

## Transportation Attitude Reference System (TARS Series)

Ruggedized Inertial Measurement Unit (IMU)

000828

Issue 2

Datasheet



### DESCRIPTION

The Transportation Attitude Reference System or TARS-IMU is a packaged sensor array designed to report vehicle angular rate, acceleration, and attitude data for demanding applications in industries such as heavy duty, off-highway transportation.

TARS-IMU enables autonomous vehicle characteristics and enhances efficiency and productivity by reporting key data required to automate and monitor movements of vehicle systems and components. The sensor fusion algorithm can be customized for specific vehicle applications through on-board firmware, allowing movement data to be filtered for extraneous environment and vehicle movements.

With two sensor models for different power levels, TARS-IMU accommodates both 5 V and 9 V to 36 V vehicle power systems. While communication is carried to the vehicle through industry standard CAN J1939 connectivity.

As a standard, TARS-IMU is calibrated on aerospace-grade rate tables at the factory to provide calibration consistency between units.

### DIFFERENTIATION

- **Flexible.** On-board firmware can tailor TARS-IMU to the specific vehicle and the specific application
- **Durable.** With top-of-the-line sealing (IP67, IP69K) TARS-IMU is ruggedized to withstand harsh or heavy-duty applications
- **Convenient.** TARS-IMU can be pre-configured at the Honeywell factory for immediate installation out of the box, or it can be delivered with customizable firmware that allows manufacturers to use a single part number across vehicles and applications

### FEATURES

- High performance IMU reports vehicle angular rate, acceleration and inclination (6 degrees of freedom)
- Ruggedized PBT thermoplastic housing design for the most demanding applications and environments (IP67 and IP69K certified)
- Advanced filtering of raw sensor data to minimize unwanted noise and vibrations, improves positioning accuracy
- Optional metal guard for added protection
- Supports 5 V and 9 V to 36 V vehicle power systems
- Operating temperature of -40°C to 85°C [-40°F to 185°F]
- Reduced power consumption
- Small form-factor

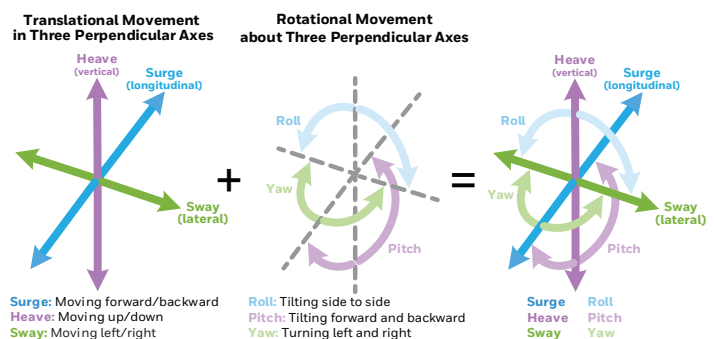
### POTENTIAL APPLICATIONS

- Equipment control
- Linkage tracking
- Work monitoring
- Operator assisted control
- Performance and output control
- Linear position
- Bucket control
- Vehicle stability control

### VALUE TO CUSTOMERS

- Designed to allow vehicle manufacturers and end users to increase efficiency with the automation of repetitive movements or complex tasks
- Enables precise movement, actuation and guidance over severe terrains and vehicle grades
- Enhances safety through enablement of monitoring and guidance capabilities that improve productivity of operators

### SIX DEGREES OF FREEDOM



### PORTFOLIO

TARS-IMU joins Honeywell's venerated sensor portfolio, and adds to the ever-increasing connected and intelligence driven capabilities that Honeywell offers. TARS-IMU is built to survive the demanding applications in industries like off-highway transportation and beyond.

# Transportation Attitude Reference System (TARS Series)

**Table 1. Sensor Specifications**

Characteristic	Min.	Typ.	Max.	Unit
<b>Gyroscope 3 axis performance</b>				
Angular rate range <sup>1</sup>	-245	–	+245	deg/s
Angular rate resolution	–	7.8125	–	mdps
In-run bias stability	–	1	–	mdps
Rate noise density	–	0.004	–	deg/s/sqrt Hz
Offset (0°C to 50°C)	-0.8	–	+0.8	deg/s
Offset (-40°C to 85°C)	-1.6	–	+1.6	deg/s
<b>Accelerometer 3 axis performance</b>				
Acceleration range <sup>1</sup>	-78.48	–	+78.48	m/s <sup>2</sup>
Acceleration resolution	–	0.01	–	m/s <sup>2</sup>
In-run bias stability	–	50	–	µg
Acceleration noise density	–	65	–	µg/sqrt Hz
Offset (0°C to 50°C)	–	±0.05	–	m/s <sup>2</sup>
Offset (-40°C to 85°C)	–	±0.15	–	m/s <sup>2</sup>
<b>Attitude (pitch and roll) performance</b>				
Range <sup>1</sup>	-85	–	+85	deg
Resolution	–	0.058	–	deg
Static error (0°C to 50°C)	–	±0.3	–	deg
Static error (-40°C to 85°C)	–	±0.9	–	deg
Translational acceleration error	–	±0.5	–	deg
Centripetal acceleration error	–	±0.5	–	deg

<sup>1</sup> Sensors are calibrated in the following ranges: ±60 deg/s for gyroscope angular rate, ±9.81 m/s<sup>2</sup> for acceleration, and ±30 deg for pitch and roll. Calibrated ranges can be extended to maximums shown with deviation to performance specifications.

