

FEATURES

- 10 kΩ and 100 kΩ resistance options
- Resistor tolerance: 8% maximum
- Wiper current: ±6 mA
- Low temperature coefficient: 35 ppm/°C
- Wide bandwidth: 3 MHz
- Fast start-up time < 75 μs
- Linear gain setting mode
- Single- and dual-supply operation
- Wide operating temperature: -40°C to +125°C
- 3 mm × 3 mm package

APPLICATIONS

- Portable electronics level adjustment
- LCD panel brightness and contrast controls
- Programmable filters, delays, and time constants
- Programmable power supplies

FUNCTIONAL BLOCK DIAGRAM

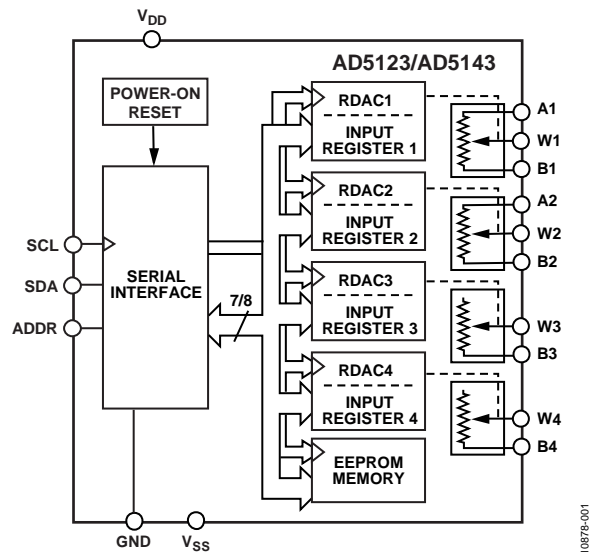


Figure 1.

GENERAL DESCRIPTION

The AD5123/AD5143 potentiometers provide a nonvolatile solution for 128-/256-position adjustment applications, offering guaranteed low resistor tolerance errors of ±8% and up to ±6 mA current density in the Ax, Bx, and Wx pins.

The low resistor tolerance and low nominal temperature coefficient simplify open-loop applications as well as applications requiring tolerance matching.

The linear gain setting mode allows independent programming of the resistance between the digital potentiometer terminals, through the R_{AW} and R_{WB} string resistors, allowing very accurate resistor matching.

The high bandwidth and low total harmonic distortion (THD) ensure optimal performance for ac signals, making the devices suitable for filter design.

The low wiper resistance of only 40 Ω at the ends of the resistor array allows for pin to pin connection.

The wiper values can be set through an I²C-compatible digital interface that also reads back the wiper register and EEPROM contents.

The AD5123/AD5143 are available in a compact, 16-lead, 3 mm × 3 mm LFCSP. The devices are guaranteed to operate over the extended industrial temperature range of -40°C to +125°C.

Table 1. Family Models

| Model | Channel | Position | Interface | Package |
|---------------------|---------|----------|----------------------|-------------|
| AD5123 ¹ | Quad | 128 | I ² C | LFCSP |
| AD5124 | Quad | 128 | SPI/I ² C | LFCSP |
| AD5124 | Quad | 128 | SPI | TSSOP |
| AD5143 | Quad | 256 | I ² C | LFCSP |
| AD5144 | Quad | 256 | SPI/I ² C | LFCSP |
| AD5144 | Quad | 256 | SPI | TSSOP |
| AD5144A | Quad | 256 | I ² C | TSSOP |
| AD5122 | Dual | 128 | SPI | LFCSP/TSSOP |
| AD5122A | Dual | 128 | I ² C | LFCSP/TSSOP |
| AD5142 | Dual | 256 | SPI | LFCSP/TSSOP |
| AD5142A | Dual | 256 | I ² C | LFCSP/TSSOP |
| AD5121 | Single | 128 | SPI/I ² C | LFCSP |
| AD5141 | Single | 256 | SPI/I ² C | LFCSP |

¹ Two potentiometers and two rheostats.

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REVISION HISTORY

2/16—Rev. A to Rev. B

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3/13—Rev. 0 to Rev. A

| | |
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10/12—Revision 0: Initial Version

SPECIFICATIONS

ELECTRICAL CHARACTERISTICS—AD5123

$V_{DD} = 2.3 \text{ V to } 5.5 \text{ V}$, $V_{SS} = 0 \text{ V}$; $V_{DD} = 2.25 \text{ V to } 2.75 \text{ V}$, $V_{SS} = -2.25 \text{ V to } -2.75 \text{ V}$; $-40^\circ\text{C} < T_A < +125^\circ\text{C}$, unless otherwise noted.

Table 2.

| Parameter | Symbol | Test Conditions/Comments | Min | Typ ¹ | Max | Unit |
|---|---|--|-------|------------------|-------|----------|
| DC CHARACTERISTICS—RHEOSTAT MODE (ALL RDACs) | | | | | | |
| Resolution | N | | 7 | | | Bits |
| Resistor Integral Nonlinearity ² | R-INL | $R_{AB} = 10 \text{ k}\Omega$ $V_{DD} \geq 2.7 \text{ V}$ | -1 | ± 0.1 | +1 | LSB |
| | | $V_{DD} < 2.7 \text{ V}$ $R_{AB} = 100 \text{ k}\Omega$ | -2.5 | ± 1 | +2.5 | LSB |
| Resistor Differential Nonlinearity ² | R-DNL | $V_{DD} \geq 2.7 \text{ V}$ | -0.5 | ± 0.1 | +0.5 | LSB |
| | | $V_{DD} < 2.7 \text{ V}$ | -1 | ± 0.25 | +1 | LSB |
| Nominal Resistor Tolerance | $\Delta R_{AB}/R_{AB}$ | | -8 | ± 1 | +8 | % |
| Resistance Temperature Coefficient ³ | $(\Delta R_{AB}/R_{AB})/\Delta T \times 10^6$ | Code = full scale | | 35 | | ppm/°C |
| Wiper Resistance ³ | R_W | Code = zero scale $R_{AB} = 10 \text{ k}\Omega$ | | 55 | 125 | Ω |
| | | $R_{AB} = 100 \text{ k}\Omega$ | | 130 | 400 | Ω |
| Bottom Scale or Top Scale | R_{BS} or R_{TS} | $R_{AB} = 10 \text{ k}\Omega$ | | 40 | 80 | Ω |
| | | $R_{AB} = 100 \text{ k}\Omega$ | | 60 | 230 | Ω |
| Nominal Resistance Match | R_{AB1}/R_{AB2} | Code = 0xFF | -1 | ± 0.2 | +1 | % |
| DC CHARACTERISTICS—POTENTIOMETER DIVIDER MODE (ALL RDACs) | | | | | | |
| Integral Nonlinearity ⁴ | INL | $R_{AB} = 10 \text{ k}\Omega$ | -0.5 | ± 0.1 | +0.5 | LSB |
| | | $R_{AB} = 100 \text{ k}\Omega$ | -0.25 | ± 0.1 | +0.25 | LSB |
| Differential Nonlinearity ⁴ | DNL | | -0.25 | ± 0.1 | +0.25 | LSB |
| | | | | | | |
| Full-Scale Error | V_{WFSE} | $R_{AB} = 10 \text{ k}\Omega$ | -1.5 | -0.1 | | LSB |
| | | $R_{AB} = 100 \text{ k}\Omega$ | -0.5 | ± 0.1 | +0.5 | LSB |
| Zero-Scale Error | V_{WZSE} | $R_{AB} = 10 \text{ k}\Omega$ | | 1 | 1.5 | LSB |
| | | $R_{AB} = 100 \text{ k}\Omega$ | | 0.25 | 0.5 | LSB |
| Voltage Divider Temperature Coefficient ³ | $(\Delta V_W/V_W)/\Delta T \times 10^6$ | Code = half scale | | ± 5 | | ppm/°C |

| Parameter | Symbol | Test Conditions/Comments | Min | Typ ¹ | Max | Unit |
|--|------------------------------|---|---------------------|---------------------|---------------------|---------------------|
| RESISTOR TERMINALS | | | | | | |
| Maximum Continuous Current | $I_A, I_B, \text{ and } I_W$ | $R_{AB} = 10 \text{ k}\Omega$ $R_{AB} = 100 \text{ k}\Omega$ | -6 -1.5 | | +6 +1.5 | mA mA |
| Terminal Voltage Range ⁵ Capacitance A, Capacitance B ³ | C_A, C_B | $f = 1 \text{ MHz, measured to GND, code = half scale}$ $R_{AB} = 10 \text{ k}\Omega$ $R_{AB} = 100 \text{ k}\Omega$ | V_{SS} | | V_{DD} | V pF pF |
| Capacitance W ³ | C_W | $f = 1 \text{ MHz, measured to GND, code = half scale}$ $R_{AB} = 10 \text{ k}\Omega$ $R_{AB} = 100 \text{ k}\Omega$ | | 25 12 | | pF pF |
| Common-Mode Leakage Current ³ | | $f = 1 \text{ MHz, measured to GND, code = half scale}$ $R_{AB} = 10 \text{ k}\Omega$ $R_{AB} = 100 \text{ k}\Omega$ $V_A = V_W = V_B$ | -500 | 12 5 ± 15 | +500 | pF pF nA |
| DIGITAL INPUTS | | | | | | |
| Input Logic ³ High | V_{INH} | | $0.7 \times V_{DD}$ | | | V |
| Low | V_{INL} | | | | $0.2 \times V_{DD}$ | V |
| Input Hysteresis ³ | V_{HYST} | | $0.1 \times V_{DD}$ | | | V |
| Input Current ³ | I_{IN} | | | | ± 1 | μA |
| Input Capacitance ³ | C_{IN} | | | 5 | | pF |
| DIGITAL OUTPUTS | | | | | | |
| Output High Voltage ³ | V_{OH} | $R_{PULL-UP} = 2.2 \text{ k}\Omega \text{ to } V_{DD}$ | | V_{DD} | | V |
| Output Low Voltage ³ | V_{OL} | $I_{SINK} = 3 \text{ mA}$ $I_{SINK} = 6 \text{ mA}$ | | | 0.4 0.6 | V V |
| Three-State Leakage Current | | | -1 | | +1 | μA |
| Three-State Output Capacitance | | | | 2 | | pF |
| POWER SUPPLIES | | | | | | |
| Single-Supply Power Range | | $V_{SS} = \text{GND}$ | 2.3 | | 5.5 | V |
| Dual-Supply Power Range | | | ± 2.25 | | ± 2.75 | V |
| Positive Supply Current | I_{DD} | $V_{IH} = V_{DD} \text{ or } V_{IL} = \text{GND}$ $V_{DD} = 5.5 \text{ V}$ $V_{DD} = 2.3 \text{ V}$ | | 0.7 400 | 5.5 | μA nA |
| Negative Supply Current | I_{SS} | $V_{IH} = V_{DD} \text{ or } V_{IL} = \text{GND}$ | -5.5 | -0.7 | | μA |
| EEPROM Store Current ^{3, 6} | $I_{DD_EEPROM_STORE}$ | $V_{IH} = V_{DD} \text{ or } V_{IL} = \text{GND}$ | | 2 | | mA |
| EEPROM Read Current ^{3, 7} | $I_{DD_EEPROM_READ}$ | $V_{IH} = V_{DD} \text{ or } V_{IL} = \text{GND}$ | | 320 | | μA |
| Power Dissipation ⁸ | P_{DISS} | $V_{IH} = V_{DD} \text{ or } V_{IL} = \text{GND}$ | | 3.5 | | μW |
| Power Supply Rejection Ratio | PSRR | $\Delta V_{DD}/\Delta V_{SS} = V_{DD} \pm 10\%$, code = full scale | | -66 | -60 | dB |

| Parameter | Symbol | Test Conditions/Comments | Min | Typ ¹ | Max | Unit |
|---|-------------|---|-----|------------------|-----|--|
| DYNAMIC CHARACTERISTICS⁹ | | | | | | |
| Bandwidth | BW | −3 dB $R_{AB} = 10\text{ k}\Omega$ $R_{AB} = 100\text{ k}\Omega$ | | 3 0.43 | | MHz MHz |
| Total Harmonic Distortion | THD | $V_{DD}/V_{SS} = \pm 2.5\text{ V}$, $V_A = 1\text{ V rms}$, $V_B = 0\text{ V}$, $f = 1\text{ kHz}$ $R_{AB} = 10\text{ k}\Omega$ $R_{AB} = 100\text{ k}\Omega$ | | −80 −90 | | dB dB |
| Resistor Noise Density | e_{N_WB} | Code = half scale, $T_A = 25^\circ\text{C}$, $f = 10\text{ kHz}$ $R_{AB} = 10\text{ k}\Omega$ $R_{AB} = 100\text{ k}\Omega$ | | 7 20 | | nV/ $\sqrt{\text{Hz}}$ nV/ $\sqrt{\text{Hz}}$ |
| V_W Settling Time | t_s | $V_A = 5\text{ V}$, $V_B = 0\text{ V}$, from zero scale to full scale, $\pm 0.5\text{ LSB}$ error band $R_{AB} = 10\text{ k}\Omega$ $R_{AB} = 100\text{ k}\Omega$ | | 2 12 | | μs μs |
| Crosstalk (C_{W1}/C_{W2}) | C_T | $R_{AB} = 10\text{ k}\Omega$ $R_{AB} = 100\text{ k}\Omega$ | | 10 25 | | nV-sec nV-sec |
| Analog Crosstalk Endurance ¹⁰ | C_{TA} | $T_A = 25^\circ\text{C}$ | | −90 1 | | dB Mcycles |
| Data Retention ^{11, 12} | | | 100 | 50 | | kcycles Years |

¹ Typical values represent average readings at 25°C , $V_{DD} = 5\text{ V}$, and $V_{SS} = 0\text{ V}$.

