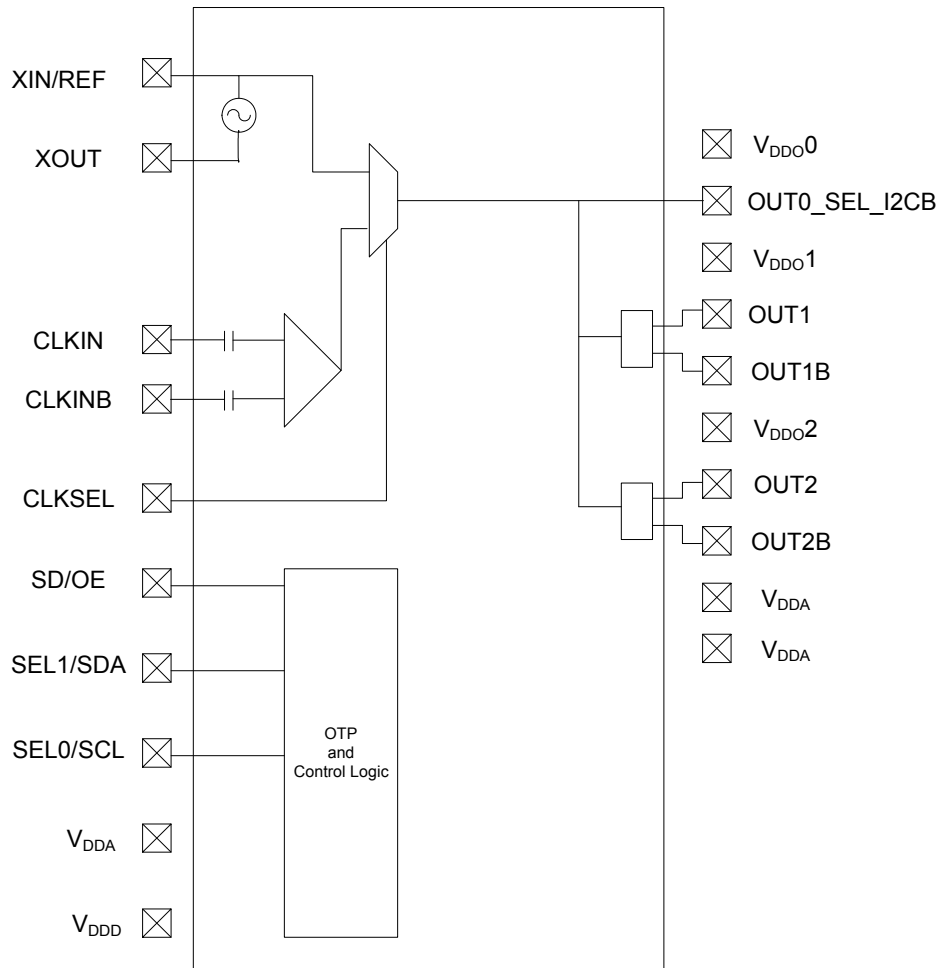




## Functional Block Diagram



## Applications

- Ethernet switch/router
- PCI Express 1.0/2.0/3.0
- Broadcast video/audio timing
- Multi-function printer
- Processor and FPGA clocking
- MSAN/DSLAM/PON
- Fiber Channel, SAN
- Telecom line cards
- 1 GbE and 10 GbE

**Table 1: Pin Descriptions**

Number	Name	Type		Description
1	CLKIN	Input	Pull-down	Differential clock input. Weak 100kohms internal pull-down.
2	CLKINB	Input	Pull-down	Complementary differential clock input. Weak 100kohms internal pull-down.
3	XOUT	Input		Crystal Oscillator interface output.
4	XIN/REF	Input		Crystal Oscillator interface input, or single-ended LVCMOS clock input. Ensure that the input voltage is 1.2V max. Refer to the section "Overdriving the XIN/REF Interface".
5	VDDA	Power		Analog functions power supply pin. Connect to 1.8V to 3.3V. VDDA and VDDD should have the same voltage applied.
6	CLKSEL	Input	Pull-down	Input clock select. Selects the active input reference source, when in Manual switchover mode. 0 = XIN/REF, XOUT (default) 1 = CLKIN, CLKINB CLKSEL Polarity can be changed by I2C programming as shown in Table 4.
7	SD/OE	Input	Pull-down	Enables/disables the outputs (OE) or powers down the chip (SD). The SH bit controls the configuration of the SD/OE pin. The SH bit needs to be high for SD/OE pin to be configured as SD. The SP bit (0x02) controls the polarity of the signal to be either active HIGH or LOW only when pin is configured as OE (Default is active LOW.) Weak internal pull down resistor. When configured as SD, device is shut down, differential outputs are driven high/low, and the single-ended LVCMOS outputs are driven low. When configured as OE, and outputs are disabled, the outputs can be selected to be tri-stated or driven high/low, depending on the programming bits as shown in the SD/OE Pin Function Truth table.
8	SEL1/SDA	Input	Pull-down	Configuration select pin, or I2C SDA input as selected by OUT0_SEL_I2CB. Weak internal pull down resistor.
9	SEL0/SCL	Input	Pull-down	Configuration select pin, or I2C SCL input as selected by OUT0_SEL_I2CB. Weak internal pull down resistor.
10	VDDA	Power		Analog functions power supply pin. Connect to 1.8V to 3.3V. VDDA and VDDD should have the same voltage applied.
11	NC			No connect.
12	NC			No connect.
13	NC			No connect.
14	NC			No connect.
15	VDDA	Power		Analog functions power supply pin. Connect to 1.8V to 3.3V. VDDA and VDDD should have the same voltage applied.
16	OUT2B	Output		Complementary Output Clock 2. Please refer to the Output Drivers section for more details.
17	OUT2	Output		Output Clock 2. Please refer to the Output Drivers section for more details.
18	VDDO2	Power		Output power supply. Connect to 1.8 to 3.3V. Sets output voltage levels for OUT2/OUT2B.
19	OUT1B	Output		Complementary Output Clock 1. Please refer to the Output Drivers section for more details.
20	OUT1	Output		Output Clock 1. Please refer to the Output Drivers section for more details.
21	VDDO1	Power		Output power supply. Connect to 1.8 to 3.3V. Sets output voltage levels for OUT1/OUT1B.
22	VDDD	Power		Digital functions power supply pin. Connect to 1.8 to 3.3V. VDDA and VDDDB should have the same voltage applied.
23	VDDO0	Power		Power supply pin for OUT0_SEL_I2CB. Connect to 1.8 to 3.3V. Sets output voltage levels for OUT0.
24	OUT0_SELB_I2C	Input/Output	Pull-down	Latched input/LVCMOS Output. At power up, the voltage at the pin OUT0_SEL_I2CB is latched by the part and used to select the state of pins 8 and 9. If a weak pull up (10Kohms) is placed on OUT0_SEL_I2CB, pins 8 and 9 will be configured as hardware select pins, SEL1 and SEL0. If a weak pull down (10Kohms) is placed on OUT0_SEL_I2CB or it is left floating, pins 8 and 9 will act as the SDA and SCL pins of an I2C interface. After power up, the pin acts as a LVCMOS reference output.
ePAD	VEE	Power		Connect to ground pad.

## Configuration and Input Descriptions

**Table 2: Configuration Table**

This table shows the SEL1, SEL0 settings to select the configuration stored in OTP. Four configurations can be stored in OTP. These can be factory programmed or user programmed.

OUT0_SEL_I2CB @ POR	SEL1	SEL0	I <sup>2</sup> C Access	REG0:7	Config
1	0	0	No	0	0
1	0	1	No	0	1
1	1	0	No	0	2
1	1	1	No	0	3
0	X	X	Yes	1	I2C defaults
0	X	X	Yes	0	0

At power up time, the SEL0 and SEL1 pins must be tied to either the VDDD/VDDA power supply so that they ramp with that supply or are tied low (this is the same as floating the pins). This will cause the register configuration to be loaded that is selected according to Table 3 above. Providing that OUT0\_SEL\_I2CB was 1 at POR and OTP register 0:7=0, after the first 10mS of operation the levels of the SELx pins can be changed, either to low or to the same level as VDDD/VDDA. The SELx pins must be driven with a digital signal of < 300nS Rise/Fall time and only a single pin can be changed at a time. After a pin level change, the device must not be interrupted for at least 1ms so that the new values have time to load and take effect.

If OUT0\_SEL\_I2CB was 0 at POR, alternate configurations can only be loaded via the I2C interface.

**Table 3: Input Clock Select**

Input clock select. Selects the active input reference source in manual switchover mode.

0 = XIN/REF, XOUT (default)

1 = CLKIN, CLKINB

CLKSEL Polarity can be changed by I<sup>2</sup>C programming as shown in Table 4.

PRIMSRC	CLKSEL	Source
0	0	XIN/REF
0	1	CLKIN, CLKINB
1	0	CLKIN, CLKINB
1	1	XIN/REF

PRIMSRC is bit 1 of Register 0x13.

## Reference Clock Input Pins and Selection

The 5P1103 supports up to two clock inputs. One input supports a crystal between XIN and XOUT. XIN can also be driven from a single ended reference clock. XIN can accept small amplitude signals like from TCXO or one channel of a differential clock.

The second clock input (CLKIN, CLKINB) is a fully differential input that only accepts a reference clock. The differential input accepts differential clocks from all the differential logic types and can also be driven from a single ended clock on one of the input pins.

The CLKSEL pin selects the input clock between either XTAL/REF or (CLKIN, CLKINB).

Either clock input can be set as the primary clock. The primary clock designation is to establish which is the main reference clock. The non-primary clock is designated as the secondary clock in case the primary clock goes absent and a backup is needed. The PRIMSRC bit determines which clock input will be selected as primary clock. When PRIMSRC bit is "0", XIN/REF is selected as the primary clock, and when "1", (CLKIN, CLKINB) as the primary clock.

The two external reference clocks can be manually selected using the CLKSEL pin. The SM bits must be set to "0x" for manual switchover which is detailed in Manual Switchover Mode section.

### Crystal Input (XIN/REF)

The crystal used should be a fundamental mode quartz crystal; overtone crystals should not be used.

A crystal manufacturer will calibrate its crystals to the nominal frequency with a certain load capacitance value. When the oscillator load capacitance matches the crystal load capacitance, the oscillation frequency will be accurate. When the oscillator load capacitance is lower than the crystal load capacitance, the oscillation frequency will be higher than nominal and vice versa so for an accurate oscillation frequency you need to make sure to match the oscillator load capacitance with the crystal load capacitance.

To set the oscillator load capacitance there are two tuning capacitors in the IC, one at XIN and one at XOUT. They can be adjusted independently but commonly the same value is used for both capacitors. The value of each capacitor is composed of a fixed capacitance amount plus a variable capacitance amount set with the XTAL[5:0] register. Adjustment of the crystal tuning capacitors allows for maximum flexibility to accommodate crystals from various manufacturers. The range of tuning capacitor values available are in accordance with the following table.