- Pitch and roll outputs per PGN61481 (Axes marking on the housing is Z-down convention required for pitch and roll outputs per J1939.)
- Acceleration outputs per PGN61485 (Acceleration data is outputted per Z-up convention required by J1939.)
- Angular rate outputs per PGN61482 (Angular rate data is outputted per Z-down convention required by J1939.)

**Table 2. Electrical Specifications • TARS-LCASS Catalog Listing**

Characteristic	Min.	Nominal	Max.	Unit
Supply voltage	4.5	5	5.5	V
Supply current	–	–	100	mA
Start-up time	500	–	2000	ms
Short circuit protection	CAN output shorted to supply voltage or ground without damage			
Open circuit protection	Single-line interruption and multiple-line interruption			
Reset response	Automatic after voltage dropout			
<b>CAN output characteristics per SAE J1939</b>				
CAN Bus data rate	–	250	–	kBaud
Signal update rate	–	–	100	Hz

# Transportation Attitude Reference System (TARS Series)

**Table 3. Electrical Specifications • TARS-HCASS Catalog Listing**

Characteristic	Min.	Nominal	Max.	Unit
Supply voltage	9	14/28	36	V
Supply current	–	–	100	mA
Reverse voltage	–	–	-36	V
Overvoltage	–	–	36	V
Start-up time	500	–	2000	ms
Short circuit protection	CAN output shorted to supply voltage or ground without damage			
Open circuit protection	Single-line interruption and multiple-line interruption			
Reset response	Automatic after voltage dropout			
<b>CAN output characteristics per SAE J1939</b>				
CAN Bus data rate	–	250	–	kBaud
Signal update rate	–	–	100	Hz

**Table 4. Environmental Specifications<sup>1</sup>**

Characteristic	Parameter
Operating temperature	-40°C to 85°C [40°F to 185°F]
Storage temperature <sup>2</sup>	-40°C to 105°C [40°F to 221°F]
Housing	PBT thermoplastic
Random vibration	10 hours at 25 Grms per MIL-STD-810, Method 514.7, Procedure I, Annex D, Category 20, 5 Hz to 500 Hz (flat spectrum)
Mechanical shock	50 g 11 ms half-sine pulse, 3 each direction, 18 total, per MIL-STD-202, Method 213
Chemical compatibility	Diesel fuel, hydraulic oil, ethylene glycol, motor oil, brake fluid, urea nitrogen, liquid lime, NPK fertilizer, ammonium hydroxide, alkaline degreaser, transmission oil, power steering fluid, and axle oil
Moisture resistance	Per MIL-STD-202, Method 106 (10 cycles, 24 hours/cycle)
Thermal shock	250 cycles, -40°C to 85°C, 73 min dwell
Salt spray	5 % salt solution, 96 hours
Ingress protection	IP67, IP69K (DIN40050-1993) with mating connector installed
RoHS	Compliant
REACH	Compliant
UV rating	Housing material meets outdoor suitability requirements per UL746C F1 rating

<sup>1</sup>For environmental conditions not covered by product specification, consult with Honeywell Engineering.

<sup>2</sup>In installed condition; otherwise, maximum storage temperature is 85°C [185°F].

**Table 5. EMC Specifications**

Characteristic	Standard	Test Level, Frequency
Radiated immunity	ISO 11452-2	125 V/m, 400 MHz to 2.5 GHz
Bulk current injection	ISO 11452-4: 2011	125 mA, 1 MHz to 400 MHz
Radiated emission	ISO 13766	30 MHz to 1 GHz
Mutual coupling	ISO 7637-3	Test pulse A, Test pulse B (-80 V, 80 V)
ESD direct contact discharge	ISO 10605	±8 kV
ESD air discharge	ISO 10605	±15 kV

