	0	X	IFF	0	•	11 01	101 101	101 ED	ED	2	2	9	
LDA, R	A ← R	‡	‡	X	0	X	IFF	0	•	11 01	101 101	101 ED	ED	2	2	9	
LD I, A	I ← A	•	•	X	•	X	•	•	•	11 01	101 101	101 ED	ED	2	2	9	
LDR, A	R ← A	•	•	X	•	X	•	•	•	11 01	101 101	101 ED	ED	2	2	9	

NOTE: IFF, the content of the interrupt enable flip-flop, (IFF<sub>2</sub>), is copied into the P/V flag.

### 16-BIT LOAD GROUP

Mnemonic	Symbolic Operation	S	Z	Flags			Opcode				No. of Bytes	No. of M Cycles	No. of T States	Comments			
				H	P/V	N	C	76	543	210					Hex		
LD dd, nn	dd ← nn	•	•	X	•	X	•	•	•	00 dd0	001		3	3	10	dd Pair	
																00 BC	
																01 DE	
LD IX, nn	IX ← nn	•	•	X	•	X	•	•	•	11 00	011 101	DD 21	DD	4	4	14	10 HL
																11 SP	
LD IY, nn	IY ← nn	•	•	X	•	X	•	•	•	11 00	111 101	FD 21	FD	4	4	14	
LD HL, (nn)	H ← (nn+1) L ← (nn)	•	•	X	•	X	•	•	•	00 101	010 2A	2A	3	5	16		
LD dd, (nn)	dd <sub>H</sub> ← (nn+1) dd <sub>L</sub> ← (nn)	•	•	X	•	X	•	•	•	11 01	101 101	ED dd1	ED	4	6	20	

NOTE: (PAIR)<sub>H</sub>, (PAIR)<sub>L</sub> refer to high order and low order eight bits of the register pair respectively. e.g., BC<sub>L</sub> = C, AF<sub>H</sub> = A.

**16-BIT LOAD GROUP** (Continued)

Mnemonic	Symbolic Operation	Flags					Opcode				No. of Bytes	No. of M Cycles	No. of T States	Comments			
		S	Z	H	P/V	N	C	76	543	210					Hex		
LD IX, (nn)	$IX_H \leftarrow (nn+1)$	•	•	X	•	X	•	•	•	•	11 011 101	DD	4	6	20		
	$IX_L \leftarrow (nn)$										00 101 010	2A					
											$\leftarrow n \rightarrow$						
											$\leftarrow n \rightarrow$						
LD IY, (nn)	$IY_H \leftarrow (nn+1)$	•	•	X	•	X	•	•	•	•	11 111 101	FD	4	6	20		
	$IY_L \leftarrow (nn)$										00 101 010	2A					
											$\leftarrow n \rightarrow$						
											$\leftarrow n \rightarrow$						
LD (nn), HL	$(nn+1) \leftarrow H$	•	•	X	•	X	•	•	•	•	00 100 010	22	3	5	16		
	$(nn) \leftarrow L$										$\leftarrow n \rightarrow$						
											$\leftarrow n \rightarrow$						
											$\leftarrow n \rightarrow$						
LD (nn), dd	$(nn+1) \leftarrow dd_H$	•	•	X	•	X	•	•	•	•	11 101 101	ED	4	6	20		
	$(nn) \leftarrow dd_L$										01 dd0 011						
											$\leftarrow n \rightarrow$						
											$\leftarrow n \rightarrow$						
LD (nn), IX	$(nn+1) \leftarrow IX_H$	•	•	X	•	X	•	•	•	•	11 011 101	DD	4	6	20		
	$(nn) \leftarrow IX_L$										00 100 010	22					
											$\leftarrow n \rightarrow$						
											$\leftarrow n \rightarrow$						
LD (nn), IY	$(nn+1) \leftarrow IY_H$	•	•	X	•	X	•	•	•	•	11 111 101	FD	4	6	20		
	$(nn) \leftarrow IY_L$										00 100 010	22					
											$\leftarrow n \rightarrow$						
											$\leftarrow n \rightarrow$						
LD SP, HL	$SP \leftarrow HL$	•	•	X	•	X	•	•	•	•	11 111 001	F9	1	1	6		
LD SP, IX	$SP \leftarrow IX$	•	•	X	•	X	•	•	•	•	11 011 101	DD	2	2	10		
											11 111 001	F9					
LD SP, IY	$SP \leftarrow IY$	•	•	X	•	X	•	•	•	•	11 111 101	FD	2	2	10		
											11 111 001	F9					
PUSH qq	$(SP-2) \leftarrow qq_L$	•	•	X	•	X	•	•	•	•	11 qq0 101		1	3	11	00	BC
	$(SP-1) \leftarrow qq_H$															01	DE
	$SP \rightarrow SP-2$															10	HL
PUSH IX	$(SP-2) \leftarrow IX_L$	•	•	X	•	X	•	•	•	•	11 011 101	DD	2	4	15	11	AF
	$(SP-1) \leftarrow IX_H$										11 100 101	E5					
	$SP \rightarrow SP-2$																
PUSH IY	$(SP-2) \leftarrow IY_L$	•	•	X	•	X	•	•	•	•	11 111 101	FD	2	4	15		
	$(SP-1) \leftarrow IY_H$										11 100 101	E5					
	$SP \rightarrow SP-2$																
POP qq	$qq_H \leftarrow (SP+1)$	•	•	X	•	X	•	•	•	•	11 qq0 001		1	3	10		
	$qq_L \leftarrow (SP)$																
	$SP \rightarrow SP+2$																
POPIX	$IX_H \leftarrow (SP+1)$	•	•	X	•	X	•	•	•	•	11 011 101	DD	2	4	14		
	$IX_L \leftarrow (SP)$										11 100 001	E1					
	$SP \rightarrow SP+2$																
POPIY	$IY_H \leftarrow (SP+1)$	•	•	X	•	X	•	•	•	•	11 111 101	FD	2	4	14		
	$IY_L \leftarrow (SP)$										11 100 001	E1					
	$SP \rightarrow SP+2$																

NOTE: (PAIR)<sub>H</sub>, (PAIR)<sub>L</sub> refer to high order and low order eight bits of the register pair respectively, e.g., BC<sub>L</sub> = C, AF<sub>H</sub> = A.

## EXCHANGE, BLOCK TRANSFER, BLOCK SEARCH GROUPS

Mnemonic	Symbolic Operation	Flags						Opcode			Hex	No. of Bytes	No. of M Cycles	No. of T States	Comments				
		S	Z	H	P/V	N	C	76	543	210									
EX DE, HL	DE ↔ HL	•	•	X	•	X	•	•	•	•	11	101	011	EB	1	1	4		
EX AF, AF'	AF ↔ AF'	•	•	X	•	X	•	•	•	•	00	001	000	08	1	1	4		
EXX	BC ↔ BC'	•	•	X	•	X	•	•	•	•	11	011	001	D9	1	1	4	Register bank and auxiliary register bank exchange	
	DE ↔ DE'																		
	HL ↔ HL'																		
EX (SP), HL	H ↔ (SP + 1) L ↔ (SP)	•	•	X	•	X	•	•	•	•	11	100	011	E3	1	5	19		
EX (SP), IX	IX <sub>H</sub> ↔ (SP + 1)	•	•	X	•	X	•	•	•	•	11	011	101	DD	2	6	23		
	IX <sub>L</sub> ↔ (SP)										11	100	011	E3					
EX (SP), IY	IY <sub>H</sub> ↔ (SP + 1)	•	•	X	•	X	•	•	•	•	11	111	101	FD	2	6	23		
	IY <sub>L</sub> ↔ (SP)										11	100	011	E3					
LDI	(DE) ← (HL)	•	•	X	0	X	†	0	•	•	11	101	101	ED	2	4	16	Load (HL) into (DE), increment the pointers and decrement the byte counter (BC)	
	DE ← DE + 1										10	100	000	A0					
	HL ← HL + 1																		
	BC ← BC - 1																		
LDIR	(DE) ← (HL)	•	•	X	0	X	0	0	•	•	11	101	101	ED	2	5	21	If BC ≠ 0	
	DE ← DE + 1										10	110	000	B0	2	4	16	If BC = 0	
	HL ← HL + 1																		
	BC ← BC - 1																		
	Repeat until BC = 0																		
LDD	(DE) ← (HL)	•	•	X	0	X	†	0	•	•	11	101	101	ED	2	4	16		
	DE ← DE - 1										10	101	000	A8					
	HL ← HL - 1																		
	BC ← BC - 1																		
LDDR	(DE) ← (HL)	•	•	X	0	X	0	0	•	•	11	101	101	ED	2	5	21	If BC ≠ 0	
	DE ← DE - 1										10	111	000	B8	2	4	16	If BC = 0	
	HL ← HL - 1																		
	BC ← BC - 1																		
	Repeat until BC = 0																		
CPI	A - (HL)	†	†	X	†	X	†	1	•	•	11	101	101	ED	2	4	16		
	HL ← HL + 1										10	100	001	A1					
	BC ← BC - 1																		

NOTE: ① P/V flag is 0 if the result of BC - 1 = 0, otherwise P/V = 1.  
 ② P/V flag is 0 only at completion of instruction.  
 ③ Z flag is 1 if A = HL, otherwise Z = 0.



