## Description

The 5P1103 is a programmable fanout buffer intended for high performance consumer, networking, industrial, computing, and data-communications applications. Configurations may be stored in on-chip One-Time Programmable (OTP) memory or changed using $I^{2} \mathrm{C}$ interface.

The outputs are generated from a single reference clock. The input reference can be crystal, external single-ended or differential clock. The reference clock can come from one of the two redundant clock inputs and is selected by CLKSEL pin. A glitchless manual switchover function allows one of the redundant clocks to be selected during normal operation. See reference clock input section for details.
Two select pins allow up to 4 different configurations to be programmed and accessible using processor GPIOs or bootstrapping. The different selections may be used for different operating modes (full function, partial function, partial power-down), regional standards (US, Japan, Europe) or system production margin testing.
The device may be configured to use one of two $I^{2} \mathrm{C}$ addresses to allow multiple devices to be used in a system.

## Pin Assignment



## Features

- Up to two high performance universal differential output pairs
- Low RMS additive phase jitter: 0.2 ps
- Four banks of internal non-volatile in-system programmable or factory programmable OTP memory
- $\mathrm{I}^{2} \mathrm{C}$ serial programming interface
- One additional LVCMOS output clock
- Two universal output pairs:
- Each configurable as one differential output pair or two LVCMOS outputs
- I/O Standards:
- Single-ended I/Os: 1.8 V to 3.3V LVCMOS
- Differential I/Os - LVPECL, LVDS and HCSL
- Input frequency ranges:
- LVCMOS Reference Clock Input (XIN/REF) - 1MHz to 200MHz
- LVDS, LVPECL, HCSL Differential Clock Input (CLKIN, CLKINB) - 1 MHz to 350 MHz
- Crystal frequency range: 8 MHz to 40 MHz
- Individually selectable output voltage (1.8V, 2.5V, 3.3V) for each output pair
- Redundant clock inputs with manual switchover
- Programmable crystal load capacitance
- Individual output enable/disable
- Power-down mode
- $1.8 \mathrm{~V}, 2.5 \mathrm{~V}$ or 3.3 V core $\mathrm{V}_{\mathrm{DDD}}, \mathrm{V}_{\mathrm{DDA}}$
- Available in 24 -pin VFQFPN $4 \mathrm{~mm} \times 4 \mathrm{~mm}$ package
- $-40^{\circ}$ to $+85^{\circ} \mathrm{C}$ industrial temperature operation


## 24-pin VFQFPN

## Functional Block Diagram



## Applications

- Ethernet switch/router
- PCI Express 1.0/2.0/3.0
- Broadcast video/audio timing
- Multi-function printer
- Processor and FPGA clocking
- MSAN/DSLAM/PON
- Fiber Channel, SAN
- Telecom line cards
- 1 GbE and 10 GbE


## Table 1:Pin Descriptions

| Number | Name | Type |  | Description |
| :---: | :---: | :---: | :---: | :---: |
| 1 | CLKIN | Input | Pull-down | Differential clock input. Weak 100kohms internal pull-down. |
| 2 | CLKINB | Input | Pull-down | Complementary differential clock input. Weak 100kohms internal pull-down. |
| 3 | XOUT | Input |  | Crystal Oscillator interface output. |
| 4 | XIN/REF | Input |  | Crystal Oscillator interface input, or single-ended LVCMOS clock input. Ensure that the input voltage is 1.2 V max. Refer to the section "Overdriving the XIN/REF Interface". |
| 5 | VDDA | Power |  | Analog functions power supply pin. Connect to 1.8 V to 3.3 V . VDDA and VDDD should have the same voltage applied. |
| 6 | CLKSEL | Input | Pull-down | Input clock select. Selects the active input reference source, when in Manual switchover mode. <br> $0=$ XIN/REF, XOUT (default) <br> 1 = CLKIN, CLKINB <br> CLKSEL Polarity can be changed by I2C programming as shown in Table 4. |
| 7 | SD/OE | Input | Pull-down | Enables/disables the outputs (OE) or powers down the chip (SD). The SH bit controls the configuration of the SD/OE pin. The SH bit needs to be high for SD/OE pin to be configured as SD. The SP bit ( $0 \times 02$ ) controls the polarity of the signal to be either active HIGH or LOW only when pin is configured as OE (Default is active LOW.) Weak internal pull down resistor. When configured as SD, device is shut down, differential outputs are driven high/low, and the singleended LVCMOS outputs are driven low. When configured as OE, and outputs are disabled, the outputs can be selected to be tri-stated or driven high/low, depending on the programming bits as shown in the SD/OE Pin Function Truth table. |
| 8 | SEL1/SDA | Input | Pull-down | Configuration select pin, or I2C SDA input as selected by OUTO_SEL_I2CB. Weak internal pull down resistor. |
| 9 | SELO/SCL | Input | Pull-down | Configuration select pin, or I2C SCL input as selected by OUTO_SEL_I2CB. Weak internal pull down resistor. |
| 10 | VDDA | Power |  | Analog functions power supply pin. Connect to 1.8 V to 3.3 V . VDDA and VDDD should have the same voltage applied. |
| 11 | NC |  |  | No connect. |
| 12 | NC |  |  | No connect. |
| 13 | NC |  |  | No connect. |
| 14 | NC |  |  | No connect. |
| 15 | VDDA | Power |  | Analog functions power supply pin. Connect to 1.8 V to 3.3 V . VDDA and VDDD should have the same voltage applied. |
| 16 | OUT2B | Output |  | Complementary Output Clock 2. Please refer to the Output Drivers section for more details. |
| 17 | OUT2 | Output |  | Output Clock 2. Please refer to the Output Drivers section for more details. |
| 18 | VDDO2 | Power |  | Output power supply. Connect to 1.8 to 3.3 V . Sets output voltage levels for OUT2/OUT2B. |
| 19 | OUT1B | Output |  | Complementary Output Clock 1. Please refer to the Output Drivers section for more details. |
| 20 | OUT1 | Output |  | Output Clock 1. Please refer to the Output Drivers section for more details. |
| 21 | VDDO1 | Power |  | Output power supply. Connect to 1.8 to 3.3 V . Sets output voltage levels for OUT1/OUT1B. |
| 22 | VDDD | Power |  | Digital functions power supply pin. Connect to 1.8 to 3.3 V . VDDA and VDDB should have the same voltage applied. |
| 23 | VDDO0 | Power |  | Power supply pin for OUTO_SEL_I2CB. Connect to 1.8 to 3.3 V . Sets output voltage levels for OUTO. |
| 24 | OUT0_SELB_I2C | Input/Output | Pull-down | Latched input/LVCMOS Output. At power up, the voltage at the pin OUTO_SEL_I2CB is latched by the part and used to select the state of pins 8 and 9. If a weak pull up (10Kohms) is placed on OUTO_SEL_I2CB, pins 8 and 9 will be configured as hardware select pins, SEL1 and SELO. If a weak pull down (10Kohms) is placed on OUTO_SEL_I2CB or it is left floating, pins 8 and 9 will act as the SDA and SCL pins of an I2C interface. After power up, the pin acts as a LVCMOS reference output. |
| ePAD | VEE | Power |  | Connect to ground pad. |

## Configuration and Input Descriptions

## Table 2: Configuration Table

This table shows the SEL1, SELO settings to select the configuration stored in OTP. Four configurations can be stored in OTP. These can be factory programmed or user programmed.

| OUT0_SEL_I2CB <br> @ POR | SEL1 | SELO | $\mathbf{I}^{2} \mathbf{C}$ <br> Access | REG0:7 | Config |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 1 | 0 | 0 | No | 0 | 0 |
| 1 | 0 | 1 | No | 0 | 1 |
| 1 | 1 | 0 | No | 0 | 2 |
| 1 | 1 | 1 | No | 0 | 3 |
| 0 | $X$ | $X$ | Yes | 1 | I2C <br> defaults |
| 0 | $X$ | $X$ | Yes | 0 | 0 |

At power up time, the SEL0 and SEL1 pins must be tied to either the VDDD/VDDA power supply so that they ramp with that supply or are tied low (this is the same as floating the pins). This will cause the register configuration to be loaded that is selected according to Table 3 above. Providing that OUTO_SEL_I2CB was 1 at POR and OTP register 0:7 $=0$, after the first 10 mS of operation the levels of the SELx pins can be changed, either to low or to the same level as VDDD/VDDA. The SELx pins must be driven with a digital signal of < 300 nS Rise/Fall time and only a single pin can be changed at a time. After a pin level change, the device must not be interrupted for at least 1 ms so that the new values have time to load and take effect.