# Transportation Attitude Reference System (TARS Series)

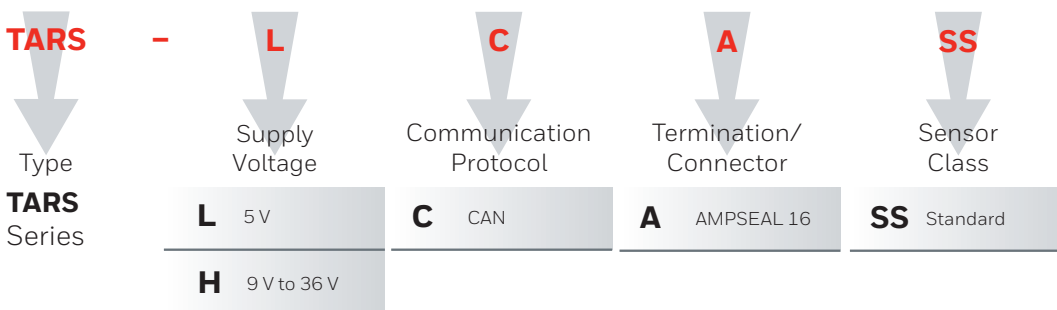
**Table 6. Installation Specifications**

Characteristic	Parameter
Mating connector	AMPSEAL 16 Series, 776487-1 for 18-16 AWG conductors or 776524-1 for 20-18 AWG conductors
CAN termination	120 Ohm termination resistor, not included in TARS-IMU unit
Weight	170 g approx.
Mounting direction	+Z
Mounting bolt	M8, installation torque 20 Nm ±2 Nm

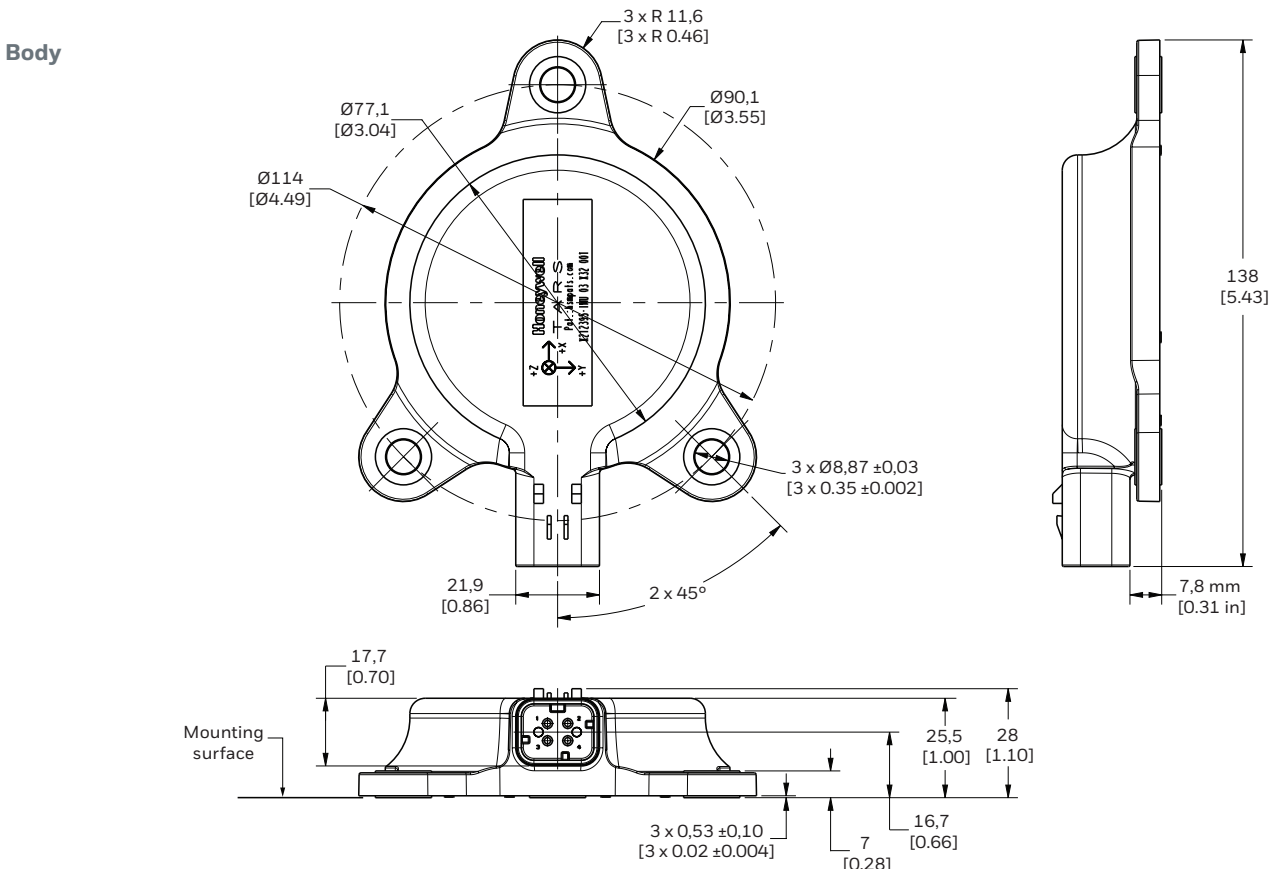
**Table 7. Order Guide**

Part Number	Description
TARS-LCASS	TARS Series Inertial Measurement Unit, 5 V, CAN protocol, AMPSEAL 16 termination, standard MEMS chip generation/performance
TARS-HCASS	TARS Series Inertial Measurement Unit, 9 V to 36 V, CAN protocol, AMPSEAL 16 termination, standard MEMS chip generation/performance