**EXCHANGE, BLOCK TRANSFER, BLOCK SEARCH GROUPS (Continued)**

Mnemonic	Symbolic Operation	S Z		Flags				Opcode				No. of Bytes	No. of M Cycles	No. of T States	Comments		
		S	Z	H	P/V	N	C	76	543	210	Hex						
CPIR	A ← (HL)	‡	‡	X	‡	X	‡	1	•	11	101	101	ED	2	5	21	If BC ≠ 0 and A ≠ (HL)
	HL ← HL + 1									10	110	001	B1	2	4	16	If BC = 0 or A = (HL)
	BC ← BC - 1 Repeat until A = (HL) or BC = 0																
CPD	A ← (HL)	‡	‡	X	‡	X	‡	1	•	11	101	101	ED	2	4	16	
	HL ← HL - 1									10	101	001	A9				
	BC ← BC - 1																
CPDR	A ← (HL)	‡	‡	X	‡	X	‡	1	•	11	101	101	ED	2	5	21	If BC ≠ 0 and A ≠ (HL)
	HL ← HL - 1									10	111	001	B9	2	4	16	If BC = 0 or A = (HL)
	BC ← BC - 1 Repeat until A = (HL) or BC = 0																

NOTE: ① P/V flag is 0 if the result of BC - 1 = 0, otherwise P/V = 1.  
 ② P/V flag is 0 only at completion of instruction.  
 ③ Z flag is 1 if A = (HL), otherwise Z = 0.

**8-BIT ARITHMETIC AND LOGICAL GROUP**

Mnemonic	Symbolic Operation	S Z		Flags				Opcode				No. of Bytes	No. of M Cycles	No. of T States	Comments										
		S	Z	H	P/V	N	C	76	543	210	Hex														
ADD A, r	A ← A + r	‡	‡	X	‡	X	V	0	‡	10	000	r		1	1	4	r Reg.								
ADD A, n	A ← A + n	‡	‡	X	‡	X	V	0	‡	11	000	110		2	2	7	000 B								
																						001 C			
																									010 D
ADD A, (HL)	A ← A + (HL)	‡	‡	X	‡	X	V	0	‡	10	000	110		1	2	7	100 H								
ADD A, (IX + d)	A ← A + (IX + d)	‡	‡	X	‡	X	V	0	‡	11	011	101	DD	3	5	19	101 L								
																									111 A
ADD A, (IY + d)	A ← A + (IY + d)	‡	‡	X	‡	X	V	0	‡	11	111	101	FD	3	5	19									
ADC A, s	A ← A + s + CY	‡	‡	X	‡	X	V	0	‡		001						s is any of r, n, (HL), (IX + d), (IY + d) as shown for ADD instruction. The indicated bits replace the 000 in the ADD set above.								
SUB s	A ← A - s	‡	‡	X	‡	X	V	1	‡		010														
SBC A, s	A ← A - s - CY	‡	‡	X	‡	X	V	1	‡		011														
AND s	A ← A > s	‡	‡	X	1	X	P	0	0		100														
OR s	A ← A > s	‡	‡	X	0	X	P	0	0		110														
XOR s	A ← A ⊕ s	‡	‡	X	0	X	P	0	0		101														
CP s	A ← s	‡	‡	X	‡	X	V	1	‡		111														



## 16-BIT ARITHMETIC GROUP

Mnemonic	Symbolic Operation	S	Z	Flags			Opcode			Hex	No. of Bytes	No. of M Cycles	No. of T States	Comments			
				H	P/V	N	C	76	543					210	ss	Reg.	
ADD HL, ss	HL ← HL + ss	•	•	X	X	X	•	0	‡	00	ssl	001		1	3	11	ss Reg. 00 BC
ADC HL, ss	HL ← HL + ss + CY	‡	‡	X	X	X	V	0	‡	11	101	101	ED	2	4	15	01 DE 10 HL 11 SP
SBC HL, ss	HL ← HL - ss - CY	‡	‡	X	X	X	V	1	‡	11	101	101	ED	2	4	15	01 ss0 010
ADD IX, pp	IX ← IX + pp	•	•	X	X	X	•	0	‡	11	011	101	DD	2	4	15	pp Reg. 00 BC 01 DE 10 IX 11 SP
ADD IY, rr	IY ← IY + rr	•	•	X	X	X	•	0	‡	11	111	101	FD	2	4	15	rr Reg. 00 BC
INC ss	ss ← ss + 1	•	•	X	•	X	•	•	•	00	ss0	011		1	1	6	01 DE
INC IX	IX ← IX + 1	•	•	X	•	X	•	•	•	11	011	101	DD	2	2	10	10 IY 11 SP
INC IY	IY ← IY + 1	•	•	X	•	X	•	•	•	11	111	101	FD	2	2	10	00 100 011 23
DEC ss	ss ← ss - 1	•	•	X	•	X	•	•	•	00	ss1	011		1	1	6	
DEC IX	IX ← IX - 1	•	•	X	•	X	•	•	•	11	011	101	DD	2	2	10	00 101 011 2B
DEC IY	IY ← IY - 1	•	•	X	•	X	•	•	•	11	111	101	FD	2	2	10	00 101 011 2B

## ROTATE AND SHIFT GROUP

Mnemonic	Symbolic Operation	S	Z	Flags			Opcode			Hex	No. of Bytes	No. of M Cycles	No. of T States	Comments			
				H	P/V	N	C	76	543						210		
RLCA		•	•	X	0	X	•	0	‡	00	000	111	07	1	1	4	Rotate left circular accumulator.
RLA		•	•	X	0	X	•	0	‡	00	010	111	17	1	1	4	Rotate left accumulator.
RRCA		•	•	X	0	X	•	0	‡	00	001	111	0F	1	1	4	Rotate right circular accumulator.
RRA		•	•	X	0	X	•	0	‡	00	011	111	1F	1	1	4	Rotate right accumulator.

**ROTATE AND SHIFT GROUP (Continued)**

Symbolic Mnemonic Operation	Flags		Flags				Opcode			No. of Bytes	No. of M Cycles	No. of T States	Comments		
	S	Z	H	P/V	N	C	76	543	210					Hex	
RLC r	†	†	X	0	X	P	0	†	11 001 011	CB	2	2	8	Rotate left circular register r.	
									00 000 r						
RLC (HL)	†	†	X	0	X	P	0	†	11 001 011	CB	2	4	15	r Reg.	
									00 000 110					000 B	
RLC (IX+d)	†	†	X	0	X	P	0	†	11 011 101	DD	4	6	23	001 C	
									11 001 011	CB				010 D	
									00 000 110					011 E	
									00 000 110					001 H	
									00 000 110					101 L	
									00 000 110					111 A	
RLC (IY+d)	†	†	X	0	X	P	0	†	11 111 101	FD	4	6	23		
									11 001 011	CB					
									00 000 110						
RL m	†	†	X	0	X	P	0	†	00 000 110					Instruction format and states are as shown for RLCs. To form new opcode replace 000 or RLCs with shown code.	
									00 010						
RRC m	†	†	X	0	X	P	0	†	001						
RR m	†	†	X	0	X	P	0	†	011						
SLA m	†	†	X	0	X	P	0	†	100						
SRA m	†	†	X	0	X	P	0	†	101						
SRL m	†	†	X	0	X	P	0	†	111						
RLD	†	†	X	0	X	P	0	•	11 101 101	ED	2	5	18		Rotate digit left and right between the accumulator and location (HL).
									01 101 111	6F					
RRD	†	†	X	0	X	P	0	•	11 101 101	ED	2	5	18		The content of the upper half of the accumulator is unaffected.
									01 100 111	67					

## BIT SET, RESET AND TEST GROUP

Mnemonic	Symbolic Operation	Flags							Opcode			No. of Bytes	No. of M Cycles	No. of T States	Comments											
		S	Z	H	P/V	N	C	76	543	210	Hex															
BIT b, r	$Z \leftarrow r_b$	X	†	X	1	X	X	0	•	11	001	011	CB	2	2	8	r Reg. 000 B									
BIT b, (HL)	$Z \leftarrow (HL)_b$	X	†	X	1	X	X	0	•	11	001	011	CB	2	3	12	001 C 010 D									
BIT b, (IX+d) <sub>b</sub>	$Z \leftarrow (IX+d)_b$	X	†	X	1	X	X	0	•	11	011	101	DD	4	5	20	011 E									
										11	001	011	CB								100 H					
										←d→																101 L
										01	b	110														111 A
BIT b, (IY+d) <sub>b</sub>	$Z \leftarrow (IY+d)_b$	X	†	X	1	X	X	0	•	11	111	101	FD	4	5	20	000 0									
										11	001	011	CB											001 1		
										←d→																010 2
										01	b	110														011 3
SET b, r	$r_b \leftarrow 1$	•	•	X	•	X	•	•	•	11	001	011	CB	2	2	8	100 4									
SET b, (HL)	$(HL)_b \leftarrow 1$	•	•	X	•	X	•	•	•	11	b	r					101 5									
										11	b	110													110 6	
SET b, (IX+d)	$(IX+d)_b \leftarrow 1$	•	•	X	•	X	•	•	•	11	011	101	DD	4	6	23										
										11	001	011	CB													
										←d→																
SET b, (IY+d)	$(IY+d)_b \leftarrow 1$	•	•	X	•	X	•	•	•	11	b	110														
										11	111	101	FD	4	6	23										
										11	001	011	CB													
RES b, m	$m_b \leftarrow 0$ $m = r, (HL),$ $(IX+d), (IY+d)$	•	•	X	•	X	•	•	•	11	b	110														
										10																

To form new opcode replace **11** of SET b, s with **10**. Flags and time states for SET instruction.