² Resistor integral nonlinearity (R-INL) error is the deviation from an ideal value measured between the maximum resistance and the minimum resistance wiper positions. R-DNL measures the relative step change from ideal between successive tap positions. The maximum wiper current is limited to $(0.7 \times V_{DD})/R_{AB}$.

³ Guaranteed by design and characterization, not subject to production test.

⁴ INL and DNL are measured at V_{WB} with the RDAC configured as a potentiometer divider similar to a voltage output DAC. $V_A = V_{DD}$ and $V_B = 0\text{ V}$. DNL specification limits of $\pm 1\text{ LSB}$ maximum are guaranteed monotonic operating conditions.

⁵ Resistor Terminal A, Resistor Terminal B, and Resistor Terminal W have no limitations on polarity with respect to each other. Dual-supply operation enables ground referenced bipolar signal adjustment.

⁶ Different from operating current; supply current for EEPROM program lasts approximately 30 ms.

⁷ Different from operating current; supply current for EEPROM read lasts approximately 20 μs .

⁸ P_{DISS} is calculated from $(I_{DD} \times V_{DD})$.

⁹ All dynamic characteristics use $V_{DD}/V_{SS} = \pm 2.5\text{ V}$.

¹⁰ Endurance is qualified to 100,000 cycles per JEDEC Standard 22, Method A117 and measured at -40°C to $+125^\circ\text{C}$.

¹¹ Retention lifetime equivalent at junction temperature (T_j) = 125°C per JEDEC Standard 22, Method A117. Retention lifetime, based on an activation energy of 1 eV, derates with junction temperature in the Flash/EE memory.

¹² 50 years applies to an endurance of 1k cycles. An endurance of 100k cycles will have an equivalent retention lifetime of 5 years.

ELECTRICAL CHARACTERISTICS—AD5143

$V_{DD} = 2.3 \text{ V to } 5.5 \text{ V}$, $V_{SS} = 0 \text{ V}$; $V_{DD} = 2.25 \text{ V to } 2.75 \text{ V}$, $V_{SS} = -2.25 \text{ V to } -2.75 \text{ V}$; $-40^\circ\text{C} < T_A < +125^\circ\text{C}$, unless otherwise noted.

Table 3.

| Parameter | Symbol | Test Conditions/Comments | Min | Typ ¹ | Max | Unit |
|---|---|--------------------------------|------|------------------|------|-----------------------|
| DC CHARACTERISTICS—RHEOSTAT MODE (ALL RDACs) | | | | | | |
| Resolution | N | | 8 | | | Bits |
| Resistor Integral Nonlinearity ² | R-INL | $R_{AB} = 10 \text{ k}\Omega$ | | | | |
| | | $V_{DD} \geq 2.7 \text{ V}$ | -2 | ± 0.2 | +2 | LSB |
| | | $V_{DD} < 2.7 \text{ V}$ | -5 | ± 1.5 | +5 | LSB |
| | | $R_{AB} = 100 \text{ k}\Omega$ | | | | |
| | | $V_{DD} \geq 2.7 \text{ V}$ | -1 | ± 0.1 | +1 | LSB |
| | | $V_{DD} < 2.7 \text{ V}$ | -2 | ± 0.5 | +2 | LSB |
| Resistor Differential Nonlinearity ² | R-DNL | | -0.5 | ± 0.2 | +0.5 | LSB |
| Nominal Resistor Tolerance | $\Delta R_{AB}/R_{AB}$ | | -8 | ± 1 | +8 | % |
| Resistance Temperature Coefficient ³ | $(\Delta R_{AB}/R_{AB})/\Delta T \times 10^6$ | Code = full scale | | 35 | | ppm/ $^\circ\text{C}$ |
| Wiper Resistance ³ | R_W | Code = zero scale | | | | |
| | | $R_{AB} = 10 \text{ k}\Omega$ | | 55 | 125 | Ω |
| | | $R_{AB} = 100 \text{ k}\Omega$ | | 130 | 400 | Ω |
| Bottom Scale or Top Scale | R_{BS} or R_{TS} | $R_{AB} = 10 \text{ k}\Omega$ | | 40 | 80 | Ω |
| | | $R_{AB} = 100 \text{ k}\Omega$ | | 60 | 230 | Ω |
| Nominal Resistance Match | R_{AB1}/R_{AB2} | Code = 0xFF | -1 | ± 0.2 | +1 | % |
| DC CHARACTERISTICS—POTENTIOMETER DIVIDER MODE (ALL RDACs) | | | | | | |
| Integral Nonlinearity ⁴ | INL | | | | | |
| | | $R_{AB} = 10 \text{ k}\Omega$ | -1 | ± 0.2 | +1 | LSB |
| | | $R_{AB} = 100 \text{ k}\Omega$ | -0.5 | ± 0.1 | +0.5 | LSB |
| Differential Nonlinearity ⁴ | DNL | | -0.5 | ± 0.2 | +0.5 | LSB |
| Full-Scale Error | V_{WFSE} | $R_{AB} = 10 \text{ k}\Omega$ | -2.5 | -0.1 | | LSB |
| | | $R_{AB} = 100 \text{ k}\Omega$ | -1 | ± 0.2 | +1 | LSB |
| Zero-Scale Error | V_{WZSE} | $R_{AB} = 10 \text{ k}\Omega$ | | 1.2 | 3 | LSB |
| | | $R_{AB} = 100 \text{ k}\Omega$ | | 0.5 | 1 | LSB |
| Voltage Divider Temperature Coefficient ³ | $(\Delta V_W/V_W)/\Delta T \times 10^6$ | Code = half scale | | ± 5 | | ppm/ $^\circ\text{C}$ |

| Parameter | Symbol | Test Conditions/Comments | Min | Typ ¹ | Max | Unit |
|---|------------------------------|--|---------------------|------------------|---------------------|---------------------|
| RESISTOR TERMINALS | | | | | | |
| Maximum Continuous Current | $I_A, I_B, \text{ and } I_W$ | $R_{AB} = 10 \text{ k}\Omega$ $R_{AB} = 100 \text{ k}\Omega$ | -6 -1.5 | | +6 +1.5 | mA mA |
| Terminal Voltage Range ⁵ | | | V_{SS} | | V_{DD} | V |
| Capacitance A, Capacitance B ³ | C_A, C_B | $f = 1 \text{ MHz}$, measured to GND, code = half scale $R_{AB} = 10 \text{ k}\Omega$ $R_{AB} = 100 \text{ k}\Omega$ | | 25 12 | | pF pF |
| Capacitance W ³ | C_W | $f = 1 \text{ MHz}$, measured to GND, code = half scale $R_{AB} = 10 \text{ k}\Omega$ $R_{AB} = 100 \text{ k}\Omega$ | | 12 5 | | pF pF |
| Common-Mode Leakage Current ³ | | $V_A = V_W = V_B$ | -500 | ± 15 | +500 | nA |
| DIGITAL INPUTS | | | | | | |
| Input Logic ³ | | | | | | |
| High | V_{INH} | | $0.7 \times V_{DD}$ | | | V |
| Low | V_{INL} | | | | $0.2 \times V_{DD}$ | V |
| Input Hysteresis ³ | V_{HYST} | | $0.1 \times V_{DD}$ | | | V |
| Input Current ³ | I_{IN} | | | | ± 1 | μA |
| Input Capacitance ³ | C_{IN} | | | 5 | | pF |
| DIGITAL OUTPUTS | | | | | | |
| Output High Voltage ³ | V_{OH} | $R_{PULL-UP} = 2.2 \text{ k}\Omega$ to V_{DD} | | V_{DD} | | V |
| Output Low Voltage ³ | V_{OL} | $I_{SINK} = 3 \text{ mA}$ $I_{SINK} = 6 \text{ mA}$ | | | 0.4 0.6 | V V |
| Three-State Leakage Current | | | -1 | | +1 | μA |
| Three-State Output Capacitance | | | | 2 | | pF |
| POWER SUPPLIES | | | | | | |
| Single-Supply Power Range | | $V_{SS} = \text{GND}$ | 2.3 | | 5.5 | V |
| Dual-Supply Power Range | | | ± 2.25 | | ± 2.75 | V |
| Positive Supply Current | I_{DD} | $V_{IH} = V_{DD}$ or $V_{IL} = \text{GND}$ $V_{DD} = 5.5 \text{ V}$ $V_{DD} = 2.3 \text{ V}$ | | 0.7 400 | 5.5 | μA nA |
| Negative Supply Current | I_{SS} | $V_{IH} = V_{DD}$ or $V_{IL} = \text{GND}$ | -5.5 | -0.7 | | μA |
| EEPROM Store Current ^{3, 6} | $I_{DD_EEPROM_STORE}$ | $V_{IH} = V_{DD}$ or $V_{IL} = \text{GND}$ | | 2 | | mA |
| EEPROM Read Current ^{3, 7} | $I_{DD_EEPROM_READ}$ | $V_{IH} = V_{DD}$ or $V_{IL} = \text{GND}$ | | 320 | | μA |
| Power Dissipation ⁸ | P_{DISS} | $V_{IH} = V_{DD}$ or $V_{IL} = \text{GND}$ | | 3.5 | | μW |
| Power Supply Rejection Ratio | PSRR | $\Delta V_{DD}/\Delta V_{SS} = V_{DD} \pm 10\%$, code = full scale | | -66 | -60 | dB |

| Parameter | Symbol | Test Conditions/Comments | Min | Typ ¹ | Max | Unit |
|---|-------------------|--|-----|------------------|-----|------------------|
| DYNAMIC CHARACTERISTICS ⁹ | | | | | | |
| Bandwidth | BW | –3 dB R _{AB} = 10 kΩ R _{AB} = 100 kΩ | | 3 0.43 | | MHz MHz |
| Total Harmonic Distortion | THD | V _{DD} /V _{SS} = ±2.5 V, V _A = 1 V rms, V _B = 0 V, f = 1 kHz R _{AB} = 10 kΩ R _{AB} = 100 kΩ | | –80 –90 | | dB dB |
| Resistor Noise Density | e _{N_WB} | Code = half scale, T _A = 25°C, f = 10 kHz R _{AB} = 10 kΩ R _{AB} = 100 kΩ | | 7 20 | | nV/√Hz nV/√Hz |
| V _W Settling Time | t _s | V _A = 5 V, V _B = 0 V, from zero scale to full scale, ±0.5 LSB error band R _{AB} = 10 kΩ R _{AB} = 100 kΩ | | 2 12 | | μs μs |
| Crosstalk (C _{W1} /C _{W2}) | C _T | R _{AB} = 10 kΩ R _{AB} = 100 kΩ | | 10 25 | | nV-sec nV-sec |
| Analog Crosstalk Endurance ¹⁰ | C _{TA} | T _A = 25°C | | –90 1 | | dB Mcycles |
| Data Retention ^{11,12} | | | 100 | 50 | | kcycles Years |

¹ Typical values represent average readings at 25°C, V_{DD} = 5 V, and V_{SS} = 0 V.