**Figure 1. Product Nomenclature**



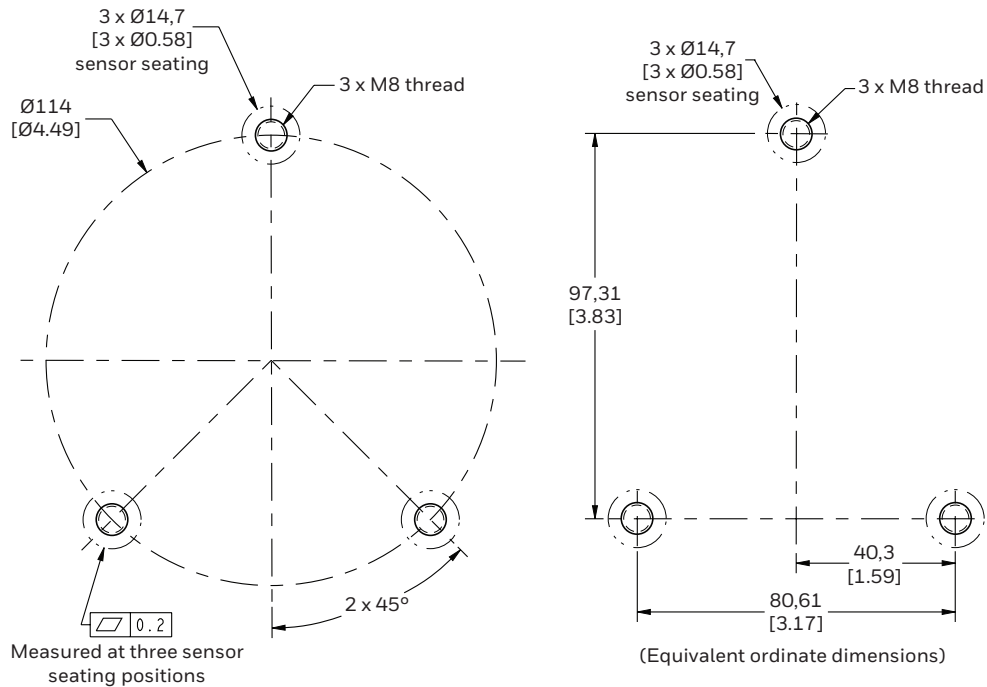
**Figure 2. Dimensions (For reference only: mm/[in])**



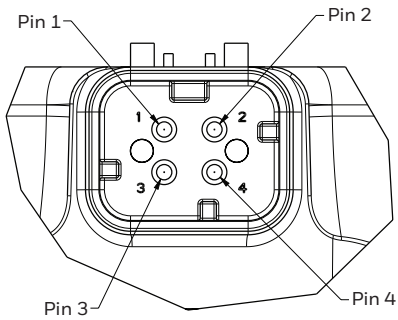
# Transportation Attitude Reference System (TARS Series)

Figure 2. Dimensions (continued)

## Mounting Holes



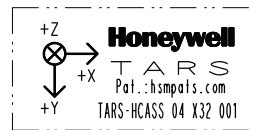
## Pinout



**Connector Termination**

Pin	Description
1	dc power
2	CAN high
3	Ground
4	CAN low

## Marking Information



### Where

**04** Product configuration code

**X32** Date code, where:

**X:** Year code for 2016, Y for 2017, Z for 2018, A for 2019, etc.

**32:** Week of final test

**001** is a consecutive number, different for each product

## ADDITIONAL MATERIALS

The following associated literature is available at [sensing.honeywell.com](http://sensing.honeywell.com):

- Product range guide
- Product installation instructions
- Application notes
- CAD models
- Product images

### **WARNING** **PERSONAL INJURY**

DO NOT USE these products as safety or emergency stop devices or in any other application where failure of the product could result in personal injury.

**Failure to comply with these instructions could result in death or serious injury.**

### **WARNING** **MISUSE OF DOCUMENTATION**

- The information presented in this product sheet is for reference only. Do not use this document as a product installation guide.
- Complete installation, operation, and maintenance information is provided in the instructions supplied with each product.

**Failure to comply with these instructions could result in death or serious injury.**

### **Warranty/Remedy**

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000828-2-EN | 2 | 07/18  
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