### XTAL[5:0] Tuning Capacitor Characteristics

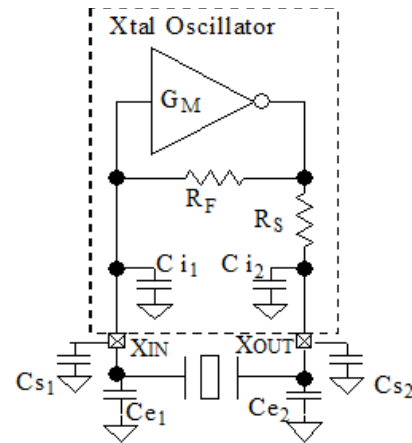
Parameter	Bits	Step (pF)	Min (pF)	Max (pF)
XTAL	6	0.5	9	25

The capacitance at each crystal pin inside the chip starts at 9pF with setting 000000b and can be increased up to 25pF with setting 111111b. The step per bit is 0.5pF.

You can write the following equation for this capacitance:

$$C_i = 9\text{pF} + 0.5\text{pF} \times \text{XTAL}[5:0]$$

The PCB where the IC and the crystal will be assembled adds some stray capacitance to each crystal pin and more capacitance can be added to each crystal pin with additional external capacitors.



You can write the following equations for the total capacitance at each crystal pin:

$$C_{XIN} = C_{i1} + C_{s1} + C_{e1}$$

$$C_{XOUT} = C_{i2} + C_{s2} + C_{e2}$$

$C_{i1}$  and  $C_{i2}$  are the internal, tunable capacitors.  $C_{i1}$  and  $C_{s2}$  are stray capacitances at each crystal pin and typical values are between 1pF and 3pF.

$C_{e1}$  and  $C_{e2}$  are additional external capacitors that can be added to increase the crystal load capacitance beyond the tuning range of the internal capacitors. However, increasing the load capacitance reduces the oscillator gain so please consult the factory when adding  $C_{e1}$  and/or  $C_{e2}$  to avoid crystal startup issues.  $C_{e1}$  and  $C_{e2}$  can also be used to adjust for unpredictable stray capacitance in the PCB.

The final load capacitance of the crystal:

$$CL = C_{XIN} \times C_{XOUT} / (C_{XIN} + C_{XOUT})$$

For most cases it is recommended to set the value for capacitors the same at each crystal pin:

$$C_{XIN} = C_{XOUT} = C_x \rightarrow CL = C_x / 2$$

The complete formula when the capacitance at both crystal pins is the same:

$$CL = (9\text{pF} + 0.5\text{pF} \times \text{XTAL}[5:0] + C_s + C_e) / 2$$

**Example 1:** The crystal load capacitance is specified as 8pF and the stray capacitance at each crystal pin is  $C_s=1.5\text{pF}$ . Assuming equal capacitance value at XIN and XOUT, the equation is as follows:

$$8\text{pF} = (9\text{pF} + 0.5\text{pF} \times \text{XTAL}[5:0] + 1.5\text{pF}) / 2 \rightarrow \\ 0.5\text{pF} \times \text{XTAL}[5:0] = 5.5\text{pF} \rightarrow \text{XTAL}[5:0] = 11 \text{ (decimal)}$$

**Example 2:** The crystal load capacitance is specified as 12pF and the stray capacitance  $C_s$  is unknown. Footprints for external capacitors  $C_e$  are added and a worst case  $C_s$  of 5pF is used. For now we use  $C_s + C_e = 5\text{pF}$  and the right value for  $C_e$  can be determined later to make 5pF together with  $C_s$ .

$$12\text{pF} = (9\text{pF} + 0.5\text{pF} \times \text{XTAL}[5:0] + 5\text{pF}) / 2 \rightarrow \\ \text{XTAL}[5:0] = 20 \text{ (decimal)}$$

## Manual Switchover Mode

When  $\text{SM}[1:0]$  is "0x", the redundant inputs are in manual switchover mode. In this mode, CLKSEL pin is used to switch between the primary and secondary clock sources. The primary and secondary clock source setting is determined by the PRIMSRC bit. During the switchover, no glitches will occur at the output of the device, although there may be frequency and phase drift, depending on the exact phase and frequency relationship between the primary and secondary clocks.

## OTP Interface

The 5P1103 can also store its configuration in an internal OTP. The contents of the device's internal programming registers can be saved to the OTP by setting `burn_start` ( $\text{W114}[3]$ ) to high and can be loaded back to the internal programming registers by setting `usr_rd_start` ( $\text{W114}[0]$ ) to high.

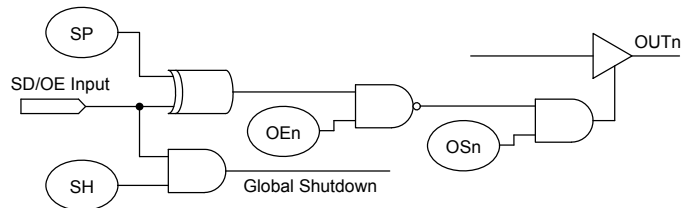
To initiate a save or restore using  $\text{I}^2\text{C}$ , only two bytes are transferred. The Device Address is issued with the read/write bit set to "0", followed by the appropriate command code. The save or restore instruction executes after the STOP condition is issued by the Master, during which time the 5P1103 will not generate Acknowledge bits. The 5P1103 will acknowledge the instructions after it has completed execution of them. During that time, the  $\text{I}^2\text{C}$  bus should be interpreted as busy by all other users of the bus.

On power-up of the 5P1103, an automatic restore is performed to load the OTP contents into the internal programming registers. The 5P1103 will be ready to accept a programming instruction once it acknowledges its 7-bit  $\text{I}^2\text{C}$  address.

Availability of Primary and Secondary  $\text{I}^2\text{C}$  addresses to allow programming for multiple devices in a system. The  $\text{I}^2\text{C}$  slave address can be changed from the default 0xD4 to 0xD0 by programming the  $\text{I}^2\text{C\_ADDR}$  bit D0. *VersaClock 5 Programming Guide* provides detailed  $\text{I}^2\text{C}$  programming guidelines and register map.

## SD/OE Pin Function

The polarity of the SD/OE signal pin can be programmed to be either active HIGH or LOW with the SP bit ( $\text{W16}[1]$ ). When SP is "0" (default), the pin becomes active LOW and when SP is "1", the pin becomes active HIGH. The SD/OE pin can be configured as either to shutdown the PLL or to enable/disable the outputs. The SH bit controls the configuration of the SD/OE pin. The SH bit needs to be high for SD/OE pin to be configured as SD.



When configured as SD, device is shut down, differential outputs are driven High/low, and the single-ended LVCMOS outputs are driven low. When configured as OE, and outputs are disabled, the outputs are driven high/low.

**Table 4: SD/OE Pin Function Truth Table**

SH bit	SP bit	OSn bit	OEn bit	SD/OE	OUTn
0	0	0	x	x	Tri-state <sup>2</sup>
0	0	1	0	x	Output active
0	0	1	1	0	Output active
0	0	1	1	1	Output driven High Low
0	1	0	x	x	Tri-state <sup>2</sup>
0	1	1	0	x	Output active
0	1	1	1	0	Output driven High Low
0	1	1	1	1	Output active
1	0	0	x	0	Tri-state <sup>2</sup>
1	0	1	0	0	Output active
1	0	1	1	0	Output active
1	1	0	x	0	Tri-state <sup>2</sup>
1	1	1	0	0	Output active
1	1	1	1	0	Output driven High Low
1	x	x	x	1	Output driven High Low <sup>1</sup>

Note 1 : Global Shutdown

Note 2 : Tri-state regardless of OEn bits

## Output Skew

Rising edges of all outputs are automatically phase aligned.

## Output Drivers

The OUT1 to OUT2 clock outputs are provided with register-controlled output drivers. By selecting the output drive type in the appropriate register, any of these outputs can support LVCMOS, LVPECL, HCSL or LVDS logic levels

The operating voltage ranges of each output is determined by

its independent output power pin ( $V_{DD0}$ ) and thus each can have different output voltage levels. Output voltage levels of 2.5V or 3.3V are supported for differential HCSL, LVPECL operation, and 1.8V, 2.5V, or 3.3V are supported for LVCMOS and differential LVDS operation.

Each output may be enabled or disabled by register bits. When disabled an output will be in a logic 0 state as determined by the programming bit table shown on page 6.

### LVCMOS Operation

When a given output is configured to provide LVCMOS levels, then both the  $OUT_x$  and  $OUT_{xB}$  outputs will toggle at the selected output frequency. All the previously described configuration and control apply equally to both outputs. Frequency, phase alignment, voltage levels and enable / disable status apply to both the  $OUT_x$  and  $OUT_{xB}$  pins. The  $OUT_x$  and  $OUT_{xB}$  outputs can be selected to be phase-aligned with each other or inverted relative to one another by register programming bits. Selection of phase-alignment may have negative effects on the phase noise performance of any part of the device due to increased simultaneous switching noise within the device.

### Device Hardware Configuration

The 5P1103 supports an internal One-Time Programmable (OTP) memory that can be pre-programmed at the factory with up to 4 complete device configuration.

These configurations can be over-written using the serial interface once reset is complete. Any configuration written via the programming interface needs to be re-written after any power cycle or reset. Please contact IDT if a specific factory-programmed configuration is desired.

### Device Start-up & Reset Behavior

The 5P1103 has an internal power-up reset (POR) circuit. The POR circuit will remain active for a maximum of 10ms after device power-up.

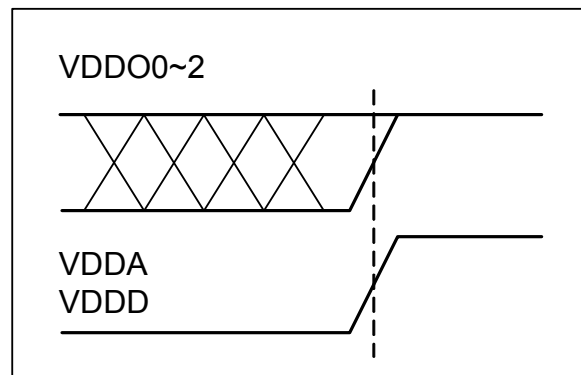
Upon internal POR circuit expiring, the device will exit reset and begin self-configuration.

The device will load internal registers using the configuration stored in the internal One-Time Programmable (OTP) memory.

Once the full configuration has been loaded, the device will respond to accesses on the serial port and will attempt to begin operation.

### Power Up Ramp Sequence

$V_{DDA}$  and  $V_{DDD}$  must ramp up together.  $V_{DD00\sim2}$  must ramp up before, or concurrently with,  $V_{DDA}$  and  $V_{DDD}$ . All power supply pins must be connected to a power rail even if the output is unused. All power supplies must ramp in a linear fashion and ramp monotonically.

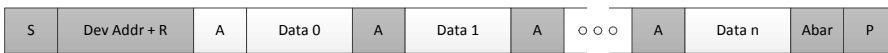


## I<sup>2</sup>C Mode Operation

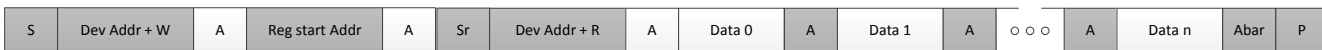
The device acts as a slave device on the I<sup>2</sup>C bus using one of the two I<sup>2</sup>C addresses (0xD0 or 0xD4) to allow multiple devices to be used in the system. The interface accepts byte-oriented block write and block read operations. Two address bytes specify the register address of the byte position of the first register to write or read. Data bytes (registers) are accessed in sequential order from the lowest to the highest byte (most significant bit first). Read and write block transfers can be stopped after any complete byte transfer. During a write operation, data will not be moved into the registers until the STOP bit is received, at which point, all data received in the block write will be written simultaneously.