² Resistor integral nonlinearity (R-INL) error is the deviation from an ideal value measured between the maximum resistance and the minimum resistance wiper positions. R-DNL measures the relative step change from ideal between successive tap positions. The maximum wiper current is limited to (0.7 × V_{DD})/R_{AB}.

³ Guaranteed by design and characterization, not subject to production test.

⁴ INL and DNL are measured at V_{WB} with the RDAC configured as a potentiometer divider similar to a voltage output DAC. V_A = V_{DD} and V_B = 0 V. DNL specification limits of ±1 LSB maximum are guaranteed monotonic operating conditions.

⁵ Resistor Terminal A, Resistor Terminal B, and Resistor Terminal W have no limitations on polarity with respect to each other. Dual-supply operation enables ground referenced bipolar signal adjustment.

⁶ Different from operating current; supply current for EEPROM program lasts approximately 30 ms.

⁷ Different from operating current; supply current for EEPROM read lasts approximately 20 μs.

⁸ P_{DISS} is calculated from (I_{DD} × V_{DD}).

⁹ All dynamic characteristics use V_{DD}/V_{SS} = ±2.5 V.

¹⁰ Endurance is qualified to 100,000 cycles per JEDEC Standard 22, Method A117 and measured at –40°C to +125°C.

¹¹ Retention lifetime equivalent at junction temperature (T_j) = 125°C per JEDEC Standard 22, Method A117. Retention lifetime, based on an activation energy of 1 eV, derates with junction temperature in the Flash/EE memory.

¹² 50 years applies to an endurance of 1k cycles. An endurance of 100k cycles will have an equivalent retention lifetime of 5 years.

INTERFACE TIMING SPECIFICATIONS

$V_{DD} = 2.3 \text{ V}$ to 5.5 V ; all specifications T_{MIN} to T_{MAX} , unless otherwise noted.

Table 4. I²C Interface

| Parameter ¹ | Test Conditions/Comments | Min | Typ | Max | Unit | Description |
|-------------------------|--------------------------|----------------|-----|------|---------------|---|
| f_{SCL}^2 | Standard mode | | | 100 | kHz | Serial clock frequency |
| | Fast mode | | | 400 | kHz | |
| t_1 | Standard mode | 4.0 | | | μs | SCL high time, t_{HIGH} |
| | Fast mode | 0.6 | | | μs | |
| t_2 | Standard mode | 4.7 | | | μs | SCL low time, t_{LOW} |
| | Fast mode | 1.3 | | | μs | |
| t_3 | Standard mode | 250 | | | ns | Data setup time, $t_{SU; DAT}$ |
| | Fast mode | 100 | | | ns | |
| t_4 | Standard mode | 0 | | 3.45 | μs | Data hold time, $t_{HD; DAT}$ |
| | Fast mode | 0 | | 0.9 | μs | |
| t_5 | Standard mode | 4.7 | | | μs | Setup time for a repeated start condition, $t_{SU; STA}$ |
| | Fast mode | 0.6 | | | μs | |
| t_6 | Standard mode | 4 | | | μs | Hold time (repeated) for a start condition, $t_{HD; STA}$ |
| | Fast mode | 0.6 | | | μs | |
| t_7 | Standard mode | 4.7 | | | μs | Bus free time between a stop and a start condition, t_{BUF} |
| | Fast mode | 1.3 | | | μs | |
| t_8 | Standard mode | 4 | | | μs | Setup time for a stop condition, $t_{SU; STO}$ |
| | Fast mode | 0.6 | | | μs | |
| t_9 | Standard mode | | | 1000 | ns | Rise time of SDA signal, t_{RDA} |
| | Fast mode | $20 + 0.1 C_L$ | | 300 | ns | |
| t_{10} | Standard mode | | | 300 | ns | Fall time of SDA signal, t_{FDA} |
| | Fast mode | $20 + 0.1 C_L$ | | 300 | ns | |
| t_{11} | Standard mode | | | 1000 | ns | Rise time of SCL signal, t_{RCL} |
| | Fast mode | $20 + 0.1 C_L$ | | 300 | ns | |
| t_{11A} | Standard mode | | | 1000 | ns | Rise time of SCL signal after a repeated start condition and after an acknowledge bit, t_{RCL1} (not shown in Figure 3) |
| | Fast mode | $20 + 0.1 C_L$ | | 300 | ns | |
| t_{12} | Standard mode | | | 300 | ns | Fall time of SCL signal, t_{FCL} |
| | Fast mode | $20 + 0.1 C_L$ | | 300 | ns | |
| t_{SP}^3 | Fast mode | 0 | | 50 | ns | Pulse width of suppressed spike (not shown in Figure 3) |
| $t_{EEPROM_PROGRAM}^4$ | | | 15 | 50 | ms | Memory program time (not shown in Figure 3) |
| $t_{EEPROM_READBACK}$ | | | 7 | 30 | μs | Memory readback time (not shown in Figure 3) |
| $t_{POWER_UP}^5$ | | | | 75 | μs | Power-on EEPROM restore time (not shown in Figure 3) |
| t_{RESET} | | | 30 | | μs | Reset EEPROM restore time (not shown in Figure 3) |

¹ Maximum bus capacitance is limited to 400 pF.

² The SDA and SCL timing is measured with the input filters enabled. Switching off the input filters improves the transfer rate; however, it has a negative effect on the EMC behavior of the device.

³ Input filtering on the SCL and SDA inputs suppresses noise spikes that are less than 50 ns for fast mode.

⁴ EEPROM program time depends on the temperature and EEPROM write cycles. Higher timing is expected at lower temperatures and higher write cycles.

⁵ Maximum time after $V_{DD} - V_{SS}$ is equal to 2.3 V.

SHIFT REGISTER AND TIMING DIAGRAMS

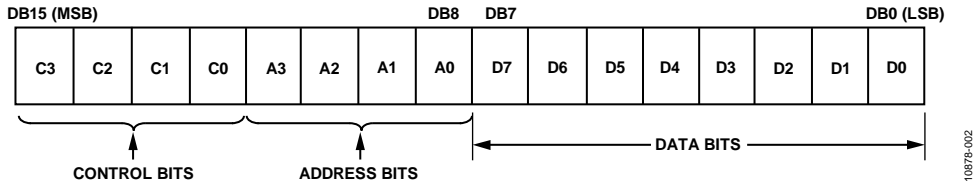


Figure 2. Input Shift Register Contents

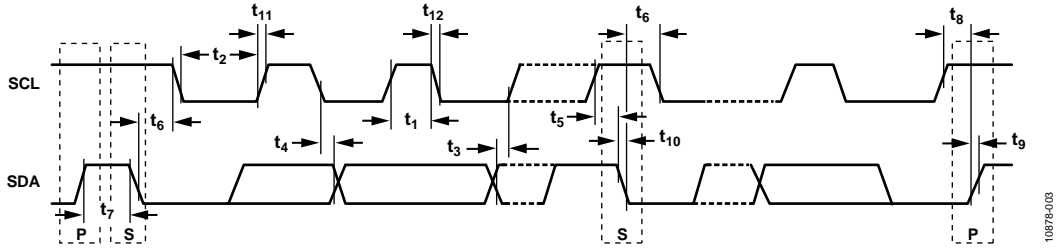


Figure 3. I²C Serial Interface Timing Diagram (Typical Write Sequence)

ABSOLUTE MAXIMUM RATINGS

$T_A = 25^\circ\text{C}$, unless otherwise noted.

Table 5.

| Parameter | Rating |
|---|--|
| V_{DD} to GND | -0.3 V to +7.0 V |
| V_{SS} to GND | +0.3 V to -7.0 V |
| V_{DD} to V_{SS} | 7 V |
| V_A, V_W, V_B to GND | $V_{SS} - 0.3\text{ V}, V_{DD} + 0.3\text{ V}$ or +7.0 V (whichever is less) |
| I_A, I_W, I_B | |
| Pulsed ¹ | |
| Frequency > 10 kHz | |
| $R_{AW} = 10\text{ k}\Omega$ | $\pm 6\text{ mA}/d^2$ |
| $R_{AW} = 100\text{ k}\Omega$ | $\pm 1.5\text{ mA}/d^2$ |
| Frequency $\leq 10\text{ kHz}$ | |
| $R_{AW} = 10\text{ k}\Omega$ | $\pm 6\text{ mA}/\sqrt{d^2}$ |
| $R_{AW} = 100\text{ k}\Omega$ | $\pm 1.5\text{ mA}/\sqrt{d^2}$ |
| Digital Inputs | -0.3 V to $V_{DD} + 0.3\text{ V}$ or +7 V (whichever is less) |
| Operating Temperature Range, T_A ³ | -40°C to +125°C |
| Maximum Junction Temperature, T_J Maximum | 150°C |
| Storage Temperature Range | -65°C to +150°C |
| Reflow Soldering | |
| Peak Temperature | 260°C |
| Time at Peak Temperature | 20 sec to 40 sec |
| Package Power Dissipation | $(T_J \text{ max} - T_A)/\theta_{JA}$ |
| FICDM | 1.5 kV |

¹ Maximum terminal current is bounded by the maximum current handling of the switches, maximum power dissipation of the package, and maximum applied voltage across any two of the A, B, and W terminals at a given resistance.

² d = pulse duty factor.

³ Includes programming of EEPROM memory.

Stresses at or above those listed under Absolute Maximum Ratings may cause permanent damage to the product. This is a stress rating only; functional operation of the product at these or any other conditions above those indicated in the operational section of this specification is not implied. Operation beyond the maximum operating conditions for extended periods may affect product reliability.

THERMAL RESISTANCE

θ_{JA} is defined by the JEDEC JESD51 standard, and the value is dependent on the test board and test environment.

Table 6. Thermal Resistance

| Package Type | θ_{JA} | θ_{JC} | Unit |
|---------------|-------------------|---------------|------|
| 16-Lead LFCSP | 89.5 ¹ | 3 | °C/W |

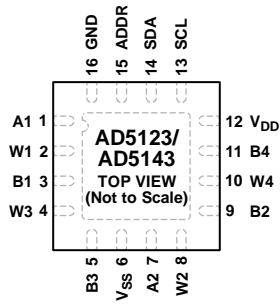
¹ JEDEC 2S2P test board, still air (0 m/sec airflow).

ESD CAUTION



ESD (electrostatic discharge) sensitive device. Charged devices and circuit boards can discharge without detection. Although this product features patented or proprietary protection circuitry, damage may occur on devices subjected to high energy ESD. Therefore, proper ESD precautions should be taken to avoid performance degradation or loss of functionality.

PIN CONFIGURATION AND FUNCTION DESCRIPTIONS



NOTES
1. INTERNALLY CONNECT THE EXPOSED PAD TO V_{SS}.