NOTE: The notation  $m_b$  indicates location m, bit b (0 to 7).

## JUMP GROUP

Mnemonic	Symbolic Operation	Flags					Opcode			No. of Bytes	No. of M Cycles	No. of T States	Comments				
		S	Z	H	P/V/N	C	76	543	210					Hex			
JP nn	PC ← nn	•	•	X	•	X	•	•	•	11	000	011	C3	3	3	10	cc Condition 000 NZ (non-zero) 001 Z (zero)
JP cc, nn	If condition cc is true PC ← nn, otherwise continue	•	•	X	•	X	•	•	•	11	cc	010		3	3	10	010 NC (non-carry) 011 C (carry) 100 PO (parity odd) 101 PE (parity even)
JR e	PC ← PC + e	•	•	X	•	X	•	•	•	00	011	000	18	2	3	12	110 P (sign positive) 111 M (sign negative)
JR C, e	If C = 0, continue If C = 1, PC ← PC + e	•	•	X	•	X	•	•	•	00	111	000	38	2	2	7	If condition not met.
														2	3	12	If condition is met.
JR NC, e	If C = 1, continue If C = 0, PC ← PC + e	•	•	X	•	X	•	•	•	00	110	000	30	2	2	7	If condition not met.
														2	3	12	If condition is met.
JP Z, e	If Z = 0, continue If Z = 1, PC ← PC + e	•	•	X	•	X	•	•	•	00	101	000	28	2	2	7	If condition not met.
														2	3	12	If condition is met.
JR NZ, e	If Z = 1, continue If Z = 0, PC ← PC + e	•	•	X	•	X	•	•	•	00	100	000	20	2	2	7	If condition not met.
														2	3	12	If condition is met.
JP (HL)	PC ← HL	•	•	X	•	X	•	•	•	11	101	001	E9	1	1	4	
JP (IX)	PC ← IX	•	•	X	•	X	•	•	•	11	011	101	DD	2	2	8	
										11	101	001	E9				
JP (IY)	PC ← IY	•	•	X	•	X	•	•	•	11	111	101	FD	2	2	8	
										11	101	001	E9				
DJNZ, e	B ← B - 1 If B = 0, continue If B ≠ 0, PC ← PC + e	•	•	X	•	X	•	•	•	00	010	000	10	2	2	8	If B = 0
														2	3	13	If B ≠ 0.

NOTES: e represents the extension in the relative addressing mode.  
e is a signal two's complement number in the range < -126, 129 >.  
e - 2 in the opcode provides an effective address of pc + e as PC is incremented by 2 prior to the addition of e.



## INPUT AND OUTPUT GROUP

Mnemonic	Symbolic Operation	Flags					Opcode				No. of Bytes	No. of M Cycles	No. of T States	Comments					
		S	Z	H	P/VN	C	76	543	210	Hex									
INA, (n)	A ← (n)	•	•	X	•	X	•	•	•	•	11	011	01	DB	2	3	11	n to A <sub>0</sub> ~ A <sub>7</sub> Acc. to A <sub>8</sub> ~ A <sub>15</sub>	
IN r, (C)	r ← (C) if r=110 only the flags will be affected	‡	‡	X	‡	X	P	0	•	•	11	101	101	ED	2	3	12	C to A <sub>0</sub> ~ A <sub>7</sub> B to A <sub>8</sub> ~ A <sub>15</sub>	
INI	(HL) ← (C)			X	‡	X	X	X	X	1	X	11	101	101	ED	2	4	16	C to A <sub>0</sub> ~ A <sub>7</sub> B to A <sub>8</sub> ~ A <sub>15</sub>
	B ← B - 1 HL ← HL + 1											10	100	010	A2				
INIR	(HL) ← (C)	X	1	X	X	X	X	X	1	X	11	101	101	ED	2	5 (if B≠0)	21	C to A <sub>0</sub> ~ A <sub>7</sub> B to A <sub>8</sub> ~ A <sub>15</sub>	
	B ← B - 1 HL ← HL + 1											10	110	010					B2
	Repeat until B = 0																2	4 (if B = 0)	16
IND	(HL) ← (C)	X	‡	X	X	X	X	X	1	X	11	101	101	ED	2	4	16	C to A <sub>0</sub> ~ A <sub>7</sub> B to A <sub>8</sub> ~ A <sub>15</sub>	
	B ← B - 1 HL ← HL - 1											10	101	010					AA
INDR	(HL) ← (C)	X	1	X	X	X	X	1	X	11	101	101	ED	2	5 (if B≠0)	21	C to A <sub>0</sub> ~ A <sub>7</sub> B to A <sub>8</sub> ~ A <sub>15</sub>		
	B ← B - 1 HL ← HL - 1											10	111					010	BA
	Repeat until B = 0																2	4 (if B = 0)	16
OUT (n), A	(n) → A	•	•	X	•	X	•	•	•	•	11	010	011	D3	2	3	11	n to A <sub>0</sub> ~ A <sub>7</sub> Acc. to A <sub>8</sub> ~ A <sub>15</sub>	
OUT (C), r	(C) → r	•	•	X	•	X	•	•	•	•	11	101	101	ED	2	3	12	C to A <sub>0</sub> ~ A <sub>7</sub> B to A <sub>8</sub> ~ A <sub>15</sub>	
OUTI	(C) ← (HL)	X	‡	X	X	X	X	1	X	11	101	101	ED	2	4	16	C to A <sub>0</sub> ~ A <sub>7</sub> B to A <sub>8</sub> ~ A <sub>15</sub>		
	B ← B - 1 HL ← HL + 1											10	100					011	A3
OTIR	(C) ← (HL)	X	1	X	X	X	X	1	X	11	101	101	ED	2	5 (if B≠0)	21	C to A <sub>0</sub> ~ A <sub>7</sub> B to A <sub>8</sub> ~ A <sub>15</sub>		
	B ← B - 1 HL ← HL + 1											10	110					011	B3
	Repeat until B = 0																2	4 (if B = 0)	16
OUTD	(C) ← (HL)	X	‡	X	X	X	X	1	X	11	101	101	ED	2	4	16	C to A <sub>0</sub> ~ A <sub>7</sub> B to A <sub>8</sub> ~ A <sub>15</sub>		
	B ← B - 1 HL ← HL - 1											10	101					011	AB
OTDR	(C) ← (HL)	X	1	X	X	X	X	1	X	11	101	101	ED	2	5 (if B≠0)	21	C to A <sub>0</sub> ~ A <sub>7</sub> B to A <sub>8</sub> ~ A <sub>15</sub>		
	B ← B - 1 HL ← HL - 1											10	111					011	
	Repeat until B = 0																2	4 (if B = 0)	16

NOTES: ① If the result of B - 1 is zero, the Z flag is set; otherwise it is reset.  
 ② Z flag is set upon instruction completion only.