If OUTO_SEL_I2CB was 0 at POR, alternate configurations can only be loaded via the I2C interface.

## Table 3: Input Clock Select

Input clock select. Selects the active input reference source in manual switchover mode.
$0=$ XIN/REF, XOUT (default)
1 = CLKIN, CLKINB
CLKSEL Polarity can be changed by $\mathrm{I}^{2} \mathrm{C}$ programming as shown in Table 4.

| PRIMSRC | CLKSEL | Source |
| :---: | :---: | :---: |
| 0 | 0 | XIN/REF |
| 0 | 1 | CLKIN, CLKINB |
| 1 | 0 | CLKIN, CLKINB |
| 1 | 1 | XIN/REF |

PRIMSRC is bit 1 of Register 0x13.

## Reference Clock Input Pins and Selection

The 5P1103 supports up to two clock inputs. One input supports a crystal between XIN and XOUT. XIN can also be driven from a single ended reference clock. XIN can accept small amplitude signals like from TCXO or one channel of a differential clock.

The second clock input (CLKIN, CLKINB) is a fully differential input that only accepts a reference clock. The differential input accepts differential clocks from all the differential logic types and can also be driven from a single ended clock on one of the input pins.

The CLKSEL pin selects the input clock between either XTAL/REF or (CLKIN, CLKINB).

Either clock input can be set as the primary clock. The primary clock designation is to establish which is the main reference clock. The non-primary clock is designated as the secondary clock in case the primary clock goes absent and a backup is needed. The PRIMSRC bit determines which clock input will be selected as primary clock. When PRIMSRC bit is " 0 ", XIN/REF is selected as the primary clock, and when " 1 ", (CLKIN, CLKINB) as the primary clock.

The two external reference clocks can be manually selected using the CLKSEL pin. The SM bits must be set to " $0 x$ " for manual switchover which is detailed in Manual Switchover Mode section.

## Crystal Input (XIN/REF)

The crystal used should be a fundamental mode quartz crystal; overtone crystals should not be used.

A crystal manufacturer will calibrate its crystals to the nominal frequency with a certain load capacitance value. When the oscillator load capacitance matches the crystal load capacitance, the oscillation frequency will be accurate. When the oscillator load capacitance is lower than the crystal load capacitance, the oscillation frequency will be higher than nominal and vice versa so for an accurate oscillation frequency you need to make sure to match the oscillator load capacitance with the crystal load capacitance.

To set the oscillator load capacitance there are two tuning capacitors in the IC, one at XIN and one at XOUT. They can be adjusted independently but commonly the same value is used for both capacitors. The value of each capacitor is composed of a fixed capacitance amount plus a variable capacitance amount set with the XTAL[5:0] register. Adjustment of the crystal tuning capacitors allows for maximum flexibility to accommodate crystals from various manufacturers. The range of tuning capacitor values available are in accordance with the following table.

## XTAL[5:0] Tuning Capacitor Characteristics

| Parameter | Bits | Step (pF) | Min (pF) | Max (pF) |
| :---: | :---: | :---: | :---: | :---: |
| XTAL | 6 | 0.5 | 9 | 25 |

The capacitance at each crystal pin inside the chip starts at 9 pF with setting 000000b and can be increased up to 25 pF with setting 111111 b . The step per bit is 0.5 pF .

You can write the following equation for this capacitance:
$\mathrm{Ci}=9 \mathrm{pF}+0.5 \mathrm{pF} \times \mathrm{XTAL}[5: 0]$
The PCB where the IC and the crystal will be assembled adds some stray capacitance to each crystal pin and more capacitance can be added to each crystal pin with additional external capacitors.


You can write the following equations for the total capacitance at each crystal pin:
$\mathrm{C}_{\mathrm{XIN}}=\mathrm{Ci}_{1}+\mathrm{Cs}_{1}+\mathrm{Ce}_{1}$
$\mathrm{C}_{\text {XOUT }}=\mathrm{Ci}_{2}+\mathrm{Cs}_{2}+\mathrm{Ce}_{2}$
$\mathrm{Ci}_{1}$ and $\mathrm{Ci}_{2}$ are the internal, tunable capacitors. $\mathrm{Ci}_{1}$ and $\mathrm{Cs}_{2}$ are stray capacitances at each crystal pin and typical values are between 1 pF and 3 pF .
$\mathrm{Ce}_{1}$ and $\mathrm{Ce}_{2}$ are additional external capacitors that can be added to increase the crystal load capacitance beyond the tuning range of the internal capacitors. However, increasing the load capacitance reduces the oscillator gain so please consult the factory when adding $\mathrm{Ce}_{1}$ and/or $\mathrm{Ce}_{2}$ to avoid crystal startup issues. $\mathrm{Ce}_{1}$ and $\mathrm{Ce}_{2}$ can also be used to adjust for unpredictable stray capacitance in the PCB.

The final load capacitance of the crystal:
$\mathrm{CL}=\mathrm{C}_{\mathrm{XIN}} \times \mathrm{C}_{\text {XOUT }} /\left(\mathrm{C}_{\text {XIN }}+\mathrm{C}_{\text {XOUT }}\right)$
For most cases it is recommended to set the value for capacitors the same at each crystal pin:
$C_{\text {XIN }}=C_{\text {XOUT }}=C x \rightarrow C L=C x / 2$
The complete formula when the capacitance at both crystal pins is the same:
$\mathrm{CL}=(9 \mathrm{pF}+0.5 \mathrm{pF} \times \mathrm{XTAL}[5: 0]+\mathrm{Cs}+\mathrm{Ce}) / 2$

Example 1: The crystal load capacitance is specified as 8 pF and the stray capacitance at each crystal pin is $\mathrm{Cs}=1.5 \mathrm{pF}$. Assuming equal capacitance value at XIN and XOUT, the equation is as follows:
$8 \mathrm{pF}=(9 \mathrm{pF}+0.5 \mathrm{pF} \times \mathrm{XTAL}[5: 0]+1.5 \mathrm{pF}) / 2 \rightarrow$
$0.5 \mathrm{pF} \times \mathrm{XTAL}[5: 0]=5.5 \mathrm{pF} \rightarrow \mathrm{XTAL[5:0]}=11$ (decimal)
Example 2: The crystal load capacitance is specified as 12 pF and the stray capacitance Cs is unknown. Footprints for external capacitors Ce are added and a worst case Cs of 5 pF is used. For now we use $\mathrm{Cs}+\mathrm{Ce}=5 \mathrm{pF}$ and the right value for Ce can be determined later to make 5 pF together with Cs.
$12 \mathrm{pF}=(9 \mathrm{pF}+0.5 \mathrm{pF} \times \mathrm{XTAL}[5: 0]+5 \mathrm{pF}) / 2 \rightarrow$
XTAL[5:0] = 20 (decimal)

## Manual Switchover Mode

When SM[1:0] is " $0 x$ ", the redundant inputs are in manual switchover mode. In this mode, CLKSEL pin is used to switch between the primary and secondary clock sources. The primary and secondary clock source setting is determined by the PRIMSRC bit. During the switchover, no glitches will occur at the output of the device, although there may be frequency and phase drift, depending on the exact phase and frequency relationship between the primary and secondary clocks.

## OTP Interface

The 5P1103 can also store its configuration in an internal OTP. The contents of the device's internal programming registers can be saved to the OTP by setting burn_start (W114[3]) to high and can be loaded back to the internal programming registers by setting usr_rd_start(W114[0]) to high.

To initiate a save or restore using $\mathrm{I}^{2} \mathrm{C}$, only two bytes are transferred. The Device Address is issued with the read/write bit set to " 0 ", followed by the appropriate command code. The save or restore instruction executes after the STOP condition is issued by the Master, during which time the 5P1103 will not generate Acknowledge bits. The 5P1103 will acknowledge the instructions after it has completed execution of them. During that time, the $I^{2} \mathrm{C}$ bus should be interpreted as busy by all other users of the bus.

On power-up of the 5P1103, an automatic restore is performed to load the OTP contents into the internal programming registers. The 5P1103 will be ready to accept a programming instruction once it acknowledges its 7 -bit $I^{2} \mathrm{C}$ address.