For full electrical I<sup>2</sup>C compliance, it is recommended to use external pull-up resistors for SDATA and SCLK. The internal pull-down resistors have a size of 100k $\Omega$  typical.

### Current Read



### Sequential Read



### Sequential Write



- from master to slave
- from slave to master
- S = start
- Sr = repeated start
- A = acknowledge
- Abar = none acknowledge
- P = stop

## I<sup>2</sup>C Slave Read and Write Cycle Sequencing



**Table 5: I<sup>2</sup>C Bus DC Characteristics**

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
V <sub>IH</sub>	Input HIGH Level	For SEL1/SDA pin and SEL0/SCL pin.	0.7xV <sub>DDD</sub>		5.5 <sup>2</sup>	V
V <sub>IL</sub>	Input LOW Level	For SEL1/SDA pin and SEL0/SCL pin.	GND-0.3		0.3xV <sub>DDD</sub>	V
V <sub>HYS</sub>	Hysteresis of Inputs		0.05xV <sub>DDD</sub>			V
I <sub>IN</sub>	Input Leakage Current		-1		30	μA
V <sub>OL</sub>	Output LOW Voltage	I <sub>OL</sub> = 3 mA			0.4	V

**Table 6: I<sup>2</sup>C Bus AC Characteristics**

Symbol	Parameter	Min	Typ	Max	Unit
F <sub>SCLK</sub>	Serial Clock Frequency (SCL)	10		400	kHz
t <sub>BUF</sub>	Bus free time between STOP and START	1.3			μs
t <sub>SU:START</sub>	Setup Time, START	0.6			μs
t <sub>HD:START</sub>	Hold Time, START	0.6			μs
t <sub>SU:DATA</sub>	Setup Time, data input (SDA)	100			ns
t <sub>HD:DATA</sub>	Hold Time, data input (SDA) <sup>1</sup>	0			μs
t <sub>OVD</sub>	Output data valid from clock			0.9	μs
C <sub>B</sub>	Capacitive Load for Each Bus Line			400	pF
t <sub>R</sub>	Rise Time, data and clock (SDA, SCL)	20 + 0.1xC <sub>B</sub>		300	ns
t <sub>F</sub>	Fall Time, data and clock (SDA, SCL)	20 + 0.1xC <sub>B</sub>		300	ns
t <sub>HIGH</sub>	HIGH Time, clock (SCL)	0.6			μs
t <sub>LOW</sub>	LOW Time, clock (SCL)	1.3			μs
t <sub>SU:STOP</sub>	Setup Time, STOP	0.6			μs

Note 1: A device must internally provide a hold time of at least 300 ns for the SDA signal (referred to the V<sub>IH</sub>(MIN) of the SCL signal) to bridge the undefined region of the falling edge of SCL.

Note 2: I2C inputs are 5V tolerant.

## Table 7: Absolute Maximum Ratings

Stresses above the ratings listed below can cause permanent damage to the 5P1103. These ratings, which are standard values for IDT commercially rated parts, are stress ratings only. Functional operation of the device at these or any other conditions above those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods can affect product reliability. Electrical parameters are guaranteed only over the recommended operating temperature range.

Item	Rating
Supply Voltage, $V_{DDA}$ , $V_{DDD}$ , $V_{DDO}$	3.465V
Inputs XIN/REF CLKIN, CLKINB Other inputs	0V to 1.2V voltage swing 0V to 1.2V voltage swing single-ended -0.5V to $V_{DDD}$
Outputs, $V_{DDO}$ (LVCMOS)	-0.5V to $V_{DDO} + 0.5V$
Outputs, $I_O$ (SDA)	10mA
Package Thermal Impedance, $\theta_{JA}$	42°C/W (0 mps)
Package Thermal Impedance, $\theta_{JC}$	41.8°C/W (0 mps)
Storage Temperature, $T_{STG}$	-65°C to 150°C
ESD Human Body Model	2000V
Junction Temperature	125°C

## Table 8: Recommended Operation Conditions

Symbol	Parameter	Min	Typ	Max	Unit
$V_{DDOX}$	Power supply voltage for supporting 1.8V outputs	1.71	1.8	1.89	V
$V_{DDOX}$	Power supply voltage for supporting 2.5V outputs	2.375	2.5	2.625	V
$V_{DDOX}$	Power supply voltage for supporting 3.3V outputs	3.135	3.3	3.465	V
$V_{DDD}$	Power supply voltage for core logic functions	1.71		3.465	V
$V_{DDA}$	Analog power supply voltage. Use filtered analog power supply.	1.71		3.465	V
$T_A$	Operating temperature, ambient	-40		+85	°C
$C_{LOAD\_OUT}$	Maximum load capacitance (3.3V LVCMOS only)			15	pF
$F_{IN}$	External reference crystal	8		40	MHz
	External reference clock CLKIN, CLKINB	1		350	
$t_{PU}$	Power up time for all $V_{DDs}$ to reach minimum specified voltage (power ramps must be monotonic)	0.05		5	ms

Note:  $V_{DDO1}$  and  $V_{DDO2}$  must be powered on either before or simultaneously with  $V_{DDD}$ ,  $V_{DDA}$  and  $V_{DDO0}$ .

**Table 9: Input Capacitance, LVCMOS Output Impedance, and Internal Pull-down Resistance** ( $T_A = +25\text{ }^\circ\text{C}$ )

Symbol	Parameter	Min	Typ	Max	Unit
CIN	Input Capacitance (SD/OE, SEL1/SDA, SEL0/SCL)		3	7	pF
Pull-down Resistor		100		300	k $\Omega$
ROUT	LVCMOS Output Driver Impedance (VDDO = 1.8V, 2.5V, 3.3V)		17		$\Omega$
XIN/REF	Programmable capacitance at XIN/REF	9		25	pF
XOUT	Programmable capacitance at XOUT	9		25	pF

**Table 10: Crystal Characteristics**

Parameter	Test Conditions	Minimum	Typical	Maximum	Units
Mode of Oscillation		Fundamental			
Frequency		8	25	40	MHz
Equivalent Series Resistance (ESR)			10	100	$\Omega$
Shunt Capacitance				7	pF
Load Capacitance (CL) @ $\leq 25$ MHz		6	8	12	pF
Load Capacitance (CL) $> 25$ MHz to 40 MHz		6		8	pF
Maximum Crystal Drive Level				100	$\mu\text{W}$

Note: Typical crystal used is [IDT 603-25-150](#) or [FOX 603-25-150](#). For different reference crystal options please go to [www.foxonline.com](http://www.foxonline.com).

**Table 11: DC Electrical Characteristics**

Symbol	Parameter	Test Conditions	Min	Typ	Max	Unit
Iddcore <sup>3</sup>	Core Supply Current	100 MHz on all outputs, 25 MHz REFCLK		4	5	mA
Iddox	Output Buffer Supply Current	LVPECL, 350 MHz, 3.3V VDDOx		35	37	mA
		LVPECL, 350 MHz, 2.5V VDDOx		33	35	mA
		LVDS, 350 MHz, 3.3V VDDOx		8	9	mA
		LVDS, 350 MHz, 2.5V VDDOx		7	8	mA
		LVDS, 350 MHz, 1.8V VDDOx		6	7	mA
		HCSL, 250 MHz, 3.3V VDDOx, 2 pF load		22	23	mA
		HCSL, 250 MHz, 2.5V VDDOx, 2 pF load		20	22	mA
		LVCMOS, 50 MHz, 3.3V, VDDOx <sup>1,2</sup>		5	6	mA
		LVCMOS, 50 MHz, 2.5V, VDDOx <sup>1,2</sup>		4	5	mA
		LVCMOS, 50 MHz, 1.8V, VDDOx <sup>1,2</sup>		3	4	mA
		LVCMOS, 200 MHz, 3.3V VDDOx <sup>1</sup>		17	18	mA
		LVCMOS, 200 MHz, 2.5V VDDOx <sup>1,2</sup>		12	13	mA
LVCMOS, 200 MHz, 1.8V VDDOx <sup>1,2</sup>		9	10	mA		
Iddpd	Power Down Current	SD asserted, I2C Programming		5	6	mA

1. Single CMOS driver active.

2. Measured into a 5" 50 Ohm trace with 2 pF load.

3. Iddcore = IddA + IddD, no loads.

**Table 12: Electrical Characteristics – Differential Clock Input Parameters** <sup>1,2</sup> (Supply Voltage  $V_{DDA}$ ,  $V_{DDD}$ ,  $V_{DDO0}$  = 3.3V  $\pm$ 5%, 2.5V  $\pm$ 5%, 1.8V  $\pm$ 5%,  $T_A$  = -40°C to +85°C)

Symbol	Parameter	Test Conditions	Min	Typ	Max	Unit
$V_{IH}$	Input HIGH Voltage–CLKIN, CLKINB	Single-ended input	0.55		1.7	V
$V_{IL}$	Input LOW Voltage–CLKIN, CLKINB	Single-ended input	GND - 0.3		0.4	V
$V_{SWING}$	Input Amplitude - CLKIN, CLKINB	Peak to Peak value, single-ended	200		1200	mV
dv/dt	Input Slew Rate - CLKIN, CLKINB	Measured differentially	0.4		8	V/ns
$I_{IL}$	Input Leakage Low Current	$V_{IN} = \text{GND}$	-5		5	$\mu\text{A}$
$I_{IH}$	Input Leakage High Current	$V_{IN} = 1.7\text{V}$			20	$\mu\text{A}$
$d_{TIN}$	Input Duty Cycle	Measurement from differential waveform	45		55	%

1. Guaranteed by design and characterization, not 100% tested in production.

2. Slew rate measured through  $\pm 75\text{mV}$  window centered around differential zero.

**Table 13: DC Electrical Characteristics for 3.3V LVCMOS** ( $V_{DDO} = 3.3\text{V} \pm 5\%$ ,  $T_A = -40^\circ\text{C}$  to  $+85^\circ\text{C}$ ) <sup>1</sup>

Symbol	Parameter	Test Conditions	Min	Typ	Max	Unit
$V_{OH}$	Output HIGH Voltage	$I_{OH} = -15\text{mA}$	2.4		$V_{DDO}$	V
$V_{OL}$	Output LOW Voltage	$I_{OL} = 15\text{mA}$			0.4	V
$I_{OZDD}$	Output Leakage Current (OUT1~4)	Tri-state outputs, $V_{DDO} = 3.465\text{V}$			5	$\mu\text{A}$
$I_{OZDD}$	Output Leakage Current (OUT0)	Tri-state outputs, $V_{DDO} = 3.465\text{V}$			30	$\mu\text{A}$
$V_{IH}$	Input HIGH Voltage	Single-ended inputs - CLKSEL, SD/OE	$0.7 \times V_{DDD}$		$V_{DDD} + 0.3$	V
$V_{IL}$	Input LOW Voltage	Single-ended inputs - CLKSEL, SD/OE	GND - 0.3		$0.3 \times V_{DDD}$	V
$V_{IH}$	Input HIGH Voltage	Single-ended input OUT0_SEL_I2CB	2		$V_{DDO0} + 0.3$	V
$V_{IL}$	Input LOW Voltage	Single-ended input OUT0_SEL_I2CB	GND - 0.3		0.4	V
$V_{IH}$	Input HIGH Voltage	Single-ended input - XIN/REF	0.8		1.2	V
$V_{IL}$	Input LOW Voltage	Single-ended input - XIN/REF	GND - 0.3		0.4	V
$T_R/T_F$	Input Rise/Fall Time	CLKSEL, SD/OE, SEL1/SDA, SEL0/SCL			300	nS