## SUMMARY OF FLAG OPERATION

Instructions	D <sub>7</sub> S	Z	H	P/V	N	D <sub>0</sub> C	Comments
ADD A, s; ADC A, s	‡	‡	X	‡	X	V 0 ‡	8-bit add or add with carry.
SUB s; SBC A, s; CP s; NEG	‡	‡	X	‡	X	V 1 ‡	8-bit subtract, subtract with carry, compare and negate accumulator.
AND s	‡	‡	X	1	X	P 0 0	Logical operation.
OR s, XOR s	‡	‡	X	0	X	P 0 0	Logical operation.
INC s	‡	‡	X	‡	X	V 0 •	8-bit increment.
DEC s	‡	‡	X	‡	X	V 1 •	8-bit decrement.
ADD DD, ss	•	•	X	X	X	• 0 ‡	16-bit add.
ADC HL, ss	‡	‡	X	X	X	V 0 ‡	16-bit add with carry.
SBC HL, ss	‡	‡	X	X	X	V 1 ‡	16-bit subtract with carry.
RLA; RLCA; RRA; RRCA	•	•	X	0	X	• 0 ‡	Rotate accumulator.
RL m; RLC m; RR m; RRC m; SLA m; SRA m; SRL m	‡	‡	X	0	X	P 0 ‡	Rotate and shift locations.
RLD; RRD	‡	‡	X	0	X	P 0 •	Rotate digit left and right.
DAA	‡	‡	X	‡	X	P • ‡	Decimal adjust accumulator.
CPL	•	•	X	1	X	• 1 •	Complement accumulator.
SCF	•	•	X	0	X	• 0 1	Set carry.
CCF	•	•	X	X	X	• 0 ‡	Complement carry.
IN r (C)	‡	‡	X	0	X	P 0 •	Input register indirect.
INI; IND; OUTI; OUTD	X	‡	X	X	X	X 1 •	Block input and output. Z = 1 if B ≠ 0, otherwise Z = 0.
INIR; INDR; OTIR; OTDR	X	1	X	X	X	X 1 •	Block input and output. Z = 1 if B ≠ 0, otherwise Z = 0.
LDI; LDD	X	X	X	0	X	‡ 0 •	Block transfer instructions. P/V = 1 if BC ≠ 0, otherwise P/V = 0.
LDIR; LDDR	X	X	X	0	X	0 0 •	Block transfer instructions. P/V = 1 if BC ≠ 0, otherwise P/V = 0.
CPI; CPIR; CPD; CPDR	X	‡	X	X	X	‡ 1 •	Block search instructions. Z = 1 if A = (HL), otherwise Z = 0. P/V = 1 if BC ≠ 0, otherwise P/V = 0.
LDA; I, LD A, R	‡	‡	X	0	X	IFF 0 •	IFF, the content of the interrupt enable flip-flop, (IFF <sub>2</sub> ), is copied into the P/V flag.
BIT b, s	X	‡	X	1	X	X 0 •	The state of bit b of location s is copied into the Z flag.

## SYMBOLIC NOTATION

Symbol	Operation	Symbol	Operation
S	Sign flag. S = 1 if the MSB of the result is 1.	‡	The flag is affected according to the result of the operation.
Z	Zero flag. Z = 1 if the result of the operation is 0.	•	The flag is unchanged by the operation.
P/V	Parity or overflow flag. Parity (P) and overflow (V) share the same flag. Logical operations affect this flag with the parity of the result while arithmetic operations affect this flag with the overflow of the result. If P/V holds parity: P/V = 1 if the result of the operation is even; P/V = 0 if result is odd. If P/V holds overflow, P/V = 1 if the result of the operation produced an overflow. If P/V does not hold overflow, P/V = 0.	0	The flag is reset by the operation.
H*	Half-carry flag. H = 1 if the add or subtract operation produced a carry into, or borrow from, bit 4 of the accumulator.	1	The flag is set by the operation.
N*	Add/Subtract flag. N = 1 if the previous operation was a subtract.	X	The flag is indeterminate.
C	Carry/Link flag. C = 1 if the operation produced a carry from the MSB of the operand or result.	V	P/V flag affected according to the overflow result of the operation.
		P	P/V flag affected according to the parity result of the operation.
		r	Any one of the CPU registers A, B, C, D, E, H, L.
		s	Any 8-bit location for all the addressing modes allowed for the particular instruction.
		ss	Any 16-bit location for all the addressing modes allowed for that instruction.
		ii	Any one of the two index registers IX or IY.
		R	Refresh counter.
		n	8-bit value in range <0, 255>.
		nn	16-bit value in range <0, 65535>.

\* H and N flags are used in conjunction with the decimal adjust instruction (DAA) to properly correct the result into packed BCD format following addition or subtraction using operands with packed BCD format.

## CPU REGISTERS

Figure 4 shows three groups of registers within the CPU. The first group consists of duplicate sets of 8-bit registers: a principal set and an alternate set [designated by ' (prime), e.g., A']. Both sets consist of the Accumulator register, the Flag register, and six general-purpose registers. Transfer of data between these duplicate sets of registers is accomplished by use of "Exchange" instructions. The result is faster response to interrupts and easy, efficient implementation of such versatile programming techniques

as background-foreground data processing. The second set of registers consists of six registers with assigned functions. These are the I (Interrupt register), the R (Refresh register), the IX and IY (Index registers), the SP (Stack Pointer), and the PC (Program Counter). The third group consists of two interrupt status flip-flops, plus an additional pair of flip-flops which assists in identifying the interrupt mode at any particular time. Table 1 provides further information on these registers.



Figure 4. CPU Registers

## INTERRUPTS: GENERAL OPERATION

The CPU accepts two interrupt input signals:  $\overline{\text{NMI}}$  and  $\overline{\text{INT}}$ . The  $\overline{\text{NMI}}$  is a non-maskable interrupt and has the highest priority.  $\overline{\text{INT}}$  is a lower priority interrupt and it requires that interrupts be enabled in software in order to operate.  $\overline{\text{INT}}$  can be connected to multiple peripheral devices in a wired-OR configuration.

The Z80 has a single response mode for interrupt service on the non-maskable interrupt. The maskable interrupt,  $\overline{\text{INT}}$ , has three programmable response modes available. These are:

- Mode 0 — similar to the 8080 microprocessor.
- Mode 1 — Peripheral Interrupt service, for use with non-8080/Z80 systems.

- Mode 2 - a vectored interrupt scheme, usually daisy-chained, for use with the Z80 Family and compatible peripheral devices.

The CPU services interrupts by sampling the  $\overline{\text{NMI}}$  and  $\overline{\text{INT}}$  signals at the rising edge of the last clock of an instruction. Further interrupt service processing depends upon the type of interrupt that was detected. Details on interrupt responses are shown in the CPU Timing Section.

**Non-Maskable Interrupt ( $\overline{\text{NMI}}$ ).** The nonmaskable interrupt cannot be disabled by program control and therefore will be accepted at all times by the CPU.  $\overline{\text{NMI}}$  is usually reserved for servicing only the highest priority type interrupts, such as that for orderly shutdown after power

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## PIN DESCRIPTIONS

**A<sub>0</sub>-A<sub>15</sub>.** *Address Bus* (output, active High, 3-state). A<sub>0</sub>-A<sub>15</sub> form a 16-bit address bus. The Address Bus provides the address for memory data bus exchanges (up to 64K bytes) and for I/O device exchanges.

**BUSACK.** *Bus Acknowledge* (output, active Low). Bus Acknowledge indicates to the requesting device that the CPU address bus, data bus, and control signals  $\overline{MREQ}$ ,  $\overline{IORQ}$ ,  $\overline{RD}$ , and  $\overline{WR}$  have entered their high-impedance states. The external circuitry can now control these lines.

**BUSREQ.** *Bus Request* (input, active Low). Bus Request has a higher priority than NMI and is always recognized at the end of the current machine cycle.  $\overline{BUSREQ}$  forces the CPU address bus, data bus, and control signals  $\overline{MREQ}$ ,  $\overline{IORQ}$ ,  $\overline{RD}$ , and  $\overline{WR}$  to go to a high-impedance state so that other devices can control these lines.  $\overline{BUSREQ}$  is normally wired-OR and requires an external pullup for these applications. Extended  $\overline{BUSREQ}$  periods due to extensive DMA operations can prevent the CPU from properly refreshing dynamic RAMs.

**D<sub>0</sub>-D<sub>7</sub>.** *Data Bus* (input/output, active High, 3-state). D<sub>0</sub>-D<sub>7</sub> constitute an 8-bit bidirectional data bus, used for data exchanges with memory and I/O.

**HALT.** *Halt State* (output, active Low).  $\overline{HALT}$  indicates that the CPU has executed a Halt instruction and is awaiting either a nonmaskable or a maskable interrupt (with the mask enabled) before operation can resume. While halted, the CPU executes NOPs to maintain memory refresh.

**INT.** *Interrupt Request* (input, active Low). Interrupt Request is generated by I/O devices. The CPU honors a request at the end of the current instruction if the internal software-controlled interrupt enable flip-flop (IFF) is enabled.  $\overline{INT}$  is normally wired-OR and requires an external pullup for these applications.

**IORQ.** *Input/Output Request* (output, active Low, 3-state).  $\overline{IORQ}$  indicates that the lower half of the address bus holds a valid I/O address for an I/O read or write operation.  $\overline{IORQ}$  is also generated concurrently with  $\overline{M1}$  during an interrupt acknowledge cycle to indicate that an interrupt response vector can be placed on the data bus.

**M1.** *Machine Cycle One* (output, active Low).  $\overline{M1}$ , together with  $\overline{MREQ}$ , indicates that the current machine cycle is the opcode fetch cycle of an instruction execution.  $\overline{M1}$ , together with  $\overline{IORQ}$ , indicates an interrupt acknowledge cycle.

**MREQ.** *Memory Request* (output, active Low, 3-state).  $\overline{MREQ}$  indicates that the address bus holds a valid address for a memory read or memory write operation.

**NMI.** *Non-Maskable Interrupt* (input, negative edge-triggered).  $\overline{NMI}$  has a higher priority than  $\overline{INT}$ .  $\overline{NMI}$  is always recognized at the end of the current instruction, independent of the status of the interrupt enable flip-flop, and automatically forces the CPU to restart at location 0066H.

**RD.** *Read* (output, active Low, 3-state).  $\overline{RD}$  indicates that the CPU wants to read data from memory or an I/O device. The addressed I/O device or memory should use this signal to gate data onto the CPU data bus.