Availability of Primary and Secondary $\mathrm{I}^{2} \mathrm{C}$ addresses to allow programming for multiple devices in a system. The $I^{2} \mathrm{C}$ slave address can be changed from the default 0xD4 to 0xD0 by programming the I2C_ADDR bit DO. VersaClock 5 Programming Guide provides detailed $\mathrm{I}^{2} \mathrm{C}$ programming guidelines and register map.

## SDIOE Pin Function

The polarity of the SD/OE signal pin can be programmed to be either active HIGH or LOW with the SP bit (W16[1]). When SP is " 0 " (default), the pin becomes active LOW and when SP is " 1 ", the pin becomes active HIGH. The SD/OE pin can be configured as either to shutdown the PLL or to enable/disable the outputs. The SH bit controls the configuration of the SD/OE pin The SH bit needs to be high for SD/OE pin to be configured as SD.


When configured as SD, device is shut down, differential outputs are driven High/low, and the single-ended LVCMOS outputs are driven low. When configured as OE, and outputs are disabled, the outputs are driven high/low.

## Table 4: SDIOE Pin Function Truth Table

| SH bit | SP bit | OSn bit | OEn bit | SDIOE | OUTn |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 0 | 0 | 0 | X | X | Tri-state ${ }^{2}$ |
| 0 | 0 | 1 | 0 | X | Output active |
| 0 | 0 | 1 | 1 | 0 | Output active |
| 0 | 0 | 1 | 1 | 1 | Output driven High Low |
| 0 | 1 | 0 | X | X | Tri-state ${ }^{2}$ |
| 0 | 1 | 1 | 0 | X | Output active |
| 0 | 1 | 1 | 1 | 0 | Output driven High Low |
| 0 | 1 | 1 | 1 | 1 | Output active |
| 1 | 0 | 0 | X | 0 | Tri-state ${ }^{2}$ |
| 1 | 0 | 1 | 0 | 0 | Output active |
| 1 | 0 | 1 | 1 | 0 | Output active |
| 1 | 1 | 0 | x | 0 | Tri-state ${ }^{2}$ |
| 1 | 1 | 1 | 0 | 0 | Output active |
| 1 | 1 | 1 | 1 | 0 | Output driven High Low |
| 1 | X | x | X | 1 | Output driven High Low ${ }^{1}$ |

Note 1 : Global Shutdown
Note 2 : Tri-state regardless of OEn bits

## Output Skew

Rising edges of all outputs are automatically phase aligned.

## Output Drivers

The OUT1 to OUT2 clock outputs are provided with register-controlled output drivers. By selecting the output drive type in the appropriate register, any of these outputs can support LVCMOS, LVPECL, HCSL or LVDS logic levels

The operating voltage ranges of each output is determined by
its independent output power pin ( $\mathrm{V}_{\text {DDO }}$ ) and thus each can have different output voltage levels. Output voltage levels of 2.5 V or 3.3 V are supported for differential HCSL, LVPECL operation, and $1.8 \mathrm{~V}, 2.5 \mathrm{~V}$, or 3.3 V are supported for LVCMOS and differential LVDS operation.

Each output may be enabled or disabled by register bits. When disabled an output will be in a logic 0 state as determined by the programming bit table shown on page 6.

## LVCMOS Operation

When a given output is configured to provide LVCMOS levels, then both the OUTx and OUTxB outputs will toggle at the selected output frequency. All the previously described configuration and control apply equally to both outputs. Frequency, phase alignment, voltage levels and enable / disable status apply to both the OUTx and OUTxB pins. The OUTx and OUTxB outputs can be selected to be phase-aligned with each other or inverted relative to one another by register programming bits. Selection of phase-alignment may have negative effects on the phase noise performance of any part of the device due to increased simultaneous switching noise within the device.

## Device Hardware Configuration

The 5P1103 supports an internal One-Time Programmable (OTP) memory that can be pre-programmed at the factory with up to 4 complete device configuration.

These configurations can be over-written using the serial interface once reset is complete. Any configuration written via the programming interface needs to be re-written after any power cycle or reset. Please contact IDT if a specific factory-programmed configuration is desired.

## Device Start-up \& Reset Behavior

The 5P1103 has an internal power-up reset (POR) circuit. The POR circuit will remain active for a maximum of 10 ms after device power-up.

Upon internal POR circuit expiring, the device will exit reset and begin self-configuration.

The device will load internal registers using the configuration stored in the internal One-Time Programmable (OTP) memory.

Once the full configuration has been loaded, the device will respond to accesses on the serial port and will attempt to begin operation.

## Power Up Ramp Sequence

VDDA and VDDD must ramp up together. VDDO0~2 must ramp up before, or concurrently with, VDDA and VDDD. All power supply pins must be connected to a power rail even if the output is unused. All power supplies must ramp in a linear fashion and ramp monotonically.


## $I^{2} \mathrm{C}$ Mode Operation

The device acts as a slave device on the $I^{2} \mathrm{C}$ bus using one of the two $\mathrm{I}^{2} \mathrm{C}$ addresses ( $0 \times \mathrm{D} 0$ or $0 \times \mathrm{D} 4$ ) to allow multiple devices to be used in the system. The interface accepts byte-oriented block write and block read operations. Two address bytes specify the register address of the byte position of the first register to write or read. Data bytes (registers) are accessed in sequential order from the lowest to the highest byte (most significant bit first). Read and write block transfers can be stopped after any complete byte transfer. During a write operation, data will not be moved into the registers until the STOP bit is received, at which point, all data received in the block write will be written simultaneously.

For full electrical $I^{2} \mathrm{C}$ compliance, it is recommended to use external pull-up resistors for SDATA and SCLK. The internal pull-down resistors have a size of $100 \mathrm{k} \Omega$ typical.

Current Read

| $S$ | Dev Addr + R | A | Data 0 | A | Data 1 | A | 000 | A | Data n | Abar | P |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |

Sequential Read

| s | Dev Addr + W | A | Reg start Addr | A | Sr | Dev Addr + R | A | Data 0 | A | Data 1 | A | $\bigcirc \circ \circ$ | A | Data n | Abar | P |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |

Sequential Write

| S | Dev Addr + W | A | Reg start Addr | A | Data 0 | A | Data 1 | A | $\circ 00$ | A | Data $n$ | A | P |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |

S = start
$\mathrm{Sr}=$ repeated start
A = acknowledge
Abar= none acknowledge
$\mathrm{P}=$ stop

## $I^{2} C$ Slave Read and Write Cycle Sequencing

## Table 5: $\mathrm{I}^{2} \mathrm{C}$ Bus DC Characteristics

| Symbol | Parameter | Conditions | Min | Typ | Max | Unit |
| :---: | :--- | :--- | :---: | :---: | :---: | :---: |
| $\mathrm{V}_{\mathrm{IH}}$ | Input HIGH Level | For SEL1/SDA pin and <br> SEL0/SCL pin. | $0.7 \times \mathrm{V}_{\mathrm{DDD}}$ |  | $5.5^{2}$ | V |
| $\mathrm{~V}_{\mathrm{IL}}$ | Input LOW Level | For SEL1/SDA pin and <br> SEL0/SCL pin. | GND-0.3 |  | $0.3 \times \mathrm{V}_{\mathrm{DDD}}$ | V |
| $\mathrm{V}_{\mathrm{HYS}}$ | Hysteresis of Inputs |  | $0.05 \times \mathrm{V}_{\mathrm{DDD}}$ |  |  | V |
| $\mathrm{I}_{\mathrm{IN}}$ | Input Leakage Current |  | -1 |  | 30 | $\mu \mathrm{~A}$ |
| $\mathrm{~V}_{\mathrm{OL}}$ | Output LOW Voltage | $\mathrm{I}_{\mathrm{OL}}=3 \mathrm{~mA}$ |  |  | 0.4 | V |