10878-004

Figure 4. Pin Configuration

Table 7. Pin Function Descriptions

| Pin No. | Mnemonic | Description |
|---------|-----------------|---|
| 1 | A1 | Terminal A of RDAC1. $V_{SS} \leq V_A \leq V_{DD}$. |
| 2 | W1 | Wiper Terminal of RDAC1. $V_{SS} \leq V_W \leq V_{DD}$. |
| 3 | B1 | Terminal B of RDAC1. $V_{SS} \leq V_B \leq V_{DD}$. |
| 4 | W3 | Wiper Terminal of RDAC3. $V_{SS} \leq V_W \leq V_{DD}$. |
| 5 | B3 | Terminal B of RDAC3. $V_{SS} \leq V_B \leq V_{DD}$. |
| 6 | V _{SS} | Negative Power Supply. Decouple this pin with 0.1 μ F ceramic capacitors and 10 μ F capacitors. |
| 7 | A2 | Terminal A of RDAC2. $V_{SS} \leq V_A \leq V_{DD}$. |
| 8 | W2 | Wiper Terminal of RDAC2. $V_{SS} \leq V_W \leq V_{DD}$. |
| 9 | B2 | Terminal B of RDAC2. $V_{SS} \leq V_B \leq V_{DD}$. |
| 10 | W4 | Wiper Terminal of RDAC4. $V_{SS} \leq V_W \leq V_{DD}$. |
| 11 | B4 | Terminal B of RDAC4. $V_{SS} \leq V_B \leq V_{DD}$. |
| 12 | V _{DD} | Positive Power Supply. Decouple this pin with 0.1 μ F ceramic capacitors and 10 μ F capacitors. |
| 13 | SCL | Serial Clock Line. Data is clocked in at the logic low transition. |
| 14 | SDA | Serial Data Input/Output. |
| 15 | ADDR | Programmable Address for Multiple Package Decoding. |
| 16 | GND | Ground Pin, Logic Ground Reference. |
| | EPAD | Internally Connect the Exposed Paddle to V _{SS} . |

TYPICAL PERFORMANCE CHARACTERISTICS

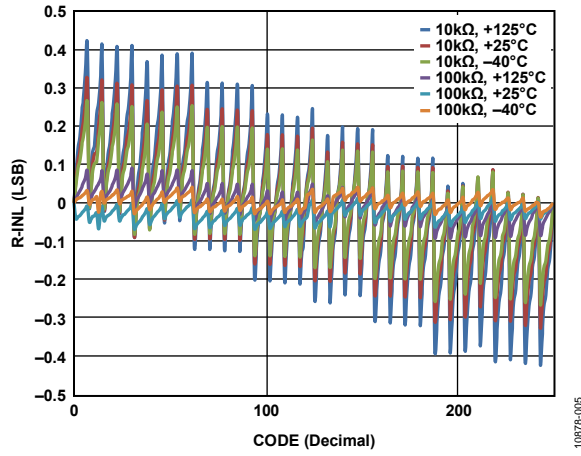


Figure 5. R-INL vs. Code (AD5143)

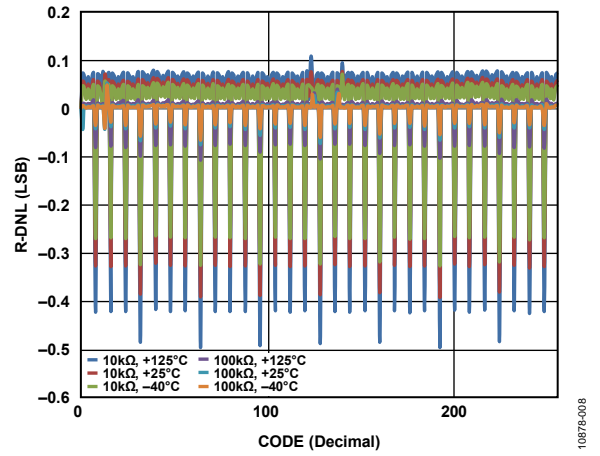


Figure 8. R-DNL vs. Code (AD5143)

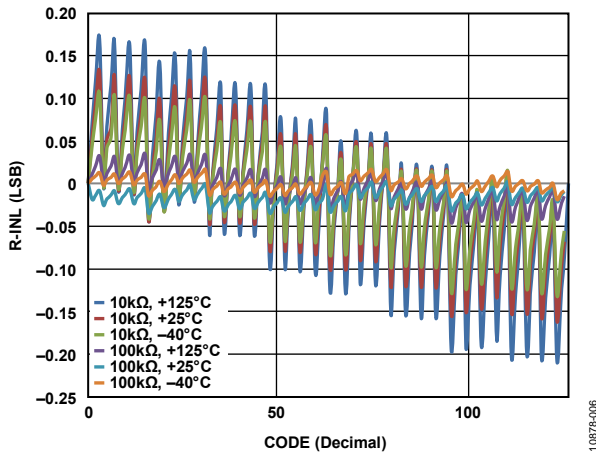


Figure 6. R-INL vs. Code (AD5123)

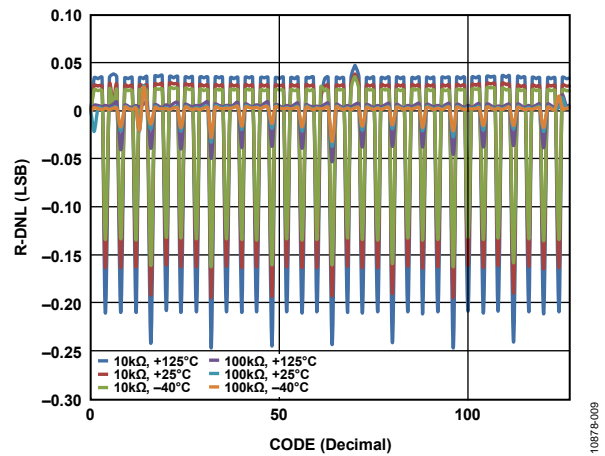


Figure 9. R-DNL vs. Code (AD5123)

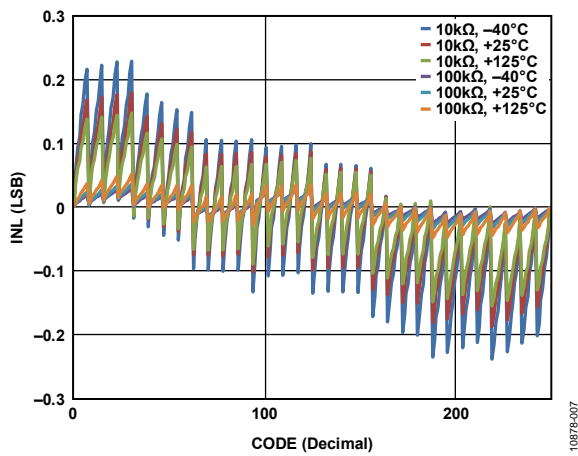


Figure 7. INL vs. Code (AD5143)

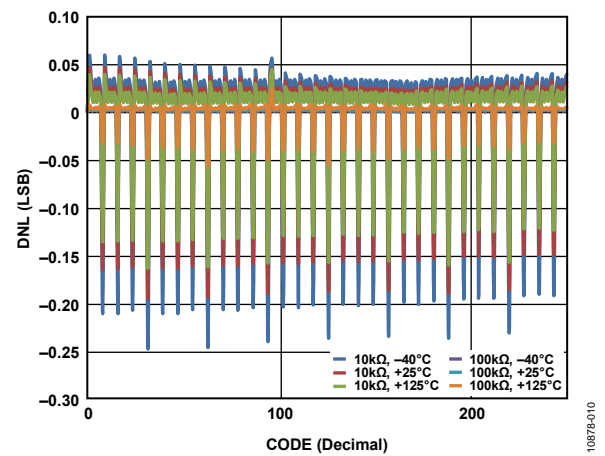


Figure 10. DNL vs. Code (AD5143)

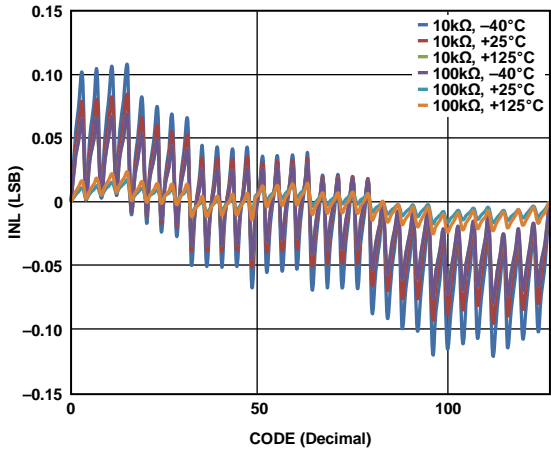


Figure 11. INL vs. Code (AD5123)

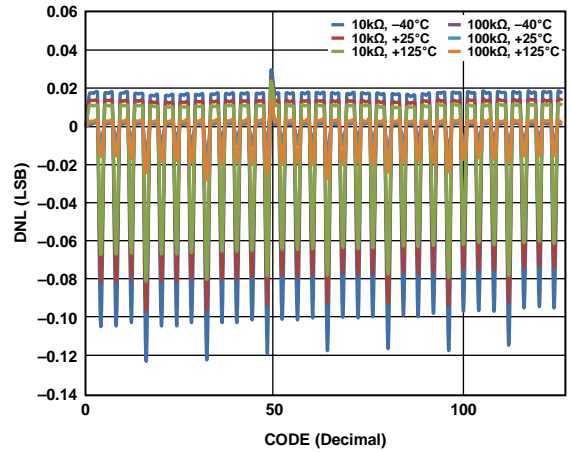


Figure 14. DNL vs. Code (AD5123)

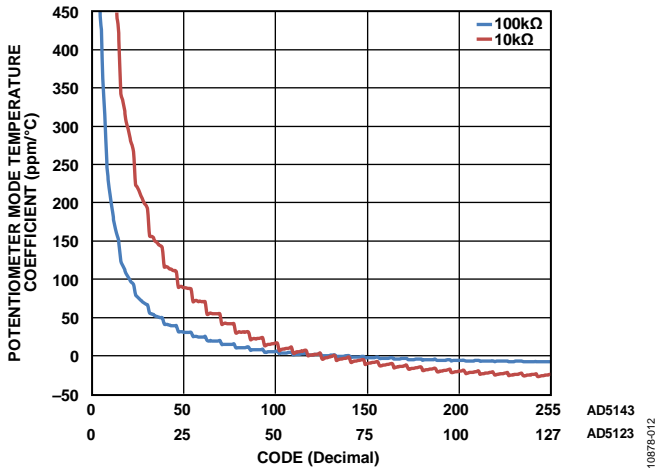


Figure 12. Potentiometer Mode Temperature Coefficient $((\Delta V_w/V_w)/\Delta T \times 10^6)$ vs. Code

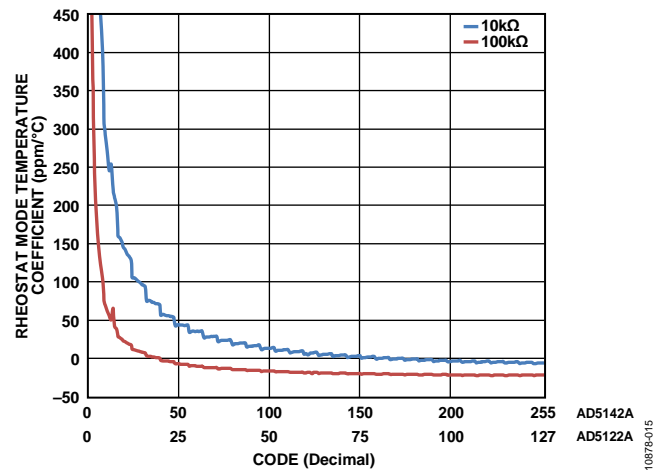


Figure 15. Rheostat Mode Temperature Coefficient $((\Delta R_{WB}/R_{WB})/\Delta T \times 10^6)$ vs. Code