**RESET.** *Reset* (input, active Low).  $\overline{RESET}$  initializes the CPU as follows: it resets the interrupt enable flip-flop, clears the PC and Registers I and R, and sets the interrupt status to Mode 0. During reset time, the address and data bus go to a high-impedance state, and all control output signals go to the inactive state. Note that  $\overline{RESET}$  must be active for a minimum of three full clock cycles before the reset operation is complete.

**RFSH.** *Refresh* (output, active Low).  $\overline{RFSH}$ , together with  $\overline{MREQ}$ , indicates that the lower seven bits of the system's address bus can be used as a refresh address to the system's dynamic memories.

**WAIT.** *Wait* (input, active Low).  $\overline{WAIT}$  indicates to the CPU that the addressed memory or I/O devices are not ready for a data transfer. The CPU continues to enter a Wait state as long as this signal is active. Extended  $\overline{WAIT}$  periods can prevent the CPU from properly refreshing dynamic memory.

**WR.** *Write* (output, active Low, 3-state).  $\overline{WR}$  indicates that the CPU data bus holds valid data to be stored at the addressed memory or I/O location.

## CPU TIMING

The Z80 CPU executes instructions by proceeding through a specific sequence of operations:

- Memory read or write
- I/O device read or write
- Interrupt acknowledge

The basic clock period is referred to as a T time or cycle, and three or more T cycles make up a machine cycle (M1, M2 or M3 for instance). Machine cycles can be extended either by the CPU automatically inserting one or more Wait states or by the insertion of one or more Wait states by the user.

**Instruction Opcode Fetch.** The CPU places the contents of the Program Counter (PC) on the address bus at the start of the cycle (Figure 5). Approximately one-half clock cycle later,  $\overline{MREQ}$  goes active. When active,  $\overline{RD}$  indicates that the memory data can be enabled onto the CPU data bus.

The CPU samples the  $\overline{WAIT}$  input with the falling edge of clock state  $T_2$ . During clock states  $T_3$  and  $T_4$  of an  $\overline{M1}$  cycle, dynamic RAM refresh can occur while the CPU starts decoding and executing the instruction. When the Refresh Control signal becomes active, refreshing of dynamic memory can take place.

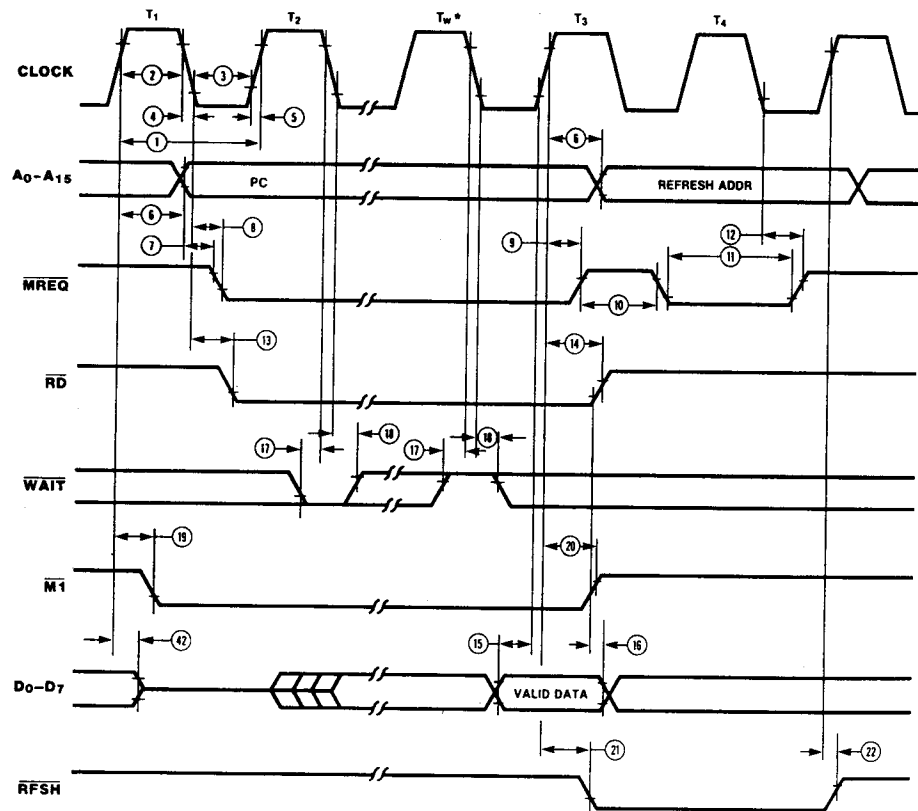


Figure 5. Instruction Opcode Fetch

**Memory Read or Write Cycles.** Figure 6 shows the timing of memory read or write cycles other than an opcode fetch ( $\overline{M1}$ ) cycle. The  $\overline{MREQ}$  and  $\overline{RD}$  signals function exactly as in the fetch cycle. In a memory write cycle,  $\overline{MREQ}$  also

becomes active when the address bus is stable. The  $\overline{WR}$  line is active when the data bus is stable, so that it can be used directly as an R/W pulse to most semiconductor memories.



Figure 6. Memory Read or Write Cycles

**Input or Output Cycles.** Figure 7 shows the timing for an I/O read or I/O write operation. During I/O operations, the CPU automatically inserts a single Wait state ( $T_{WA}$ ). This

extra Wait state allows sufficient time for an I/O port to decode the address from the port address lines.



$T_{WA}$  = One wait cycle automatically inserted by CPU.

**Figure 7. Input or Output Cycles**

**Interrupt Request/Acknowledge Cycle.** The CPU samples the interrupt signal with the rising edge of the last clock cycle at the end of any instruction (Figure 8). When an interrupt is accepted, a special M1 cycle is generated.

During this  $\overline{M1}$  cycle,  $\overline{IORQ}$  becomes active (instead of  $\overline{MREQ}$ ) to indicate that the interrupting device can place an 8-bit vector on the data bus. The CPU automatically adds two Wait states to this cycle.



**Non-Maskable Interrupt Request Cycle.**  $\overline{\text{NMI}}$  is sampled at the same time as the maskable interrupt input  $\overline{\text{INT}}$  but has higher priority and cannot be disabled under software control. The subsequent timing is similar to that of a normal

memory read operation except that data put on the bus by the memory is ignored. The CPU instead executes a restart (RST) operation and jumps to the  $\overline{\text{NMI}}$  service routine located at address 0066H (Figure 9).



\*Although  $\overline{\text{NMI}}$  is an asynchronous input, to guarantee its being recognized on the following machine cycle,  $\overline{\text{NMI}}$ 's falling edge must occur no later than the rising edge of the clock cycle preceding the last state of any instruction cycle (T<sub>L1</sub>).

Figure 9. Non-Maskable Interrupt Request Operation



**Bus Request/Acknowledge Cycle.** The CPU samples  $\overline{\text{BUSREQ}}$  with the rising edge of the last clock period of any machine cycle (Figure 10). If  $\overline{\text{BUSREQ}}$  is active, the CPU sets its address, data, and  $\overline{\text{MREQ}}$ ,  $\overline{\text{IORQ}}$ ,  $\overline{\text{RD}}$ , and  $\overline{\text{WR}}$  lines

to a high-impedance state with the rising edge of the next clock pulse. At that time, any external device can take control of these lines, usually to transfer data between memory and I/O devices.



NOTES: 1)  $T_{LM}$  = Last state of any M cycle.  
2)  $T_x$  = An arbitrary clock cycle used by requesting device.

Figure 10. BUS Request/Acknowledge Cycle

**Halt Acknowledge Cycle.** When the CPU receives a  $\overline{\text{HALT}}$  instruction, it executes NOP states until either an  $\overline{\text{INT}}$  or  $\overline{\text{NMI}}$  input is received. When in the Halt state, the  $\overline{\text{HALT}}$  output is active and remains so until an interrupt is received (Figure 11).  $\overline{\text{INT}}$  will also force a Halt exit.



\*Although  $\overline{\text{NMI}}$  is an asynchronous input, to guarantee its being recognized on the following machine cycle,  $\overline{\text{NMI}}$ 's falling edge must occur no later than the rising edge of the clock cycle preceding the last state of any instruction cycle ( $T_{L1}$ ).

Figure 11. Halt Acknowledge

**Reset Cycle.**  $\overline{\text{RESET}}$  must be active for at least three clock cycles for the CPU to properly accept it. As long as  $\overline{\text{RESET}}$  remains active, the address and data buses float, and the control outputs are inactive. Once  $\overline{\text{RESET}}$  goes inactive, two internal T cycles are consumed before the CPU resumes normal processing operation.  $\overline{\text{RESET}}$  clears the PC register, so the first opcode fetch will be to location 0000H (Figure 12).



Figure 12. Reset Cycle

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**Power-Down mode of operation (Only applies to CMOS Z80 CPU).**

CMOS Z80 CPU supports Power-Down mode of operation.

This mode is also referred to as the "standby mode", and supply current for the CPU goes down as low as 10 uA (Where specified as  $I_{cc2}$ ).