1. See "Recommended Operating Conditions" table.

**Table 14: DC Electrical Characteristics for 2.5V LVCMOS** ( $V_{DDO} = 2.5V \pm 5\%$ ,  $T_A = -40^\circ\text{C}$  to  $+85^\circ\text{C}$ )

Symbol	Parameter	Test Conditions	Min	Typ	Max	Unit
VOH	Output HIGH Voltage	IOH = -12mA	0.7xVDDO		VDDD + 0.3	V
VOL	Output LOW Voltage	IOL = 12mA			0.4	V
IOZDD	Output Leakage Current	Tri-state outputs, VDDO = 2.625V			5	$\mu\text{A}$
VOH	Output HIGH Voltage	IOH = -12mA, OUT0	0.6 xVDDO		VDDD + 0.3	V
VOL	Output LOW Voltage	IOL = 12mA, OUT0			0.4	V
IOZDD	Output Leakage Current	Tri-state outputs, VDDO = 2.625V, OUT0			30	$\mu\text{A}$
VIH	Input HIGH Voltage	Single-ended inputs - CLKSEL, SD/OE	0.7xVDDD		VDDD + 0.3	V
VIL	Input LOW Voltage	Single-ended inputs - CLKSEL, SD/OE	GND - 0.3		0.3xVDDD	V
VIH	Input HIGH Voltage	Single-ended input OUT0_SEL_I2CB	1.7		VDDO0 + 0.35	V
VIL	Input LOW Voltage	Single-ended input OUT0_SEL_I2CB	GND - 0.3		0.4	V
VIH	Input HIGH Voltage	Single-ended input - XIN/REF	0.8		1.2	V
VIL	Input LOW Voltage	Single-ended input - XIN/REF	GND - 0.3		0.4	V
TR/TF	Input Rise/Fall Time	CLKSEL, SD/OE, SEL1/SDA, SEL0/SCL			300	nS

**Table 15: DC Electrical Characteristics for 1.8V LVCMOS** ( $V_{DDO} = 1.8V \pm 5\%$ ,  $T_A = -40^\circ\text{C}$  to  $+85^\circ\text{C}$ )

Symbol	Parameter	Test Conditions	Min	Typ	Max	Unit
VOH	Output HIGH Voltage	IOH = -8mA	0.7 xVDDO		VDDO	V
VOL	Output LOW Voltage	IOL = 8mA			0.25 x VDDO	V
IOZDD	Output Leakage Current	Tri-state outputs, VDDO = 3.465V			5	$\mu\text{A}$
VOH	Output HIGH Voltage	IOH = -8mA, OUT0	0.6 xVDDO		VDDO	V
VOL	Output LOW Voltage	IOL = 8mA, OUT0			0.25 x VDDO	V
IOZDD	Output Leakage Current	Tri-state outputs, VDDO = 3.465V, OUT0			30	$\mu\text{A}$
VIH	Input HIGH Voltage	Single-ended inputs - CLKSEL, SD/OE	0.7 * VDDD		VDDD + 0.3	V
VIL	Input LOW Voltage	Single-ended inputs - CLKSEL, SD/OE	GND - 0.3		0.3 * VDDD	V
VIH	Input HIGH Voltage	Single-ended input OUT0_SEL_I2CB	0.65 * VDDO0		VDDO0 + 0.3	V
VIL	Input LOW Voltage	Single-ended input OUT0_SEL_I2CB	GND - 0.3		0.4	V
VIH	Input HIGH Voltage	Single-ended input - XIN/REF	0.8		1.2	V
VIL	Input LOW Voltage	Single-ended input - XIN/REF	GND - 0.3		0.4	V
TR/TF	Input Rise/Fall Time	CLKSEL, SD/OE, SEL1/SDA, SEL0/SCL			300	nS

**Table 16: DC Electrical Characteristics for LVDS** ( $V_{DDO} = 3.3V \pm 5\%$  or  $2.5V \pm 5\%$ ,  $T_A = -40^\circ\text{C}$  to  $+85^\circ\text{C}$ )

Symbol	Parameter	Min	Typ	Max	Unit
$V_{OT}(+)$	Differential Output Voltage for the TRUE binary state	247		454	mV
$V_{OT}(-)$	Differential Output Voltage for the FALSE binary state	-247		-454	mV
$\Delta V_{OT}$	Change in $V_{OT}$ between Complimentary Output States			50	mV
$V_{OS}$	Output Common Mode Voltage (Offset Voltage)	1.125	1.25	1.375	V
$\Delta V_{OS}$	Change in $V_{OS}$ between Complimentary Output States			50	mV
$I_{OS}$	Outputs Short Circuit Current, $V_{OUT+}$ or $V_{OUT-} = 0V$ or $V_{DDO}$		9	24	mA
$I_{OSD}$	Differential Outputs Short Circuit Current, $V_{OUT+} = V_{OUT-}$		6	12	mA

**Table 17: DC Electrical Characteristics for LVDS** ( $V_{DDO} = 1.8V \pm 5\%$ ,  $T_A = -40^\circ\text{C}$  to  $+85^\circ\text{C}$ )

Symbol	Parameter	Min	Typ	Max	Unit
$V_{OT}(+)$	Differential Output Voltage for the TRUE binary state	247		454	mV
$V_{OT}(-)$	Differential Output Voltage for the FALSE binary state	-247		-454	mV
$\Delta V_{OT}$	Change in $V_{OT}$ between Complimentary Output States			50	mV
$V_{OS}$	Output Common Mode Voltage (Offset Voltage)	0.8	0.875	0.95	V
$\Delta V_{OS}$	Change in $V_{OS}$ between Complimentary Output States			50	mV
$I_{OS}$	Outputs Short Circuit Current, $V_{OUT+}$ or $V_{OUT-} = 0V$ or $V_{DDO}$		9	24	mA
$I_{OSD}$	Differential Outputs Short Circuit Current, $V_{OUT+} = V_{OUT-}$		6	12	mA

**Table 18: DC Electrical Characteristics for LVPECL** ( $V_{DDO} = 3.3V \pm 5\%$  or  $2.5V \pm 5\%$ ,  $T_A = -40^\circ\text{C}$  to  $+85^\circ\text{C}$ )

Symbol	Parameter	Min	Typ	Max	Unit
$V_{OH}$	Output Voltage HIGH, terminated through $50\Omega$ tied to $V_{DD} - 2V$	$V_{DDO} - 1.19$		$V_{DDO} - 0.69$	V
$V_{OL}$	Output Voltage LOW, terminated through $50\Omega$ tied to $V_{DD} - 2V$	$V_{DDO} - 1.94$		$V_{DDO} - 1.4$	V
$V_{SWING}$	Peak-to-Peak Output Voltage Swing	0.55		0.993	V

**Table 19: Electrical Characteristics – DIF 0.7V Low Power HCSL Differential Outputs**( $V_{DDO} = 3.3V \pm 5\%$ ,  $2.5V \pm 5\%$ ,  $T_A = -40^\circ\text{C}$  to  $+85^\circ\text{C}$ )

Symbol	Parameter	Conditions	Min	Typ	Max	Units	Notes
dV/dt	Slew Rate	Scope averaging on	1		4	V/ns	1,2,3
$V_{HIGH}$	Voltage High	Statistical measurement on single-ended signal using oscilloscope math function (Scope averaging ON)	660		850	mV	1,6,7
$V_{LOW}$	Voltage Low		-150		150	mV	1,6
$V_{MAX}$	Maximum Voltage	Measurement on single-ended signal using absolute value (Scope averaging off)			1150	mV	1
$V_{MIN}$	Minimum Voltage		-300			mV	1
$V_{SWING}$	Voltage Swing	Scope averaging off	300			mV	1,2,6
$V_{CROSS}$	Crossing Voltage Value	Scope averaging off	250		550	mV	1,4,6
$\Delta V_{CROSS}$	Crossing Voltage Variation	Scope averaging off			140	mV	1,5

1. Guaranteed by design and characterization. Not 100% tested in production

2. Measured from differential waveform.

3. Slew rate is measured through the  $V_{SWING}$  voltage range centered around differential 0V. This results in a +/-150mV window around differential 0V.4.  $V_{CROSS}$  is defined as voltage where Clock = Clock# measured on a component test board and only applies to the differential rising edge (i.e. Clock rising and Clock# falling).5. The total variation of all  $V_{CROSS}$  measurements in any particular system. Note that this is a subset of  $V_{CROSS}$  min/max ( $V_{CROSS}$  absolute) allowed. The intent is to limit  $V_{CROSS}$  induced modulation by setting  $\Delta V_{CROSS}$  to be smaller than  $V_{CROSS}$  absolute.

6. Measured from single-ended waveform.

7. Measured with scope averaging off, using statistics function. Variation is difference between min. and max.

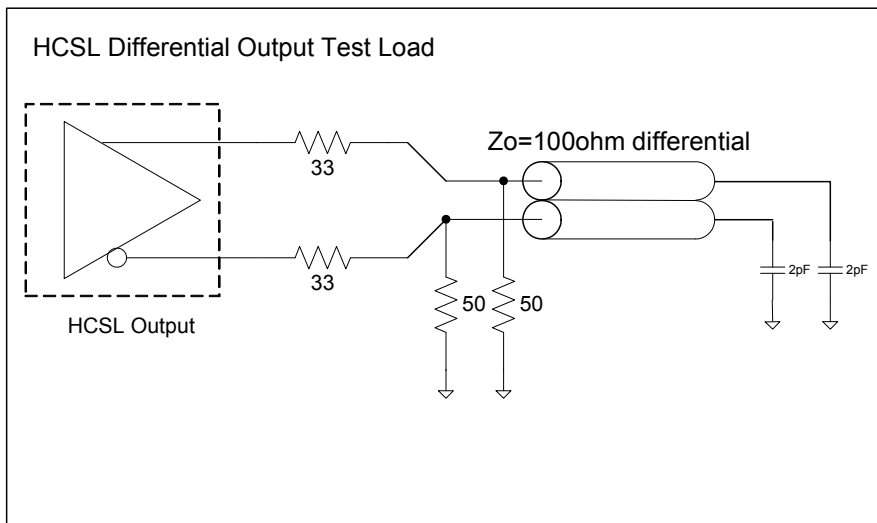
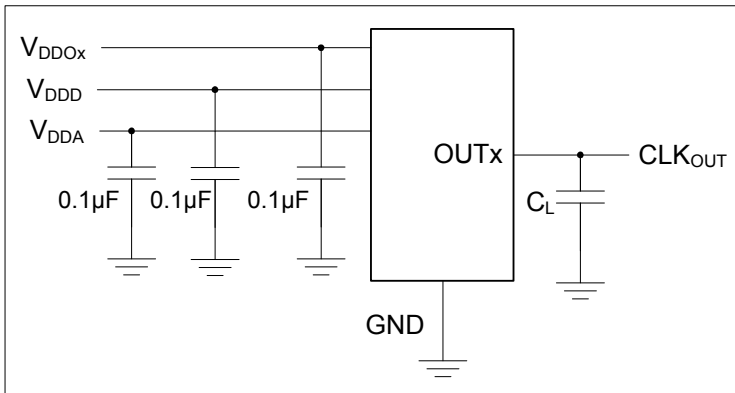
**Table 20: AC Timing Electrical Characteristics**