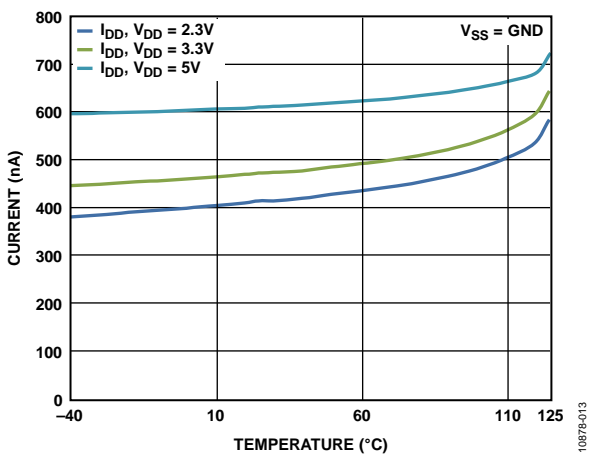


Figure 13. Supply Current vs. Temperature

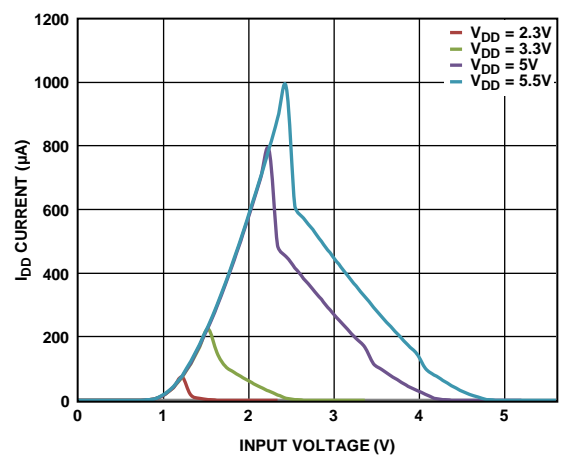


Figure 16. I_{DD} Current vs. Digital Input Voltage

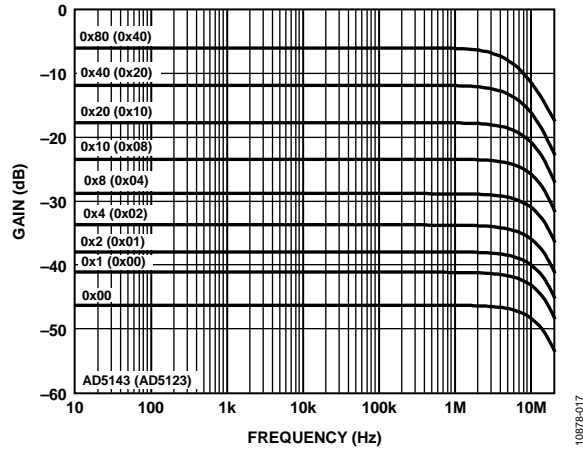


Figure 17. 10 kΩ Gain vs. Frequency and Code

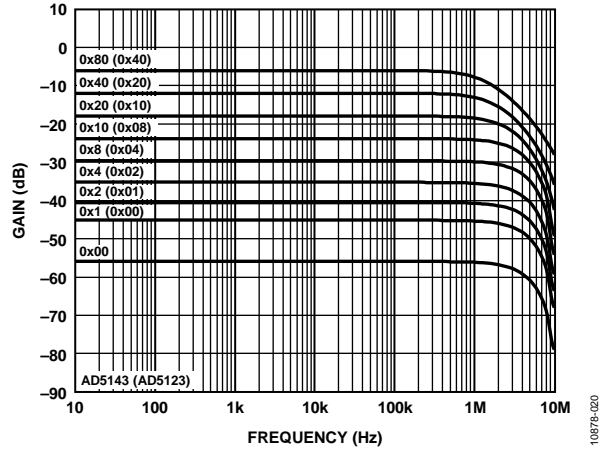


Figure 20. 100 kΩ Gain vs. Frequency and Code

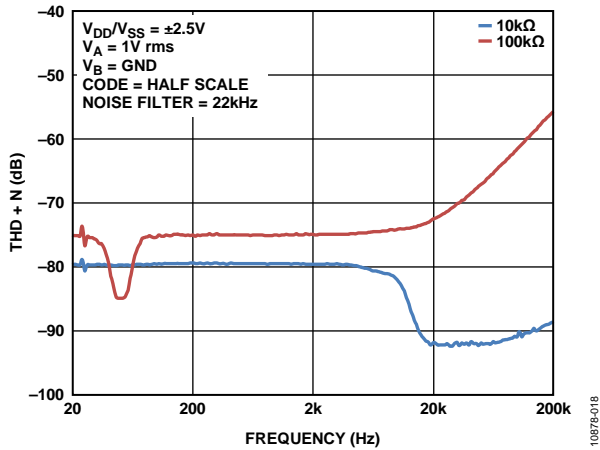


Figure 18. Total Harmonic Distortion Plus Noise (THD + N) vs. Frequency

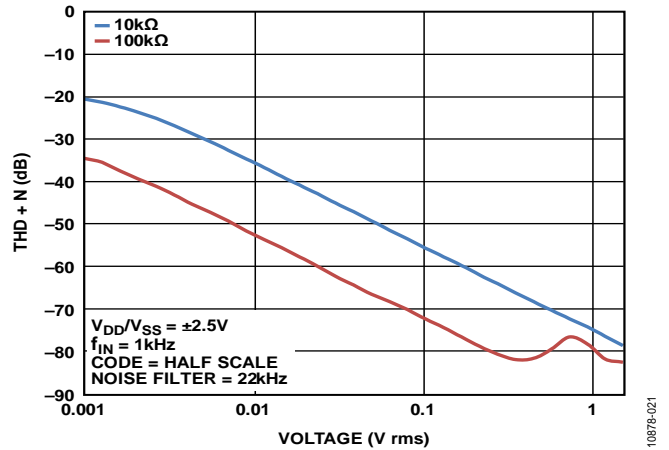


Figure 21. Total Harmonic Distortion Plus Noise (THD + N) vs. Amplitude

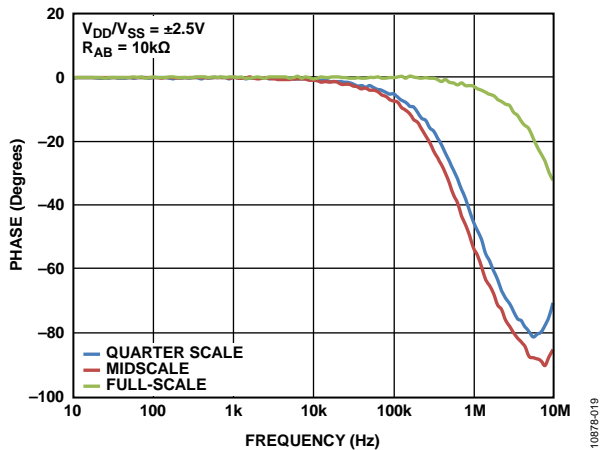


Figure 19. Normalized Phase Flatness vs. Frequency, $R_{AB} = 10\text{ k}\Omega$

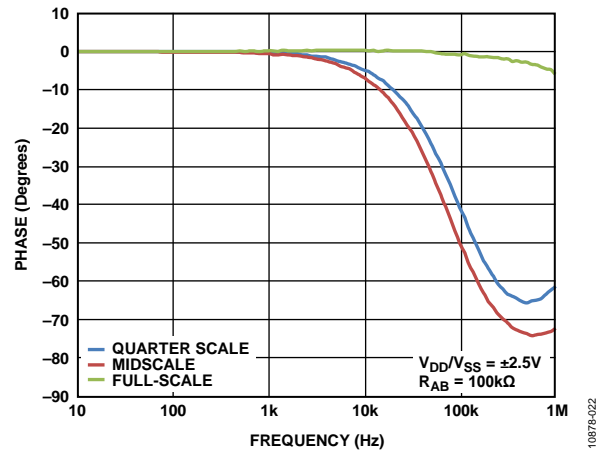


Figure 22. Normalized Phase Flatness vs. Frequency, $R_{AB} = 100\text{ k}\Omega$

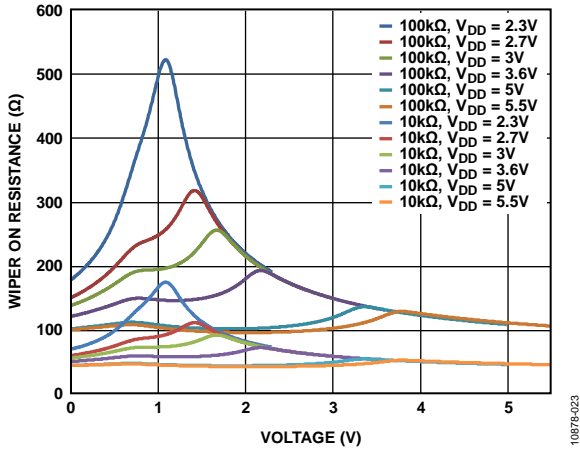


Figure 23. Incremental Wiper On Resistance vs. Positive Power Supply (V_{DD})