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**Power-Down Acknowledge Cycle.** When the clock input to the CPU is stopped at either a High or Low level, the CPU stops its operation and maintains all registers and control signals. However,  $I_{cc2}$  (standby supply current) is guaranteed only when the system clock is stopped at a Low

level during  $T_4$  of the machine cycle following the execution of the HALT instruction. The timing diagram for the power-down function, when implemented with the HALT instruction, is shown in Figure 13.



Figure 13. Power-Down Acknowledge

**Power-Down Release Cycle.** The system clock must be supplied to the CPU to release the power-down state. When the system clock is supplied to the CLK input, the CPU restarts operations from the point at which the power-down state was implemented. The timing diagrams for the release from power-down mode are shown in Figure 14.

**NOTES:**

- 1) When the external oscillator has been stopped to enter the power-down state, some warm-up time may be required to obtain a stable clock for the release.
- 2) When the HALT instruction is executed to enter the power-down state, the CPU will also enter the Halt state. An interrupt signal (either  $\overline{\text{NMI}}$  or  $\overline{\text{INT}}$ ) or a RESET signal must be applied to the CPU after the system clock is supplied in order to release the power-down state.



Figure 14a.



Figure 14b.



Figure 14c.

Figure 13. Power-Down Release

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## ABSOLUTE MAXIMUM RATINGS

Voltage on  $V_{CC}$  with respect to  $V_{SS}$  . . . . . -0.3V to +7V  
Voltages on all inputs with respect  
to  $V_{SS}$  . . . . . -0.3V to  $V_{CC} + 0.3V$   
Operating Ambient  
Temperature . . . . . See Ordering Information  
Storage Temperature . . . . . -65°C to +150°C

Stresses greater than those listed under Absolute Maximum Ratings may cause permanent damage to the device. This is a stress rating only; operation of the device at any condition above those indicated in the operational sections of these specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

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## STANDARD TEST CONDITIONS

The DC Characteristics and capacitance sections below apply for the following standard test conditions, unless otherwise noted. All voltages are referenced to GND (0V). Positive current flows into the referenced pin.

The Ordering Information section lists temperature ranges and product numbers. Package drawings are in the Package Information section. Refer to the Literature List for additional documentation.

Available operating temperature ranges are:

■ **S = 0°C to +70°C**

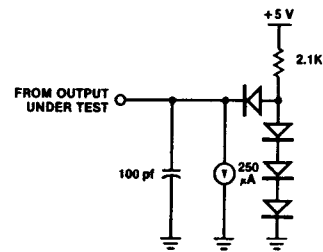
**Voltage Supply Range:**

NMOS:  $+4.75V \leq V_{CC} \leq +5.25V$

CMOS:  $+4.50V \leq V_{CC} \leq +5.50V$

■ **E = -40°C to 100°C,  $+4.50V \leq V_{CC} \leq +5.50V$**

All ac parameters assume a load capacitance of 100 pf. Add 10 ns delay for each 50 pf increase in load up to a maximum of 200 pf for the data bus and 100 pf for address and control lines. AC timing measurements are referenced to 1.5 volts (except for clock, which is referenced to the 10% and 90% points).



## DC CHARACTERISTICS (Z84C00/CMOS Z80 CPU)

Symbol	Parameter	Min	Max	Unit	Condition
V <sub>ILC</sub>	Clock Input Low Voltage	-0.3	0.45	V	
V <sub>IHC</sub>	Clock Input High Voltage	V <sub>CC</sub> - .6	V <sub>CC</sub> + .3	V	
V <sub>IL</sub>	Input Low Voltage	-0.3	0.8	V	
V <sub>IH</sub>	Input High Voltage	2.2	V <sub>CC</sub>	V	
V <sub>OL</sub>	Output Low Voltage		0.4	V	I <sub>OL</sub> = 2.0 mA
V <sub>OH1</sub>	Output High Voltage	2.4		V	I <sub>OH</sub> = -1.6 mA
V <sub>OH2</sub>	Output High Voltage	V <sub>CC</sub> - 0.8		V	I <sub>OH</sub> = -250 μA
I <sub>CC1</sub>	Power Supply Current	4 MHz	20	mA	V <sub>CC</sub> = 5V
		6 MHz	30	mA	V <sub>IH</sub> = V <sub>CC</sub> - 0.2V
		8 MHz	40	mA	V <sub>IL</sub> = 0.2V
		10 MHz	50	mA	
I <sub>CC2</sub>	Standby Supply Current	20 MHz	100	mA	V <sub>CC</sub> = 5V
			10	μA	V <sub>CC</sub> = 5V
					CLK = (0)
					V <sub>IH</sub> = V <sub>CC</sub> - 0.2V
					V <sub>IL</sub> = 0.2V
I <sub>LI</sub>	Input Leakage Current	-10	10	μA	V <sub>IN</sub> = 0.4 to V <sub>CC</sub>
I <sub>LO</sub>	3-State Output Leakage Current in Float	-10	10 <sup>2</sup>	μA	V <sub>OUT</sub> = 0.4 to V <sub>CC</sub>

1. Measurements made with outputs floating.
2. A<sub>15</sub>-A<sub>0</sub>, D<sub>7</sub>-D<sub>0</sub>, MREQ, IORQ, RD, and WR.
3. I<sub>CC2</sub> standby supply current is guaranteed only when the supplied clock is stopped at a low level during T<sub>4</sub> of the machine cycle immediately following the execution of a HALT instruction.

## CAPACITANCE

Symbol	Parameter	Min	Max	Unit
C <sub>CLOCK</sub>	Clock Capacitance		10	pf
C <sub>IN</sub>	Input Capacitance		5	pf
C <sub>OUT</sub>	Output Capacitance		15	pf

T<sub>A</sub> = 25°C, f = 1 MHz.  
Unmeasured pins returned to ground.

## AC CHARACTERISTICS† (Z84C00/CMOS Z80 CPU)

V<sub>cc</sub>=5.0V ± 10%, unless otherwise specified

No	Symbol	Parameter	Z84C0004**		Z84C0006		Z84C0008		Z84C0010		Z84C0020[1]		Unit	Note
			Min	Max	Min	Max	Min	Max	Min	Max	Min	Max		
1	TcC	Clock Cycle time	250*	DC	162*	DC	125*	DC	100*	DC	50*	DC	nS	
2	TwCh	Clock Pulse width (high)	110	DC	65	DC	55	DC	40	DC	20	DC	nS	
3	TwCl	Clock Pulse width (low)	110	DC	65	DC	55	DC	40	DC	20	DC	nS	
4	TfC	Clock Fall time		30		20		10		10		10	nS	
5	TrC	Clock Rise time		30		20		10		10		10	nS	
6	TdCr(A)	Address valid from Clock Rise		110		90		80		65		57	nS	[2]
7	TdA(MREQf)	Address valid to /MREQ Fall	65*		35*		20*		5*		-15*		nS	
8	TdCf(MREQf)	Clock Fall to /MREQ Fall delay		85		70		60		55		40	nS	
9	TdCr(MREQr)	Clock Rise to /MREQ Rise delay		85		70		60		55		40	nS	
10	TwMREQh	/MREQ pulse width (High)	110*		65*		45**		30*		10*		nS	[3]
11	TwMREQl	/MREQ pulse width (low)	220*		132*		100*		75*		25*		nS	[3]
12	TdCf(MERQr)	Clock Fall to /MREQ Rise delay		85		70		60		55		40	nS	
13	TdCf(RDf)	Clock Fall to /RD Fall delay		95		80		70		65		40	nS	
14	TdCr(RDr)	Clock Rise to /RD Rise delay		85		70		60		55		40	nS	
15	TsD(Cr)	Data setup time to Clock Rise	35		30		30		25		12		nS	
16	ThD(RDr)	Data hold time after /RD Rise	0		0		0		0		0		nS	
17	TsWAIT(Cf)	/WAIT setup time to Clock Fall	70		60		50		20		7.5		nS	
18	ThWAIT(Cf)	/WAIT hold time after Clock Fall	10		10		10		10		10		nS	
19	TdCr(M1f)	Clock Rise to /M1 Fall delay		100		80		70		65		45	nS	
20	TdCr(M1r)	Clock Rise to /M1 Rise delay		100		80		70		65		45	nS	
21	TdCr(RFSHf)	Clock Rise to /RFSH Fall delay		130		110		95		80		60	nS	
22	TdCr(RFSHr)	Clock Rise to /RFSH Rise delay		120		100		85		80		60	nS	
23	TdCf(RDr)	Clock Fall to /RD Rise delay		85		70		60		55		40	nS	
24	TdCr(RDf)	Clock Rise to /RD Fall delay		85		70		60		55		40	nS	
25	TsD(Cf)	Data setup to Clock Fall during M2, M3, M4 or M5 cycles		50		40		30		25		12	nS	
26	TdA(IORQf)	Address stable prior to /IORQ Fall	180*		107*		75*		50*		0*		nS	
27	TdCr(IORQf)	Clock Rise to /IORQ Fall delay		75		65		55		50		40	nS	
28	TdCf(IORQr)	Clock Fall to /IORQ Rise delay		85		70		60		55		40	nS	
29	TdD(WRf)Mw	Data stable prior to /WR Fall	80*		22*		5*		40*		-10*		nS	
30	TdCf(WRf)	Clock Fall to /WR Fall delay		80		70		60		55		40	nS	
31	TwWR	/WR pulse width	220*		132*		100*		75*		25*		nS	
32	TdCf(WRr)	Clock Fall to /WR Rise delay		80		70		60		55		40	nS	
33	TdD(WRf)IO	Data stable prior to /WR Fall	-10*		-55*		-55*		-10*		-30*		nS	
34	TdCr(WRf)	Clock Rise to /WR Fall delay		65		60		60		50		40	nS	
35	TdWRr(D)	Data stable from /WR Rise	60*		30*		15*		10*		0*		nS	
36	TdCf(HALT)	Clock Fall to /HALT 'L' or 'H'		300		260		225		90		70	nS	
37	TwNMI	/NMI pulse width	80		60		60		60		60		nS	
38	TsBUSREQ (Cr)	/BUSREQ setup time to Clock Rise	50		50		40		30		15		nS	

\*For clock periods other than the minimums shown, calculate parameters using the table on the following page.  
Calculated values above assumed TrC = TtC = 20 ns.