 (V<sub>DDO</sub> = 3.3V+5% or 2.5V+5% or 1.8V ±5%, TA = -40°C to +85°C)

(Spread Spectrum Generation = OFF)

Symbol	Parameter	Test Conditions	Min.	Typ.	Max.	Units
f <sub>IN</sub>	Input Frequency	Input frequency limit (XIN)	8		40	MHz
		Input frequency limit (REF)	1		200	MHz
		Input frequency limit (CLKIN, CLKINB)	1		350	MHz
f <sub>OUT</sub>	Output Frequency	Single ended clock output limit (LVCMOS)	1		200	MHz
		Differential clock output limit (LVPECL/ LVDS/HCSL)	1		350	
t <sub>2</sub>	Input Duty Cycle	Duty Cycle	45	50	55	%
t <sub>3</sub>	Output Duty Cycle Distortion	LVPECL Output Duty Cycle Distortion	-5		5	%
		LVPECL Output Duty Cycle Distortion	-5		5	%
		HCSL Output Duty Cycle Distortion	-5		5	%
		LVCMOS Output Duty Cycle Distortion @ 2.5V and 3.3V	-5		5	%
		LVCMOS Output Duty Cycle Distortion @ 1.8 V, f <100MHz	-5		5	%
		LVCMOS Output Duty Cycle Distortion @ 1.8 V, f >=100MHz	-10		10	%
t <sub>4</sub>	Slew Rate, SLEW[1:0] = 11	Single-ended 3.3V LVCMOS output clock rise and fall time, @ 125MHz 25% to 75% of VDDO (Output Load = 5 pF)	1.7	2.7	4.1	V/ns
	Slew Rate, SLEW[1:0] = 10	Single-ended 3.3V LVCMOS output clock rise and fall time, @ 125MHz 25% to 75% of VDDO (Output Load = 5 pF)	1.4	2.4	3.8	V/ns
	Slew Rate, SLEW[1:0] = 01	Single-ended 3.3V LVCMOS output clock rise and fall time, @ 125MHz 25% to 75% of VDDO (Output Load = 5 pF)	1.3	2.3	3.7	V/ns
	Slew Rate, SLEW[1:0] = 00	Single-ended 3.3V LVCMOS output clock rise and fall time, @ 125MHz 25% to 75% of VDDO (Output Load = 5 pF)	1.1	2.1	3.6	V/ns
	Slew Rate, SLEW[1:0] = 11	Single-ended 2.5V LVCMOS output clock rise and fall time, @ 125MHz 25% to 75% of VDDO (Output Load = 5 pF)	0.9	1.7	2.6	V/ns
	Slew Rate, SLEW[1:0] = 10	Single-ended 2.5V LVCMOS output clock rise and fall time, @ 125MHz 25% to 75% of VDDO (Output Load = 5 pF)	0.6	1.4	2.3	V/ns
	Slew Rate, SLEW[1:0] = 01	Single-ended 2.5V LVCMOS output clock rise and fall time, @ 125MHz 25% to 75% of VDDO (Output Load = 5 pF)	0.6	1.3	2.2	V/ns
	Slew Rate, SLEW[1:0] = 00	Single-ended 2.5V LVCMOS output clock rise and fall time, @ 125MHz 25% to 75% of VDDO (Output Load = 5 pF)	0.6	1.2	2.1	V/ns
	Slew Rate, SLEW[1:0] = 11	Single-ended 1.8V LVCMOS output clock rise and fall time, @ 125MHz 25% to 75% of VDDO (Output Load = 5 pF)	0.7	1.2	2.1	V/ns
	Slew Rate, SLEW[1:0] = 10	Single-ended 1.8V LVCMOS output clock rise and fall time, @ 125MHz 25% to 75% of VDDO (Output Load = 5 pF)	0.4	0.9	1.7	V/ns
	Slew Rate, SLEW[1:0] = 01	Single-ended 1.8V LVCMOS output clock rise and fall time, @ 125MHz 25% to 75% of VDDO (Output Load = 5 pF)	0.4	0.8	1.6	V/ns
	Slew Rate, SLEW[1:0] = 00	Single-ended 1.8V LVCMOS output clock rise and fall time, @ 125MHz 25% to 75% of VDDO (Output Load = 5 pF)	0.3	0.7	1.4	V/ns
	t <sub>5</sub>	Rise Times	LVDS, 20% to 80%, single-ended		300	
Fall Times		LVDS, 80% to 20%, single-ended		300		
Rise Times		LVPECL, 20% to 80%, single-ended		400		
Fall Times		LVPECL, 80% to 20%, single-ended		400		
t <sub>6</sub>	Buffer Additive Phase Jitter, RMS	f <sub>REF</sub> =125MHz, LVCMOS, V <sub>pp</sub> =1V, Integration range: 12kHz–20MHz		0.2		ps
t <sub>7</sub>	Output Skew	Skew between the same frequencies, with outputs using the same driver format and phase delay set to 0 ns.		35		ps
	Input to Output Skew	Skew from input to output		3		ns

## Test Circuits and Loads



## Test Circuits and Loads for Outputs



## 5P1103 Application Schematic

The following figure shows an example of 5P1103 application schematic. Input and output terminations shown are intended as examples only and may not represent the exact user configuration. In this example, the device is operated at  $V_{DD}, V_{DDA} = 3.3V$ . The decoupling capacitors should be located as close as possible to the power pin. A 12pF parallel resonant 8MHz to 40MHz crystal is used in this example. Different crystal frequencies may be used. The  $C1 = C2 = 5pF$  are recommended for frequency accuracy. If different crystal types are used, please consult IDT for recommendations. For different board layout, the  $C1$  and  $C2$  may be slightly adjusted for optimizing frequency accuracy.

As with any high speed analog circuitry, the power supply pins are vulnerable to random noise. To achieve optimum jitter performance, power supply isolation is required. 5P1103 provides separate power supplies to isolate any high switching noise from coupling into the part.

In order to achieve the best possible filtering, it is recommended that the placement of the filter components be on the device side of the PCB as close to the power pins as possible. If space is limited, the 0.1uf capacitor in each power pin filter should be placed on the device side. The other components can be on the opposite side of the PCB.

Power supply filter recommendations are a general guideline to be used for reducing external noise from coupling into the devices. The filter performance is designed for a wide range of noise frequencies. This low-pass filter starts to attenuate noise at approximately 10 kHz. If a specific frequency noise component is known, such as switching power supply frequencies, it is recommended that component values be adjusted and if required, additional filtering be added. Additionally, good general design practices for power plane voltage stability suggests adding bulk capacitance in the local area of all devices.

The schematic example focuses on functional connections and is not configuration specific. Refer to the pin description and functional tables in the datasheet to ensure the logic control inputs are properly set.

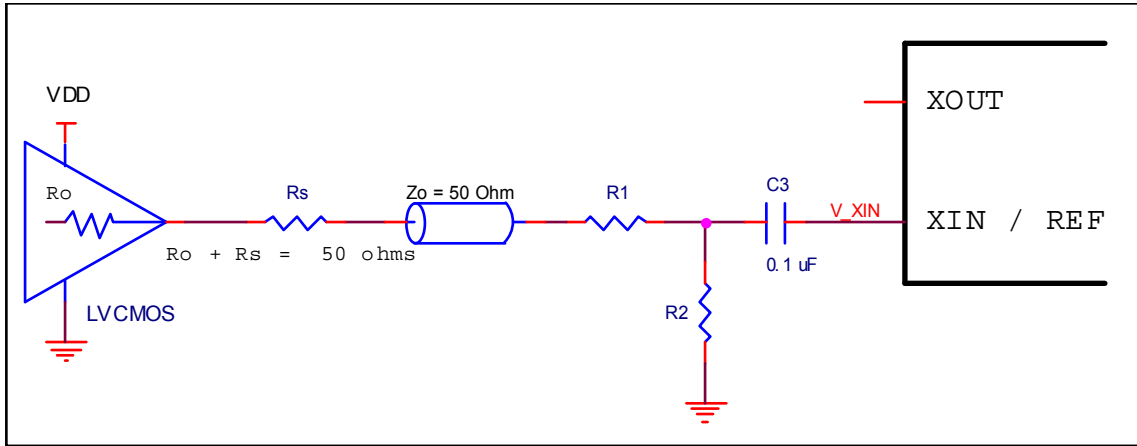


## Overdriving the XIN/REF Interface

### LVC MOS Driver

The XIN/REF input can be overdriven by an LVC MOS driver or by one side of a differential driver through an AC coupling capacitor. The XOUT pin can be left floating. The amplitude of the input signal should be between 500mV and 1.2V and the slew rate should not be less than 0.2V/ns. Figure General Diagram for LVC MOS Driver to XTAL Input Interface shows an example of the interface diagram for a LVC MOS driver.

This configuration has three properties; the total output impedance of  $R_o$  and  $R_s$  matches the 50 ohm transmission line impedance, the  $V_{rx}$  voltage is generated at the CLKIN inputs which maintains the LVC MOS driver voltage level across the transmission line for best S/N and the  $R_1$ - $R_2$  voltage divider values ensure that the clock level at XIN is less than the maximum value of 1.2V.



### General Diagram for LVC MOS Driver to XTAL Input Interface

Table 21 Nominal Voltage Divider Values vs LVC MOS VDD for XIN shows resistor values that ensure the maximum drive level for the XIN/REF port is not exceeded for all combinations of 5% tolerance on the driver VDD, the VDDA and 5% resistor

tolerances. The values of the resistors can be adjusted to reduce the loading for slower and weaker LVC MOS driver by increasing the voltage divider attenuation as long as the minimum drive level is maintained over all tolerances. To assist this assessment, the total load on the driver is included in the table.

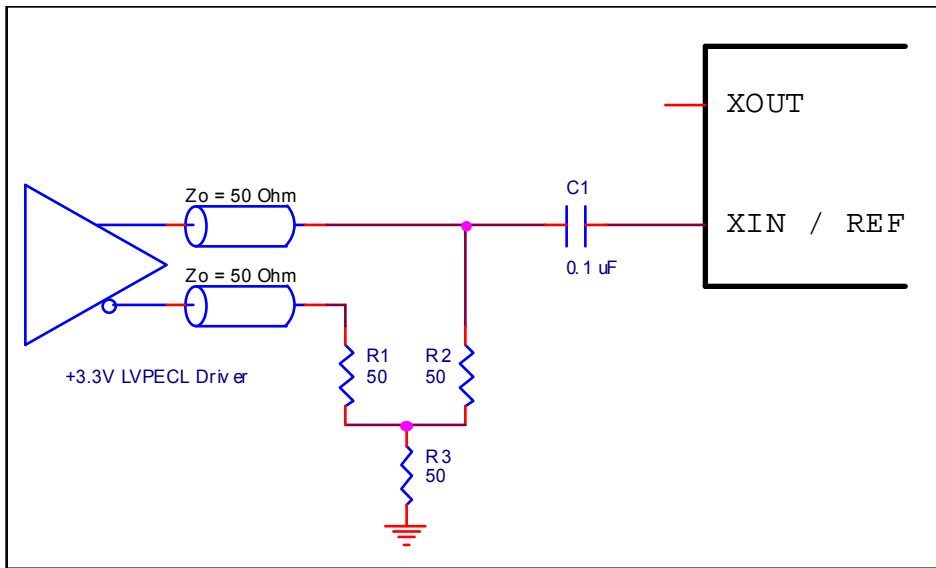
Table 21:Nominal Voltage Divider Values vs LVC MOS VDD for XIN

LVC MOS Driver VDD	$R_o+R_s$	$R_1$	$R_2$	$V_{XIN}$ (peak)	$R_o+R_s+R_1+R_2$
3.3	50.0	130	75	0.97	255
2.5	50.0	100	100	1.00	250
1.8	50.0	62	130	0.97	242

## LVPECL Driver

Figure General Diagram for LVPECL Driver to XTAL Input Interface shows an example of the interface diagram for a +3.3V LVPECL driver. This is a standard LVPECL termination with one side of the driver feeding the XIN/REF input. It is recommended that all components in the schematics be placed in the layout; though some components might not be

used, they can be utilized for debugging purposes. The datasheet specifications are characterized and guaranteed by using a quartz crystal as the input. If the driver is 2.5V LVPECL, the only change necessary is to use the appropriate value of R3.