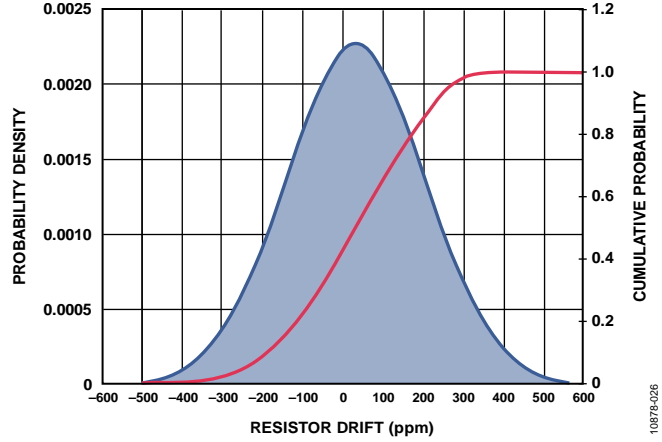


Figure 26. Resistor Lifetime Drift

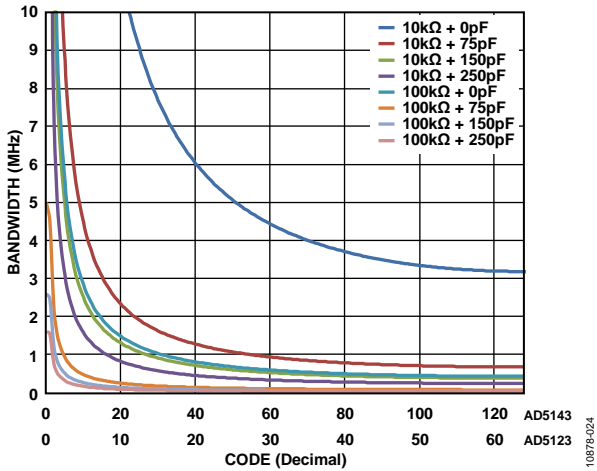


Figure 24. Maximum Bandwidth vs. Code and Net Capacitance

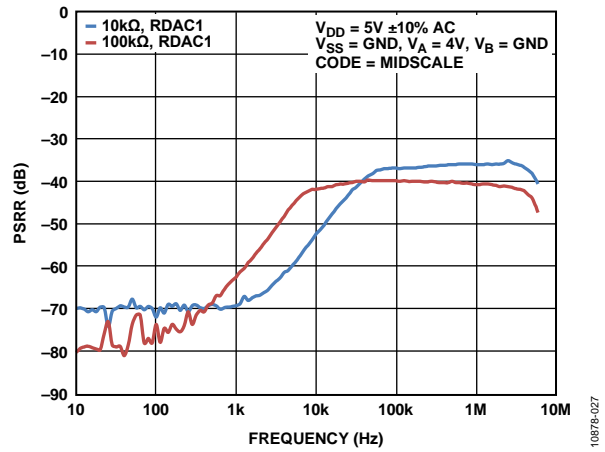


Figure 27. Power Supply Rejection Ratio (PSRR) vs. Frequency

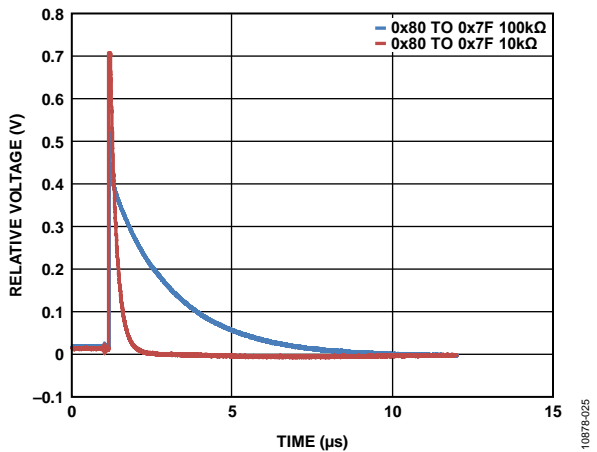


Figure 25. Maximum Transition Glitch

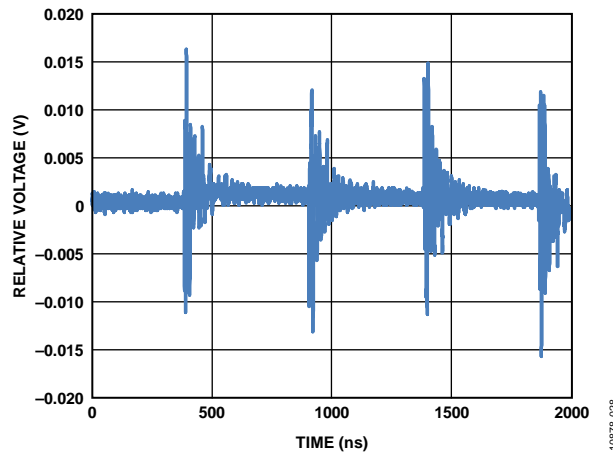


Figure 28. Digital Feedthrough

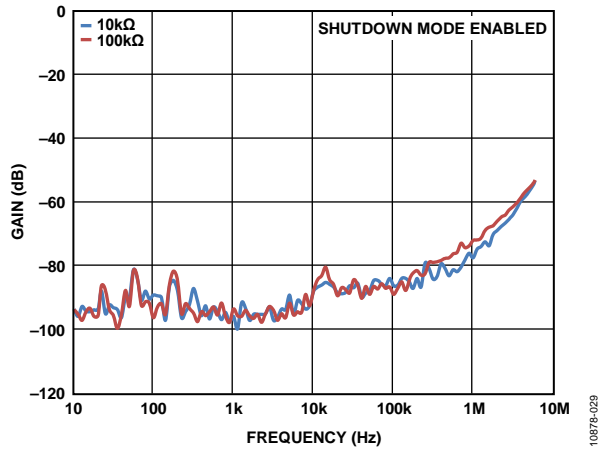


Figure 29. Shutdown Isolation vs. Frequency

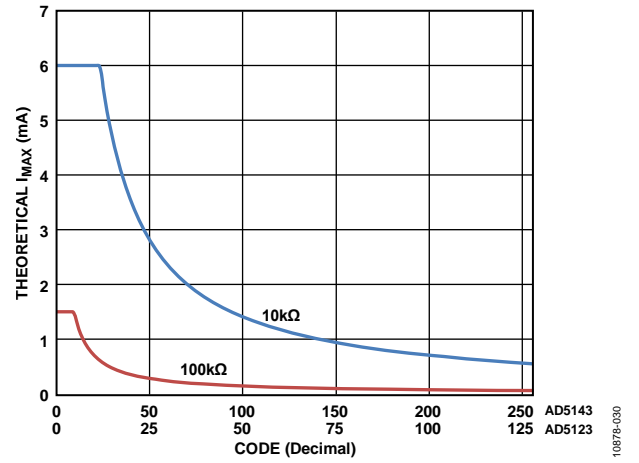


Figure 30. Theoretical Maximum Current vs. Code

TEST CIRCUITS

Figure 31 to Figure 35 define the test conditions used in the Specifications section.

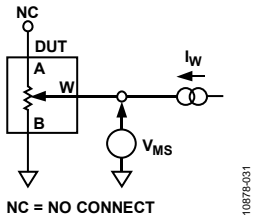


Figure 31. Resistor Integral Nonlinearity Error (Rheostat Operation; R-INL, R-DNL)

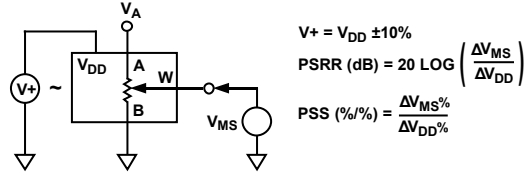


Figure 34. Power Supply Sensitivity and Power Supply Rejection Ratio (PSS, PSRR)

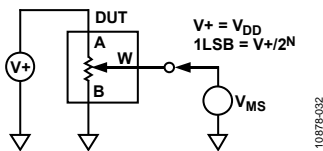


Figure 32. Potentiometer Divider Nonlinearity Error (INL, DNL)

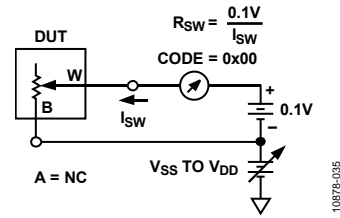


Figure 35. Incremental On Resistance

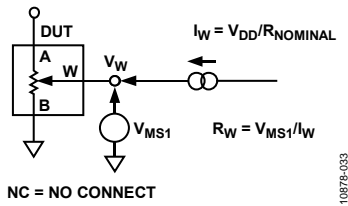


Figure 33. Wiper Resistance

THEORY OF OPERATION

The AD5123/AD5143 digital programmable potentiometers are designed to operate as true variable resistors for analog signals within the terminal voltage range of $V_{SS} < V_{TERM} < V_{DD}$. The resistor wiper position is determined by the RDAC register contents. The RDAC register acts as a scratchpad register that allows unlimited changes of resistance settings. A secondary register (the input register) can preload the RDAC register data.

The RDAC register can be programmed with any position setting using the I²C interface (depending on the model). When a desirable wiper position is found, this value can be stored in the EEPROM memory. Thereafter, the wiper position is always restored to that position for subsequent power-ups. The storing of EEPROM data takes approximately 15 ms; during this time, the device is locked and does not acknowledge any new command, preventing any changes from taking place.

RDAC REGISTER AND EEPROM

The RDAC register directly controls the position of the digital potentiometer wiper. For example, when the RDAC register is loaded with 0x80 (AD5143, 256 taps), the wiper is connected to half scale of the variable resistor. The RDAC register is a standard logic register; there is no restriction on the number of changes allowed.

It is possible to both write to and read from the RDAC register using the digital interface (see Table 9).

The contents of the RDAC register can be stored to the EEPROM using Command 9 (see Table 9). Thereafter, the RDAC register always sets at that position for any future on off on power supply sequence. It is possible to read back data saved into the EEPROM with Command 3 (see Table 9).

Alternatively, the EEPROM can be written to independently using Command 11 (see Table 15).

INPUT SHIFT REGISTER

For the AD5123/AD5143, the input shift register is 16 bits wide, as shown in Figure 2. The 16-bit word consists of four control bits, followed by four address bits and by eight data bits.

If the AD5143 RDAC or EEPROM registers are read from or written to, the lowest data bit (Bit 0) is ignored.

Data is loaded MSB first (Bit 15). The four control bits determine the function of the software command, as listed in Table 9 and Table 15.

I²C SERIAL DATA INTERFACE

The AD5123/AD5143 has 2-wire, I²C-compatible serial interfaces. These devices can be connected to an I²C bus as a slave device, under the control of a master device. See Figure 3 for a timing diagram of a typical write sequence.

The AD5123/AD5143 supports standard (100 kHz) and fast (400 kHz) data transfer modes. Support is not provided for 10-bit addressing and general call addressing.

The 2-wire serial bus protocol operates as follows:

1. The master initiates a data transfer by establishing a start condition, which is when a high-to-low transition on the SDA line occurs while SCL is high. The following byte is the address byte, which consists of the 7-bit slave address and an R/W bit. The slave device corresponding to the transmitted address responds by pulling SDA low during the ninth clock pulse (this is called the acknowledge bit). At this stage, all other devices on the bus remain idle while the selected device waits for data to be written to, or read from, the shift register.
If the R/W bit is set high, the master reads from the slave device. However, if the R/W bit is set low, the master writes to the slave device.
2. Data is transmitted over the serial bus in sequences of nine clock pulses (eight data bits followed by an acknowledge bit). The transitions on the SDA line must occur during the low period of SCL and remain stable during the high period of SCL.
3. When all data bits have been read from or written to, a stop condition is established. In write mode, the master pulls the SDA line high during the tenth clock pulse to establish a stop condition. In read mode, the master issues a no acknowledge for the ninth clock pulse (that is, the SDA line remains high). The master then brings the SDA line low before the tenth clock pulse, and then high again during the tenth clock pulse to establish a stop condition.

I²C ADDRESS

The facility to make hardwired changes to ADDR allows the user to incorporate up to three of these devices on one bus as outlined in Table 8.

Table 8. I²C Address Selection

| ADDR Pin | 7-Bit I ² C Device Address |
|-------------------------|---------------------------------------|
| V _{DD} | 0101000 |
| No connect ¹ | 0101010 |
| GND | 0101011 |

¹ Not available in bipolar mode (V_{SS} < 0 V).

Table 9. Reduced Commands Operation Truth Table

| Command Number | Control Bits[DB15:DB12] | | | | Address Bits[DB11:DB8] ¹ | | | | Data Bits[DB7:DB0] ¹ | | | | | | | | Operation | | |
|----------------|-------------------------|----|----|----|-------------------------------------|----|----|----|---------------------------------|----|----|----|----|----|----|----|--|------------------------------|-------------|
| | C3 | C2 | C1 | C0 | A3 | A2 | A1 | A0 | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 | | | |
| 0 | 0 | 0 | 0 | 0 | X | X | X | X | X | X | X | X | X | X | X | X | NOP: do nothing | | |
| 1 | 0 | 0 | 0 | 1 | 0 | 0 | A1 | A0 | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 | Write contents of serial register data to RDAC | | |
| 2 | 0 | 0 | 1 | 0 | 0 | 0 | A1 | A0 | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 | Write contents of serial register data to input register | | |
| 3 | 0 | 0 | 1 | 1 | 0 | 0 | A1 | A0 | X | X | X | X | X | X | D1 | D0 | Read back contents | | |
| | | | | | | | | | | | | | | | | | D1 | D0 | Data |
| | | | | | | | | | | | | | | | | | 0 | 1 | EEPROM |
| | | | | | | | | | | | | | | | | | 1 | 1 | RDAC |
| 9 | 0 | 1 | 1 | 1 | 0 | 0 | A1 | A0 | X | X | X | X | X | X | X | X | 1 | Copy RDAC register to EEPROM | |
| 10 | 0 | 1 | 1 | 1 | 0 | 0 | A1 | A0 | X | X | X | X | X | X | X | X | 0 | Copy EEPROM into RDAC | |
| 14 | 1 | 0 | 1 | 1 | X | X | X | X | X | X | X | X | X | X | X | X | X | Software reset | |
| 15 | 1 | 1 | 0 | 0 | A3 | A2 | A1 | A0 | X | X | X | X | X | X | X | D0 | Software shutdown | | |
| | | | | | | | | | | | | | | | | | D0 | Condition | |
| | | | | | | | | | | | | | | | | | 0 | Normal mode | |
| | | | | | | | | | | | | | | | | | 1 | Shutdown mode | |

¹ X means don't care.

Table 10. Reduced Address Bits Table

| A3 | A2 | A1 | A0 | Channel | Stored Channel Memory |
|----|----------------|----------------|----------------|--------------|-----------------------|
| 1 | X ¹ | X ¹ | X ¹ | All channels | Not applicable |
| 0 | 0 | 0 | 0 | RDAC1 | RDAC1 |
| 0 | 0 | 0 | 1 | RDAC2 | RDAC2 |
| 0 | 0 | 1 | 0 | RDAC3 | RDAC3 |
| 0 | 0 | 1 | 1 | RDAC4 | RDAC4 |

¹ X means don't care.

ADVANCED CONTROL MODES

The AD5123/AD5143 digital potentiometers include a set of user programming features to address the wide number of applications for these universal adjustment devices (see Table 15 and Table 17).

Key programming features include the following:

- Input register
- Linear gain setting mode
- Low wiper resistance feature
- Linear increment and decrement instructions
- ± 6 dB increment and decrement instructions
- Burst mode (I²C only)
- Reset
- Shutdown mode

Input Register

The AD5123/AD5143 include one input register per RDAC register. These registers allow preloading of the value for the associated RDAC register. These registers can be written to using Command 2 and read back using Command 3 (see Table 15).

This feature allows a synchronous and asynchronous update of one or all of the RDAC registers at the same time.

The transfer from the input register to the RDAC register is done synchronously by Command 8 (see Table 15).

If new data is loaded in an RDAC register, this RDAC register automatically overwrites the associated input register.