†Units in nanoseconds (ns).

†† For loading ≥ 50 pf. Decrease width by 10 ns for each additional 50 pf.

\*\*4 MHz CMOS Z80 is obsoleted and replaced by 6 MHz

### AC CHARACTERISTICS† (Z84C00/CMOS Z80 CPU; Continued)

V<sub>CC</sub>=5.0V ± 10%, unless otherwise specified

No	Symbol	Parameter	Z84C0004**		Z84C0006		Z84C0008		Z84C0010		Z84C0020[1]		Unit	Note
			Min	Max	Min	Max	Min	Max	Min	Max	Min	Max		
39	ThBUSREQ (Cr)	/BUSREQ hold time after Clock Rise	10		10		10		10		10		nS	
40	TdCr (BUSACKf)	Clock Rise to /BASACK Fall delay		100		90		80		75		40	nS	
41	TdCf (BUSACKr)	Clock Fall to /BASACK Rise delay		100		90		80		75		40	nS	
42	TdCr(Dz)	Clock Rise to Data float delay		90		80		70		65		40	nS	
43	TdCr(CTz)	Clock Rise to Control Outputs Float Delay (/MREQ, /IORQ, /RD and /WR)		80		70		60		65		40	nS	
44	TdCr(Az)	Clock Rise to Address float delay		90		80		70		75		40	nS	
45	TdCTr(A)	Address Hold time from /MREQ, /IORQ, /RD or /WR	80*		35*		20*		20*		0*		nS	
46	TsRESET(Cr)	/RESET to Clock Rise setup time	60		60		45		40		15		nS	
47	ThRESET(Cr)	/RESET to Clock Rise Hold time	10		10		10		10		10		nS	
48	TsINTf(Cr)	/INT Fall to Clock Rise Setup Time	80		70		55		50		15		nS	
49	ThINTR(Cr)	/INT Rise to Clock Rise Hold Time	10		10		10		10		10		nS	
50	TdM1f (IORQf)	/M1 Fall to /IORQ Fall delay	565*		359*		270*		220*		100*		nS	
51	TdCf(IORQf)	/Clock Fall to /IORQ Fall delay		85		70		60		55		45	nS	
52	TdCf(IORQr)	Clock Rise to /IORQ Rise delay		85		70		60		55		45	nS	
53	TdCf(D)	Clock Fall to Data Valid delay		150		130		115		110		75	nS	

#### Notes:

\* For Clock periods other than the minimum shown, calculate parameters using the following table.

Calculated values above assumed TrC = TtC = maximum.

\*\* 4 MHz CMOS Z80 is obsolete and replaced by 6 MHz

[1] Z84C0020 parameters are guaranteed with 50pF load Capacitance.

[2] If Capacitive Load is other than 50pF, please use Figure 1. to calculate the value.

[3] Increasing delay by 10nS for each 50pF increase in loading, 200pF max for data lines, and 100pF for control lines.

### FOOTNOTES TO AC CHARACTERISTICS

No	Symbol	Parameter	Z84C0004**	Z84C0006	Z84C0008	Z84C0010	Z84C0020
1	TcC	TwCh + TwCl + TrC + TtC					
7	TdA(MREQf)	TwCh + TtC	-65	-50	-45	-45	-45
10	TwMREQh	TwCh + TtC	-20	-20	-20	-20	-20
11	TwMREQf	TcC	-30	-30	-25	-25	-25
26	TdA(IORQf)	TcC	-70	-55	-50	-50	-50
29	TdD(WRf)	TcC	-170	-140	-120	-60	-60
31	TwWR	TcC	-30	-30	-25	-25	-25
33	TdD(WRf)	TwCl + TrC	-140	-140	-120	-60	-60
35	TdWRr(D)	TwCl + TrC	-70	-55	-50	-40	-25
45	TdCTr(A)	TwCl + TrC	-50	-50	-45	-30	-30
50	TdM1f(IORQf)	2TcC + TwCh + TtC	-65	-50	-45	-30	-30

AC Test Conditions: V<sub>IH</sub> = 2.0 V  
V<sub>IL</sub> = 0.8 V

V<sub>OH</sub> = 1.5 V  
V<sub>OL</sub> = 1.5 V

V<sub>IHC</sub> = V<sub>CC</sub> - 0.6 V  
V<sub>ILC</sub> = 0.45 V

FLOAT = ±0.5 V





Figure 1. Address Delay Characteristics (Parameter 6)

### DC CHARACTERISTICS (Z8400/NMOS Z80 CPU)

All parameters are tested unless otherwise noted.

Symbol	Parameter	Min	Max	Unit	Test Condition
$V_{ILC}$	Clock Input Low Voltage	-0.3	0.45	V	
$V_{IHC}$	Clock Input High Voltage	$V_{CC} - .6$	$V_{CC} + .3$	V	
$V_{IL}$	Input Low Voltage	-0.3	0.8	V	
$V_{IH}$	Input High Voltage	$2.0^1$	$V_{CC}$	V	
$V_{OL}$	Output Low Voltage		0.4	V	$I_{OL} = 2.0 \text{ mA}$
$V_{OH}$	Output High Voltage	$2.4^1$		V	$I_{OH} = -250 \mu\text{A}$
$I_{CC}$	Power Supply Current		200	mA	Note 3
$I_{LI}$	Input Leakage Current		10	$\mu\text{A}$	$V_{IN} = 0 \text{ to } V_{CC}$
$I_{LO}$	3-State Output Leakage Current in Float	-10	$10^2$	$\mu\text{A}$	$V_{OUT} = 0.4 \text{ to } V_{CC}$

1. For military grade parts, refer to the Z80 Military Electrical Specification.

2.  $A_{15}$ - $A_0$ ,  $D_7$ - $D_0$ ,  $MREQ$ ,  $IORD$ ,  $RD$ , and  $WR$ .

3. Measurements made with outputs floating.

### CAPACITANCE

Guaranteed by design and characterization.

Symbol	Parameter	Min	Max	Unit
$C_{CLOCK}$	Clock Capacitance		35	pf
$C_{IN}$	Input Capacitance		5	pf
$C_{OUT}$	Output Capacitance		15	pf

NOTES:

$T_A = 25^\circ\text{C}$ ,  $f = 1 \text{ MHz}$ .

Unmeasured pins returned to ground.