Table 6: $I^{2} \mathrm{C}$ Bus AC Characteristics

| Symbol | Parameter | Min | Typ | Max | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: |
| $\mathrm{F}_{\text {SCLK }}$ | Serial Clock Frequency (SCL) | 10 |  | 400 | kHz |
| $\mathrm{t}_{\text {BUF }}$ | Bus free time between STOP and START | 1.3 |  |  | $\mu \mathrm{s}$ |
| $\mathrm{t}_{\text {SU:START }}$ | Setup Time, START | 0.6 |  |  | $\mu \mathrm{s}$ |
| $\mathrm{t}_{\text {HD: START }}$ | Hold Time, START | 0.6 |  |  | $\mu \mathrm{s}$ |
| $\mathrm{t}_{\text {SU:DATA }}$ | Setup Time, data input (SDA) | 100 |  |  | ns |
| $\mathrm{t}_{\text {HD: DATA }}$ | Hold Time, data input (SDA) ${ }^{1}$ | 0 |  |  | $\mu \mathrm{s}$ |
| tovd | Output data valid from clock |  |  | 0.9 | $\mu \mathrm{s}$ |
| $\mathrm{C}_{\mathrm{B}}$ | Capacitive Load for Each Bus Line |  |  | 400 | pF |
| $\mathrm{t}_{\mathrm{R}}$ | Rise Time, data and clock (SDA, SCL) | $20+0.1 \times \mathrm{C}_{\mathrm{B}}$ |  | 300 | ns |
| $t_{F}$ | Fall Time, data and clock (SDA, SCL) | $20+0.1 \times \mathrm{C}_{\mathrm{B}}$ |  | 300 | ns |
| $\mathrm{t}_{\mathrm{HIGH}}$ | HIGH Time, clock (SCL) | 0.6 |  |  | $\mu \mathrm{s}$ |
| t Low | LOW Time, clock (SCL) | 1.3 |  |  | $\mu \mathrm{s}$ |
| $\mathrm{t}_{\text {SU:STOP }}$ | Setup Time, STOP | 0.6 |  |  | $\mu \mathrm{s}$ |

Note 1: A device must internally provide a hold time of at least 300 ns for the SDA signal (referred to the $\mathrm{V}_{\mathrm{IH}}(\mathrm{MIN})$ of the SCL signal) to bridge the undefined region of the falling edge of SCL
Note 2: I2C inputs are 5V tolerant.

## Table 7: Absolute Maximum Ratings

Stresses above the ratings listed below can cause permanent damage to the 5P1103. These ratings, which are standard values for IDT commercially rated parts, are stress ratings only. Functional operation of the device at these or any other conditions above those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods can affect product reliability. Electrical parameters are guaranteed only over the recommended operating temperature range.

| Item | Rating |
| :--- | :--- |
| Supply Voltage, $\mathrm{V}_{\mathrm{DDA}}, \mathrm{V}_{\mathrm{DDD}}, \mathrm{V}_{\mathrm{DDO}}$ | 3.465 V |
| Inputs | 0 V to 1.2 V voltage swing |
| XIN/REF | 0 V to 1.2 V voltage swing single-ended |
| CLKIN, CLKINB | -0.5 V to $\mathrm{V}_{\mathrm{DDD}}$ |
| Other inputs | -0.5 V to $\mathrm{V}_{\mathrm{DDO}}+0.5 \mathrm{~V}$ |
| Outputs, $\mathrm{V}_{\mathrm{DDO}}$ (LVCMOS) | 10 mA |
| Outputs, $\mathrm{I}_{\mathrm{O}}$ (SDA) | $42^{\circ} \mathrm{C} / \mathrm{W}(0 \mathrm{mps})$ |
| Package Thermal Impedance, $\theta_{\mathrm{JA}}$ | $41.8^{\circ} \mathrm{C} / \mathrm{W}(0 \mathrm{mps})$ |
| Package Thermal Impedance, $\theta_{\mathrm{JC}}$ | $-65^{\circ} \mathrm{C}$ to $150^{\circ} \mathrm{C}$ |
| Storage Temperature, $\mathrm{T}_{\text {STG }}$ | 2000 V |
| ESD Human Body Model | $125^{\circ} \mathrm{C}$ |
| Junction Temperature |  |

Table 8: Recommended Operation Conditions

| Symbol | Parameter | Min | Typ | Max | Unit |
| :---: | :--- | :---: | :---: | :---: | :---: |
| $\mathrm{V}_{\text {DDOX }}$ | Power supply voltage for supporting 1.8V outputs | 1.71 | 1.8 | 1.89 | V |
| $\mathrm{~V}_{\text {DDOX }}$ | Power supply voltage for supporting 2.5V outputs | 2.375 | 2.5 | 2.625 | V |
| $\mathrm{~V}_{\text {DDOX }}$ | Power supply voltage for supporting 3.3V outputs | 3.135 | 3.3 | 3.465 | V |
| $\mathrm{~V}_{\text {DDD }}$ | Power supply voltage for core logic functions | 1.71 |  | 3.465 | V |
| $\mathrm{~V}_{\text {DDA }}$ | Analog power supply voltage. Use filtered analog power <br> supply. | 1.71 |  | 3.465 | V |
| $\mathrm{~T}_{\mathrm{A}}$ | Operating temperature, ambient | -40 |  | +85 | ${ }^{\circ} \mathrm{C}$ |
| $\mathrm{C}_{\text {LOAD_OUT }}$ | Maximum load capacitance (3.3V LVCMOS only) |  |  | 15 | pF |
| $\mathrm{F}_{\text {IN }}$ | External reference crystal | 8 |  | 40 | MHz |
|  | External reference clock CLKIN, CLKINB | 1 |  | 350 | ms |
| $\mathrm{t}_{\text {PU }}$ | Power up time for all $\mathrm{V}_{\mathrm{DD}}$ s to reach minimum specified <br> voltage (power ramps must be monotonic) | 0.05 |  | 5 |  |

Note: $\mathrm{V}_{\mathrm{DDO}} 1$ and $\mathrm{V}_{\mathrm{DDO}} 2$ must be powered on either before or simultaneously with $\mathrm{V}_{\mathrm{DDD}}, \mathrm{V}_{\mathrm{DDA}}$ and $\mathrm{V}_{\mathrm{DDO}} 0$.

## Table 9: Input Capacitance, LVCMOS Output Impedance, and Internal Pull-down Resistance ( $\mathrm{T}_{\mathrm{A}}=+25^{\circ} \mathrm{C}$ )

| Symbol | Parameter | Min | Typ | Max | Unit |
| :--- | :--- | :---: | :---: | :---: | :---: |
| CIN | Input Capacitance (SD/OE, SEL1/SDA, SELO/SCL) |  | 3 | 7 | pF |
| Pull-down Resistor |  | 100 |  | 300 | $\mathrm{k} \Omega$ |
| ROUT | LVCMOS Output Driver Impedance (VDDO =1.8V,2.5V,3.3V) |  |  |  | $\Omega$ |
| XIN/REF | Programmable capacitance at XIN/REF | 9 |  | 25 | pF |
| XOUT | Programmable capacitance at XOUT | 9 |  | 25 | pF |

## Table 10: Crystal Characteristics

| Parameter | Test Conditions | Minimum | Typical | Maximum | Units |
| :--- | :--- | :--- | :---: | :---: | :---: | :---: |
| Mode of Oscillation |  | Fundamental |  |  |  |
| Frequency |  | 8 | 25 | 40 | MHz |
| Equivalent Series Resistance (ESR) |  |  | 10 | 100 | $\Omega$ |
| Shunt Capacitance |  |  |  | 7 | pF |
| Load Capacitance (CL) @ <=25 MHz |  | 6 | 8 | 12 | pF |
| Load Capacitance (CL) >25M to 40M |  | 6 |  | 8 | pF |
| Maximum Crystal Drive Level |  |  |  | 100 | $\mu \mathrm{~W}$ |

Note: Typical crystal used is IDT 603-25-150 or FOX 603-25-150. For different reference crystal options please go to www.foxonline.com.