Linear Gain Setting Mode

The patented architecture of the AD5123/AD5143 allows the independent control of each string resistor, R_{AW} , and R_{WB} . To enable linear gain setting mode, use Command 16 (see Table 15) to set Bit D2 of the control register (see Table 17).

This mode of operation can control the potentiometer as two independent rheostats connected at a single point, W terminal, as opposed to potentiometer mode where each resistor is complementary, $R_{AW} = R_{AB} - R_{WB}$.

This mode enables a second input and an RDAC register per channel, as shown in Table 16; however, the actual RDAC contents remain unchanged. The same operations are valid for potentiometer and linear setting gain modes. The devices restore in potentiometer mode after a reset or power-up.

Low Wiper Resistance Feature

The AD5123/AD5143 include two commands to reduce the wiper resistance between the terminals when the devices achieve full scale or zero scale. These extra positions are called bottom scale, BS, and top scale, TS. The resistance between Terminal A and Terminal W at top scale is specified as R_{TS} . Similarly, the bottom scale resistance between Terminal B and Terminal W is specified as R_{BS} .

The contents of the RDAC registers are unchanged by entering in these positions. There are three ways to exit from top scale and bottom scale: by using Command 12 or Command 13 (see Table 15); by loading new data in an RDAC register, which includes increment/decrement operations; or by entering shutdown mode, Command 15 (see Table 15).

Table 11 and Table 12 show the truth tables for the top scale position and the bottom scale position, respectively, when the potentiometer or linear gain setting mode is enabled.

Table 11. Top Scale Truth Table

| Linear Gain Setting Mode | | Potentiometer Mode | |
|--------------------------|----------|--------------------|----------|
| R_{AW} | R_{WB} | R_{AW} | R_{WB} |
| R_{AB} | R_{AB} | R_{TS} | R_{AB} |

Table 12. Bottom Scale Truth Table

| Linear Gain Setting Mode | | Potentiometer Mode | |
|--------------------------|----------|--------------------|----------|
| R_{AW} | R_{WB} | R_{AW} | R_{WB} |
| R_{TS} | R_{BS} | R_{AB} | R_{BS} |

Linear Increment and Decrement Instructions

The increment and decrement commands (Command 4 and Command 5 in Table 15) are useful for linear step adjustment applications. These commands simplify microcontroller software coding by allowing the controller to send an increment or decrement command to the device. The adjustment can be individual or in a ganged potentiometer arrangement, where all wiper positions are changed at the same time.

For an increment command, executing Command 4 automatically moves the wiper to the next resistance RDAC position. This command can be executed in a single channel or multiple channels.

±6 dB Increment and Decrement Instructions

Two programming instructions produce logarithmic taper increment or decrement of the wiper position control by an individual potentiometer or by a ganged potentiometer arrangement where all RDAC register positions are changed simultaneously. The +6 dB increment is activated by Command 6, and the –6 dB decrement is activated by Command 7 (see Table 15). For example, starting with the zero-scale position and executing Command 6 ten times moves the wiper in 6 dB steps to the full-scale position. When the wiper position is near the maximum setting, the last 6 dB increment instruction causes the wiper to go to the full-scale position (see Table 13).

Incrementing the wiper position by +6 dB essentially doubles the RDAC register value, whereas decrementing the wiper position by –6 dB halves the register value. Internally, the AD5123/AD5143 use shift registers to shift the bits left and right to achieve a ±6 dB increment or decrement. These functions are useful for various audio/video level adjustments, especially for white LED brightness settings in which human visual responses are more sensitive to large adjustments than to small adjustments.

Table 13. Detailed Left Shift and Right Shift Functions for the ±6 dB Step Increment and Decrement

| Left Shift (+6 dB/Step) | Right Shift (–6 dB/Step) |
|-------------------------|--------------------------|
| 0000 0000 | 1111 1111 |
| 0000 0001 | 0111 1111 |
| 0000 0010 | 0011 1111 |
| 0000 0100 | 0001 1111 |
| 0000 1000 | 0000 1111 |
| 0001 0000 | 0000 0111 |
| 0010 0000 | 0000 0011 |
| 0100 0000 | 0000 0001 |
| 1000 0000 | 0000 0000 |
| 1111 1111 | 0000 0000 |

Burst Mode

By enabling the burst mode, multiple data bytes can be sent to the device consecutively. After the command byte, the device interprets the consecutive bytes as data bytes for the command.

A new command can be sent by generating a repeat start or by a stop and start condition.

The burst mode is activated by setting Bit D3 of the control register (see Table 17).

Reset

The AD5123/AD5143 can be reset through software by executing Command 14 (see Table 15). The reset command loads the RDAC registers with the contents of the EEPROM and takes approximately 30 μs. The EEPROM is preloaded to midscale at the factory, and initial power-up is, accordingly, at midscale.

Shutdown Mode

The AD5123/AD5143 can be placed in shutdown mode by executing the software shutdown command, Command 15 (see Table 15), and setting the LSB (D0) to 1. This feature places the RDAC in a zero power consumption state where the device operates in potentiometer mode, Terminal A is open-circuited, and the wiper, Terminal W, is connected to Terminal B; however, a finite wiper resistance of 40 Ω is present. When the device is configured in linear gain setting mode, the resistor addressed, R_{AW} or R_{WB}, is internally placed at high impedance. Table 14 shows the truth table depending on the device operating mode. The contents of the RDAC register are unchanged by entering shutdown mode. However, all commands listed in Table 15 are supported while in shutdown mode. Execute Command 15 (see Table 15) and set the LSB (D0) to 0 to exit shutdown mode.

Table 14. Truth Table for Shutdown Mode

| Linear Gain Setting Mode | | Potentiometer Mode | |
|--------------------------|-----------------|--------------------|-----------------|
| R _{AW} | R _{WB} | R _{AW} | R _{WB} |
| High impedance | High impedance | High impedance | R _{BS} |

EEPROM OR RDAC REGISTER PROTECTION

The EEPROM and RDAC registers can be protected by disabling any update to these registers. This can be done by using software or by using hardware. If these registers are protected by software, set Bit D0 and/or Bit D1 (see Table 17), which protects the RDAC and EEPROM registers independently.

When RDAC is protected, the only operation allowed is to copy the EEPROM into the RDAC register.

Table 15. Advance Commands Operation Truth Table

| Command Number | Control Bits[DB15:DB12] | | | | Address Bits[DB11:DB8] ¹ | | | | Data Bits[DB7:DB0] ¹ | | | | | | | | Operation | | |
|----------------|-------------------------|------|----|----|-------------------------------------|----|----|----|---------------------------------|----|----|----|----|----|----|----|--|----|------------------|
| | C3 | C2 | C1 | C0 | A3 | A2 | A1 | A0 | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 | | | |
| 0 | 0 | 0 | 0 | 0 | X | X | X | X | X | X | X | X | X | X | X | X | NOP: do nothing | | |
| 1 | 0 | 0 | 0 | 1 | A3 | A2 | A1 | A0 | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 | Write contents of serial register data to RDAC | | |
| 2 | 0 | 0 | 1 | 0 | A3 | A2 | A1 | A0 | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 | Write contents of serial register data to input register | | |
| 3 | 0 | 0 | 1 | 1 | X | A2 | A1 | A0 | X | X | X | X | X | X | D1 | D0 | Read back contents | | |
| | | | | | | | | | | | | | | | | | D1 | D0 | Data |
| | | | | | | | | | | | | | | | | | 0 | 0 | Input register |
| | | | | | | | | | | | | | | | | | 0 | 1 | EEPROM |
| | | | | | | | | | | | | | | | | | 1 | 0 | Control register |
| 1 | 1 | RDAC | | | | | | | | | | | | | | | | | |
| 4 | 0 | 1 | 0 | 0 | A3 | A2 | A1 | A0 | X | X | X | X | X | X | X | 1 | Linear RDAC increment | | |
| 5 | 0 | 1 | 0 | 0 | A3 | A2 | A1 | A0 | X | X | X | X | X | X | X | 0 | Linear RDAC decrement | | |
| 6 | 0 | 1 | 0 | 1 | A3 | A2 | A1 | A0 | X | X | X | X | X | X | X | 1 | +6 dB RDAC increment | | |
| 7 | 0 | 1 | 0 | 1 | A3 | A2 | A1 | A0 | X | X | X | X | X | X | X | 0 | -6 dB RDAC decrement | | |
| 8 | 0 | 1 | 1 | 0 | A3 | A2 | A1 | A0 | X | X | X | X | X | X | X | X | Copy input register to RDAC (software LRDAC) | | |
| 9 | 0 | 1 | 1 | 1 | 0 | 0 | A1 | A0 | X | X | X | X | X | X | X | 1 | Copy RDAC register to EEPROM | | |
| 10 | 0 | 1 | 1 | 1 | 0 | 0 | A1 | A0 | X | X | X | X | X | X | X | 0 | Copy EEPROM into RDAC | | |
| 11 | 1 | 0 | 0 | 0 | 0 | 0 | A1 | A0 | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 | Write contents of serial register data to EEPROM | | |
| 12 | 1 | 0 | 0 | 1 | A3 | A2 | A1 | A0 | 1 | X | X | X | X | X | X | D0 | Top scale D0 = 0; normal mode D0 = 1; shutdown mode | | |
| 13 | 1 | 0 | 0 | 1 | A3 | A2 | A1 | A0 | 0 | X | X | X | X | X | X | D0 | Bottom scale D0 = 1; enter D0 = 0; exit | | |
| 14 | 1 | 0 | 1 | 1 | X | X | X | X | X | X | X | X | X | X | X | X | Software reset | | |
| 15 | 1 | 1 | 0 | 0 | A3 | A2 | A1 | A0 | X | X | X | X | X | X | X | D0 | Software shutdown D0 = 0; normal mode D0 = 1; device placed in shutdown mode | | |
| 16 | 1 | 1 | 0 | 1 | X | X | X | X | X | X | X | X | D3 | D2 | D1 | D0 | Copy serial register data to control register | | |

¹ X means don't care.

Table 16. Address Bits

| A3 | A2 | A1 | A0 | Potentiometer Mode | | Linear Gain Setting Mode | | Stored RDAC Memory |
|----|----------------|----------------|----------------|--------------------|----------------|--------------------------|------------------|--------------------|
| | | | | Input Register | RDAC Register | Input Register | RDAC Register | |
| 1 | X ¹ | X ¹ | X ¹ | All channels | All channels | All channels | All channels | Not applicable |
| 0 | 0 | 0 | 0 | RDAC1 | RDAC1 | R _{WB1} | R _{WB1} | RDAC1 |
| 0 | 1 | 0 | 0 | Not applicable | Not applicable | R _{AW1} | R _{AW1} | Not applicable |
| 0 | 0 | 0 | 1 | RDAC2 | RDAC2 | R _{WB2} | R _{WB2} | RDAC2 |
| 0 | 1 | 0 | 1 | Not applicable | Not applicable | R _{AW2} | R _{AW2} | Not applicable |
| 0 | 0 | 1 | 0 | RDAC3 | RDAC3 | R _{WB3} | R _{WB3} | RDAC3 |
| 0 | 1 | 1 | 0 | Not applicable | Not applicable | R _{AW3} | R _{AW3} | Not applicable |
| 0 | 0 | 1 | 1 | RDAC4 | RDAC4 | R _{WB4} | R _{WB4} | RDAC4 |
| 0 | 1 | 1 | 1 | Not applicable | Not applicable | R _{AW4} | R _{AW4} | Not applicable |

¹ X means don't care.

Table 17. Control Register Bit Descriptions

| Bit Name | Description |
|----------|---|
| D0 | RDAC register write protect 0 = wiper position frozen to value in EEPROM memory 1 = allows update of wiper position through digital interface (default) |
| D1 | EEPROM program enable 0 = EEPROM program disabled 1 = enables device for EEPROM program (default) |
| D2 | Linear setting mode/potentiometer mode 0 = potentiometer mode (default) 1 = linear gain setting mode |
| D3 | Burst mode 0 = disabled (default) 1 = enabled (no disable after stop or repeat start condition) |

RDAC ARCHITECTURE

To achieve optimum performance, Analog Devices, Inc., has patented the RDAC segmentation architecture for all the digital potentiometers. In particular, the AD5123/AD5143 employ a three-stage segmentation approach, as shown in Figure 36. The AD5123/AD5143 wiper switch is designed with the transmission gate CMOS topology and with the gate voltage derived from V_{DD} and V_{SS}.