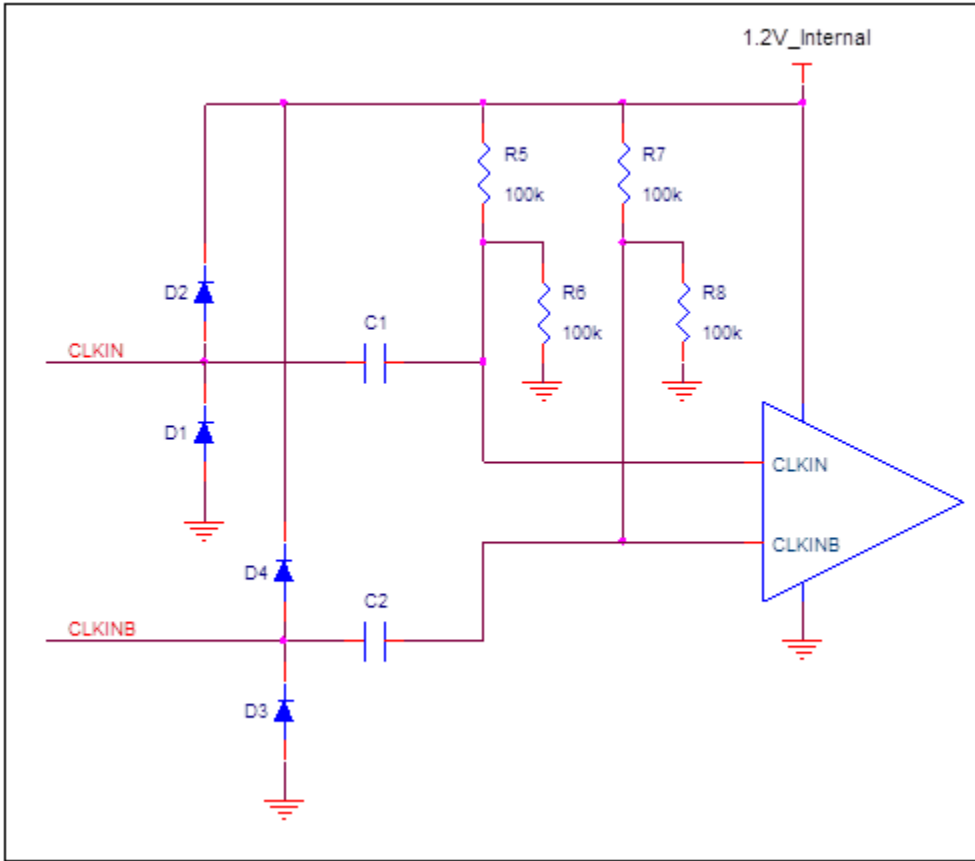


**General Diagram for +3.3V LVPECL Driver to XTAL Input Interface**

## CLKIN Equivalent Schematic

Figure *CLKIN Equivalent Schematic* below shows the basis of the requirements on VIH max, VIL min and the 1200 mV p-p single ended Vswing maximum.

- The CLKIN and CLKINB Vih max spec comes from the cathode voltage on the input ESD diodes D2 and D4, which are referenced to the internal 1.2V supply. CLKIN or CLKINB voltages greater than  $1.2\text{V} + 0.5\text{V} = 1.7\text{V}$  will be clamped by these diodes. CLKIN and CLKINB input voltages less than  $-0.3\text{V}$  will be clamped by diodes D1 and D3.
- The 1.2V p-p maximum Vswing input requirement is determined by the internally regulated 1.2V supply for the actual clock receiver. This is the basis of the Vswing spec in Table 13.

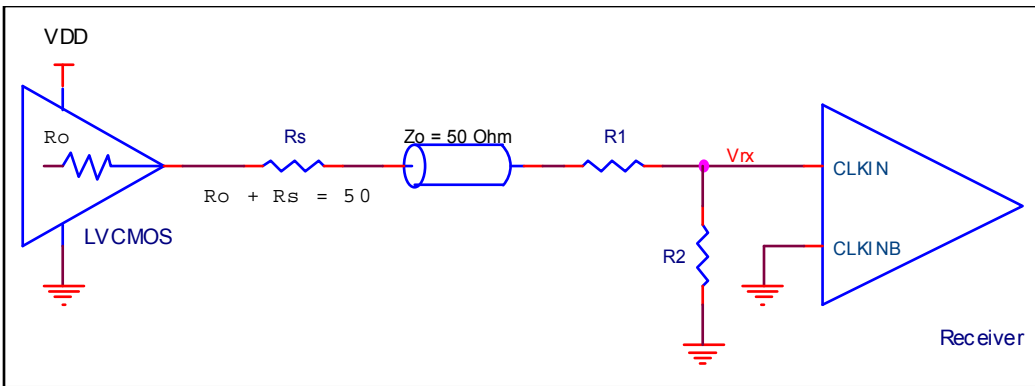


CLKIN Equivalent Schematic

### Wiring the Differential Input to Accept Single-Ended Levels

Figure *Recommended Schematic for Wiring a Differential Input to Accept Single-ended Levels* shows how a differential input can be wired to accept single ended levels. This configuration has three properties; the total output impedance of  $R_o$  and  $R_s$  matches the 50 ohm transmission line

impedance, the  $V_{rx}$  voltage is generated at the CLKIN inputs which maintains the LVCMOS driver voltage level across the transmission line for best S/N and the R1-R2 voltage divider values ensure that  $V_{rx}$  p-p at CLKIN is less than the maximum value of 1.2V.



Recommended Schematic for Wiring a Differential Input to Accept Single-ended Levels

**Table 22 Nominal Voltage Divider Values vs Driver VDD** shows resistor values that ensure the maximum drive level for the CLKIN port is not exceeded for all combinations of 5% tolerance on the driver VDD, the VDD0 and 5% resistor tolerances. The values of the resistors can be adjusted to

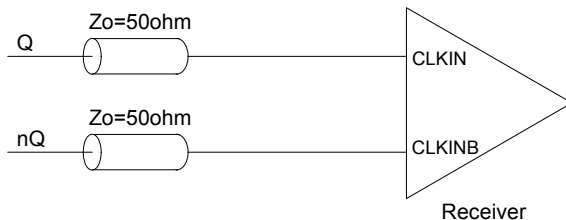
reduce the loading for slower and weaker LVCMOS driver by increasing the impedance of the R1-R2 divider. To assist this assessment, the total load on the driver is included in the table.

**Table 22:Nominal Voltage Divider Values vs Driver VDD**

LVCMOS Driver VDD	Ro+Rs	R1	R2	Vrx (peak)	Ro+Rs+R1+R2
3.3	50.0	130	75	0.97	255
2.5	50.0	100	100	1.00	250
1.8	50.0	62	130	0.97	242

## HCSL Differential Clock Input Interface

CLKIN/CLKINB will accept DC coupled HCSL signals.

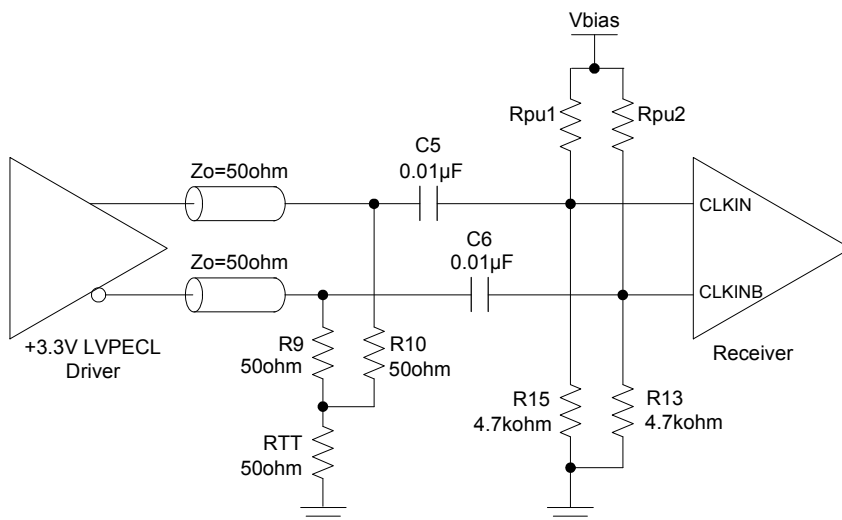


### CLKIN, CLKINB Input Driven by an HCSL Driver

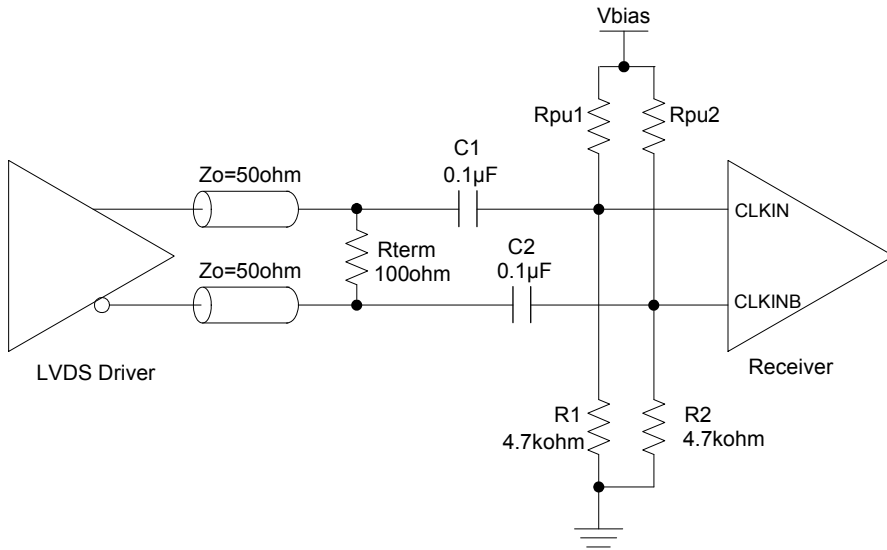
## 3.3V Differential LVPECL Clock Input Interface

The logic levels of 3.3V LVPECL and LVDS can exceed VIH max for the CLKIN/B pins. Therefore the LVPECL levels must be AC coupled to the differential input and the DC bias restored with external voltage dividers. A single table of bias

resistor values is provided below for both for 3.3V LVPECL and LVDS. Vbias can be VDDD, VDD0X or any other available voltage at the receiver that is most conveniently accessible in layout.