## Table 11: DC Electrical Characteristics

| Symbol | Parameter | Test Conditions | Min | Typ | Max | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Iddcore ${ }^{3}$ | Core Supply Current | 100 MHz on all outputs, 25 MHz REFCLK |  | 4 | 5 | mA |
| Iddox | Output Buffer Supply Current | LVPECL, 350 MHz , 3.3V VDDOx |  | 35 | 37 | mA |
|  |  | LVPECL, 350 MHz , 2.5V VDDOx |  | 33 | 35 | mA |
|  |  | LVDS, 350 MHz , 3.3V VDDOx |  | 8 | 9 | mA |
|  |  | LVDS, 350 MHz , 2.5V VDDOx |  | 7 | 8 | mA |
|  |  | LVDS, 350 MHz , 1.8V VDDOx |  | 6 | 7 | mA |
|  |  | HCSL, 250 MHz , 3.3V VDDOx, 2 pF load |  | 22 | 23 | mA |
|  |  | HCSL, 250 MHz , 2.5V VDDOx, 2 pF load |  | 20 | 22 | mA |
|  |  | LVCMOS, $50 \mathrm{MHz}, 3.3 \mathrm{~V}, \mathrm{VDDOx}{ }^{1,2}$ |  | 5 | 6 | mA |
|  |  | LVCMOS, 50 MHz , 2.5 V , VDDOx ${ }^{1,2}$ |  | 4 | 5 | mA |
|  |  | LVCMOS, 50 MHz , 1.8V, VDDOx ${ }^{1,2}$ |  | 3 | 4 | mA |
|  |  | LVCMOS, 200 MHz , 3.3V VDDOx ${ }^{1}$ |  | 17 | 18 | mA |
|  |  | LVCMOS, 200 MHz , 2.5V VDDOx ${ }^{1,2}$ |  | 12 | 13 | mA |
|  |  | LVCMOS, 200 MHz , 1.8V VDDOx ${ }^{1,2}$ |  | 9 | 10 | mA |
| Iddpd | Power Down Current | SD asserted, I2C Programming |  | 5 | 6 | mA |

[^0]Table 12: Electrical Characteristics - Differential Clock Input Parameters ${ }^{\mathbf{1 , 2}}$ (Supply
Voltage $\mathrm{V}_{\text {DDA }}, \mathrm{V}_{\text {DDD }}, \mathrm{V}_{\text {DDO }} 0=3.3 \mathrm{~V} \pm 5 \%, 2.5 \mathrm{~V} \pm 5 \%, 1.8 \mathrm{~V} \pm 5 \%, \mathrm{TA}=-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ )

| Symbol | Parameter | Test Conditions | Min | Typ | Max |
| :---: | :--- | :--- | :---: | :---: | :---: |
| $\mathrm{V}_{\mathrm{IH}}$ | Input HIGH Voltage-CLKIN, CLKINB | Single-ended input | 0.55 |  | 1.7 |
| $\mathrm{~V}_{\mathrm{IL}}$ | Input LOW Voltage-CLKIN, CLKINB | Single-ended input | $\mathrm{GND}-0.3$ |  | 0.4 |
| $\mathrm{~V}_{\mathrm{SWING}}$ | Input Amplitude - CLKIN, CLKINB | Peak to Peak value, single-ended | 200 | V |  |
| $\mathrm{dv} / \mathrm{dt}$ | Input Slew Rate - CLKIN, CLKINB | Measured differentially | 0.4 | 1200 | mV |
| $\mathrm{I}_{\mathrm{IL}}$ | Input Leakage Low Current | $\mathrm{V}_{\mathrm{IN}}=\mathrm{GND}$ | -5 | 8 | $\mathrm{~V} / \mathrm{ns}$ |
| $\mathrm{I}_{\mathrm{IH}}$ | Input Leakage High Current | $\mathrm{V}_{\mathrm{IN}}=1.7 \mathrm{~V}$ |  | 5 A |  |
| $\mathrm{~d}_{\mathrm{TIN}}$ | Input Duty Cycle | Measurement from differential <br> waveform | 45 |  |  |

1. Guaranteed by design and characterization, not $100 \%$ tested in production.
2. Slew rate measured through $\pm 75 \mathrm{mV}$ window centered around differential zero

Table 13: DC Electrical Characteristics for 3.3V LVCMOS $\left(V_{D D O}=3.3 V \pm 5 \%, T A=-40^{\circ} \mathrm{C} \text { to }+85^{\circ} \mathrm{C}\right)^{\mathbf{1}}$

| Symbol | Parameter | Test Conditions | Min | Typ | Max | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| VOH | Output HIGH Voltage | $\mathrm{IOH}=-15 \mathrm{~mA}$ | 2.4 |  | VDDO | V |
| VOL | Output LOW Voltage | $\mathrm{IOL}=15 \mathrm{~mA}$ |  |  | 0.4 | V |
| IOZDD | Output Leakage Current (OUT1~4) | Tri-state outputs, VDDO $=3.465 \mathrm{~V}$ |  |  | 5 | $\mu \mathrm{A}$ |
| IOZDD | Output Leakage Current (OUT0) | Tri-state outputs, VDDO $=3.465 \mathrm{~V}$ |  |  | 30 | $\mu \mathrm{A}$ |
| VIH | Input HIGH Voltage | Single-ended inputs - CLKSEL, SD/OE | 0.7xVDDD |  | VDDD + 0.3 | V |
| VIL | Input LOW Voltage | Single-ended inputs - CLKSEL, SD/OE | GND - 0.3 |  | $0.3 x \mathrm{VDDD}$ | V |
| VIH | Input HIGH Voltage | Single-ended input OUT0_SEL_I2CB | 2 |  | VDDO0 + 0.3 | V |
| VIL | Input LOW Voltage | Single-ended input OUT0_SEL_I2CB | GND - 0.3 |  | 0.4 | V |
| VIH | Input HIGH Voltage | Single-ended input - XIN/REF | 0.8 |  | 1.2 | V |
| VIL | Input LOW Voltage | Single-ended input - XIN/REF | GND - 0.3 |  | 0.4 | V |
| TR/TF | Input Rise/Fall Time | CLKSEL, SD/OE, SEL1/SDA, SELO/SCL |  |  | 300 | nS |

[^1]Table 14: DC Electrical Characteristics for 2.5V LVCMOS ( $\mathrm{V}_{\mathrm{DDO}}=2.5 \mathrm{~V} \pm 5 \%, \mathrm{TA}=-40^{\circ} \mathrm{C}$ to $\left.+85^{\circ} \mathrm{C}\right)$

| Symbol | Parameter | Test Conditions | Min | Typ | Max | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| VOH | Output HIGH Voltage | $\mathrm{IOH}=-12 \mathrm{~mA}$ | 0.7xVDDO |  | VDDD + 0.3 | V |
| VOL | Output LOW Voltage | $\mathrm{IOL}=12 \mathrm{~mA}$ |  |  | 0.4 | V |
| IOZDD | Output Leakage Current | Tri-state outputs, VDDO $=2.625 \mathrm{~V}$ |  |  | 5 | $\mu \mathrm{A}$ |
| VOH | Output HIGH Voltage | $\mathrm{IOH}=-12 \mathrm{~mA}$, OUT0 | 0.6 xVDDO |  | VDDD + 0.3 | V |
| VOL | Output LOW Voltage | $\mathrm{IOL}=12 \mathrm{~mA}$, OUT0 |  |  | 0.4 | V |
| IOZDD | Output Leakage Current | Tri-state outputs, VDDO $=2.625 \mathrm{~V}$, OUT0 |  |  | 30 | $\mu \mathrm{A}$ |
| VIH | Input HIGH Voltage | Single-ended inputs - CLKSEL, SD/OE | 0.7xVDDD |  | VDDD + 0.3 | V |
| VIL | Input LOW Voltage | Single-ended inputs - CLKSEL, SD/OE | GND - 0.3 |  | 0.3xVDDD | V |
| VIH | Input HIGH Voltage | Single-ended input OUT0_SEL_I2CB | 1.7 |  | VDDO0 + 0.35 | V |
| VIL | Input LOW Voltage | Single-ended input OUT0_SEL_I2CB | GND - 0.3 |  | 0.4 | V |
| VIH | Input HIGH Voltage | Single-ended input - XIN/REF | 0.8 |  | 1.2 | V |
| VIL | Input LOW Voltage | Single-ended input - XIN/REF | GND - 0.3 |  | 0.4 | V |
| TR/TF | Input Rise/Fall Time | CLKSEL, SD/OE, SEL1/SDA, SELO/SCL |  |  | 300 | nS |