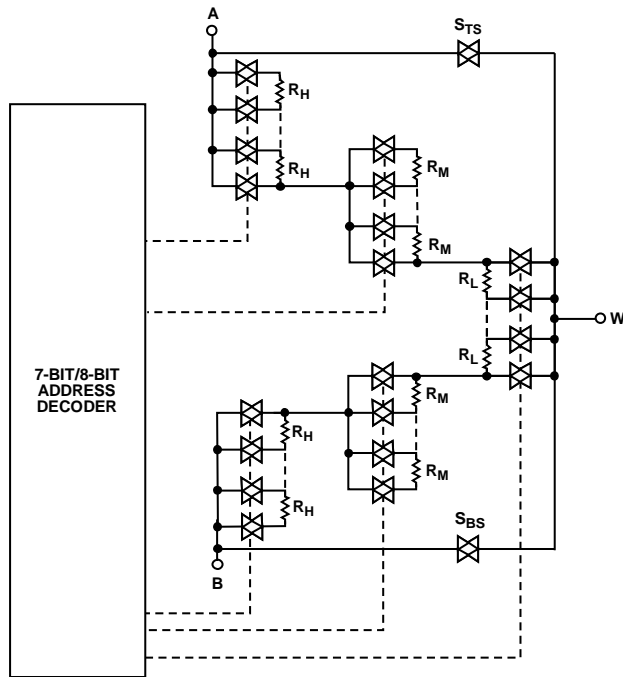


Figure 36. AD5123/AD5143 Simplified RDAC Circuit

Top Scale/Bottom Scale Architecture

In addition, the AD5123/AD5143 include new positions to reduce the resistance between terminals. These positions are called bottom scale and top scale. At bottom scale, the typical wiper resistance decreases from 130 Ω to 60 Ω (R_{AB} = 100 kΩ). At top scale, the resistance between Terminal A and Terminal W is decreased by 1 LSB, and the total resistance is reduced to 60 Ω (R_{AB} = 100 kΩ).

PROGRAMMING THE VARIABLE RESISTOR

Rheostat Operation—±8% Resistor Tolerance

The AD5123/AD5143 operate in rheostat mode when only two terminals are used as a variable resistor. The unused terminal can be floating, or it can be tied to Terminal W, as shown in Figure 37.

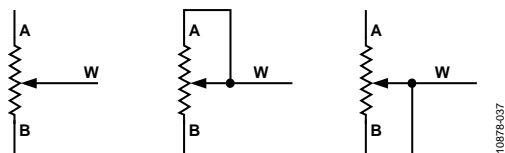


Figure 37. Rheostat Mode Configuration

The nominal resistance between Terminal A and Terminal B, R_{AB}, is 10 kΩ or 100 kΩ, and has 128/256 tap points accessed by the wiper terminal. The 7-bit/8-bit data in the RDAC latch is decoded to select one of the 128/256 possible wiper settings. The general equations for determining the digitally programmed output resistance between Terminal W and Terminal B are

AD5123:

$$R_{WB}(D) = \frac{D}{128} \times R_{AB} + R_W \quad \text{From 0x00 to 0x7F} \quad (1)$$

AD5143:

$$R_{WB}(D) = \frac{D}{256} \times R_{AB} + R_W \quad \text{From 0x00 to 0xFF} \quad (2)$$

where:

D is the decimal equivalent of the binary code in the 7-bit/8-bit RDAC register.

R_{AB} is the end to end resistance.

R_W is the wiper resistance.

In potentiometer mode, similar to the mechanical potentiometer, the resistance between Terminal W and Terminal A also produces a digitally controlled complementary resistance, R_{WA}. R_{WA} also gives a maximum of 8% absolute. R_{WA} starts at the maximum resistance value and decreases as the data loaded into the latch increases. The general equations for this operation are

AD5123:

$$R_{AW}(D) = \frac{128 - D}{128} \times R_{AB} + R_W \quad \text{From 0x00 to 0x7F} \quad (3)$$

AD5143:

$$R_{AW}(D) = \frac{256 - D}{256} \times R_{AB} + R_W \quad \text{From 0x00 to 0xFF} \quad (4)$$

where:

D is the decimal equivalent of the binary code in the 7-bit/8-bit RDAC register.

R_{AB} is the end to end resistance.

R_W is the wiper resistance.

If the device is configured in linear gain setting mode, the resistance between Terminal W and Terminal A is directly proportional to the code loaded in the associate RDAC register. The general equations for this operation are

AD5123:

$$R_{AW}(D) = \frac{D}{128} \times R_{AB} + R_W \quad \text{From 0x00 to 0x7F} \quad (5)$$

AD5143:

$$R_{AW}(D) = \frac{D}{256} \times R_{AB} + R_W \quad \text{From 0x00 to 0xFF} \quad (6)$$

where:

D is the decimal equivalent of the binary code in the 7-bit/8-bit RDAC register.

R_{AB} is the end to end resistance.

R_W is the wiper resistance.

In the bottom scale condition or top scale condition, a finite total wiper resistance of 40 Ω is present. Regardless of which setting the device is operating in, limit the current between Terminal A to Terminal B, Terminal W to Terminal A, and Terminal W to Terminal B, to the maximum continuous current of ±6 mA or to the pulse current specified in Table 5. Otherwise, degradation or possible destruction of the internal switch contact can occur.

PROGRAMMING THE POTENTIOMETER DIVIDER

Voltage Output Operation

The digital potentiometer easily generates a voltage divider at wiper-to-B and wiper-to-A that is proportional to the input voltage at A to B, as shown in Figure 38.

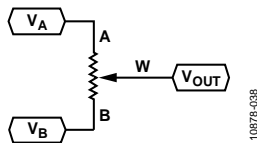


Figure 38. Potentiometer Mode Configuration

Connecting Terminal A to 5 V and Terminal B to ground produces an output voltage at the Wiper W to Terminal B ranging from 0 V to 5 V. The general equation defining the output voltage at V_W with respect to ground for any valid input voltage applied to Terminal A and Terminal B is

$$V_W(D) = \frac{R_{WB}(D)}{R_{AB}} \times V_A + \frac{R_{AW}(D)}{R_{AB}} \times V_B \tag{7}$$

where:

R_{WB}(D) can be obtained from Equation 1 and Equation 2.

R_{AW}(D) can be obtained from Equation 3 and Equation 4.

Operation of the digital potentiometer in the divider mode results in a more accurate operation over temperature. Unlike the rheostat mode, the output voltage is dependent mainly on the ratio of the internal resistors, R_{AW} and R_{WB}, and not the absolute values. Therefore, the temperature drift reduces to 5 ppm/°C.

TERMINAL VOLTAGE OPERATING RANGE

The AD5123/AD5143 are designed with internal ESD diodes for protection. These diodes also set the voltage boundary of the terminal operating voltages. Positive signals present on Terminal A, Terminal B, or Terminal W that exceed V_{DD} are clamped by the forward-biased diode. There is no polarity constraint between V_A, V_W, and V_B, but they cannot be higher than V_{DD} or lower than V_{SS}.

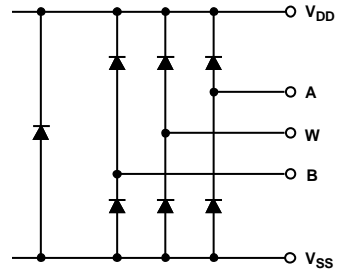


Figure 39. Maximum Terminal Voltages Set by V_{DD} and V_{SS}

POWER-UP SEQUENCE

Because there are diodes to limit the voltage compliance at Terminal A, Terminal B, and Terminal W (see Figure 39), it is important to power up V_{DD} first before applying any voltage to Terminal A, Terminal B, and Terminal W. Otherwise, the diode is forward-biased such that V_{DD} is powered unintentionally. The ideal power-up sequence is V_{SS}, V_{DD}, digital inputs, and V_A, V_B, and V_W. The order of powering V_A, V_B, V_W, and digital inputs is not important as long as they are powered after V_{SS} and V_{DD}. Regardless of the power-up sequence and the ramp rates of the power supplies, once V_{DD} is powered, the power-on preset activates, which restores EEPROM values to the RDAC registers.

LAYOUT AND POWER SUPPLY BIASING

It is always a good practice to use a compact, minimum lead length layout design. Ensure that the leads to the input are as direct as possible with a minimum conductor length. Ground paths must have low resistance and low inductance. It is also good practice to bypass the power supplies with quality capacitors. Apply low equivalent series resistance (ESR) 1 μF to 10 μF tantalum or electrolytic capacitors at the supplies to minimize any transient disturbance and to filter low frequency ripple. Figure 40 illustrates the basic supply bypassing configuration for the AD5123/AD5143.

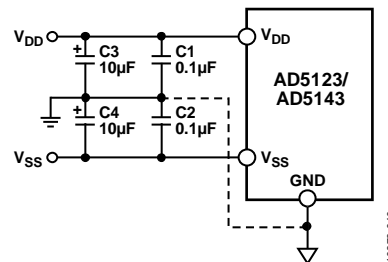
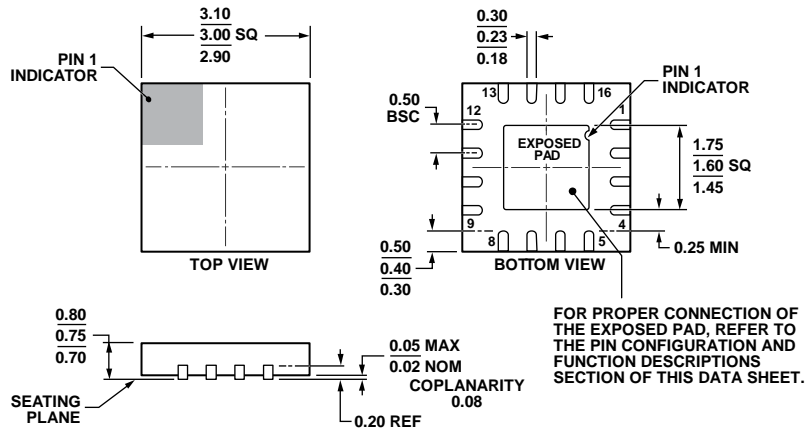


Figure 40. Power Supply Bypassing

OUTLINE DIMENSIONS



COMPLIANT TO JEDEC STANDARDS MO-220-WEED-6.

Figure 41. 16-Lead Lead Frame Chip Scale Package [LFCSP_WQ]
 3 mm × 3 mm Body, Very Very Thin Quad
 (CP-16-22)
 Dimensions shown in millimeters

08-16-2010 E

ORDERING GUIDE

| Model ^{1, 2} | R _{AB} (kΩ) | Resolution | Interface | Temperature Range | Package Description | Package Option | Branding |
|-----------------------|----------------------|------------|------------------|-------------------|---------------------|----------------|----------|
| AD5123BCPZ10-RL7 | 10 | 128 | I ² C | -40°C to +125°C | 16-Lead LFCSP_WQ | CP-16-22 | DGZ |
| AD5123BCPZ100-RL7 | 100 | 128 | I ² C | -40°C to +125°C | 16-Lead LFCSP_WQ | CP-16-22 | DH0 |
| AD5143BCPZ10-RL7 | 10 | 256 | I ² C | -40°C to +125°C | 16-Lead LFCSP_WQ | CP-16-22 | DH1 |
| AD5143BCPZ100-RL7 | 100 | 256 | I ² C | -40°C to +125°C | 16-Lead LFCSP_WQ | CP-16-22 | DH2 |
| EVAL-AD5143DBZ | | | | | Evaluation Board | | |

¹ Z = RoHS Compliant Part.

² The evaluation board is shipped with the 10 kΩ R_{AB} resistor option; however, the board is compatible with all of the available resistor value options.

NOTES

I²C refers to a communications protocol originally developed by Philips Semiconductors (now NXP Semiconductors).

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