### CLKIN, CLKINB Input Driven by a 3.3V LVPECL Driver



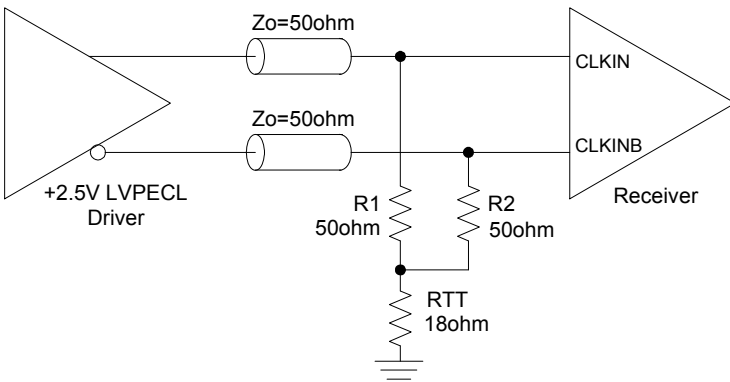
**CLKIN, CLKINB Input Driven by an LVDS Driver**

**Table 23: Bias Resistors for 3.3V LVPECL and LVDS Drive to CLKIN/B**

Vbias (V)	Rpu1/2 (kohm)	CLKIN/B Bias Voltage (V)
3.3	22	0.58
2.5	15	0.60
1.8	10	0.58

**2.5V Differential LVPECL Clock Input Interface**

The maximum DC 2.5V LVPECL voltage meets the VIH max CLKIN requirement. Therefore 2.5V LVPECL can be connected directly to the CLKIN terminals without AC coupling

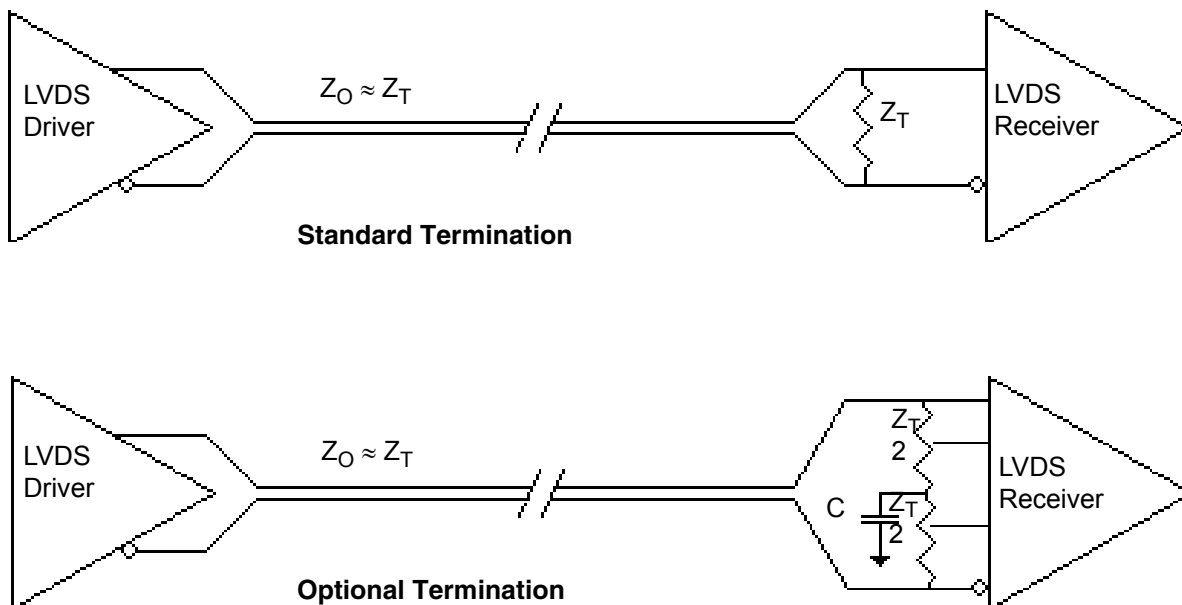


**CLKIN, CLKINB Input Driven by a 2.5V LVPECL Driver**

## LVDS Driver Termination

For a general LVDS interface, the recommended value for the termination impedance ( $Z_T$ ) is between  $90\Omega$  and  $132\Omega$ . The actual value should be selected to match the differential impedance ( $Z_0$ ) of your transmission line. A typical point-to-point LVDS design uses a  $100\Omega$  parallel resistor at the receiver and a  $100\Omega$  differential transmission-line environment. In order to avoid any transmission-line reflection issues, the components should be surface mounted and must be placed as close to the receiver as possible. The standard termination schematic as shown in figure *Standard Termination* or the termination of figure *Optional Termination* can be used, which uses a center tap capacitance to help filter

common mode noise. The capacitor value should be approximately  $50\text{pF}$ . In addition, since these outputs are LVDS compatible, the input receiver's amplitude and common-mode input range should be verified for compatibility with the IDT LVDS output. If using a non-standard termination, it is recommended to contact IDT and confirm that the termination will function as intended. For example, the LVDS outputs cannot be AC coupled by placing capacitors between the LVDS outputs and the  $100\text{ ohm}$  shunt load. If AC coupling is required, the coupling caps must be placed between the  $100\text{ ohm}$  shunt termination and the receiver. In this manner the termination of the LVDS output remains DC coupled

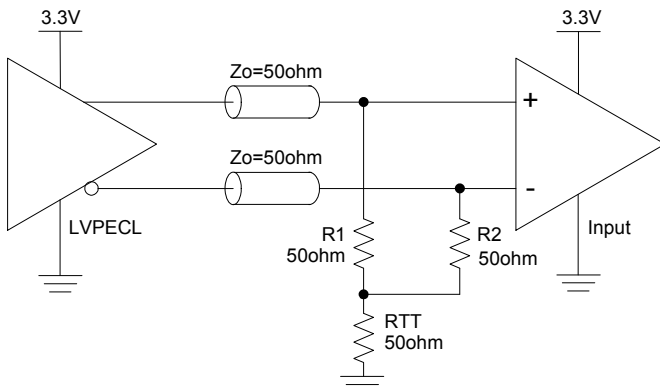




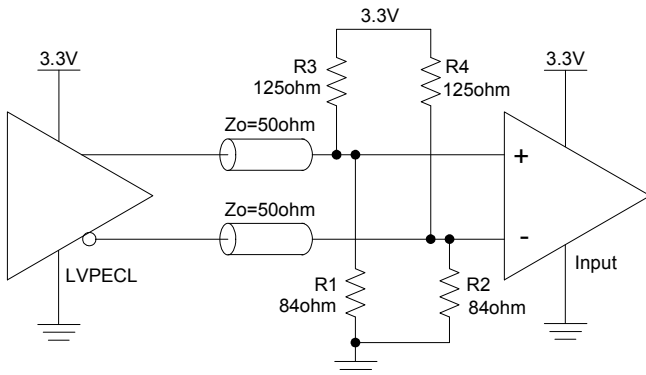
## Termination for 3.3V LVPECL Outputs

The clock layout topology shown below is a typical termination for LVPECL outputs. The two different layouts mentioned are recommended only as guidelines.

The differential outputs generate ECL/LVPECL compatible outputs. Therefore, terminating resistors (DC current path to ground) or current sources must be used for functionality. These outputs are designed to drive  $50\Omega$  transmission lines. Matched impedance techniques should be used to maximize operating frequency and minimize signal distortion. The figure below show two different layouts which are recommended only as guidelines. Other suitable clock layouts may exist and it would be recommended that the board designers simulate to guarantee compatibility across all printed circuit and clock component process variations.



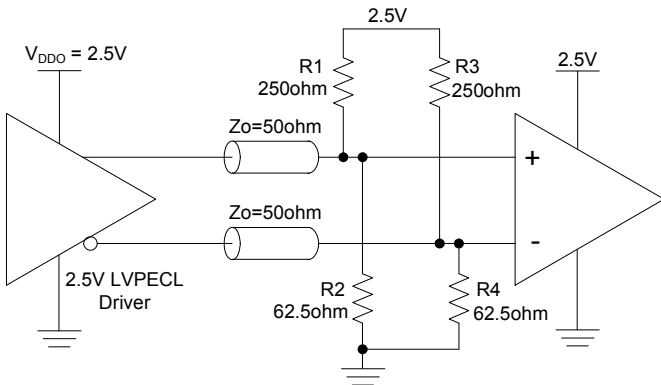
### 3.3V LVPECL Output Termination (1)



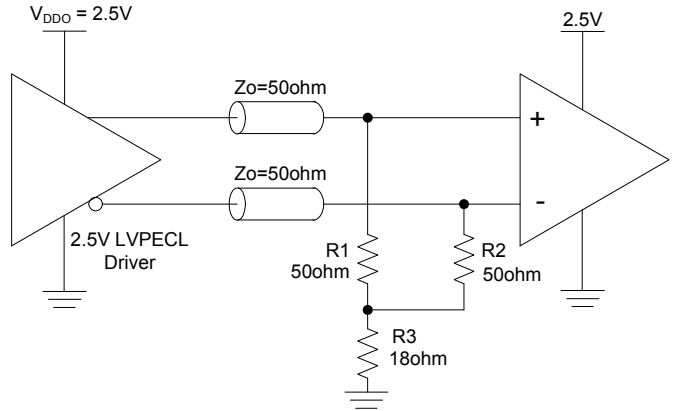
### 3.3V LVPECL Output Termination (2)

## Termination for 2.5V LVPECL Outputs

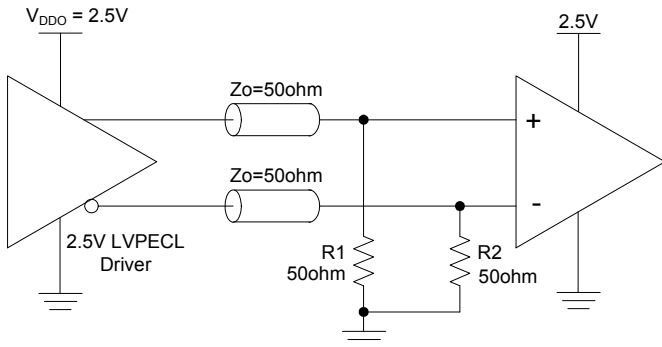
Figures 2.5V LVPECL Driver Termination Example (1) and (2) show examples of termination for 2.5V LVPECL driver. These terminations are equivalent to terminating  $50\Omega$  to  $V_{DDO} - 2V$ . For  $V_{DDO} = 2.5V$ , the  $V_{DDO} - 2V$  is very close to ground level. The R3 in Figure 2.5V LVPECL Driver Termination Example (3) can be eliminated and the termination is shown in example (2).