Table 15: DC Electrical Characteristics for 1.8V LVCMOS $\left(\mathrm{V}_{\mathrm{DDO}}=1.8 \mathrm{~V} \pm 5 \%, \mathrm{TA}=-40^{\circ} \mathrm{C}\right.$ to $\left.+85^{\circ} \mathrm{C}\right)$

| Symbol | Parameter | Test Conditions | Min | Typ | Max | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| VOH | Output HIGH Voltage | $\mathrm{IOH}=-8 \mathrm{~mA}$ | $0.7 \times \mathrm{VDDO}$ |  | VDDO | V |
| VOL | Output LOW Voltage | $\mathrm{IOL}=8 \mathrm{~mA}$ |  |  | $0.25 \times$ VDDO | V |
| IOZDD | Output Leakage Current | Tri-state outputs, VDDO $=3.465 \mathrm{~V}$ |  |  | 5 | $\mu \mathrm{A}$ |
| VOH | Output HIGH Voltage | $\mathrm{IOH}=-8 \mathrm{~mA}$, OUT0 | $0.6 \times \mathrm{VDDO}$ |  | VDDO | V |
| VOL | Output LOW Voltage | $\mathrm{IOL}=8 \mathrm{~mA}$, OUT0 |  |  | $0.25 \times$ VDDO | V |
| IOZDD | Output Leakage Current | Tri-state outputs, VDDO $=3.465 \mathrm{~V}$, OUT0 |  |  | 30 | $\mu \mathrm{A}$ |
| VIH | Input HIGH Voltage | Single-ended inputs - CLKSEL, SD/OE | 0.7 * VDDD |  | VDDD + 0.3 | V |
| VIL | Input LOW Voltage | Single-ended inputs - CLKSEL, SD/OE | GND - 0.3 |  | 0.3 * VDDD | V |
| VIH | Input HIGH Voltage | Single-ended input OUTO_SEL_I2CB | 0.65 * VDDO0 |  | VDDD0 + 0.3 | V |
| VIL | Input LOW Voltage | Single-ended input OUTO_SEL_I2CB | GND - 0.3 |  | 0.4 | V |
| VIH | Input HIGH Voltage | Single-ended input - XIN/REF | 0.8 |  | 1.2 | V |
| VIL | Input LOW Voltage | Single-ended input - XIN/REF | GND - 0.3 |  | 0.4 | V |
| TR/TF | Input Rise/Fall Time | CLKSEL, SD/OE, SEL1/SDA, SELO/SCL |  |  | 300 | nS |

Table 16: DC Electrical Characteristics for $\operatorname{LVDS}\left(V_{\text {DDO }}=3.3 \mathrm{~V} \pm 5 \%\right.$ or $2.5 \mathrm{~V} \pm 5 \%, \mathrm{TA}=-40^{\circ} \mathrm{C}$ to $\left.+85^{\circ} \mathrm{C}\right)$

| Symbol | Parameter | Min | Typ | Max | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: |
| $\mathrm{V}_{\text {OT }}{ }^{+}$) | Differential Output Voltage for the TRUE binary state | 247 |  | 454 | mV |
| $\mathrm{V}_{\text {OT }}(-)$ | Differential Output Voltage for the FALSE binary state | -247 |  | -454 | mV |
| $\triangle \mathrm{V}_{\text {OT }}$ | Change in $\mathrm{V}_{\text {OT }}$ between Complimentary Output States |  |  | 50 | mV |
| $\mathrm{V}_{\text {OS }}$ | Output Common Mode Voltage (Offset Voltage) | 1.125 | 1.25 | 1.375 | V |
| $\triangle \mathrm{V}_{\text {OS }}$ | Change in $\mathrm{V}_{\text {OS }}$ between Complimentary Output States |  |  | 50 | mV |
| l OS | Outputs Short Circuit Current, $\mathrm{V}_{\text {OUT }}+$ or $\mathrm{V}_{\text {OUT }}-=0 \mathrm{~V}$ or $\mathrm{V}_{\text {DDO }}$ |  | 9 | 24 | mA |
| IOSD | Differential Outputs Short Circuit Current, $\mathrm{V}_{\text {OUT }}{ }^{+}=\mathrm{V}_{\text {OUT }}{ }^{-}$ |  | 6 | 12 | mA |

Table 17: DC Electrical Characteristics for LVDS ( $\mathrm{V}_{\mathrm{DDO}}=1.8 \mathrm{~V} \pm 5 \%, \mathrm{TA}=-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ )

| Symbol | Parameter | Min | Typ | Max | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: |
| $\mathrm{V}_{\mathrm{OT}}{ }^{(+)}$ | Differential Output Voltage for the TRUE binary state | 247 |  | 454 | mV |
| $\mathrm{V}_{\text {OT }}(-)$ | Differential Output Voltage for the FALSE binary state | -247 |  | -454 | mV |
| $\triangle \mathrm{V}_{\mathrm{OT}}$ | Change in $\mathrm{V}_{\text {OT }}$ between Complimentary Output States |  |  | 50 | mV |
| $\mathrm{V}_{\text {OS }}$ | Output Common Mode Voltage (Offset Voltage) | 0.8 | 0.875 | 0.95 | V |
| $\triangle \mathrm{V}_{\text {OS }}$ | Change in $\mathrm{V}_{\text {OS }}$ between Complimentary Output States |  |  | 50 | mV |
| los | Outputs Short Circuit Current, $\mathrm{V}_{\text {OUT }}+$ or $\mathrm{V}_{\text {OUT }}-=0 \mathrm{~V}$ or $\mathrm{V}_{\text {DDO }}$ |  | 9 | 24 | mA |
| IOSD | Differential Outputs Short Circuit Current, $\mathrm{V}_{\mathrm{OUT}^{+}}=\mathrm{V}_{\text {OUT }}{ }^{-}$ |  | 6 | 12 | mA |

Table 18: DC Electrical Characteristics for LVPECL (VDDO $=3.3 \mathrm{~V} \pm 5 \%$ or $2.5 \mathrm{~V} \pm 5 \%, \mathrm{TA}=-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ )

| Symbol | Parameter | Min | Typ | Max | Unit |
| :---: | :--- | :---: | :---: | :---: | :---: |
| $\mathrm{V}_{\mathrm{OH}}$ | Output Voltage HIGH, terminated through $50 \Omega$ tied to $\mathrm{V}_{\mathrm{DD}}-2 \mathrm{~V}$ | $\mathrm{~V}_{\mathrm{DDO}}-1.19$ |  | $\mathrm{~V}_{\mathrm{DDO}}-0.69$ | V |
| $\mathrm{~V}_{\mathrm{OL}}$ | Output Voltage LOW, terminated through $50 \Omega$ tied to $\mathrm{V}_{\mathrm{DD}}-2 \mathrm{~V}$ | $\mathrm{~V}_{\mathrm{DDO}}-1.94$ |  | $\mathrm{~V}_{\mathrm{DDO}}-1.4$ | V |
| $\mathrm{~V}_{\text {SWING }}$ | Peak-to-Peak Output Voltage Swing | 0.55 |  | 0.993 | V |

Table 19: Electrical Characteristics - DIF 0.7V Low Power HCSL Differential Outputs
$\left(\mathrm{V}_{\text {DD }}=3.3 \mathrm{~V} \pm 5 \%, 2.5 \mathrm{~V} \pm 5 \%, \mathrm{TA}=-40^{\circ} \mathrm{C}\right.$ to $\left.+85^{\circ} \mathrm{C}\right)$

| Symbol | Parameter | Conditions | Min | Typ | Max | Units | Notes |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| dV/dt | Slew Rate | Scope averaging on | 1 |  | 4 | V/ns | 1,2,3 |
| $\mathrm{V}_{\text {HIGH }}$ | Voltage High | Statistical measurement on single-ended signal using oscilloscope math function (Scope averaging ON) | 660 |  | 850 | mV | 1,6,7 |
| V ${ }_{\text {LOW }}$ | Voltage Low |  | -150 |  | 150 | mV | 1,6 |
| $\mathrm{V}_{\text {MAX }}$ | Maximum Voltage | Measurement on single-ended signal using absolute value (Scope averaging off) |  |  | 1150 | mV | 1 |
| $\mathrm{V}_{\text {MIN }}$ | Minimum Voltage |  | -300 |  |  | mV | 1 |
| $\mathrm{V}_{\text {SWING }}$ | Voltage Swing | Scope averaging off | 300 |  |  | mV | 1,2,6 |
| $\mathrm{V}_{\text {CROSS }}$ | Crossing Voltage Value | Scope averaging off | 250 |  | 550 | mV | 1,4,6 |
| $\Delta \mathrm{V}_{\text {cross }}$ | Crossing Voltage Variation | Scope averaging off |  |  | 140 | mV | 1,5 |

1. Guaranteed by design and characterization. Not $100 \%$ tested in production
2. Measured from differential waveform.
3. Slew rate is measured through the $\mathrm{V}_{\text {SWING }}$ voltage range centered around differential 0 V . This results in $\mathrm{a}+/-150 \mathrm{mV}$ window around differential 0 V ,
4. $V_{\text {CROss }}$ is defined as voltage where Clock = Clock\# measured on a component test board and only applies to the differential rising edge (i.e. Clock rising and Clock\# falling).
5. The total variation of all $\mathrm{V}_{\text {CROSS }}$ measurements in any particular system. Note that this is a subset of $\mathrm{V}_{\text {CROSS }} \min / m a x\left(\mathrm{~V}_{\text {CROSS }}\right.$ absolute) allowed. The intent is to limit $\mathrm{V}_{\text {CROSS }}$ induced modulation by setting $\Delta \mathrm{V}_{\text {CROSS }}$ to be smaller than $\mathrm{V}_{\text {CROSS }}$ absolute.
6. Measured from single-ended waveform.
7. Measured with scope averaging off, using statistics function. Variation is difference between min. and max.