## AC CHARACTERISTICS† (Z8400/NMOS Z80 CPU)

Number	Symbol	Parameter	Z0840004		Z0840006		Z0840008	
			Min	Max	Min	Max	Min	Max
1	TcC	Clock Cycle Time	250*		162*		125*	
2	TwCh	Clock Pulse Width (High)	110	2000	65	2000	55	2000
3	TwCl	Clock Pulse Width (Low)	110	2000	65	2000	55	2000
4	TfC	Clock Fall Time		30		20		10
5	TrC	Clock Rise Time		30		20		10
6	TdCr(A)	Clock ↑ to Address Valid Delay		110		90		80
7	TdA(MREQf)	Address Valid to $\overline{\text{MREQ}}$ ↓ Delay	65*		35*		20*	
8	TdCf(MREQf)	Clock ↓ to $\overline{\text{MREQ}}$ ↓ Delay		85		70		60
9	TdCr(MREQr)	Clock ↑ to $\overline{\text{MREQ}}$ ↑ Delay		85		70		60
10	TwMREQh	$\overline{\text{MREQ}}$ Pulse Width (High)	110*††		65*††		45*††	
11	TwMREQl	$\overline{\text{MREQ}}$ Pulse Width (Low)	220*††		135*††		100*††	
12	TdCf(MREQr)	Clock ↓ to $\overline{\text{MREQ}}$ ↑ Delay		85		70		60
13	TdCf(RDf)	Clock ↓ to $\overline{\text{RD}}$ ↓ Delay		95		80		70
14	TdCr(RDr)	Clock ↑ to $\overline{\text{RD}}$ ↑ Delay		85		70		60
15	TsD(Cr)	Data Setup Time to Clock ↑	35		30		30	
16	ThD(RDr)	Data Hold Time to $\overline{\text{RD}}$ ↑		0		0		0
17	TsWAIT(Cf)	$\overline{\text{WAIT}}$ Setup Time to Clock ↓	70		60		50	
18	ThWAIT(Cf)	$\overline{\text{WAIT}}$ Hold Time after Clock ↓		0		0		0
19	TdCr(M1f)	Clock ↑ to $\overline{\text{M1}}$ ↓ Delay		100		80		70
20	TdCr(M1r)	Clock ↑ to $\overline{\text{M1}}$ ↑ Delay		100		80		70
21	TdCr(RFSHf)	Clock ↑ to $\overline{\text{RFSH}}$ ↓ Delay		130		110		95
22	TdCr(RFSHr)	Clock ↑ to $\overline{\text{RFSH}}$ ↑ Delay		120		100		85
23	TdCf(RDr)	Clock ↓ to $\overline{\text{RD}}$ ↑ Delay		85		70		60
24	TdCr(RDf)	Clock ↑ to $\overline{\text{RD}}$ ↓ Delay		85		70		60
25	TsD(Cf)	Data Setup to Clock ↓ during M <sub>2</sub> , M <sub>3</sub> , M <sub>4</sub> , or M <sub>5</sub> Cycles	50		40		30	
26	TdA(IORQf)	Address Stable prior to $\overline{\text{IORQ}}$ ↓	180*		110*		75*	
27	TdCr(IORQf)	Clock ↑ to $\overline{\text{IORQ}}$ ↓ Delay		75		65		55
28	TdCf(IORQr)	Clock ↓ to $\overline{\text{IORQ}}$ ↑ Delay		85		70		60
29	TdD(WRf)	Data Stable prior to $\overline{\text{WR}}$ ↓	80*		25*		5*	
30	TdCf(WRf)	Clock ↓ to $\overline{\text{WR}}$ ↓ Delay		80		70		60
31	TwWR	$\overline{\text{WR}}$ Pulse Width	220*		135*		100*	
32	TdCf(WRr)	Clock ↓ to $\overline{\text{WR}}$ ↑ Delay		80		70		60
33	TdD(WRf)	Data Stable prior to $\overline{\text{WR}}$ ↓	-10*		-55*		55*	
34	TdCr(WRf)	Clock ↑ to $\overline{\text{WR}}$ ↓ Delay		65		60		55
35	TdWRr(D)	Data Stable from $\overline{\text{WR}}$ ↑	60*		30*		15*	
36	TdCf(HALT)	Clock ↓ to $\overline{\text{HALT}}$ ↑ or ↓		300		260		225
37	TwNMI	$\overline{\text{NMI}}$ Pulse Width	80		70		60*	
38	TsBUSREQ(Cr)	$\overline{\text{BUSREQ}}$ Setup Time to Clock ↑	50		50		40	

\*For clock periods other than the minimums shown, calculate parameters using the table on the following page. Calculated values above assumed TrC = TfC = 20 ns.

†Units in nanoseconds (ns).

†† For loading ≥ 50 pf., Decrease width by 10 ns for each additional 50 pf.

## AC CHARACTERISTICS† (Z8400/NMOS Z80 CPU; Continued)

Number	Symbol	Parameter	Z0840004		Z0840006		Z0840008	
			Min	Max	Min	Max	Min	Max
39	ThBUSREQ(Cr)	BUSREQ Hold Time after Clock ↑	0		0		0	
40	TdCr(BUSACKf)	Clock ↑ to BUSACK ↓ Delay		100		90		80
41	TdCl(BUSACKr)	Clock ↓ to BUSACK ↑ Delay		100		90		80
42	TdCr(Dz)	Clock ↑ to Data Float Delay		90		80		70
43	TdCr(CTz)	Clock ↑ to Control Outputs Float Delay (MREQ, IORQ, RD, and WR)		80		70		60
44	TdCr(Az)	Clock ↑ to Address Float Delay		90		80		70
45	TdCTr(A)	MREQ ↑, IORQ ↑, RD ↑, and WR ↑ to Address Hold Time	80*		35*		20*	
46	TsRESET(Cr)	RESET to Clock ↑ Setup Time	60		60		45	
47	ThRESET(Cr)	RESET to Clock ↑ Hold Time		0		0		0
48	TsINTf(Cr)	INT to Clock ↑ Setup Time	80		70		55	
49	ThINTr(Cr)	INT to Clock ↑ Hold Time		0		0		0
50	TdM1f(IORQf)	M1 ↓ to IORQ ↓ Delay	565*		365*		270*	
51	TdCl(IORQf)	Clock ↓ to IORQ ↓ Delay		85		70		60
52	TdCl(IORQr)	Clock ↑ IORQ ↑ Delay		85		70		60
53	TdCl(D)	Clock ↓ to Data Valid Delay		150		130		115

\*For clock periods other than the minimums shown, calculate parameters using the following table. Calculated values above assumed TrC = TIC = 20 ns.

†Units in nanoseconds (ns).

## FOOTNOTES TO AC CHARACTERISTICS

Number	Symbol	General Parameter	Z0840004	Z0840006	Z0840008
1	TcC	TwCh + TwCl + TrC + TfC			
7	TdA(MREQf)	TwCh + TfC	- 65	- 50	- 45
10	TwMREQh	TwCh + TfC	- 20	- 20	- 20
11	TwMREQl	TcC	- 30	- 30	- 25
26	TdA(IORQf)	TcC	- 70	- 55	- 50
29	TdD(WRf)	TcC	- 170	- 140	- 120
31	TwWR	TcC	- 30	- 30	- 25
33	TdD(WRf)	TwCl + TrC	- 140	- 140	- 120
35	TdWRr(D)	TwCl + TrC	- 70	- 55	- 50
45	TdCTr(A)	TwCl + TrC	- 50	- 50	- 45
50	TdM1f(IORQf)	2TcC + TwCh + TfC	- 65	- 50	- 45

AC Test Conditions:

$V_{IH} = 2.0\text{ V}$        $V_{OH} = 1.5\text{ V}$   
 $V_{IL} = 0.8\text{ V}$        $V_{OL} = 1.5\text{ V}$   
 $V_{IHC} = V_{CC} - 0.6\text{ V}$        $FLOAT = \pm 0.5\text{ V}$   
 $V_{ILC} = 0.45\text{ V}$

# Customer Support

For answers to technical questions about the product, documentation, or any other issues with Zilog's offerings, please visit Zilog's Knowledge Base at <http://www.zilog.com/kb>.

For any comments, detail technical questions, or reporting problems, please visit Zilog's Technical Support at <http://support.zilog.com>.

Компания «Океан Электроники» предлагает заключение долгосрочных отношений при поставках импортных электронных компонентов на взаимовыгодных условиях!

Наши преимущества:

- Поставка оригинальных импортных электронных компонентов напрямую с производств Америки, Европы и Азии, а так же с крупнейших складов мира;
- Широкая линейка поставок активных и пассивных импортных электронных компонентов (более 30 млн. наименований);
- Поставка сложных, дефицитных, либо снятых с производства позиций;
- Оперативные сроки поставки под заказ (от 5 рабочих дней);
- Экспресс доставка в любую точку России;
- Помощь Конструкторского Отдела и консультации квалифицированных инженеров;
- Техническая поддержка проекта, помощь в подборе аналогов, поставка прототипов;
- Поставка электронных компонентов под контролем ВП;
- Система менеджмента качества сертифицирована по Международному стандарту ISO 9001;
- При необходимости вся продукция военного и аэрокосмического назначения проходит испытания и сертификацию в лаборатории (по согласованию с заказчиком);
- Поставка специализированных компонентов военного и аэрокосмического уровня качества (Xilinx, Altera, Analog Devices, Intersil, Interpoint, Microsemi, Actel, Aeroflex, Peregrine, VPT, Syfer, Eurofarad, Texas Instruments, MS Kennedy, Miteq, Cobham, E2V, MA-COM, Hittite, Mini-Circuits, General Dynamics и др.);

Компания «Океан Электроники» является официальным дистрибьютором и эксклюзивным представителем в России одного из крупнейших производителей разъемов военного и аэрокосмического назначения «JONHON», а так же официальным дистрибьютором и эксклюзивным представителем в России производителя высокотехнологичных и надежных решений для передачи СВЧ сигналов «FORSTAR».



## JONHON

«JONHON» (основан в 1970 г.)

Разъемы специального, военного и аэрокосмического назначения:

(Применяются в военной, авиационной, аэрокосмической, морской, железнодорожной, горно- и нефтедобывающей отраслях промышленности)

«FORSTAR» (основан в 1998 г.)

ВЧ соединители, коаксиальные кабели, кабельные сборки и микроволновые компоненты:

(Применяются в телекоммуникациях гражданского и специального назначения, в средствах связи, РЛС, а так же военной, авиационной и аэрокосмической отраслях промышленности).



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