2.5V LVPECL Driver Termination Example (1)



2.5V LVPECL Driver Termination Example (3)



2.5V LVPECL Driver Termination Example (2)

## PCI Express Application Note

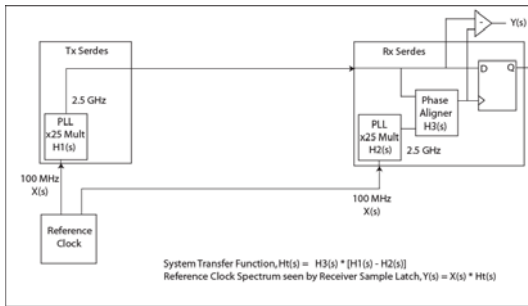
PCI Express jitter analysis methodology models the system response to reference clock jitter. The block diagram below shows the most frequently used Common Clock Architecture in which a copy of the reference clock is provided to both ends of the PCI Express Link. In the jitter analysis, the transmit (Tx) and receive (Rx) serdes PLLs are modeled as well as the phase interpolator in the receiver. These transfer functions are called H1, H2, and H3 respectively. The overall system transfer function at the receiver is:

$$H_t(s) = H_3(s) \times [H_1(s) - H_2(s)]$$

The jitter spectrum seen by the receiver is the result of applying this system transfer function to the clock spectrum X(s) and is:

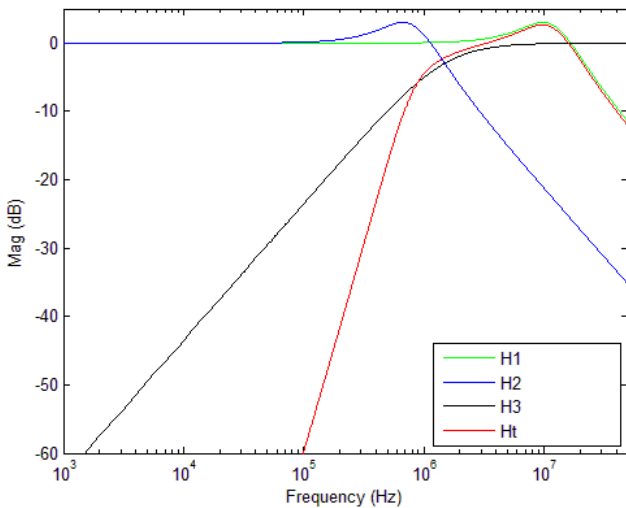
$$Y(s) = X(s) \times H_3(s) \times [H_1(s) - H_2(s)]$$

In order to generate time domain jitter numbers, an inverse Fourier Transform is performed on X(s)\*H3(s) \* [H1(s) - H2(s)].



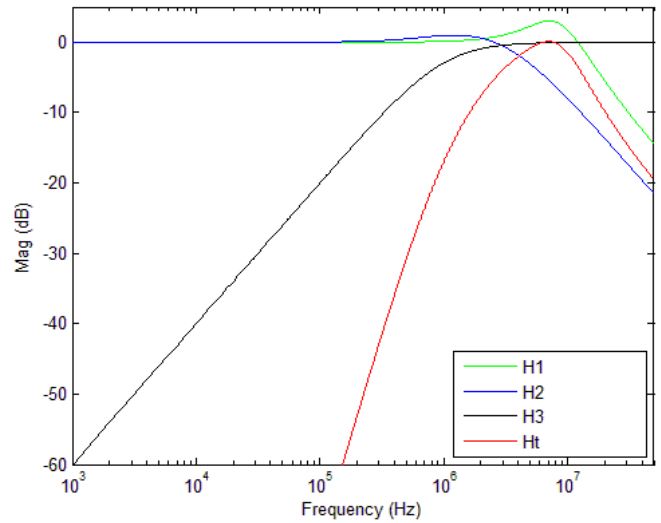
### PCI Express Common Clock Architecture

For PCI Express Gen 1, one transfer function is defined and the evaluation is performed over the entire spectrum: DC to Nyquist (e.g for a 100MHz reference clock: 0Hz – 50MHz) and the jitter result is reported in peak-peak.

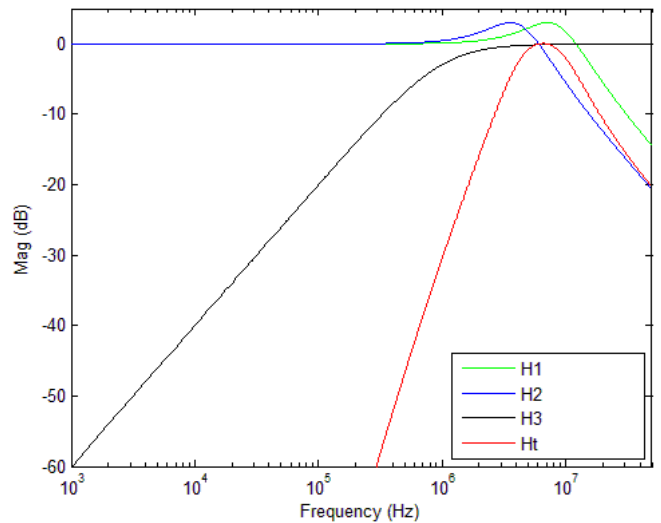


PCIe Gen1 Magnitude of Transfer Function

For PCI Express Gen2, two transfer functions are defined with 2 evaluation ranges and the final jitter number is reported in RMS. The two evaluation ranges for PCI Express Gen 2 are 10kHz – 1.5MHz (Low Band) and 1.5MHz – Nyquist (High Band). The plots show the individual transfer functions as well as the overall transfer function Ht.

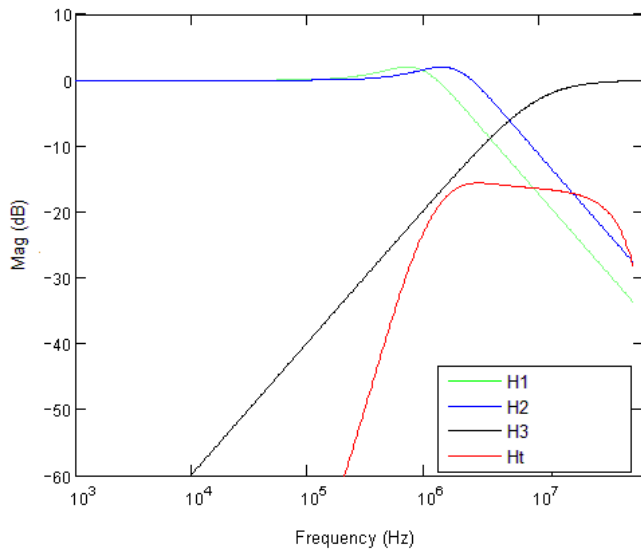


PCIe Gen2A Magnitude of Transfer Function



PCIe Gen2B Magnitude of Transfer Function

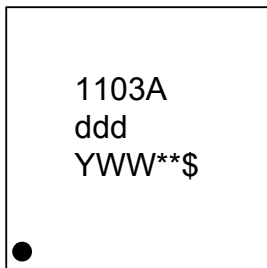
For PCI Express Gen 3, one transfer function is defined and the evaluation is performed over the entire spectrum. The transfer function parameters are different from Gen 1 and the jitter result is reported in RMS.



### PCIe Gen3 Magnitude of Transfer Function

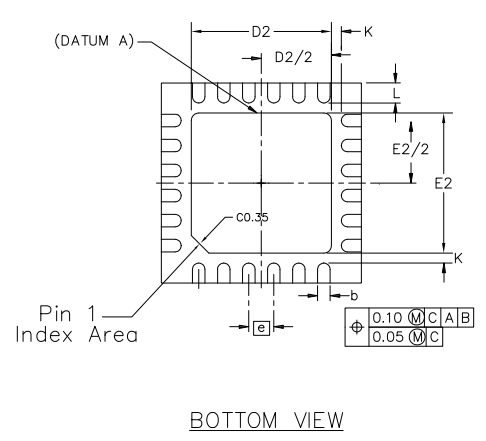
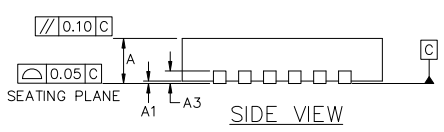
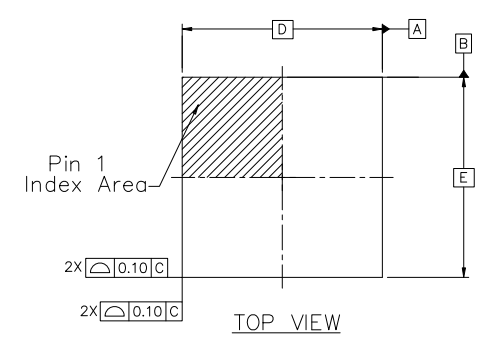
For a more thorough overview of PCI Express jitter analysis methodology, please refer to IDT Application Note PCI Express Reference Clock Requirements.

### Marking Diagram



1. Line 1 is the truncated part number.
2. "ddd" denotes dash code.
3. "YWW" is the last digit of the year and week that the part was assembled.
4. "\*\*" denotes sequential lot number.
5. "\$" denotes mark code.

REVISIONS			
REV	DESCRIPTION	DATE	APPROVED
00	INITIAL RELEASE	11/17/15	J.H
01	ADD CHAMFER	10/12/16	J.H



SYMBOL	DIMENSIONS		
	MIN.	NOM.	MAX.
A	0.80	0.90	1.00
A1	0.00	0.02	0.05
A3	0.20 REF		
K	0.20		
D	4.00 BSC		
E	4.00 BSC		
D2	2.70	2.80	2.90
E2	2.70	2.80	2.90
e	0.50 BSC		
L	0.30	0.40	0.50
b	0.18	0.25	0.30

- NOTES :
1. DIMENSIONING AND TOLERANCING CONFORME TO ASME Y14.5M - 1994.
  2. ALL DIMENSIONS ARE IN MILLIMETERS.

TOLERANCES UNLESS SPECIFIED		6024 Silver Creek Valley Road San Jose, CA 95138 PHONE: (408) 284-8200 www.IDT.com FAX: (408) 284-8591
DECIMAL	ANGULAR	
XX±	±	
XXX±		
XXXX±		
APPROVALS	DATE	TITLE
DRAWN <i>RAC</i>	11/17/15	NL/NLG24 PACKAGE OUTLINE
CHECKED		4.0 x 4.0 mm BODY
		0.5 mm PITCH QFN
	SIZE	DRAWING No.
	C	PSC-4192-02
		REV 01
DO NOT SCALE DRAWING		SHEET 1 OF 2



## Ordering Information

Part / Order Number	Marking	Shipping Packaging	Package	Temperature
5P1103AdddNLGI	see page 29	Trays	24-pin VFQFPN	-40° to +85°C
5P1103AdddNLGI8		Tape and Reel	24-pin VFQFPN	-40° to +85°C

Note: “ddd” denotes specific order codes.

“G” after the two-letter package code denotes Pb-Free configuration, RoHS compliant.

## Revision History

Rev.	Date	Originator	Description of Change
A	04/15/15	B. Chandhoke	Initial release.
B	04/30/15	B. Chandhoke	Replaced “clock buffer” with “fanout buffer” Removed “A” version letter from part number title header
C	06/19/15	B. Chandhoke	Removed the “Output Divides” section.
D	07/13/15	B. Chandhoke	1. Added conditions text and min/max values for VIH/VIL. 2. Updated 1.8V, 2.5V, and 3.3V VIH/VIL conditions text and min/max values for “Single-ended inputs - CLKSEL, SD/OE” 3. Added IDT and Fox crystal references.



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