## Table 20: AC Timing Electrical Characteristics

## $\left(\mathrm{V}_{\mathrm{DDO}}=3.3 \mathrm{~V}+5 \%\right.$ or $2.5 \mathrm{~V}+5 \%$ or $1.8 \mathrm{~V} \pm 5 \%, \mathrm{TA}=-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ )

(Spread Spectrum Generation = OFF)


## Test Circuits and Loads



HCSL Differential Output Test Load


## Test Circuits and Loads for Outputs

## 5P1103 Application Schematic

The following figure shows an example of 5P1103 application schematic. Input and output terminations shown are intended as examples only and may not represent the exact user configuration. In this example, the device is operated at $\mathrm{V}_{\mathrm{DDD}}, \mathrm{V}_{\mathrm{DDA}}=3.3 \mathrm{~V}$. The decoupling capacitors should be located as close as possible to the power pin. A 12 pF parallel resonant 8 MHz to 40 MHz crystal is used in this example. Different crystal frequencies may be used. The C1 $=\mathrm{C} 2=5 \mathrm{pF}$ are recommended for frequency accuracy. If different crystal types are used, please consult IDT for recommendations. For different board layout, the C1 and C2 may be slightly adjusted for optimizing frequency accuracy.

As with any high speed analog circuitry, the power supply pins are vulnerable to random noise. To achieve optimum jitter performance, power supply isolation is required. 5P1103 provides separate power supplies to isolate any high switching noise from coupling into the part.

In order to achieve the best possible filtering, it is recommended that the placement of the filter components be on the device side of the PCB as close to the power pins as possible. If space is limited, the 0.1 uf capacitor in each power pin filter should be placed on the device side. The other components can be on the opposite side of the PCB.

Power supply filter recommendations are a general guideline to be used for reducing external noise from coupling into the devices. The filter performance is designed for a wide range of noise frequencies. This low-pass filter starts to attenuate noise at approximately 10 kHz . If a specific frequency noise component is known, such as switching power supply frequencies, it is recommended that component values be adjusted and if required, additional filtering be added. Additionally, good general design practices for power plane voltage stability suggests adding bulk capacitance in the local area of all devices.

The schematic example focuses on functional connections and is not configuration specific. Refer to the pin description and functional tables in the datasheet to ensure the logic control inputs are properly set.

5P1103 Reference Schematic


## Overdriving the XIN/REF Interface

## LVCMOS Driver

The XIN/REF input can be overdriven by an LVCMOS driver or by one side of a differential driver through an AC coupling capacitor. The XOUT pin can be left floating. The amplitude of the input signal should be between 500 mV and 1.2 V and the slew rate should not be less than $0.2 \mathrm{~V} / \mathrm{ns}$. Figure General Diagram for LVCMOS Driver to XTAL Input Interface shows an example of the interface diagram for a LVCMOS driver.

This configuration has three properties; the total output impedance of Ro and Rs matches the 50 ohm transmission line impedance, the Vrx voltage is generated at the CLKIN inputs which maintains the LVCMOS driver voltage level across the transmission line for best S/N and the R1-R2 voltage divider values ensure that the clock level at XIN is less than the maximum value of 1.2 V .


## General Diagram for LVCMOS Driver to XTAL Input Interface

Table 21 Nominal Voltage Divider Values vs LVCMOS VDD for XIN shows resistor values that ensure the maximum drive level for the XIN/REF port is not exceeded for all combinations of $5 \%$ tolerance on the driver VDD, the VDDA and 5\% resistor
tolerances. The values of the resistors can be adjusted to reduce the loading for slower and weaker LVCMOS driver by increasing the voltage divider attenuation as long as the minimum drive level is maintained over all tolerances. To assist this assessment, the total load on the driver is included in the table.

Table 21:Nominal Voltage Divider Values vs LVCMOS VDD for XIN

| LVCMOS Driver VDD | Ro+Rs | R1 | R2 | V_XIN (peak) | Ro+Rs+R1+R2 |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 3.3 | 50.0 | 130 | 75 | 0.97 | 255 |
| 2.5 | 50.0 | 100 | 100 | 1.00 | 250 |
| 1.8 | 50.0 | 62 | 130 | 0.97 | 242 |

## LVPECL Driver

Figure General Diagram for LVPECL Driver to XTAL Input Interface shows an example of the interface diagram for a +3.3 V LVPECL driver. This is a standard LVPECL termination with one side of the driver feeding the XIN/REF input. It is recommended that all components in the schematics be placed in the layout; though some components might not be
used, they can be utilized for debugging purposes. The datasheet specifications are characterized and guaranteed by using a quartz crystal as the input. If the driver is 2.5 V LVPECL, the only change necessary is to use the appropriate value of $R 3$.


## General Diagram for +3.3V LVPECL Driver to XTAL Input Interface

## CLKIN Equivalent Schematic

Figure CLKIN Equivalent Schematic below shows the basis of the requirements on VIH max, VIL min and the 1200 mV p-p single ended Vswing maximum.

- The CLKIN and CLKINB Vih max spec comes from the cathode voltage on the input ESD diodes D2 and D4, which are referenced to the internal 1.2 V supply. CLKIN or CLKINB voltages greater than $1.2 \mathrm{~V}+0.5 \mathrm{~V}=1.7 \mathrm{~V}$ will be clamped by these diodes. CLKIN and CLKINB input voltages less than -0.3 V will be clamped by diodes D1 and D3.
- The 1.2 V p-p maximum Vswing input requirement is determined by the internally regulated 1.2 V supply for the actual clock receiver. This is the basis of the Vswing spec in Table 13.



## CLKIN Equivalent Schematic

## Wiring the Differential Input to Accept Single-Ended Levels

Figure Recommended Schematic for Wiring a Differential Input to Accept Single-ended Levels shows how a differential input can be wired to accept single ended levels. This configuration has three properties; the total output impedance of Ro and Rs matches the 50 ohm transmission line
impedance, the Vrx voltage is generated at the CLKIN inputs which maintains the LVCMOS driver voltage level across the transmission line for best $\mathrm{S} / \mathrm{N}$ and the R1-R2 voltage divider values ensure that Vrx p-p at CLKIN is less than the maximum value of 1.2 V .


## Recommended Schematic for Wiring a Differential Input to Accept Single-ended Levels

Table 22 Nominal Voltage Divider Values vs Driver VDD shows resistor values that ensure the maximum drive level for the CLKIN port is not exceeded for all combinations of 5\% tolerance on the driver VDD, the Vddo_0 and 5\% resistor tolerances. The values of the resistors can be adjusted to
reduce the loading for slower and weaker LVCMOS driver by increasing the impedance of the R1-R2 divider. To assist this assessment, the total load on the driver is included in the table.

Table 22:Nominal Voltage Divider Values vs Driver VDD

| LVCMOS Driver VDD | Ro+Rs | R1 | R2 | Vrx (peak) | Ro+Rs+R1+R2 |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 3.3 | 50.0 | 130 | 75 | 0.97 | 255 |
| 2.5 | 50.0 | 100 | 100 | 1.00 | 250 |
| 1.8 | 50.0 | 62 | 130 | 0.97 | 242 |

## HCSL Differential Clock Input Interface

CLKIN/CLKINB will accept DC coupled HCSL signals.


Receiver

## CLKIN, CLKINB Input Driven by an HCSL Driver

### 3.3V Differential LVPECL Clock Input Interface

The logic levels of 3.3V LVPECL and LVDS can exceed VIH max for the CLKIN/B pins. Therefore the LVPECL levels must be AC coupled to the differential input and the DC bias restored with external voltage dividers. A single table of bias
resistor values is provided below for both for 3.3V LVPECL and LVDS. Vbias can be VDDD, $\mathrm{V}_{\text {DDOX }}$ or any other available voltage at the receiver that is most conveniently accessible in layout.


CLKIN, CLKINB Input Driven by a 3.3V LVPECL Driver


## CLKIN, CLKINB Input Driven by an LVDS Driver

Table 23:Bias Resistors for 3.3V LVPECL and LVDS Drive to CLKIN/B

| Vbias <br> (V) | Rpu1/2 <br> (kohm) | CLKIN/B Bias Voltage <br> (V) |
| :---: | :---: | :---: |
| 3.3 | 22 | 0.58 |
| 2.5 | 15 | 0.60 |
| 1.8 | 10 | 0.58 |

### 2.5V Differential LVPECL Clock Input Interface

The maximum DC 2.5V LVPECL voltage meets the VIH max CLKIN requirement. Therefore 2.5 V LVPECL can be connected directly to the CLKIN terminals without AC coupling


## CLKIN, CLKINB Input Driven by a 2.5V LVPECL Driver

## LVDS Driver Termination

For a general LVDS interface, the recommended value for the termination impedance $\left(Z_{T}\right)$ is between $90 \Omega$. and $132 \Omega$. The actual value should be selected to match the differential impedance (Zo) of your transmission line. A typical point-to-point LVDS design uses a $100 \Omega$ parallel resistor at the receiver and a $100 \Omega$. differential transmission-line environment. In order to avoid any transmission-line reflection issues, the components should be surface mounted and must be placed as close to the receiver as possible. The standard termination schematic as shown in figure Standard Termination or the termination of figure Optional Termination can be used, which uses a center tap capacitance to help filter
common mode noise. The capacitor value should be approximately 50 pF . In addition, since these outputs are LVDS compatible, the input receiver's amplitude and common-mode input range should be verified for compatibility with the IDT LVDS output. If using a non-standard termination, it is recommended to contact IDT and confirm that the termination will function as intended. For example, the LVDS outputs cannot be AC coupled by placing capacitors between the LVDS outputs and the 100 ohm shunt load. If AC coupling is required, the coupling caps must be placed between the 100 ohm shunt termination and the receiver. In this manner the termination of the LVDS output remains DC coupled


## Termination for 3.3V LVPECL Outputs

The clock layout topology shown below is a typical termination for LVPECL outputs. The two different layouts mentioned are recommended only as guidelines.

The differential outputs generate ECL/LVPECL compatible outputs. Therefore, terminating resistors (DC current path to ground) or current sources must be used for functionality. These outputs are designed to drive $50 \Omega$ transmission lines. Matched impedance techniques should be used to maximize operating frequency and minimize signal distortion. The figure below show two different layouts which are recommended only as guidelines. Other suitable clock layouts may exist and it would be recommended that the board designers simulate to guarantee compatibility across all printed circuit and clock component process variations.


### 3.3V LVPECL Output Termination (1)



### 3.3V LVPECL Output Termination (2)

## Termination for 2.5V LVPECL Outputs

Figures 2.5V LVPECL Driver Termination Example (1) and (2) show examples of termination for 2.5 V LVPECL driver. These terminations are equivalent to terminating $50 \Omega$ to $\mathrm{V}_{\mathrm{DDO}}-2 \mathrm{~V}$. For $\mathrm{V}_{\mathrm{DDO}}=2.5 \mathrm{~V}$, the $\mathrm{V}_{\mathrm{DDO}}-2 \mathrm{~V}$ is very close to ground level. The R3 in Figure 2.5V LVPECL Driver Termination Example (3) can be eliminated and the termination is shown in example (2).


### 2.5V LVPECL Driver Termination Example (1)


2.5V LVPECL Driver Termination Example (3)

2.5V LVPECL Driver Termination Example (2)

## PCI Express Application Note

PCI Express jitter analysis methodology models the system response to reference clock jitter. The block diagram below shows the most frequently used Common Clock Architecture in which a copy of the reference clock is provided to both ends of the PCI Express Link. In the jitter analysis, the transmit (Tx) and receive ( Rx ) serdes PLLs are modeled as well as the phase interpolator in the receiver. These transfer functions are called H1, H2, and H3 respectively. The overall system transfer function at the receiver is:
$\mathrm{Ht}(\mathrm{s})=\mathrm{H} 3(\mathrm{~s}) \times[\mathrm{H} 1$ (s) $-\mathrm{H} 2(\mathrm{~s})]$
The jitter spectrum seen by the receiver is the result of applying this system transfer function to the clock spectrum $X(s)$ and is:
$\mathrm{Y}(\mathrm{s})=\mathrm{X}(\mathrm{s}) \times \mathrm{H} 3(\mathrm{~s}) \times[\mathrm{H} 1(\mathrm{~s})-\mathrm{H} 2(\mathrm{~s})]$
In order to generate time domain jitter numbers, an inverse Fourier Transform is performed on X(s)*H3(s) * [H1(s) H2(s)].


## PCI Express Common Clock Architecture

For PCI Express Gen 1, one transfer function is defined and the evaluation is performed over the entire spectrum: DC to Nyquist (e.g for a 100 MHz reference clock: $0 \mathrm{~Hz}-50 \mathrm{MHz}$ ) and the jitter result is reported in peak-peak.


## PCIe Gen1 Magnitude of Transfer Function

For PCI Express Gen2, two transfer functions are defined with 2 evaluation ranges and the final jitter number is reported in RMS. The two evaluation ranges for PCI Express Gen 2 are $10 \mathrm{kHz}-1.5 \mathrm{MHz}$ (Low Band) and 1.5 MHz - Nyquist (High Band). The plots show the individual transfer functions as well as the overall transfer function Ht .


PCle Gen2A Magnitude of Transfer Function


## PCle Gen2B Magnitude of Transfer Function

For PCI Express Gen 3, one transfer function is defined and the evaluation is performed over the entire spectrum. The transfer function parameters are different from Gen 1 and the jitter result is reported in RMS.


## PCle Gen3 Magnitude of Transfer Function

For a more thorough overview of PCI Express jitter analysis methodology, please refer to IDT Application Note PCI Express Reference Clock Requirements.

## Marking Diagram



1. Line 1 is the truncated part number.
2. "ddd" denotes dash code.
3. "YWW" is the last digit of the year and week that the part was assembled.
4. "**" denotes sequential lot number.
5. "\$" denotes mark code.

| M | DIMENSIONS |  |  |
| :---: | :---: | :---: | :---: |
| L | MIN. | NOM. | MAX. |
| A | 0.80 | 0.90 | 1.00 |
| A1 | 0.00 | 0.02 | 0.05 |
| A3 | 0.20 REF |  |  |
| K | 0.20 |  |  |
| D | 4.00 BSC |  |  |
| E | 4.00 BSC |  |  |
| D2 | 2.70 | 2.80 | 2.90 |
| E2 | 2.70 | 2.80 | 2.90 |
| © | 0.50 BSC |  |  |
| L | 0.30 | 0.40 | 0.50 |
| b | 0.18 | 0.25 | 0.30 |

NOTES
DIMENSIONING AND TOLERANCING CONFORME TO ASME Y14.5M - 1994.
2. ALL DIMENSIONS ARE IN MILLIMETERS.


BOTTOM VIEW



## Ordering Information

| Part / Order Number | Marking | Shipping Packaging | Package | Temperature |
| :---: | :---: | :---: | :---: | :---: |
| 5P1103AdddNLGI | see page 29 | Trays | 24 -pin VFQFPN | $-40^{\circ}$ to $+85^{\circ} \mathrm{C}$ |
| 5P1103AdddNLGI8 |  | Tape and Reel | 24 -pin VFQFPN | $-40^{\circ}$ to $+85^{\circ} \mathrm{C}$ |

Note: "ddd" denotes specific order codes.
"G" after the two-letter package code denotes Pb-Free configuration, RoHS compliant.

## Revision History

| Rev. | Date | Originator | Description of Change |
| :---: | :---: | :---: | :--- |
| A | $04 / 15 / 15$ | B. Chandhoke | Initial release. |
| B | $04 / 30 / 15$ | B. Chandhoke | Replaced "clock buffer" with "fanout buffer" <br> Removed "A" version letter from part number title header |
| C | $06 / 19 / 15$ | B. Chandhoke | Removed the "Output Divides" section. |
| D | $07 / 13 / 15$ | B. Chandhoke | 1. Added conditions text and min/max values for VIH/VIL. <br> 2. Updated 1.8V, 2.5V, and 3.3V VIH/VIL conditions text and min/max values for "Single-ended <br> inputs - CLKSEL, SD/OE" <br> 3. Added IDT and Fox crystal references. |

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[^0]:    1. Single CMOS driver active
    2. Measured into a 5 " 50 Ohm trace with 2 pF load
    3. Iddcore $=\operatorname{IddA}+I d d D$, no loads.
[^1]:    1. See "Recommended Operating Conditions" table.
